

# CSE 380

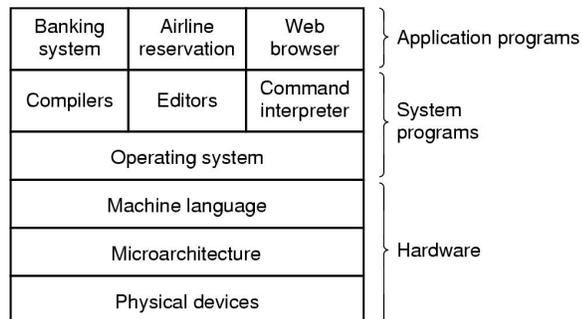
## Computer Operating Systems

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Lecture Note 1: Introduction

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## What is an Operating System?



Operating systems provides an interface between hardware and user programs, and makes hardware usable

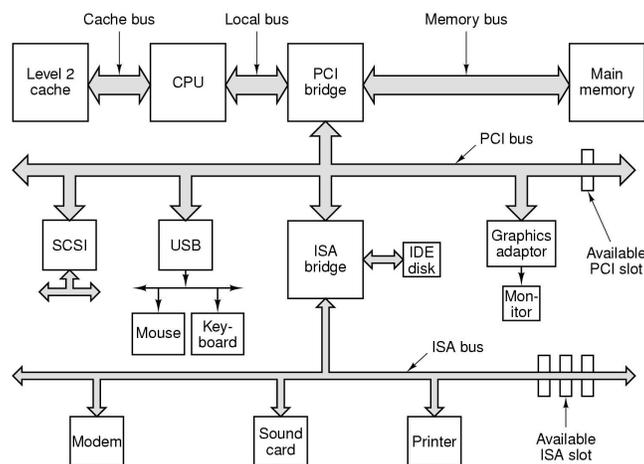
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## Resource Abstraction and Sharing

- ❑ It is an extended machine providing abstraction of the hardware
  - Hides the messy details which must be performed
  - Presents user with a virtual machine, easier to use
- ❑ It is a resource manager
  - Time on CPU is shared among multiple users/programs
  - Space in memory and on disks is shared among multiple users/programs

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## Pentium Architecture



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## Abstractions in OS

### Hardware

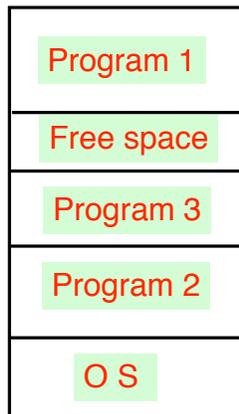
- Disks
- Memory
- Processors
- Network
- Monitor
- Keyboard
- Mouse

### OS abstraction

- Files
- Programs
- Threads / Processes
- Communication
- Windows and GUI
- Input
- Locator

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## Sharing of Memory

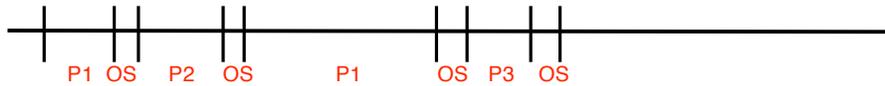


### Issues

- Allocation schemes
- Protection from each other
- Protecting OS code
- Translating logical addresses to physical
- Swapping programs
- What if physical memory is small: Virtual memory

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## Timesharing



- ❑ At any point, only one program can run on CPU
- ❑ Context switch: changing the program that has CPU
- ❑ When to switch (goal: to optimize the CPU usage)
  - When a program terminates
  - When a program has run “long enough”
  - When a program executes a system call or waits for I/O
  - When an external interrupt arrives (e.g. mouse click)
- ❑ OS must do all the book-keeping necessary for context switch, with minimum number of instructions

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## Challenges in OS

### Why can't Microsoft still get rid of all bugs in Windows ?

- ❑ Performance is critical
  - How to reduce the memory and time overhead due to OS
- ❑ Synchronization and deadlocks due to shared resources
- ❑ Scheduling of multiple programs
  - Fairness, response time, real-time applications
- ❑ Memory management
  - Virtual memory, paging, segmentation
- ❑ Security and Protection
  - Authorization, authentication, viruses
- ❑ Interrupt management and error handling
- ❑ Marketability and backward compatibility

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## How does OS work?

- ❑ OS gets control of the CPU repeatedly
- ❑ Let's look at two typical scenarios to get a glimpse of how things work (we will get a more accurate and detailed understanding as the course progresses)
- ❑ Basic knowledge about computer architecture is essential !  
(Read Sec 1.4 to review CSE 240)

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## Inside a CPU

- ❑ State of a running program
  - Registers
  - Program counter (PC)
  - Stack pointer
  - Program status word (PSW)
- ❑ Key distinction in PSW: user mode vs kernel (OS) mode
- ❑ Key instruction for OS calls: TRAP (switch to kernel mode)
- ❑ Many operations (such as accessing I/O devices) are possible only in the kernel mode

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## Different types of Memory

Typical access time		Typical capacity
1 nsec	Registers	<1 KB
2 nsec	Cache	1 MB
10 nsec	Main memory	64-512 MB
10 msec	Magnetic disk	5-50 GB
100 sec	Magnetic tape	20-100 GB

- ❑ Use of disks unavoidable (permanence and size)
- ❑ Access time is significantly slower for disks

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## Sample Scenario 1

- ❑ Consider a statement to read from a file in a user program P
- ❑ User program stores parameters such as file-id, memory-address, number-of-bytes, and system-call number of read, and executes TRAP instruction to invoke OS
- ❑ Hardware saves the state of current program, sets the mode-bit in PSW register in CPU to 1, and transfers control to a fixed location in OS code
- ❑ OS maintains an internal file table that stores relevant information about all open files

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## Sample Scenario 1 (continued)

- ❑ OS read routine examines the parameters, checks for errors (e.g. file must be open), consults its file table, and determines the disk address from where data is to be retrieved
- ❑ then it sets up registers to initiate transfer by the disk controller
- ❑ While disk controller is transferring data from disk to memory, OS can suspend current program, and switch to a different program
- ❑ When OS routine finishes the job, it stores the status code, and returns control to the user program P (hardware resets mode-bit)
- ❑ Note: Disk controller is accessed only by OS code (this is ensured by hardware protection)

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## Sample Scenario 2

- ❑ Consider an assignment  $x:=y$  in a program P
- ❑ Compiler assigns logical addresses, say Add1 and Add2, for program variables in P's data space
- ❑ When P is loaded in memory, OS assigns a physical base address to store P and its data
- ❑ Compiled code looks like  
Load (R, Add1); Store (R, Add2)
- ❑ While executing Load instruction the hardware translates the logical address Add1 to a physical memory location (this is done by Memory Management Unit MMU)

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## Sample Scenario 2 (continued)

- ❑ However, OS may not keep all of P in memory all the time
- ❑ OS maintains an internal table, called page table, that keeps track of which blocks of P are in memory
- ❑ If Add1 is not in memory, MMU generates a page fault, and transfers control to OS
- ❑ OS examines the cause, and initiates a disk transfer to load in the relevant block of P
- ❑ OS needs to decide memory allocation for the block to be fetched (page replacement algorithms)
- ❑ While this block is being fetched, P may be suspended using a context switch

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## Brief History of Operating Systems

- ❑ 1940's -- First Computers
- ❑ 1950's -- Batch Processing
- ❑ 1960's -- Multiprogramming (timesharing)
- ❑ 1970's -- Minicomputers & Microprocessors
- ❑ 1980's -- Networking, Distributed Systems, Parallel (multiprocessor) Systems
- ❑ 1990's and Beyond -- PCs, WWW, Mobile Systems, embedded systems

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## 1940's -- First Computers

- ❑ Computer dedicated to one user/programmer at a time. Program loaded manually by programmer, using console switches. Debugging using console lights.
- ❑ Advantages:
  - Interactive (user gets immediate response)
- ❑ Disadvantages:
  - Expensive machine idle most of time, because people are slow.
  - Programming & debugging are tedious.
  - Each program must include code to operate peripherals -- error prone, device dependencies.
- ❑ Libraries of subroutines to drive peripherals are example of typical OS service.

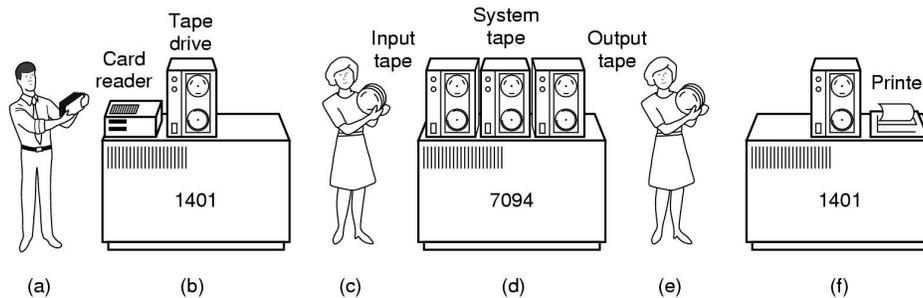
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## 1950's -- Batch Processing

- ❑ User/programmer submits a deck of cards that describes a job to be executed.
- ❑ Jobs submitted by various users are sequenced automatically by a resident monitor.
- ❑ Tape drives available for batching of input and spooling of output.
- ❑ Advantages:
  - Computer system is kept busier.
- ❑ Disadvantages:
  - No longer interactive; longer turnaround time.
  - CPU is still idle for I/O-bound jobs.
- ❑ OS issues -- command processor (JCL), protection of resident monitor from user programs, loading of user programs after monitor.

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## Typical Batch System



### Early batch system

- bring cards to 1401
- read cards to tape
- put tape on 7094 which does computing
- put tape on 1401 which prints output

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## 1960's -- Multiprogramming (timesharing)

- ❑ The advent of the I/O processor made simultaneous I/O and CPU processing possible.
- ❑ CPU is multiplexed (shared) among a number of jobs -- while one job waiting for I/O, another can use CPU.
- ❑ Advantages:
  - Interactiveness is restored.
  - CPU is kept busy.
- ❑ Disadvantages:
  - Hardware and O.S. required become significantly more complex.
- ❑ **Timesharing** - switch CPU among jobs for pre-defined time interval
- ❑ Most O.S. issues arise from trying to support multiprogramming -- CPU scheduling, deadlock, protection, memory management, virtual memory, etc.
- ❑ CTSS (Compatible Time Sharing System), Multics

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## 1970's - Minicomputers & Microprocessors

- ❑ Trend towards many small to mid-range personal computers, rather than a single mainframe.
- ❑ Early minicomputers and microprocessors were small, so there was some regression to earlier OS ideas.
  - e.g. DOS on PC is still essentially a batch system similar to those used in 1960, with some modern OS ideas thrown in (e.g., hierarchical file system).
- ❑ This trend changing rapidly because of powerful new microprocessors.
- ❑ Also, the user interface (GUI) became more important.
- ❑ **UNIX**, DOS

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## 1980's - Networking

- ❑ Powerful workstations (e.g., PDP, VAX, Sunstations, etc.)
- ❑ Local area networks (e.g., Ethernet, Token ring) and long-distance network (Arpanet)
- ❑ Networks organized with clients and servers
- ❑ Decentralization of computing requires more communication (e.g., resource sharing)
- ❑ O.S. issues -- network communication protocols, data encryption, security, reliability, consistency of distributed data
- ❑ Real-Time Systems – timing constraints, deadlines, QoS (quality of service)

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## 1990's and Beyond

- ❑ Parallel Computing (tera-flops)
- ❑ Powerful PCs, Multimedia computers
- ❑ High-speed, long-distance communication links to send large amounts of data, including graphical, audio and video
- ❑ World Wide Web
- ❑ Electronic notebooks and PDAs using wireless communication technologies
- ❑ Embedded computers: medical devices, cars, smartcards
- ❑ O.S. issues -- Large heterogeneous systems, mobile computing, utilization of power, security, etc.

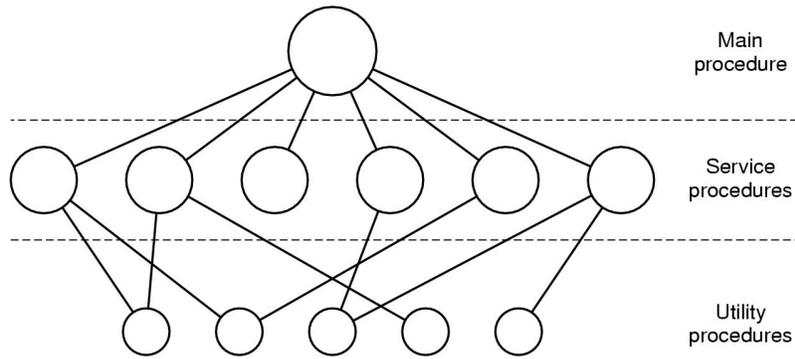
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## Operating System Structure

- ❑ Monolithic Systems
- ❑ Layered Systems
- ❑ Virtual Machines
- ❑ Client-Server Model

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## Operating System Structure (1)



Simple structuring model for a monolithic system

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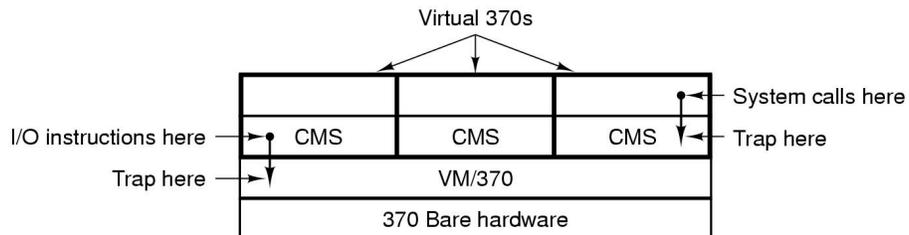
## Operating System Structure (2)

Layer	Function
5	The operator
4	User programs
3	Input/output management
2	Operator-process communication
1	Memory and drum management
0	Processor allocation and multiprogramming

Structure of the THE operating system

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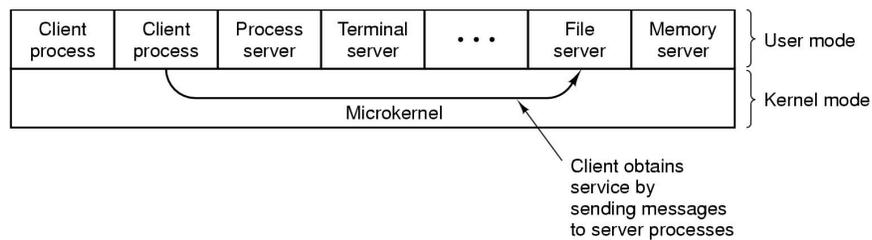
## Operating System Structure (3)



Structure of VM/370 with CMS

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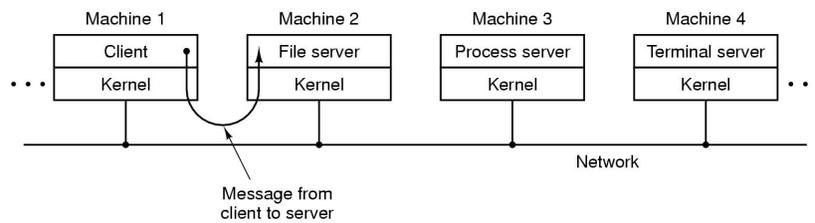
## Operating System Structure (4)



The client-server model

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## Operating System Structure (5)



The client-server model in a distributed system