

Chapter 8

Input/Output

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Examples of Input/Output (I/O) Devices

User output

- Display, printer, speakers

User input

- Keyboard, mouse, trackball, game controller, scanner, microphone, touch screens, camera (still and video)

Storage

- Disk drives, CD & DVD drives, flash-based storage, tape drive

Communication

- Network (wired, wireless, optical, infrared), modem

Sensor inputs

- Temperature, vibration, motion, acceleration, GPS
- Barcode scanner, magnetic strip reader, RFID reader

Control outputs

- Motors, actuators

Input/Output: Connecting to the Outside World

So far, we've learned how to...

- Compute with values in registers
- Move data between memory and registers

But how do we interact with computers?

- Game console (Playstation, Xbox)
- DVD player
- MP3 player (iPod)
- Cell phone
- Automated Teller Machine (ATM)
- Car's airbag controller
- Web server

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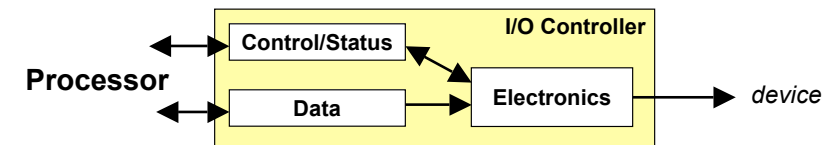
I/O Controller

Control/Status Registers

- CPU tells device what to do -- write to control register
- CPU checks whether task is done -- read status register

Data Registers

- CPU transfers data to/from device



Device electronics

- Performs actual operation
 - Pixels to screen, bits to/from disk, characters from keyboard

How does software interact with I/O?

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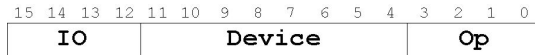
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Memory-Mapped vs. I/O Instructions

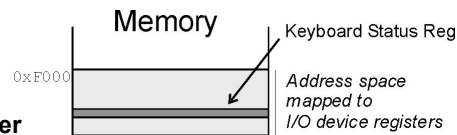
Instructions

- Designate opcode(s) for I/O
- Register and operation encoded in instruction



Memory-mapped

- Assign a memory address to each device register
- Use data movement instructions (LD/ST) for control and data transfer
- Hardware intercepts these address
- **No actual memory access performed**



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LC-3 I/O Devices (Extended)

Memory-mapped I/O (Table A.3)

| Location | I/O Register | Function |
|--------------|-------------------------------|--|
| xFE00 | Keyboard Status Reg (KBSR) | Bit [15] is one when keyboard has received a new character. |
| xFE02 | Keyboard Data Reg (KBDR) | Bits [7:0] contain the last character typed on keyboard. |
| xFE04 | Display Status Register (DSR) | Bit [15] is one when device ready to display another char on screen. |
| xFE06 | Display Data Register (DDR) | Character written to bits [7:0] will be displayed on screen. |
| xFE08 | Timer Status Register (TSR) | Bit[15] is one when timer goes off; cleared when read. |
| xFE0A | Timer Interval Register (TIR) | Timer interval in msec. |

Polling and Interrupts

- We'll talk first about polling, a bit on interrupts later

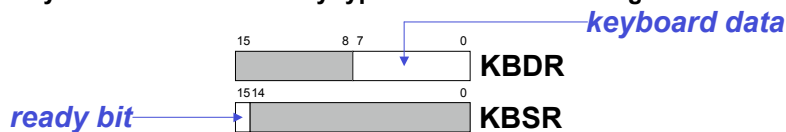
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Input from Keyboard

When a character is typed:

- Its ASCII code is placed in bits [7:0] of KBDR (bits [15:8] are always zero)
- The "ready bit" (KBSR[15]) is set to one
- Keyboard is disabled -- any typed characters will be ignored



When KBDR is read:

- **KBSR[15] is set to zero**
- Keyboard is enabled

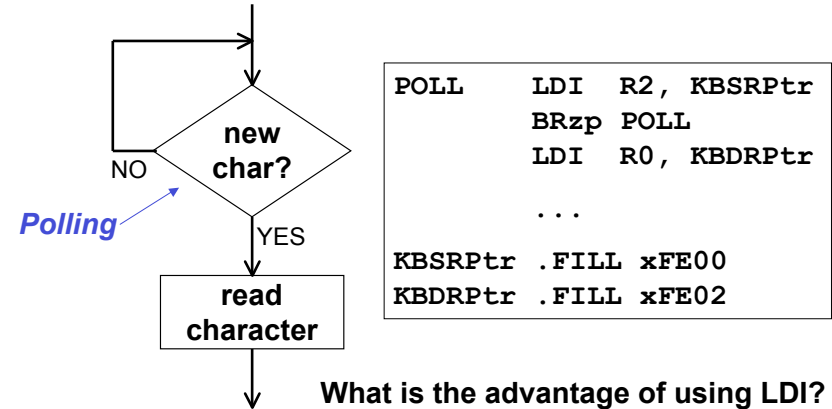
Alternative implementation: buffering keyboard input

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Basic Input Routine

Put the ASCII value of the character typed into R0



What is the advantage of using LDI?

What if you don't test KBSR before reading data from keyboard?

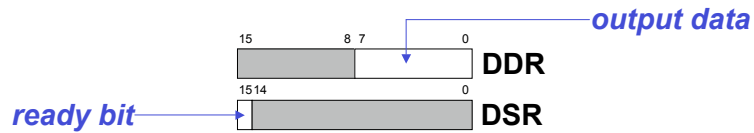
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Output to Monitor

When Monitor is ready to display another character:

- The "ready bit" (DSR[15]) is set to one



When data is written to Display Data Register:

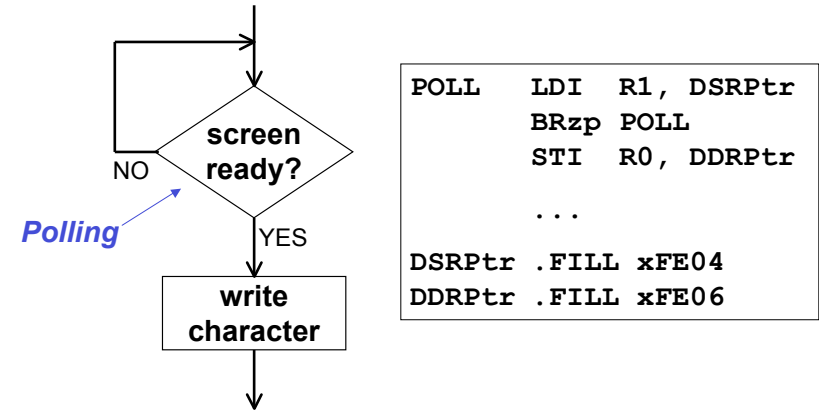
- DSR[15] is set to zero
- Character in DDR[7:0] is displayed
- Any other character data written to DDR is ignored (while DSR[15] is zero)

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Basic Output Routine

R0 is the ASCII value of the character to be displayed



What if you don't test KBSR before send data to display?

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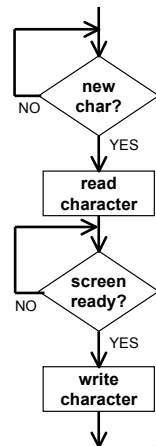
Keyboard Echo Routine

Usually, input character is also printed to screen

- User gets feedback on character typed and knows its ok to type the next character

```

POLL1  LDI  R2, KBSRPtr
      BRzp POLL1
      LDI  R0, KBDRPtr
POLL2  LDI  R1, DSRPtr
      BRzp POLL2
      STI  R0, DDRPtr
      ...
KBSRPtr .FILL xFE00
KBDRPtr .FILL xFE02
DSRPtr  .FILL xFE04
DDRPtr  .FILL xFE06
    
```



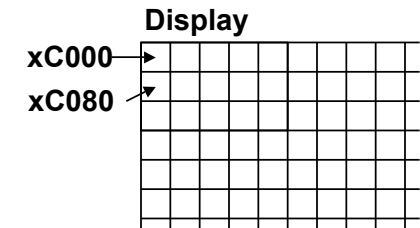
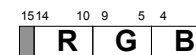
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Pixel-Based Display

A display consists of many dots (pixels)

- Color of each pixel represented by a 16-bit value
 - 5 bits for each of Red/Green/Blue
 - 32 thousand distinct colors



Memory-mapped pixels

- One memory location per pixel
- 128x124 pixels
- Memory region xC000 to xFDFF
 - xC000 to xC07F is first row of display
 - xC080 to xC0FF is second row of display
- Set the corresponding location to change its color

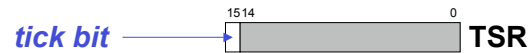
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Timer Device

A periodic timer “tick”

- Allows a program to detect when an interval of time has passed
- Our implementation (for the LC-3) uses a simple fix-interval timer



Using TSR (Timer Status Register):

- “Tick” bit is set every n milliseconds
- Read the value of the bit from memory location (xFE08)
- Bit reset to zero after every read
- Change interval via Timer Interval Register (TIR, xFE0A)

Why did we add the display and timer? For Snake!

Internal Hard Drives

A large magnetic disk

- Spinning at 10,000 RPM
- A magnetic head reads from the surface of the disk

Larger capacity than memory

- Contain 100s of gigabytes of data
- In contrast: main memory is commonly a gigabyte or two

Interface is block-level

- Request a particular “block” to read from the disk
- All of that block is written into memory
- Or read from memory, written to disk

Disk Interface

The LC-3 simulator doesn’t support disks, but if it did...

- Read or write “block” of 256 16-bit words (512 bytes)
- Access any of $2^{16} = 65536$ blocks
- Resulting maximum disk size: 32 megabytes (32 million bytes)

Interface

- DiskStatusRegister: ready bit (just like keyboard and display)
- DiskControlRegister: tell disk what to do
- DiskBlockRegister: disk block address to read or write
- DiskMemoryRegister: address of starting memory location

Block read operation

- Wait for disk to be “idle”
- Set BlockRegister (source), MemoryRegister (destination)
- Set Control to “Read” - the doorbell
- Wait for disk to finish read (status bit becomes “idle” again)

Disk Interface

Write operation

- Wait for disk to be “idle”
- Set BlockRegister (destination), MemoryRegister (source)
- Set Control to “Write” - the doorbell
- Wait for disk to finish write (status bit becomes “idle” again)

Direct Memory Access (DMA)

- This type of “device writes to or reads from memory” interface
- Allows large amounts of data to move without intervention from the processor (for example, an entire disk block)
- Status register changes upon completion
- Network interfaces also use DMA
- Used by all high-speed, high-performance devices

Two Ways to Control Devices

Who determines when the next data transfer occurs?

Polling

- CPU keeps checking status register until new data arrives or device ready for next data
- Example: spinning on keyboard status register
- “Are we there yet? Are we there yet? Are we there yet?”

Interrupts

- Device sends a special signal to CPU when new data arrives or device ready for next data
- CPU can be performing other tasks instead of polling device
- “Wake me when we get there.”

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Interrupt-Driven I/O

To implement an interrupt mechanism, we need

- Way for software to **enable** interrupts on device
 - Set a bit in the device’s status register
- Way for I/O device to **signal** that event has occurred
 - When device status changes, hijack processor
 - “jumps” to interrupt service routine (PC = Mem[x0100+i])

Interrupt service routine More information in Chapter 10

- Operating system code at a well-know location
- Uses regular I/O register to interact with devices
- Interrupt simply tells the software **when** to query

Not implemented in LC-3 simulator

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Interrupt-Driven I/O

External device can. . .

- (1) Force currently executing program to stop
- (2) Have the processor satisfy the device’s needs
- (3) Resume the stopped program as if nothing happened

Why?

- Polling consumes a lot of cycles, especially for rare events – these cycles can be used for more computation
- Again, I/O devices are slow
- Examples:
 - Process previous input while collecting current input (See Example 8.1 in text)
 - Waiting for disk write to complete (overlap disk write with other work)
 - Another example? Network interface

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Role of the Operating System

In real systems, only the operating system (OS) does I/O

- “Normal” programs ask the OS to perform I/O on its behalf

Hardware prevents non-operating system code from

- Accessing I/O registers
- Operating system code and data
- Accessing the code and data of other programs

Why?

- **Protect programs from themselves**
- **Protect programs from each other**
- **Multi-user environments**

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Memory Protection

The hardware has two modes

- “Supervisor” or “privileged” mode
- “User” or “unprivileged” mode

Code in privileged mode

- Can do *anything*
- Used exclusively by the operating system

Code in user mode

- Can’t access I/O parts of memory
- Can only access some parts of memory

Division of labor

- Operating system (OS) - make policy choices
- Hardware - enforce the OS’s policy

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OS and Hardware Cooperate for Protection

Hardware support for protected memory

- For example, consider a 16-bit protection register (MPR) in the processor
 - MPR[0] corresponds to x0000 - x0FFF
 - MPR[1] corresponds to x1000 - x1FFF
 - MPR[2] corresponds to x2000 - x2FFF, etc.

When a processor performs a load or store

- Checks the corresponding bit in MPR
- If MPR bit is not set (and not in privileged mode)
 - Trigger illegal access handler

The OS must set these bits before running each program

- Example, If a program should access only x4000 - x6FFF
 - OS sets MPR[4, 5, 6] to 1 (the rest are set to 0)

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Invoking the Operating System

How does non-privileged code perform I/O?

- Answer: it doesn’t; it asks the OS to perform I/O on its behalf

How is this done?

- Making a system call into the operating system

In LC-3: The TRAP instruction

- Calls into the operating system (sets privileged mode)
- Different part of the OS called for each trap number
- OS performs the operations (in privileged mode)
- OS leaves privileged mode
- OS returns control back to user program (jumps to the PC after the TRAP instruction)

Topic of next chapter...

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