## Fall 2020 CIS 515

## Fundamentals of Linear Algebra and Optimization Jean Gallier

## Homework 1

September 2, 2020; Due September 21, 2020

Problem B1 (30 pts). (i) Prove that the axioms of vector spaces imply that

$$\alpha \cdot 0 = 0$$

$$0 \cdot v = 0$$

$$\alpha \cdot (-v) = -(\alpha \cdot v)$$

$$(-\alpha) \cdot v = -(\alpha \cdot v),$$

for all  $v \in E$  and all  $\alpha \in K$ , where E is a vector space over K.

(ii) For every  $\lambda \in \mathbb{R}$  and every  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ , define  $\lambda x$  by

$$\lambda x = \lambda(x_1, \dots, x_n) = (\lambda x_1, \dots, \lambda x_n).$$

Recall that every vector  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$  can be written uniquely as

$$x = x_1 e_1 + \dots + x_n e_n,$$

where  $e_i = (0, ..., 0, 1, 0, ..., 0)$ , with a single 1 in position i. For any operation  $\cdot : \mathbb{R} \times \mathbb{R}^n \to \mathbb{R}^n$ , if  $\cdot$  satisfies the axiom (V1) of a vector space, then prove that for any  $\alpha \in \mathbb{R}$ , we have

$$\alpha \cdot x = \alpha \cdot (x_1 e_1 + \dots + x_n e_n) = \alpha \cdot (x_1 e_1) + \dots + \alpha \cdot (x_n e_n).$$

Conclude that  $\cdot$  is completely determined by its action on each of the one-dimensional subspaces of  $\mathbb{R}^n$  spanned by  $e_i$   $(1 \le i \le n)$ .

- (iii) Use (ii) to define operations  $\cdot: \mathbb{R} \times \mathbb{R}^n \to \mathbb{R}^n$  that satisfy the axioms (V1–V3), but for which axiom V4 fails.
- (iv) Extra credit (20 pts). For any operation  $\cdot : \mathbb{R} \times \mathbb{R}^n \to \mathbb{R}^n$ , prove that if  $\cdot$  satisfies the axioms (V2–V3), then for every rational number  $r \in \mathbb{Q}$  and every vector  $x \in \mathbb{R}^n$ , we have

$$r \cdot x = r(1 \cdot x).$$

In the above equation,  $1 \cdot x$  is some vector  $(y_1, \ldots, y_n) \in \mathbb{R}^n$  not necessarily equal to  $x = (x_1, \ldots, x_n)$ , and

$$r(1 \cdot x) = (ry_1, \dots, ry_n),$$

as in part (ii).

Use (iv) to conclude that any operation  $\cdot: \mathbb{Q} \times \mathbb{R}^n \to \mathbb{R}^n$  that satisfies the axioms (V1–V3) is completely determined by the action of 1 on the one-dimensional subspaces of  $\mathbb{R}^n$  spanned by  $e_1, \ldots, e_n$ .

**Problem B2 (45 pts).** (In solving this problem, **do not use determinants**). (1) Let  $(u_1, \ldots, u_m)$  and  $(v_1, \ldots, v_m)$  be two families of vectors in some vector space E. Assume that each  $v_i$  is a linear combination of the  $u_j$ s, so that

$$v_i = a_{i\,1}u_1 + \dots + a_{i\,m}u_m, \quad 1 \le i \le m,$$

and that the matrix  $A = (a_{ij})$  is an upper-triangular matrix, which means that if  $1 \leq j < i \leq m$ , then  $a_{ij} = 0$ . Prove that if  $(u_1, \ldots, u_m)$  are linearly independent and if all the diagonal entries of A are nonzero, then  $(v_1, \ldots, v_m)$  are also linearly independent.

Hint. Use induction on m.

(2) Let  $A = (a_{ij})$  be an upper-triangular matrix. Prove that if all the diagonal entries of A are nonzero, then A is invertible and the inverse  $A^{-1}$  of A is also upper-triangular.

Hint. Use induction on m and multiplication by blocks.

Prove that if A is invertible, then all the diagonal entries of A are nonzero (do not use determinants or eigenvalues!).

Hint. Use induction on m and multiplication by blocks.

(3) Prove that if the families  $(u_1, \ldots, u_m)$  and  $(v_1, \ldots, v_m)$  are related as in (1), then  $(u_1, \ldots, u_m)$  are linearly independent iff  $(v_1, \ldots, v_m)$  are.

Problem B3 (80 pts). Consider the polynomials

$$B_0^2(t) = (1-t)^2$$
  $B_1^2(t) = 2(1-t)t$   $B_2^2(t) = t^2$   
 $B_0^3(t) = (1-t)^3$   $B_1^3(t) = 3(1-t)^2t$   $B_2^3(t) = 3(1-t)t^2$   $B_3^3(t) = t^3$ ,

known as the *Bernstein polynomials* of degree 2 and 3.

(1) Show that the Bernstein polynomials  $B_0^2(t)$ ,  $B_1^2(t)$ ,  $B_2^2(t)$  are expressed as linear combinations of the basis  $(1, t, t^2)$  of the vector space of polynomials of degree at most 2 as follows:

$$\begin{pmatrix} B_0^2(t) \\ B_1^2(t) \\ B_2^2(t) \end{pmatrix} = \begin{pmatrix} 1 & -2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ t \\ t^2 \end{pmatrix}.$$

Prove that

$$B_0^2(t) + B_1^2(t) + B_2^2(t) = 1.$$

(2) Show that the Bernstein polynomials  $B_0^3(t)$ ,  $B_1^3(t)$ ,  $B_2^3(t)$ ,  $B_3^3(t)$  are expressed as linear combinations of the basis  $(1, t, t^2, t^3)$  of the vector space of polynomials of degree at most 3 as follows:

$$\begin{pmatrix} B_0^3(t) \\ B_1^3(t) \\ B_2^3(t) \\ B_3^3(t) \end{pmatrix} = \begin{pmatrix} 1 & -3 & 3 & -1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ t \\ t^2 \\ t^3 \end{pmatrix}.$$

Prove that

$$B_0^3(t) + B_1^3(t) + B_2^3(t) + B_3^3(t) = 1.$$

- (3) Prove that the Bernstein polynomials of degree 2 are linearly independent, and that the Bernstein polynomials of degree 3 are linearly independent.
  - (4) Recall that the binomial coefficient  $\binom{m}{k}$  is given by

$$\binom{m}{k} = \frac{m!}{k!(m-k)!},$$

with  $0 \le k \le m$ .

For any  $m \geq 1$ , we have the m+1 Bernstein polynomials of degree m given by

$$B_k^m(t) = \binom{m}{k} (1-t)^{m-k} t^k, \quad 0 \le k \le m.$$

Prove that

$$B_k^m(t) = \sum_{j=k}^m (-1)^{j-k} \binom{m}{j} \binom{j}{k} t^j.$$
 (\*)

Use the above to prove that  $B_0^m(t), \ldots, B_m^m(t)$  are linearly independent.

(5) Prove that

$$B_0^m(t) + \dots + B_m^m(t) = 1.$$

**Extra credit (20 pts)**. What can you say about the symmetries of the  $(m+1) \times (m+1)$  matrix expressing  $B_0^m, \ldots, B_m^m$  in terms of the basis  $1, t, \ldots, t^m$ ?

Prove your claim (beware that in equation (\*) the coefficient of  $t^j$  in  $B_k^m$  is the entry on the (k+1)th row of the (j+1)th column, since  $0 \le k, j \le m$ . Make appropriate modifications to the indices).

What can you say about the sum of the entries on each row of the above matrix? What about the sum of the entries on each column?

(6) (This is **no longer for extra credit!**) The purpose of this question is to express the  $t^i$  in terms of the Bernstein polynomials  $B_0^m(t), \ldots, B_m^m(t)$ , with  $0 \le i \le m$ .

First, prove that

$$t^{i} = \sum_{j=0}^{m-i} t^{i} B_{j}^{m-i}(t), \quad 0 \le i \le m.$$

Then prove that

$$\binom{m}{i}\binom{m-i}{j} = \binom{m}{i+j}\binom{i+j}{i}.$$

Use the above facts to prove that

$$t^{i} = \sum_{j=0}^{m-i} \frac{\binom{i+j}{i}}{\binom{m}{i}} B_{i+j}^{m}(t).$$

Conclude that the Bernstein polynomials  $B_0^m(t), \ldots, B_m^m(t)$  form a basis of the vector space of polynomials of degree  $\leq m$ .

Compute the matrix expressing  $1, t, t^2$  in terms of  $B_0^2(t), B_1^2(t), B_2^2(t)$ , and the matrix expressing  $1, t, t^2, t^3$  in terms of  $B_0^3(t), B_1^3(t), B_2^3(t), B_3^3(t)$ .

You should find

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1/2 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

and

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1/3 & 2/3 & 1 \\ 0 & 0 & 1/3 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

(7) A polynomial curve C(t) of degree m in the plane is the set of points  $C(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$  given by two polynomials of degree  $\leq m$ ,

$$x(t) = \alpha_0 t^{m_1} + \alpha_1 t^{m_1 - 1} + \dots + \alpha_{m_1}$$
  
$$y(t) = \beta_0 t^{m_2} + \beta_1 t^{m_2 - 1} + \dots + \beta_{m_2},$$

with  $1 \le m_1, m_2 \le m$  and  $\alpha_0, \beta_0 \ne 0$ .

Prove that there exist m+1 points  $b_0, \ldots, b_m \in \mathbb{R}^2$  so that

$$C(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = B_0^m(t)b_0 + B_1^m(t)b_1 + \dots + B_m^m(t)b_m$$

for all  $t \in \mathbb{R}$ , with  $C(0) = b_0$  and  $C(1) = b_m$ . Are the points  $b_1, \ldots, b_{m-1}$  generally on the curve?

We say that the curve C is a Bézier curve and  $(b_0, \ldots, b_m)$  is the list of control points of the curve (control points need not be distinct).

**Remark:** Because  $B_0^m(t) + \cdots + B_m^m(t) = 1$  and  $B_i^m(t) \geq 0$  when  $t \in [0,1]$ , the curve segment C[0,1] corresponding to  $t \in [0,1]$  belongs to the convex hull of the control points. This is an important property of Bézier curves which is used in geometric modeling to find the intersection of curve segments. Bézier curves play an important role in computer graphics and geometric modeling, but also in robotics because they can be used to model the trajectories of moving objects.

**Problem B4 (40 pts).** (a) Let A be an  $n \times n$  matrix. If A is invertible, prove that for any  $x \in \mathbb{R}^n$ , if Ax = 0, then x = 0.

The converse is true: If for all  $x \in \mathbb{R}^n$ , Ax = 0 implies that x = 0, then A is invertible. We will prove this fact later, and you may use it without proof in part (b) of this problem.

(b) Let A be an  $m \times n$  matrix and let B be an  $n \times m$  matrix. Prove that  $I_m - AB$  is invertible iff  $I_n - BA$  is invertible.

Hint. Look at A(I + BA) and (I + AB)A.

**Problem B5 (40 pts).** Consider the following  $n \times n$  matrix, for  $n \geq 3$ :

$$B = \begin{pmatrix} 1 & -1 & -1 & -1 & \cdots & -1 & -1 \\ 1 & -1 & 1 & 1 & \cdots & 1 & 1 \\ 1 & 1 & -1 & 1 & \cdots & 1 & 1 \\ 1 & 1 & 1 & -1 & \cdots & 1 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 1 & 1 & 1 & \cdots & -1 & 1 \\ 1 & 1 & 1 & 1 & \cdots & 1 & -1 \end{pmatrix}$$

(1) If we denote the columns of B by  $b_1, \ldots, b_n$ , prove that

$$(n-3)b_1 - (b_2 + \dots + b_n) = 2(n-2)e_1$$

$$b_1 - b_2 = 2(e_1 + e_2)$$

$$b_1 - b_3 = 2(e_1 + e_3)$$

$$\vdots$$

$$b_1 - b_n = 2(e_1 + e_n),$$

where  $e_1, \ldots, e_n$  are the canonical basis vectors of  $\mathbb{R}^n$ .

(2) Prove that B is invertible and that its inverse  $A = (a_{ij})$  is given by

$$a_{11} = \frac{(n-3)}{2(n-2)}, \quad a_{i1} = -\frac{1}{2(n-2)} \quad 2 \le i \le n$$

and

$$a_{ii} = -\frac{(n-3)}{2(n-2)}, \quad 2 \le i \le n$$

$$a_{ji} = \frac{1}{2(n-2)}, \quad 2 \le i \le n, j \ne i.$$

(3) Show that the n diagonal  $n \times n$  matrices  $D_i$  defined such that the diagonal entries of  $D_i$  are equal the entries (from top down) of the ith column of B form a basis of the space of  $n \times n$  diagonal matrices (matrices with zeros everywhere except possibly on the diagonal). For example, when n = 4, we have

$$D_{1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$D_{2} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$D_{3} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$D_{4} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}.$$

**Problem B6 (30 pts).** Let H be the set of  $3 \times 3$  upper triangular matrices given by

$$H = \left\{ \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\}.$$

- (1) Prove that H with the binary operation of matrix multiplication is a group; find explicitly the inverse of every matrix in H. Is H abelian (commutative)?
- (2) Given two groups  $G_1$  and  $G_2$ , recall that a homomorphism is a function  $\varphi \colon G_1 \to G_2$  such that

$$\varphi(ab) = \varphi(a)\varphi(b), \quad a, b \in G_1.$$

Prove that  $\varphi(e_1) = e_2$  (where  $e_i$  is the identity element of  $G_i$ ) and that

$$\varphi(a^{-1}) = (\varphi(a))^{-1}, \quad a \in G_1.$$

(3) Let  $S^1$  be the unit circle, that is

$$S^{1} = \{e^{i\theta} = \cos\theta + i\sin\theta \mid 0 \le \theta < 2\pi\},\$$

and let  $\varphi$  be the function given by

$$\varphi \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix} = (a, c, e^{ib}).$$

Prove that  $\varphi$  is a surjective function onto  $G = \mathbb{R} \times \mathbb{R} \times S^1$ , and that if we define multiplication on this set by

$$(x_1, y_1, u_1) \cdot (x_2, y_2, u_2) = (x_1 + x_2, y_1 + y_2, e^{ix_1y_2}u_1u_2),$$

then G is a group and  $\varphi$  is a group homomorphism from H onto G.

(4) Extra credit (10 pts). The kernel of a homomorphism  $\varphi \colon G_1 \to G_2$  is defined as

$$Ker(\varphi) = \{ a \in G_1 \mid \varphi(a) = e_2 \}.$$

Find explicitly the kernel of  $\varphi$  and show that it is a subgroup of H.

**Problem B7 (10 pts).** For any  $m \in \mathbb{Z}$  with m > 0, the subset  $m\mathbb{Z} = \{mk \mid k \in \mathbb{Z}\}$  is an abelian subgroup of  $\mathbb{Z}$ . Check this.

- (1) Give a group isomorphism (an invertible homomorphism) from  $m\mathbb{Z}$  to  $\mathbb{Z}$ .
- (2) Check that the inclusion map  $i: m\mathbb{Z} \to \mathbb{Z}$  given by i(mk) = mk is a group homomorphism. Prove that if  $m \geq 2$  then there is no group homomorphism  $p: \mathbb{Z} \to m\mathbb{Z}$  such that  $p \circ i = \mathrm{id}$ .

**Remark:** The above shows that abelian groups fail to have some of the properties of vector spaces. We will show later that a linear map satisfying the condition  $p \circ i = \text{id}$  always exists.

TOTAL: 275 + 50 points.