
An Introduction to Manifold Methods

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High Dimensional Data

- ▶ Raw Format of Natural Data is often **high** dimensional.
- ▶ Curse of Dimensionality.
- ▶ Search for low dimensional structure and models.

Principal Components Analysis

Given $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^D$

Find $y_1, \dots, y_n \in \mathbb{R}$ such that

$$y_i = \mathbf{w} \cdot \mathbf{x}_i$$

and

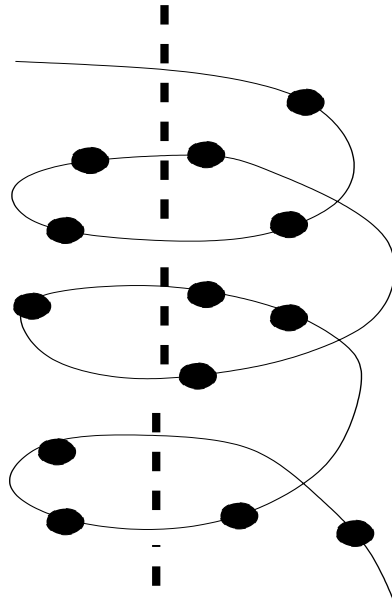
$$\max_{\mathbf{w}} \text{Variance}(\{y_i\}) = \sum_i y_i^2 = \mathbf{w}^T \left(\sum_i \mathbf{x}_i \mathbf{x}_i^T \right) \mathbf{w}$$

\mathbf{w}_* = leading eigenvector of $\sum_i \mathbf{x}_i \mathbf{x}_i^T$

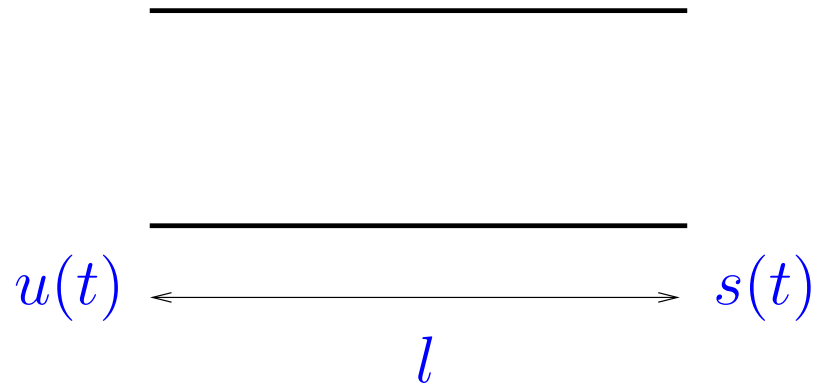
Manifold Model

Suppose data does not lie on a linear subspace.

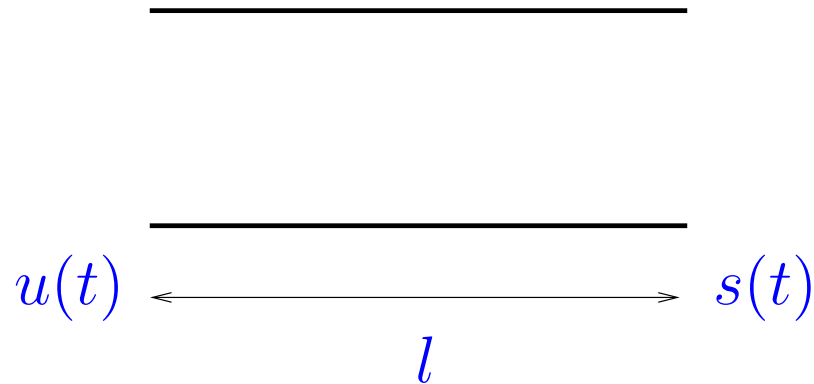
Yet data has inherently one degree of freedom.



An Acoustic Example



An Acoustic Example



One Dimensional Air Flow

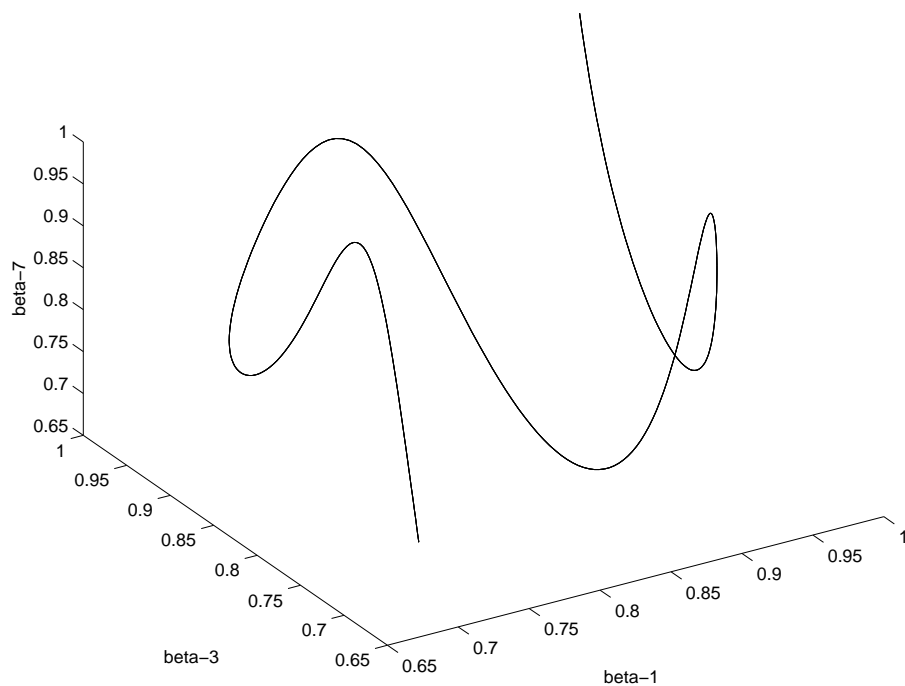
$$(i) \frac{\partial V}{\partial x} = -\frac{A}{\rho c^2} \frac{\partial P}{\partial t}$$

$$(ii) \frac{\partial P}{\partial x} = -\frac{\rho}{A} \frac{\partial V}{\partial t}$$

$V(x, t)$ = volume velocity

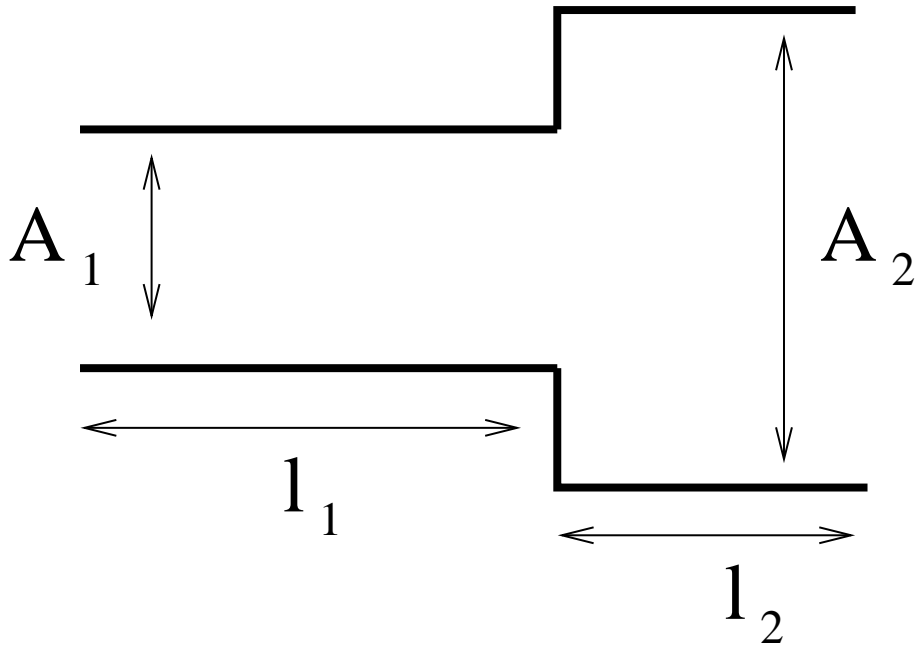
$P(x, t)$ = pressure

Solutions



$$u(t) = \sum_{n=1}^{\infty} \alpha_n \sin(n\omega_0 t) \in l_2$$

$$s(t) = \sum_{n=1}^{\infty} \beta_n \sin(n\omega_0 t) \in l_2$$

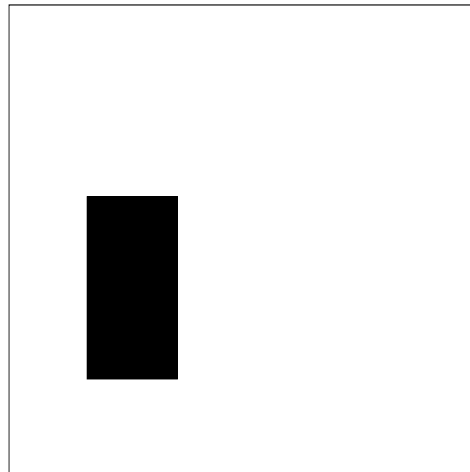


Vocal Tract modeled as a sequence of tubes.
(e.g. Stevens, 1998)

Vision Example

$$f : \mathbb{R}^2 \rightarrow [0, 1]$$

$$\mathcal{F} = \{f \mid f(x, y) = v(x - t, y - r)\}$$



Learning when data $\sim \mathcal{M} \subset \mathbb{R}^N$

- ▶ Clustering: $\mathcal{M} \rightarrow \{1, \dots, k\}$
connected components, min cut
- ▶ Classification: $\mathcal{M} \rightarrow \{-1, +1\}$
 P on $\mathcal{M} \times \{-1, +1\}$
- ▶ Dimensionality Reduction: $f : \mathcal{M} \rightarrow \mathbb{R}^n \quad n \ll N$
- ▶ \mathcal{M} unknown: what can you learn about \mathcal{M} from data?
e.g. dimensionality, connected components
holes, handles, homology
curvature, geodesics

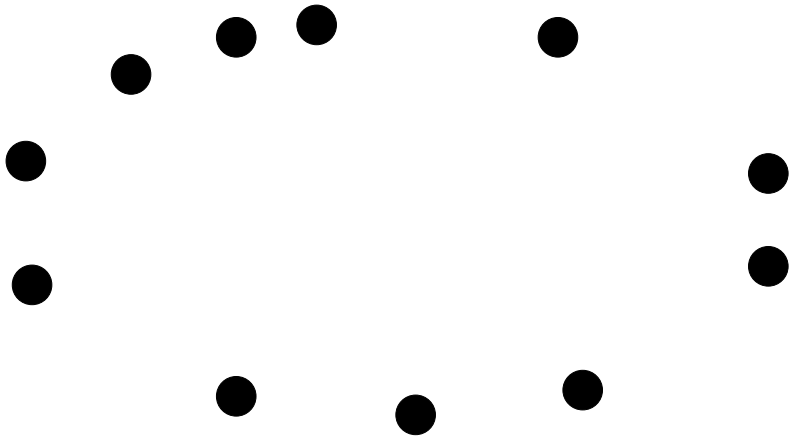
Dimensionality Reduction

Given $x_1, \dots, x_n \in \mathcal{M} \subset \mathbb{R}^N$,

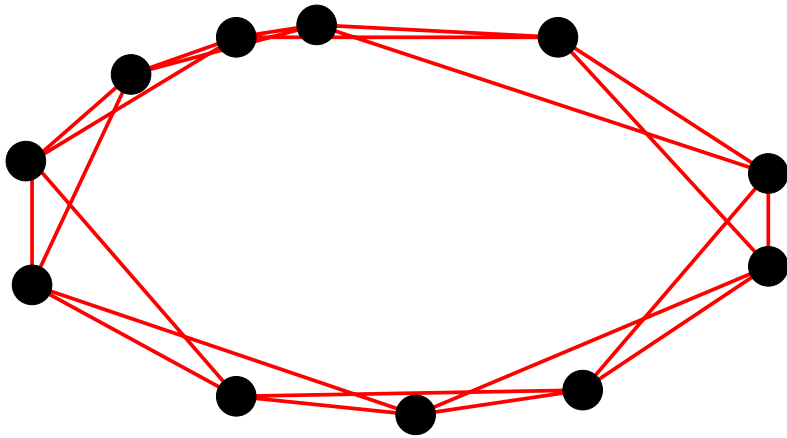
Find $y_1, \dots, y_n \in \mathbb{R}^d$ where $d \ll N$

- ▶ ISOMAP (Tenenbaum, et al, 00)
- ▶ LLE (Roweis, Saul, 00)
- ▶ Laplacian Eigenmaps (Belkin, Niyogi, 01)
- ▶ Hessian Eigenmaps (Donoho, Grimes, 02)
- ▶ Diffusion Maps (Coifman, Lafon, et al, 04)

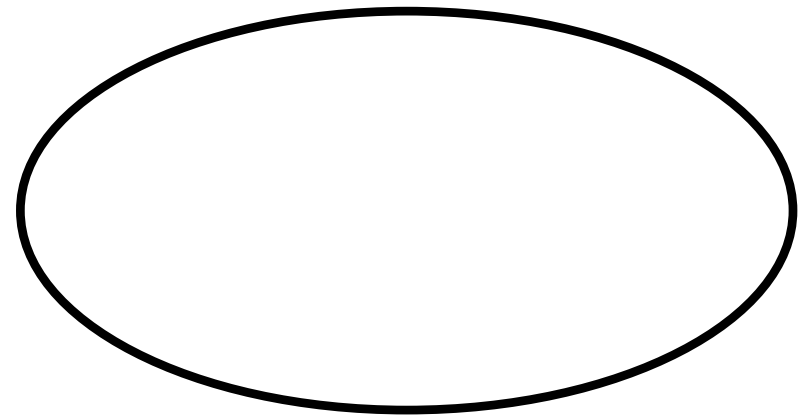
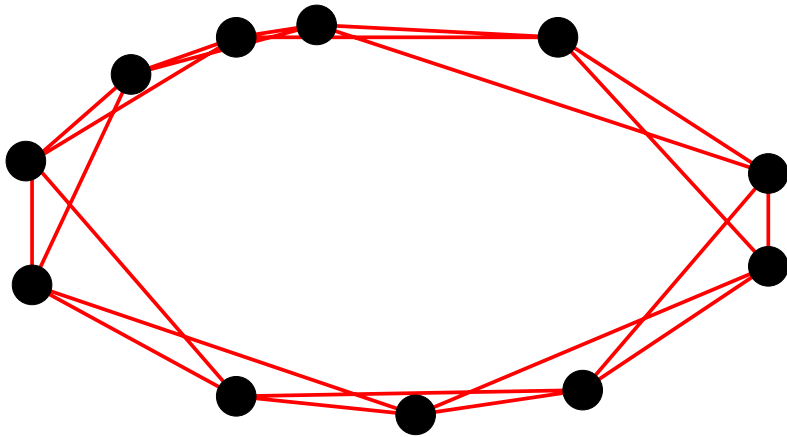
Algorithmic framework



Algorithmic framework



Algorithmic framework



Neighborhood graph common to all methods.

1. Construct Neighborhood Graph.
2. Find **shortest path** distances.

D_{ij} is $n \times n$

3. Embed using Multidimensional Scaling.

Multidimensional Scaling

Consider a positive definite matrix A .

Then A_{ij} corresponds to inner products.

$$A = \sum_{i=1}^n \lambda_i \phi_i \phi_i^T$$

Then for any $x \in \{1, \dots, n\}$

$$\psi(x) = \left(\sqrt{\lambda_1} \phi_1(x), \dots, \sqrt{\lambda_k} \phi_k(x) \right) \in \mathbb{R}^k$$

approximates inner products and therefore distances.

Therefore find A such that

$$A_{ii} + A_{jj} - 2A_{ij} \approx D_{ij}$$

Good Answer:

$$A = -\frac{1}{2}HDH \text{ where } H = I - \frac{1}{n}\mathbf{1}\mathbf{1}^T$$

Laplacian Eigenmaps

Step 1 [Constructing the Graph]

$$e_{ij} = 1 \Leftrightarrow \mathbf{x}_i \text{ "close to" } \mathbf{x}_j$$

1. ϵ -neighborhoods. [parameter $\epsilon \in \mathbb{R}$] Nodes i and j are connected by an edge if

$$\|\mathbf{x}_i - \mathbf{x}_j\|^2 < \epsilon$$

2. n nearest neighbors. [parameter $n \in \mathbb{N}$] Nodes i and j are connected by an edge if i is among n nearest neighbors of j or j is among n nearest neighbors of i .

Laplacian Eigenmaps

Step 2. [*Choosing the weights*].

1. **Heat kernel.** [*parameter $t \in \mathbb{R}$*]. If nodes i and j are connected, put

$$W_{ij} = e^{-\frac{\|x_i - x_j\|^2}{t}}$$

2. **Simple-minded.** [*No parameters*]. $W_{ij} = 1$ if and only if vertices i and j are connected by an edge.

Laplacian Eigenmaps

Step 3. [*Eigenmaps*] Compute eigenvalues and eigenvectors for the generalized eigenvector problem:

$$Lf = \lambda Df$$

D is diagonal matrix where

$$D_{ii} = \sum_j W_{ij}$$

$$L = D - W$$

Let $\mathbf{f}_0, \dots, \mathbf{f}_{k-1}$ be eigenvectors.

Leave out the eigenvector \mathbf{f}_0 and use the next m lowest eigenvectors for embedding in an m -dimensional Euclidean space.

Find $y_1, \dots, y_n \in \mathbb{R}$

$$\min \sum_{i,j} (y_i - y_j)^2 W_{ij}$$

Tries to preserve **locality**

A Fundamental Identity

But

$$\frac{1}{2} \sum_{i,j} (y_i - y_j)^2 W_{ij} = \mathbf{y}^T L \mathbf{y}$$

$$\begin{aligned} \sum_{i,j} (y_i - y_j)^2 W_{ij} &= \sum_{i,j} (y_i^2 + y_j^2 - 2y_i y_j) W_{ij} \\ &= \sum_i y_i^2 D_{ii} + \sum_j y_j^2 D_{jj} - 2 \sum_{i,j} y_i y_j W_{ij} \\ &= 2\mathbf{y}^T L \mathbf{y} \end{aligned}$$

$$\lambda = 0 \rightarrow \mathbf{y} = \mathbf{1}$$

$$\min_{\mathbf{y}^T \mathbf{1} = 0} \mathbf{y}^T L \mathbf{y}$$

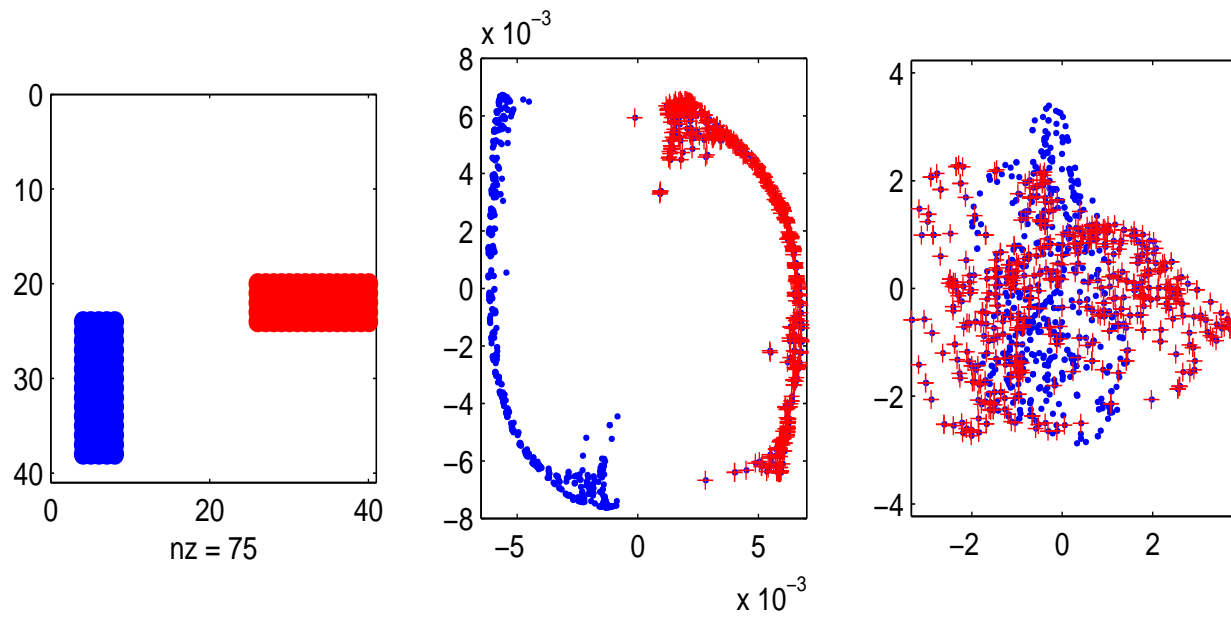
Let $Y = [\mathbf{y}_1 \mathbf{y}_2 \dots \mathbf{y}_m]$

$$\sum_{i,j} \|Y_i - Y_j\|^2 W_{ij} = \text{trace}(Y^T L Y)$$

subject to $Y^T Y = I$.

Use eigenvectors of L to embed.

PCA versus Laplacian Eigenmaps



smooth map $f : \mathcal{M} \rightarrow \mathbb{R}$

$$\int_{\mathcal{M}} \|\nabla_{\mathcal{M}} f\|^2 \approx \sum_{i \sim j} W_{ij} (f_i - f_j)^2$$

Recall standard gradient in \mathbb{R}^k of $f(z_1, \dots, z_k)$

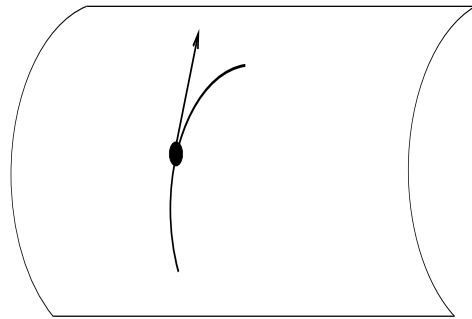
$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial z_1} \\ \frac{\partial f}{\partial z_2} \\ \cdot \\ \cdot \\ \frac{\partial f}{\partial z_k} \end{bmatrix}$$

Curves on Manifolds

Consider a curve on \mathcal{M}

$$c(t) \in \mathcal{M} \quad t \in (-1, 1) \quad p = c(0); \quad q = c(\tau)$$

$$f(c(t)) : (-1, 1) \rightarrow \mathbb{R}$$



$$|f(0) - f(\tau)| \lesssim d_G(p, q) \|\nabla_M f(p)\|$$

A Basic Fact

$$\int_{\mathcal{M}} \|\nabla_{\mathcal{M}} f\|^2 = \int f \cdot \Delta_{\mathcal{M}} f$$

This is like

$$\sum_{i,j} W_{ij} (f_i - f_j)^2 = \mathbf{f}^T \mathbf{L} \mathbf{f}$$

where

$\Delta_{\mathcal{M}} f$ is the manifold Laplacian

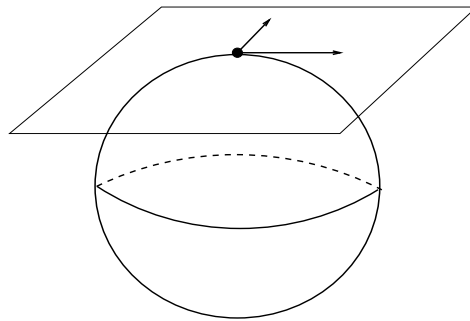
Manifold Laplacian

Recall ordinary Laplacian in \mathbb{R}^k

This maps

$$f(x_1, \dots, x_k) \rightarrow \left(- \sum_{i=1}^k \frac{\partial^2 f}{\partial x_i^2} \right)$$

Manifold Laplacian is the same on the tangent space.



Properties of Laplacian

Eigensystem

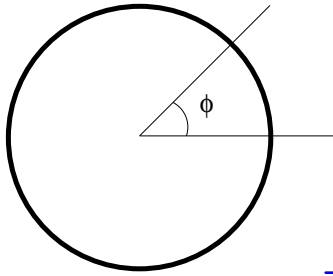
$$\Delta_{\mathcal{M}} f = \lambda_i \phi_i$$

$$\lambda_i \geq 0 \text{ and } \lambda_i \rightarrow \infty$$

$\{\phi_i\}$ form an orthonormal basis for $L^2(\mathcal{M})$

$$\int \|\nabla_{\mathcal{M}} \phi_i\|^2 = \lambda_i$$

The Circle: An Example



$$-\frac{d^2u}{dt^2} = \lambda u \text{ where } u(0) = u(2\pi)$$

Eigenvalues are

$$\lambda_n = n^2$$

Eigenfunctions are

$$\sin(nt), \cos(nt)$$

From graphs to manifolds

$$f : \mathcal{M} \rightarrow \mathbb{R} \quad x \in \mathcal{M} \quad x_1, \dots, x_n \in \mathcal{M}$$

Graph Laplacian:

$$L_n^t(f)(x) = f(x) \sum_j e^{-\frac{\|x-x_j\|^2}{t}} - \sum_j f(x_j) e^{-\frac{\|x-x_j\|^2}{t}}$$

Theorem 1 [pointwise convergence] $t_n = n^{-\frac{1}{k+2+\alpha}}$

$$\lim_{n \rightarrow \infty} \frac{(4\pi t_n)^{-\frac{k+2}{2}}}{n} L_n^{t_n} f(x) = \mathcal{L}_{\mathcal{M}} f(x)$$

Theorem 2 [uniform convergence]

$$\lim_{n \rightarrow \infty} \sup_{x \in \mathcal{M}, f \in \mathcal{B}} \left| \frac{(4\pi t_n)^{-\frac{k+2}{2}}}{n} L_n^{t_n} f(x) - \mathcal{L}_{\mathcal{M}} f(x) \right| = 0$$

Theorem 3 [convergence of eigenfunctions]

$$Eig[L_n^{t_n}] \rightarrow Eig[\mathcal{L}_{\mathcal{M}}]$$