

# Satisfiability Modulo Theories (SMT): ideas and applications

Università Degli Studi Di Milano

Scuola di Dottorato in Informatica, 2010

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# Linear Arithmetic

- Many approaches
  - Graph-based for difference logic:  $a - b \leq 3$
  - Fourier-Motzkin elimination:
$$t_1 \leq ax, bx \leq t_2 \Rightarrow bt_1 \leq at_2$$
  - Standard Simplex
  - **General Form Simplex**

# Difference Logic: $a - b \leq 5$

Very useful in practice!

Most arithmetical constraints in software verification/analysis are in this fragment.

$$x := x + 1$$



$$x_1 = x_0 + 1$$



$$x_1 - x_0 \leq 1, x_0 - x_1 \leq -1$$

# Job shop scheduling

$d_{i,j}$	Machine 1	Machine 2
Job 1	2	1
Job 2	3	1
Job 3	2	3

$max = 8$

## Solution

$t_{1,1} = 5, t_{1,2} = 7, t_{2,1} = 2,$   
 $t_{2,2} = 6, t_{3,1} = 0, t_{3,2} = 3$

## Encoding

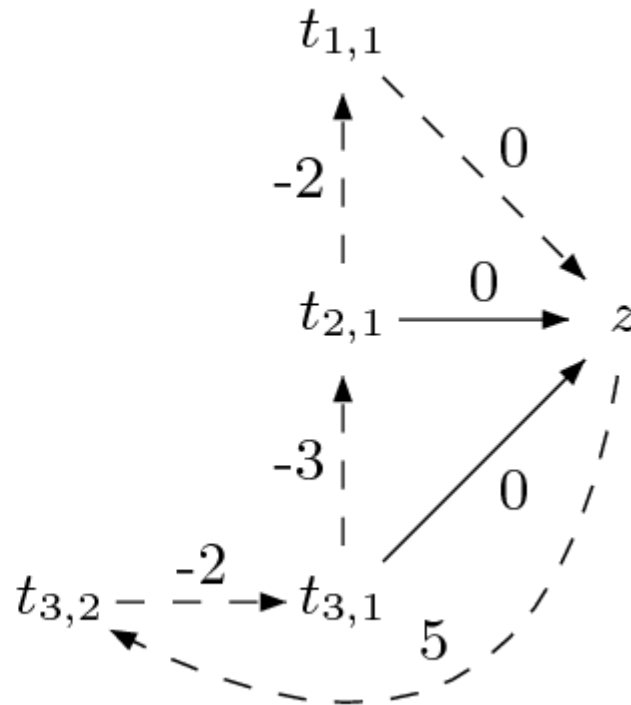
$(t_{1,1} \geq 0) \wedge (t_{1,2} \geq t_{1,1} + 2) \wedge (t_{1,2} + 1 \leq 8) \wedge$   
 $(t_{2,1} \geq 0) \wedge (t_{2,2} \geq t_{2,1} + 3) \wedge (t_{2,2} + 1 \leq 8) \wedge$   
 $(t_{3,1} \geq 0) \wedge (t_{3,2} \geq t_{3,1} + 2) \wedge (t_{3,2} + 3 \leq 8) \wedge$   
 $((t_{1,1} \geq t_{2,1} + 3) \vee (t_{2,1} \geq t_{1,1} + 2)) \wedge$   
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 $((t_{1,2} \geq t_{2,2} + 1) \vee (t_{2,2} \geq t_{1,2} + 1)) \wedge$   
 $((t_{1,2} \geq t_{3,2} + 3) \vee (t_{3,2} \geq t_{1,2} + 1)) \wedge$   
 $((t_{2,2} \geq t_{3,2} + 3) \vee (t_{3,2} \geq t_{2,2} + 1))$

# Difference Logic

Chasing negative cycles!

Algorithms based on Bellman-Ford ( $O(mn)$ ).

$$\begin{array}{rcll} z & - & t_{1,1} & \leq 0 \\ z & - & t_{2,1} & \leq 0 \\ z & - & t_{3,1} & \leq 0 \\ t_{3,2} & - & z & \leq 5 \\ t_{3,1} & - & t_{3,2} & \leq -2 \\ t_{2,1} & - & t_{3,1} & \leq -3 \\ t_{1,1} & - & t_{2,1} & \leq -2 \end{array}$$



# Standard Simplex

Many solvers (e.g., ICS, Simplify) are based on the Standard Simplex.

$$a - d + 2e = 3$$

$$b - d = 1$$

$$c + d - e = -1$$

$$a, b, c, d, e \geq 0$$

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$$\begin{pmatrix} 1 & 0 & 0 & -1 & 2 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \\ e \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

$$Ax = b \text{ and } x \geq 0.$$

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$$\begin{aligned}a - d + 2e &= 3 \\b - d &= 1 \\c + d - e &= -1 \\a, b, c, d, e &\geq 0\end{aligned}$$

We say  $a, b, c$  are the basic (or dependent) variables

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We say **d,e** are the non-basic (or non-dependent) variables.

$$Ax = b \text{ and } x \geq 0.$$

# Standard Simplex

- Incrementality: add/remove equations
- Slow backtracking
- No theory propagation

# Fast Linear Arithmetic

- Simplex General Form
- Algorithm based on the dual simplex
- Non redundant proofs
- Efficient backtracking
- Efficient theory propagation
- Support for string inequalities:  $t > 0$
- Preprocessing step
- Integer problems:
  - Gomory cuts, Branch & Bound, GCD test

# General Form

**General Form:**  $Ax = 0$  and  $l_j \leq x_j \leq u_j$

Example:

$$x \geq 0, (x + y \leq 2 \vee x + 2y \geq 6), (x + y = 2 \vee x + 2y > 4)$$

$\rightsquigarrow$

$$s_1 \equiv x + y, s_2 \equiv x + 2y,$$

$$x \geq 0, (s_1 \leq 2 \vee s_2 \geq 6), (s_1 = 2 \vee s_2 > 4)$$

Only **bounds** (e.g.,  $s_1 \leq 2$ ) are asserted during the search.

**Unconstrained variables** can be **eliminated** before the beginning of the search.

# From Definitions to a Tableau

$$s_1 \equiv x + y, \quad s_2 \equiv x + 2y$$

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$$s_2 = x + 2y$$



$$s_1 - x - y = 0$$

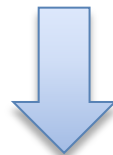
$$s_2 - x - 2y = 0$$

# From Definitions to a Tableau

$$s_1 \equiv x + y, \quad s_2 \equiv x + 2y$$



$$s_1 = x + y,$$
$$s_2 = x + 2y$$



$$s_1 - x - y = 0$$

$$s_2 - x - 2y = 0$$

$s_1, s_2$  are basic (dependent)

$x, y$  are non-basic



# Pivoting

A way to swap a basic with a non-basic variable!

It is just equational reasoning.

Key invariant: a basic variable occurs in only one equation.

Example: swap  $s_1$  and  $y$

$$s_1 - x - y = 0$$

$$s_2 - x - 2y = 0$$

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$$-s_1 + x + y = 0$$

$$s_2 - x - 2y = 0$$

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$$s_2 - x - 2y = 0$$



$$-s_1 + x + y = 0$$

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$$-s_1 + x + y = 0$$

$$s_2 - x - 2y = 0$$



$$-s_1 + x + y = 0$$

$$s_2 - 2s_1 + x = 0$$

It is just substituting equals by equals.

# Pivoting

## Definition:

An assignment (model) is a mapping from variables to values

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$$s_2 - x - 2y = 0$$



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## Key Property:

If an assignment satisfies the equations before a pivoting step, then it will also satisfy them after!

# Pivoting

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**A way to swap a basic with a non-basic variable!**

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Key invariant: a basic variable occurs in only one equation.

Example: swap  $s_2$  and  $y$

$$s_1 - x - y = 0$$

$$s_2 - x - 2y = 0$$



$$-s_1 + x + y = 0$$

$$s_2 - x - 2y = 0$$



$$-s_1 + x + y = 0$$

$$s_2 - 2s_1 + x = 0$$

## Example:

$$M(x) = 1$$

$$M(y) = 1$$

$$M(s_1) = 2$$

$$M(s_2) = 3$$

It is just substituting equals by equals.

## Key Property:

If an assignment satisfies the equations before a pivoting step, then it will also satisfy them after!

# Equations + Bounds + Assignment

An **assignment** (model) is a mapping from variables to values.

We maintain an **assignment** that satisfies all **equations** and **bounds**.

The assignment of non dependent variables implies the assignment of dependent variables.

**Equations + Bounds** can be used to derive **new bounds**.

Example:  $x = y - z, y \leq 2, z \geq 3 \rightsquigarrow x \leq -1$ .

The **new bound** may be inconsistent with the already known bounds.

Example:  $x \leq -1, x \geq 0$ .

# “Repairing Models”

If the assignment of a non-basic variable does not satisfy a bound, then fix it and propagate the change to all dependent variables.

$$a = c - d$$

$$b = c + d$$

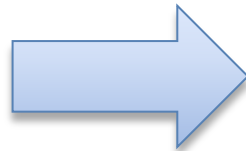
$$M(a) = 0$$

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$$M(c) = 0$$

$$M(d) = 0$$

$$1 \leq c$$



$$a = c - d$$

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$$M(a) = 1$$

$$M(b) = 1$$

$$M(c) = 1$$

$$M(d) = 0$$

$$1 \leq c$$



# “Repairing Models”

If the assignment of a non-basic variable does not satisfy a bound, then fix it and propagate the change to all dependent variables. **Of course, we may introduce new “problems”.**

$$a = c - d$$

$$b = c + d$$

$$M(a) = 0$$

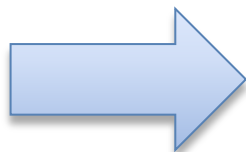
$$M(b) = 0$$

$$M(c) = 0$$

$$M(d) = 0$$

$$1 \leq c$$

$$a \leq 0$$



$$a = c - d$$

$$b = c + d$$

$$M(a) = 1$$

$$M(b) = 1$$

$$M(c) = 1$$

$$M(d) = 0$$

$$1 \leq c$$

$$a \leq 0$$

# “Repairing Models”

If the assignment of a basic variable does not satisfy a bound, then pivot it, fix it, and propagate the change to its new dependent variables.

$a = c - d$	$c = a + d$	$c = a + d$
$b = c + d$	$b = a + 2d$	$b = a + 2d$
$M(a) = 0$	$M(a) = 0$	$M(a) = 1$
$M(b) = 0$	$M(b) = 0$	$M(b) = 1$
$M(c) = 0$	$M(c) = 0$	$M(c) = 1$
$M(d) = 0$	$M(d) = 0$	$M(d) = 0$
$1 \leq a$	$1 \leq a$	$1 \leq a$

# “Repairing Models”

Sometimes, a model cannot be repaired. It is pointless to pivot.

$$a = b - c$$

$$a \leq 0, 1 \leq b, c \leq 0$$

$$M(a) = 1$$

$$M(b) = 1$$

$$M(c) = 0$$

The value of  $M(a)$  is too big. We can reduce it by:

- reducing  $M(b)$

  - not possible  $b$  is at lower bound

- increasing  $M(c)$

  - not possible  $c$  is at upper bound

# “Repairing Models”

Extracting proof from failed repair attempts is easy.

$$s_1 \equiv a + d, s_2 \equiv c + d$$

$$a = s_1 - s_2 + c$$

$$a \leq 0, 1 \leq s_1, s_2 \leq 0, 0 \leq c$$

$$M(a) = 1$$

$$M(s_1) = 1$$

$$M(s_2) = 0$$

$$M(c) = 0$$

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$$s_1 \equiv a + d, s_2 \equiv c + d$$

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$$a \leq 0, 1 \leq s_1, s_2 \leq 0, 0 \leq c$$

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$\{ a \leq 0, 1 \leq s_1, s_2 \leq 0, 0 \leq c \}$  is inconsistent

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$\{ a \leq 0, 1 \leq s_1, s_2 \leq 0, 0 \leq c \}$  is inconsistent

$\{ a \leq 0, 1 \leq a + d, c + d \leq 0, 0 \leq c \}$  is inconsistent

# Strict Inequalities

The method described only handles non-strict inequalities (e.g.,  $x \leq 2$ ).

For integer problems, strict inequalities can be converted into non-strict inequalities.  $x < 1 \rightsquigarrow x \leq 0$ .

For rational/real problems, strict inequalities can be converted into non-strict inequalities using a small  $\delta$ .  $x < 1 \rightsquigarrow x \leq 1 - \delta$ .

We do not compute a  $\delta$ , **we treat it symbolically**.

**$\delta$  is an infinitesimal parameter:**  $(c, k) = c + k\delta$

# Example

► Initial state

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	
$M(y) = 0$	$u = x + 2y$	
$M(s) = 0$	$v = x - y$	
$M(u) = 0$		
$M(v) = 0$		



# Example

▶ Asserting  $s \geq 1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	
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$M(s) = 0$	$v = x - y$	
$M(u) = 0$		
$M(v) = 0$		

# Example

- ▶ Asserting  $s \geq 1$  assignment does not satisfy new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 0$	$u = x + 2y$	
$M(s) = 0$	$v = x - y$	
$M(u) = 0$		
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# Example

- ▶ Asserting  $s \geq 1$  pivot  $s$  and  $x$  ( $s$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

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$M(x) = 0$	$s = x + y$	$s \geq 1$
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Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = x + 2y$	
$M(s) = 0$	$v = x - y$	
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$M(x) = 0$	$x = s - y$	$s \geq 1$
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$M(s) = 0$	$v = s - 2y$	
$M(u) = 0$		
$M(v) = 0$		

# Example

- ▶ Asserting  $s \geq 1$  update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = s + y$	
$M(s) = 1$	$v = s - 2y$	
$M(u) = 0$		
$M(v) = 0$		

# Example

- ▶ Asserting  $s \geq 1$  update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = s + y$	
$M(s) = 1$	$v = s - 2y$	
$M(u) = 1$		
$M(v) = 1$		

# Example

► Asserting  $x \geq 0$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
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$M(s) = 1$	$v = s - 2y$	
$M(u) = 1$		
$M(v) = 1$		



# Example

- ▶ Asserting  $x \geq 0$  assignment satisfies new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	
$M(u) = 1$		
$M(v) = 1$		

# Example

► Case split  $\neg y \leq 1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/>
$M(u) = 1$		
$M(v) = 1$		

# Example

- ▶ Case split  $\neg y \leq 1$  assignment does not satisfies new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
$M(y) = 0$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y > 1$
$M(u) = 1$		
$M(v) = 1$		

# Example

- ▶ Case split  $\neg y \leq 1$  update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = s - y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y > 1$
$M(u) = 1$		
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# Example

- ▶ Case split  $\neg y \leq 1$  update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
$M(x)$	$= -\delta$	$x = s - y$	$s \geq 1$
$M(y)$	$= 1 + \delta$	$u = s + y$	$x \geq 0$
$M(s)$	$= 1$	$v = s - 2y$	<hr/> $y > 1$
$M(u)$	$= 2 + \delta$		
$M(v)$	$= -1 - 2\delta$		

# Example

► Bound violation

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
$M(x)$	$= -\delta$	$x = s - y$	$s \geq 1$
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$M(v)$	$= -1 - 2\delta$		

# Example

- ▶ Bound violation pivot  $x$  and  $s$  ( $x$  is a dependent variables).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
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$M(v)$	$= -1 - 2\delta$		



# Example

- ▶ Bound violation pivot  $x$  and  $s$  ( $x$  is a dependent variables).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
$M(x)$	$= -\delta$	$s = x + y$	$s \geq 1$
$M(y)$	$= 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s)$	$= 1$	$v = x - y$	<hr/> $y > 1$
$M(u)$	$= 2 + \delta$		
$M(v)$	$= -1 - 2\delta$		

# Example

- ▶ Bound violation update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
$M(x)$	$= 0$	$s = x + y$	$s \geq 1$
$M(y)$	$= 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s)$	$= 1$	$v = x - y$	<hr/> $y > 1$
$M(u)$	$= 2 + \delta$		
$M(v)$	$= -1 - 2\delta$		

# Example

- ▶ Bound violation update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		
$M(v) = -1 - \delta$		

# Example

► Theory propagation  $x \geq 0, y > 1 \rightsquigarrow u > 2$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		
$M(v) = -1 - \delta$		

# Example

► Theory propagation  $u > 2 \rightsquigarrow \neg u \leq -1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		$u > 2$
$M(v) = -1 - \delta$		

# Example

► Boolean propagation  $\neg y \leq 1 \rightsquigarrow v \geq 2$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		$u > 2$
$M(v) = -1 - \delta$		

# Example

► Theory propagation  $v \geq 2 \rightsquigarrow \neg v \leq -2$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		$u > 2$
$M(v) = -1 - \delta$		

# Example

► Conflict empty clause

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y > 1$
$M(u) = 2 + 2\delta$		$u > 2$
$M(v) = -1 - \delta$		



# Example

► Backtracking

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/>
$M(u) = 2 + 2\delta$		
$M(v) = -1 - \delta$		

# Example

► Asserting  $y \leq 1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

	Model	Equations	Bounds
$M(x)$	$= 0$	$s = x + y$	$s \geq 1$
$M(y)$	$= 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s)$	$= 1 + \delta$	$v = x - y$	<hr/>
$M(u)$	$= 2 + 2\delta$		
$M(v)$	$= -1 - \delta$		

# Example

- ▶ Asserting  $y \leq 1$  assignment does not satisfy new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1 + \delta$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y \leq 1$
$M(u) = 2 + 2\delta$		
$M(v) = -1 - \delta$		

# Example

- ▶ Asserting  $y \leq 1$  update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1$	$u = x + 2y$	$x \geq 0$
$M(s) = 1 + \delta$	$v = x - y$	<hr/> $y \leq 1$
$M(u) = 2 + 2\delta$		
$M(v) = -1 - \delta$		

# Example

- ▶ Asserting  $y \leq 1$  update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$s = x + y$	$s \geq 1$
$M(y) = 1$	$u = x + 2y$	$x \geq 0$
$M(s) = 1$	$v = x - y$	<hr/> $y \leq 1$
$M(u) = 2$		
$M(v) = -1$		

# Example

► Theory propagation  $s \geq 1, y \leq 1 \rightsquigarrow v \geq -1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y \leq 1$
$M(u) = 2$		
$M(v) = -1$		

# Example

► Theory propagation  $v \geq -1 \rightsquigarrow \neg v \leq -2$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq -1$
$M(v) = -1$		

# Example

► Boolean propagation  $\neg v \leq -2 \rightsquigarrow v \geq 0$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq -1$
$M(v) = -1$		



# Example

- ▶ Bound violation assignment does not satisfy new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq 0$
$M(v) = -1$		

# Example

- ▶ Bound violation pivot  $u$  and  $s$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$v = s - 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq 0$
$M(v) = -1$		

# Example

- ▶ Bound violation pivot  $u$  and  $s$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = s - y$	$s \geq 1$
$M(y) = 1$	$u = s + y$	$x \geq 0$
$M(s) = 1$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq 0$
$M(v) = -1$		

# Example

- ▶ Bound violation pivot  $u$  and  $s$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 1$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq 0$
$M(v) = -1$		

# Example

- ▶ Bound violation    update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 0$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 1$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 2$		$v \geq 0$
$M(v) = 0$		

# Example

- ▶ Bound violation    update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 2$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 3$		$v \geq 0$
$M(v) = 0$		

# Example

► Boolean propagation  $\neg v \leq -2 \rightsquigarrow u \leq -1$

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 2$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 3$		$v \geq 0$
$M(v) = 0$		

# Example

- ▶ Bound violation assignment does not satisfy new bound.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 2$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 3$		$v \geq 0$
$M(v) = 0$		$u \leq -1$



# Example

- ▶ Bound violation pivot  $u$  and  $y$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$u = v + 3y$	$x \geq 0$
$M(s) = 2$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 3$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violation pivot  $u$  and  $y$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = v + y$	$s \geq 1$
$M(y) = 1$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = 2$	$s = v + 2y$	<hr/> $y \leq 1$
$M(u) = 3$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violation pivot  $u$  and  $y$  ( $u$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = 1$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = 2$	$s = \frac{2}{3}u + \frac{1}{3}v$	<hr/>
$M(u) = 3$		$y \leq 1$
$M(v) = 0$		$v \geq 0$
		$u \leq -1$

# Example

- ▶ Bound violation    update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 1$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = 1$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = 2$	$s = \frac{2}{3}u + \frac{1}{3}v$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violation    update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = -\frac{2}{3}$	$s = \frac{2}{3}u + \frac{1}{3}v$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

► Bound violations

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = -\frac{2}{3}$	$s = \frac{2}{3}u + \frac{1}{3}v$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violations pivot  $s$  and  $v$  ( $s$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = -\frac{2}{3}$	$s = \frac{2}{3}u + \frac{1}{3}v$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violations pivot  $s$  and  $v$  ( $s$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = \frac{1}{3}u + \frac{2}{3}v$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = \frac{1}{3}u - \frac{1}{3}v$	$x \geq 0$
$M(s) = -\frac{2}{3}$	$v = 3s - 2u$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$



# Example

- ▶ Bound violations pivot  $s$  and  $v$  ( $s$  is a dependent variable).

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = 2s - u$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = -s + u$	$x \geq 0$
$M(s) = -\frac{2}{3}$	$v = 3s - 2u$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violations update assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = -\frac{1}{3}$	$x = 2s - u$	$s \geq 1$
$M(y) = -\frac{1}{3}$	$y = -s + u$	$x \geq 0$
$M(s) = 1$	$v = 3s - 2u$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 0$		$u \leq -1$

# Example

- ▶ Bound violations update dependent variables assignment.

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 3$	$x = 2s - u$	$s \geq 1$
$M(y) = -2$	$y = -s + u$	$x \geq 0$
$M(s) = 1$	$v = 3s - 2u$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 5$		$u \leq -1$

# Example

- ▶ Found satisfying assignment

$$s \geq 1, x \geq 0$$

$$(y \leq 1 \vee v \geq 2), (v \leq -2 \vee v \geq 0), (v \leq -2 \vee u \leq -1)$$

Model	Equations	Bounds
$M(x) = 3$	$x = 2s - u$	$s \geq 1$
$M(y) = -2$	$y = -s + u$	$x \geq 0$
$M(s) = 1$	$v = 3s - 2u$	<hr/> $y \leq 1$
$M(u) = -1$		$v \geq 0$
$M(v) = 5$		$u \leq -1$

# Correctness

**Completeness:** trivial

**Soundness:** also trivial

**Termination:** non trivial.

We cannot choose arbitrary variable to pivot.

Assume the variables are ordered.

Bland's rule: select the smallest basic variable **c** that does not satisfy its bounds, then select the smallest non-basic in the row of **c** that can be used for pivoting.

**Too technical.**

Uses the fact that a tableau has a finite number of configurations. Then, any infinite trace will have cycles.

# Data-structures

Array of rows (equations).

Each row is a dynamic array of tuples:

(coefficient, variable, pos\_in\_occs, is\_dead)

Each variable  $x$  has a “set” (dynamic array) of occurrences:

(row\_idx, pos\_in\_row, is\_dead)

Each variable  $x$  has a “field”  $\text{row}[x]$

$\text{row}[x]$  is -1 if  $x$  is non basic

otherwise,  $\text{row}[x]$  contains the idx of the row containing  $x$

Each variable  $x$  has “fields”:  $\text{lower}[x]$ ,  $\text{upper}[x]$ , and  $\text{value}[x]$

# Data-structures

**rows**: array of rows (equations).

Each row is a dynamic array of tuples:

(coefficient, variable, pos\_in\_occs, is\_dead)

**occs[x]**: Each variable  $x$  has a “set” (dynamic array) of occurrences:

(row\_idx, pos\_in\_row, is\_dead)

**row[x]**:

row[x] is -1 if  $x$  is non basic

otherwise, row[x] contains the idx of the row containing  $x$

Other “fields”: **lower[x]**, **upper[x]**, and **value[x]**

**atoms[x]**: atoms (assigned/unassigned) that contains  $x$

# Data-structures

$$s_1 \equiv a + b, s_2 \equiv c - b$$

$$p_1 \equiv a \leq 0, p_2 \equiv 1 \leq s_1, p_3 \equiv 1 \leq s_2$$

$p_1, p_2$  were already assigned

$$a - s_1 + s_2 + c = 0$$

$$b - c + s_2 = 0$$

$$a \leq 0, 1 \leq s_1$$

$$M(a) = 0 \quad \text{value}[a] = 0$$

$$M(b) = -1 \quad \text{value}[a] = -1$$

$$M(c) = 0 \quad \text{value}[c] = 0$$

$$M(s_1) = 1 \quad \text{value}[s_1] = 1$$

$$M(s_2) = 1 \quad \text{value}[s_2] = 1$$

```
rows = [  
    [(1, a, 0, t), (-1, s1, 0, t), (1, s2, 1, t), (1, c, 0, t)],  
    [(1, b, 0, t), (-1, c, 1, t), (1, s2, 2, t)] ]
```

```
occs[a] = [(0, 0, f)]
```

```
occs[b] = [(1, 0, f)]
```

```
occs[c] = [(0, 3, f), (1, 1, f)]
```

```
occs[s1] = [(0, 1, f)]
```

```
occs[s2] = [(0, 0, t), (0, 2, f), (1, 2, f)]
```

```
row[a] = 0, row[b] = 1, row[c] = -1, ...
```

```
upper[a] = 0, lower[s1] = 1
```

```
atoms[a] = {p1}, atoms[s1] = {p2}, ...
```



# Combining Theories

In practice, we need a combination of theories.

$b + 2 = c$  and  $f(\text{read}(\text{write}(a,b,3), c-2)) \neq f(c-b+1)$

A theory is a set (potentially infinite) of first-order sentences.

**Main questions:**

Is the union of two theories  $T1 \cup T2$  consistent?

Given a solvers for  $T1$  and  $T2$ , how can we build a solver for  $T1 \cup T2$ ?

# Disjoint Theories

Two theories are disjoint if they do not share function/constant and predicate symbols.

= is the only exception.

Example:

The theories of arithmetic and arrays are disjoint.

Arithmetic symbols:  $\{0, -1, 1, -2, 2, \dots, +, -, *, >, <, \geq, \leq\}$

Array symbols:  $\{\text{read}, \text{write}\}$

# Purification

It is a different name for our “naming” subterms procedure.

$b + 2 = c, f(\text{read}(\text{write}(a,b,3), c-2)) \neq f(c-b+1)$



$b + 2 = c, v_6 \neq v_7$

$v_1 \equiv 3, v_2 \equiv \text{write}(a, b, v_1), v_3 \equiv c-2, v_4 \equiv \text{read}(v_2, v_3),$

$v_5 \equiv c-b+1, v_6 \equiv f(v_4), v_7 \equiv f(v_5)$

# Purification

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$$v_5 \equiv c-b+1, v_6 \equiv f(v_4), v_7 \equiv f(v_5)$$



$$b + 2 = c, v_1 \equiv 3, v_3 \equiv c-2, v_5 \equiv c-b+1,$$

$$v_2 \equiv \text{write}(a, b, v_1), v_4 \equiv \text{read}(v_2, v_3),$$

$$v_6 \equiv f(v_4), v_7 \equiv f(v_5), v_6 \neq v_7$$

# Stably Infinite Theories

A theory is stably infinite if every satisfiable QFF is satisfiable in an infinite model.

EUF and arithmetic are stably infinite.

Bit-vectors are not.

# Important Result

**The union of two consistent, disjoint, stably infinite theories is consistent.**

# Convexity

A theory  $T$  is **convex** iff

for all finite sets  $S$  of literals and

for all  $a_1 = b_1 \vee \dots \vee a_n = b_n$

$S$  implies  $a_1 = b_1 \vee \dots \vee a_n = b_n$

iff

$S$  implies  $a_i = b_i$  for some  $1 \leq i \leq n$

# Convexity: Results

Every convex theory with non trivial models is stably infinite.

All **Horn equational** theories are convex.

formulas of the form  $s_1 \neq r_1 \vee \dots \vee s_n \neq r_n \vee t = t'$

**Linear rational arithmetic** is convex.



# Convexity: Negative Results

Linear integer arithmetic is not convex

$$1 \leq a \leq 2, b = 1, c = 2 \text{ implies } a = b \vee a = c$$

Nonlinear arithmetic

$$a^2 = 1, b = 1, c = -1 \text{ implies } a = b \vee a = c$$

Theory of bit-vectors

Theory of arrays

$$c_1 = \text{read}(\text{write}(a, i, c_2), j), c_3 = \text{read}(a, j) \\ \text{implies } c_1 = c_2 \vee c_1 = c_3$$

# Combination of non-convex theories

EUF is convex ( $O(n \log n)$ )

IDL is non-convex ( $O(nm)$ )

**EUF  $\cup$  IDL is NP-Complete**

Reduce 3CNF to **EUF  $\cup$  IDL**

For each boolean variable  $p_i$  add  $0 \leq a_i \leq 1$

For each clause  $p_1 \vee \neg p_2 \vee p_3$  add

$$f(a_1, a_2, a_3) \neq f(0, 1, 0)$$

# Combination of non-convex theories

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For each boolean variable  $p_i$  add  $0 \leq a_i \leq 1$

For each clause  $p_1 \vee \neg p_2 \vee p_3$  add

$$f(a_1, a_2, a_3) \neq f(0, 1, 0)$$



implies

$$a_1 \neq 0 \vee a_2 \neq 1 \vee a_3 \neq 0$$

# Nelson-Oppen Combination

Let  $\mathcal{T}_1$  and  $\mathcal{T}_2$  be consistent, stably infinite theories over disjoint (countable) signatures. Assume satisfiability of conjunction of literals can be decided in  $O(T_1(n))$  and  $O(T_2(n))$  time respectively. Then,

1. The combined theory  $\mathcal{T}$  is consistent and stably infinite.
2. Satisfiability of quantifier free conjunction of literals in  $\mathcal{T}$  can be decided in  $O(2^{n^2} \times (T_1(n) + T_2(n)))$ .
3. If  $\mathcal{T}_1$  and  $\mathcal{T}_2$  are convex, then so is  $\mathcal{T}$  and satisfiability in  $\mathcal{T}$  is in  $O(n^3 \times (T_1(n) + T_2(n)))$ .

# Nelson-Oppen Combination

The combination procedure:

**Initial State:**  $\phi$  is a conjunction of literals over  $\Sigma_1 \cup \Sigma_2$ .

**Purification:** Preserving satisfiability transform  $\phi$  into  $\phi_1 \wedge \phi_2$ ,  
such that,  $\phi_i \in \Sigma_i$ .

**Interaction:** Guess a partition of  $\mathcal{V}(\phi_1) \cap \mathcal{V}(\phi_2)$  into disjoint  
subsets. Express it as conjunction of literals  $\psi$ .

Example. The partition  $\{x_1\}, \{x_2, x_3\}, \{x_4\}$  is represented  
as  $x_1 \neq x_2, x_1 \neq x_4, x_2 \neq x_4, x_2 = x_3$ .

**Component Procedures** : Use individual procedures to decide  
whether  $\phi_i \wedge \psi$  is satisfiable.

**Return:** If both return yes, return yes. No, otherwise.

# Soundness

Each step is satisfiability preserving.

Say  $\phi$  is satisfiable (in the combination).

- ▶ Purification:  $\phi_1 \wedge \phi_2$  is satisfiable.
- ▶ Iteration: for some partition  $\psi$ ,  $\phi_1 \wedge \phi_2 \wedge \psi$  is satisfiable.
- ▶ Component procedures:  $\phi_1 \wedge \psi$  and  $\phi_2 \wedge \psi$  are both satisfiable in component theories.
- ▶ Therefore, if the procedure return unsatisfiable, then  $\phi$  is unsatisfiable.

# Completeness

Suppose the procedure returns satisfiable.

- ▶ Let  $\psi$  be the partition and  $A$  and  $B$  be models of  $\mathcal{T}_1 \wedge \phi_1 \wedge \psi$  and  $\mathcal{T}_2 \wedge \phi_2 \wedge \psi$ .
- ▶ The component theories are stably infinite. So, assume the models are infinite (of same cardinality).
- ▶ Let  $h$  be a bijection between  $|A|$  and  $|B|$  such that  $h(A(x)) = B(x)$  for each shared variable.
- ▶ Extend  $B$  to  $\bar{B}$  by interpretations of symbols in  $\Sigma_1$ :  
$$\bar{B}(f)(b_1, \dots, b_n) = h(A(f)(h^{-1}(b_1), \dots, h^{-1}(b_n)))$$
- ▶  $\bar{B}$  is a model of:  
$$\mathcal{T}_1 \wedge \phi_1 \wedge \mathcal{T}_2 \wedge \phi_2 \wedge \psi$$

# NO deterministic procedure (for convex theories)

Instead of **guessing**, we can **deduce** the equalities to be shared.

**Purification:** no changes.

**Interaction:** Deduce an equality  $x = y$ :

$$\mathcal{T}_1 \vdash (\phi_1 \Rightarrow x = y)$$

Update  $\phi_2 := \phi_2 \wedge x = y$ . And vice-versa. Repeat until no further changes.

**Component Procedures** : Use individual procedures to decide whether  $\phi_i$  is satisfiable.

Remark:  $\mathcal{T}_i \vdash (\phi_i \Rightarrow x = y)$  iff  $\phi_i \wedge x \neq y$  is not satisfiable in  $\mathcal{T}_i$ .



# NO deterministic procedure

## Completeness

Assume the theories are convex.

- ▶ Suppose  $\phi_i$  is satisfiable.
- ▶ Let  $E$  be the set of equalities  $x_j = x_k$  ( $j \neq k$ ) such that,  $\mathcal{T}_i \not\vdash \phi_i \Rightarrow x_j = x_k$ .
- ▶ By convexity,  $\mathcal{T}_i \not\vdash \phi_i \Rightarrow \bigvee_E x_j = x_k$ .
- ▶  $\phi_i \wedge \bigwedge_E x_j \neq x_k$  is satisfiable.
- ▶ The proof now is identical to the nondeterministic case.
- ▶ Sharing equalities is sufficient, because a theory  $\mathcal{T}_1$  can assume that  $x^B \neq y^B$  whenever  $x = y$  is not implied by  $\mathcal{T}_2$  and vice versa.

# NO procedure: Example

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$$

## Arithmetic

$$b + 2 = c,$$

$$v_1 \equiv 3,$$

$$v_3 \equiv c-2,$$

$$v_5 \equiv c-b+1$$

## Arrays

$$v_2 \equiv \text{write}(a, b, v_1),$$

$$v_4 \equiv \text{read}(v_2, v_3)$$

## EUUF

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$v_6 \neq v_7$$

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EUUF

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$v_6 \neq v_7$$

Substituting  $c$

# NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7$

Propagating  $v_3 = b$

# NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3$

Arrays

$\mathbf{v}_2 \equiv \text{write}(a, \mathbf{b}, v_1),$

$v_4 \equiv \text{read}(\mathbf{v}_2, \mathbf{v}_3),$

$v_3 = b$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b$

Deducing  $v_4 = v_1$

# NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

$v_3 = b,$

**$v_4 = v_1$**

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b$

Propagating  $v_4 = v_1$

# NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3,$

$v_4 = v_1$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

$v_3 = b,$

$v_4 = v_1$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b,$

$v_4 = v_1$

Propagating  $v_5 = v_1$

# NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3,$

$v_4 = v_1$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

$v_3 = b,$

$v_4 = v_1$

EUf

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b,$

$v_4 = v_1,$

$v_5 = v_1$

Congruence:  $v_6 = v_7$



# NO procedure: Example

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$$

## Arithmetic

$$b + 2 = c,$$

$$v_1 \equiv 3,$$

$$v_3 \equiv b,$$

$$v_5 \equiv 3,$$

$$v_4 = v_1$$

Unsatisfiable

## Arrays

$$v_2 \equiv \text{write}(a, b, v_1),$$

$$v_4 \equiv \text{read}(v_2, v_3),$$

$$v_3 = b,$$

$$v_4 = v_1$$

## EUUF

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$\mathbf{v_6 \neq v_7},$$

$$v_3 = b,$$

$$v_4 = v_1,$$

$$v_5 = v_1,$$

$$\mathbf{v_6 = v_7}$$

# NO deterministic procedure

Deterministic procedure may **fail** for non-convex theories.

$$0 \leq a \leq 1, 0 \leq b \leq 1, 0 \leq c \leq 1,$$

$$f(a) \neq f(b),$$

$$f(a) \neq f(c),$$

$$f(b) \neq f(c)$$

# Combining Procedures in Practice

## Propagate all implied equalities.

- ▶ Deterministic Nelson-Oppen.
- ▶ Complete only for convex theories.
- ▶ It may be expensive for some theories.

## Delayed Theory Combination.

- ▶ Nondeterministic Nelson-Oppen.
- ▶ Create set of interface equalities ( $x = y$ ) between shared variables.
- ▶ Use SAT solver to guess the partition.
- ▶ Disadvantage: the number of additional equality literals is quadratic in the number of shared variables.

# Combining Procedures in Practice

Common to these methods is that they are **pessimistic** about which equalities are propagated.

## Model-based Theory Combination

- ▶ **Optimistic approach.**
- ▶ Use a candidate model  $M_i$  for one of the theories  $\mathcal{T}_i$  and propagate all equalities implied by the candidate model, hedging that other theories will agree.

**if**  $M_i \models \mathcal{T}_i \cup \Gamma_i \cup \{u = v\}$  **then** propagate  $u = v$  .

- ▶ If not, use backtracking to fix the model.
- ▶ It is cheaper to enumerate equalities that are implied in a particular model than of all models.

# Example

$$x = f(y - 1), f(x) \neq f(y), 0 \leq x \leq 1, 0 \leq y \leq 1$$

Purifying

# Example

$$x = f(z), f(x) \neq f(y), 0 \leq x \leq 1, 0 \leq y \leq 1, z = y - 1$$

# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *2$	$0 \leq y \leq 1$	$A(y) = 0$
	$\{z\}$	$E(z) = *3$	$z = y - 1$	$A(z) = -1$
	$\{f(x)\}$	$E(f) = \{ *1 \mapsto *4,$		
	$\{f(y)\}$		$*2 \mapsto *5,$	
		$*3 \mapsto *1,$		
		$else \mapsto *6 \}$		

Assume  $x = y$

# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, y, f(z)\}$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{z\}$	$E(y) = *_1$	$0 \leq y \leq 1$	$A(y) = 0$
$x = y$	$\{f(x), f(y)\}$	$E(z) = *_2$	$z = y - 1$	$A(z) = -1$
		$E(f) = \{*_1 \mapsto *_3,$	$x = y$	
		$*_2 \mapsto *_1,$		
		$\text{else} \mapsto *_4\}$		

Unsatisfiable



# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *2$	$0 \leq y \leq 1$	$A(y) = 0$
$x \neq y$	$\{z\}$	$E(z) = *3$	$z = y - 1$	$A(z) = -1$
	$\{f(x)\}$	$E(f) = \{ *1 \mapsto *4,$	$x \neq y$	
	$\{f(y)\}$	$*2 \mapsto *5,$		
		$*3 \mapsto *1,$		
		$else \mapsto *6 \}$		

Backtrack, and assert  $x \neq y$ .

$\mathcal{T}_A$  model need to be fixed.

# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{z\}$	$E(z) = *3$	$z = y - 1$	$A(z) = 0$
	$\{f(x)\}$	$E(f) = \{*1 \mapsto *4,$	$x \neq y$	
	$\{f(y)\}$	$*2 \mapsto *5,$		
		$*3 \mapsto *1,$		
		$else \mapsto *6\}$		

Assume  $x = z$

# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
<i>Literals</i>	<i>Eq. Classes</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$\{x, z, f(x), f(z)\}$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$		$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{y\}$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$\{f(y)\}$	$E(f) = \{*_1 \mapsto *_1, *_2 \mapsto *_3, \text{else} \mapsto *_4\}$	$x \neq y$	$x = z$

Satisfiable

# Example

$\mathcal{T}_E$			$\mathcal{T}_A$	
<i>Literals</i>	<i>Eq. Classes</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$\{x, z,$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$f(x), f(z)\}$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{y\}$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$\{f(y)\}$	$E(f) = \{*_1 \mapsto *_1,$	$x \neq y$	
		$*_2 \mapsto *_3,$	$x = z$	
		$else \mapsto *_4\}$		

Let  $h$  be the bijection between  $|E|$  and  $|A|$ .

$$h = \{*_1 \mapsto 0, *_2 \mapsto 1, *_3 \mapsto -1, *_4 \mapsto 2, \dots\}$$

# Example

$\mathcal{T}_E$		$\mathcal{T}_A$	
<i>Literals</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$E(f) = \{*_1 \mapsto *_1,$ $*_2 \mapsto *_3,$ $\text{else} \mapsto *_4\}$	$x \neq y$	$A(f) = \{0 \mapsto 0$ $1 \mapsto -1$ $\text{else} \mapsto 2\}$

Extending  $A$  using  $h$ .

$$h = \{*_1 \mapsto 0, *_2 \mapsto 1, *_3 \mapsto -1, *_4 \mapsto 2, \dots\}$$

# Model Mutation

Sometimes  $M(x) = M(y)$  by accident.

$$\bigwedge_{i=1}^N f(x_i) \geq 0 \wedge x_i \geq 0$$

**Model mutation:** diversify the current model.

# Freedom Intervals

## Model mutation without pivoting

For each non basic variable  $x_j$  compute  $[L_j, U_j]$

Each row containing  $x_j$  enforces a limit on how much it can be increase and/or decreased without violating the bounds of the basic variable in the row.

# Opportunistic Equality Propagation

We say a variable is fixed if the lower and upper bound are the same.

$$1 \leq x \leq 1$$

A polynomial  $P$  is fixed if all its variables are fixed.

Given a fixed polynomial  $P$  of the form  $2x_1 + x_2$ ,  
we use  $M(P)$  to denote  $2M(x_1) + M(x_2)$



# Opportunistic Equality Propagation

FixedEq

$$l_i \leq x_i \leq u_i, \quad l_j \leq x_j \leq u_j \implies x_i = x_j \quad \text{if} \quad l_i = u_i = l_j = u_j$$

EqRow

$$x_i = x_j + P \implies x_i = x_j \quad \text{if} \quad P \text{ is fixed, and } M(P) = 0$$

EqOffsetRows

$$\begin{array}{l} x_i = x_k + P_1 \\ x_j = x_k + P_2 \end{array} \implies x_i = x_j \quad \text{if} \quad \left\{ \begin{array}{l} P_1 \text{ and } P_2 \text{ are fixed, and} \\ M(P_1) = M(P_2) \end{array} \right.$$

EqRows

$$\begin{array}{l} x_i = P + P_1 \\ x_j = P + P_2 \end{array} \implies x_i = x_j \quad \text{if} \quad \left\{ \begin{array}{l} P_1 \text{ and } P_2 \text{ are fixed, and} \\ M(P_1) = M(P_2) \end{array} \right.$$

# Non-stably infinite theories in practice

Bit-vector theory is not stably-infinite.

How can we support it?

**Solution:** add a predicate  $is-bv(x)$  to the bit-vector theory (intuition:  $is-bv(x)$  is true iff  $x$  is a bitvector).

The result of the bit-vector operation  $op(x, y)$  is not specified if  $\neg is-bv(x)$  or  $\neg is-bv(y)$ .

**The new bit-vector theory is stably-infinite.**

# Reduction Functions

A **reduction function** reduces the satisfiability problem for a complex theory into the satisfiability problem of a simpler theory.

Ackermannization is a reduction function.

# Reduction Functions

Theory of commutative functions.

- ▶  $\forall x, y. f(x, y) = f(y, x)$
- ▶ Reduction to EUF
- ▶ For every  $f(a, b)$  in  $\phi$ , do  $\phi := \phi \wedge f(a, b) = f(b, a)$ .