CIS-800-003: Topics in Parallel Programmability

Joe Devietti 9 Jan 2013

and now, your host...

- devietti@cis
- Office hours: by appointment
- Levine 572

Anatomy of a class

- short presentation on paper(s) 20 minutes
- discussion questions 45 minutes
- [optional] context for next research topic 15 minutes

Course Mechanics (1/2)

- paper presentations
- "reading quizzes" on Blackboard
 - a few questions about each paper
 - due the morning before class

Course Mechanics (2/2)

- Future Work™ Fridays!
 - half a page on an idea related to a paper we've read that week
 - due most Fridays, via Blackboard
- Larger future work write-up
 - 2 pages
 - due at the end of the semester
 - upgrade one of your previous ideas, or something new

Course Mechanics (3/2)

- no exams or projects
- no stress!

Sequential Consistency



What is sequential consistency?

What is sequential consistency?

operational

What is sequential consistency?

operational

mathematical

byte b = 8;

byte
$$b = 8$$
;

long
$$x = 8$$
;

byte
$$b = 8$$
;

long
$$x = 8$$
;

$$X++;$$

```
x == 0 \&\& y == 0
x = 1;
r1 = y;
y = 1;
r2 = x;
```

```
x == 0 &  y == 0

x = 1;

r1 = y;

r2 = x;

r2 = 0?
```

```
x == 0 \&\& y == 0
            x = 1; y = 1;
            r1 = y; r2 = x;
           can r1 == 0 \&\& r2 == 0?
x = 1;
r1 = y;
y = 1;
y = 1;
x = 1;
r2 = x; r1 = y;
```

```
x == 0 \&\& y == 0
                                                                                                                     x = 1; y = 1;
                                                                                                                        r1 = y; r2 = x;
                                                                                                            can r1 == 0 \&\& r2 == 0?
x = 1; y = 1; x = 1; x = 1; y = 1; y
                                                                                                                                                                                               r1 = y; r2 = x;
 r2 = x; r1 = y;
```

```
x == 0 \&\& y == 0
                                                                                           x = 1; y = 1;
                                                                                             r1 = y; r2 = x;
                                                                                    can r1 == 0.88 r2 == 0.9
x = 1; y = 1; x = 1; x = 1; y = 1; y
                                                                                                                                                      r1 = y; r2 = x;
 r2 = x; r1 = y;
                                                                                             y = 1; y = 1; x = 1;
                                                                                              r2 = x; r1 = y;
                                                                                               r1 = y; r2 = x;
```

double-checked locking

```
class Foo {
   private Singleton s = null;
   public Singleton getS() {
      if (s == null) {
        s = new Singleton();
      }
      return s;
   }
}
```

double-checked locking

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    }
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}
```

Turn-based mutual exclusion

```
turn = 0;
while (turn != me) {}
// critical section
turn = (turn+1) % NUM_THREADS;
```

Dekker's algorithm

```
flag[0] = false
flag[1] = false
turn = 0
flag[0] = true;
while (flag[1] == true) {
    if (turn ≠ 0) {
        flag[0] = false;
        while (turn \neq 0) {}
        flag[0] = true;
// critical section
turn = 1;
flag[0] = false;
```

Dekker's algorithm

```
f[ag[0] = fa]se
                     flag[1] = false
                     turn
flag[0] = true;
                               flag[1] = true;
while (flag[1] == true) {
                               while (flag[0] == true) {
                                   if (turn ≠ 1) {
   if (turn ≠ 0) {
      flag[0] = false;
                                      flag[1] = false;
      while (turn \neq 0) {}
                                     while (turn \neq 1) {}
      flag[0] = true;
                                     flag[1] = true;
                               // critical section
// critical section
                               turn = 0;
flag[1] = false;
turn = 1;
flag[0] = false;
```

How do we implement SC?

How to Make a Multiprocessor Computer That Correctly Executes Multiprocess Programs

LESLIE LAMPORT

Abstract—Many large sequential computers execute operations in a different order than is specified by the program. A correct execution

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processors issue memory requests in program order

a memory module services requests from a FIFO queue

there may be multiple memory modules