



Model-driven Test Generation

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September 22, 2004

Outline and scope

- Classification of model-driven testing
- Conformance testing for communication protocols
- Coverage-based testing
 - Coverage criteria
 - Coverage-based test generation
- Can we do more? (open questions)



Testing classification

- By component level
 - Unit testing
 - Integration testing
 - System testing
- By abstraction level
 - Black box
 - White box
 - Grey box ???



Testing classification

- By purpose
 - Functional testing
 - Performance testing
 - Robustness testing
 - Stress testing
- Who performs testing?
 - Developers
 - In-house QA
 - Third-party



Functional testing

- An implementation can exhibit a variety of behaviors
- For each behavior, we can tell whether it is correct or not
- A *test* can be applied to the implementation and accept or reject one or more behaviors
 - The test fails if a behavior is rejected
- A *test suite* is a finite collection of tests
 - Testing fails if any test in the suite fails



Formal methods in testing

- “Testing can never demonstrate the absence of errors, only their presence.”
Edsger W. Dijkstra
- How can formal methods help?
- Add rigor!
 - Reliably identify what should to be tested
 - Provide basis for test generation
 - Provide basis for test execution



Model-driven testing

- Rely on a model of the system
 - Different interpretations of a model
- Model is a requirement
 - Black-box conformance testing
 - QA or third party
- Model is a design artifact
 - Grey-box unit/system testing
 - QA or developers



Conformance testing

- A specification prescribes legal behaviors
- Does the implementation conform to the specification?
 - Need the notion of conformance
- Not interested in:
 - How the system is implemented?
 - What went wrong if an error is found?
 - What else the system can do?



Test hypothesis

- How do we relate beasts of different species?
 - Implementation is a physical object
 - Specification is a formal object
- **Assume** there is a formal model that is faithful to implementation
 - We do not know it!
- Define conformance between the model and the specification
 - Generate tests to demonstrate conformance



Conformance testing with LTS

- Requirement is specified as a labeled transition system
- Implementation is modeled as an input-output transition system
- Conformance relation is given by **ioco**
 - [Tretmans96]
 - Built upon earlier work on testing preorders



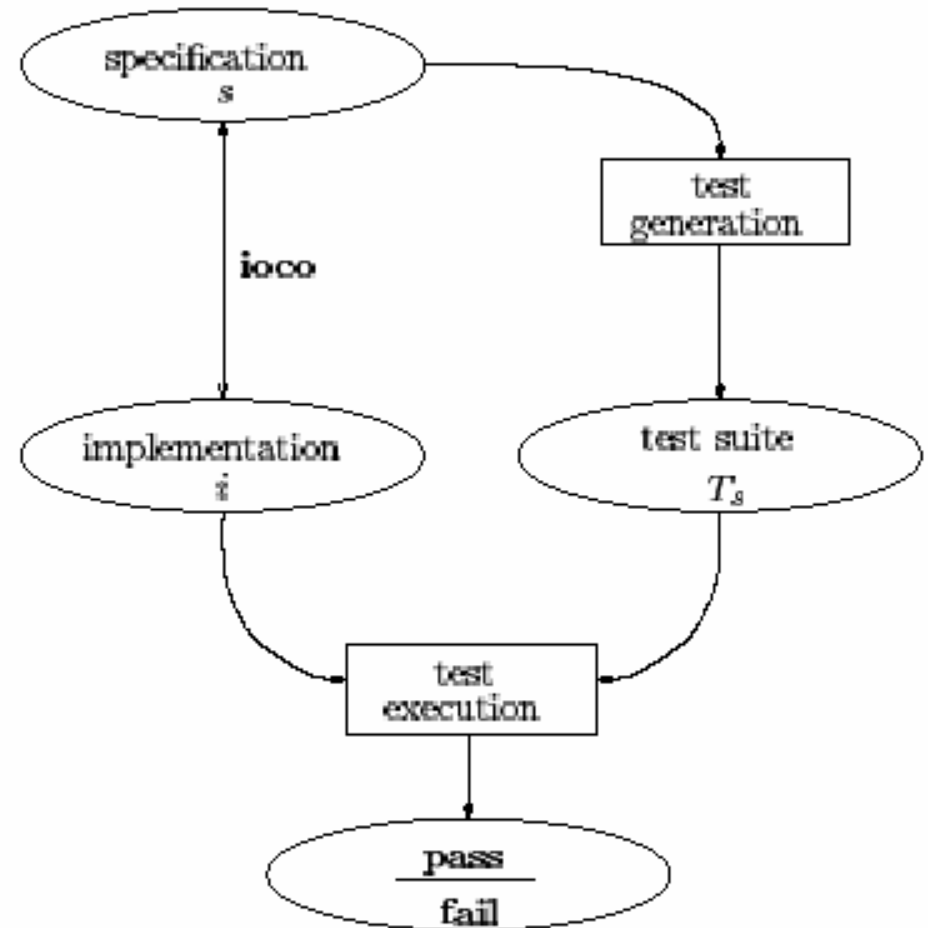
Historical reference

- Process equivalences:
 - Trace equivalence/preorder is too coarse
 - Bisimulation/simulation is too fine
- Middle ground:
 - Failures equivalence in CSP
 - may- and must-testing by Hennessy
 - Testing preorder by de Nicola
 - They are all the same!
- Right notion but hard to compute

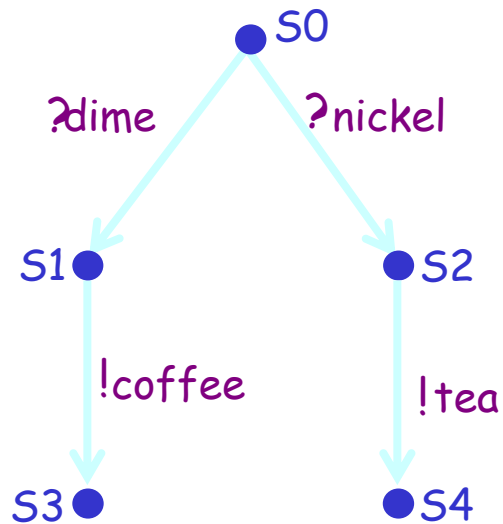


Testing architecture

- Implementation relation
- Test generation algorithm
- Test execution engine



Input-Output Transition Systems



$$L_I = \{ ?dime, ?nickel \}$$

$$L_U = \{ !coffee, !tea \}$$

dime, nickel

from user to machine
initiative with user
machine cannot refuse

input
 L_I

$$L_I \cap L_U = \emptyset$$

coffee, tea

from machine to user
initiative with machine
user cannot refuse

output
 L_U

$$L_I \cup L_U = L$$



Input-Output Transition Systems

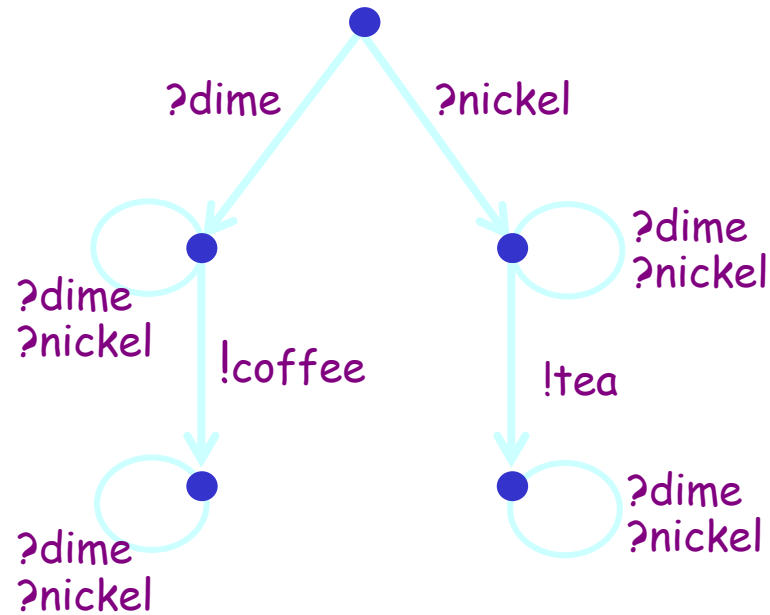
Input-Output Transition Systems

$$\text{IOTS}(L_I, L_U) \subseteq \text{LTS}(L_I \cup L_U)$$

IOTS is LTS with Input-Output and always enabled inputs:

for all states s ,

for all inputs $?a \in L_I$: $s \xrightarrow{?a}$

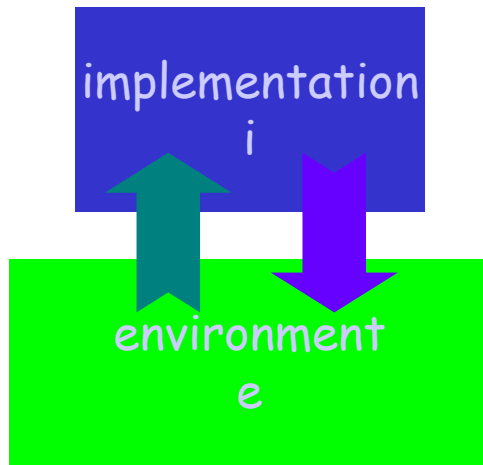


$$L_I = \{ ?dime, ?nickel \}$$

$$L_U = \{ !coffee, !tea \}$$



Preorders on IOTS



imp



$$i \in \text{IOTS}(L_I, L_U)$$

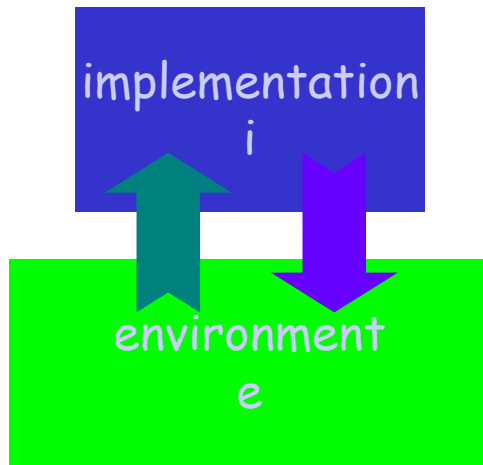
$$s \in \text{LTS}(L_I \cup L_U)$$

$$imp \subseteq \text{IOTS}(L_I, L_U) \times \text{LTS}(L_I \cup L_U)$$

Observing IOTS where system inputs interact with environment outputs, and vice versa



Preorders on IOTS



imp



$$i \in \text{IOTS}(L_I, L_U)$$

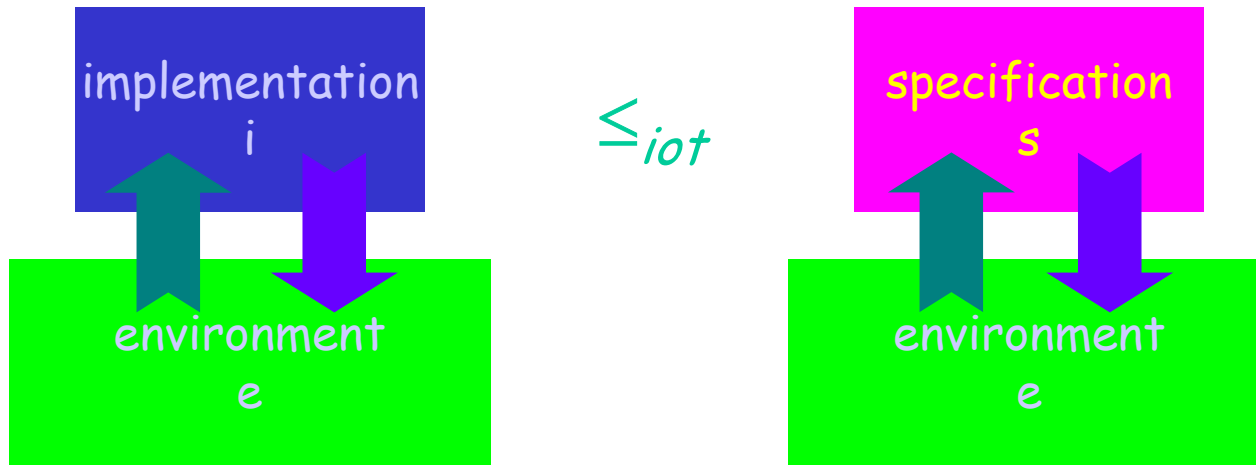
$$s \in \text{LTS}(L_I \cup L_U)$$

$$i \text{ imp } s \iff \forall e \in E. \text{obs}(e, i) \subseteq \text{obs}(e, s)$$

$$\downarrow$$
$$\text{IOTS}(L_U, L_I)$$



Input-Output Testing Relation



$$i \in \text{IOTS}(L_I, L_U)$$

$$s \in \text{LTS}(L_I \cup L_U)$$

$$i \leq_{iot} s \Leftrightarrow \forall e \in \text{IOTS}(L_U, L_I) . \text{obs}(e, i) \subseteq \text{obs}(e, s)$$

$$\text{obs}(e, p) = (\text{traces}(e \parallel p), \text{qtraces}(e \parallel p))$$

$$\text{qtraces}(p) = \sigma \in L^* . p \text{ after } \sigma \text{ refuses } L_U$$



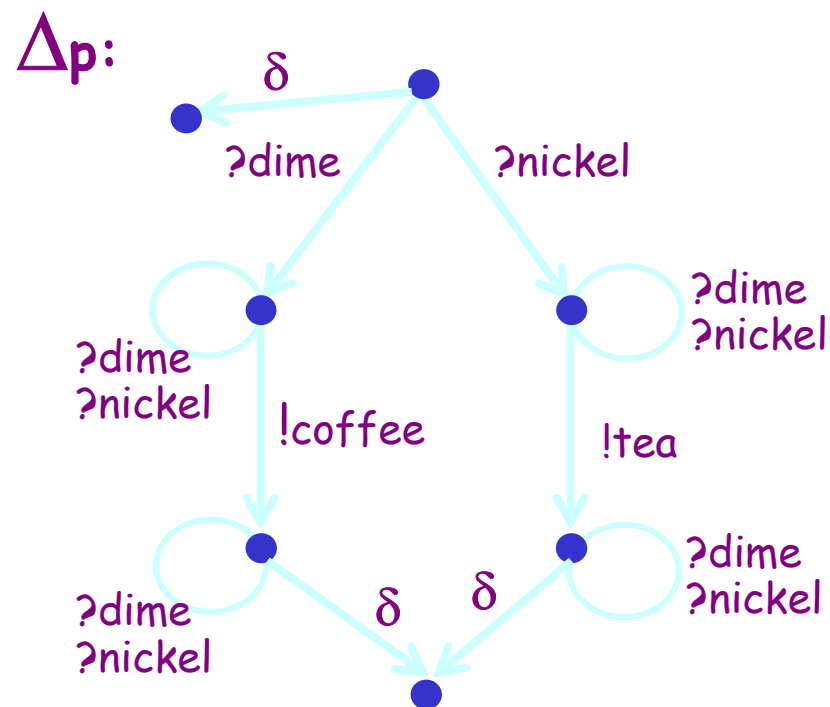
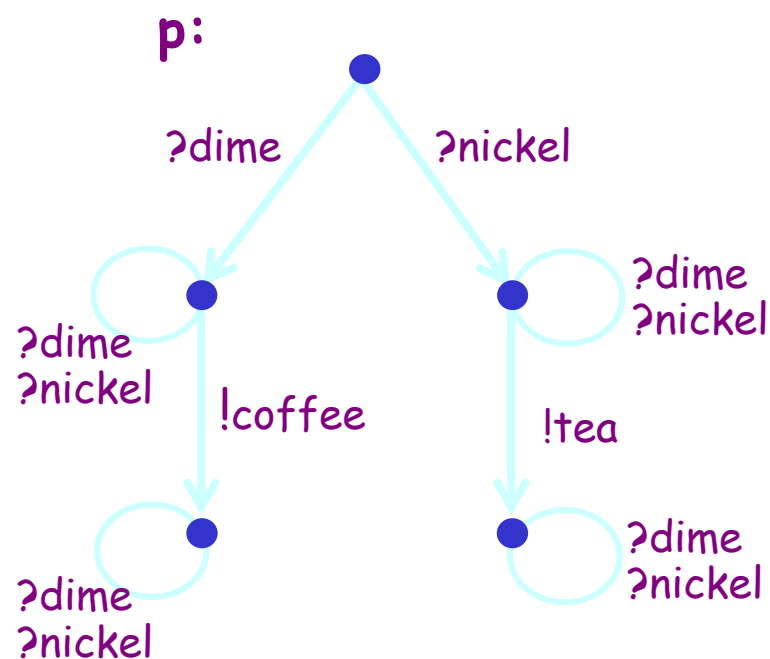
Testing preorders – a side note

- One of the reasons for using IOTS over LTS is that \leq_{iot} is computationally simpler than conventional testing preorder
 - Testing preorder requires us to compare sets of pairs (trace, refusal set)
 - At the same time \leq_{iot} allows us to use inclusion of weakly quiescent traces:
 - inputs can never be refused by i , and outputs can never be refused by e
 - i after σ refuses $A \Rightarrow A = \emptyset$ or $A = L_U$



Representing quiescence

- Extend IOTS with quiescent transitions
- deterministic δ -trace automata



Conformance relation **ioconf**

- Finally...

$$i \leq_{iot} s \Leftrightarrow \forall \sigma \in L^*. \text{out}(\Delta i \text{ after } \sigma) \subseteq \text{out}(\Delta s \text{ after } \sigma)$$

- Allow underspecification

- restrict to traces of s

$$i \text{ ioconf } s =_{\text{def}}$$

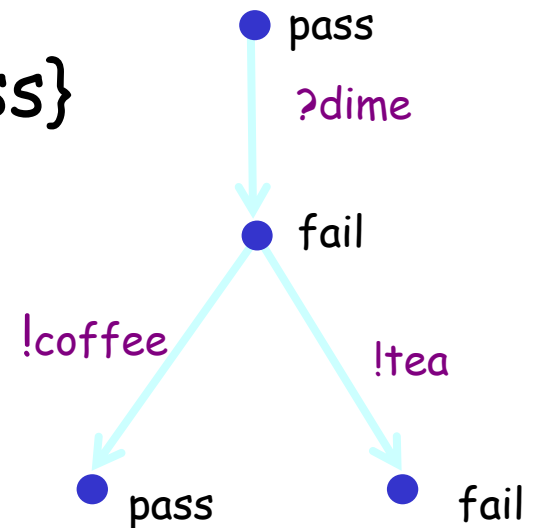
$$\forall \sigma \in \text{traces}(\Delta s) \cap L^*. \text{out}(\Delta i \text{ after } \sigma) \subseteq \text{out}(\Delta s \text{ after } \sigma)$$

- **ioconf_F**: use arbitrary F instead of traces of s
- Conformance relation **ioco** accounts for *repetitive quiescence*



Test cases

- A test case is a deterministic IOTS(L_U, L_I) with finite behaviors
 - Note reversed inputs and outputs
 - Do not allow choice between outputs or between input and output
- Verdict function $v: S \rightarrow \{\text{fail}, \text{pass}\}$
- Test run: i passes t $\stackrel{\text{def}}{=} (i || t)$ after σ deadlocks $\Rightarrow v(t \text{ after } \sigma) = \text{pass}$



Test generation

- Test suite T_s for a specification s is **complete**:
 $i \text{ ioconf } s \text{ iff } \forall t \in T_s . i \text{ passes } t$
- Test suite T_s is **sound** if
 $i \text{ ioconf } s \Rightarrow \forall t \in T_s . i \text{ passes } t$
- Complete test suites are usually infinite
 - Aim at generating sound test suites



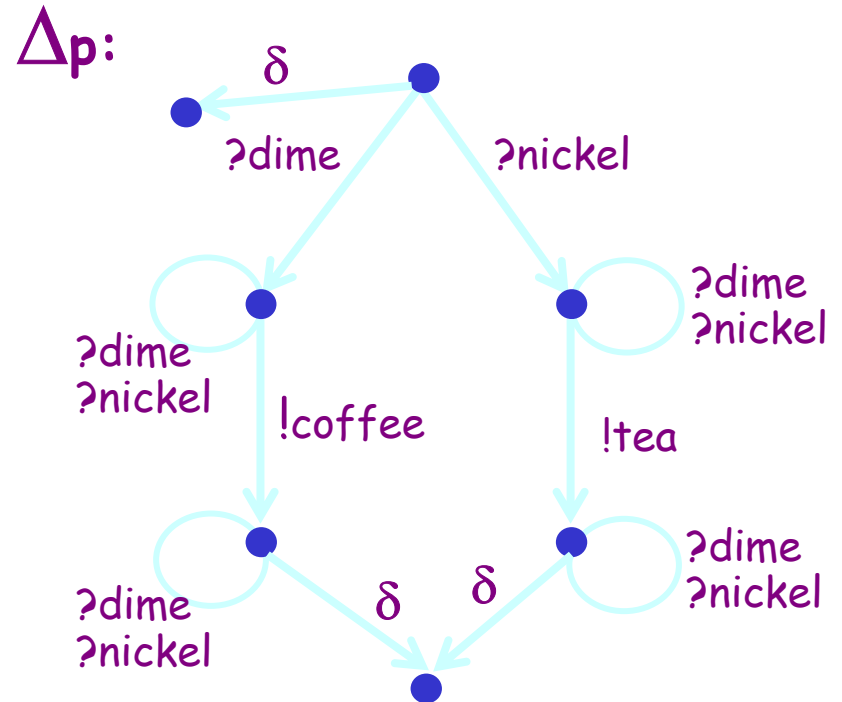
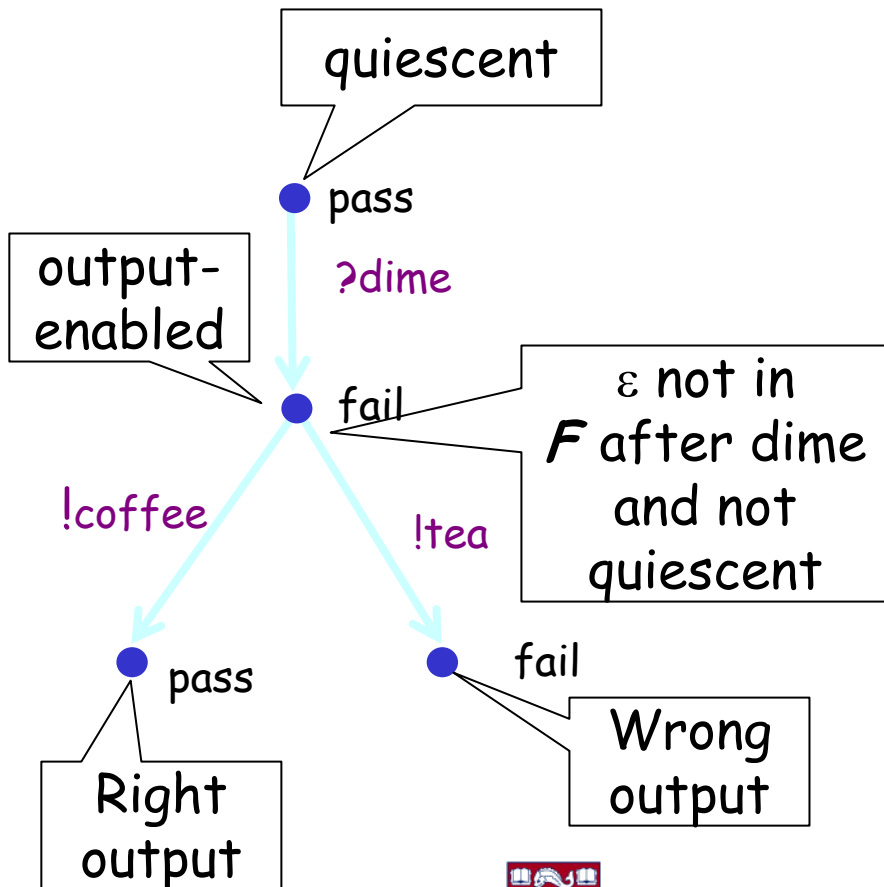
Test generation algorithm

- $\text{Gen}(\Delta_S, F)$
 - Choose non-deterministically:
 1. $t = \text{stop}$ and $v(t) = \text{pass}$
 2. $t = a . \text{Gen}(\Delta'_S, F \text{ after } a)$, with $\Delta_S \xrightarrow{a} \Delta'_S$
 $v(t) = \text{pass}$
 3. $t = \sum \{x.\text{stop} \mid x \in L_U, x \notin \text{out}(\Delta_S)\} + \sum \{x.t_x \mid x \in \text{out}(\Delta_S)\}$
 $v(t) = \text{pass}$ if $\delta \in \text{out}(\Delta_S) \vee \varepsilon \in F$; otherwise fail
 $v(\text{stop}) = \text{fail}$ if $\varepsilon \notin F$; otherwise pass



Example

- $F = \text{dime.coffee}$



Test purposes

- Where does F come from?
- Test purposes:
 - Requirements, use cases
 - Automata, message sequence charts
- Test purposes represent "interesting" or "significant" behaviors
 - Define "interesting" or "significant"...
- Can we come up with test purposes automatically?



Summary: conformance testing

- Advantages:
 - Very rigorous formal foundation
 - Size of the test suite is controlled by use cases
- Disadvantages:
 - How much have we learned about the system that passed the test suite?
 - Does not guarantee coverage



Coverage-based testing

- Traditional:
 - Tests are derived from the implementation structure (code)
- Model-driven:
 - Cover the model instead of code
 - Model should be much closer to the implementation in structure
- Relies on coverage criteria



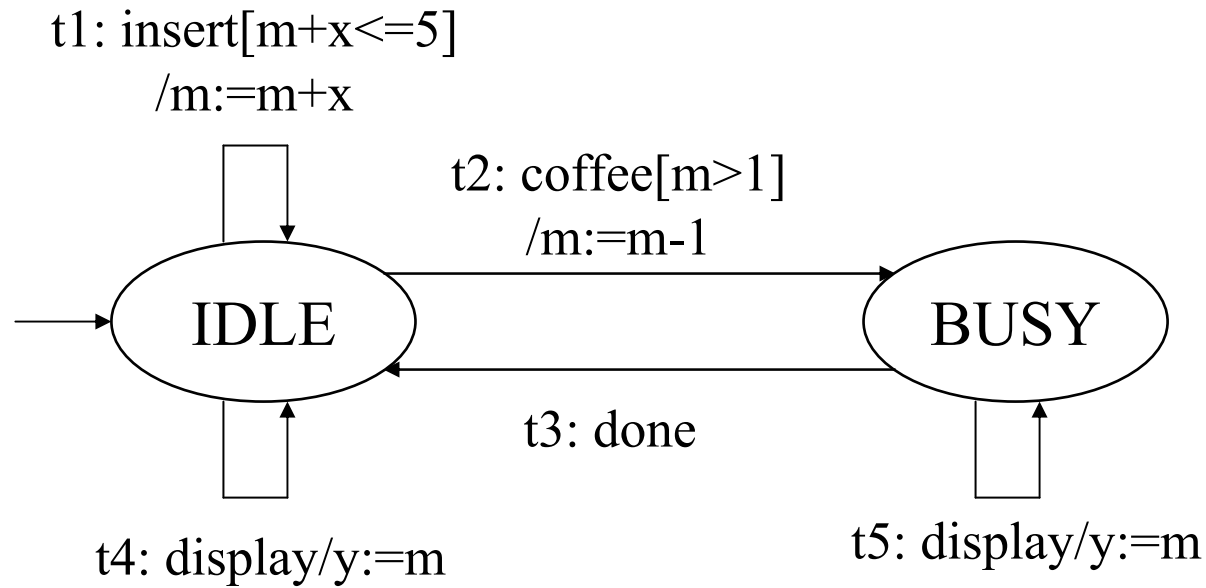
Coverage criteria and tests

- [HongLeeSokolskyUral02]
- Control flow:
 - all-states
 - all-transitions
- Data flow:
 - all-defs
 - all-uses
 - all-inputs
 - all-outputs
- Test is a linear sequence of inputs and outputs



Specifications: EFSM

- Transition systems equipped with variables
- Transitions have guards and update blocks



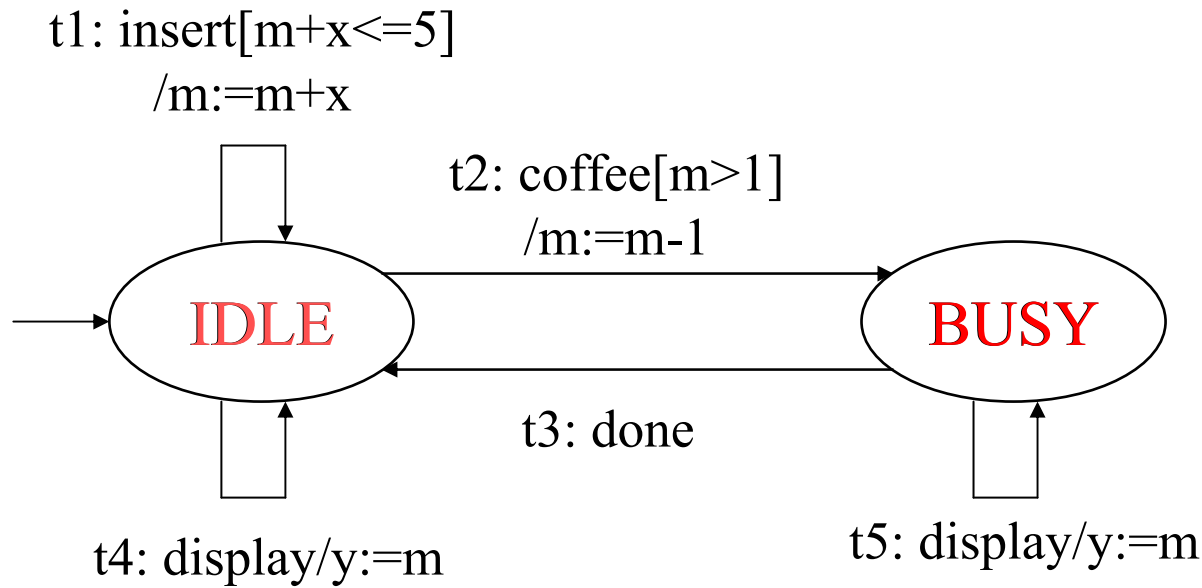
Coverage criteria

- Each coverage criterion is represented by a set of temporal logic formulas
 - WCTL: a subset of CTL
 - Atomic propositions p_1, \dots, p_n
 - Temporal operators EX, EU, EF
 - Conjunctions: at most one non-atomic conjunct
 - Negations is applied only to atomic propositions
 - Unrestricted disjunctions
 - E.g.: $EF(p_1 \ \& \ EF p_2)$
 - WCTL formulas have linear witnesses



All-states coverage criterion

- Requires every state be covered at least once
- With every state s , associate $EF(s)$ & EF_{exit}



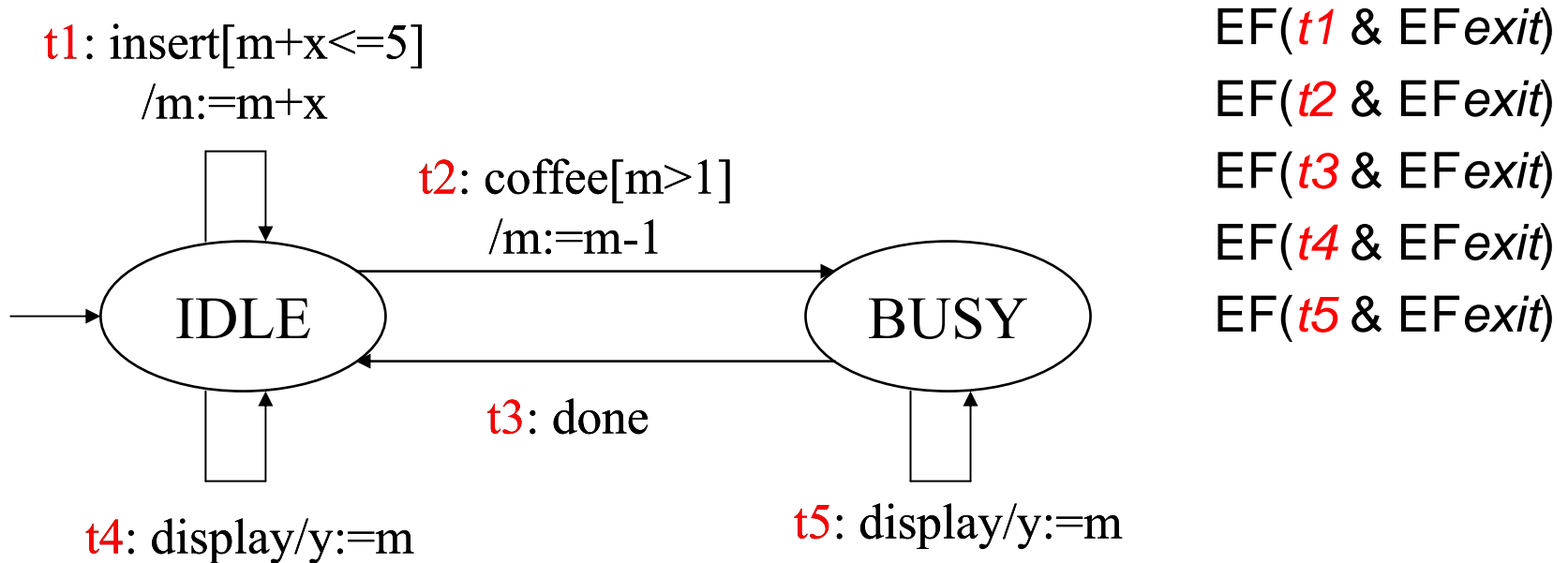
$EF(idle)$ & EF_{exit}

$EF(busy)$ & EF_{exit}



All-transitions coverage criterion

- Requires every transition be covered at least once
- With every transition t , associate $EF(t \ \& \ EF_{exit})$



Data flow: definitions and uses

- **Definition:** a value is assigned to a variable
- **Use:** a value of a variable is used in an expression
- Variables are defined and used in transitions
- **Definition-use pair:** (v, t, t')
 - v is defined by t
 - v is used by t'
 - There is a path from t to t' free from other definitions of v

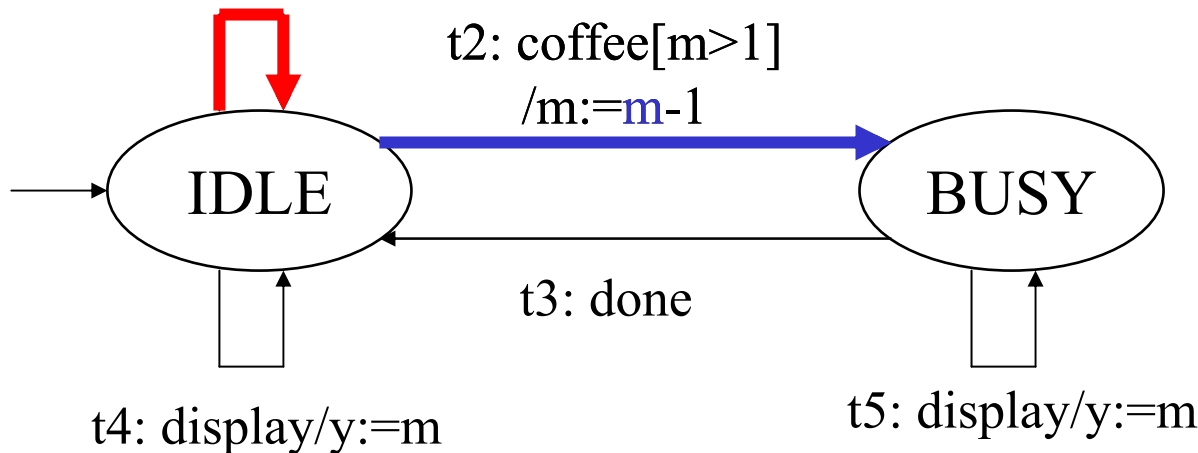


Covering a du-pair

- With a du-pair (v, t, t') , *associate*
 - $EF(t \ \& \ EXE[!def(v) \cup (t' \ \& \ EF_{exit})])$
 - $def(v)$: disjunction of all transitions that define v

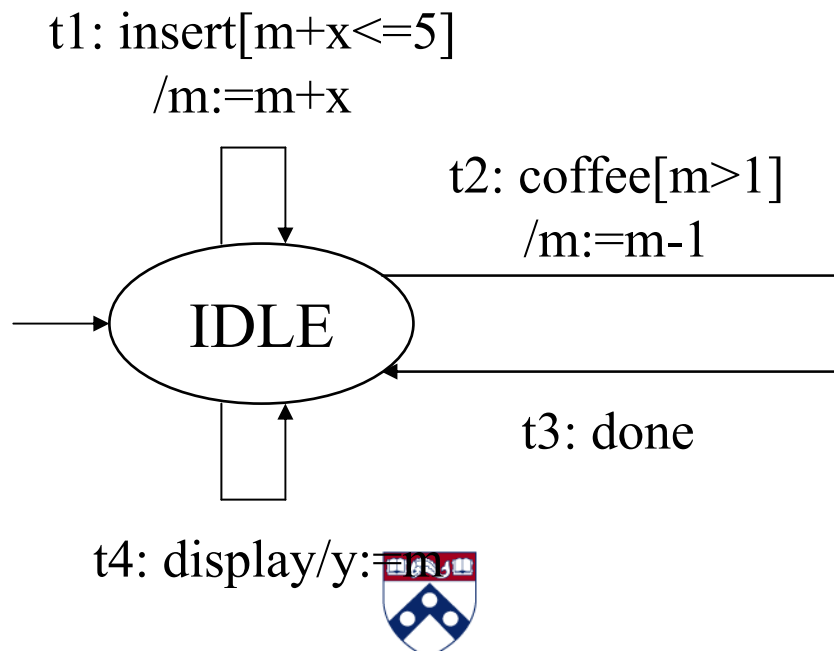
t1: insert[m+x<=5]
/m:=m+x

$EF(t1 \ \& \ EXE[!(t1 \ | \ t2) \cup (t2 \ \& \ EF_{exit})])$



Data-flow coverage criteria

- All-defs coverage criterion: a definition-clear path
 - from *every* definition to *some* use
- All-uses coverage criterion: a definition-clear path
 - from *every* definition to *every* use

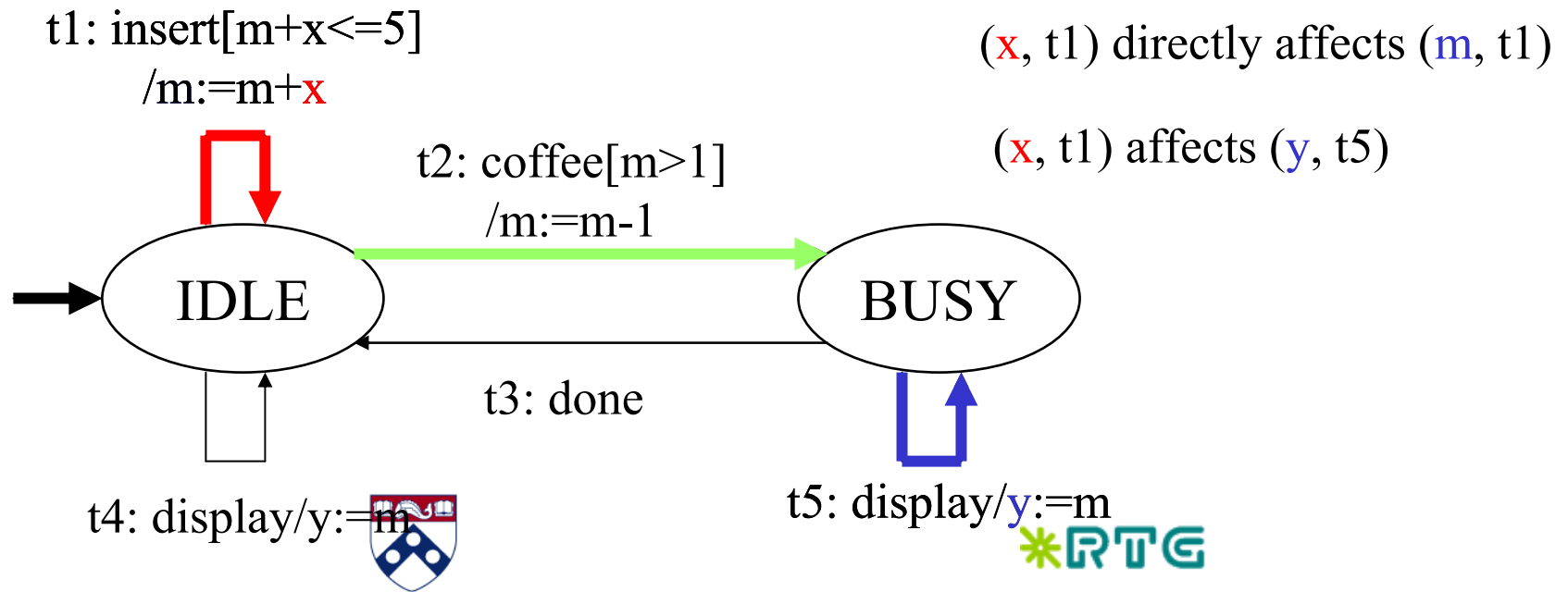


All-uses coverage criterion

$EF(t1 \& EXE[!(t1 \mid t2) \cup (t1 \& EFexit)])$
 $EF(t1 \& EXE[!(t1 \mid t2) \cup (t2 \& EFexit)])$
 $EF(t1 \& EXE[!(t1 \mid t2) \cup (t4 \& EFexit)])$
 $EF(t1 \& EXE[!(t1 \mid t2) \cup (t5 \& EFexit)])$
 $EF(t2 \& EXE[!(t1 \mid t2) \cup (t1 \& EFexit)])$
 $EF(t2 \& EXE[!(t1 \mid t2) \cup (t2 \& EFexit)])$
 $EF(t2 \& EXE[!(t1 \mid t2) \cup (t4 \& EFexit)])$
 $EF(t2 \& EXE[!(t1 \mid t2) \cup (t5 \& EFexit)])$

Data flow chains

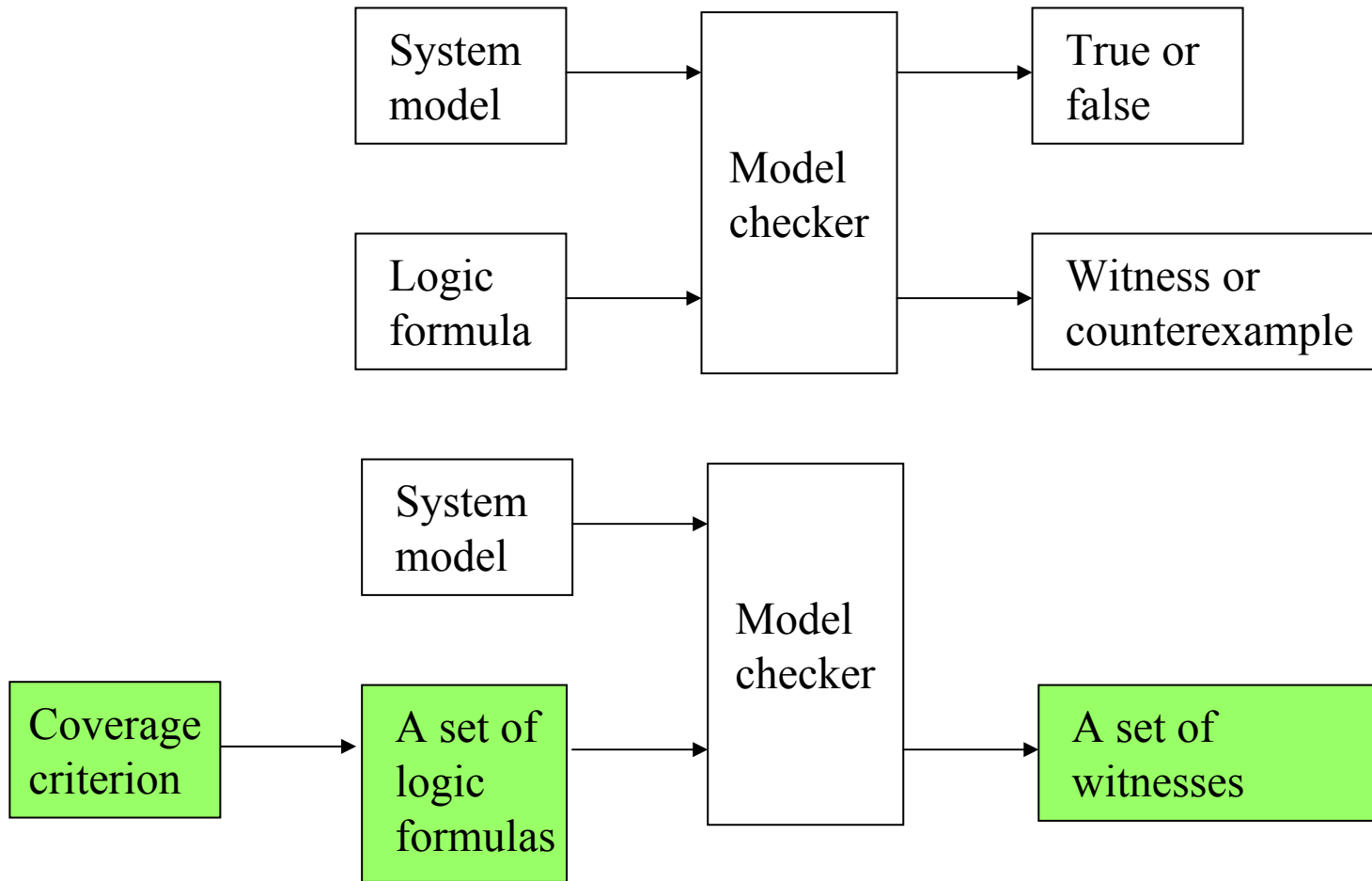
- Affect pair (v, t, v', t') : the value of v used by t affects the value of v' defined at t'
 - Either $t=t'$ ((v,t) directly affects (v',t')) or
 - there is a du-pair (v'',t,t') s.t. (v,t) directly affects (v'',t) and (v'',t') affects (v',t')



Data flow chain coverage

- Affect pair (v, t, v', t')
 - May consist of an arbitrary number of definition-use pairs
 - We extend CTL with least fixpoint operators
 - Alternatively, we can use (alternation-free) mu-calculus
- All-inputs coverage criterion
 - Requires a path from *every* input to *some* output be covered at least once
- All-outputs coverage criterion
 - Requires a path from *every* input to *every* output be covered at least once

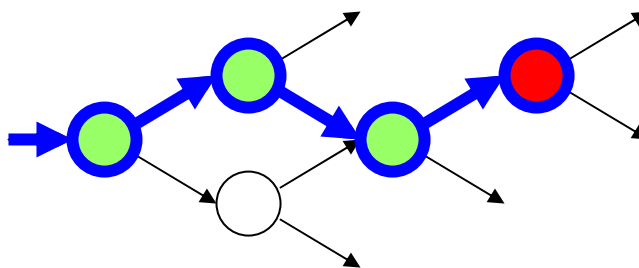
Test Generation



Test Generation

- *Generating a witness for a formula*
 - Cost: the length of a witness
 - A minimal-cost witness for a formula
 - Existing model checkers generate a minimal-cost witness by breadth-first search of state space

$E[\text{green} \text{ U } \text{red}]$



Test Generation

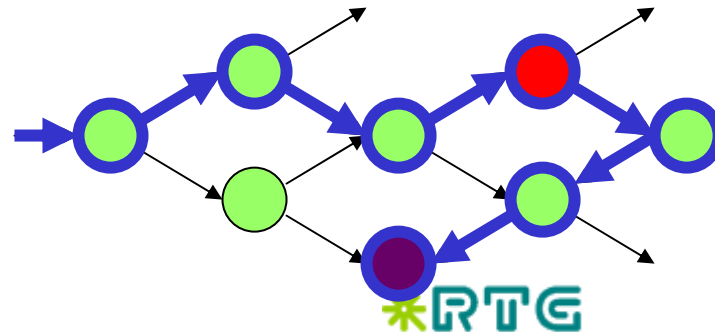
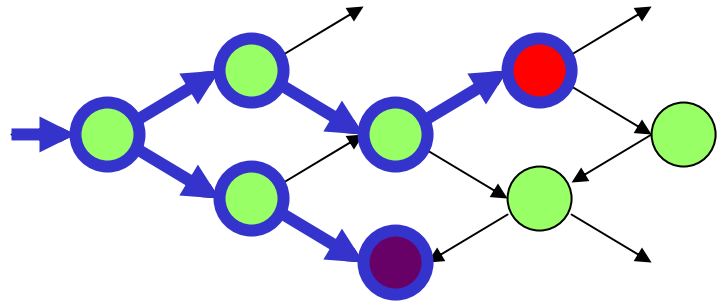
- Costs
 - The total length of witnesses or
 - The number of witnesses
- Both optimization problems are NP-hard

$E[\text{Green} \cup \text{Red}]$

$E[\text{Green} \cup \text{Purple}]$

$E[\text{Green} \cup \text{Red}]$

$E[\text{Green} \cup \text{Purple}]$



*RTG

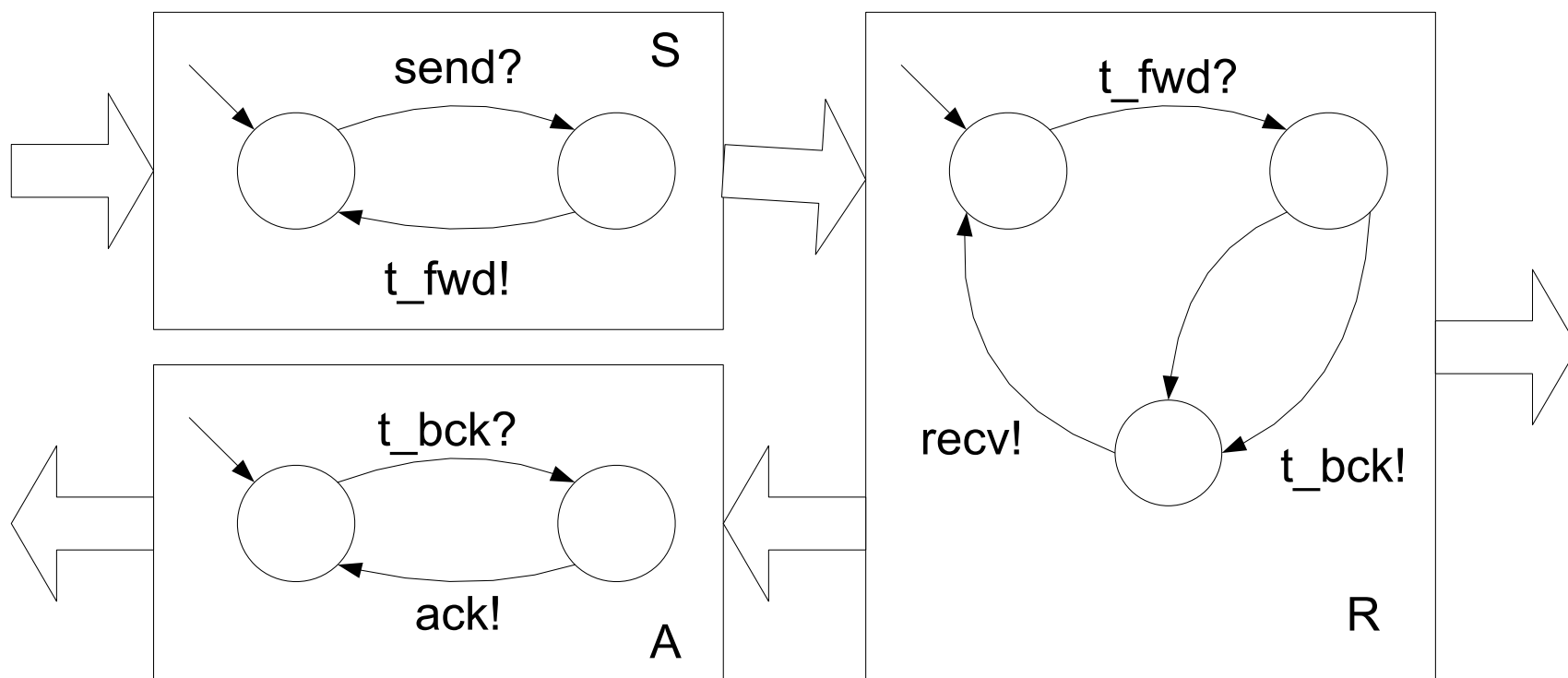
Coverage for distributed systems

- What if our system is a collection of components?
- Possible solutions:
 - Generate tests for each components
 - Clearly unsatisfactory; does not test integration
 - Generate tests from the product of component models
 - Too many redundant tests
- Non-determinism is another problem



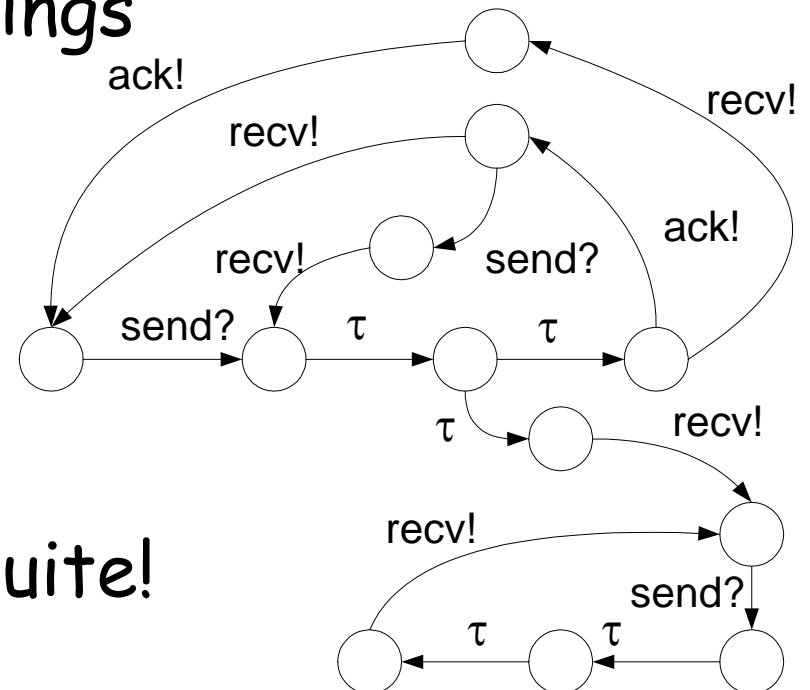
Example

- Producer-consumer with acknowledgements



Covering product transition system

- Linear tests bring trouble:
send?.ack!.recv!
 - May fail if the system chooses a different path
- Tests differ in interleavings of independent events
 - No need to test
send?.ack!.recv!
send?.recv!.ack!
separately
- State explosion in test suite!



Partial orders for test generation

- Use **event structures** instead of transition systems [Heninger97]
- Test generation covers the event structure
- Allows natural generation of distributed testers



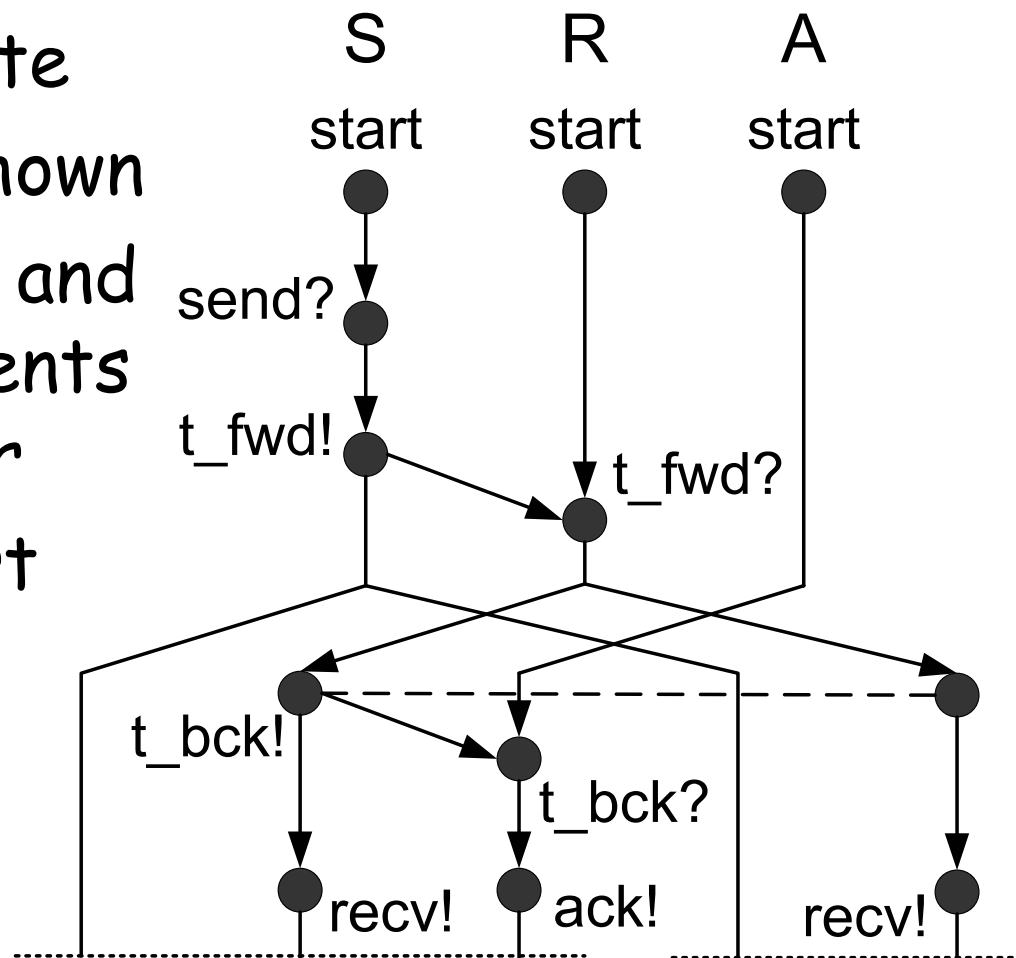
Prime event structures (PES)

- Set of events E
 - Events are occurrences of actions
- Causality relation $\prec \subseteq E \times E$
 - Partial order
- Conflict relation $\# \subseteq E \times E$
 - irreflexive and symmetric
- Labeling function $l: E \rightarrow A$
- Finite causality $\{e' \mid e' \prec e\}$ is finite
- Conflict inheritance $e \# e' \wedge e' \prec e'' \Rightarrow e \# e''$



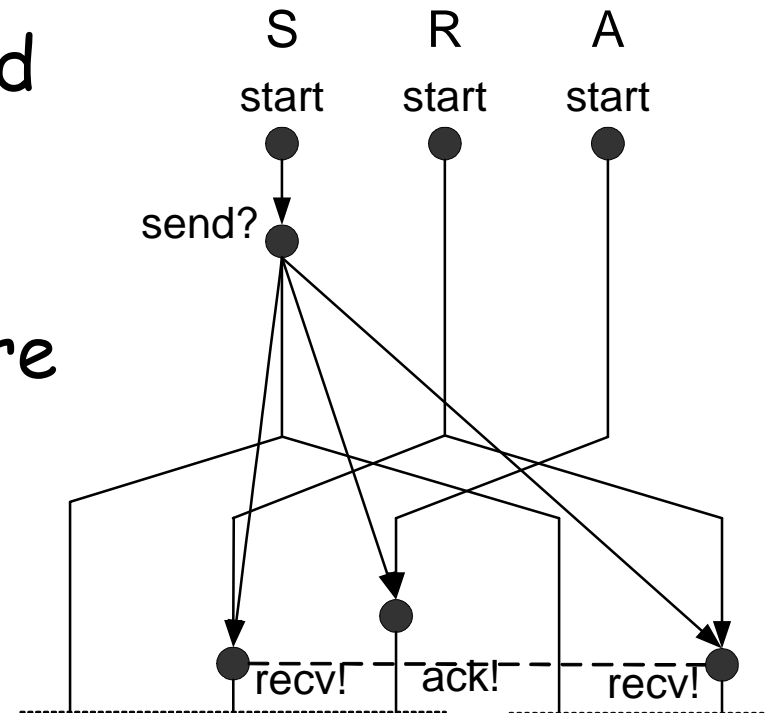
Producer-consumer PES

- Structure is infinite
 - Initial part is shown
- Causally unrelated and non-conflicting events can occur together
- Behaviors will start repeating
 - Can stop with finite structure



Test generation with PES

- Project PES on observable actions, propagating conflicts
- Every path in the PES should be covered
- Tests consist of distributed testers with coordination messages between tests
 - Coordination messages are inserted when there is a causal edge between locations



Summary: coverage-based testing

- Advantages:
 - Exercise the specification to the desired degree
 - Does not rely on test purpose selection
- Disadvantages:
 - Large and unstructured test suites
 - If the specification is an overapproximation, tests may be infeasible



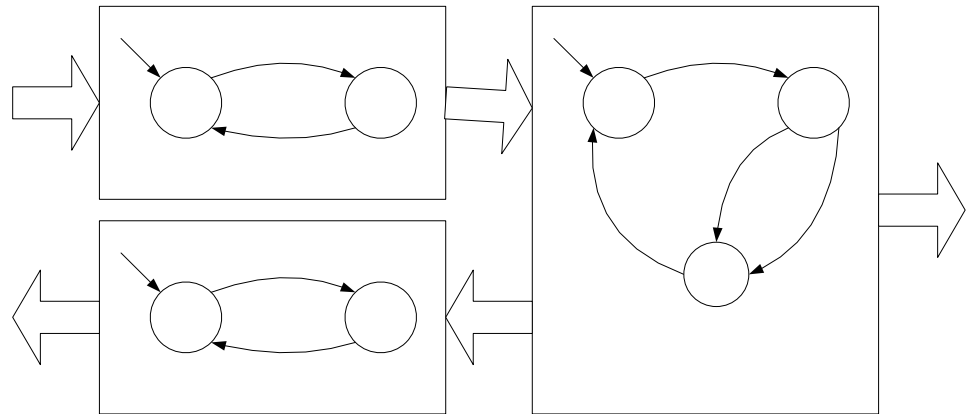
Generation of test purposes

- Recent work: [HenningerLuUral-03]
- Construct PES
- Generate MSC (message sequence charts) to cover PES
- Use MSC as test purposes in **ioco**-based test generation



Controllability of testing

- Conformance testing may not provide enough guarantees
 - With branching tests, test purpose behavior may be avoided
 - What if I never see **ack**?



- Problem: inherent uncertainty in the system

How to contain uncertainty?

- Avoidance (no need to increase control)
 - During testing, compute confidence measure
 - E. g., accumulate coverage
 - Stop at the desired confidence level
- Prevention (add more control)
 - Use instrumentation to resolve uncertainty
 - What to instrument?
 - Use model for guidance
- Anyone needs a project to work on?



Test generation tools

- TorX
 - Based on **ioco**
 - On-the-fly test generation and execution
 - Symbolic testing (data parameterization)
 - LOTOS, Promela, ...
 - <http://fmt.cs.utwente.nl/tools/torx/>
- TGV
 - Based on symbolic **ioconf**
 - LOTOS, SDL, UML
 - <http://www.irisa.fr/pampa/VALIDATION/TGV/TGV.html>

