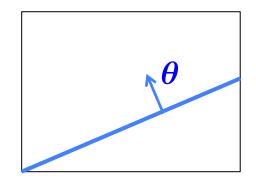


Linear Classification: The Perceptron

Linear Classifiers

- A **hyperplane** partitions \mathbb{R}^d into two half-spaces
 - Defined by the normal vector $oldsymbol{ heta} \in \mathbb{R}^d$
 - heta is orthogonal to any vector lying on the hyperplane



- Assumed to pass through the origin
 - ullet This is because we incorporated bias term $\, heta_0\,$ into it by $\,x_0=1\,$

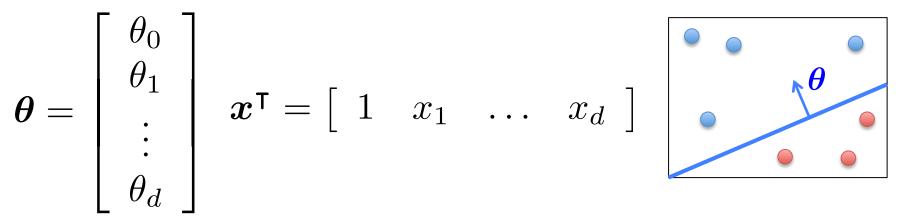
• Consider classification with +1, -1 labels ...

Linear Classifiers

Linear classifiers: represent decision boundary by hyperplane

$$oldsymbol{ heta} = \left[egin{array}{c} heta_0 \ heta_1 \ dots \ heta_d \end{array}
ight]$$

$$\boldsymbol{x}^{\intercal} = \begin{bmatrix} 1 & x_1 & \dots & x_d \end{bmatrix}$$



$$h(\boldsymbol{x}) = \operatorname{sign}(\boldsymbol{\theta}^{\intercal} \boldsymbol{x})$$
 where $\operatorname{sign}(z) = \begin{cases} 1 & \text{if } z \geq 0 \\ -1 & \text{if } z < 0 \end{cases}$

- Note that:
$$\boldsymbol{\theta}^\intercal \boldsymbol{x} > 0 \implies y = +1$$
 $\boldsymbol{\theta}^\intercal \boldsymbol{x} < 0 \implies y = -1$

The Perceptron

$$h(\boldsymbol{x}) = \operatorname{sign}(\boldsymbol{\theta}^{\intercal} \boldsymbol{x})$$
 where $\operatorname{sign}(z) = \begin{cases} 1 & \text{if } z \geq 0 \\ -1 & \text{if } z < 0 \end{cases}$

• The perceptron uses the following update rule each time it receives a new training instance $(\boldsymbol{x}^{(i)}, y^{(i)})$

$$\theta_{j} \leftarrow \theta_{j} - \frac{\alpha}{2} \left(h_{\theta} \left(\boldsymbol{x}^{(i)} \right) - y^{(i)} \right) x_{j}^{(i)}$$
either 2 or -2

- If the prediction matches the label, make no change
- Otherwise, adjust θ

The Perceptron

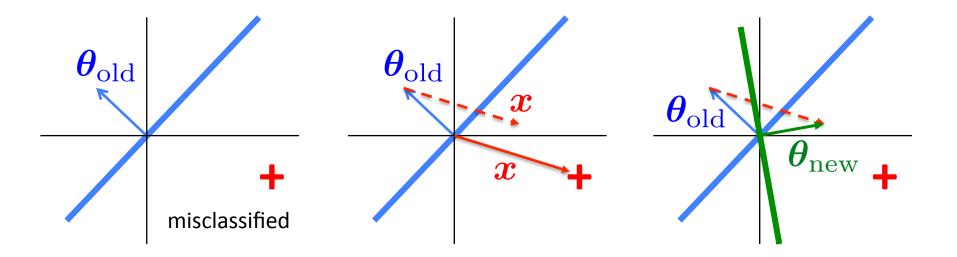
• The perceptron uses the following update rule each time it receives a new training instance $(\boldsymbol{x}^{(i)}, y^{(i)})$

$$\theta_{j} \leftarrow \theta_{j} - \frac{\alpha}{2} \left(h_{\theta} \left(\boldsymbol{x}^{(i)} \right) - y^{(i)} \right) x_{j}^{(i)}$$
either 2 or -2

- Re-write as $\theta_j \leftarrow \theta_j + \alpha y^{(i)} x_j^{(i)}$ (only upon misclassification)
 - Can eliminate α in this case, since its only effect is to scale θ by a constant, which doesn't affect performance

Perceptron Rule: If $m{x}^{(i)}$ is misclassified, do $m{ heta} \leftarrow m{ heta} + y^{(i)} m{x}^{(i)}$

Why the Perceptron Update Works



Why the Perceptron Update Works

- Consider the misclassified example (y = +1)
 - Perceptron wrongly thinks that $m{ heta}_{
 m old}^{\intercal}m{x} < 0$
- Update:

$$\boldsymbol{\theta}_{\text{new}} = \boldsymbol{\theta}_{\text{old}} + y\boldsymbol{x} = \boldsymbol{\theta}_{\text{old}} + \boldsymbol{x}$$
 (since $y = +1$)

Note that

$$egin{aligned} oldsymbol{ heta}_{
m new} oldsymbol{x} &= (oldsymbol{ heta}_{
m old} oldsymbol{+} oldsymbol{x})^\intercal oldsymbol{x} \ &= oldsymbol{ heta}_{
m old}^\intercal oldsymbol{x} + oldsymbol{x}^\intercal oldsymbol{x} \ & \|oldsymbol{x}\|_2^2 > 0 \end{aligned}$$

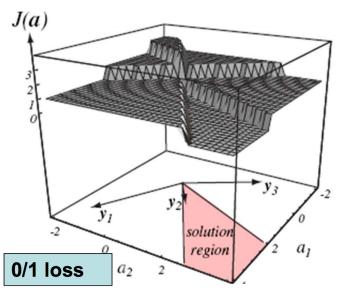
- $m{\cdot}$ Therefore, $m{ heta}_{
 m new}^{\intercal}m{x}$ is less negative than $m{ heta}_{
 m old}^{\intercal}m{x}$
 - So, we are making ourselves more correct on this example!

The Perceptron Cost Function

- Prediction is correct if $y^{(i)} \boldsymbol{x}^{(i)} \boldsymbol{\theta} > 0$
- Could have used 0/1 loss

$$J_{0/1}(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^{n} \ell(sign(x^{(i)}\boldsymbol{\theta}), y^{(i)})$$

where $\ell()$ is 0 if the prediction is correct, 1 otherwise



Doesn't produce a useful gradient

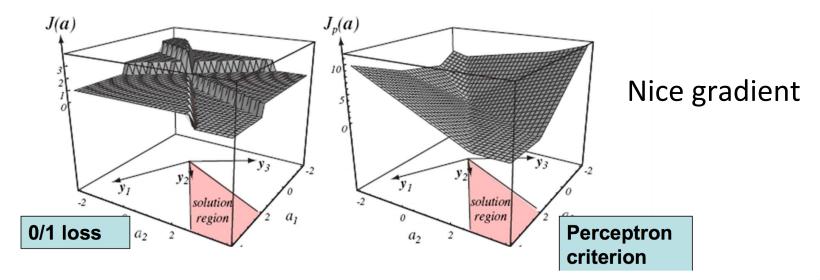
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The Perceptron Cost Function

The perceptron uses the following cost function

$$J_p(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^n \max(0, -y^{(i)} x^{(i)} \boldsymbol{\theta})$$

- $-\max(0,-y^{(i)}x^{(i)}oldsymbol{ heta})$ is 0 if the prediction is correct
- Otherwise, it is the confidence in the misprediction



Online Perceptron Algorithm

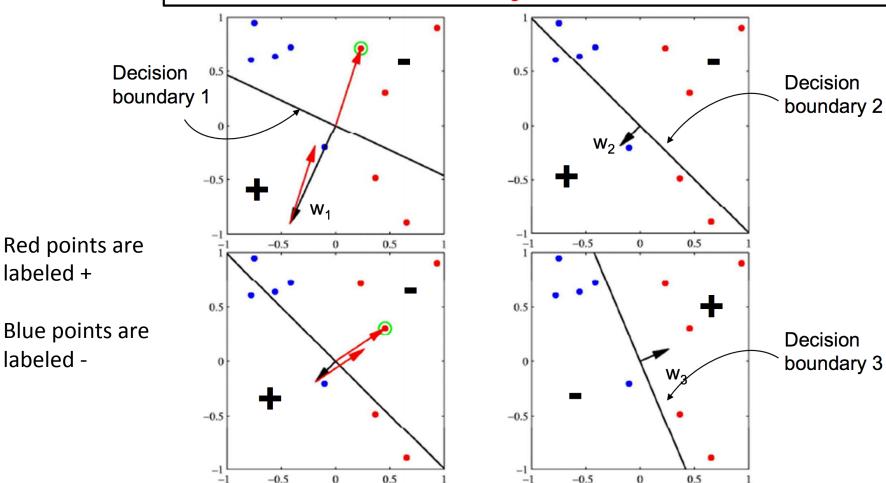
```
Let \boldsymbol{\theta} \leftarrow [0,0,\dots,0]
Repeat:
Receive training example (\boldsymbol{x}^{(i)},y^{(i)})
if y^{(i)}\boldsymbol{x}^{(i)}\boldsymbol{\theta} \leq 0 // prediction is incorrect \boldsymbol{\theta} \leftarrow \boldsymbol{\theta} + y^{(i)}\boldsymbol{x}^{(i)}
```

Online learning – the learning mode where the model update is performed each time a single observation is received

Batch learning – the learning mode where the model update is performed after observing the entire training set

Online Perceptron Algorithm

When an error is made, moves the weight in a direction that corrects the error



See the perceptron in action: www.youtube.com/watch?v=vGwemZhPlsA

Batch Perceptron

```
Given training data \{(\boldsymbol{x}^{(i)}, y^{(i)})\}_{i=1}^n
Let \boldsymbol{\theta} \leftarrow [0, 0, \dots, 0]
Repeat:
           Let \Delta \leftarrow [0, 0, \dots, 0]
           for i = 1 \dots n, do
                    if y^{(i)}\boldsymbol{x}^{(i)}\boldsymbol{\theta} \leq 0
                                                                    // prediction for i<sup>th</sup> instance is incorrect
                             \Delta \leftarrow \Delta + y^{(i)} x^{(i)}
           \Delta \leftarrow \Delta/n
                                                                       // compute average update
           \theta \leftarrow \theta + \alpha \Delta
Until \|\mathbf{\Delta}\|_2 < \epsilon
```

- Simplest case: $\alpha = 1$ and don't normalize, yields the fixed increment perceptron
- Guaranteed to find a separating hyperplane if one exists

Improving the Perceptron

- The Perceptron produces many heta's during training
- The standard Perceptron simply uses the final heta at test time
 - This may sometimes not be a good idea!
 - Some other θ may be correct on 1,000 consecutive examples, but one mistake ruins it!
- Idea: Use a combination of multiple perceptrons
 - (i.e., neural networks!)
- **Idea:** Use the intermediate θ 's
 - **Voted Perceptron**: vote on predictions of the intermediate θ 's
 - Averaged Perceptron: average the intermediate θ 's