

# Advanced Geometric Methods in Computer Science

## Jean Gallier & Dan Guralnik

### Homework 3

June 14; Due June 21, 2013

Do Exercise 2.IV.1, 2.IV.4, 3.III.1, and 3.IV.1, from the handouts on the web, and the problems below.

**Problem B1 (20 pts).** Let  $\varphi: E \times E \rightarrow \mathbb{R}$  be a bilinear form on a real vector space  $E$  of finite dimension  $n$ . Given any basis  $(e_1, \dots, e_n)$  of  $E$ , let  $A = (a_{ij})$  be the matrix defined such that

$$a_{ij} = \varphi(e_i, e_j),$$

$1 \leq i, j \leq n$ . We call  $A$  the matrix of  $\varphi$  w.r.t. the basis  $(e_1, \dots, e_n)$ .

(a) For any two vectors  $x$  and  $y$ , if  $X$  and  $Y$  denote the column vectors of coordinates of  $x$  and  $y$  w.r.t. the basis  $(e_1, \dots, e_n)$ , prove that

$$\varphi(x, y) = X^T AY.$$

(b) Recall that  $A$  is a *symmetric* matrix if  $A = A^T$ . Prove that  $\varphi$  is symmetric if  $A$  is a symmetric matrix.

(c) If  $(f_1, \dots, f_n)$  is another basis of  $E$  and  $P$  is the change of basis matrix from  $(e_1, \dots, e_n)$  to  $(f_1, \dots, f_n)$ , prove that the matrix of  $\varphi$  w.r.t. the basis  $(f_1, \dots, f_n)$  is

$$P^T AP.$$

The common rank of all matrices representing  $\varphi$  is called the *rank* of  $\varphi$ .

**Problem B2 (40 pts).** Let  $\varphi: E \times E \rightarrow \mathbb{R}$  be a symmetric bilinear form on a real vector space  $E$  of finite dimension  $n$ . Two vectors  $x$  and  $y$  are said to be *conjugate or orthogonal* w.r.t.  $\varphi$  if  $\varphi(x, y) = 0$ . The main purpose of this problem is to prove that there is a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ .

(a) Prove that if  $\varphi(x, x) = 0$  for all  $x \in E$ , then  $\varphi$  is identically null on  $E$ .

Otherwise, we can assume that there is some vector  $x \in E$  such that  $\varphi(x, x) \neq 0$ . Use induction to prove that there is a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ .

For the induction step, proceed as follows. Let  $(e_1, e_2, \dots, e_n)$  be a basis of  $E$ , with  $\varphi(e_1, e_1) \neq 0$ . Prove that there are scalars  $\lambda_2, \dots, \lambda_n$  such that each of the vectors

$$v_i = e_i + \lambda_i e_1$$

is conjugate to  $e_1$  w.r.t.  $\varphi$ , where  $2 \leq i \leq n$ , and that  $(e_1, v_2, \dots, v_n)$  is a basis.

(b) Let  $(e_1, \dots, e_n)$  be a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ , and assume that they are ordered such that

$$\varphi(e_i, e_i) = \begin{cases} \theta_i \neq 0 & \text{if } 1 \leq i \leq r, \\ 0 & \text{if } r+1 \leq i \leq n, \end{cases}$$

where  $r$  is the rank of  $\varphi$ . Show that the matrix of  $\varphi$  w.r.t.  $(e_1, \dots, e_n)$  is a diagonal matrix, and that

$$\varphi(x, y) = \sum_{i=1}^r \theta_i x_i y_i,$$

where  $x = \sum_{i=1}^n x_i e_i$  and  $y = \sum_{i=1}^n y_i e_i$ .

Prove that for every symmetric matrix  $A$ , there is an invertible matrix  $P$  such that

$$P^\top A P = D,$$

where  $D$  is a diagonal matrix.

(c) Prove that there is an integer  $p$ ,  $0 \leq p \leq r$  (where  $r$  is the rank of  $\varphi$ ), such that  $\varphi(u_i, u_i) > 0$  for exactly  $p$  vectors of every basis  $(u_1, \dots, u_n)$  of vectors that are pairwise conjugate w.r.t.  $\varphi$  (*Sylvester's inertia theorem*).

Proceed as follows. Assume that in the basis  $(u_1, \dots, u_n)$ , for any  $x \in E$ , we have

$$\varphi(x, x) = \alpha_1 x_1^2 + \dots + \alpha_p x_p^2 - \alpha_{p+1} x_{p+1}^2 - \dots - \alpha_r x_r^2,$$

where  $x = \sum_{i=1}^n x_i u_i$ , and that in the basis  $(v_1, \dots, v_n)$ , for any  $x \in E$ , we have

$$\varphi(x, x) = \beta_1 y_1^2 + \dots + \beta_q y_q^2 - \beta_{q+1} y_{q+1}^2 - \dots - \beta_r y_r^2,$$

where  $x = \sum_{i=1}^n y_i v_i$ , with  $\alpha_i > 0$ ,  $\beta_i > 0$ ,  $1 \leq i \leq r$ .

Assume that  $p > q$  and derive a contradiction. First, consider  $x$  in the subspace  $F$  spanned by

$$(u_1, \dots, u_p, u_{r+1}, \dots, u_n),$$

and observe that  $\varphi(x, x) \geq 0$  if  $x \neq 0$ . Next, consider  $x$  in the subspace  $G$  spanned by

$$(v_{q+1}, \dots, v_r),$$

and observe that  $\varphi(x, x) < 0$  if  $x \neq 0$ . Prove that  $F \cap G$  is nontrivial (i.e., contains some nonnull vector), and derive a contradiction. This implies that  $p \leq q$ . Finish the proof.

The pair  $(p, r - p)$  is called the *signature* of  $\varphi$ .

(d) A symmetric bilinear form  $\varphi$  is *definite* if for every  $x \in E$ , if  $\varphi(x, x) = 0$ , then  $x = 0$ .

Prove that a symmetric bilinear form is definite iff its signature is either  $(n, 0)$  or  $(0, n)$ . In other words, a symmetric definite bilinear form has rank  $n$  and is either positive or negative.

**Problem B3 (30 pts).** Let  $\| \cdot \|$  be any matrix norm. Given an invertible  $n \times n$  matrix  $A$ , if  $c = 1/(2 \|A^{-1}\|)$ , then for every  $n \times n$  matrix  $H$ , if  $\|H\| \leq c$ , then  $A + H$  is invertible. Furthermore, if  $\| \cdot \|$  is an operator norm and if  $\|H\| \leq c$ , then  $\|(A + H)^{-1}\| \leq 1/c$ .

**Problem B4 (20 pts).** Let  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  be the function given by

$$f(x, y) = \begin{cases} \frac{x^2 y}{x^4 + y^2} & \text{if } (x, y) \neq (0, 0) \\ 0 & \text{if } (x, y) = (0, 0). \end{cases}$$

(a) Compute the directional derivative  $D_u f(0, 0)$  of  $f$  at  $(0, 0)$  for every vector  $u = (u_1, u_2) \neq 0$ .

(b) Prove that the derivative  $Df(0, 0)$  does not exist. What is the behavior of the function  $f$  on the parabola  $y = x^2$  near the origin  $(0, 0)$ ?

**Problem B5 (40 pts).** (a) Let  $f: M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$  be the function defined on  $n \times n$  matrices by

$$f(A) = A^2.$$

Prove that

$$Df_A(H) = AH + HA,$$

for all  $A, H \in M_n(\mathbb{R})$ .

(b) Let  $f: M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$  be the function defined on  $n \times n$  matrices by

$$f(A) = A^3.$$

Prove that

$$Df_A(H) = A^2 H + A H A + H A^2,$$

for all  $A, H \in M_n(\mathbb{R})$ .

(c) Let  $f: GL(n, \mathbb{R}) \rightarrow M_n(\mathbb{R})$  be the function defined on invertible  $n \times n$  matrices by

$$f(A) = A^{-1}.$$

Prove that

$$Df_A(H) = -A^{-1} H A^{-1},$$

for all  $A \in GL(n, \mathbb{R})$  and for all  $H \in M_n(\mathbb{R})$ .

**Problem B6 (60 pts).** Let  $H$  be a symmetric positive definite matrix and let  $K$  be any symmetric matrix.

(1) Prove that  $HK$  is diagonalizable, with real eigenvalues.

(2) If  $K$  is also positive definite, then prove that the eigenvalues of  $HK$  are positive.

(3) If  $K$  is any symmetric matrix, prove that the number of positive (resp. negative) eigenvalues of  $HK$  is equal to the number of positive (resp. negative) eigenvalues of  $K$ .

**Problem B7 (80 pts).** Recall that a matrix  $B \in M_n(\mathbb{R})$  is skew-symmetric if

$$B^\top = -B.$$

Check that the set  $\mathfrak{so}(n)$  of skew-symmetric matrices is a vector space of dimension  $n(n-1)/2$ , and thus is isomorphic to  $\mathbb{R}^{n(n-1)/2}$ .

(a) Given a rotation matrix

$$R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix},$$

where  $0 < \theta < \pi$ , prove that there is a skew symmetric matrix  $B$  such that

$$R = (I - B)(I + B)^{-1}.$$

(b) Prove that the eigenvalues of a skew-symmetric matrix are either 0 or pure imaginary (that is, of the form  $i\mu$  for  $\mu \in \mathbb{R}$ ).

Let  $C: \mathfrak{so}(n) \rightarrow M_n(\mathbb{R})$  be the function given by

$$C(B) = (I - B)(I + B)^{-1}.$$

Prove that if  $B$  is skew-symmetric, then  $I - B$  and  $I + B$  are invertible, and so  $C$  is well-defined. Prove that

$$(I + B)(I - B) = (I - B)(I + B),$$

and that

$$(I + B)(I - B)^{-1} = (I - B)^{-1}(I + B).$$

Prove that

$$(C(B))^\top C(B) = I$$

and that

$$\det C(B) = +1,$$

so that  $C(B)$  is a rotation matrix. Furthermore, show that  $C(B)$  does not admit  $-1$  as an eigenvalue.

(c) Let  $\mathbf{SO}(n)$  be the group of  $n \times n$  rotation matrices. Prove that the map

$$C: \mathfrak{so}(n) \rightarrow \mathbf{SO}(n)$$

is bijective onto the subset of rotation matrices that do not admit  $-1$  as an eigenvalue. Show that the inverse of this map is given by

$$B = (I + R)^{-1}(I - R) = (I - R)(I + R)^{-1},$$

where  $R \in \mathbf{SO}(n)$  does not admit  $-1$  as an eigenvalue. Check that  $C$  is a homeomorphism between  $\mathfrak{so}(n)$  and  $C(\mathfrak{so}(n))$ .

(d) If  $f: M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$  and  $g: M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$  are differentiable matrix functions, prove that

$$d(fg)_A(B) = df_A(B)g(A) + f(A)dg_A(B),$$

for all  $A, B \in M_n(\mathbb{R})$ .

(e) Prove that

$$dC(B)(A) = -[I + (I - B)(I + B)^{-1}]A(I + B)^{-1}.$$

Prove that  $dC(B)$  is injective, for every skew-symmetric matrix  $B$ . Prove that  $C$  a parametrization of  $\mathbf{SO}(n)$ .