

## Advanced geometric methods

## Homework 2

October 27, 2003; Due November 11, beginning of class

You may work in groups of 2 or 3. Please, write up your solutions as clearly and concisely as possible. Be rigorous! You will have to present your solutions of the problems during a special problem session.

“A problems” are for practice only, and should not be turned in.

**Problem A1.** Let  $(e_1, \dots, e_n)$  be an orthonormal basis for  $E$ . If  $X$  and  $Y$  are arbitrary  $n \times n$  matrices, denoting as usual the  $j$ th column of  $X$  by  $X_j$ , and similarly for  $Y$ , show that

$$X^T Y = (X_i \cdot Y_j)_{1 \leq i, j \leq n}.$$

Use this to prove that

$$A^T A = A A^T = I_n$$

iff the column vectors  $(A_1, \dots, A_n)$  form an orthonormal basis. Show that the conditions  $A A^T = I_n$ ,  $A^T A = I_n$ , and  $A^{-1} = A^T$  are equivalent.

**Problem A2.** Compute the real Fourier coefficients of the function  $id(x) = x$  over  $[-\pi, \pi]$  and prove that

$$x = 2 \left( \frac{\sin x}{1} - \frac{\sin 2x}{2} + \frac{\sin 3x}{3} - \dots \right).$$

What is the value of the Fourier series at  $\pm\pi$ ? What is the value of the Fourier near  $\pm\pi$ ? Do you find this surprising?

**Problem A3.** Prove Lemma 6.2.2 from my book.

“B problems” must be turned in.

**Problem B1 (30 pts).** (1) If an upper triangular  $n \times n$  matrix  $R$  is invertible, prove that its inverse is also upper triangular.

(2) If an upper triangular matrix is orthogonal, prove that it must be a diagonal matrix.

If  $A$  is an invertible  $n \times n$  matrix and if  $A = Q_1 R_1 = Q_2 R_2$ , where  $R_1$  and  $R_2$  are upper triangular with positive diagonal entries and  $Q_1, Q_2$  are orthogonal, prove that  $Q_1 = Q_2$  and  $R_1 = R_2$ .

**Problem B2 (30 pts).** Consider the Euclidean space  $\mathbb{E}^n$ , and let  $O = (0, \dots, 0)$ . Given any  $x \in \mathbb{E}^n$ ,  $x \neq O$ , let  $H(x)$  be the affine hyperplane perpendicular to  $Ox$  and passing through the point  $x'$  on the line  $Ox$  and such that  $\mathbf{Ox} \cdot \mathbf{Ox}' = 1$ . Equivalently,  $H(x)$  is the affine hyperplane defined by

$$H(x) = \{y \in \mathbb{E}^n \mid x \cdot y = 1\}.$$

We call  $H(x)$  the *polar* or *dual* of  $x$ . Conversely, given any affine hyperplane  $H$  not passing through  $O$ , there is clearly a unique  $x \in \mathbb{E}^n$  so that  $H(x) = H$ , and we call  $x$  the *pole* or *dual* of  $H$ .

Given a subset  $A$  of  $\mathbb{E}^n$ , let

$$A^* = \{y \in \mathbb{E}^n \mid x \cdot y \leq 1, \forall x \in A\}.$$

We call  $A^*$  the *polar* or *reciprocal* of  $A$ .

(a) Check that  $A^*$  is the intersection of all the closed half-spaces containing  $O$  determined by the polar hyperplanes of points of  $A$ . Thus, conclude that  $A^*$  is convex.

Let  $B^n(r)$  be the ball of radius  $r > 0$  and center  $O$ , i.e.,

$$B^n(r) = \{x \in \mathbb{E}^n \mid \|x\| \leq r\}.$$

Show that  $B^n(r)^* = B^n(1/r)$ .

Prove that the dual  $C^*$  of the cube  $C = [-1, 1]^n$  is the convex hull of the  $2n$  points  $\{e_i, -e_i \mid 1 \leq i \leq n\}$ , where  $e_i = (0, \dots, 0, 1, 0, \dots, 0)$ , the  $i$ th vector in the standard basis. The dual of a cube is called a *cross-polytope*. Check that the cube  $C$  has  $2^n$  vertices and  $2n$  faces, whereas its dual  $C^*$  has  $2n$  vertices and  $2^n$  faces. Draw  $C^*$  for  $n = 3$ .

(b) A *convex polyhedron* or *convex body*  $P$  is a bounded subset of  $\mathbb{E}^n$  with nonempty interior obtained as the intersection of a finite number of closed half-spaces. We will prove in class that a convex polyhedron  $P$  is the convex hull of a finite set of points with nonempty interior and conversely. We will also prove that the dual of a convex polyhedron containing  $O$  is a convex polyhedron. Observe that the duality exchanges vertices of  $P$  and the faces of  $P^*$ .

What is the dual of an  $n$ -simplex?

(c) Consider in  $\mathbb{E}^3$  the polyhedron  $I$  defined as follows. If  $\tau = (\sqrt{5} + 1)/2$ , then the vertices of  $I$  are the twelve points

$$(0, \pm\tau, \pm 1), \quad (\pm 1, 0, \pm\tau), \quad (\pm\tau, \pm 1, 0).$$

This polyhedron is called an *icosahedron*. Check that the icosahedron has 20 faces. Draw an icosahedron (or better, make a cardboard model).

Prove that the dual  $D$  of the icosahedron is a convex polyhedron whose twenty vertices are

$$(\pm 1, \pm 1, \pm 1), \quad (0, \pm 1/\tau, \pm \tau), \quad (\pm \tau, 0, \pm 1/\tau), \quad (\pm 1/\tau, \pm \tau, 0).$$

This polyhedron  $D$  is called a *dodecahedron*. Observe that it is “built up” on the cube  $[-1, 1]^3$ . Can you explain how? Check that the dodecahedron has 12 faces. Draw a dodecahedron (or better, make a cardboard model).

**Problem B3 (50 pts).** (1) Review the modified Gram–Schmidt method. Recall that to compute  $Q'_{k+1}$ , instead of projecting  $A_{k+1}$  onto  $Q_1, \dots, Q_k$  in a single step, it is better to perform  $k$  projections. We compute  $Q_{k+1}^1, Q_{k+1}^2, \dots, Q_{k+1}^k$  as follows:

$$\begin{aligned} Q_{k+1}^1 &= A_{k+1} - (A_{k+1} \cdot Q_1) Q_1, \\ Q_{k+1}^{i+1} &= Q_{k+1}^i - (Q_{k+1}^i \cdot Q_{i+1}) Q_{i+1}, \end{aligned}$$

where  $1 \leq i \leq k-1$ .

Prove that  $Q'_{k+1} = Q_{k+1}^k$ .

(2) Write two computer programs to compute the  $QR$ -decomposition of an invertible matrix. The first one should use the standard Gram–Schmidt method, and the second one the modified Gram–Schmidt method. Run both on a number of matrices, up to dimension at least 10. Do you observe any difference in their performance in terms of numerical stability?

Run your programs on the Hilbert matrix  $H_n = (1/(i+j-1))_{1 \leq i, j \leq n}$ . What happens?

**Extra Credit.** (20 points) Write a program to solve linear systems of equations  $Ax = b$ , using your version of the  $QR$ -decomposition program, where  $A$  is an  $n \times n$  matrix.

**Problem B4 (30 pts).** Let  $\varphi: E \times E \rightarrow \mathbb{R}$  be a bilinear form on a real vector space  $E$  of finite dimension  $n$ . Given any basis  $(e_1, \dots, e_n)$  of  $E$ , let  $A = (\alpha_{ij})$  be the matrix defined such that

$$\alpha_{ij} = \varphi(e_i, e_j),$$

$1 \leq i, j \leq n$ . We call  $A$  the matrix of  $\varphi$  w.r.t. the basis  $(e_1, \dots, e_n)$ .

(a) For any two vectors  $x$  and  $y$ , if  $X$  and  $Y$  denote the column vectors of coordinates of  $x$  and  $y$  w.r.t. the basis  $(e_1, \dots, e_n)$ , prove that

$$\varphi(x, y) = X^T AY.$$

(b) Recall that  $A$  is a *symmetric* matrix if  $A = A^T$ . Prove that  $\varphi$  is symmetric if  $A$  is a symmetric matrix.

(c) If  $(f_1, \dots, f_n)$  is another basis of  $E$  and  $P$  is the change of basis matrix from  $(e_1, \dots, e_n)$  to  $(f_1, \dots, f_n)$ , prove that the matrix of  $\varphi$  w.r.t. the basis  $(f_1, \dots, f_n)$  is

$$P^T AP.$$

The common rank of all matrices representing  $\varphi$  is called the *rank* of  $\varphi$ .

**Problem B5 (80 pts).** Let  $\varphi: E \times E \rightarrow \mathbb{R}$  be a symmetric bilinear form on a real vector space  $E$  of finite dimension  $n$ . Two vectors  $x$  and  $y$  are said to be *conjugate w.r.t.  $\varphi$*  if  $\varphi(x, y) = 0$ . The main purpose of this problem is to prove that there is a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ .

(a) Prove that if  $\varphi(x, x) = 0$  for all  $x \in E$ , then  $\varphi$  is identically null on  $E$ .

Otherwise, we can assume that there is some vector  $x \in E$  such that  $\varphi(x, x) \neq 0$ . Use induction to prove that there is a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ .

For the induction step, proceed as follows. Let  $(e_1, e_2, \dots, e_n)$  be a basis of  $E$ , with  $\varphi(e_1, e_1) \neq 0$ . Prove that there are scalars  $\lambda_2, \dots, \lambda_n$  such that each of the vectors

$$v_i = e_i + \lambda_i e_1$$

is conjugate to  $e_1$  w.r.t.  $\varphi$ , where  $2 \leq i \leq n$ , and that  $(e_1, v_2, \dots, v_n)$  is a basis.

(b) Let  $(e_1, \dots, e_n)$  be a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$ , and assume that they are ordered such that

$$\varphi(e_i, e_i) = \begin{cases} \theta_i \neq 0 & \text{if } 1 \leq i \leq r, \\ 0 & \text{if } r+1 \leq i \leq n, \end{cases}$$

where  $r$  is the rank of  $\varphi$ . Show that the matrix of  $\varphi$  w.r.t.  $(e_1, \dots, e_n)$  is a diagonal matrix, and that

$$\varphi(x, y) = \sum_{i=1}^r \theta_i x_i y_i,$$

where  $x = \sum_{i=1}^n x_i e_i$  and  $y = \sum_{i=1}^n y_i e_i$ .

Prove that for every symmetric matrix  $A$ , there is an invertible matrix  $P$  such that

$$P^\top A P = D,$$

where  $D$  is a diagonal matrix.

(c) Prove that there is an integer  $p$ ,  $0 \leq p \leq r$  (where  $r$  is the rank of  $\varphi$ ), such that  $\varphi(u_i, u_i) > 0$  for exactly  $p$  vectors of every basis  $(u_1, \dots, u_n)$  of vectors that are pairwise conjugate w.r.t.  $\varphi$  (*Sylvester's inertia theorem*).

Proceed as follows. Assume that in the basis  $(u_1, \dots, u_n)$ , for any  $x \in E$ , we have

$$\varphi(x, x) = \alpha_1 x_1^2 + \dots + \alpha_p x_p^2 - \alpha_{p+1} x_{p+1}^2 - \dots - \alpha_r x_r^2,$$

where  $x = \sum_{i=1}^n x_i u_i$ , and that in the basis  $(v_1, \dots, v_n)$ , for any  $x \in E$ , we have

$$\varphi(x, x) = \beta_1 y_1^2 + \dots + \beta_q y_q^2 - \beta_{q+1} y_{q+1}^2 - \dots - \beta_r y_r^2,$$

where  $x = \sum_{i=1}^n y_i v_i$ , with  $\alpha_i > 0$ ,  $\beta_i > 0$ ,  $1 \leq i \leq r$ .

Assume that  $p > q$  and derive a contradiction. First, consider  $x$  in the subspace  $F$  spanned by

$$(u_1, \dots, u_p, u_{r+1}, \dots, u_n),$$

and observe that  $\varphi(x, x) \geq 0$  if  $x \neq 0$ . Next, consider  $x$  in the subspace  $G$  spanned by

$$(v_{q+1}, \dots, v_r),$$

and observe that  $\varphi(x, x) < 0$  if  $x \neq 0$ . Prove that  $F \cap G$  is nontrivial (i.e., contains some nonnull vector), and derive a contradiction. This implies that  $p \leq q$ . Finish the proof.

The pair  $(p, r - p)$  is called the *signature* of  $\varphi$ .

(d) A symmetric bilinear form  $\varphi$  is *definite* if for every  $x \in E$ , if  $\varphi(x, x) = 0$ , then  $x = 0$ .

Prove that a symmetric bilinear form is definite iff its signature is either  $(n, 0)$  or  $(0, n)$ . In other words, a symmetric definite bilinear form has rank  $n$  and is either positive or negative.

(e) The *kernel* of a symmetric bilinear form  $\varphi$  is the subspace consisting of the vectors that are conjugate to all vectors in  $E$ . We say that a symmetric bilinear form  $\varphi$  is *nondegenerate* if its kernel is trivial (i.e., equal to  $\{0\}$ ).

Prove that a symmetric bilinear form  $\varphi$  is nondegenerate iff its rank is  $n$ , the dimension of  $E$ . Is a definite symmetric bilinear form  $\varphi$  nondegenerate? What about the converse?

Prove that if  $\varphi$  is nondegenerate, then there is a basis of vectors that are pairwise conjugate w.r.t.  $\varphi$  and such that  $\varphi$  is represented by the matrix

$$\begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix}$$

where  $(p, q)$  is the signature of  $\varphi$ .

(f) Given a nondegenerate symmetric bilinear form  $\varphi$  on  $E$ , prove that for every linear map  $f: E \rightarrow E$ , there is a unique linear map  $f^*: E \rightarrow E$  such that

$$\varphi(f(u), v) = \varphi(u, f^*(v)),$$

for all  $u, v \in E$ . The map  $f^*$  is called the *adjoint of  $f$  (w.r.t. to  $\varphi$ )*. Given any basis  $(u_1, \dots, u_n)$ , if  $\Omega$  is the matrix representing  $\varphi$  and  $A$  is the matrix representing  $f$ , prove that  $f^*$  is represented by  $\Omega^{-1}A^T\Omega$ .

Prove that Lemma 6.2.4 of my book also holds, i.e., the map  $\flat: E \rightarrow E^*$  is a canonical isomorphism.

A linear map  $f: E \rightarrow E$  is an *isometry w.r.t.  $\varphi$*  if

$$\varphi(f(x), f(y)) = \varphi(x, y)$$

for all  $x, y \in E$ . Prove that a linear map  $f$  is an isometry w.r.t.  $\varphi$  iff

$$f^* \circ f = f \circ f^* = \text{id}.$$

Prove that the set of isometries w.r.t.  $\varphi$  is a group. This group is denoted by  $\mathbf{O}(\varphi)$ , and its subgroup consisting of isometries having determinant  $+1$  by  $\mathbf{SO}(\varphi)$ . Given any basis of  $E$ , if  $\Omega$  is the matrix representing  $\varphi$  and  $A$  is the matrix representing  $f$ , prove that  $f \in \mathbf{O}(\varphi)$  iff

$$A^\top \Omega A = \Omega.$$

Given another nondegenerate symmetric bilinear form  $\psi$  on  $E$ , we say that  $\varphi$  and  $\psi$  are *equivalent* if there is a bijective linear map  $h: E \rightarrow E$  such that

$$\psi(x, y) = \varphi(h(x), h(y)),$$

for all  $x, y \in E$ . Prove that the groups of isometries  $\mathbf{O}(\varphi)$  and  $\mathbf{O}(\psi)$  are isomorphic (use the map  $f \mapsto h \circ f \circ h^{-1}$  from  $\mathbf{O}(\psi)$  to  $\mathbf{O}(\varphi)$ ).

If  $\varphi$  is a nondegenerate symmetric bilinear form of signature  $(p, q)$ , prove that the group  $\mathbf{O}(\varphi)$  is isomorphic to the group of  $n \times n$  matrices  $A$  such that

$$A^\top \begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix} A = \begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix}.$$

**Remark:** In view of question (f), the groups  $\mathbf{O}(\varphi)$  and  $\mathbf{SO}(\varphi)$  are also denoted by  $\mathbf{O}(p, q)$  and  $\mathbf{SO}(p, q)$  when  $\varphi$  has signature  $(p, q)$ . They are Lie groups. In particular, the group  $\mathbf{SO}(3, 1)$ , known as the *Lorentz group*, plays an important role in the theory of special relativity.

**Problem B6 (50 pts).** (a) Let  $C$  be a circle of radius  $R$  and center  $O$ , and let  $P$  be any point in the Euclidean plane  $\mathbb{E}^2$ . Consider the lines  $\Delta$  through  $P$  that intersect the circle  $C$ , generally in two points  $A$  and  $B$ . Prove that for all such lines,

$$\mathbf{PA} \cdot \mathbf{PB} = \|\mathbf{PO}\|^2 - R^2.$$

*Hint.* If  $P$  is not on  $C$ , let  $B'$  be the antipodal of  $B$  (i.e.,  $\mathbf{OB}' = -\mathbf{OB}$ ). Then  $\mathbf{AB} \cdot \mathbf{AB}' = 0$  and

$$\mathbf{PA} \cdot \mathbf{PB} = \mathbf{PB}' \cdot \mathbf{PB} = (\mathbf{PO} - \mathbf{OB}) \cdot (\mathbf{PO} + \mathbf{OB}) = \|\mathbf{PO}\|^2 - R^2.$$

The quantity  $\|\mathbf{PO}\|^2 - R^2$  is called the *power of  $P$  w.r.t.  $C$* , and it is denoted by  $\mathcal{P}(P, C)$ . Show that if  $\Delta$  is tangent to  $C$ , then  $A = B$  and

$$\|\mathbf{PA}\|^2 = \|\mathbf{PO}\|^2 - R^2.$$

Show that  $P$  is inside  $C$  iff  $\mathcal{P}(P, C) < 0$ , on  $C$  iff  $\mathcal{P}(P, C) = 0$ , outside  $C$  if  $\mathcal{P}(P, C) > 0$ .

If the equation of  $C$  is

$$x^2 + y^2 - 2ax - 2by + c = 0,$$

prove that the power of  $P = (x, y)$  w.r.t.  $C$  is given by

$$\mathcal{P}(P, C) = x^2 + y^2 - 2ax - 2by + c.$$

(b) Given two nonconcentric circles  $C$  and  $C'$ , show that the set of points having equal power w.r.t.  $C$  and  $C'$  is a line orthogonal to the line through the centers of  $C$  and  $C'$ . If the equations of  $C$  and  $C'$  are

$$x^2 + y^2 - 2ax - 2by + c = 0 \quad \text{and} \quad x^2 + y^2 - 2a'x - 2b'y + c' = 0,$$

show that the equation of this line is

$$2(a - a')x + 2(b - b')y + c' - c = 0.$$

This line is called the *radical axis* of  $C$  and  $C'$ .

(c) Given three distinct nonconcentric circles  $C$ ,  $C'$ , and  $C''$ , prove that either the three pairwise radical axes of these circles are parallel or that they intersect in a single point  $\omega$  that has equal power w.r.t.  $C$ ,  $C'$ , and  $C''$ . In the first case, the centers of  $C$ ,  $C'$ , and  $C''$  are collinear. In the second case, if the power of  $\omega$  is positive, prove that  $\omega$  is the center of a circle  $\Gamma$  orthogonal to  $C$ ,  $C'$ , and  $C''$ , and if the power of  $\omega$  is negative,  $\omega$  is inside  $C$ ,  $C'$ , and  $C''$ .

(d) Given any  $k \in \mathbb{R}$  with  $k \neq 0$  and any point  $a$ , recall that an *inversion of pole  $a$  and power  $k$*  is a map  $h: (\mathbb{E}^n - \{a\}) \rightarrow \mathbb{E}^n$  defined such that for every  $x \in \mathbb{E}^n - \{a\}$ ,

$$h(x) = a + k \frac{\mathbf{ax}}{\|\mathbf{ax}\|^2}.$$

For example, when  $n = 2$ , choosing any orthonormal frame with origin  $a$ ,  $h$  is defined by the map

$$(x, y) \mapsto \left( \frac{kx}{x^2 + y^2}, \frac{ky}{x^2 + y^2} \right).$$

When the centers of  $C$ ,  $C'$  and  $C''$  are not collinear and the power of  $\omega$  is positive, prove that by a suitable inversion,  $C$ ,  $C'$  and  $C''$  are mapped to three circles whose centers are collinear.

Prove that if three distinct nonconcentric circles  $C$ ,  $C'$ , and  $C''$  have collinear centers, then there are at most eight circles simultaneously tangent to  $C$ ,  $C'$ , and  $C''$ , and at most two for those exterior to  $C$ ,  $C'$ , and  $C''$ .

(e) Prove that an inversion in  $\mathbb{E}^3$  maps a sphere to a sphere or to a plane. Prove that inversions preserve tangency and orthogonality of planes and spheres.

**TOTAL: 270 points.**