# When do Best Response Dynamics Converge? 

Aaron Roth

University of Pennsylvania

January 302024

## Overview

- We know best response dynamics (BRD) converges in congestion games.


## Overview

- We know best response dynamics (BRD) converges in congestion games.
- Is that it? How much further can we push it?


## Overview

- We know best response dynamics (BRD) converges in congestion games.
- Is that it? How much further can we push it?
- Today: study a couple more games in which BRD converges, and try to abstract what is needed.


## Overview

- We know best response dynamics (BRD) converges in congestion games.
- Is that it? How much further can we push it?
- Today: study a couple more games in which BRD converges, and try to abstract what is needed.
- Characterize exactly when BRD is guaranteed to converge.


## Load Balancing Games on Identical Machines

## Definition

A load balancing game on identical machines models $n$ players $i \in P$ scheduling jobs of size $w_{i}>0$ on $m$ identical machines $F$.
The game has:

1. Action space $A_{i}=F$ for each player
2. For each machine $j \in F$, a load $\ell_{j}(a)=\sum_{i: a_{i}=j} w_{i}$

The cost of player $i$ is the load of the machine he plays on: $c_{i}(a)=\ell_{a_{i}}(a)$.

## Load Balancing Games on Identical Machines

## Definition

A load balancing game on identical machines models $n$ players $i \in P$ scheduling jobs of size $w_{i}>0$ on $m$ identical machines $F$.
The game has:

1. Action space $A_{i}=F$ for each player
2. For each machine $j \in F$, a load $\ell_{j}(a)=\sum_{i: a_{i}=j} w_{i}$

The cost of player $i$ is the load of the machine he plays on: $c_{i}(a)=\ell_{a_{i}}(a)$.

Almost a congestion game - but facility costs depend on which players are using them.

## Load Balancing Games on Identical Machines

## Load Balancing Games on Identical Machines

Theorem
Best response dynamics converge in load balancing games on identical machines.

## Load Balancing Games on Identical Machines

Theorem
Best response dynamics converge in load balancing games on identical machines.

Corollary
Load balancing games on identical machines have pure strategy Nash equilibria

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\Delta c_{i}(a) \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right)
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a)
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\Delta \phi(a) \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right)
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right)
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right) \\
& =\frac{1}{2}\left(2 w_{i} \ell_{j^{\prime}}(a)+w_{i}^{2}-2 w_{i} \ell_{j}(a)+w_{i}^{2}\right)
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right) \\
& =\frac{1}{2}\left(2 w_{i} \ell_{j^{\prime}}(a)+w_{i}^{2}-2 w_{i} \ell_{j}(a)+w_{i}^{2}\right) \\
& =w_{i}\left(\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a)\right)
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right) \\
& =\frac{1}{2}\left(2 w_{i} \ell_{j^{\prime}}(a)+w_{i}^{2}-2 w_{i} \ell_{j}(a)+w_{i}^{2}\right) \\
& =w_{i}\left(\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a)\right) \\
& =w_{i} \cdot \Delta c_{i}(a)
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right) \\
& =\frac{1}{2}\left(2 w_{i} \ell_{j^{\prime}}(a)+w_{i}^{2}-2 w_{i} \ell_{j}(a)+w_{i}^{2}\right) \\
& =w_{i}\left(\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a)\right) \\
& =w_{i} \cdot \Delta c_{i}(a) \\
& <0
\end{aligned}
$$

## Proof

Define $\phi(a)=\frac{1}{2} \sum_{j=1}^{m} \ell_{j}(a)^{2}$. Suppose player $i$ switches from machine $j$ to machine $j^{\prime}$. Then we have:

$$
\begin{aligned}
\Delta c_{i}(a) & \equiv c_{i}\left(j^{\prime}, a_{-i}\right)-c_{i}\left(j, a_{-i}\right) \\
& =\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a) \\
& <0
\end{aligned}
$$

Similarly, we have:

$$
\begin{aligned}
\Delta \phi(a) & \equiv \phi\left(j^{\prime}, a_{-i}\right)-\phi\left(j, a_{-i}\right) \\
& =\frac{1}{2}\left(\left(\ell_{j^{\prime}}(a)+w_{i}\right)^{2}+\left(\ell_{j}(a)-w_{i}\right)^{2}-\ell_{j^{\prime}}(a)^{2}-\ell_{j}(a)^{2}\right) \\
& =\frac{1}{2}\left(2 w_{i} \ell_{j^{\prime}}(a)+w_{i}^{2}-2 w_{i} \ell_{j}(a)+w_{i}^{2}\right) \\
& =w_{i}\left(\ell_{j^{\prime}}(a)+w_{i}-\ell_{j}(a)\right) \\
& =w_{i} \cdot \Delta c_{i}(a) \\
& <0
\end{aligned}
$$

Note: $\Delta c_{i} \neq \Delta \phi$.

## Red State/Blue State Game

And now - a game that doesn't look like a congestion game.

## Red State/Blue State Game

And now - a game that doesn't look like a congestion game.
Definition
The Red State/Blue State game is played on a graph $G=(V, E)$.

1. The players are vertices $P=V$.
2. Each edge $e=(i, j) \in E$ has weight $w_{e}$
3. Actions $A_{i}=\{-1,1\}$ (read $\{$ red, blue $\}$ )
4. $u_{i}(a)=\sum_{e=(i, j) \in E} w_{e} \cdot a_{i} \cdot a_{j}=\sum_{j: a_{i}=a_{j}} w_{i, j}-\sum_{j: a_{i} \neq a_{j}} w_{i, j}$

## Red State/Blue State Game

And now - a game that doesn't look like a congestion game.

## Definition

The Red State/Blue State game is played on a graph $G=(V, E)$.

1. The players are vertices $P=V$.
2. Each edge $e=(i, j) \in E$ has weight $w_{e}$
3. Actions $A_{i}=\{-1,1\}$ (read \{red, blue $\}$ )
4. $u_{i}(a)=\sum_{e=(i, j) \in E} w_{e} \cdot a_{i} \cdot a_{j}=\sum_{j: a_{i}=a_{j}} w_{i, j}-\sum_{j: a_{i} \neq a_{j}} w_{i, j}$
"Everyone picks an affiliation, and obtains utility equal to the weight of friends who pick the same affiliation, and disutility equal to the weight of friends who don't."

## Red State/Blue State Game

## Red State/Blue State Game

Theorem
The Red-State/Blue-State game always has a pure strategy Nash equilibrium.

Proof
Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Proof
Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

## Proof

Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

$$
\Delta u_{i}=\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j}
$$

## Proof

Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

$$
\begin{aligned}
\Delta u_{i} & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}
\end{aligned}
$$

## Proof

Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

$$
\begin{aligned}
\Delta u_{i} & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}
\end{aligned}
$$

Similarly:

$$
\Delta \phi=\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j}
$$

## Proof

Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

$$
\begin{aligned}
\Delta u_{i} & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}
\end{aligned}
$$

Similarly:

$$
\begin{aligned}
\Delta \phi & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}
\end{aligned}
$$

## Proof

Define:

$$
\phi(a)=\sum_{j<i} w_{i, j} a_{i} a_{j}
$$

Now consider a best response move made by player $i$. We have:

$$
\begin{aligned}
\Delta u_{i} & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}
\end{aligned}
$$

Similarly:

$$
\begin{aligned}
\Delta \phi & =\sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j}-\sum_{j \neq i} w_{e} \cdot\left(-a_{i}\right) \cdot a_{j} \\
& =2 \sum_{j \neq i} w_{e} \cdot a_{i} \cdot a_{j} \\
& =\Delta u_{i}
\end{aligned}
$$

## Abstracting Away...

What do we need to make the proof work?

## Abstracting Away...

What do we need to make the proof work?
Definition
A function $\phi: A \rightarrow \mathbb{R}_{\geq 0}$ is an exact potential function for a game $G$ if for all $a \in A$, all $i$, and all $a_{i}, b_{i} \in A_{i}$ :

$$
\phi\left(b_{i}, a_{-i}\right)-\phi\left(a_{i}, a_{-i}\right)=c_{i}\left(b_{i}, a_{-i}\right)-c_{i}\left(a_{i}, a_{-i}\right)
$$

## Abstracting Away...

What do we need to make the proof work?

## Definition

A function $\phi: A \rightarrow \mathbb{R}_{\geq 0}$ is an exact potential function for a game $G$ if for all $a \in A$, all $i$, and all $a_{i}, b_{i} \in A_{i}$ :

$$
\phi\left(b_{i}, a_{-i}\right)-\phi\left(a_{i}, a_{-i}\right)=c_{i}\left(b_{i}, a_{-i}\right)-c_{i}\left(a_{i}, a_{-i}\right)
$$

## Definition

$\phi: A \rightarrow \mathbb{R}_{\geq 0}$ is an ordinal potential function for a game $G$ if for all $a \in A$, all $i$, and all $a_{i}, b_{i} \in A_{i}$ :

$$
\left(c_{i}\left(b_{i}, a_{-i}\right)-c_{i}\left(a_{i}, a_{-i}\right)<0\right) \Rightarrow\left(\phi\left(b_{i}, a_{-i}\right)-\phi\left(a_{i}, a_{-i}\right)<0\right)
$$

i.e. the change in utility is always equal in sign to the change in potential.

## A Characterization

Theorem
Best response dynamics is guaranteed to converge in a game $G$ if and only if the game has an ordinal potential function.

## A Characterization

Theorem
Best response dynamics is guaranteed to converge in a game $G$ if and only if the game has an ordinal potential function.

So our proof technique is without loss of generality!

## Proof

1. We've already seen the forward direction (ordinal potential function $\Rightarrow$ BRD converges) several times now, so lets prove the reverse direction.

## Proof

1. We've already seen the forward direction (ordinal potential function $\Rightarrow$ BRD converges) several times now, so lets prove the reverse direction.
2. Consider a graph $G=(V, E)$ :
2.1 Let each $a \in A$ be a vertex in the graph: i.e. $V=A$.
2.2 For each pair of vertices $a, b \in V$, add a directed edge $(a, b)$ if it is possible to get to get from $b$ to $a$ via a best response move - i.e. if there is some index $i$ such that $b=\left(b_{i}, a_{-i}\right)$, and $c_{i}\left(b_{i}, a_{-i}\right)<c_{i}(a)$.

## Proof

1. We've already seen the forward direction (ordinal potential function $\Rightarrow$ BRD converges) several times now, so lets prove the reverse direction.
2. Consider a graph $G=(V, E)$ :
2.1 Let each $a \in A$ be a vertex in the graph: i.e. $V=A$.
2.2 For each pair of vertices $a, b \in V$, add a directed edge $(a, b)$ if it is possible to get to get from $b$ to $a$ via a best response move - i.e. if there is some index $i$ such that $b=\left(b_{i}, a_{-i}\right)$, and $c_{i}\left(b_{i}, a_{-i}\right)<c_{i}(a)$.
3. BRD can be viewed as traversing this graph: Start at an arbitrary vertex $a$, and then traverse arbitrary outgoing edges.

## Proof

1. We've already seen the forward direction (ordinal potential function $\Rightarrow$ BRD converges) several times now, so lets prove the reverse direction.
2. Consider a graph $G=(V, E)$ :
2.1 Let each $a \in A$ be a vertex in the graph: i.e. $V=A$.
2.2 For each pair of vertices $a, b \in V$, add a directed edge $(a, b)$ if it is possible to get to get from $b$ to $a$ via a best response move - i.e. if there is some index $i$ such that $b=\left(b_{i}, a_{-i}\right)$, and $c_{i}\left(b_{i}, a_{-i}\right)<c_{i}(a)$.
3. $B R D$ can be viewed as traversing this graph: Start at an arbitrary vertex $a$, and then traverse arbitrary outgoing edges.
4. Nash Equilibria are the sinks in this graph.

## Proof

1. We've already seen the forward direction (ordinal potential function $\Rightarrow$ BRD converges) several times now, so lets prove the reverse direction.
2. Consider a graph $G=(V, E)$ :
2.1 Let each $a \in A$ be a vertex in the graph: i.e. $V=A$.
2.2 For each pair of vertices $a, b \in V$, add a directed edge $(a, b)$ if it is possible to get to get from $b$ to $a$ via a best response move - i.e. if there is some index $i$ such that $b=\left(b_{i}, a_{-i}\right)$, and $c_{i}\left(b_{i}, a_{-i}\right)<c_{i}(a)$.
3. $B R D$ can be viewed as traversing this graph: Start at an arbitrary vertex $a$, and then traverse arbitrary outgoing edges.
4. Nash Equilibria are the sinks in this graph.
5. BRD converges $=$ there are no cycles in this graph.

Proof


## Proof

1. So suppose BRD converges (i.e. $G$ is acyclic). We construct a potential function $\phi$.

## Proof

1. So suppose BRD converges (i.e. $G$ is acyclic). We construct a potential function $\phi$.
2. The graph is acyclic, so: from every state $a$ there is some sink $s$ that is reachable. (why?)

## Proof

1. So suppose BRD converges (i.e. $G$ is acyclic). We construct a potential function $\phi$.
2. The graph is acyclic, so: from every state a there is some sink $s$ that is reachable. (why?)
3. For each vertex $a$, define $\phi(a)$ to be the length of the longest finite path from $a$ to any sink $s$.

## Proof

1. So suppose BRD converges (i.e. $G$ is acyclic). We construct a potential function $\phi$.
2. The graph is acyclic, so: from every state a there is some sink $s$ that is reachable. (why?)
3. For each vertex $a$, define $\phi(a)$ to be the length of the longest finite path from $a$ to any sink $s$.
4. We need: for any edge $a \rightarrow b, \phi(b)<\phi(a)$.

## Proof

1. So suppose BRD converges (i.e. $G$ is acyclic). We construct a potential function $\phi$.
2. The graph is acyclic, so: from every state $a$ there is some sink $s$ that is reachable. (why?)
3. For each vertex $a$, define $\phi(a)$ to be the length of the longest finite path from $a$ to any sink $s$.
4. We need: for any edge $a \rightarrow b, \phi(b)<\phi(a)$.
5. Its true! $\phi(a) \geq \phi(b)+1$. (why?)

## Thanks!

See you next class - stay healthy!

