Proofs, Computability, Undecidability, Complexity, And the Lambda Calculus An Introduction

Jean Gallier and Jocelyn Quaintance Department of Computer and Information Science University of Pennsylvania Philadelphia, PA 19104, USA e-mail: jean@seas.upenn.edu

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Preface

The main goal of this book is to present a mix of material dealing with

- (1) Proof systems.
- (2) Computability and undecidability.
- (3) The pure lambda Calculus of Church.
- (4) The simply-typed lambda Calculus of Church.
- (5) The polymorphic second-order lambda Calculus of Girard (system F).
- (6) Some aspects of complexity theory.

Historically, the theory of computability and undecidability arose from Hilbert's efforts to completely formalize mathematics and from Gödel's first incompleteness theorem that showed that such a program was doomed to fail. People realized that to carry out both Hilbert's program and Gödel's work it was necessary to define precisely what is the notion of a *computable function* and the notion of a mechanically checkable proof. The first definition given around 1934 was that of the class of computable function in the sense of Herbrand– Gödel–Kleene. The second definition given by Church in 1935-1936 was the notion of a function definable in the λ -calculus. The equivalence of these two definitions was shown by Kleene in 1936. Shortly after in 1936, Turing introduced a third definition, that of a Turingcomputable function. Turing proved the equivalence of his definition with the Herbrand– Gödel–Kleene definition in 1937 (his proofs are rather sketchy compared to Kleene's proofs). All these historical papers can be found in a fascinating book edited by Martin Davis [30].

Negative results pointing out limitations of the notion of computability started to appear: Gödel's first (and second) incompleteness result, but also Church's theorem on the undecidability of validity in first-order logic, and Turing's result on the undecidability of the halting problem for Turing machines. Although originally the main focus was on the notion of function, these undecidability results triggered the study of computable and noncomputable sets of natural numbers.

Other definitions of the computable functions were given later. From our point of view, the most important ones are

- (1) RAM programs and RAM-computable functions by Shepherdson and Sturgis (1963), and anticipated by Post (1944); see Machtey and Young [51].
- (2) Diophantine-definable sets (Davis–Putnam–Robinson–Matiyasevich); see Davis [11, 12].

We find the RAM-progam model quite attractive because it is a very simplified realistic model of the true architecture of a modern computer. Technically, we also find it more convenient to assign Gödel numbers to RAM programs than assigning Gödel numbers to Turing machines. Every RAM program can be converted to a Turing machine and viceversa in polynomial time (going from a Turing machine to a RAM is quite horrific), so the two models are equivalent in a strong sense. So from our perspective Turing machines could be dispensed with, but there is a problem. The problem is that the Turing machine model seems more convenient to cope with time or space restrictions, that is, to define complexity classes.

There is actually no difficulty in defining nondeterministic RAM programs and to impose a time restriction on the program counter or a space restriction on the size of registers, but nobody seems to follow this path. This seems unfortunate to us because it appears that it would be easier to justify the fact that certain reductions can be carried out in polynomial time (or space) by writing a RAM program rather than by constructing a Turing machine. Regarding this issue, we are not aware than anyone actually provides Turing machines computing these reductions, even for SAT.

In any case, we will stick to the tradition of using Turing machines when discussing complexity classes.

In addition to presenting the RAM-program model, the Turing machine model, the Herbrand–Gödel–Kleene definition of the computable functions, and showing their equivalence, we provide an introduction to recursion theory (see Chapter 10). In particular, we discuss creative and productive sets (see Rogers [64]). This allows us to cover most of the main undecidability results. These include

- (1) The undecidability of the halting problem for RAM programs (and Turing machines).
- (2) Rice's theorem for the computable functions.
- (3) Rice's extended theorem for the listable sets.
- (4) A strong form of Gödel' first incompleteness theorem (in terms of creative sets) following Rogers [64].
- (5) The fact that the true first-order sentences of arithmetic are not even listable (a productive set) following Rogers [64].
- (6) The undecidability of the Post correspondence problem (PCP) using a proof due to Dana Scott.

- (7) The undecidability of the validity in first-order logic (Church's theorem), using a proof due to Robert Floyd.
- (8) The undecidability of Hilbert's tenth problem (the DPRM theorem) following Davis [11].
- (9) Another strong form of Gödel' first incompleteness theorem, as a consequence of diophantine definability following Davis [11].

The following topics are rarely covered in books on the theory of computation and undecidability.

- (1) In Section 2.14, we introduce Church's simply-typed λ -calculus as a mechanism to represent proof trees in intuitionistic propositional logic based on \Rightarrow . This is an instance of the "Curry–Howard isomorphism," in which propositions correspond to types and proofs correspond to certain kinds of typed λ -terms. This is a prelude to the introduction of the "pure" (untyped) λ -calculus.
- (2) We discuss unification (see Chapter 3) and type inferencing in Section 2.15. Unification is a major tool in automated theorem proving and plays a key role in type inferencing, which is an important topic in functional programming.
- (3) In Chapter 6, we introduce Church's (untyped) λ -calculus and show how the computable functions and the partial computable functions are definable in the λ -calculus, using a method due to Barendregt [5].
- (4) In Chapter 7, we discuss extensively the family of total computable functions definable in the second-order polymorphic λ -calculus of Girard, known as *system F*. This set of functions turns out to be the family of computable functions that can be proven total in a system of intuitionistic second-order arithmetic known as \mathbf{HA}^2 . This remarkable result was proven by Girard [28].

Proving that a computable function provably total in \mathbf{HA}^2 is computable in system F is achieved by representing proofs in \mathbf{HA}^2 as certain kinds of terms containing the terms of system F as a subsystem. This is an instance of the "Curry–Howard isomorphism," in which propositions correspond to types and proofs correspond to certain kinds of typed λ -terms. The term calculus encoding proofs in \mathbf{HA}^2 is denoted $\lambda \mathbf{Ni}^2$. Since the term calculus $\lambda \mathbf{Ni}^2$ contains terms not in system F, it is necessary to define a map, the collapsing map, converting a term in $\lambda \mathbf{Ni}^2$ to a term in system F. Actually, there is a technical complication because the absurdity proposition \perp is not provable, and thus is not the type of any term in $\lambda \mathbf{Ni}^2$. To circumvent this problem, it is necessary to introduce an auxiliary term system $\lambda 2\Omega$ and to define two maps, one from $\lambda \mathbf{Ni}^2$ to $\lambda 2\Omega$, and one from $\lambda 2\Omega$ to system F.

There is also a difficulty in mapping proofs in \mathbf{HA}^2 directly to terms in $\lambda 2\Omega$ because of the induction axiom of \mathbf{HA}^2 , so it is necessary to define the intuitionistic second-order

logic proof system \mathbf{HA}^{2*} . Formulae in \mathbf{HA}^2 can be converted to formulae in \mathbf{HA}^{2*} by a process of relativization of quantifiers (the D-translation), in such a way that the relativization of the induction axiom of \mathbf{HA}^2 is provable in \mathbf{HA}^{2*} , so \mathbf{HA}^{2*} does not not have any induction axiom. As a consequence, if a formula P is provable in \mathbf{HA}^2 , then its D-translation $P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} without any induction axiom. The process of quantifier relativization involves a second-order predicate $\mathbf{N}^{\wedge}(v)$ that defines the notion of natural number as Dedekind did in his famous paper of 1888 (Was sind und was sollen die Zallen?). Then the formula $\forall vP$ is replaced by $\forall v(\mathbf{N}^{\wedge}(v) \Rightarrow P^{\mathbb{D}})$.

We follow closely Troelstra and Schwichtenberg [73], but many technical details are omitted in this book, so we filled in some of the missing proofs.

(5) In Chapter 11 we discuss the definability of the listable sets in terms of Diophantine equations (zeros of polynomials with integer coefficients) and state the famous result about the undecidability of Hilbert's tenth problem (the DPRM theorem). We follow the masterly exposition of Davis [11, 12].

A possibly unusual aspect of our book is that we begin with two chapters on mathematical reasoning and logic. Given the origins of the theory of computation and undecidability, we feel that this is very appropriate. We present proof systems in natural deduction style (a la Prawitz), which makes it easy to discuss the special role of the proof-by-contradiction principle, and to introduce intuitionistic logic, which is the result of removing this rule from the set of inference rules. It is also quite natural to explain how proofs in intuitionistic propositional logic are represented by simply-typed λ -terms. Then it is easy to introduce the "Curry–Howard isomorphism."

Our treatment of complexity theory is limited to \mathcal{P} , \mathcal{NP} , co- \mathcal{NP} , \mathcal{EXP} , \mathcal{NEXP} , \mathcal{PS} (PSPACE) and \mathcal{NPS} (NPSPACE) and is fairly standard. However, we prove that SAT is \mathcal{NP} -complete by first proving (following Lewis and Papadimitriou [50]) that a bounded tiling problem is \mathcal{NP} -complete.

In Chapter 15 we treat the result that primality testing is in \mathcal{NP} in more details than most other sources, relying on an improved version of a theorem of Lucas as discussed in Crandall and Pomerance [7]. The only result that we omit is the existence of primitive roots in $(\mathbb{Z}/p\mathbb{Z})^*$ when p is prime.

In Chapter 16 we prove Savitch's theorem ($\mathcal{PS} = \mathcal{NPS}$). We state the fact that the validity of quantified boolean formulae is \mathcal{PS} -complete and provide parts of the proof. We conclude with the beautiful proof of Statman [68] that provability in intuitionistic propositional logic is \mathcal{PS} -complete. We do not give all the details but we prove the correctness of Statman's amazing translation of a valid QBF into an intuitionistically provable proposition.

We feel strongly that one does not learn mathematics without reading (and struggling through) proofs, so we tried to provide as many proofs as possible. Among some of the omissions, we do not show how to construct a Gödel sentence in the proof of the first incompleteness theorem; Rogers [64] leaves this as an exercise! We also do not give a complete

proof of Statman's result. Giving a complete proof of the DPRM would require the inclusion of some very technical number theory material. This would probably turn off most readers and be of very little value so we decided to omit the most arduous material. However, we present an almost complete proof. We have omitted the hardest step: showing that the exponential function is Diophantine definable. Whenever a proof is omitted, we provide a pointer to a source that contains such a proof.

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Chapter 1

Mathematical Reasoning And Basic Logic

1.1 Introduction

One of the main goals of this book is to show how to

construct and read mathematical proofs.

Why?

- 1. Computer scientists and engineers write *programs* and build systems.
- 2. It is very important to have *rigorous methods* to check that these programs and systems behave as expected (are *correct*, have *no bugs*).
- 3. It is also important to have methods to analyze the complexity of programs (time/space complexity).

More generally, it is crucial to have a firm grasp of the *basic reasoning principles and* rules of logic. This leads to the question:

What is a proof?

There is no short answer to this question. However, it seems fair to say that a proof is some kind of *deduction (derivation)* that proceeds from a set of *hypotheses (premises, axioms)* in order to derive a *conclusion*, using some *proof templates* (also called *logical rules*).

A first important observation is that there are different *degrees of formality* of proofs.

1. Proofs can be very *informal*, using a set of loosely defined logical rules, possibly omitting steps and premises. 2. Proofs can be *completely formal*, using a very clearly defined set of rules and premises. Such proofs are usually processed or produced by programs called *proof checkers* and *theorem provers*.

Thus, a human prover evolves in a spectrum of formality.

It should be said that *it is practically impossible to write formal proofs*. This is because it would be extremely tedious and time-consuming to write such proofs and these proofs would be huge and thus, very hard to read.

In principle, it is possible to write formalized proofs and sometimes it is desirable to do so if we want to have absolute confidence in a proof. For example, we would like to be sure that a flight-control system is not buggy so that a plane does not accidentally crash, that a program running a nuclear reactor will not malfunction, or that nuclear missiles will not be fired as a result of a buggy "alarm system."

Thus, it is very important to develop tools to assist us in constructing formal proofs or checking that formal proofs are correct. Such systems do exist, for example Isabelle, COQ, TPS, NUPRL, PVS, Twelf. However, 99.99% of us will not have the time or energy to write formal proofs.

Even if we never write formal proofs, it is important to understand clearly what are the rules of reasoning (proof templates) that we use when we construct informal proofs.

The goal of this chapter is to explain what is a proof and how we construct proofs using various *proof templates* (also known as *proof rules*).

This chapter is an abbreviated and informal version of Chapter 2. It is meant for readers who have never been exposed to a presentation of the rules of mathematical reasoning (the rules for constructing mathematical proofs) and basic logic. Readers with a good background in these topics may decide to skip this chapter and proceed directly to Chapter 13.3. This will not cause any problem, and there will be no gap, since the other chapters are written so that they do not rely on the material of Chapter 1 (except for a few remarks).

1.2 Logical Connectives, Definitions

In order to define the notion of proof rigorously, we would have to define a formal language in which to express statements very precisely, and we would have to set up a proof system in terms of axioms and proof rules (also called inference rules). We do not go into this in this chapter as this would take too much time. Instead, we content ourselves with an intuitive idea of what a statement is and focus on stating as precisely as possible the rules of logic (proof templates) that are used in constructing proofs.

In mathematics and computer science, we **prove statements.** Statements may be *atomic* or *compound*, that is, built up from simpler statements using *logical connectives*, such as *implication* (if-then), *conjunction* (and), *disjunction* (or), *negation* (not), and (existential or universal) *quantifiers*.

As examples of atomic statements, we have:

1. "A student is eager to learn."

- 2. "A student wants an A."
- 3. "An odd integer is never 0."
- 4. "The product of two odd integers is odd."

Atomic statements may also contain "variables" (standing for arbitrary objects). For example,

- 1. human(x): "x is a human."
- 2. needs-to-drink(x): "x needs to drink."

An example of a compound statement is

 $human(x) \Rightarrow needs-to-drink(x).$

In the above statement, \Rightarrow is the symbol used for logical implication. If we want to assert that every human needs to drink, we can write

$$\forall x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x));$$

this is read "For every x, if x is a human, then x needs to drink."

If we want to assert that some human needs to drink we write

$$\exists x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x));$$

this is read "There is some x such that, if x is a human, then x needs to drink."

We often denote statements (also called *propositions* or *(logical)* formulae) using letters, such as A, B, P, Q, and so on, typically uppercase letters (but sometimes Greek letters, φ , ψ , etc.).

Compound statements are defined as follows: if P and Q are statements, then

- (1) the conjunction of P and Q is denoted $P \wedge Q$ (pronounced, P and Q),
- (2) the disjunction of P and Q is denoted $P \lor Q$ (pronounced, P or Q),
- (3) the *implication* of P and Q is denoted by $P \Rightarrow Q$ (pronounced, if P then Q, or P implies Q).

We also have the atomic statements \perp (*falsity*) (think of it as the statement that is false no matter what); and the atomic statement \top (*truth*) (think of it as the statement that is always true).

The constant \perp is also called *falsum* or *absurdum*. It is a formalization of the notion of *absurdity* or *inconsistency* (a state in which contradictory facts hold).

Given any proposition P, it is convenient to define

(4) the negation $\neg P$ of P (pronounced, not P) as $P \Rightarrow \bot$. Thus, $\neg P$ (sometimes denoted $\sim P$) is just a shorthand for $P \Rightarrow \bot$.

The intuitive idea is that $\neg P$ (an abbreviation for $P \Rightarrow \bot$) is true if and only if P is false. Actually, because we don't know what truth is, it is "safer" to say that $\neg P$ is provable if and only if for every proof of P we can derive a contradiction (namely, \bot is provable). By provable, we mean that a proof can be constructed using some rules that will be described shortly (see Section 1.3).

Whenever necessary to avoid ambiguities, we add matching parentheses: $(P \land Q)$, $(P \lor Q)$, $(P \Rightarrow Q)$. For example, $P \lor Q \land R$ is ambiguous; it means either $(P \lor (Q \land R))$ or $((P \lor Q) \land R)$. Another important logical operator is *equivalence*.

If P and Q are statements, then

(5) the equivalence of P and Q is denoted $P \equiv Q$ (or $P \iff Q$); it is an abbreviation for $(P \Rightarrow Q) \land (Q \Rightarrow P)$. We often say "P if and only if Q" or even "P iff Q" for $P \equiv Q$.

As a consequence, to prove a logical equivalence $P \equiv Q$, we have to prove **both** implications $P \Rightarrow Q$ and $Q \Rightarrow P$.

The meaning of the logical connectives $(\land, \lor, \Rightarrow, \neg, \equiv)$ is intuitively clear. This is certainly the case for and (\land) , since a conjunction $P \land Q$ is true if and only if both P and Q are true (if we are not sure what "true" means, replace it by the word "provable"). However, for or (\lor) , do we mean inclusive or or exclusive or? In the first case, $P \lor Q$ is true if either P or Q is true, but in the second case, $P \lor Q$ is true if either P or Q is true but not both at the same time (again, in doubt change "true" to "provable"). We always mean inclusive or.

The situation is worse for *implication* (\Rightarrow) . When do we consider that $P \Rightarrow Q$ is true (provable)? The answer is that it depends on the rules! The "classical" answer is that $P \Rightarrow Q$ is false (not provable) if and only if P is true and Q is false. For an alternative view (that of intuitionistic logic), see Chapter 2. In this chapter (and all others except Chapter 2), we adopt the classical view of logic. Since negation (\neg) is defined in terms of implication, in the classical view, $\neg P$ is true if and only if P is false.

The purpose of the *proof rules*, or *proof templates*, is to spell out rules for constructing proofs which reflect, and in fact specify, the meaning of the logical connectives.

Before we present the proof templates, it should be said that nothing of much interest can be proven in mathematics if we do not have at our disposal various objects such as numbers, functions, graphs, etc. This brings up the issue of where we begin, what may we assume. In set theory, everything, even the natural numbers, can be built up from the empty set! This is a remarkable construction, but it takes a tremendous amount of work. For us, we assume that we know what the set

$$\mathbb{N} = \{0, 1, 2, 3, \ldots\}$$

of *natural numbers* is, as well as the set

$$\mathbb{Z} = \{\ldots, -3, -2, -1, 0, 1, 2, 3, \ldots\}$$

of *integers* (which allows negative natural numbers). We also assume that we know how to add, subtract, and multiply (perhaps even divide) integers (as well as some of the basic properties of these operations), and we know what the ordering of the integers is.

The way to introduce new objects in mathematics is to make *definitions*. Basically, a definition characterizes an object by some property. Technically, we define a "gizmo" x by introducing a so-called predicate (or property) gizmo(x), which is an abbreviation for some possibly complicated logical proposition P(x). The idea is that x is a "gizmo" if and only if gizmo(x) holds if and only if P(x) holds. We may write

$$\operatorname{gizmo}(x) \equiv P(x),$$

or

$$\operatorname{gizmo}(x) \stackrel{\text{def}}{\equiv} P(x).$$

Note that gizmo is just a name, but P(x) is a (possibly complex) proposition.

It is also convenient to define properties (also called *predicates*) of one or more objects as abbreviations for possibly complicated logical propositions. In this case, a property $p(x_1, \ldots, x_n)$ of some objects x_1, \ldots, x_n holds if and only if some logical proposition $P(x_1, \ldots, x_n)$ holds. We may write

$$p(x_1,\ldots,x_n) \equiv P(x_1,\ldots,x_n)$$

or

$$p(x_1,\ldots,x_n) \stackrel{\text{def}}{\equiv} P(x_1,\ldots,x_n).$$

Here too, p is just a name, but $P(x_1, \ldots, x_n)$ is a (possibly complex) proposition.

Let us give a few examples of definitions.

Definition 1.1. Given two integers $a, b \in \mathbb{Z}$, we say that a is a multiple of b if there is some $c \in \mathbb{Z}$, such that a = bc. In this case, we say that a is divisible by b, that b is a divisor of a (or b is a factor of a), and that b divides a. We use the notation $b \mid a$.

In Definition 1.1, we define the predicate divisible (a, b) in terms of the proposition P(a, b) given by

there is some $c \in \mathbb{N}$, such that a = bc.

For example, 15 is divisible by 3 since $15 = 3 \cdot 5$. On the other hand, 14 is not divisible by 3. **Definition 1.2.** A integer $a \in \mathbb{Z}$ is *even* if it is of the form a = 2b for some $b \in \mathbb{Z}$, *odd* if it is of the form a = 2b + 1 for some $b \in \mathbb{Z}$.

In Definition 1.2, the property even(a) of a being even is defined in terms of the predicate P(a) given by

there is some
$$b \in \mathbb{N}$$
, such that $a = 2b$.

The property odd(a) is obtained by changing a = 2b to a = 2b + 1 in P(a). The integer 14 is even, and the integer 15 is odd. Beware that we can't assert yet that if an integer is not even, then it is odd. Although this is true, this needs to be proven and requires induction, which we haven't discussed yet.

Prime numbers play a fundamental role in mathematics. Let us review their definition.

Definition 1.3. A natural number $p \in \mathbb{N}$ is *prime* if $p \ge 2$ and if the only divisors of p are 1 and p.

In the above definition, the property prime(p) is defined by the predicate P(p) given by

 $p \geq 2$, and for all $q \in \mathbb{N}$, if divisible(p,q), then q = 1 or q = p.

If we expand the definition of a prime number by replacing the predicate divisible by its defining formula, we get a rather complicated formula. Definitions allow us to be more concise.

According to Definition 1.3, the number 1 is not prime even though it is only divisible by 1 and itself (again 1). The reason for not accepting 1 as a prime is not capricious. It has to do with the fact that if we allowed 1 to be a prime, then certain important theorems (such as the unique prime factorization theorem would no longer hold.

Nonprime natural numbers (besides 1) have a special name too.

Definition 1.4. A natural number $a \in \mathbb{N}$ is *composite* if a = bc for some natural numbers b, c with $b, c \geq 2$.

For example, 4, 15, 36 are composite. Note that 1 is neither prime nor composite. We are now ready to introduce the proof templates for implication.

1.3 Meaning of Implication and Proof Templates for Implication

First, it is important to say that there are two types of proofs:

- 1. Direct proofs.
- 2. Indirect proofs.

Indirect proofs use the proof-by-contradiction principle, which will be discussed soon.

Because propositions do not arise from the vacuum but instead are built up from a set of atomic propositions using logical connectives (here, \Rightarrow), we assume the existence of an "official set of atomic propositions," or set of *propositional symbols*, $\mathbf{PS} = {\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3, \ldots}$. So, for example, $\mathbf{P}_1 \Rightarrow \mathbf{P}_2$ and $\mathbf{P}_1 \Rightarrow (\mathbf{P}_2 \Rightarrow \mathbf{P}_1)$ are propositions. Typically, we use uppercase letters such as P, Q, R, S, A, B, C, and so on, to denote arbitrary propositions formed using atoms from **PS**.

We begin by presenting proof templates to construct direct proofs of implications. An implication $P \Rightarrow Q$ can be understood as an if-then statement; that is, if P is true, then Q is also true. A better interpretation is that any proof of $P \Rightarrow Q$ can be used to construct a proof of Q, given any proof of P. As a consequence of this interpretation, we show later that if $\neg P$ is provable, then $P \Rightarrow Q$ is also provable (instantly) whether or not Q is provable. In such

a situation, we often say that $P \Rightarrow Q$ is vacuously provable. For example, $(P \land \neg P) \Rightarrow Q$ is provable for any arbitrary Q.

It might help to view the action of proving an implication $P \Rightarrow Q$ as the construction of a program that converts a proof of P into a proof of Q. Then if we supply a proof of P as input to this program (the proof of $P \Rightarrow Q$), it will output a proof of Q. If we don't give the right kind of input to this program, for example, a "wrong proof" of P, we should not expect the program to return a proof of Q. However, this does not say that the program is incorrect; the program was designed to do the right thing only if it is given the right kind of input. From this functional point of view (also called constructive), we should not be shocked that the provability of an implication $P \Rightarrow Q$ generally yields no information about the provability of Q.

Example 1.1. For a concrete example, say *P* stands for the statement,

"Our candidate for president wins in Pennsylvania,"

and Q stands for

"Our candidate is elected president."

Then $P \Rightarrow Q$ asserts that *if* our candidate for president wins in Pennsylvania, *then* our candidate is elected president.

If $P \Rightarrow Q$ holds, then if indeed our candidate for president wins in Pennsylvania then for sure our candidate will win the presidential election. However, if our candidate does not win in Pennsylvania, we can't predict what will happen. Our candidate may still win the presidential election but he/she may not.

If our candidate president does not win in Pennsylvania, then the statement $P \Rightarrow Q$ should be regarded as holding, though perhaps uninteresting.

Example 1.2. For one more example, let odd(n) assert that n is an odd natural number and let Q(n, a, b) assert that $a^n + b^n$ is divisible by a + b, where a, b are any given natural numbers. By divisible, we mean that we can find some natural number c, so that

$$a^n + b^n = (a+b)c.$$

Then we claim that the implication $odd(n) \Rightarrow Q(n, a, b)$ is provable.

As usual, let us assume odd(n), so that n = 2k + 1, where k = 0, 1, 2, 3, ... But then, we can easily check that

$$a^{2k+1} + b^{2k+1} = (a+b) \left(\sum_{i=0}^{2k} (-1)^i a^{2k-i} b^i \right),$$

which shows that $a^{2k+1} + b^{2k+1}$ is divisible by a + b. Therefore, we proved the implication $odd(n) \Rightarrow Q(n, a, b)$.

If n is not odd, then the implication $odd(n) \Rightarrow Q(n, a, b)$ yields no information about the provability of the statement Q(n, a, b), and that is fine. Indeed, if n is even and $n \ge 2$, then in general, $a^n + b^n$ is not divisible by a + b, but this may happen for some special values of n, a, and b, for example: n = 2, a = 2, b = 2.

During the process of constructing a proof, it may be necessary to introduce a list of *hypotheses*, also called *premises* (or *assumptions*), which grows and shrinks during the proof. When a proof is finished, it should have an empty list of premises.

The process of managing the list of premises during a proof is a bit technical. In Chapter 2, we study carefully two methods for managing the list of premises that may appear during a proof. In this chapter we are much more casual about it, which is the usual attitude when we write informal proofs. It suffices to be aware that at certain steps, some premises must be added, and at other special steps, premises must be discarded. We may view this as a process of making certain propositions active or inactive. To make matters clearer, we call the process of constructing a proof using a set of premises a *deduction*, and we reserve the word *proof* for a deduction whose set of premises is empty. Every deduction has a possibly empty list of *premises* and a single *conclusion*. The list of premises is usually denoted by Γ , and if the conclusion of the deduction is P, we say that we have a *deduction of* P from the premises Γ .

The first proof template allows us to make obvious deductions.

Proof Template 1.1. (Trivial Deductions)

If $P_1, \ldots, P_i, \ldots, P_n$ is a list of propositions assumed as premises (where each P_i may occur more than once), then for each P_i , we have a deduction with conclusion P_i .

All other proof templates are of two kinds: introduction rules or elimination rules. The meaning of these words will be explained after stating the next two proof templates.

The second proof template allows the construction of a deduction whose conclusion is an implication $P \Rightarrow Q$.

Proof Template 1.2. (Implication-Intro)

Given a list Γ of premises (possibly empty), to obtain a deduction with conclusion $P \Rightarrow Q$ proceed as follows:

- 1. Add one or more occurrences of P as additional premises to the list Γ .
- 2. Make a deduction of the conclusion Q from P and the premises in Γ .
- 3. Delete P from the list of premises.

The third proof template allows the constructions of a deduction from two other deductions.

Proof Template 1.3. (Implication-Elim or Modus Ponens)

Given a deduction with conclusion $P \Rightarrow Q$ from a list of premises Γ and a deduction with conclusion P from a list of premises Δ , we obtain a deduction with conclusion Q. The list of premises of this new deduction is the list Γ, Δ .

1.3. MEANING OF IMPLICATION AND PROOF TEMPLATES FOR IMPLICATION23

The modus-ponens proof template formalizes the use of *auxiliary lemmas*, a mechanism that we use all the time in making mathematical proofs. Think of $P \Rightarrow Q$ as a lemma that has already been established and belongs to some database of (useful) lemmas. This lemma says if I can prove P, then I can prove Q. Now suppose that we manage to give a proof of P. It follows from modus ponens that Q is also provable.

Mathematicians are very fond of modus ponens because it gives a potential method for proving important results. If Q is an important result and if we manage to build a large catalog of implications $P \Rightarrow Q$, there may be some hope that, some day, P will be proven, in which case Q will also be proven. So they build large catalogs of implications! This has been going on for the famous problem known as P versus NP. So far, no proof of any premise of such an implication involving P versus NP has been found (and it may never be found).

Beware, when we deduce that an implication $P \Rightarrow Q$ is provable, we **do not** prove that P and Q are provable; we only prove that if P is provable, then Q is provable.

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In case you wonder why the words "Intro" and "Elim" occur in the names assigned to the proof templates, the reason is the following:

- 1. If the proof template is tagged with X-Intro, the connective X appears in the conclusion of the proof template; it is introduced. For example, in Proof Template 1.2, the conclusion is $P \Rightarrow Q$, and \Rightarrow is indeed introduced.
- 2. If the proof template is tagged with X-Elim, the connective X appears in one of the premises of the proof template but it does not appear in the conclusion; it is eliminated. For example, in Proof Template 1.3 (modus ponens), $P \Rightarrow Q$ occurs as a premise but the conclusion is Q; the symbol \Rightarrow has been eliminated.

The introduction/elimination pattern is a characteristic of the kind of proof system that we are describing, which is called a *natural deduction proof system*.

Example 1.3. Let us give a simple example of the use of Proof Template 1.2. Recall that a natural number n is odd iff it is of the form 2k + 1, where $k \in \mathbb{N}$. Let us denote the fact that a number n is odd by odd(n). We would like to prove the implication

$$odd(n) \Rightarrow odd(n+2).$$

Following Proof Template 1.2, we add odd(n) as a premise (which means that we take as proven the fact that n is odd) and we try to conclude that n + 2 must be odd. However, to say that n is odd is to say that n = 2k + 1 for some natural number k. Now,

$$n+2 = 2k+1+2 = 2(k+1)+1,$$

which means that n + 2 is odd. (Here, n = 2h + 1, with h = k + 1, and k + 1 is a natural number because k is.)

Thus, we prove that if we assume odd(n), then we can conclude odd(n+2), and according to Proof Template 1.2, by Step (3) we delete the premise odd(n), and we obtain a proof of the proposition

$$odd(n) \Rightarrow odd(n+2).$$

It should be noted that the above proof of the proposition $\operatorname{odd}(n) \Rightarrow \operatorname{odd}(n+2)$ does not depend on any premises (other than the implicit fact that we are assuming n is a natural number). In particular, this proof does not depend on the premise $\operatorname{odd}(n)$, which was assumed (became "active") during our subproof step. Thus, after having applied the Proof Template 1.2, we made sure that the premise $\operatorname{odd}(n)$ is deactivated.

Example 1.4. For a second example, we wish to prove the proposition $P \Rightarrow P$.

According to Proof Template 1.2, we assume P. But then by Proof Template 1.1, we obtain a deduction with premise P and conclusion P; by executing Step (3) of Proof Template 1.2, the premise P is deleted, and we obtain a deduction of $P \Rightarrow P$ from the empty list of premises. Thank God, $P \Rightarrow P$ is provable!

Proofs described in words as above are usually better understood when represented as trees. We will reformulate our proof templates in tree form and explain very precisely how to build proofs as trees in Chapter 2. For now, we use tree representations of proofs in an informal way.

1.4 Proof Trees and Deduction Trees

A proof tree is drawn with its leaves at the top, corresponding to assumptions, and its root at the bottom, corresponding to the conclusion. In computer science, trees are usually drawn with their root at the top and their leaves at the bottom, but proof trees are drawn as the trees that we see in nature. Instead of linking nodes by edges, it is customary to use horizontal bars corresponding to the proof templates. One or more nodes appear as premises above a vertical bar, and the conclusion of the proof template appears immediately below the lowest horizontal bar. Proof trees are usually constructed from the bottom up (but not always), and once completed, they are read from the top down.

According to the first step of proof of $P \Rightarrow P$ (presented in words), we move the premise P to the list of premises, building a deduction of the conclusion P from the premise P corresponding to the following unfinished tree in which some leaf is labeled with the premise P, but with a missing subtree establishing P as the conclusion

$$\frac{P^x}{P}$$

$$\frac{P}{P \Rightarrow P}$$
Implication-Intro x

The premise P is tagged with the label x, which corresponds to the proof rule which causes its deletion from the list of premises.

In order to obtain a proof, we need to apply a proof template which allows us to deduce P from P, and of course, this is the Trivial Deduction proof template.

The finished proof is represented by the tree shown below. Observe that the premise P is tagged with the symbol $\sqrt{}$, which means that it has been deleted from the list of premises. The tree representation of proofs also has the advantage that we can tag the premises in such a way that each tag indicates which rule causes the corresponding premise to be deleted. In the tree below, the premise P is tagged with x, and it is deleted when the proof template indicated by x is applied.

$$\frac{\frac{P^{x}}{P}}{P \Rightarrow P}$$
 Trivial Deduction
Implication-Intro x

Example 1.5. For a third example, we prove the proposition $P \Rightarrow (Q \Rightarrow P)$.

According to Proof Template 1.2, we assume P as a premise and we try to prove $Q \Rightarrow P$ assuming P. In order to prove $Q \Rightarrow P$, by Proof Template 1.2, we assume Q as a new premise, so the set of premises becomes $\{P, Q\}$, and then we try to prove P from P and Q.

At this stage, we have the following unfinished tree with two leaves labeled P and Q but with a missing subtree establishing P as the conclusion.

$$\frac{P^{x}, Q^{y}}{Q \Rightarrow P} \qquad \text{Implication-Intro }_{y} \\
\frac{P}{Q \Rightarrow P} \qquad \text{Implication-Intro }_{x} \\
P \Rightarrow (Q \Rightarrow P)$$

We need to find a deduction of P from the premises P and Q. By Proof Template 1.1 (trivial deductions), we have a deduction with the list of premises $\{P, Q\}$ and conclusion P. Then, executing Step (3) of Proof Template 1.2 twice, we delete the premise Q and then the premise P (in this order), and we obtain a proof of $P \Rightarrow (Q \Rightarrow P)$. The above proof of $P \Rightarrow (Q \Rightarrow P)$ (presented in words) is represented by the following tree:

$$\begin{array}{c} \frac{P^{x\sqrt{}},Q^{y\sqrt{}}}{P} & \text{Trivial Deduction} \\ \hline \frac{P}{Q \Rightarrow P} & \text{Implication-Intro } y \\ \hline P \Rightarrow (Q \Rightarrow P) & \text{Implication-Intro } x \end{array}$$

Observe that both premises P and Q are tagged with the symbol $\sqrt{}$, which means that they have been deleted from the list of premises.

We tagged the premises in such a way that each tag indicates which rule causes the corresponding premise to be deleted. In the above tree, Q is tagged with y, and it is deleted when the proof template indicated by y is applied, and P is tagged with x, and it is deleted when the proof template indicated by x is applied. In a proof, *all* leaves must be tagged with the symbol $\sqrt{}$.

Example 1.6. Let us now give a proof of $P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q)$.

Using Proof Template 1.2, we assume both P and $P \Rightarrow Q$ and we try to prove Q. At this stage, we have the following unfinished tree with two leaves labeled $P \Rightarrow Q$ and P but with a missing subtree establishing Q as the conclusion.

$$(P \Rightarrow Q)^{x} \qquad P^{y}$$

$$\frac{Q}{(P \Rightarrow Q) \Rightarrow Q}$$
Implication-Intro x
$$P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q)$$
Implication-Intro y

We can use Proof Template 1.3 to derive a deduction of Q from $P \Rightarrow Q$ and P. Finally, we execute Step (3) of Proof Template 1.2 to delete $P \Rightarrow Q$ and P (in this order), and we obtain a proof of $P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q)$. A tree representation of the above proof is shown below.

$$\begin{array}{c|c} (P \Rightarrow Q)^{x\sqrt{}} & P^{y\sqrt{}} \\ \hline \\ \hline \\ \hline \\ Q \\ \hline \\ \hline \\ \hline \\ \hline \\ (P \Rightarrow Q) \Rightarrow Q \\ \hline \\ P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q) \end{array} \\ \mbox{Implication-Intro } _{y} \\ \hline \\ \mbox{Implication-Intro } _{y} \\ \hline \end{array}$$

Remark: We have not yet examined how we can represent precisely arbitrary deductions. This can be done using certain types of trees where the nodes are tagged with lists of premises. Two methods for doing this are carefully defined in Chapter 2. It turns out that the same premise may be used in more than one location in the tree, but in our informal presentation, we ignore such fine details.

We now describe the proof templates dealing with the connectives $\neg, \land, \lor, \equiv$.

1.5 Proof Templates for \neg

Recall that $\neg P$ is an abbreviation for $P \Rightarrow \bot$. We begin with the proof templates for negation, involving direct proofs.

Proof Template 1.4. (Negation-Intro)

Given a list Γ of premises (possibly empty), to obtain a deduction with conclusion $\neg P$ proceed as follows:

- 1. Add one or more occurrences of P as additional premises to the list Γ .
- 2. Derive a contradiction. More precisely, make a deduction of the conclusion \perp from P and the premises in Γ .
- 3. Delete P from the list of premises.

Proof Template 1.4 is a special case of Proof Template 1.2, since $\neg P$ is an abbreviation for $P \Rightarrow \perp$.

Proof Template 1.5. (Negation-Elim)

Given a deduction with conclusion $\neg P$ from a list of premises Γ and a deduction with conclusion P from a list of premises Δ , we obtain a contradiction; that is, a deduction with conclusion \bot . The list of premises of this new deduction is Γ, Δ .

Proof Template 1.5 is a special case of Proof Template 1.3, since $\neg P$ is an abbreviation for $P \Rightarrow \perp$.

Proof Template 1.6. (*Perp-Elim*)

Given a deduction with conclusion \perp (a contradiction), for every proposition Q, we obtain a deduction with conclusion Q. The list of premises of this new deduction is the same as the original list of premises.

The next proof template for negation constructs an indirect proof; it is the *proof-by-contradiction* principle.

Proof Template 1.7. (Proof-By-Contradiction Principle)

Given a list Γ of premises (possibly empty), to obtain a deduction with conclusion P proceed as follows:

- 1. Add one or more occurrences of $\neg P$ as additional premises to Γ .
- 2. Derive a contradiction. More precisely, make a deduction of the conclusion \perp from $\neg P$ and the premises in Γ .
- 3. Delete $\neg P$ from the list of premises.

Proof Template 1.7 (the proof-by-contradiction principle) also has the fancy name of *reductio ad absurdum rule*, *RAA* for short.

Proof Template 1.6 may seem silly and one might wonder why we stated it. It turns out that it is subsumed by Proof Template 1.7, but it is still useful to state it as a proof template.

Example 1.7. Let us prove that for every natural number n, if n^2 is odd, then n itself must be odd.

We use the proof-by-contradiction principle (Proof Template 1.7), so we assume that n is not odd, which means that n is even. (Actually, in this step, we are using a property of the natural numbers that is proven by induction, but let's not worry about that right now; a proof can be found in Section 1.12). But to say that n is even means that n = 2k for some k and then $n^2 = 4k^2 = 2(2k^2)$, so n^2 is even, contradicting the assumption that n^2 is odd. By the proof-by-contradiction principle (Proof Template 1.7), we conclude that n must be odd. **Example 1.8.** Let us prove that $\neg \neg P \Rightarrow P$.

It turns out that this requires using the proof-by-contradiction principle (Proof Template 1.7). First, by Proof Template 1.2, assume $\neg \neg P$ as a premise. Then by the proof-by-contradiction principle (Proof Template 1.7), in order to prove P, assume $\neg P$. By Proof Template 1.5, we obtain a contradiction (\bot). Thus, by Step (3) of the proof-by-contradiction principle (Proof Template 1.7), we delete the premise $\neg P$, and we obtain a deduction of P from $\neg \neg P$. Finally, by Step (3) of Proof Template 1.2, we delete the premise $\neg \neg P$ and obtain a proof of $\neg \neg P \Rightarrow P$. This proof has the following tree representation.

Example 1.9. Now we prove that $P \Rightarrow \neg \neg P$.

First, by Proof Template 1.2, assume P as a premise. In order to prove $\neg \neg P$ using Proof Template 1.4, assume $\neg P$. We now have the two premises $\neg P$ and P, so by Proof Template 1.5, we obtain a contradiction (\bot). By Step (3) of Proof Template 1.4, we delete the premise $\neg P$, and we obtain a deduction of $\neg \neg P$ from P. Finally, by Step (3) of Proof Template 1.2, delete the premise P to obtain a proof of $P \Rightarrow \neg \neg P$. This proof has the following tree representation.

Observe that the previous two examples show that the equivalence $P \equiv \neg \neg P$ is provable. As a consequence of this equivalence, if we prove a negated proposition $\neg P$ using the proofby-contradiction principle, we assume $\neg \neg P$, and we deduce a contradiction. But since $\neg \neg P$ and P are equivalent (as far as provability), this amounts to deriving a contradiction from P, which is just the Proof Template 1.4.

In summary, to prove a negated proposition $\neg P$, always use Proof Template 1.4.

On the other hand, to prove a nonnegated proposition, it is generally not possible to tell if a direct proof exists or if the proof-by-contradiction principle is required. There are propositions for which it is required, for example $\neg \neg P \Rightarrow P$ and $(\neg (P \Rightarrow Q)) \Rightarrow P$.

Example 1.10. Let us now prove that $(\neg(P \Rightarrow Q)) \Rightarrow \neg Q$.

First, by Proof Template 1.2, we add $\neg(P \Rightarrow Q)$ as a premise. Then in order to prove $\neg Q$ from $\neg(P \Rightarrow Q)$, we use Proof Template 1.4, and we add Q as a premise. We obtain the following deduction tree with a piece missing.

Now, recall that we showed in Example 1.5 that $P \Rightarrow Q$ is provable assuming Q (with P and Q switched). Then, since $\neg(P \Rightarrow Q)$ is a premise, by Proof Template 1.5, we obtain a deduction of \bot ; see below.

We now execute Step (3) of Proof Template 1.4, delete the premise Q to obtain a deduction of $\neg Q$ from $\neg (P \Rightarrow Q)$, and we execute Step (3) of Proof Template 1.2 to delete the premise $\neg (P \Rightarrow Q)$ and obtain a proof of $(\neg (P \Rightarrow Q)) \Rightarrow \neg Q$. The above proof corresponds to the following tree.

$$\begin{array}{ccc} & & \frac{Q^{y\sqrt{}} & P^{x\sqrt{}}}{P \Rightarrow Q} & \text{Trivial Deduction} \\ \hline & & \frac{Q}{P \Rightarrow Q} & \text{Implication-Intro } x \\ \hline & & \frac{-(P \Rightarrow Q)^{z\sqrt{}}}{P \Rightarrow Q} & \text{Negation-Elim} \\ \hline & & \frac{-1}{\neg Q} & \text{Negation-Elim} \\ \hline & & \frac{-1}{(\neg(P \Rightarrow Q)) \Rightarrow \neg Q} & \text{Implication-Intro } z \end{array}$$

Here is an example using Proof Templates 1.6 (Perp-Elim) and 1.7 (RAA).

Example 1.11. Let us prove that $(\neg(P \Rightarrow Q)) \Rightarrow P$.

First, we use Proof Template 1.2, and we assume $\neg(P \Rightarrow Q)$ as a premise. Next, we use the proof-by-contradiction principle (Proof Template 1.7). So in order to prove P, we assume $\neg P$ as another premise. The next step is to deduce $P \Rightarrow Q$. By Proof Template 1.2, we assume P as an additional premise. By Proof Template 1.5, from $\neg P$ and P we

obtain a deduction of \bot , and then by Proof Template 1.6, a deduction of Q from $\neg P$ and P. By Proof Template 1.2, executing Step (3), we delete the premise P and we obtain a deduction of $P \Rightarrow Q$. At this stage, we have the premises $\neg P, \neg(P \Rightarrow Q)$ and a deduction of $P \Rightarrow Q$, so by Proof Template 1.5, we obtain a deduction of \bot . This is a contradiction, so by Step (3) of the proof-by-contradiction principle (Proof Template 1.7), we can delete the premise $\neg P$, and we have a deduction of P from $\neg(P \Rightarrow Q)$. Finally, we execute Step (3) of Proof Template 1.2 and delete the premise $\neg(P \Rightarrow Q)$, which yields the desired proof of $(\neg(P \Rightarrow Q)) \Rightarrow P$. The above proof has the following tree representation.

$$\begin{array}{c|c} & \overline{\neg P^{y\sqrt{}}} & P^{x\sqrt{}} & \text{Negation-Elim} \\ & \underline{-} & Perp-Elim \\ & Q & \text{Implication-Intro } x \\ \hline (P \Rightarrow Q)^{z\sqrt{}} & P \Rightarrow Q & \text{Negation-Elim} \\ \hline & \underline{-} & \text{RAA } y \\ \hline & \underline{-} & P & \text{Implication-Intro } z \\ \hline & (\neg(P \Rightarrow Q)) \Rightarrow P & \text{Implication-Intro } z \end{array}$$

The reader may be surprised by how many steps are needed in the above proof and may wonder whether the proof-by-contradiction principle is actually needed. It can be shown that the proof-by-contradiction principle must be used, and unfortunately there is no shorter proof.

Even though Proof Template 1.4 qualifies as a direct proof template, it proceeds by deriving a contradiction, so we suggest to call it the *proof-by-contradiction for negated propositions* principle.

Remark: The fact that the implication $\neg \neg P \Rightarrow P$ is provable has the interesting consequence that if we take $\neg \neg P \Rightarrow P$ as an *axiom* (which means that $\neg \neg P \Rightarrow P$ is assumed to be provable without requiring any proof), then the proof-by-contradiction principle (Proof Template 1.7) becomes redundant. Indeed, Proof Template 1.7 is subsumed by Proof Template 1.4, because if we have a deduction of \bot from $\neg P$, then by Proof Template 1.4 we delete the premise $\neg P$ to obtain a deduction of $\neg \neg P$. Since $\neg \neg P \Rightarrow P$ is assumed to be provable, by Proof Template 1.3, we get a proof of P. The tree shown below illustrates what is going on. In this tree, a proof of \bot from the premise $\neg P$ is denoted by \mathcal{D} .

$$\neg P^{x\sqrt{px}}$$

$$D$$

$$\frac{\bot}{\neg \neg P \Rightarrow P} \qquad \neg \neg P$$
Negation-Intro x
$$P$$
Implication-Elim

Proof Templates 1.5 and 1.6 together imply that if a contradiction is obtained during a deduction because two inconsistent propositions P and $\neg P$ are obtained, then *all* propositions are provable (anything goes). This explains why mathematicians are leavy of inconsistencies.

1.6 Proof Templates for \land, \lor, \equiv

The proof templates for conjunction are the simplest.

Proof Template 1.8. (And-Intro)

Given a deduction with conclusion P from a list of premises Γ and a deduction with conclusion Q from a list of premises Δ , we obtain a deduction with conclusion $P \wedge Q$. The list of premises of this new deduction is Γ, Δ .

Proof Template 1.9. (And-Elim)

Given a deduction with conclusion $P \wedge Q$, we obtain a deduction with conclusion P, and a deduction with conclusion Q. The list of premises of these new deductions is the same as the list of premises of the original deduction.

Let us consider a few examples of proofs using the proof templates for conjunction as well as Proof Templates 1.4 and 1.7.

Example 1.12. Let us prove that for any natural number n, if n is divisible by 2 and n is divisible by 3, then n is divisible by 6. This is expressed by the proposition

$$((2 \mid n) \land (3 \mid n)) \Rightarrow (6 \mid n).$$

We start by using Proof Templates 1.2, and we add the premise $(2 \mid n) \land (3 \mid n)$. Using Proof Template 1.9 twice, we obtain deductions of $(2 \mid n)$ and $(3 \mid n)$ from $(2 \mid n) \land (3 \mid n)$. But $(2 \mid n)$ means that

n = 2a

for some $a \in \mathbb{N}$, and $3 \mid n$ means that

n = 3b

for some $b \in \mathbb{N}$. This implies that

$$n = 2a = 3b.$$

Because 2 and 3 are relatively prime (their only common divisor is 1), the number 2 must divide b (and 3 must divide a), so b = 2c for some $c \in \mathbb{N}$. Here we are using Euclid's lemma. So we have shown that

$$n = 3b = 3 \cdot 2c = 6c,$$

which says that n is divisible by 6. We conclude with Step (3) of Proof Template 1.2 by deleting the premise $(2 \mid n) \land (3 \mid n)$, and we obtain our proof.

Example 1.13. Let us prove that for any natural number n, if n is divisible by 6, then n is divisible by 2 and n is divisible by 3. This is expressed by the proposition

$$(6 \mid n) \Rightarrow ((2 \mid n) \land (3 \mid n)).$$

We start by using Proof Template 1.2, and we add the premise $6 \mid n$. This means that

$$n = 6a = 2 \cdot 3a$$

for some $a \in \mathbb{N}$. This implies that $2 \mid n$ and $3 \mid n$, so we have a deduction of $2 \mid n$ from the premise $6 \mid n$, and a deduction of $3 \mid n$ from the premise $6 \mid n$. By Proof Template 1.8, we obtain a deduction of $(2 \mid n) \land (3 \mid n)$ from $6 \mid n$, and we apply Step (3) of Proof Template 1.2 to delete the premise $6 \mid n$ and obtain our proof.

Example 1.14. Let us prove that a natural number n cannot be even and odd simultaneously. This is expressed as the proposition

$$\neg (\mathrm{odd}(n) \wedge \mathrm{even}(n)).$$

We begin with Proof Template 1.4, and we assume $odd(n) \wedge even(n)$ as a premise. Using Proof Template 1.9 twice, we obtain deductions of odd(n) and even(n) from $odd(n) \wedge even(n)$. Now, odd(n) says that n = 2a + 1 for some $a \in \mathbb{N}$, and even(n) says that n = 2b for some $b \in \mathbb{N}$. But then,

$$n = 2a + 1 = 2b$$

so we obtain 2(b-a) = 1. Since b-a is an integer, either 2(b-a) = 0 (if a = b) or $|2(b-a)| \ge 2$, so we obtain a contradiction. Applying Step (3) of Proof Template 1.4, we delete the premise $odd(n) \land even(n)$, and we have a proof of $\neg(odd(n) \land even(n))$.

Example 1.15. Let us prove that $(\neg(P \Rightarrow Q)) \Rightarrow (P \land \neg Q)$.

We start by using Proof Templates 1.2, and we add $\neg(P \Rightarrow Q)$ as a premise. Now in Example 1.11, we showed that $(\neg(P \Rightarrow Q)) \Rightarrow P$ is provable, and this proof contains a deduction of P from $\neg(P \Rightarrow Q)$. Similarly, in Example 1.10, we showed that $(\neg(P \Rightarrow Q)) \Rightarrow$ $\neg Q$ is provable, and this proof contains a deduction of $\neg Q$ from $\neg(P \Rightarrow Q)$. By Proof Template 1.8, we obtain a deduction of $P \land \neg Q$ from $\neg(P \Rightarrow Q)$, and executing Step (3) of Proof Templates 1.2, we obtain a proof of $(\neg(P \Rightarrow Q)) \Rightarrow (P \land \neg Q)$. The following tree represents the above proof. Observe that *two copies* of the premise $\neg(P \Rightarrow Q)$ are needed.

$$\frac{\neg P^{y\sqrt{P^{x\sqrt{P^{x\sqrt{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{Q^{P^{x\sqrt{P^{x}}}}}}}}}}}}}}}}}}{\frac{\neg (P \Rightarrow Q)^{z\sqrt{P^{x\sqrt{P^{x}}}}}}}{P \Rightarrow Q}}{P \Rightarrow Q}}{\frac{1}{\frac{1}{(\neg (P \Rightarrow Q)) \Rightarrow (P \land \neg Q)}}}^{z}}}}$$

Observe that the left subtree comes from the proof tree Example 1.11 and the right subtree comes from the proof tree in Example 1.10.

Next, we present the proof templates for disjunction.

Proof Template 1.10. (Or-Intro)

Given a list Γ of premises (possibly empty),

- 1. If we have a deduction with conclusion P, then we obtain a deduction with conclusion $P \lor Q$.
- 2. If we have a deduction with conclusion Q, then we obtain a deduction with conclusion $P \lor Q$.

In both cases, the new deduction has Γ as premises.

Proof Template 1.11. (Or-Elim or Proof-By-Cases)

Given three lists of premises Γ , Δ , Λ , to obtain a deduction of some proposition R as conclusion, proceed as follows:

- 1. Construct a deduction of some disjunction $P \vee Q$ from the list of premises Γ .
- 2. Add one or more occurrences of P as additional premises to the list Δ and find a deduction of R from P and Δ .
- 3. Add one or more occurrences of Q as additional premises to the list Λ and find a deduction of R from Q and Λ .

The list of premises after applying this rule is Γ, Δ, Λ .

Note that in making the two deductions of R, the premise $P \lor Q$ is not assumed.

Example 1.16. Let us show that for any natural number n, if 4 divides n or 6 divides n, then 2 divides n. This can be expressed as

$$((4 \mid n) \lor (6 \mid n)) \Rightarrow (2 \mid n).$$

First, by Proof Template 1.2, we assume $(4 \mid n) \lor (6 \mid n)$ as a premise. Next, we use Proof Template 1.11, the proof-by-cases principle. First, assume $(4 \mid n)$. This means that

$$n = 4a = 2 \cdot 2a$$

for some $a \in \mathbb{N}$. Therefore, we conclude that $2 \mid n$. Next, assume $(6 \mid n)$. This means that

$$n = 6b = 2 \cdot 3b$$

for some $b \in \mathbb{N}$. Again, we conclude that $2 \mid n$. Since $(4 \mid n) \lor (6 \mid n)$ is a premise, by Proof Template 1.11, we can obtain a deduction of $2 \mid n$ from $(4 \mid n) \lor (6 \mid n)$. Finally, by Proof Template 1.2, we delete the premise $(4 \mid n) \lor (6 \mid n)$ to obtain our proof.

Proof Template 1.10 (Or-Intro) may seem trivial, so let us show an example illustrating its use.

Example 1.17. Let us prove that $\neg(P \lor Q) \Rightarrow (\neg P \land \neg Q)$.

First by Proof Template 1.2, we assume $\neg(P \lor Q)$ (two copies). In order to derive $\neg P$, by Proof Template 1.4, we also assume P. Then by Proof Template 1.10, we deduce $P \lor Q$, and since we have the premise $\neg(P \lor Q)$, by Proof Template 1.5, we obtain a contradiction. By Proof Template 1.4, we can delete the premise P and obtain a deduction of $\neg P$ from $\neg(P \lor Q)$.

In a similar way, we can construct a deduction of $\neg Q$ from $\neg (P \lor Q)$. By Proof Template 1.8, we get a deduction of $\neg P \land \neg Q$ from $\neg (P \lor Q)$, and we finish by applying Proof Template 1.2. A tree representing the above proof is shown below.

$$\frac{\neg (P \lor Q)^{z \checkmark}}{\frac{\bot}{\neg P}} \quad \begin{array}{c} \operatorname{Or-Intro} & \frac{Q^{w \checkmark}}{P \lor Q} & \operatorname{Or-Intro} \\ \frac{\neg (P \lor Q)^{z \checkmark}}{\frac{\bot}{\neg P}} & \frac{\neg (P \lor Q)^{z \checkmark}}{\frac{\bot}{\neg Q}} & \frac{Q^{w \checkmark}}{P \lor Q} \\ \end{array} \quad \begin{array}{c} \operatorname{Or-Intro} \\ \frac{\neg (P \lor Q)^{z \checkmark}}{\frac{\neg (P \lor Q)^{z \checkmark}}{\neg Q}} & \frac{Q^{w \checkmark}}{P \lor Q} \\ \frac{\neg (P \lor Q)^{z \checkmark}}{\frac{\neg P \land \neg Q}{\neg Q}} & \frac{\neg P \land \neg Q}{z} \\ \end{array}$$

The proposition $(\neg P \land \neg Q) \Rightarrow \neg (P \lor Q)$ is also provable using the proof-by-cases principle. Here is a proof tree; we leave it as an exercise to the reader to check that the proof templates have been applied correctly.

$$\frac{(\neg P \land \neg Q)^{t\sqrt{}}}{(\neg P \land \neg Q)^{t\sqrt{}}} \underbrace{P^{x\sqrt{}}}_{px\sqrt{}} \qquad \underbrace{\frac{(\neg P \land \neg Q)^{t\sqrt{}}}{\neg Q} \qquad Q^{y\sqrt{}}}_{px\sqrt{}}}_{Qy\sqrt{}}$$

$$\frac{(\neg P \land \neg Q)^{z\sqrt{}}}{(\neg P \land \neg Q)} \xrightarrow{z}_{(\neg P \land \neg Q)} \xrightarrow{t}_{r,y}$$

As a consequence, the equivalence

$$\neg (P \lor Q) \equiv (\neg P \land \neg Q)$$

is provable. This is one of three identities known as *de Morgan laws*.

Example 1.18. Next, let us prove that $\neg(\neg P \lor \neg Q) \Rightarrow P$. A tree representing the proof is shown below.

$$\frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \qquad \overline{\neg P \lor \neg Q}}{\frac{\bot}{P} \qquad \text{RAA } x} \\ \frac{\neg (\neg P \lor \neg Q) \Rightarrow P}{\neg (\neg P \lor \neg Q) \Rightarrow P} \qquad y$$

First by Proof Template 1.2, we assume $\neg(\neg P \lor \neg Q)$ as a premise. In order to prove P from $\neg(\neg P \lor \neg Q)$, we use the proof-by-contradiction principle (Proof Template 1.7). So we add $\neg P$ as a premise. Now by Proof Template 1.10, we can deduce $\neg P \lor \neg Q$ from $\neg P$, and since $\neg(\neg P \lor \neg Q)$ is a premise, by Proof Template 1.5, we obtain a contradiction. By the proof-by-contradiction principle (Proof Template 1.7), we delete the premise $\neg P$, and we obtain a deduction of P from $\neg(\neg P \lor \neg Q)$. We conclude by using Proof Template 1.2 to delete the premise $\neg(\neg P \lor \neg Q)$ and to obtain our proof.

A similar proof shows that $\neg(\neg P \lor \neg Q) \Rightarrow Q$ is provable. Putting together the proofs of P and Q from $\neg(\neg P \lor \neg Q)$ using Proof Template 1.8, we obtain a proof of

$$\neg(\neg P \lor \neg Q) \Rightarrow (P \land Q)$$

A tree representing this proof is shown below.

$$\frac{\neg (\neg P \lor \neg Q)^{y} \checkmark}{\frac{1}{P}} \frac{\neg P^{x} \checkmark}{\neg P \lor \neg Q} \qquad \frac{\neg Q^{w} \checkmark}{\neg P \lor \neg Q}$$

$$\frac{\neg (\neg P \lor \neg Q)^{y} \checkmark}{\frac{1}{Q}} \frac{\neg (\neg P \lor \neg Q)^{y} \checkmark}{\neg P \lor \neg Q}$$

$$\frac{\neg Q^{w} \checkmark}{\neg P \lor \neg Q}$$

$$\frac{\neg Q^{w} \checkmark}{\neg P \lor \neg Q}$$

$$\frac{\neg Q^{w} \lor}{\neg P \lor \neg Q}$$

Example 1.19. The proposition $\neg(P \land Q) \Rightarrow (\neg P \lor \neg Q)$ is provable. A tree represented the proof is shown below.

$$\frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \quad \frac{\neg P^{x \checkmark}}{\neg P \lor \neg Q}}{\frac{\bot}{P} \quad RAA x} \qquad \frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \quad \frac{\neg Q^{w \checkmark}}{\neg P \lor \neg Q}}{\frac{\bot}{Q} \quad RAA x}$$
$$\frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \quad \frac{\neg P \lor \neg Q}{\neg P \lor \neg Q}}{\frac{\bot}{Q} \quad RAA x}$$
$$\frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \quad \frac{\neg P \lor \neg Q}{\neg P \lor \neg Q}}{\frac{\neg P \lor \neg Q}{\neg P \lor \neg Q}} \quad \frac{\neg (\neg P \lor \neg Q)^{y \checkmark} \quad \frac{\neg Q^{w \checkmark}}{\neg P \lor \neg Q}}{\neg (P \land Q) \Rightarrow \neg P \lor \neg Q} \quad t$$

First by Proof Template 1.2, we assume $\neg(P \land Q)$ as a premise. Next, we use the proofby-contradiction principle (Proof Template 1.7) to deduce $\neg P \lor \neg Q$, so we also assume $\neg(\neg P \lor \neg Q)$. Now, we just showed that $P \land Q$ is provable from the premise $\neg(\neg P \lor \neg Q)$. Using the premise $\neg(P \land Q)$, by Proof Principle 1.5, we derive a contradiction, and by the proof-by-contradiction principle, we delete the premise $\neg(\neg P \lor \neg Q)$ to obtain a deduction of $\neg P \lor \neg Q$ from $\neg(P \land Q)$. We finish the proof by applying Proof Template 1.2.

The next example is particularly interesting because the proof-by-contradiction principle must be used.

Example 1.20. We prove the proposition

$$P \lor \neg P$$
.

We use the proof-by-contradiction principle (Proof Template 1.7), so we assume $\neg(P \lor \neg P)$ as a premise. The first tricky part of the proof is that we actually assume that we have *two* copies of the premise $\neg(P \lor \neg P)$.

Next, the second tricky part of the proof is that using one of the two copies of $\neg (P \lor \neg P)$, we are going to deduce $P \lor \neg P$. For this, we first derive $\neg P$ using Proof Template 1.4, so we assume P. By Proof Template 1.10, we deduce $P \lor \neg P$, but we have the premise $\neg (P \lor \neg P)$, so by Proof Template 1.5, we obtain a contradiction. Next, by Proof Template 1.4, we delete the premise P, deduce $\neg P$, and then by Proof Template 1.10, we deduce $P \lor \neg P$.

Since we still have a second copy of the premise $\neg(P \lor \neg P)$, by Proof Template 1.5, we get a contradiction! The only premise left is $\neg(P \lor \neg P)$ (two copies of it), so by the proofby-contradiction principle (Proof Template 1.7), we delete the premise $\neg(P \lor \neg P)$, and we obtain the desired proof of $P \lor \neg P$.

$$\frac{\neg (P \lor \neg P)^{x \checkmark} \qquad \frac{P^{y \checkmark}}{P \lor \neg P}}{(P \lor \neg P)^{x \checkmark} \qquad \frac{\neg (P \lor \neg P)^{x \checkmark}}{P \lor \neg P}} \qquad \text{Negation-Elim}}$$

$$\frac{\neg (P \lor \neg P)^{x \checkmark} \qquad \frac{\neg P}{P \lor \neg P}}{(P \lor \neg P)^{x \lor \neg P}} \qquad \text{Negation-Elim}}$$

If the above proof made you dizzy, this is normal. The sneaky part of this proof is that when we proceed by contradiction and assume $\neg(P \lor \neg P)$, this proposition is an inconsistency, so it allows us to derive $P \lor \neg P$, which then clashes with $\neg(P \lor \neg P)$ to yield a contradiction. Observe that during the proof we actually showed that $\neg \neg(P \lor \neg P)$ is provable. The proofby-contradiction principle is needed to get rid of the double negation.

The fact is that even though the proposition $P \lor \neg P$ seems obviously "true," its truth is viewed as controversial by certain mathematicians and logicians. To some extent, this is why
its proof has to be a bit tricky and has to involve the proof-by-contradiction principle. This matter is discussed quite extensively in Chapter 2. In this chapter, which is more informal, let us simply say that the proposition $P \vee \neg P$ is known as the *law of excluded middle*. Indeed, intuitively, it says that for every proposition P, either P is true or $\neg P$ is true; there is no middle alternative.

It can be shown that if we take all formulae of the form $P \vee \neg P$ as axioms, then the proof-by-contradiction principle is derivable from the other proof templates; see Section 2.8. Furthermore, the propositions $\neg \neg P \Rightarrow P$ and $P \vee \neg P$ are equivalent (that is, $(\neg \neg P \Rightarrow P) \equiv (P \vee \neg P)$ is provable).

Typically, to prove a disjunction $P \vee Q$, it is rare that we can use Proof Template 1.10 (Or-Intro), because this requires constructing of a proof of P or a proof of Q in the first place. But the fact that $P \vee Q$ is provable does not imply in general that either a proof of P or a proof of Q can be produced, as the example of the proposition $P \vee \neg P$ shows (other examples can be given). Thus, usually to prove a disjunction we use the proof-by-contradiction principle. Here is an example.

Example 1.21. Given some natural numbers p, q, we wish to prove that if 2 divides pq, then either 2 divides p or 2 divides q. This can be expressed by

$$(2 \mid pq) \Rightarrow ((2 \mid p) \lor (2 \mid q)).$$

We use the proof-by-contradiction principle (Proof Template 1.7), so we assume $\neg((2 \mid p) \lor (2 \mid q))$ as a premise. This is a proposition of the form $\neg(P \lor Q)$, and in Example 1.17 we showed that $\neg(P \lor Q) \Rightarrow (\neg P \land \neg Q)$ is provable. Thus, by Proof Template 1.3, we deduce that $\neg(2 \mid p) \land \neg(2 \mid q)$. By Proof Template 1.9, we deduce both $\neg(2 \mid p)$ and $\neg(2 \mid q)$. Using some basic arithmetic, this means that p = 2a + 1 and q = 2b + 1 for some $a, b \in \mathbb{N}$. But then,

$$pq = 2(2ab + a + b) + 1$$

and pq is not divisible by 2, a contradiction. By the proof-by-contradiction principle (Proof Template 1.7), we can delete the premise $\neg((2 \mid p) \lor (2 \mid q))$ and obtain the desired proof.

Another proof template which is convenient to use is the *proof-by-contrapositive principle*.

Proof Template 1.12. (Proof-By-Contrapositive)

Given a list of premises Γ , to prove an implication $P \Rightarrow Q$, proceed as follows:

- 1. Add $\neg Q$ to the list of premises Γ .
- 2. Construct a deduction of $\neg P$ from the premises $\neg Q$ and Γ .
- 3. Delete $\neg Q$ from the list of premises.

It is not hard to see that the proof-by-contrapositive principle (Proof Template 1.12) can be derived from the proof-by-contradiction principle. We leave this as an exercise. **Example 1.22.** We prove that for any two natural numbers $m, n \in \mathbb{N}$, if m + n is even, then m and n have the same parity. This can be expressed as

 $\operatorname{even}(m+n) \Rightarrow ((\operatorname{even}(m) \land \operatorname{even}(n)) \lor (\operatorname{odd}(m) \land \operatorname{odd}(n))).$

According to Proof Template 1.12 (proof-by-contrapositive principle), let us assume $\neg((\operatorname{even}(m) \land \operatorname{even}(n)) \lor (\operatorname{odd}(m) \land \operatorname{odd}(n)))$. Using the implication proven in Example 1.17 $((\neg(P \lor Q)) \Rightarrow \neg P \land \neg Q))$ and Proof Template 1.3, we deduce that $\neg(\operatorname{even}(m) \land \operatorname{even}(n))$ and $\neg(\operatorname{odd}(m) \land \operatorname{odd}(n))$. Using the result of Example 1.19 and modus ponens (Proof Template 1.3), we deduce that $\neg\operatorname{even}(m) \lor \neg\operatorname{even}(n)$ and $\neg\operatorname{odd}(m) \lor \neg\operatorname{odd}(n)$. At this point, we can use the proof-by-cases principle (twice) to deduce that $\neg\operatorname{even}(m + n)$ holds. We leave some of the tedious details as an exercise. In particular, we use the fact proven in Chapter 2 that $\operatorname{even}(p)$ iff $\neg\operatorname{odd}(p)$ (see Section 2.20).

We treat *logical equivalence* as a derived connective: that is, we view $P \equiv Q$ as an abbreviation for $(P \Rightarrow Q) \land (Q \Rightarrow P)$. In view of the proof templates for \land , we see that to prove a logical equivalence $P \equiv Q$, we just have to prove both implications $P \Rightarrow Q$ and $Q \Rightarrow P$. For the sake of completeness, we state the following proof template.

Proof Template 1.13. (Equivalence-Intro)

Given a list of premises Γ , to obtain a deduction of an equivalence $P \equiv Q$, proceed as follows:

- 1. Construct a deduction of the implication $P \Rightarrow Q$ from the list of premises Γ .
- 2. Construct a deduction of the implication $Q \Rightarrow P$ from the list of premises Γ .

The proof templates described in this section and the previous one allow proving propositions which are known as the propositions of *classical propositional logic*. We also say that this set of proof templates is a *natural deduction proof system* for propositional logic; see Prawitz [60] and Gallier [18].

1.7 De Morgan Laws and Other Useful Rules of Logic

In Section 1.5, we proved certain implications that are special cases of the so-called *de Morgan laws*.

Proposition 1.1. The following equivalences (de Morgan laws) are provable:

$$\neg \neg P \equiv P$$
$$\neg (P \land Q) \equiv \neg P \lor \neg Q$$
$$\neg (P \lor Q) \equiv \neg P \land \neg Q.$$

The following equivalence expressing \Rightarrow in terms of \lor and \neg is also provable:

$$P \Rightarrow Q \equiv \neg P \lor Q.$$

The following proposition (the law of the excluded middle) is provable:

 $P \lor \neg P$.

The proofs that we have not shown are left as exercises (sometimes tedious).

Proposition 1.1 shows a property that is very specific to classical logic, namely, that the logical connectives $\Rightarrow, \land, \lor, \neg$ are not independent. For example, we have $P \land Q \equiv \neg(\neg P \lor \neg Q)$, which shows that \land can be expressed in terms of \lor and \neg . Similarly, $P \Rightarrow Q \equiv \neg P \lor Q$ shows that \Rightarrow can be expressed in terms of \lor and \neg .

The next proposition collects a list of equivalences involving conjunction and disjunction that are used all the time. Constructing proofs using the proof templates is not hard but tedious.

Proposition 1.2. The following propositions are provable:

$$P \lor P \equiv P$$
$$P \land P \equiv P$$
$$P \lor Q \equiv Q \lor P$$
$$P \land Q \equiv Q \land P$$

The last two assert the commutativity of \lor and \land . We have distributivity of \land over \lor and of \lor over \land :

$$P \land (Q \lor R) \equiv (P \land Q) \lor (P \land R)$$
$$P \lor (Q \land R) \equiv (P \lor Q) \land (P \lor R).$$

We have associativity of \land and \lor :

$$P \land (Q \land R) \equiv (P \land Q) \land R$$
$$P \lor (Q \lor R) \equiv (P \lor Q) \lor R.$$

1.8 Formal Versus Informal Proofs; Some Examples

In this section, we give some explicit examples of proofs illustrating the proof templates that we just discussed. But first, it should be said that *it is practically impossible to write formal proofs* (i.e., proofs written using the proof templates of the system presented earlier) of "real" statements that are not "toy propositions." This is because it would be extremely tedious and time-consuming to write such proofs, and these proofs would be huge and thus very hard to read.

As we said before, it is possible in principle to write formalized proofs; however, most of us will never do so. So, what *do* we do?

Well, we construct "informal" proofs in which we still make use of the proof templates that we have presented but we take shortcuts and sometimes we even omit proof steps (some proof templates such as 1.9 (And-Elim) and 1.10 (Or-Intro)), and we use a natural language (here, presumably, English) rather than formal symbols (we say "and" for \land , "or" for \lor , etc.). As an example of a shortcut, when using the Proof Template 1.11 (Or-Elim), in most cases, the disjunction $P \lor Q$ has an "obvious proof" because P and Q "exhaust all the cases," in the sense that Q subsumes $\neg P$ (or P subsumes $\neg Q$) and classically, $P \lor \neg P$ is an axiom. Also, we implicitly keep track of the open premises of a proof in our head rather than explicitly delete premises when required. This may be the biggest source of mistakes, and we should make sure that when we have finished a proof, there are no "dangling premises," that is, premises that were never used in constructing the proof. If we are "lucky," some of these premises are in fact unnecessary and we should discard them. Otherwise, this indicates that there is something wrong with our proof, and we should make sure that every premise is indeed used somewhere in the proof or else look for a counterexample.

We urge our readers to read Chapter 3 of Gowers [31], which contains very illuminating remarks about the notion of proof in mathematics.

The next question is then, "How does one write good informal proofs?"

It is very hard to answer such a question because the notion of a "good" proof is quite subjective and partly a social concept. Nevertheless, people have been writing informal proofs for centuries so there are at least many examples of what to do (and what not to do). As with everything else, practicing a sport, playing a music instrument, knowing "good" wines, and so on, *the more you practice, the better you become*. Knowing the theory of swimming is fine, but you have to get wet and do some actual swimming. Similarly, knowing the proof rules is important, but you have to put them to use.

Write proofs as much as you can. Find good proof writers (like good swimmers, good tennis players, etc.), try to figure out why they write clear and easily readable proofs, and try to emulate what they do. Don't follow bad examples (it will take you a little while to "smell" a bad proof style).

Another important point is that nonformalized proofs make heavy use of modus ponens. This is because, when we search for a proof, we rarely (if ever) go back to first principles. This would result in extremely long proofs that would be basically incomprehensible. Instead, we search in our "database" of facts for a proposition of the form $P \Rightarrow Q$ (an auxiliary lemma) that is already known to be proven, and if we are smart enough (lucky enough), we find that we can prove P and thus we deduce Q, the proposition that we really want to prove. Generally, we have to go through several steps involving auxiliary lemmas. This is why it is important to build up a database of proven facts as large as possible about a mathematical field: numbers, trees, graphs, surfaces, and so on. This way, we increase the chance that we will be able to prove some fact about some field of mathematics (by practicing constructing proofs).

And now we return to some explicit examples of informal proofs.

Recall that the set of integers is the set

$$\mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\},\$$

and that the set of natural numbers is the set

$$\mathbb{N} = \{0, 1, 2, \ldots\}.$$

(Some authors exclude 0 from \mathbb{N} . We don't like this discrimination against zero.) The following facts are essentially obvious from the definition of even and odd.

- (a) The sum of even integers is even.
- (b) The sum of an even integer and of an odd integer is odd.
- (c) The sum of two odd integers is even.
- (d) The product of odd integers is odd.
- (e) The product of an even integer with any integer is even.

We will construct deductions using sets of premises consisting of the above propositions. Now we prove the following fact using the proof-by-cases method.

Proposition 1.3. Let a, b, c be odd integers. For any integers p and q, if p and q are not both even, then

$$ap^2 + bpq + cq^2$$

is odd.

Proof. We consider the three cases:

- 1. p and q are odd. In this case, as a, b, and c are odd, by (d), all the products ap^2 , bpq, and cq^2 are odd. By (c), $ap^2 + bpq$ is even and by (b), $ap^2 + bpq + cq^2$ is odd.
- 2. p is even and q is odd. In this case, by (e), both ap^2 and bpq are even and by (d), cq^2 is odd. But then, by (a), $ap^2 + bpq$ is even and by (b), $ap^2 + bpq + cq^2$ is odd.
- 3. p is odd and q is even. This case is analogous to the previous case, except that p and q are interchanged. The reader should have no trouble filling in the details.

All three cases exhaust all possibilities for p and q not to be both even, thus the proof is complete by Proof Template 1.11 applied twice, because there are three cases instead of two.

The set of rational numbers \mathbb{Q} consists of all fractions p/q, where $p, q \in \mathbb{Z}$, with $q \neq 0$. The set of real numbers is denoted by \mathbb{R} . A real number, $a \in \mathbb{R}$, is said to be *irrational* if it cannot be expressed as a number in \mathbb{Q} (a fraction).

We now use Proposition 1.3 and the proof by contradiction method to prove the following.

Proposition 1.4. Let a, b, c be odd integers. Then the equation

$$aX^2 + bX + c = 0$$

has no rational solution X. Equivalently, every zero of the above equation is irrational.

Proof. We proceed by contradiction (by this, we mean that we use the proof-by-contradiction principle). So assume that there is a rational solution X = p/q. We may assume that p and q have no common divisor, which implies that p and q are not both even. As $q \neq 0$, if $aX^2 + bX + c = 0$, then by multiplying by q^2 , we get

$$ap^2 + bpq + cq^2 = 0.$$

However, as p and q are not both even and a, b, c are odd, we know from Proposition 1.3 that $ap^2 + bpq + cq^2$ is odd. This contradicts the fact that $p^2 + bpq + cq^2 = 0$ and thus finishes the proof.

As an example of the proof-by-contrapositive method, we prove that if an integer n^2 is even, then n must be even.

Proof. Observe that if an integer is not even, then it is odd (and vice versa). This fact may seem quite obvious, but to prove it actually requires using *induction* (which we haven't officially met yet). A rigorous proof is given in Section 1.12.

Now the contrapositive of our statement is: if n is odd, then n^2 is odd. But to say that n is odd is to say that n = 2k + 1, and then $n^2 = (2k + 1)^2 = 4k^2 + 4k + 1 = 2(2k^2 + 2k) + 1$, which shows that n^2 is odd.

As another illustration of the proof methods that we have just presented, let us prove that $\sqrt{2}$ is irrational, which means that $\sqrt{2}$ is *not* rational. The reader may also want to look at the proof given by Gowers in Chapter 3 of his book [31]. Obviously, our proof is similar but we emphasize Step (2) a little more.

Because we are trying to prove that $\sqrt{2}$ is not rational, we use Proof Template 1.4. Thus, let us assume that $\sqrt{2}$ is rational and derive a contradiction. Here are the steps of the proof.

- (1) If $\sqrt{2}$ is rational, then there exist some integers $p, q \in \mathbb{Z}$, with $q \neq 0$, so that $\sqrt{2} = p/q$.
- (2) Any fraction p/q is equal to some fraction r/s, where r and s are not both even.
- (3) By (2), we may assume that

$$\sqrt{2} = \frac{p}{q},$$

where $p, q \in \mathbb{Z}$ are not both even and with $q \neq 0$.

(4) By (3), because $q \neq 0$, by multiplying both sides by q, we get

$$q\sqrt{2} = p.$$

(5) By (4), by squaring both sides, we get

$$2q^2 = p^2.$$

- (6) Inasmuch as $p^2 = 2q^2$, the number p^2 must be even. By a fact previously established, p itself is even; that is, p = 2s, for some $s \in \mathbb{Z}$.
- (7) By (6), if we substitute 2s for p in the equation in (5), we get $2q^2 = 4s^2$. By dividing both sides by 2, we get

$$q^2 = 2s^2.$$

- (8) By (7), we see that q^2 is even, from which we deduce (as above) that q itself is even.
- (9) Now, assuming that $\sqrt{2} = p/q$ where p and q are not both even (and $q \neq 0$), we concluded that both p and q are even (as shown in (6) and (8)), reaching a contradiction. Therefore, by negation introduction, we proved that $\sqrt{2}$ is not rational.

A closer examination of the steps of the above proof reveals that the only step that may require further justification is Step (2): that any fraction p/q is equal to some fraction r/s, where r and s are not both even.

This fact does require a proof, and the proof uses the division algorithm, which itself requires induction. Besides this point, all the other steps only require simple arithmetic properties of the integers and are constructive.

Remark: Actually, every fraction p/q is equal to some fraction r/s, where r and s have no common divisor, except 1. This follows from the fact that every pair of integers has a greatest common divisor (a gcd; and r and s are obtained by dividing p and q by their gcd. Using this fact and Euclid's lemma, we can obtain a shorter proof of the irrationality of $\sqrt{2}$. First, we may assume that p and q have no common divisor besides 1 (we say that p and qare relatively prime). From (5), we have

$$2q^2 = p^2$$

so q divides p^2 . However, q and p are relatively prime and as q divides $p^2 = p \times p$, by Euclid's lemma, q divides p. But because 1 is the only common divisor of p and q, we must have q = 1. Now, we get $p^2 = 2$, which is impossible inasmuch as 2 is not a perfect square.

The above argument can be easily adapted to prove that if the positive integer n is not a perfect square, then \sqrt{n} is not rational.

We conclude this section by showing that the proof-by-contradiction principle allows for proofs of propositions that may lack a constructive nature. In particular, it is possible to prove disjunctions $P \lor Q$ which states some alternative that cannot be settled.

For example, consider the question: are there two irrational real numbers a and b, such that a^b is rational? Here is a way to prove that this is indeed the case. Consider the number

 $\sqrt{2}^{\sqrt{2}}$. If this number is rational, then $a = \sqrt{2}$ and $b = \sqrt{2}$ is an answer to our question (because we already know that $\sqrt{2}$ is irrational). Now, observe that

$$(\sqrt{2}^{\sqrt{2}})^{\sqrt{2}} = \sqrt{2}^{\sqrt{2} \times \sqrt{2}} = \sqrt{2}^2 = 2$$
 is rational.

Thus, if $\sqrt{2}^{\sqrt{2}}$ is not rational, then $a = \sqrt{2}^{\sqrt{2}}$ and $b = \sqrt{2}$ is an answer to our question. Because $P \vee \neg P$ is provable using the proof-by-contradiction principle ($\sqrt{2}^{\sqrt{2}}$ is rational or it is not rational), we proved that

 $(\sqrt{2} \text{ is irrational and } \sqrt{2}^{\sqrt{2}} \text{ is rational) or}$ $(\sqrt{2}^{\sqrt{2}} \text{ and } \sqrt{2} \text{ are irrational and } (\sqrt{2}^{\sqrt{2}})^{\sqrt{2}} \text{ is rational).}$

However, the above proof does not tell us whether $\sqrt{2}^{\sqrt{2}}$ is rational!

We see one of the shortcomings of classical reasoning: certain statements (in particular, disjunctive or existential) are provable but their proof does not provide an explicit answer. For this reason, classical logic is considered to be *nonconstructive*.

Remark: Actually, it turns out that another irrational number b can be found so that $\sqrt{2}^{b}$ is rational, and the proof that b is not rational is fairly simple. It also turns out that the exact nature of $\sqrt{2}^{\sqrt{2}}$ (rational or irrational) is known. The answers to these puzzles can be found in Section 1.10.

1.9 Truth Tables and Truth-Value Semantics

So far we have deliberately focused on the construction of proofs using proof templates, but have ignored the notion of truth. We can't postpone any longer a discussion of the truth-value semantics for classical propositional logic.

We all learned early on that the logical connectives \Rightarrow , \land , \lor , \neg and \equiv can be interpreted as Boolean functions, that is, functions whose arguments and whose values range over the set of *truth values*,

$$\mathbf{BOOL} = \{\mathbf{true}, \mathbf{false}\}.$$

P	Q	$P \Rightarrow Q$	$P \wedge Q$	$P \lor Q$	$\neg P$	$P \equiv Q$
true	true	true	true	true	false	true
true	false	false	false	true	false	false
false	true	true	false	true	true	false
false	false	true	false	false	true	true

These functions are given by the following *truth table*.

Note that the implication $P \Rightarrow Q$ is false (has the value **false**) exactly when P =**true** and Q = **false**.

Now any proposition P built up over the set of atomic propositions $\mathbf{PS} = {\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3, \ldots}$ (our propositional symbols) contains a finite set of propositional letters, say

$$\{P_1,\ldots,P_m\}.$$

If we assign some truth value (from **BOOL**) to each symbol P_i , then we can "compute" the *truth value* of P under this assignment by using recursively the truth table above. For example, the proposition $\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$, under the truth assignment v given by

$$\mathbf{P}_1 = \mathbf{true}, \ \mathbf{P}_2 = \mathbf{false}$$

evaluates to false. Indeed, the truth value, $v(\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2))$, is computed recursively as

$$v(\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)) = v(\mathbf{P}_1) \Rightarrow v(\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$$

Now, $v(\mathbf{P}_1) = \mathbf{true}$ and $v(\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$ is computed recursively as

$$v(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) = v(\mathbf{P}_1) \Rightarrow v(\mathbf{P}_2).$$

Because $v(\mathbf{P}_1) = \mathbf{true}$ and $v(\mathbf{P}_2) = \mathbf{false}$, using our truth table, we get

 $v(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) = \mathbf{true} \Rightarrow \mathbf{false} = \mathbf{false}.$

Plugging this into the right-hand side of $v(\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2))$, we finally get

 $v(\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)) = \mathbf{true} \Rightarrow \mathbf{false} = \mathbf{false}.$

However, under the truth assignment v given by

$$\mathbf{P}_1 = \mathbf{true}, \ \mathbf{P}_2 = \mathbf{true},$$

we find that our proposition evaluates to **true**.

The values of a proposition can be determined by creating a *truth table*, in which a proposition is evaluated by computing recursively the truth values of its subexpressions. For example, the truth table corresponding to the proposition $\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$ is

\mathbf{P}_1	\mathbf{P}_2	$\mathbf{P}_1 \Rightarrow \mathbf{P}_2$	$\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$
true	true	true	\mathbf{true}
true	false	false	false
false	true	true	true
false	false	true	true

If we now consider the proposition $P = (\mathbf{P}_1 \Rightarrow (\mathbf{P}_2 \Rightarrow \mathbf{P}_1))$, its truth table is

\mathbf{P}_1	\mathbf{P}_2	$\mathbf{P}_2 \Rightarrow \mathbf{P}_1$	$\mathbf{P}_1 \Rightarrow (\mathbf{P}_2 \Rightarrow \mathbf{P}_1)$
true	true	true	\mathbf{true}
true	false	true	true
false	true	false	true
false	false	true	true

which shows that P evaluates to **true** for all possible truth assignments.

The truth table of a proposition containing m variables has 2^m rows. When m is large, 2^m is very large, and computing the truth table of a proposition P may not be practically feasible. Even the problem of finding whether there is a truth assignment that makes P true is hard. This is actually a very famous problem in computer science.

A proposition P is said to be *valid* or a *tautology* if in the truth table for P all the entries in the column corresponding to P have the value **true**. This means that P evaluates to **true** for all 2^m truth assignments.

What's the relationship between validity and provability? *Remarkably, validity and provability are equivalent.*

In order to prove the above claim, we need to do two things:

- (1) Prove that if a proposition P is provable using the proof templates that we described earlier, then it is valid. This is known as *soundness* or *consistency* (of the proof system).
- (2) Prove that if a proposition P is valid, then it has a proof using the proof templates. This is known as the *completeness* (of the proof system).

In general, it is relatively easy to prove (1) but proving (2) can be quite complicated. In this book, we content ourselves with soundness.

Proposition 1.5. (Soundness of the proof templates) If a proposition P is provable using the proof templates described earlier, then it is valid (according to the truth-value semantics).

Sketch of Proof. It is enough to prove that if there is a deduction of a proposition P from a set of premises Γ , then for every truth assignment for which all the propositions in Γ evaluate to **true**, then P evaluates to **true**. However, this is clear for the axioms, and every proof template preserves that property.

Now, if P is provable, a proof of P has an empty set of premises, and so P evaluates to **true** for all truth assignments, which means that P is valid. \Box

Theorem 1.6. (Completeness) If a proposition P is valid (according to the truth-value semantics), then P is provable using the proof templates.

Proofs of completeness for classical logic can be found in van Dalen [75] or Gallier [24] (but for a different proof system).

Soundness (Proposition 1.5) has a very useful consequence: in order to prove that a proposition P is not provable, it is enough to find a truth assignment for which P evaluates to **false**. We say that such a truth assignment is a *counterexample* for P (or that P can be *falsified*).

For example, no propositional symbol \mathbf{P}_i is provable because it is falsified by the truth assignment $\mathbf{P}_i = \mathbf{false}$.

1.10. PROOF TEMPLATES FOR THE QUANTIFIERS

The soundness of our proof system also has the extremely important consequence that \perp cannot be proven in this system, which means that contradictory statements cannot be derived. This is by no means obvious at first sight, but reassuring.

Note that completeness amounts to the fact that every unprovable proposition has a counterexample. Also, in order to show that a proposition is provable, it suffices to compute its truth table and check that the proposition is valid. This may still be a lot of work, but it is a more "mechanical" process than attempting to find a proof. For example, here is a truth table showing that $(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) \equiv (\neg \mathbf{P}_1 \lor \mathbf{P}_2)$ is valid.

\mathbf{P}_1	\mathbf{P}_2	$\mathbf{P}_1 \Rightarrow \mathbf{P}_2$	$\neg \mathbf{P}_1 \lor \mathbf{P}_2$	$(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) \equiv (\neg \mathbf{P}_1 \lor \mathbf{P}_2)$
true	true	true	true	true
true	false	false	false	true
false	true	true	true	true
false	false	true	true	true

1.10 Proof Templates for the Quantifiers

As we mentioned in Section 1.1, atomic propositions may contain variables. The intention is that such variables correspond to arbitrary objects. An example is

 $human(x) \Rightarrow needs-to-drink(x).$

In mathematics, we usually prove universal statements, that is statements that hold for all possible "objects," or existential statements, that is, statements asserting the existence of some object satisfying a given property. As we saw earlier, we assert that every human needs to drink by writing the proposition

$$\forall x (\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x)).$$

The symbol \forall is called a *universal quantifier*. Observe that once the quantifier \forall (pronounced "for all" or "for every") is applied to the variable x, the variable x becomes a placeholder, and replacing x by y or any other variable *does not change anything*. We say that x is a *bound variable* (sometimes a "dummy variable").

If we want to assert that some human needs to drink, we write

$$\exists x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x)).$$

The symbol \exists is called an *existential quantifier*. Again, once the quantifier \exists (pronounced "there exists") is applied to the variable x, the variable x becomes a placeholder. However, the intended meaning of the second proposition is very different and weaker than the first. It only asserts the existence of some object satisfying the statement

$$human(x) \Rightarrow needs-to-drink(x)$$

Statements may contain variables that are not bound by quantifiers. For example, in

 $\exists x \operatorname{parent}(x, y),$

the variable x is bound but the variable y is not. Here, the intended meaning of parent(x, y) is that x is a parent of y, and the intended meaning of $\exists x \text{ parent}(x, y)$ is that any given y has some parent x. Variables that are not bound are called *free*. The proposition

 $\forall y \exists x \operatorname{parent}(x, y),$

which contains only bound variables is meant to assert that every y has some parent x. Typically, in mathematics, we only prove statements without free variables. However, statements with free variables may occur during intermediate stages of a proof.

Now, in addition to propositions of the form $P \land Q, P \lor Q, P \Rightarrow Q, \neg P, P \equiv Q$, we add two new kinds of propositions (also called formulae):

- 1. Universal formulae, which are formulae of the form $\forall xP$, where P is any formula and x is any variable.
- 2. Existential formulae, which are formulae of the form $\exists x P$, where P is any formula and x is any variable.

The intuitive meaning of the statement $\forall xP$ is that P holds for all possible objects x, and the intuitive meaning of the statement $\exists xP$ is that P holds for some object x. Thus, we see that it would be useful to use symbols to denote various objects. For example, if we want to assert some facts about the "parent" predicate, we may want to introduce some *constant symbols* (for short, constants) such as "Jean," "Mia," and so on and write

parent(Jean, Mia)

to assert that Jean is a parent of Mia. Often, we also have to use *function symbols* (or *operators, constructors*), for instance, to write a statement about numbers: +, *, and so on. Using constant symbols, function symbols, and variables, we can form *terms*, such as

$$(x * x + 1) * (3 * y + 2).$$

In addition to function symbols, we also use *predicate symbols*, which are names for atomic properties. We have already seen several examples of predicate symbols: "odd," "even," "prime," "human," "parent." So in general, when we try to prove properties of certain classes of objects (people, numbers, strings, graphs, and so on), we assume that we have a certain *alphabet* consisting of constant symbols, function symbols, and predicate symbols. By using these symbols and an infinite supply of variables, we can form *terms* and *predicate terms*. We say that we have a (*logical*) *language*. Using this language, we can write compound statements. A detailed presentation of this approach is given in Chapter 2. Here, we follow a more informal and more intuitive approach. We use the notion of term as a synonym for

some specific object. Terms are often denoted by the Greek letter τ , sometimes subscripted. A variable qualifies as a term.

When working with propositions possibly containing quantifiers, it is customary to use the term *formula* instead of proposition. The term proposition is typically reserved to formulae without quantifiers.

Unlike the proof templates for \Rightarrow, \lor, \land , and \bot , which are rather straightforward, the proof templates for quantifiers are more subtle due to the presence of variables (occurring in terms and predicates), and the fact that it is sometimes necessary to make *substitutions*.

Given a formula P containing some free variable x and given a term τ , the result of replacing all occurrences of x by τ in P is called a *substitution* and is denoted $P[\tau/x]$ (and pronounced "the result of substituting τ for x in P"). Substitutions can be defined rigorously by recursion. Let us simply give an example. Consider the predicate P(x) = odd(2x + 1). If we substitute the term $\tau = (y + 1)^2$ for x in P(x), we obtain

$$P[\tau/x] = \text{odd}(2(y+1)^2 + 1).$$

We have to be careful to forbid inferences that would yield "wrong" results, and for this, we have to be very precise about the way we use free variables. More specifically, we have to exercise care when we make *substitutions* of terms for variables in propositions. If $P(t_1, t_2, \ldots, t_n)$ is a statement containing the free variables t_1, \ldots, t_n and if τ_1, \ldots, τ_n are terms, we can form the new statement

$$P[\tau_1/t_1,\ldots,\tau_n/t_n]$$

obtained by substituting the term τ_i for all free occurrences of the variable t_i , for i = 1, ..., n. By the way, we denote terms by the Greek letter τ because we use the letter t for a variable, and using t for both variables and terms would be confusing; sorry.

However, if $P(t_1, t_2, \ldots, t_n)$ contains quantifiers, some bad things can happen; namely, some of the variables occurring in some term τ_i may become quantified when τ_i is substituted for t_i . For example, consider

$$\forall x \exists y P(x, y, z)$$

which contains the free variable z, and substitute the term x + y for z; we get

$$\forall x \exists y P(x, y, x+y).$$

We see that the variables x and y occurring in the term x + y become bound variables after substitution. We say that there is a "capture" of variables.

This is not what we intended to happen. To fix this problem, we recall that bound variables are really placeholders so they can be renamed without changing anything. Therefore, we can rename the bound variables x and y in $\forall x \exists y P(x, y, z)$ to u and v, getting the statement $\forall u \exists v P(u, v, z)$ and now, the result of the substitution is

$$\forall u \exists v P(u, v, x+y),$$

where x and y are free. Again, all this needs to be explained very carefully, but in this chapter, we will content ourselves with an informal treatment.

We begin with the proof templates for the universal quantifier.

Proof Template 1.14. (Forall-Intro)

Let Γ be a list of premises and y be a variable that does not occur free in any premise in Γ or in $\forall xP$. If we have a deduction of the formula P[y/x] from Γ , then we obtain a deduction of $\forall xP$ from Γ .

Proof Template 1.15. (Forall-Elim)

Let Γ be a list of premises and τ be a term representing some specific object. If we have a deduction of $\forall x P$ from Γ , then we obtain a deduction of $P[\tau/x]$ from Γ .

The Proof Template 1.14 may look a little strange, but the idea behind it is actually very simple: because y is totally unconstrained, if P[y/x] (the result of replacing all occurrences of x by y in P) is provable (from Γ), then intuitively, P[y/x] holds for any arbitrary object, and so, the statement $\forall xP$ should also be provable (from Γ).

Note that we can't deduce $\forall x P$ from P[y/x] because the deduction has the single premise P[y/x], and y occurs in P[y/x] (unless x does not occur in P).

The meaning of Proof Template 1.15 is that if $\forall x P$ is provable (from Γ), then P holds for all objects and so, in particular for the object denoted by the term τ ; that is, $P[\tau/x]$ should be provable (from Γ).

Here are the proof templates for the existential quantifier.

Proof Template 1.16. (Exist-Intro)

Let Γ be a list of premises and τ be a term representing some specific object. If we have a deduction of $P[\tau/x]$ from Γ , then we obtain a deduction of $\exists x P(x)$ from Γ .

Proof Template 1.17. (Exist-Elim)

Let Γ and Δ be a two lists of premises. Let C and $\exists xP$ be formulae, and y be a variable that does not occur free in any premise in Δ , in $\exists xP$, or in C. To obtain a deduction of C from Γ, Δ , proceed as follows:

- 1. Make a deduction of $\exists x P$ from Γ .
- 2. Add one or more occurrences of P[y/x] as premises to Δ and find a deduction of C from P[y/x] and Δ .
- 3. Delete the premise P[y/x].

If $P[\tau/x]$ is provable (from Γ), this means that the object denoted by τ satisfies P, so $\exists xP$ should be provable (this latter formula asserts the existence of some object satisfying P, and τ is such an object).

Proof Template 1.17 is reminiscent of the proof-by-cases principle (Proof template 1.11) and is a little more tricky. It goes as follows. Suppose that we proved $\exists xP$ (from Γ). Moreover, suppose that for every possible case P[y/x] we were able to prove C (from Δ). Then, as we have "exhausted" all possible cases and as we know from the provability of $\exists xP$ that some case must hold, we can conclude that C is provable (from Γ, Δ) without using P[y/x] as a premise.

Like the proof-by-cases principle, Proof Template 1.17 is not very constructive. It allows making a conclusion C by considering alternatives without knowing which one actually occurs.

Constructing proofs using the proof templates for the quantifiers can be quite tricky due to the restrictions on variables. In practice, we always use "fresh" (brand new) variables to avoid problems. Also, when we use Proof Template 1.14, we begin by saying "let y be arbitrary," then we prove P[y/x] (mentally substituting y for x), and we conclude with: "since y is arbitrary, this proves $\forall xP$." We proceed in a similar way when using Proof Template 1.17, but this time we say "let y be arbitrary" in Step (2). When we use Proof Template 1.15, we usually say: "since $\forall xP$ holds, it holds for all x, so in particular it holds for τ , and thus $P[\tau/x]$ holds." Similarly, when using Proof Template 1.16, we say "Since $P[\tau/x]$ holds for a specific object τ , we can deduce that $\exists xP$ holds."

Here is an example of a "wrong proof" in which the \forall -introduction rule is applied illegally, and thus, yields a statement that is actually false (not provable). In the incorrect "proof" below, P is an atomic predicate symbol taking two arguments (e.g., "parent"), and 0 is a constant denoting zero:

$$\frac{\begin{array}{c} P(u,0)^{x} \\ \hline \forall tP(t,0) \end{array}}{P(u,0) \Rightarrow \forall tP(t,0)} \quad \begin{array}{c} \text{Implication-Intro } x \\ \hline P(u,0) \Rightarrow \forall tP(t,0) \end{array}$$

$$\overline{\begin{array}{c} \forall s(P(s,0) \Rightarrow \forall tP(t,0)) \\ \hline P(0,0) \Rightarrow \forall tP(t,0) \end{array}} \quad \begin{array}{c} \text{Forall-Intro} \\ \hline \text{Forall-Elim} \end{array}$$

The problem is that the variable u occurs free in the premise P[u/t, 0] = P(u, 0) and therefore, the application of the \forall -introduction rule in the first step is illegal. However, note that this premise is discharged in the second step, and so the application of the \forall introduction rule in the third step is legal. The (false) conclusion of this faulty proof is that $P(0,0) \Rightarrow \forall tP(t,0)$ is provable. Indeed, there are plenty of properties such that the fact that the single instance P(0,0) holds does not imply that P(t,0) holds for all t.

Let us now give two examples of a proof using the proof templates for \forall and \exists .

Example 1.23. For any natural number n, let odd(n) be the predicate that asserts that n is odd, namely

$$odd(n) \equiv \exists m((m \in \mathbb{N}) \land (n = 2m + 1))$$

First, let us prove that

$$\forall a ((a \in \mathbb{N}) \Rightarrow \text{odd}(2a+1)).$$

By Proof Template 1.14, let x be a fresh variable; we need to prove

$$(x \in \mathbb{N}) \Rightarrow \text{odd}(2x+1).$$

By Proof Template 1.2, assume $x \in \mathbb{N}$. If we consider the formula

$$(m \in \mathbb{N}) \land (2x+1 = 2m+1),$$

by substituting x for m, we get

$$(x \in \mathbb{N}) \land (2x+1 = 2x+1),$$

which is provable since $x \in \mathbb{N}$. By Proof Template 1.16, we obtain

$$\exists m (m \in \mathbb{N}) \land (2x+1 = 2m+1);$$

that is, odd(2x + 1) is provable. Using Proof Template 1.2, we delete the premise $x \in \mathbb{N}$, and we have proven

$$(x \in \mathbb{N}) \Rightarrow \text{odd}(2x+1).$$

This proof no longer has any premises, so we can safely conclude that

$$\forall a ((a \in \mathbb{N}) \Rightarrow \text{odd}(2a+1)).$$

Next, consider the term $\tau = 7$. By Proof Template 1.15, we obtain

$$(7 \in \mathbb{N}) \Rightarrow \text{odd}(15).$$

Since $7 \in \mathbb{N}$, by modus ponens we deduce that 15 is odd.

Let us now consider the term $\tau = (b+1)^2$ with $b \in \mathbb{N}$. By Proof Template 1.15, we obtain

$$((b+1)^2 \in \mathbb{N}) \Rightarrow \text{odd}(2(b+1)^2 + 1).$$

But $b \in \mathbb{N}$ implies that $(b+1)^2 \in \mathbb{N}$, so by modus ponens and Proof Template 1.2, we deduce that

$$(b \in \mathbb{N}) \Rightarrow \text{odd}(2(b+1)^2 + 1).$$

Example 1.24. Let us prove the formula $\forall x(P \land Q) \Rightarrow \forall xP \land \forall xQ$.

First using Proof Template 1.2, we assume $\forall x (P \land Q)$ (two copies). The next step uses a trick. Since variables are terms, if u is a fresh variable, then by Proof Template 1.15, we deduce $(P \land Q)[u/x]$. Now we use a property of substitutions which says that

$$(P \land Q)[u/x] = P[u/x] \land Q[u/x].$$

We can now use Proof Template 1.9 (twice) to deduce P[u/x] and Q[u/x]. But remember that the premise is $\forall x(P \land Q)$ (two copies), and since u is a fresh variable, it does not occur in this premise, so we can safely apply Proof Template 1.14 and conclude $\forall xP$, and similarly $\forall xQ$. By Proof Template 1.8, we deduce $\forall xP \land \forall xQ$ from $\forall x(P \land Q)$. Finally, by Proof Template 1.2, we delete the premise $\forall x(P \land Q)$ and obtain our proof. The above proof has the following tree representation.

$\forall x (P \land Q)^{x \checkmark}$	$\forall x (P \land Q)^{x \checkmark}$		
$\overline{P[u/x] \wedge Q[u/x]}$	$\overline{P[u/x] \wedge Q[u/x]}$		
P[u/x]	Q[u/x]		
$\forall xP$	$\forall xQ$		
$\forall x P \land \forall x Q$			
$\overline{\forall x(P \land Q) \Rightarrow \forall xP \land \forall xQ}$			

The reader should show that $\forall x P \land \forall x Q \Rightarrow \forall x (P \land Q)$ is also provable.

However, in general, one can't just replace \forall by \exists (or \land by \lor) and still obtain provable statements. For example, $\exists x P \land \exists x Q \Rightarrow \exists x (P \land Q)$ is not provable at all.

Here are some useful equivalences involving quantifiers. The first two are analogous to the de Morgan laws for \wedge and \vee .

Proposition 1.7. The following formulae are provable:

$$\neg \forall xP \equiv \exists x \neg P$$
$$\neg \exists xP \equiv \forall x \neg P$$
$$\forall x(P \land Q) \equiv \forall xP \land \forall xQ$$
$$\exists x(P \lor Q) \equiv \exists xP \lor \exists xQ$$
$$\exists x(P \land Q) \Rightarrow \exists xP \land \exists xQ$$
$$\forall xP \lor \forall xQ \Rightarrow \forall x(P \lor Q).$$

The proof system that uses all the proof templates that we have defined proves formulae of *classical first-order logic*.

One should also be careful that the order of the quantifiers is important. For example, a formula of the form

 $\forall x \exists y P$

is generally not equivalent to the formula

 $\exists y \forall x P.$

The second formula asserts the existence of some object y, such that P holds for all x. But in the first formula, for every x, there is some y, such that P holds, but each y depends on x and there may not be a single y that works for all x. Another amusing mistake involves negating a universal quantifier. The formula $\forall x \neg P$ is not equivalent to $\neg \forall x P$. Once, traveling from Philadelphia to New York, I heard a train conductor say, "All doors will not open." Actually, he meant "not all doors will open," which would give us a chance to get out!

Remark: We can illustrate, again, the fact that classical logic allows for nonconstructive proofs by re-examining the example at the end of Section 1.8. There, we proved that if $\sqrt{2}^{\sqrt{2}}$ is rational, then $a = \sqrt{2}$ and $b = \sqrt{2}$ are both irrational numbers, such that a^b is rational, and if $\sqrt{2}^{\sqrt{2}}$ is irrational, then $a = \sqrt{2}^{\sqrt{2}}$ and $b = \sqrt{2}$ are both irrational numbers, such that a^b is rational, then $a = \sqrt{2}^{\sqrt{2}}$ and $b = \sqrt{2}$ are both irrational numbers, such that a^b is rational. By Proof Template 1.16, we deduce that if $\sqrt{2}^{\sqrt{2}}$ is rational, then there exist some irrational numbers a, b so that a^b is rational, and if $\sqrt{2}^{\sqrt{2}}$ is irrational, then there exist some irrational numbers a, b so that a^b is rational. In classical logic, as $P \vee \neg P$ is provable, by the proof-by-cases principle, we just proved that there exist some irrational numbers a and b so that a^b is rational.

However, this argument does not give us explicitly numbers a and b with the required properties. It only tells us that such numbers must exist.

Now, it turns out that $\sqrt{2}^{\sqrt{2}}$ is indeed irrational (this follows from the Gelfond-Schneider theorem, a hard theorem in number theory). Furthermore, there are also simpler explicit solutions, such as $a = \sqrt{2}$ and $b = \log_2 9$, as the reader should check.

1.11 Sets and Set Operations

In this section, we review the definition of a set and basic set operations. This section takes the "naive" point of view that a set is an unordered collection of objects, without duplicates, the collection being regarded as a single object.

Given a set A, we write that some object a is an element of (belongs to) the set A as

 $a \in A$,

and that a is not an element of A (does not belong to A) as

```
a \notin A.
```

The symbol \in is the *set membership* symbol.

A set can either be defined explicitly by listing its elements within curly braces (the symbols $\{ \text{ and } \}$) or as a collection of objects satisfying a certain property. For example, the set C consisting of the colors red, blue, green is given by

$$C = \{ \text{red}, \text{blue}, \text{green} \}.$$

Because the order of elements in a set is irrelevant, the set C is also given by

$$C = \{\text{green}, \text{red}, \text{blue}\}.$$

In fact, a moment of reflexion reveals that there are six ways of writing the set C.

If we denote by \mathbb{N} the set of natural numbers

$$\mathbb{N} = \{0, 1, 2, 3, \ldots\}$$

then the set E of even integers can be defined in terms of the property even of being even by

$$E = \{ n \in \mathbb{N} \mid \operatorname{even}(n) \}.$$

More generally, given some property P and some set X, we denote the set of all elements of X that satisfy the property P by

$$\{x \in X \mid P(x)\} \quad \text{or} \quad \{x \mid x \in X \land P(x)\}.$$

When are two sets A and B equal? The answer is given by the first proof template of set theory, called the Extensionality Axiom.

Proof Template 1.18. (Extensionality Axiom)

Two sets A and B are equal iff they have exactly the same elements; that is, every element of A is an element of B and conversely. This can be written more formally as

$$\forall x (x \in A \Rightarrow x \in B) \land \forall x (x \in B \Rightarrow x \in A).$$

There is a special set having no elements at all, the *empty set*, denoted \emptyset . The empty set is characterized by the property

$$\forall x (x \notin \emptyset)$$

Next, we define the notion of inclusion between sets.

Definition 1.5. Given any two sets, A and B, we say that A is a subset of B (or that A is included in B), denoted $A \subseteq B$, iff every element of A is also an element of B, that is,

$$\forall x (x \in A \Rightarrow x \in B).$$

We say that A is a proper subset of B iff $A \subseteq B$ and $A \neq B$. This implies that there is some $b \in B$ with $b \notin A$. We usually write $A \subset B$.

For example, if $A = \{\text{green}, \text{blue}\}$ and $C = \{\text{green}, \text{red}, \text{blue}\}$, then

$$A \subseteq C.$$

Note that the empty set is a subset of every set.

Observe the important fact that equality of two sets can be expressed by

$$A = B$$
 iff $A \subseteq B$ and $B \subseteq A$.

Proving that two sets are equal may be quite complicated if the definitions of these sets are complex, and the above method is the safe one.

If a set A has a finite number of elements, then this number (a natural number) is called the *cardinality* of the set and is denoted by |A| (sometimes by card(A)). Otherwise, the set is said to be *infinite*. The cardinality of the empty set is 0.

Sets can be combined in various ways, just as numbers can be added, multiplied, *etc.* However, operations on sets tend to mimic logical operations such as disjunction, conjunction, and negation, rather than the arithmetical operations on numbers. The most basic operations are union, intersection, and relative complement.

Definition 1.6. For any two sets A and B, the union of A and B is the set $A \cup B$ defined such that

$$x \in A \cup B$$
 iff $(x \in A) \lor (x \in B)$.

This reads x is a member of $A \cup B$ if either x belongs to A or x belongs to B (or both). We also write

$$A \cup B = \{ x \mid x \in A \quad \text{or} \quad x \in B \}$$

The *intersection of* A and B is the set $A \cap B$ defined such that

$$x \in A \cap B$$
 iff $(x \in A) \land (x \in B)$.

This reads x is a member of $A \cap B$ if x belongs to A and x belongs to B. We also write

$$A \cap B = \{ x \mid x \in A \quad \text{and} \quad x \in B \}.$$

The relative complement (or set difference) of A and B is the set A - B defined such that

 $x \in A - B$ iff $(x \in A) \land \neg (x \in B)$.

This reads x is a member of A - B if x belongs to A and x does not belong to B. We also write

$$A - B = \{ x \mid x \in A \text{ and } x \notin B \}.$$

Example 1.25. For example, if $A = \{0, 2, 4, 6\}$ and $B = \{0, 1, 3, 5\}$, then

$$A \cup B = \{0, 1, 2, 3, 4, 5, 6\}$$
$$A \cap B = \{0\}$$
$$A - B = \{2, 4, 6\}.$$

Two sets A, B are said to be *disjoint* if $A \cap B = \emptyset$. It is easy to see that if A and B are two finite sets and if A and B are disjoint, then

$$|A \cup B| = |A| + |B|.$$

In general, by writing

$$A \cup B = (A \cap B) \cup (A - B) \cup (B - A),$$

if A and B are finite, it can be shown that

$$|A \cup B| = |A| + |B| - |A \cap B|.$$

The situation in which we manipulate subsets of some fixed set X often arises, and it is useful to introduce a special type of relative complement with respect to X. For any subset A of X, the *complement* \overline{A} of A in X is defined by

$$\overline{A} = X - A,$$

which can also be expressed as

$$\overline{A} = \{ x \in X \mid x \notin A \}.$$

Venn diagrams provide a convenient way to illustrate set relationships and set operations. Venn diagrams use circles and their areas, i.e. disks, to denote individual sets. Overlaps between different disks to illustrate set relationships. Individual elements of the set, if depicted, are represented by words, numbers, or symbols inside the circle. For example, the sets $C = \{\text{green, red, blue}\}$ and $A = \{\text{green, blue}\}$ are depicted as two disks, and the fact that $A \subseteq C$ is depicted by the disk representing A nested inside the disk representing C; see Figure 1.1.



Figure 1.1: The set $C = \{\text{green, red, blue}\}$ is the larger disk, while the set $A = \{\text{green, blue}\}$ is the smaller disk. The fact that $A \subseteq C$ is illustrated by nesting A inside of C.

Venn diagrams can also be used to illustrate union, intersection, and relative complement. Since sets A and B are represented by disks, if A and B have any elements in common, the two disks must overlap to form a "figure eight." The union $A \cup B$ is the area of entire figure eight, while the intersection $A \cap B$ is "crescent" shaped area determined by the overlap of the two disks. The relative complement A - B is the area given by removing the crescentshaped $A \cap B$ from the disk which depicts A, while the relative complement B - A is the



Figure 1.2: Let $A = \{0, 2, 4, 6\}$ and $B = \{0, 1, 3, 5\}$. The union $A \cup B$ is the entire colored area, the intersection $A \cap B$ is the light purple crescent, the relative complement A - B is the bright blue area, while the relative complement B - A is the pink area.

area given by removing the crescent-shaped $A \cap B$ from the disk which depicts B. All of this is illustrated in Figure 1.2 for the sets $A = \{0, 2, 4, 6\}$ and $B = \{0, 1, 3, 5\}$.

Note that if the sets A and B are disjoint, the union $A \cup B$ is represented by the area of two distinct disks. Technically, such a diagram is called an Euler diagram since a Venn diagram of $A \cup B$ must always contain a region or area (in this case empty) which represents $A \cap B$. But for ease of exposition, we will refer to all disk diagram representations of sets and set operations as Venn diagrams. Regardless of whether A and B are distinct, we can readily depict the fact that

$$A \cup B = (A \cap B) \cup (A - B) \cup (B - A)$$

via a Venn diagram as seen in Figure 1.3.



Figure 1.3: The Venn diagram representation of the identity $A \cup B = (A \cap B) \cup (A - B) \cup (B - A)$.

We also can use Venn diagrams to depict \overline{A} , where $A \subseteq X$. Since the disk for A is nested

inside the disk for X, we represent \overline{A} as the area inside the disk for X, which is outside of the disk representing A; see Figure 1.4.



Figure 1.4: Let X be the blue disk and A be the red disk. Note that $A \subseteq X$. Then \overline{A} is blue area outside of the red disk. Clearly, $X = A \cup \overline{A}$.

Venn diagrams can also be used to represent three or more sets, where each set is represented by its own disk. In Figure 1.5, we show a Venn diagram for three sets A, B, and C. However, for n sets such a diagram must contain $2^n - 1$ regions representing all possible set intersections. Hence, when $n \ge 5$, Venn diagrams become unwieldy. We leave it as an exercise for the reader to use Venn diagrams to illustrate the identities of Proposition 1.8.



Figure 1.5: A Venn diagram representation for sets A, B, and C, where A is a blue disk, B is a pink disk, and C is a peach disk. The middle "triangular" region formed by the overlap of all three disks represents $A \cap B \cap C$.

Using the union operation, we can form bigger sets by taking unions with singletons. For example, we can form

$$\{a, b, c\} = \{a, b\} \cup \{c\}.$$

Remark: We can systematically construct bigger and bigger sets by the following method: given any set A, let

$$A^+ = A \cup \{A\}.$$

If we start from the empty set, we obtain the sets

$$\emptyset, \{\emptyset\}, \{\emptyset, \{\emptyset\}\}, \{\emptyset, \{\emptyset\}, \{\emptyset, \{\emptyset\}\}\}, etc.$$

These sets can be used to define the natural numbers, and the + operation corresponds to the successor function on the natural numbers (i.e., $n \mapsto n+1$).

The algebraic properties of union, intersection, and complementation are inherited from the properties of disjunction, conjunction, and negation. The following proposition lists some of the most important properties of union, intersection, and complementation. Some of these properties are versions of Proposition 1.2 for subsets.

Proposition 1.8. The following equations hold for all sets A, B, C:

$$A \cup \emptyset = A$$
$$A \cap \emptyset = \emptyset$$
$$A \cup A = A$$
$$A \cap A = A$$
$$A \cup B = B \cup A$$
$$A \cap B = B \cap A.$$

The last two assert the commutativity of \cup and \cap . We have distributivity of \cap over \cup and of \cup over \cap :

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$
$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C).$$

We have associativity of \cap and \cup :

$$A \cap (B \cap C) = (A \cap B) \cap C$$
$$A \cup (B \cup C) = (A \cup B) \cup C.$$

Proof. We use Proposition 1.2. Let us prove that $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$, leaving the proof of the other equations as an exercise. We prove the two inclusions $A \cap (B \cup C) \subseteq (A \cap B) \cup (A \cap C)$ and $(A \cap B) \cup (A \cap C) \subseteq A \cap (B \cup C)$.

Assume that $x \in A \cap (B \cup C)$. This means that $x \in A$ and $x \in B \cup C$; that is

$$(x \in A) \land ((x \in B) \lor (x \in C)).$$

Using the distributivity of \wedge over \vee , we obtain

$$((x \in A) \land (x \in B)) \lor ((x \in A) \land (x \in C)).$$

But the above says that $x \in (A \cap B) \cup (A \cap C)$, which proves our first inclusion.

Conversely, assume that $x \in (A \cap B) \cup (A \cap C)$. This means that $x \in (A \cap B)$ or $x \in (A \cap C)$; that is

$$((x \in A) \land (x \in B)) \lor ((x \in A) \land (x \in C)).$$

Using the distributivity of \land over \lor (in the other direction), we obtain

$$(x \in A) \land ((x \in B) \lor (x \in C)),$$

which says that $x \in A \cap (B \cup C)$, and proves our second inclusion.

Note that we could have avoided two arguments by proving that $x \in A \cap (B \cup C)$ iff $(A \cap B) \cup (A \cap C)$, using the fact that the distributivity of \wedge over \vee is a logical equivalence. \Box

We also have the following version of Proposition 1.1 for subsets.

Proposition 1.9. For every set X and any two subsets A, B of X, the following identities hold:

$$\overline{\overline{A}} = A$$
$$\overline{(A \cap B)} = \overline{A} \cup \overline{B}$$
$$\overline{(A \cup B)} = \overline{A} \cap \overline{B}$$

The last two are de Morgan laws.

Another operation is the power set formation. It is indeed a "powerful" operation, in the sense that it allows us to form very big sets.

Definition 1.7. Given any set A, there is a set $\mathcal{P}(A)$, also denoted 2^A , called the *power set* of A, whose members are exactly the subsets of A; that is

$$X \in \mathcal{P}(A) \quad \text{iff} \quad X \subseteq A$$

For example, if $A = \{a, b, c\}$, then

$$\mathcal{P}(A) = \{ \emptyset, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\} \},\$$

a set containing eight elements. Note that the empty set and A itself are always members of $\mathcal{P}(A)$.

Remark: If A has n elements, it is not hard to show that $\mathcal{P}(A)$ has 2^n elements. For this reason, many people, including us, prefer the notation 2^A for the power set of A.

It is possible to define the union of possibly infinitely many sets. Given any set X (think of X as a set of sets), there is a set $\bigcup X$ defined so that

$$x \in \bigcup X$$
 iff $\exists B (B \in X \land x \in B).$

This says that $\bigcup X$ consists of all elements that belong to some member of X.

If we take $X = \{A, B\}$, where A and B are two sets, we see that

$$\bigcup \{A, B\} = A \cup B.$$

Observe that

$$\bigcup \{A\} = A, \quad \bigcup \{A_1, \dots, A_n\} = A_1 \cup \dots \cup A_n,$$

and in particular, $\bigcup \emptyset = \emptyset$.

We can also define infinite intersections. For every nonempty set X there is a set $\bigcap X$ defined by

$$x \in \bigcap X$$
 iff $\forall B(B \in X \Rightarrow x \in B).$

Observe that

$$\bigcap \{A, B\} = A \cap B, \quad \bigcap \{A_1, \dots, A_n\} = A_1 \cap \dots \cap A_n.$$

However, $\bigcap \emptyset$ is undefined. Indeed, $\bigcap \emptyset$ would have to be the set of all sets, since the condition

$$\forall B(B \in \emptyset \Rightarrow x \in B)$$

holds trivially for all B (as the empty set has no members). However, there is no such set because its existence would lead to a paradox! This point is discussed is Chapter 2. Let us simply say that dealing with big infinite sets is tricky.

Thorough and yet accessible presentations of set theory can be found in Halmos [33] and Enderton [15].

We close this chapter with a quick discussion of induction on the natural numbers.

1.12 Induction and the Well-Ordering Principle on the Natural Numbers

Recall that the set of natural numbers is the set \mathbb{N} given by

$$\mathbb{N} = \{0, 1, 2, 3, \ldots\}.$$

In this chapter, we do not attempt to define the natural numbers from other concepts, such as sets. We assume that they are "God given." One of our main goals is to prove properties of the natural numbers. For this, certain subsets called inductive play a crucial role.

Definition 1.8. We say that a subset S of \mathbb{N} is *inductive* iff

- (1) $0 \in S$.
- (2) For every $n \in S$, we have $n + 1 \in S$.

One of the most important proof principles for the natural numbers is the following:

Proof Template 1.19. (Induction Principle for \mathbb{N})

Every inductive subset S of \mathbb{N} is equal to \mathbb{N} itself; that is $S = \mathbb{N}$.

Let us give one example illustrating Proof Template 1.19. Many more examples are given in Chapter 13.3.

Example 1.26. We prove that for every real number $a \neq 1$ and every natural number n, we have

$$1 + a + \dots + a^n = \frac{a^{n+1} - 1}{a - 1}$$

This can also be written as

$$\sum_{i=0}^{n} a^{i} = \frac{a^{n+1} - 1}{a - 1},\tag{(*)}$$

with the convention that $a^0 = 1$, even if a = 0.

Proof. Let S be the set of natural numbers n for which the identity (*) holds, and let us prove that S is inductive.

First, we need to prove that $0 \in S$. The left-hand side becomes $a^0 = 1$, and the righthand side is (a-1)/(a-1), which is equal to 1 since we assume that $a \neq 1$. Therefore, (*) holds for n = 0; that is, $0 \in S$.

Next, assume that $n \in S$ (this is called the *induction hypothesis*). We need to prove that $n + 1 \in S$. Observe that

$$\sum_{i=0}^{n+1} a^i = \sum_{i=0}^n a^i + a^{n+1}$$

Now, since we assumed that $n \in S$, we have

$$\sum_{i=0}^{n} a^{i} = \frac{a^{n+1} - 1}{a - 1},$$

and we deduce that

$$\sum_{i=0}^{n+1} a^{i} = \sum_{i=0}^{n} a^{i} + a^{n+1}$$
$$= \frac{a^{n+1} - 1}{a - 1} + a^{n+1}$$
$$= \frac{a^{n+1} - 1 + a^{n+2} - a^{n+1}}{a - 1}$$
$$= \frac{a^{n+2} - 1}{a - 1}.$$

This proves that $n + 1 \in S$. Therefore, S is inductive, and so $S = \mathbb{N}$.

We show how to rephrase this induction principle a little more conveniently using the notion of function in Chapter 13.3.

Another important property of \mathbb{N} is the so-called *well-ordering principle*. This principle turns out to be equivalent to the induction principle for \mathbb{N} . In this chapter, we accept the well-ordering principle without proof.

Proof Template 1.20. (Well-Ordering Principle for \mathbb{N})

Every nonempty subset of \mathbb{N} has a smallest element.

Proof Template 1.20 can be used to prove properties of \mathbb{N} by contradiction. For example, consider the property that every natural number n is either even or odd.

Proof. For the sake of contradiction (here, we use the proof-by-contradiction principle), assume that our statement does not hold. If so, the subset S of natural numbers n for which n is neither even nor odd is nonempty. By the well-ordering principle, the set S has a smallest element, say m.

If m = 0, then 0 would be neither even nor odd, a contradiction since 0 is even. Therefore, m > 0. But then, $m - 1 \notin S$, since m is the smallest element of S. This means that m - 1is either even or odd. But if m - 1 is even, then m - 1 = 2k for some k, so m = 2k + 1 is odd, and if m - 1 is odd, then m - 1 = 2k + 1 for some k, so m = 2(k + 1) is even. We just proved that m is either even or odd, contradicting the fact that $m \in S$. Therefore, S must be empty and we proved the desired result. \Box

We conclude this section with one more example showing the usefulness of the wellordering principle.

Example 1.27. Suppose we have a property P(n) of the natural numbers such that P(n) holds for at least some n, and that for every n such that P(n) holds and $n \ge 100$, then there is some m < n such that P(m) holds. We claim that there is some m < 100 such that P(m) holds.

Proof. Let S be the set of natural numbers n such that P(n) holds. By hypothesis, there is some n such that P(n) holds, so S is nonempty. By the well-ordering principle, the set S has a smallest element, say m. For the sake of contradiction, assume that $m \ge 100$. Then since P(m) holds and $m \ge 100$, by the hypothesis there is some m' < m such that P(m') holds, contradicting the fact that m is the smallest element of S. Therefore, by the proof-by-contradiction principle, we conclude that m < 100, as claimed.

Beware that the well-ordering principle is false for \mathbb{Z} because \mathbb{Z} does not have a smallest element.

1.13 Summary

The main goal of this chapter is to describe how to construct proofs in terms of *proof* templates. A brief and informal introduction to sets and set operations is also provided.

- We describe the syntax of *propositions*.
- We define the proof templates for *implication*.
- We show that *deductions* proceed from *assumptions* (or *premises*) according to *proof templates*.
- We introduce falsity \perp and negation $\neg P$ as an abbreviation for $P \Rightarrow \perp$. We describe the proof templates for conjunction, disjunction, and negation.
- We show that one of the rules for negation is the *proof-by-contradiction* rule (also known as RAA). It plays a special role, in the sense that it allows for the construction of indirect proofs.
- We present the *proof-by-contrapositive rule*.
- We present the *de Morgan laws* as well as some basic properties of \lor and \land .
- We give some examples of proofs of "real" statements.
- We give an example of a nonconstructive proof of the statement: there are two irrational numbers, a and b, such that a^b is rational.
- We explain the *truth-value semantics* of propositional logic.
- We define the *truth tables* for the boolean functions associated with the logical connectives (and, or, not, implication, equivalence).
- We define the notion of *validity* and *tautology*.
- We discuss *soundness* (or *consistency*) and *completeness*.
- We state the *soundness and completeness theorems* for propositional classical logic.
- We explain how to use *counterexamples* to prove that certain propositions are not provable.
- We add *first-order quantifiers* ("for all" \forall and "there exists" \exists) to the language of propositional logic and define *first-order logic*.
- We describe *free* and *bound* variables.
- We describe proof templates for the quantifiers.

- We prove some "de Morgan"-type rules for the quantified formulae.
- We introduce *sets* and explain when two sets are equal.
- We define the notion of *subset*.
- We define some basic operations on sets: the union $A \cup B$, intersection $A \cap B$, and relative complement A B.
- We define the *complement* of a subset of a given set.
- We prove some basic properties of union, intersection and complementation, including the *de Morgan laws*.
- We define the *power set* of a set.
- We define *inductive subsets* of \mathbb{N} and state the *induction principle for* \mathbb{N} .
- We state the well-ordering principle for \mathbb{N} .

1.14 Problems

Problem 1.1. Give a proof of the proposition $(P \Rightarrow Q) \Rightarrow ((P \Rightarrow (Q \Rightarrow R)) \Rightarrow (P \Rightarrow R))$.

Problem 1.2. (a) Prove the "de Morgan" laws:

$$\neg (P \land Q) \equiv \neg P \lor \neg Q$$
$$\neg (P \lor Q) \equiv \neg P \land \neg Q.$$

(b) Prove the propositions $(P \land \neg Q) \Rightarrow \neg (P \Rightarrow Q)$ and $\neg (P \Rightarrow Q) \Rightarrow (P \land \neg Q)$.

Problem 1.3. (a) Prove the equivalences

$$P \lor P \equiv P$$
$$P \land P \equiv P$$
$$P \lor Q \equiv Q \lor P$$
$$P \land Q \equiv Q \land P.$$

(b) Prove the equivalences

$$P \land (P \lor Q) \equiv P$$
$$P \lor (P \land Q) \equiv P.$$

Problem 1.4. Prove the propositions

$$\begin{split} P &\Rightarrow (Q \Rightarrow (P \land Q)) \\ (P \Rightarrow Q) \Rightarrow ((P \Rightarrow \neg Q) \Rightarrow \neg P) \\ (P \Rightarrow R) \Rightarrow ((Q \Rightarrow R) \Rightarrow ((P \lor Q) \Rightarrow R)) \end{split}$$

Problem 1.5. Prove the following equivalences:

$$P \land (P \Rightarrow Q) \equiv P \land Q$$

$$Q \land (P \Rightarrow Q) \equiv Q$$

$$(P \Rightarrow (Q \land R)) \equiv ((P \Rightarrow Q) \land (P \Rightarrow R)).$$

Problem 1.6. Prove the propositions

$$(P \Rightarrow Q) \Rightarrow \neg \neg (\neg P \lor Q)$$
$$\neg \neg (\neg \neg P \Rightarrow P).$$

Problem 1.7. Prove the proposition $\neg \neg (P \lor \neg P)$.

Problem 1.8. Prove the propositions

$$(P \lor \neg P) \Rightarrow (\neg \neg P \Rightarrow P) \quad \text{and} \quad (\neg \neg P \Rightarrow P) \Rightarrow (P \lor \neg P).$$

Problem 1.9. Prove the propositions

$$(P \Rightarrow Q) \Rightarrow \neg \neg (\neg P \lor Q) \text{ and } (\neg P \Rightarrow Q) \Rightarrow \neg \neg (P \lor Q).$$

Problem 1.10. (a) Prove the distributivity of \land over \lor and of \lor over \land :

$$P \land (Q \lor R) \equiv (P \land Q) \lor (P \land R)$$
$$P \lor (Q \land R) \equiv (P \lor Q) \land (P \lor R).$$

(b) Prove the associativity of \land and \lor :

$$P \land (Q \land R) \equiv (P \land Q) \land R$$
$$P \lor (Q \lor R) \equiv (P \lor Q) \lor R.$$

Problem 1.11. (a) Let $X = \{X_i \mid 1 \leq i \leq n\}$ be a finite family of sets. Prove that if $X_{i+1} \subseteq X_i$ for all i, with $1 \leq i \leq n-1$, then

$$\bigcap X = X_n$$

Prove that if $X_i \subseteq X_{i+1}$ for all i, with $1 \le i \le n-1$, then

$$\bigcup X = X_n.$$

(b) Recall that $\mathbb{N}_+ = \mathbb{N} - \{0\} = \{1, 2, 3, \dots, n, \dots\}$. Give an example of an infinite family of sets, $X = \{X_i \mid i \in \mathbb{N}_+\}$, such that

- 1. $X_{i+1} \subseteq X_i$ for all $i \ge 1$.
- 2. X_i is infinite for every $i \ge 1$.
- 3. $\bigcap X$ has a single element.

(c) Give an example of an infinite family of sets, $X = \{X_i \mid i \in \mathbb{N}_+\}$, such that

- 1. $X_{i+1} \subseteq X_i$ for all $i \ge 1$.
- 2. X_i is infinite for every $i \ge 1$.
- 3. $\bigcap X = \emptyset$.

Problem 1.12. An integer, $n \in \mathbb{Z}$, is divisible by 3 iff n = 3k, for some $k \in \mathbb{Z}$. Thus (by the division theorem), an integer, $n \in \mathbb{Z}$, is not divisible by 3 iff it is of the form n = 3k + 1 or n = 3k + 2, for some $k \in \mathbb{Z}$ (you don't have to prove this).

Prove that for any integer, $n \in \mathbb{Z}$, if n^2 is divisible by 3, then n is divisible by 3.

Hint. Prove the contrapositive. If n of the form n = 3k + 1 or n = 3k + 2, then so is n^2 (for a different k).

Problem 1.13. Use Problem 1.12 to prove that $\sqrt{3}$ is irrational, that is, $\sqrt{3}$ can't be written as $\sqrt{3} = p/q$, with $p, q \in \mathbb{Z}$ and $q \neq 0$.

Problem 1.14. Prove that $b = \log_2 9$ is irrational. Then prove that $a = \sqrt{2}$ and $b = \log_2 9$ are two irrational numbers such that a^b is rational.

Chapter 2

Mathematical Reasoning And Logic, A Deeper View

2.1 Introduction

This chapter is a more advanced and more formal version of Chapter 1. The reader should review Chapter 1 before reading this chapter, which relies rather heavily on it.

As in Chapter 1, the goal of this chapter is to provide an answer to the question, "What is a proof?" We do so by formalizing the basic rules of reasoning that we use, most of the time subconsciously, in a certain kind of formalism known as a *natural deduction system*. We give a (very) quick introduction to *mathematical logic*, with a very deliberate *proof-theoretic* bent, that is, neglecting almost completely all semantic notions, except at a very intuitive level. We still feel that this approach is fruitful because the mechanical and rules-of-thegame flavor of proof systems is much more easily grasped than semantic concepts. In this approach, we follow Peter Andrews' motto [2]:

"To truth through proof."

We present various natural deduction systems due to Prawitz and Gentzen (in more modern notation), both in their intuitionistic and classical version. The adoption of natural deduction systems as proof systems makes it easy to question the validity of some of the inference rules, such as the *principle of proof by contradiction*. In brief, we try to explain to our readers the difference between *constructive* and *classical* (i.e., not necessarily constructive) proofs. In this respect, we plant the seed that there is a deep relationship between *constructive proofs* and the notion of *computation* (the "Curry–Howard isomorphism" or "formulae-as-types principle," see Section 2.13 and Howard [38]).

2.2 Logical Connectives and Propositions

In this section, we review some basic proof principles and attempt to clarify, at least informally, what constitutes a mathematical proof. In order to define the notion of proof rigorously, we would have to define a formal language in which to express statements very precisely and we would have to set up a proof system in terms of axioms and proof rules (also called inference rules). We do not go into this as it would take too much time. Instead, we content ourselves with an intuitive idea of what a statement is and focus on stating as precisely as possible the rules of logic that are used in constructing proofs. Readers who really want to see a thorough (and rigorous) introduction to logic are referred to Gallier [24], van Dalen [75], or Huth and Ryan [41], a nice text with a computer science flavor. A beautiful exposition of logic (from a proof-theoretic point of view) is also given in Troelstra and Schwichtenberg [73], but at a more advanced level.

We also highly recommend the beautifully written little book by Timothy Gowers (Fields Medalist, 1998) [31] which, among other things, discusses the notion of proof in mathematics (as well as the necessity of formalizing proofs without going overboard).

In mathematics and computer science, we **prove statements.** Recall that statements may be *atomic* or *compound*, that is, built up from simpler statements using *logical connectives*, such as *implication* (if-then), *conjunction* (and), *disjunction* (or), *negation* (not), and (existential or universal) quantifiers.

As examples of atomic statements, we have:

- (1) "A student is eager to learn."
- (2) "The product of two odd integers is odd."

Atomic statements may also contain "variables" (standing for arbitrary objects). For example,

- (1) human(x): "x is a human."
- (2) needs-to-drink(x): "x needs to drink."

An example of a compound statement is

 $human(x) \Rightarrow needs-to-drink(x).$

In the above statement, \Rightarrow is the symbol used for logical implication. If we want to assert that every human needs to drink, we can write

 $\forall x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x));$

this is read: "For every x, if x is a human, then x needs to drink."

If we want to assert that some human needs to drink, we write

 $\exists x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x));$

this is read: "There is some x such that if x is a human, then x needs to drink."

We often denote statements (also called *propositions* or *(logical)* formulae) using letters such as A, B, P, Q, and so on, typically uppercase letters (but sometimes Greek letters φ, ψ , etc.).

Recall from Section 1.2 that *compound statements* are defined as follows. If P and Q are statements, then

- (1) the conjunction of P and Q is denoted $P \wedge Q$ (pronounced P and Q),
- (2) the disjunction of P and Q is denoted $P \lor Q$ (pronounced P or Q),
- (3) the *implication* of P and Q is denoted by $P \Rightarrow Q$ (pronounced if P then Q, or P implies Q).

Instead of using the symbol \Rightarrow , some authors use the symbol \rightarrow and write an implication as $P \rightarrow Q$. We do not like to use this notation because the symbol \rightarrow is already used in the notation for functions $(f \colon A \rightarrow B)$. The symbol \supset is sometimes used instead of \Rightarrow . We mostly use the symbol \Rightarrow .

We also have the atomic statement \perp (*falsity*), think of it as the statement that is false no matter what; and the atomic statement \top (*truth*), think of it as the statement that is always true.

The constant \perp is also called *falsum* or *absurdum*. It is a formalization of the notion of *absurdity inconsistency* (a state in which contradictory facts hold).

Given any proposition P, it is convenient to define

(4) the negation $\neg P$ of P (pronounced not P) as $P \Rightarrow \bot$. Thus, $\neg P$ (sometimes denoted $\sim P$) is just a shorthand for $P \Rightarrow \bot$. We write $\neg P \equiv (P \Rightarrow \bot)$.

The intuitive idea is that $\neg P \equiv (P \Rightarrow \bot)$ is true if and only if P is false. Actually, because we don't know what truth is, it is "safer" (and more constructive) to say that $\neg P$ is provable if and only if for every proof of P we can derive a contradiction (namely, \bot is provable). In particular, P should not be provable. For example, $\neg(Q \land \neg Q)$ is provable (as we show later, because any proof of $Q \land \neg Q$ yields a proof of \bot). However, the fact that a proposition Pis **not** provable does not imply that $\neg P$ is provable. There are plenty of propositions such that both P and $\neg P$ are not provable, such as $Q \Rightarrow R$, where Q and R are two unrelated propositions (with no common symbols).

Whenever necessary to avoid ambiguities, we add matching parentheses: $(P \land Q)$, $(P \lor Q)$, $(P \Rightarrow Q)$. For example, $P \lor Q \land R$ is ambiguous; it means either $(P \lor (Q \land R))$ or $((P \lor Q) \land R)$. Another important logical operator is *equivalence*.

If P and Q are statements, then

(5) the equivalence of P and Q is denoted $P \equiv Q$ (or $P \iff Q$); it is an abbreviation for $(P \Rightarrow Q) \land (Q \Rightarrow P)$. We often say "P if and only if Q," or even "P iff Q" for $P \equiv Q$.

To prove a logical equivalence $P \equiv Q$, we have to prove **both** implications $P \Rightarrow Q$ and $Q \Rightarrow P$.

As discussed in Sections 1.2 and 1.3, the meaning of the logical connectives $(\land, \lor, \Rightarrow, \neg, \equiv)$ is intuitively clear. This is certainly the case for and (\land) , since a conjunction $P \land Q$ is true if and only if both P and Q are true (if we are not sure what "true" means, replace it by the word "provable"). However, for or (\lor) , do we mean inclusive or or exclusive or? In the first case, $P \lor Q$ is true if both P and Q are true, but in the second case, $P \lor Q$ is false if both

P and *Q* are true (again, when in doubt, change "true" to "provable"). We always mean inclusive or. The situation is worse for implication (\Rightarrow). When do we consider that $P \Rightarrow Q$ is true (provable)? The answer is that it depends on the rules! The "classical" answer is that $P \Rightarrow Q$ is false (not provable) if and only if *P* is true and *Q* is false.

Of course, there are problems with the above paragraph. What does truth have to do with all this? What do we mean when we say, "P is true"? What is the relationship between truth and provability?

These are actually deep (and tricky) questions, whose answers are not so obvious. One of the major roles of logic is to clarify the notion of truth and its relationship to provability. We avoid these fundamental issues by dealing exclusively with the notion of proof. So, the big question is: what is a proof?

An alternative view (that of intuitionistic logic) of the meaning of implication is that any proof of $P \Rightarrow Q$ can be used to construct a proof of Q given any proof of P. As a consequence of this interpretation, we show later that if $\neg P$ is provable, then $P \Rightarrow Q$ is also provable (instantly), whether or not Q is provable. In such a situation, we often say that $P \Rightarrow Q$ is vacuously provable.

2.3 Proof Rules, Deductions and Proof Trees for Implication

During the process of constructing a proof, it may be necessary to introduce a list of *hypotheses*, also called *premises* (or *assumptions*), which grows and shrinks during the proof. When a proof is finished, *it should have an empty list of premises*. As we show shortly, this amounts to proving implications of the form

$$(P_1 \wedge P_2 \wedge \cdots \wedge P_n) \Rightarrow Q.$$

However, there are certain advantages in defining the notion of *proof* (or *deduction*) of a proposition from a set of premises. Sets of premises are usually denoted using uppercase Greek letters, such as Γ or Δ .

Roughly speaking, a *deduction* of a proposition Q from a multiset of premises Γ is a finite labeled tree, whose root is labeled with Q (the *conclusion*), and whose leaves are labeled with premises from Γ (possibly with multiple occurrences), and such that every interior node corresponds to a given set of *proof rules* (or *inference rules*). In Chapter 1, proof rules were called proof templates. Certain simple deduction trees are declared as obvious proofs, also called *axioms*. The process of managing the list of premises during a proof is a bit technical and can be achieved in various ways. We will present a method due to Prawitz and another method due to Gentzen.

There are many kinds of proof systems: Hilbert-style systems, natural-deduction systems, Gentzen sequents systems, and so on. We describe a so-called *natural deduction system* invented by G. Gentzen in the early 1930s (and thoroughly investigated by D. Prawitz in the mid 1960s).


Figure 2.1: David Hilbert, 1862–1943 (left and middle), Gerhard Gentzen, 1909–1945 (middle right), and Dag Prawitz, 1936– (right).

The major advantage of this system is that *it captures quite nicely the "natural" rules of reasoning that one uses when proving mathematical statements*. This does not mean that it is easy to find proofs in such a system or that this system is indeed very intuitive. We begin with the inference rules for implication and first consider the following question.

How do we proceed to prove an implication, $A \Rightarrow B$? The proof rule corresponds to Proof Template 1.2 (Implication-Intro) and the reader may want to first review the examples discussed in Section 1.3. The rule, called \Rightarrow -intro, is: assume that A has already been proven and then prove B, making as many uses of A as needed.

An important point is that a proof should not depend on any "open" assumptions (premises), and to address this problem, we introduce a mechanism of "discharging" or "closing" premises, as we discussed in Section 1.3.

What this means is that certain rules of our logic are required to discard (the usual terminology is "discharge") certain occurrences of premises, so that the resulting proof does not depend on these premises.

Technically, there are various ways of implementing the discharging mechanism but they all involve some form of tagging (with a "new" variable). For example, the rule formalizing the process that we have just described to prove an implication, $A \Rightarrow B$, known as \Rightarrow -*introduction*, uses a tagging mechanism described precisely in Definition 2.1.

Now, the rule that we have just described is not sufficient to prove certain propositions that should be considered provable under the "standard" intuitive meaning of implication. For example, after a moment of thought, I think most people would want the proposition $P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q)$ to be provable. If we follow the procedure that we have advocated, we assume both P and $P \Rightarrow Q$ and we try to prove Q. For this, we need a new rule, namely:

If P and $P \Rightarrow Q$ are both provable, then Q is provable.

The above rule is known as the \Rightarrow -elimination rule (or modus ponens) and it is formalized in tree-form in Definition 2.1. It corresponds to Proof Template 1.3.

We now make the above rules precise and for this, we represent proofs and deductions as certain kinds of trees and view the logical rules (inference rules) as tree-building rules. In the definition below, the expression Γ, P stands for the multiset obtained by adding one more occurrence of P to Γ . More precisely, the expression Γ, P is an abbreviation for the multiset Γ, P, \ldots, P , with $k \geq 1$. So P may already belong to Γ . Similarly, if Γ and Δ are two multisets of propositions, then Γ, Δ denotes the union of Γ and Δ as a multiset, which means that if P occurs k_1 times in Γ and P occurs k_2 times in Δ , then P occurs $k_1 + k_2$ times in Γ, Δ $(k_1, k_2 \in \mathbb{N})$.

 $\Delta \mathcal{D} P$

A picture such as

represents a deduction tree \mathcal{D} whose root is labeled with P and leaves are labeled with propositions from the *multiset* Δ (a set possibly with multiple occurrences of its members). Some of the propositions in Δ may be tagged by variables. The list of untagged propositions in Δ is the list of *premises* of the deduction tree. We often use an abbreviated version of the above notation where we omit the deduction \mathcal{D} , and simply write

$\Delta P.$

For example, in the deduction tree below (where all rules that implication eliminations rules),

$$\frac{P \Rightarrow (R \Rightarrow S) \qquad P}{R \Rightarrow S} \qquad \frac{Q \Rightarrow R}{R} \qquad \frac{P \Rightarrow Q}{Q} \qquad P}{R}$$

no leaf is tagged, so the premises form the multiset

 $\Delta = \{ P \Rightarrow (R \Rightarrow S), P, Q \Rightarrow R, P \Rightarrow Q, P \},\$

with two occurrences of P, and the conclusion is S.

As we saw in our earlier example, certain inference rules have the effect that some of the original premises may be discarded; the traditional jargon is that some premises may be discharged (or closed). This is the case for the inference rule whose conclusion is an implication. When one or several occurrences of some proposition P are discharged by an inference rule, these occurrences (which label some leaves) are tagged with some new variable not already appearing in the deduction tree. If x is a new tag, the tagged occurrences of Pare denoted P^x and we indicate the fact that premises were discharged by that inference by writing x immediately to the right of the inference bar. For example,

$$\frac{\frac{P^x, Q}{Q}}{P \Rightarrow Q}$$

x

is a deduction tree in which the premise P is discharged by the inference rule. This deduction tree only has Q as a premise, inasmuch as P is discharged.

What is the meaning of the horizontal bars? Actually, nothing really. Here, we are victims of an old habit in logic. Observe that there is always a single proposition immediately under a bar but there may be several propositions immediately above a bar. The intended meaning of the bar is that the proposition below it is obtained as the result of applying an inference rule to the propositions above it. For example, in

$$\frac{Q \Rightarrow R}{R} \qquad Q$$

the proposition R is the result of applying the \Rightarrow -elimination rule (see Definition 2.1 below) to the two premises $Q \Rightarrow R$ and Q. Thus, the use of the bar is just a convention used by logicians going back at least to the 1900s. Removing the bar everywhere would not change anything in our trees, except perhaps reduce their readability. Most logic books draw proof trees using bars to indicate inferences. Therefore, we also use bars in depicting our proof trees.

Because propositions do not arise from the vacuum but instead are built up from a set of atomic propositions using logical connectives (here, \Rightarrow), we assume the existence of an "official set of atomic propositions," or set of *propositional symbols*, $\mathbf{PS} = \{\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3, \ldots\}$. So for example, $\mathbf{P}_1 \Rightarrow \mathbf{P}_2$ and $\mathbf{P}_1 \Rightarrow (\mathbf{P}_2 \Rightarrow \mathbf{P}_1)$ are propositions. Typically, we use uppercase letters such as P, Q, R, S, A, B, C, and so on, to denote arbitrary propositions formed using atoms from **PS**.

Definition 2.1. The axioms, inference rules, and deduction trees for *implicational logic* are defined as follows.

Axioms.

(i) Every one-node tree labeled with a single proposition P is a deduction tree for P with set of premises $\{P\}$.

(ii) The tree

$$\frac{\Gamma, P}{P}$$

is a deduction tree for the proposition P, with multiset set of premises Γ, P .

The above is a concise way of denoting a two-node tree with its leaf labeled with the multiset consisting of the proposition P and the propositions in Γ , each of these propositions (including P) having possibly multiple occurrences but at least one, and whose root is labeled with P. A more explicit form is

$$\underbrace{\frac{P_1, \cdots, P_1}{P_1, \cdots, P_i, \cdots, P_i, \cdots, P_i, \cdots, P_n, \cdots, P_n}}_{P_i}$$

where $k_1, \ldots, k_n \ge 1$ and $n \ge 1$. This axiom says that we always have a deduction of P_i from any set of premises including P_i . They correspond to the Proof Template 1.1 (Trivial Deduction).

The \Rightarrow -introduction rule.

If \mathcal{D} is a deduction tree for Q from the premises in Γ and one or more occurrences of the proposition P, then

$$\Gamma, P^{x}$$

$$\mathcal{D}$$

$$Q$$

$$\overline{P \Rightarrow Q}$$

x

is a deduction tree for $P \Rightarrow Q$ from Γ .

This proof rule is a formalization of Proof Template 1.2 (Implication-Intro). This rule is described more accurately as

$$\Gamma, \overbrace{P^x, \dots, P^x}^k$$
$$\frac{\mathcal{D}}{\frac{Q}{P \Rightarrow Q}} x$$

Note that this inference rule has the additional effect of discharging a nonempty multiset of $k \ge 1$ occurrences of the premise P, which label *distinct leaves* of the deduction \mathcal{D} . These occurrences are tagged with a new variable x, and the tag x is also placed immediately to the right of the inference bar. This is a reminder that the deduction tree whose conclusion is $P \Rightarrow Q$ no longer has the k occurrences of P labeled with x as premises. The new multiset of premises of this deduction tree for $P \Rightarrow Q$ is Γ , which may contain occurrences of P.

The \Rightarrow -elimination rule.

If \mathcal{D}_1 is a deduction tree for $P \Rightarrow Q$ from the premises Γ and \mathcal{D}_2 is a deduction for P from the premises Δ , then

$$\frac{\begin{array}{ccc}
\Gamma & \Delta \\
\mathcal{D}_1 & \mathcal{D}_2 \\
\end{array}}{\begin{array}{c}
P \Rightarrow Q & P \\
\hline
Q
\end{array}}$$

is a deduction tree for Q from the premises in the multiset Γ, Δ . This rule is also known as *modus ponens*. This proof rule is a formalization of Proof Template 1.3 (Implication-Elim).

In the above axioms and rules, Γ or Δ may be empty; P, Q denote arbitrary propositions built up from the atoms in **PS**; and $\mathcal{D}, \mathcal{D}_1$, and \mathcal{D}_2 denote deductions, possibly a one-node tree.

Definition 2.2. A deduction tree is either a one-node tree labeled with a single proposition or a tree constructed using the above axioms and rules. A proof tree is a deduction tree such that all its premises are discharged. The above proof system is denoted $\mathcal{N}_m^{\Rightarrow}$ (here, the subscript m stands for *minimal*, referring to the fact that this is a bare-bones logical system).

Observe that a proof tree has at least two nodes. A proof tree Π for a proposition P may be denoted

 Π P

with an empty set of premises (we don't display \emptyset on top of Π). We tend to denote deductions by the letter \mathcal{D} and proof trees by the letter Π , possibly subscripted.

We emphasize that the \Rightarrow -introduction rule says that in order to prove an implication $P \Rightarrow Q$ from a set of premises Γ , we assume that P has already been proven, add P to the premises in Γ , and then prove Q from Γ and P. Once this is done, the premise P is deleted.

This rule formalizes the kind of reasoning that we all perform whenever we prove an implication statement. In that sense, it is a natural and familiar rule, except that we perhaps never stopped to think about what we are really doing. However, the business about discharging the premise P when we are through with our argument is a bit puzzling. Most people probably never carry out this "discharge step" consciously, but such a process does take place implicitly.

Remarks:

- 1. Only the leaves of a deduction tree may be discharged. Interior nodes, including the root, are *never* discharged.
- 2. Once a set of leaves labeled with some premise P marked with the label x has been discharged, none of these leaves can be discharged again. So each label (say x) can only be used once. This corresponds to the fact that some leaves of our deduction trees get "killed off" (discharged).
- 3. A proof is a deduction tree whose leaves are *all discharged* (Γ is empty). This corresponds to the philosophy that if a proposition has been proven, then the validity of the proof should not depend on any assumptions that are still active. We may think of a deduction tree as an unfinished proof tree.
- 4. When constructing a proof tree, we have to be careful not to include (accidentally) extra premises that end up not being discharged. If this happens, we probably made a mistake and the redundant premises should be deleted. On the other hand, if we have a proof tree, we can always add extra premises to the leaves and create a new proof tree from the previous one by discharging all the new premises.
- 5. Beware, when we deduce that an implication $P \Rightarrow Q$ is provable, we **do not** prove that P and Q are provable; we only prove that if P is provable, then Q is provable.

The \Rightarrow -elimination rule formalizes the use of *auxiliary lemmas*, a mechanism that we use all the time in making mathematical proofs. Think of $P \Rightarrow Q$ as a lemma that has already

been established and belongs to some database of (useful) lemmas. This lemma says if I can prove P, then I can prove Q. Now, suppose that we manage to give a proof of P. It follows from the \Rightarrow -elimination rule that Q is also provable.

Observe that in an introduction rule, the conclusion contains the logical connective associated with the rule, in this case, \Rightarrow ; this justifies the terminology "introduction". On the other hand, in an elimination rule, the logical connective associated with the rule is gone (although it may still appear in Q). The other inference rules for \land , \lor , and the like, follow this pattern of introduction and elimination.

2.4 Examples of Proof Trees

(a) Here is a proof tree for $P \Rightarrow P$.

$$\frac{\frac{P^x}{P}}{P \Rightarrow P} \quad x$$

So, $P \Rightarrow P$ is provable; this is the least we should expect from our proof system! Note that

$$\frac{P^x}{P \Rightarrow P} \quad x$$

is also a valid proof tree for $P \Rightarrow P$, because the one-node tree labeled with P is a deduction tree.

(b) Here is a proof tree for $(P \Rightarrow Q) \Rightarrow ((Q \Rightarrow R) \Rightarrow (P \Rightarrow R))$.

$$\begin{array}{c} (P \Rightarrow Q)^z & P^x \\ \hline \\ (Q \Rightarrow R)^y & \hline \\ Q \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ R \\ \hline \\ \hline \\ P \Rightarrow R \\ \hline \\ \hline \\ (Q \Rightarrow R) \Rightarrow (P \Rightarrow R) \\ \hline \\ \hline \\ \hline \\ (P \Rightarrow Q) \Rightarrow ((Q \Rightarrow R) \Rightarrow (P \Rightarrow R)) \\ \hline \end{array} \right)^z$$

In order to better appreciate the difference between a deduction tree and a proof tree, consider the following two examples.

Example 2.1. The tree below is a deduction tree because two of its leaves are labeled with the premises $P \Rightarrow Q$ and $Q \Rightarrow R$, that have not been discharged yet. So, this tree represents a deduction of $P \Rightarrow R$ from the set of premises $\Gamma = \{P \Rightarrow Q, Q \Rightarrow R\}$, but it is *not a proof tree* because $\Gamma \neq \emptyset$. However, observe that the original premise P, labeled x, has been discharged.

$$\begin{array}{c} P \Rightarrow Q \qquad P^{x} \\ Q \Rightarrow R \qquad \hline Q \\ \hline \hline R \\ \hline R \\ \hline P \Rightarrow R \end{array}^{x} \end{array}$$

Example 2.2. The next tree was obtained from the previous one by applying the \Rightarrow -introduction rule which triggered the discharge of the premise $Q \Rightarrow R$ labeled y, which is no longer active. However, the premise $P \Rightarrow Q$ is still active (has not been discharged yet), so the tree below is a deduction tree of $(Q \Rightarrow R) \Rightarrow (P \Rightarrow R)$ from the set of premises $\Gamma = \{P \Rightarrow Q\}$. It is not yet a proof tree inasmuch as $\Gamma \neq \emptyset$.

$$\frac{(Q \Rightarrow R)^{y}}{Q} \xrightarrow{P \Rightarrow Q} \frac{P^{x}}{Q}$$

$$\frac{R}{P \Rightarrow R} \xrightarrow{x}{Q}$$

$$\frac{R}{(Q \Rightarrow R) \Rightarrow (P \Rightarrow R)} \xrightarrow{y}$$

Finally, one more application of the \Rightarrow -introduction rule discharged the premise $P \Rightarrow Q$, at last, yielding the proof tree in (b).

(c) This example illustrates the fact that different proof trees may arise from the same set of premises $\{P, Q\}$. For example, here are proof trees for $Q \Rightarrow (P \Rightarrow P)$ and $P \Rightarrow (Q \Rightarrow P)$.

$$\frac{\frac{P^x, Q^y}{P}}{\frac{P \Rightarrow P}{Q \Rightarrow (P \Rightarrow P)}} \quad x$$

and

$$\frac{\frac{P^x, Q^y}{P}}{\frac{Q \Rightarrow P}{P \Rightarrow (Q \Rightarrow P)}} \xrightarrow{x} .$$

Similarly, there are six proof trees with a conclusion of the form

$$A \Rightarrow (B \Rightarrow (C \Rightarrow P))$$

beginning with the deduction

$$\frac{P^x, Q^y, R^z}{P}$$

where A, B, C correspond to the six permutations of the premises P, Q, R.

Note that we would not have been able to construct the above proofs if Axiom (ii),

$$\frac{\Gamma, P}{P} \quad ,$$

were not available. We need a mechanism to "stuff" more premises into the leaves of our deduction trees in order to be able to discharge them later on. We may also view Axiom (ii) as a *weakening rule*, whose purpose is to weaken a set of assumptions. Even though we are assuming all of the propositions in Γ and P, we only use the assumption P. The necessity of allowing multisets of premises is illustrated by the following proof of the proposition $P \Rightarrow (P \Rightarrow (Q \Rightarrow (P \Rightarrow P)))).$

$$\begin{array}{c} \displaystyle \frac{P^{u},P^{v},P^{y},Q^{w},Q^{x}}{P} \\ \displaystyle \frac{P}{P\Rightarrow P} & y \\ \hline Q\Rightarrow (P\Rightarrow P) & x \\ \hline Q\Rightarrow (Q\Rightarrow (P\Rightarrow P)) & w \\ \hline P\Rightarrow (Q\Rightarrow (Q\Rightarrow (P\Rightarrow P))) & v \\ \hline P\Rightarrow (P\Rightarrow (Q\Rightarrow (Q\Rightarrow (P\Rightarrow P)))) & y \\ \hline P\Rightarrow (P\Rightarrow (Q\Rightarrow (Q\Rightarrow (P\Rightarrow P)))) & y \\ \hline \end{array}$$

(d) In the next example which shows a proof of

$$(A \Rightarrow (B \Rightarrow C)) \Rightarrow ((A \Rightarrow B) \Rightarrow (A \Rightarrow C)),$$

the two occurrences of A labeled x are discharged simultaneously.

$$\frac{(A \Rightarrow (B \Rightarrow C))^z \quad A^x}{B \Rightarrow C} \qquad \frac{(A \Rightarrow B)^y \quad A^x}{B}$$

$$\frac{\frac{(A \Rightarrow B)^y \quad A^x}{B}}{\frac{C}{A \Rightarrow C}}$$

$$\frac{\frac{C}{A \Rightarrow C}}{(A \Rightarrow B) \Rightarrow (A \Rightarrow C)} \qquad y$$

$$\frac{(A \Rightarrow (B \Rightarrow C)) \Rightarrow ((A \Rightarrow B) \Rightarrow (A \Rightarrow C))}{(A \Rightarrow B) \Rightarrow (A \Rightarrow C))} \qquad z$$

(e) In contrast to Example (d), in the proof tree below with conclusion

$$A \Rightarrow \left(\left(A \Rightarrow (B \Rightarrow C) \right) \Rightarrow \left((A \Rightarrow B) \Rightarrow (A \Rightarrow C) \right) \right),$$

the two occurrences of A are *discharged separately*. To this effect, they are labeled differently.

$$\frac{(A \Rightarrow (B \Rightarrow C))^{z} \qquad A^{x}}{B \Rightarrow C} \qquad \frac{(A \Rightarrow B)^{y} \qquad A^{t}}{B}$$

$$\frac{\overline{(A \Rightarrow C)}^{z}}{\overline{(A \Rightarrow C)}^{x}}$$

$$\frac{\overline{(A \Rightarrow C)}^{x}}{\overline{(A \Rightarrow B) \Rightarrow (A \Rightarrow C)}^{y}}$$

$$\frac{\overline{(A \Rightarrow (B \Rightarrow C)) \Rightarrow ((A \Rightarrow B) \Rightarrow (A \Rightarrow C))}^{z}}{A \Rightarrow ((A \Rightarrow (B \Rightarrow C)) \Rightarrow ((A \Rightarrow B) \Rightarrow (A \Rightarrow C)))} \qquad t$$

How do we find these proof trees? Well, we could try to enumerate all possible proof trees systematically and see if a proof of the desired conclusion turns up. Obviously, this is a very inefficient procedure and moreover, how do we know that all possible proof trees will be generated and how do we know that such a method will terminate after a finite number of steps (what if the proposition proposed as a conclusion of a proof is not provable)?

Finding an algorithm to decide whether a proposition is provable is a very difficult problem and for sets of propositions with enough "expressive power" (such as propositions involving first-order quantifiers), it can be shown that there is **no** procedure that will give an answer in all cases and terminate in a finite number of steps for all possible input propositions. We come back to this point in Section 2.13. However, for the system $\mathcal{N}_m^{\Rightarrow}$, such a procedure exists, but it is not easy to prove that it terminates in all cases and in fact, it can take a very long time.

What we did, and we strongly advise our readers to try it when they attempt to construct proof trees, is to construct the proof tree from the *bottom up*, starting from the proposition labeling the root, rather than top-down, that is, starting from the leaves. During this process, whenever we are trying to prove a proposition $P \Rightarrow Q$, we use the \Rightarrow -introduction rule backward, that is, we add P to the set of active premises and we try to prove Q from this new set of premises. At some point, we get stuck with an atomic proposition, say R. Call the resulting deduction \mathcal{D}_{bu} ; note that R is the only active (undischarged) premise of \mathcal{D}_{bu} and the node labeled R immediately below it plays a special role; we call it the special node of \mathcal{D}_{bu} .

Here is an illustration of this method for Example (d). At the end of the bottom-up process, we get the deduction tree \mathcal{D}_{bu} .

In the above deduction tree, the proposition R = C is the only active (undischarged) premise. To turn the above deduction tree into a proof tree, we need to construct a deduction of C from the premises other than C. This is a more creative step which can be quite difficult. The trick is now to switch strategies and start building a proof tree top-down, starting from the leaves, using the \Rightarrow -elimination rule. If everything works out well, we get a deduction with root R, say \mathcal{D}_{td} , and then we glue this deduction \mathcal{D}_{td} to the deduction \mathcal{D}_{bu} in such a way that the root of \mathcal{D}_{td} is identified with the special node of \mathcal{D}_{bu} labeled R.

We also have to make sure that all the discharged premises are linked to the correct instance of the \Rightarrow -introduction rule that caused them to be discharged. One of the difficulties is that during the bottom-up process, we don't know how many copies of a premise need to be discharged in a single step. We only find out how many copies of a premise need to be discharged during the top-down process.

Going back to our example, at the end of the top-down process, we get the deduction tree \mathcal{D}_{td} .

$$\frac{A \Rightarrow (B \Rightarrow C) \qquad A}{B \Rightarrow C} \qquad \frac{A \Rightarrow B}{B} \qquad A$$

Finally, after gluing \mathcal{D}_{td} on top of \mathcal{D}_{bu} (which has the correct number of premises to be discharged), we get our proof tree:

(f) The following example shows that proofs may be redundant. The proposition $P \Rightarrow ((P \Rightarrow Q) \Rightarrow Q)$ has the following proof.

$$\begin{array}{ccc} \displaystyle \frac{(P\Rightarrow Q)^x & P^y}{Q} \\ \hline \\ \hline \\ \displaystyle \frac{Q}{(P\Rightarrow Q)\Rightarrow Q} & x \\ \hline \\ P\Rightarrow ((P\Rightarrow Q)\Rightarrow Q) & y \end{array}$$

Now, say P is the proposition $R \Rightarrow R$, which has the proof

$$\frac{\frac{R^z}{R}}{R \Rightarrow R} \quad z$$

Using \Rightarrow -elimination, we obtain a proof of $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ from the proof of $(R \Rightarrow R) \Rightarrow (((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q)$ and the proof of $R \Rightarrow R$ shown above.

$$\frac{((R \Rightarrow R) \Rightarrow Q)^{x} \quad (R \Rightarrow R)^{y}}{Q}$$

$$\frac{Q}{((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q} \xrightarrow{x} \qquad \frac{R^{z}}{R}$$

$$\frac{(R \Rightarrow R) \Rightarrow (((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q)}{((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q} \xrightarrow{y} \qquad \frac{R \Rightarrow R}{R \Rightarrow R}$$

Note that the above proof is *redundant*. The deduction tree shown in blue has the proposition $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ as conclusion but the proposition $R \Rightarrow R$ is introduced in the step labeled y and immediately eliminated in the next step. A more direct proof can be obtained as follows. Undo the last \Rightarrow -introduction (involving the proposition $R \Rightarrow R$ and the tag y) in the proof of $(R \Rightarrow R) \Rightarrow (((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q)$ obtaining the deduction tree shown in blue above

$$\frac{((R \Rightarrow R) \Rightarrow Q)^x \qquad R \Rightarrow R}{Q}$$

$$\frac{Q}{((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q} \qquad x$$

and then glue the proof of $R \Rightarrow R$ on top of the leaf $R \Rightarrow R$, obtaining the desired proof of $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$.

$$\frac{\frac{R^z}{R}}{Q} \xrightarrow{x} ((R \Rightarrow R) \Rightarrow Q)^x \qquad R \Rightarrow R \qquad z$$

$$\frac{((R \Rightarrow R) \Rightarrow Q)^x \qquad x}{((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q} \xrightarrow{x}$$

In general, one has to exercise care with the label variables. It may be necessary to rename some of these variables to avoid clashes. What we have above is an example of *proof substitution* also called *proof* normalization. We come back to this topic in Section 2.13.

2.5 A Gentzen-Style System for Natural Deduction

The process of discharging premises when constructing a deduction is admittedly a bit confusing. Part of the problem is that a deduction tree really represents the last of a sequence of stages (corresponding to the application of inference rules) during which the current set of "active" premises, that is, those premises that have not yet been discharged (closed, cancelled) evolves (in fact, shrinks). Some mechanism is needed to keep track of which premises are no longer active and this is what this business of labeling premises with variables achieves. Historically, this is the first mechanism that was invented. However, Gentzen (in the 1930s) came up with an alternative solution that is mathematically easier to handle. Moreover, it turns out that this notation is also better suited to computer implementations, if one wishes to implement an automated theorem prover.

The point is to keep a record of all undischarged assumptions at every stage of the deduction. Thus, a deduction is now a tree whose nodes are labeled with pairs of the form $\langle \Gamma, P \rangle$, where P is a proposition, and Γ is a record of all undischarged assumptions at the stage of the deduction associated with this node.

Instead of using the notation $\langle \Gamma, P \rangle$, which is a bit cumbersome, Gentzen used expressions of the form $\Gamma \to P$, called *sequents*.

It should be noted that the symbol \rightarrow is used as a *separator* between the left-hand side Γ , called the *antecedent*, and the right-hand side P, called the *conclusion* (or *succedent*) and any other symbol could be used. Of course \rightarrow is reminiscent of implication but we should not identify \rightarrow and \Rightarrow . Still, it turns out that a sequent $\Gamma \rightarrow P$ is provable if and only if $(P_1 \wedge \cdots \wedge P_m) \Rightarrow P$ is provable, where $\Gamma = (P_1, \ldots, P_m)$.

During the construction of a deduction tree, it is necessary to discharge packets of assumptions consisting of one or more occurrences of the same proposition. To this effect, it is convenient to tag packets of assumptions with labels, in order to discharge the propositions in these packets in a single step. We use variables for the labels, and a packet labeled with x consisting of occurrences of the proposition P is written as x: P.

Definition 2.3. A sequent is an expression $\Gamma \to P$, where Γ is any finite set of the form $\{x_1: P_1, \ldots, x_m: P_m\}$ called a context, where x_i are pairwise distinct (but P_i need not be distinct). Given $\Gamma = \{x_1: P_1, \ldots, x_m: P_m\}$, the notation $\Gamma, x: P$ is only well-defined when $x \neq x_i$ for all $i, 1 \leq i \leq m$, in which case it denotes the set $\{x_1: P_1, \ldots, x_m: P_m, x: P\}$. Given two contexts Γ and Δ , the context $\Gamma \cup \Delta$ is the union of the sets of pairs $(x_i: P_i)$ in Γ and the set of pairs $(y_k: Q_j)$ in Δ , provided that if $x: P \in \Gamma$ and $x: Q \in \Delta$ for the same variable x, then P = Q. In this case, we say that Γ and Δ are consistent. So if x: P occurs both in Γ and Δ , then x: P also occurs in $\Gamma \cup \Delta$ (once).

One can think of a context $\Gamma = \{x_1 : P_1, \ldots, x_m : P_m\}$ as a set of type declarations for the variables x_1, \ldots, x_m (x_i has type P_i). It should be noted that in the Prawitz-style formalism for proof trees, premises are treated as *multisets*, but in the Gentzen-style formalism, premises are *sets* of tagged pairs.

Using sequents, the axioms and rules of Definition 2.4 are now expressed as follows.

Definition 2.4. The axioms and inference rules of the system $\mathcal{NG}_m^{\Rightarrow}$ (*implicational logic*, Gentzen-sequent style (the \mathcal{G} in \mathcal{NG} stands for Gentzen)) are listed below.

$$\Gamma, x \colon P \to P \quad (\text{Axioms})$$

$$\frac{\Gamma, x \colon P \to Q}{\Gamma \to P \Rightarrow Q} \quad (\Rightarrow\text{-intro})$$

$$\frac{\Gamma \to P \Rightarrow Q \quad \Delta \to P}{\Gamma \cup \Delta \to Q} \quad (\Rightarrow-elim).$$

In an axiom or the rule $(\Rightarrow -intro)$, it is assumed that $x \colon P \notin \Gamma$. In an application of the rule $(\Rightarrow -intro)$, in the lower sequent, the proposition P labeled x is deleted from the list of premises occurring on the left-hand side of the arrow in the upper sequent. We say that the proposition P that appears as a hypothesis of the deduction is *discharged* (or *closed*). In the rule $(\Rightarrow -elim)$, it is assumed that Γ and Δ are consistent contexts. A *deduction tree* is either a one-node tree labeled with an axiom or a tree constructed using the above inference rules. A *proof tree* is a deduction tree whose conclusion is a sequent with an empty set of premises (a sequent of the form $\rightarrow P$).

It is important to note that the ability to label packets consisting of occurrences of the same proposition with different labels is essential, in order to be able to have control over which groups of packets of assumptions are discharged simultaneously. Equivalently, we could avoid tagging packets of assumptions with variables if we assume that in a sequent $\Gamma \rightarrow C$, the expression Γ is a *multiset* of propositions.

Let us display the proof tree for the second proof tree in Example (c) in our new Gentzensequent system. The orginal proof tree is

$$\frac{\frac{P^x, Q^y}{P}}{\frac{Q \Rightarrow P}{Q \Rightarrow P}} \xrightarrow{y}$$

$$\overline{P \Rightarrow (Q \Rightarrow P)}$$

x

and the corresponding proof tree in our new system is

$$\frac{x \colon P, y \colon Q \to P}{x \colon P \to Q \Rightarrow P}$$
$$\xrightarrow{\qquad \rightarrow P \Rightarrow (Q \Rightarrow P)}$$

Below, we show a proof of the first proposition of Example (d) given above in our new system. Since the tree is too wide to fit in the page, we set $Q = B \Rightarrow C$.

$$\begin{array}{l} \displaystyle \frac{z \colon A \Rightarrow Q \to A \Rightarrow Q \quad x \colon A \to A}{z \colon A \Rightarrow (B \Rightarrow C), x \colon A \to B \Rightarrow C} & \displaystyle \frac{y \colon A \Rightarrow B \to A \Rightarrow B \quad x \colon A \to A}{y \colon A \Rightarrow B, x \colon A \to B} \\ \\ \hline \\ \displaystyle \frac{z \colon A \Rightarrow (B \Rightarrow C), x \colon A \to B \Rightarrow C}{z \colon A \Rightarrow (B \Rightarrow C), y \colon A \Rightarrow B, x \colon A \to C} \\ \\ \hline \\ \displaystyle \frac{z \colon A \Rightarrow (B \Rightarrow C), y \colon A \Rightarrow B \to A \Rightarrow C}{z \colon A \Rightarrow (B \Rightarrow C) \to (A \Rightarrow B) \Rightarrow (A \Rightarrow C)} \\ \hline \\ \hline \\ \displaystyle \rightarrow (A \Rightarrow (B \Rightarrow C)) \Rightarrow ((A \Rightarrow B) \Rightarrow (A \Rightarrow C)) \end{array}$$

It is not hard to design an algorithm that converts a deduction tree (or a proof tree) in the system $\mathcal{N}_m^{\Rightarrow}$ into a deduction tree (or a proof tree) in the system $\mathcal{N}_m^{\Rightarrow}$, and vice-versa.

In both cases, the underlying tree is exactly the same, and there is a bijection between the sets of undischarged premises in both representations.

After experimenting with the construction of proofs, one gets the feeling that every proof can be simplified to a "unique minimal" proof, if we define "minimal" in a suitable sense, namely, that a minimal proof never contains an elimination rule immediately following an introduction rule (for more on this, see Section 2.13). Then it turns out that to define the notion of uniqueness of proofs, the second version is preferable. However, it is important to realize that in general, a proposition may possess distinct minimal proofs.

In principle, it does not matter which of the two systems $\mathcal{N}_m^{\Rightarrow}$ or $\mathcal{N}\mathcal{G}_m^{\Rightarrow}$ we use to construct deductions; it is basically a matter of taste. The Prawitz-style system $\mathcal{N}_m^{\Rightarrow}$ produces proofs that are closer to the informal proofs that humans construct. One the other hand, the Gentzen-style system $\mathcal{N}\mathcal{G}_m^{\Rightarrow}$ is better suited for implementing theorem provers. My experience is that I make fewer mistakes with the Gentzen-sequent style system $\mathcal{N}\mathcal{G}_m^{\Rightarrow}$.

We now describe the inference rules dealing with the connectives \land , \lor , and \perp .

In this section, we describe the proof rules for all the connectives of propositional logic both in Prawitz-style and in Gentzen-style. As we said earlier, the rules of the Prawitz-style system are closer to the rules that human use informally, and the rules of the Gentzen-style system are more convenient for computer implementations of theorem provers.

The rules involving \perp are not as intuitively justified as the other rules. In fact, in the early 1900s, some mathematicians, especially L. Brouwer (1881–1966), questioned the validity of the proof-by-contradiction rule, among other principles. This led to the idea that it may be useful to consider proof systems of different strength. The weakest (and considered the safest) system is called *minimal logic*. This system rules out the \perp -elimination rule (the ability to deduce any proposition once a contradiction has been established) and the proof-by-contradiction rule. *Intuitionistic logic* rules out the proof-by-contradiction rule, and *classical logic* allows all the rules. Most people use classical logic, but intuitionistic logic is an interesting alternative because it is more constructive. We will elaborate on this point later. Minimal logic is just too weak.

Recall that $\neg P$ is an abbreviation for $P \Rightarrow \bot$.

Definition 2.5. The axioms, inference rules, and deduction trees for *(propositional) classical logic* are defined as follows. In the axioms and rules below, Γ , Δ , or Λ may be empty; P, Q, R denote arbitrary propositions built up from the atoms in **PS**; \mathcal{D} , \mathcal{D}_1 , \mathcal{D}_2 denote deductions, possibly a one-node tree; and all the premises labeled x or y are discharged.

Axioms:

(i) Every one-node tree labeled with a single proposition P is a deduction tree for P with set of premises $\{P\}$.

(ii) The tree

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 $\frac{\Gamma, P}{P}$

is a deduction tree for P with multiset of premises Γ, P .

The \Rightarrow -introduction rule:

If \mathcal{D} is a deduction of Q from the premises in Γ and one or more occurrences of the proposition P, then

$$\begin{array}{c}
 \Gamma, P^x \\
 \mathcal{D} \\
 Q \\
 \overline{P \Rightarrow Q}
 \end{array}$$

x

is a deduction tree for $P \Rightarrow Q$ from Γ . As in Definition 2.1, recall that Γ, P is an abbreviation

for the multiset Γ, P, \ldots, P , with $k \ge 1$. This inference rule has the additional effect of discharging a nonempty multiset of occurrences of the premise P (which label distinct leaves of the deduction \mathcal{D}). These occurrences are tagged with a new variable x, and the tag x is also placed immediately to the right of the inference bar. This proof rule corresponds to Proof Template 1.2 (Implication-Intro).

The \Rightarrow -elimination rule (or modus ponens):

If \mathcal{D}_1 is a deduction tree for $P \Rightarrow Q$ from the premises Γ , and \mathcal{D}_2 is a deduction for P from the premises Δ , then

$$\begin{array}{ccc}
\Gamma & \Delta \\
\mathcal{D}_1 & \mathcal{D}_2 \\
P \Rightarrow Q & P \\
\hline
Q
\end{array}$$

is a deduction tree for Q from the premises in the multiset Γ, Δ . This proof rule corresponds to Proof Template 1.3 (Implication-Elim).

The \wedge -introduction rule:

If \mathcal{D}_1 is a deduction tree for P from the premises Γ , and \mathcal{D}_2 is a deduction for Q from the premises Δ , then

$$\begin{array}{ccc}
 \Gamma & \Delta \\
 \mathcal{D}_1 & \mathcal{D}_2 \\
 \underline{P & Q} \\
 \overline{P \wedge Q}
 \end{array}$$

is a deduction tree for $P \wedge Q$ from the premises in the multiset Γ, Δ . This proof rule corresponds to Proof Template 1.8 (And-Intro).

The \wedge -elimination rule:

If \mathcal{D} is a deduction tree for $P \wedge Q$ from the premises Γ , then



are deduction trees for P and Q from the premises Γ . This proof rule corresponds to Proof Template 1.9 (And-elim).

The \lor -introduction rule:

If \mathcal{D} is a deduction tree for P or for Q from the premises Γ , then

$$\begin{array}{ccc}
\Gamma & & \Gamma \\
\mathcal{D} & & \mathcal{D} \\
P \\
\frac{P}{P \lor Q} & & \frac{Q}{P \lor Q}
\end{array}$$

are deduction trees for $P \lor Q$ from the premises in Γ . This proof rule corresponds to Proof Template 1.10 (Or-Intro).

The V-elimination rule:

If \mathcal{D}_1 is a deduction tree for $P \vee Q$ from the premises Γ , \mathcal{D}_2 is a deduction for R from the premises in the multiset Δ and one or more occurrences of P, and \mathcal{D}_3 is a deduction for R from the premises in the multiset Λ and one or more occurrences of Q, then

$$\frac{\Gamma}{D_1} \quad \begin{array}{c} \Delta, P^x & \Lambda, Q^y \\ D_1 & D_2 & D_3 \\ \hline P \lor Q & R & R \\ \hline R & & & \\ \hline R & & & \\ \hline \end{array} \quad x,y$$

is a deduction tree for R from the premises in the multiset Γ, Δ, Λ . A nonempty set of premises P in \mathcal{D}_2 labeled x and a nonempty set of premises Q in \mathcal{D}_3 labeled y are discharged. This proof rule corresponds to Proof Template 1.11 (Or-Elim).

The \perp -elimination rule:

If \mathcal{D} is a deduction tree for \perp from the premises Γ , then



is a deduction tree for P from the premises Γ , for any proposition P. This proof rule corresponds to Proof Template 1.6 (Perp-Elim).

The proof-by-contradiction rule (also known as reductio ad absurdum rule, for short RAA):

If \mathcal{D} is a deduction tree for \perp from the premises in the multiset Γ and one or more occurrences of $\neg P$, then



is a deduction tree for P from the premises Γ . A nonempty set of premises $\neg P$ labeled x are discharged. This proof rule corresponds to Proof Template 1.7 (Proof-By-Contradiction Principle).

Because $\neg P$ is an abbreviation for $P \Rightarrow \bot$, the \neg -introduction rule is a special case of the \Rightarrow -introduction rule (with $Q = \bot$). However, it is worth stating it explicitly.

The ¬-introduction rule:

If \mathcal{D} is a deduction tree for \perp from the premises in the multiset Γ and one or more occurrences of P, then

$$\begin{array}{c} \Gamma, P^x \\ \mathcal{D} \\ \underline{\perp} \\ \neg P \end{array}$$

x

is a deduction tree for $\neg P$ from the premises Γ . A nonempty set of premises P labeled x are discharged. This proof rule corresponds to Proof Template 1.4 (Negation-Intro).

The above rule can be viewed as a proof-by-contradiction principle applied to negated propositions.

Similarly, the \neg -elimination rule is a special case of \Rightarrow -elimination applied to $\neg P$ (= $P \Rightarrow \bot$) and P.

The ¬-elimination rule:

If \mathcal{D}_1 is a deduction tree for $\neg P$ from the premises Γ , and \mathcal{D}_2 is a deduction for P from the premises Δ , then

$$\begin{array}{ccc}
\Gamma & \Delta \\
\mathcal{D}_1 & \mathcal{D}_2 \\
\neg P & P \\
\end{array}$$

is a deduction tree for \perp from the premises in the multiset Γ, Δ . This proof rule corresponds to Proof Template 1.5 (Negation-Elim).

A deduction tree is either a one-node tree labeled with a single proposition or a tree constructed using the above axioms and inference rules. A proof tree is a deduction tree such that all its premises are discharged. The above proof system is denoted $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (here, the subscript c stands for classical).

Definition 2.6. The system obtained by removing the proof-by-contradiction (RAA) rule is called *(propositional) intuitionistic logic* and is denoted $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$. The system obtained

by deleting both the \perp -elimination rule and the proof-by-contradiction rule is called *(propositional) minimal logic* and is denoted $\mathcal{N}_m^{\Rightarrow,\wedge,\vee,\perp}$

The version of $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp}$ in terms of Gentzen sequents is the following.

Definition 2.7. The axioms and inference rules of the system $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$ (of propositional classical logic, Gentzen-sequent style) are listed below.

$$\begin{split} & \Gamma, x \colon P \to P \quad (\text{Axioms}) \\ & \frac{\Gamma, x \colon P \to Q}{\Gamma \to P \Rightarrow Q} \quad (\Rightarrow\text{-intro}) \\ & \frac{\Gamma \to P \Rightarrow Q \quad \Delta \to P}{\Gamma \cup \Delta \to Q} \quad (\Rightarrow\text{-elim}) \\ & \frac{\Gamma \to P \quad \Delta \to Q}{\Gamma \cup \Delta \to P \land Q} \quad (\land\text{-intro}) \\ & \frac{\Gamma \to P \land Q}{\Gamma \to P} \quad (\land\text{-elim}) \quad \frac{\Gamma \to P \land Q}{\Gamma \to Q} \quad (\land\text{-elim}) \\ & \frac{\Gamma \to P}{\Gamma \to P \lor Q} \quad (\lor\text{-intro}) \quad \frac{\Gamma \to Q}{\Gamma \to P \lor Q} \quad (\lor\text{-intro}) \\ & \frac{\Gamma \to P}{\Gamma \to P \lor Q} \quad (\lor\text{-intro}) \quad \frac{\Gamma \to Q}{\Gamma \to P \lor Q} \quad (\lor\text{-intro}) \\ & \frac{\Gamma \to P}{\Gamma \cup \Delta \cup \Lambda \to R} \quad (\forall\text{-elim}) \\ & \frac{\Gamma, x \colon P \to \bot}{\Gamma \to P} \quad (by\text{-contra}) \\ & \frac{\Gamma, x \colon P \to \bot}{\Gamma \to \neg P} \quad (\neg\text{-introduction}) \\ & \frac{\Gamma \to \neg P \quad \Delta \to P}{\Gamma \cup \Delta \to \bot} \quad (\neg\text{-elimination}). \end{split}$$

The following restrictions apply. In the axioms and the rule $(\Rightarrow -intro)$, $x \colon P \notin \Gamma$; in the rule $(\lor -elim)$, $x \colon P \notin \Delta$ and $y \colon Q \notin \Lambda$; in the rule (by - contra), $x \colon \neg P \notin \Gamma$; and in the rule $(\neg -introduction)$, $x \colon P \notin \Gamma$.

A deduction tree is either a one-node tree labeled with an axiom or a tree constructed using the above inference rules. A proof tree is a deduction tree whose conclusion is a sequent with an empty set of premises (a sequent of the form $\emptyset \to P$).

The rule $(\perp -elim)$ is trivial (does nothing) when $P = \perp$. Therefore, from now, on we assume that $P \neq \perp$. Propositional minimal logic, denoted $\mathcal{NG}_m^{\Rightarrow,\wedge,\vee,\perp}$, is obtained by dropping the $(\perp -elim)$ and (by-contra) rules. Propositional intuitionistic logic, denoted $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$, is obtained by dropping the (by-contra) rule.

Definition 2.8. When we say that a proposition P is provable from Γ , we mean that we can construct a proof tree, whose conclusion is P and set of premises is Γ , in one of the systems $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ or $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$. Therefore, when we use the word "provable" unqualified, we mean provable in *classical logic*. If P is provable from Γ in one of the intuitionistic systems $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ or $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$, then we say *intuitionistically provable* (and similarly, if P is provable from Γ in one of the systems $\mathcal{N}_m^{\Rightarrow,\wedge,\vee,\perp}$ or $\mathcal{NG}_m^{\Rightarrow,\wedge,\vee,\perp}$, then we say *provable* in *minimal logic*).

When P is provable from Γ , most people write $\Gamma \vdash P$, or $\vdash \Gamma \rightarrow P$, sometimes with the name of the corresponding proof system tagged as a subscript on the sign \vdash if necessary to avoid ambiguities. When Γ is empty, we just say P is provable (provable in intuitionistic logic, and so on) and write $\vdash P$.

We treat *logical equivalence* as a derived connective; that is, we view $P \equiv Q$ as an abbreviation for $(P \Rightarrow Q) \land (Q \Rightarrow P)$. In view of the inference rules for \land , we see that to prove a logical equivalence $P \equiv Q$, we just have to prove both implications $P \Rightarrow Q$ and $Q \Rightarrow P$.

Since the only difference between the proof systems $\mathcal{N}_m^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{N}\mathcal{G}_m^{\Rightarrow,\wedge,\vee,\perp}$ is the way in which they perform the bookkeeping of premises, it is intuitively clear that they are equivalent. However, they produce different kinds of proof, so to be rigorous, we must check that the proof systems $\mathcal{N}_m^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{N}\mathcal{G}_m^{\Rightarrow,\wedge,\vee,\perp}$, as well as the systems $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{N}\mathcal{G}_i^{\Rightarrow,\wedge,\vee,\perp}$ and the systems $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{N}\mathcal{G}_c^{\Rightarrow,\wedge,\vee,\perp}$, are equivalent. This is not hard to show but is a bit tedious; see Problem 2.14.

In view of the \neg -elimination rule, we may be tempted to interpret the provability of a negation $\neg P$ as "P is not provable." Indeed, if $\neg P$ and P were both provable, then \bot would be provable. So, P should not be provable if $\neg P$ is. However, if P is not provable, then $\neg P$ is **not** provable in general. There are plenty of propositions such that neither P nor $\neg P$ is provable (for instance P, with P an atomic proposition). Thus, the fact that P is not provable is not equivalent to the provability of $\neg P$ and we should not interpret $\neg P$ as "P is not provable."

Let us now make some (much-needed) comments about the above inference rules. There is no need to repeat our comments regarding the \Rightarrow -rules.

- (1) The \vee -introduction rule says that if P (or Q) has been proved from Γ , then $P \vee Q$ is also provable from Γ . Again, this makes sense intuitively as $P \vee Q$ is "weaker" than P and Q.
- (2) The \vee -elimination rule formalizes the *proof-by-cases* method. It is a more subtle rule. The idea is that if we know that in the case where P is already assumed to be provable and similarly, in the case where Q is already assumed to be provable that we can prove R (also using premises in Γ), then if $P \vee Q$ is also provable from Γ , as we have "covered both cases," it should be possible to prove R from Γ only (i.e., the premises P and Q are discarded). For example, if remain1(n) is the proposition that asserts n is a natural number of the form 4k + 1 and remain3(n) is the proposition that asserts n is

a natural number of the form 4k + 3 (for some natural number k), then we can prove the implication

 $(\operatorname{remain1}(n) \lor \operatorname{remain3}(n)) \Rightarrow \operatorname{odd}(n),$

where odd(n) asserts that n is odd, namely, that n is of the form 2h + 1 for some h.

To prove the above implication we first assume the premise, remain $1(n) \lor remain 3(n)$. Next, we assume each of the alternatives in this proposition.

When we assume remain 1(n), we have n = 4k + 1 = 2(2k) + 1 for some k, so n is odd. When we assume remain 3(n), we have n = 4k + 3 = 2(2k + 1) + 1, so again, n is odd. By \lor -elimination, we conclude that odd(n) follows from the premise remain $1(n) \lor$ remain 3(n), and by \Rightarrow -introduction, we obtain a proof of our implication.

- (3) The \perp -elimination rule formalizes the principle that once a false statement has been established, then anything should be provable.
- (4) The ¬-introduction rule is a proof-by-contradiction principle applied to negated propositions. In order to prove ¬P, we assume P and derive a contradiction (⊥). It is a more restrictive principle than the classical proof-by-contradiction rule (RAA). Indeed, if the proposition P to be proven is not a negation (P is not of the form ¬Q), then the ¬-introduction rule cannot be applied. On the other hand, the classical proof-by-contradiction rule can be applied but we have to assume ¬P as a premise. For further comments on the difference between the ¬-introduction rule and the classical proof-by-contradiction rule, see Section 2.8.
- (5) The proof-by-contradiction rule formalizes the method of proof by contradiction. That is, in order to prove that P can be deduced from some premises Γ, one may assume the negation ¬P of P (intuitively, assume that P is false) and then derive a contradiction from Γ and ¬P (i.e., derive falsity). Then P actually follows from Γ without using ¬P as a premise, that is, ¬P is discharged. For example, let us prove by contradiction that if n² is odd, then n itself must be odd, where n is a natural number.

According to the proof-by-contradiction rule, let us assume that n is not odd, which means that n is even. (Actually, in this step, we are using a property of the natural numbers that is proven by induction but let's not worry about that right now. A proof is given in Section 2.20.) But to say that n is even means that n = 2k for some k and then $n^2 = 4k^2 = 2(2k^2)$, so n^2 is even, contradicting the assumption that n^2 is odd. By the proof-by-contradiction rule, we conclude that n must be odd.

Remark: If the proposition P to be proven is of the form $\neg Q$, then if we use the proofby-contradiction rule, we have to assume the premise $\neg \neg Q$ and then derive a contradiction. Because we are using classical logic, we often make implicit use of the fact that $\neg \neg Q$ is equivalent to Q (see Proposition 2.2) and instead of assuming $\neg \neg Q$ as a premise, we assume Q as a premise. But then, observe that we are really using \neg -introduction.

In summary, when trying to prove a proposition P by contradiction, proceed as follows.



Figure 2.2: L. E. J. Brouwer, 1881–1966.

- (1) If P is a negated formula (P is of the form $\neg Q$), then use the \neg -introduction rule; that is, assume Q as a premise and derive a contradiction.
- (2) If P is not a negated formula, then use the proof-by-contradiction rule; that is, assume $\neg P$ as a premise and derive a contradiction.

2.7 Constructivism Versus Classical Logic

Most people, I believe, will be comfortable with the rules of minimal logic and will agree that they constitute a "reasonable" formalization of the rules of reasoning involving \Rightarrow , \land , and \lor . Indeed, these rules seem to express the intuitive meaning of the connectives \Rightarrow , \land , and \lor . However, some may question the two rules \perp -elimination and proof-by-contradiction. Indeed, their meaning is not as clear and, certainly, the proof-by-contradiction rule introduces a form of indirect reasoning that is somewhat worrisome.

The problem has to do with the meaning of disjunction and negation and more generally, with the notion of *constructivity* in mathematics. In fact, in the early 1900s, some mathematicians, especially L. Brouwer (1881–1966), questioned the validity of the proof-bycontradiction rule, among other principles.

Two specific cases illustrate the problem, namely, the propositions

$$P \lor \neg P$$
 and $\neg \neg P \Rightarrow P$.

As we show shortly, the above propositions are both provable in classical logic; see Proposition 2.1 and Proposition 2.2.

Now, Brouwer and some mathematicians belonging to his school of thought (the so-called "intuitionists" or "constructivists") advocate that in order to prove a disjunction $P \lor Q$ (from some premises Γ), one has to either *exhibit* a proof of P or a proof or Q (from Γ). However, it can be shown that this fails for $P \lor \neg P$. The fact that $P \lor \neg P$ is provable (in classical logic) **does not** imply (in general) that either P is provable or that $\neg P$ is provable. That $P \lor \neg P$ is provable is sometimes called the *principle (or law) of the excluded middle*. In intuitionistic logic, $P \lor \neg P$ is **not** provable (in general). Of course, if one gives up the proof-by-contradiction rule, then fewer propositions become provable. On the other hand,

one may claim that the propositions that remain provable have more constructive proofs and thus feel on safer grounds.

A similar controversy arises with the proposition $\neg \neg P \Rightarrow P$ (double-negation rule). If we give up the proof-by-contradiction rule, then this formula is no longer provable (i.e., $\neg \neg P$ is no longer equivalent to P). Perhaps this relates to the fact that if one says "I don't have no money," then this does not mean that this person has money. (Similarly, with "I can't get no satisfaction.") However, note that one can still prove $P \Rightarrow \neg \neg P$ in minimal logic (try doing it). Even stranger, $\neg \neg \neg P \Rightarrow \neg P$ is provable in intuitionistic (and minimal) logic, so $\neg \neg \neg P$ and $\neg P$ are equivalent intuitionistically.

Remark: Suppose we have a deduction

$$\begin{array}{c} \Gamma, \neg P \\ \mathcal{D} \\ \bot \end{array}$$

as in the proof-by-contradiction rule. Then by ¬-introduction, we get a deduction of $\neg \neg P$ from Γ :

So, if we knew that $\neg \neg P$ was equivalent to P (actually, if we knew that $\neg \neg P \Rightarrow P$ is provable), then the proof-by-contradiction rule would be justified as a valid rule (it follows from modus ponens). We can view the proof-by-contradiction rule as a sort of act of faith that consists in saying that if we can derive an inconsistency (i.e., chaos) by assuming the falsity of a statement P, then P has to hold in the first place. It is not so clear that such an act of faith is justified and the intuitionists refuse to take it.

Constructivity in mathematics is a fascinating subject but it is a topic that is really outside the scope of this book. What we hope is that our brief and very incomplete discussion of constructivity issues made the reader aware that the rules of logic are not cast in stone and that, in particular, there isn't **only one** logic.

We feel safe in saying that most mathematicians work with classical logic and only a few of them have reservations about using the proof-by-contradiction rule. Nevertheless, intuitionistic logic has its advantages, especially when it comes to proving the correctness of programs (a branch of computer science). We come back to this point several times in this book.

In the rest of this section, we make further useful remarks about (classical) logic and give some explicit examples of proofs illustrating the inference rules of classical logic. We begin by proving that $P \vee \neg P$ is provable in classical logic.

Proposition 2.1. The proposition $P \lor \neg P$ is provable in classical logic.

Proof. We prove that $P \lor (P \Rightarrow \bot)$ is provable by using the proof-by-contradiction rule as shown below.

$$\begin{array}{ccc} & & \frac{P^{x}}{P^{\vee}} & & \forall \text{-intro} \\ \\ & & \frac{((P \lor (P \Rightarrow \bot)) \Rightarrow \bot)^{y}}{P \lor (P \Rightarrow \bot)} & & \\ \hline & & \frac{\bot}{P \Rightarrow \bot} & & \forall \text{-intro} \\ \hline & & \frac{P \Rightarrow \bot}{P \lor (P \Rightarrow \bot)} & & \forall \text{-intro} \\ \hline & & \frac{\bot}{P \lor (P \Rightarrow \bot)} & & y \text{ (by-contra)} \\ \hline & & P \lor (P \Rightarrow \bot) & & & \\ \hline & & P \lor (P \Rightarrow \bot) & & & \\ \hline \end{array}$$

Next, we consider the equivalence of P and $\neg \neg P$.

Proposition 2.2. The proposition $P \Rightarrow \neg \neg P$ is provable in minimal logic. The proposition $\neg \neg P \Rightarrow P$ is provable in classical logic. Therefore, in classical logic, P is equivalent to $\neg \neg P$.

Proof. We leave $P \Rightarrow \neg \neg P$ is provable in minimal logic as an exercise. Below is a proof of $\neg \neg P \Rightarrow P$ using the proof-by-contradiction rule.

$$\frac{((P \Rightarrow \bot) \Rightarrow \bot)^{y} \qquad (P \Rightarrow \bot)^{x}}{\frac{\bot}{P} \qquad x \text{ (by-contra)}}$$

$$\frac{((P \Rightarrow \bot) \Rightarrow \bot) \Rightarrow P \qquad \qquad \square$$

The next proposition shows why \perp can be viewed as the "ultimate" contradiction.

Proposition 2.3. In intuitionistic logic, the propositions \perp and $P \land \neg P$ are equivalent for all P. Thus, \perp and $P \land \neg P$ are also equivalent in classical propositional logic

Proof. We need to show that both $\bot \Rightarrow (P \land \neg P)$ and $(P \land \neg P) \Rightarrow \bot$ are provable in intuitionistic logic. The provability of $\bot \Rightarrow (P \land \neg P)$ is an immediate consequence or \bot -elimination, with $\Gamma = \emptyset$. For $(P \land \neg P) \Rightarrow \bot$, we have the following proof.

$$\frac{(P \wedge \neg P)^{x}}{\neg P} \quad \frac{(P \wedge \neg P)^{x}}{P}$$

$$\frac{\bot}{(P \wedge \neg P) \Rightarrow \bot} \quad x \qquad \Box$$

So, in intuitionistic logic (and also in classical logic), \perp is equivalent to $P \land \neg P$ for all P. This means that \perp is the "ultimate" contradiction; it corresponds to total inconsistency. By the way, we could have the bad luck that the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ or even

 $\mathcal{N}_m^{\Rightarrow,\wedge,\vee,\perp}$) is *inconsistent*, that is, \perp is provable. Fortunately, this is not the case, although this is hard to prove. (It is also the case that $P \vee \neg P$ and $\neg \neg P \Rightarrow P$ are **not** provable in intuitionistic logic, but this too is hard to prove.)

2.8 Clearing Up Differences Among ¬-Introduction, ⊥-Elimination, and RAA

The differences between the rules, \neg -introduction, \bot -elimination, and (RAA), the proofby-contradiction rule, are often unclear to the uninitiated reader and this tends to cause confusion. In this section, we try to clear up some common misconceptions about these rules.

Confusion 1. Why is RAA not a special case of \neg -introduction?

$$\begin{array}{ccc} \Gamma, P^{x} & & \Gamma, \neg P^{x} \\ \mathcal{D} & & \mathcal{D} \\ \frac{\bot}{\neg P} & x \left(\neg \text{-intro}\right) & & \frac{\bot}{P} & x \left(\text{RAA}\right) \end{array}$$

The only apparent difference between \neg -introduction (on the left) and RAA (on the right) is that in RAA, the premise P is negated but the conclusion is not, whereas in \neg -introduction the premise P is not negated but the conclusion is.

The important difference is that the conclusion of RAA is **not** negated. If we had applied \neg -introduction instead of RAA on the right, we would have obtained

$$\begin{array}{c} \Gamma, \neg P^{x} \\ \mathcal{D} \\ \hline \\ \neg \neg P \end{array} \quad x \left(\neg \text{-intro} \right)$$

where the conclusion would have been $\neg \neg P$ as opposed to P. However, as we already said earlier, $\neg \neg P \Rightarrow P$ is **not** provable intuitionistically. Consequently, RAA **is not** a special case of \neg -introduction. On the other hand, one may view \neg -introduction as a "constructive" version of RAA applying to negated propositions (propositions of the form $\neg P$).

Confusion 2. Is there any difference between \perp -elimination and RAA?

$$\begin{array}{ccc}
\Gamma & & & \Gamma, \neg P^{x} \\
\mathcal{D} & & & \mathcal{D} \\
\frac{\bot}{P} & (\bot \text{-elim}) & & & \frac{\bot}{P} & x (\text{RAA})
\end{array}$$

The difference is that \perp -elimination does not discharge any of its premises. In fact, RAA is a stronger rule that implies \perp -elimination as we now demonstrate.

RAA implies \perp -Elimination

Suppose we have a deduction

 $\Gamma \mathcal{D} \ \perp$

Then for any proposition P, we can add the premise $\neg P$ to every leaf of the above deduction tree and we get the deduction tree

 $\Gamma, \neg P$ \mathcal{D}' \perp

We can now apply RAA to get the following deduction tree of P from Γ (because $\neg P$ is discharged), which simulates \perp -elimination.

$$\begin{array}{l} \Gamma, \neg P^{x} \\ \mathcal{D}' \\ \frac{\bot}{P} & x \, (\text{RAA}) \end{array}$$

The above considerations also show that RAA is obtained from \neg -introduction by adding the new rule of $\neg \neg$ -elimination (also called *double-negation elimination*):

$$\frac{\mathcal{D}}{\frac{\neg \neg P}{P}} \quad (\neg \neg \text{-elimination})$$

Indeed, we now have the following deduction which is equivalent to RAA.

Some authors prefer adding the $\neg\neg$ -elimination rule to intuitionistic logic instead of RAA in order to obtain classical logic. As we just demonstrated, the two additions are equivalent: by adding either RAA or $\neg\neg$ -elimination to intuitionistic logic, we get classical logic.

There is another way to obtain RAA from the rules of intuitionistic logic, this time using the propositions of the form $P \vee \neg P$. We saw in Proposition 2.1 that all formulae of the form $P \vee \neg P$ are provable in classical logic (using RAA).

Confusion 3. Are propositions of the form $P \vee \neg P$ provable in intuitionistic logic? The answer is **no**, which may be disturbing to some readers. In fact, it is quite difficult to prove that propositions of the form $P \vee \neg P$ are not provable in intuitionistic logic. One method consists in using the fact that intuitionistic proofs can be normalized (see Section 2.13 for more on normalization of proofs). Another method uses Kripke models (see Section 2.12 and van Dalen [75]).

Part of the difficulty in understanding, at some intuitive level, why propositions of the form $P \vee \neg P$ are not provable in intuitionistic logic is that the notion of truth based on the truth values **true** and **false**, is deeply rooted in all of us. In this frame of mind, it seems ridiculous to question the provability of $P \vee \neg P$, because its truth value is **true** whether P is assigned the value **true** or **false**. Classical two-valued truth-value semantics is too crude for intuitionistic logic.

Another difficulty is that it is tempting to equate the notion of truth and the notion of provability. Unfortunately, because classical truth-value semantics is too crude for intuitionistic logic, there are propositions that are universally true (i.e., they evaluate to **true** for all possible truth assignments of the atomic letters in them) and yet they are **not** provable intuitionistically. The propositions $P \vee \neg P$ and $\neg \neg P \Rightarrow P$ are such examples.

One of the major motivations for advocating intuitionistic logic is that it yields proofs that are more constructive than classical proofs. For example, in classical logic, when we prove a disjunction $P \vee Q$, we generally can't conclude that either P or Q is provable, as exemplified by $P \vee \neg P$. A more interesting example involving a nonconstructive proof of a disjunction is given in Section 2.9. But in intuitionistic logic, from a proof of $P \vee Q$, it is possible to extract either a proof of P or a proof of Q (and similarly for existential statements; see Section 2.17). This property is not easy to prove. It is a consequence of the normal form for intuitionistic proofs (see Section 2.13).

In brief, besides being a fun intellectual game, intuitionistic logic is only an interesting alternative to classical logic if we care about the constructive nature of our proofs. But then, we are forced to abandon the classical two-valued truth-value semantics and adopt other semantics such as Kripke semantics. If we do not care about the constructive nature of our proofs and if we want to stick to two-valued truth-value semantics, then we should stick to classical logic. Most people do that, so don't feel bad if you are not comfortable with intuitionistic logic.

One way to gauge how intuitionistic logic differs from classical logic is to ask what kind of propositions need to be added to intuitionistic logic in order to get classical logic. It turns out that if all the propositions of the form $P \vee \neg P$ are considered to be axioms, then RAA follows from some of the rules of intuitionistic logic.

RAA Holds in Intuitionistic Logic + All Axioms $P \lor \neg P$.

The proof involves a subtle use of the \perp -elimination and \vee -elimination rules which may be a bit puzzling. Assume, as we do when we use the proof-by-contradiction rule (RAA) that we have a deduction

$$\Gamma, \neg P$$

 \mathcal{D}
 \perp .

Here is the deduction tree demonstrating that RAA is a derived rule.

$$\frac{\Gamma, \neg P^{y}}{\mathcal{D}} \\
\frac{P \lor \neg P}{P} \frac{\frac{P^{x}}{P}}{P} \frac{\frac{\bot}{P}}{x,y} (\bot \text{-elim}) \\
\frac{P \lor \neg P}{P} x,y (\lor \text{-elim})$$

At first glance, the rightmost subtree

$$\begin{array}{c}
\Gamma, \neg P^y \\
\mathcal{D} \\
\stackrel{\perp}{-P} (\bot\text{-elim})
\end{array}$$

appears to use RAA and our argument looks circular. But this is not so because the premise $\neg P$ labeled y is *not* discharged in the step that yields P as conclusion; the step that yields P is a \perp -elimination step. The premise $\neg P$ labeled y is actually discharged by the \lor -elimination rule (and so is the premise P labeled x). So our argument establishing RAA is not circular after all.

In conclusion, intuitionistic logic is obtained from classical logic by taking away the proofby-contradiction rule (RAA). In this more restrictive proof system, we obtain more constructive proofs. In that sense, the situation is better than in classical logic. The major drawback is that we can't think in terms of classical truth-value semantics anymore.

Conversely, classical logic is obtained from intuitionistic logic in at least three ways:

- 1. Add the proof-by-contradiction rule (RAA).
- 2. Add the $\neg\neg$ -elimination rule.
- 3. Add all propositions of the form $P \lor \neg P$ as axioms.

2.9 De Morgan Laws and Other Rules of Classical Logic

In Section 1.7, we discussed the de Morgan laws. Now that we also know about intuitionistic logic, we revisit these laws.

Proposition 2.4. The following equivalences (de Morgan laws) are provable in classical logic.

$$\neg (P \land Q) \equiv \neg P \lor \neg Q$$
$$\neg (P \lor Q) \equiv \neg P \land \neg Q.$$

In fact, $\neg(P \lor Q) \equiv \neg P \land \neg Q$ and $(\neg P \lor \neg Q) \Rightarrow \neg(P \land Q)$ are provable in intuitionistic logic. The proposition $(P \land \neg Q) \Rightarrow \neg(P \Rightarrow Q)$ is provable in intuitionistic logic and $\neg(P \Rightarrow Q) \Rightarrow (P \land \neg Q)$ is provable in classical logic. Therefore, $\neg(P \Rightarrow Q)$ and $P \land \neg Q$ are equivalent in classical logic. Furthermore, $P \Rightarrow Q$ and $\neg P \lor Q$ are equivalent in classical logic and $(\neg P \lor Q) \Rightarrow (P \Rightarrow Q)$ is provable in intuitionistic logic.

Proof. We only prove the very last part of Proposition 2.4, leaving the other parts as a series of exercises. Here is an intuitionistic proof of $(\neg P \lor Q) \Rightarrow (P \Rightarrow Q)$.

$$\begin{array}{cccc} & \frac{\neg P^z & P^x}{\overset{\perp}{Q}} & & \frac{P^y & Q^t}{Q} \\ & \frac{(\neg P \lor Q)^w}{P \Rightarrow Q} & x & \frac{P^y & Q^t}{Q} & y \\ \hline & \frac{(\neg P \lor Q)^w}{P \Rightarrow Q} & & P \Rightarrow Q & z,t \\ \hline & \frac{P \Rightarrow Q}{(\neg P \lor Q) \Rightarrow (P \Rightarrow Q)} & w \end{array}$$

Here is a classical proof of $(P \Rightarrow Q) \Rightarrow (\neg P \lor Q)$.

				$\neg P^x$
		$(\neg(\neg P \lor Q$	$))^{y}$	$\overline{\neg P \lor Q}$
	$(P \Rightarrow Q)^z$		$\frac{\perp}{P}$	x RAA
	(, , , ,	Q		
$\frac{(\neg(\neg P \lor Q))^y}{(\neg(\neg P \lor Q))^y}$		$\neg P \lor Q$		
	$\frac{\bot}{\neg P \lor}$	\overline{Q} <i>y</i> RAA		
	$(P \Rightarrow Q) \Rightarrow ($	$(\neg P \lor Q)$	5	
C 1 C				

The other proofs are left as exercises.

Propositions 2.2 and 2.4 show a property that is very specific to classical logic, namely, that the logical connectives $\Rightarrow, \land, \lor, \neg$ are not independent. For example, we have $P \land Q \equiv \neg(\neg P \lor \neg Q)$, which shows that \land can be expressed in terms of \lor and \neg . In intuitionistic logic, \land and \lor cannot be expressed in terms of each other via negation.

The fact that the logical connectives $\Rightarrow, \land, \lor, \neg$ are not independent in classical logic suggests the following question. Are there propositions, written in terms of \Rightarrow only, that are provable classically but not provable intuitionistically?

The answer is yes. For instance, the proposition $((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$ (known as *Peirce's law*) is provable classically, but it can be shown that it is not provable intuitionistically. Here is a proof of $((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$ using RAA.

$$\begin{array}{c} \displaystyle \frac{\neg P^y \quad P^z}{\overset{\perp}{Q}} \\ \\ \displaystyle \frac{((P \Rightarrow Q) \Rightarrow P)^x \quad P \Rightarrow Q}{P} \\ \\ \displaystyle \frac{\neg P^y \quad P}{\overset{\perp}{P} y \ (\text{RAA})} \\ \\ \displaystyle \frac{\neg P \quad P}{((P \Rightarrow Q) \Rightarrow P) \Rightarrow P} \\ \end{array}$$

On the other hand, if we add all instances $((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$ of Peirce's law as axioms to intuitionictic logic, then (RAA) is derivable. In fact, it suffices to add the special case of Peirce's law with $Q = \bot$, namely

$$((P \Rightarrow \bot) \Rightarrow P) \Rightarrow P \equiv (\neg P \Rightarrow P) \Rightarrow P.$$

Assume, as we do when we use the proof-by-contradiction rule (RAA) that we have a deduction

$$\Gamma, \neg P$$

 \mathcal{D}
 \bot

Here is the deduction tree demonstrating that RAA is a derived rule, where the leftmost leaf is the axiom

$$(\neg P \Rightarrow P) \Rightarrow P.$$

$$\begin{array}{c} \Gamma, \neg P^{y} \\ \mathcal{D} \\ \frac{-\frac{1}{P}}{P} (\bot \text{-elim}) \\ \hline P \\ (\neg P \Rightarrow P) \Rightarrow P \\ \hline P \\ \hline \end{array} \begin{array}{c} x \ (\Rightarrow \text{-intro}) \\ (\Rightarrow \text{-elim}) \end{array}$$

In addition to the proof-by-cases method and the proof-by-contradiction method, we also have the proof-by-contrapositive method valid in classical logic:

Proof-by-contrapositive rule:

$$\Gamma, \neg Q^{x}$$
$$\mathcal{D}$$
$$\neg P$$
$$\overline{P \Rightarrow Q} \quad x$$

This rule says that in order to prove an implication $P \Rightarrow Q$ (from Γ), one may assume $\neg Q$ as proven, and then deduce that $\neg P$ is provable from Γ and $\neg Q$. This inference rule is valid in classical logic because we can construct the following deduction.

$$\begin{array}{c}
 \Gamma, \neg Q^{x} \\
 \overline{\mathcal{D}} \\
 \frac{\neg P \quad P^{y}}{-\frac{\bot}{Q} \quad x \quad (\text{RAA})} \\
 \frac{Q}{\overline{P \Rightarrow Q}} \quad y
 \end{array}$$

As as example of the proof-by-contrapositive method, we prove that if an integer n^2 is even, then n must be even.

Observe that if an integer is not even, then it is odd (and vice versa). This fact may seem quite obvious but to prove it actually requires using *induction* (which we haven't officially met yet). A rigorous proof is given in Section 2.20.

Now the contrapositive of our statement is: if n is odd, then n^2 is odd. Here, P is " n^2 is even" and Q is n is even. But to say that n is odd is to say that n = 2k + 1 and then $n^2 = (2k+1)^2 = 4k^2 + 4k + 1 = 2(2k^2 + 2k) + 1$, which shows that n^2 is odd.

As it is, because the above proof uses the proof-by-contrapositive method, it is not constructive. Thus, the question arises, is there a constructive proof of the above fact?

Indeed there is a constructive proof if we observe that every integer n is either even or odd but not both. Now, one might object that we just relied on the law of the excluded middle but there is a way to circumvent this problem by using *induction*; see Section 2.20 for a rigorous proof.

Now, because an integer is odd iff it is not even, we may proceed to prove that if n^2 is even, then n is not odd, by using our constructive version of the proof-by-contradiction principle, namely, \neg -introduction.

Proof. Therefore, assume that n^2 is even and n is odd. Then n = 2k + 1, which implies that $n^2 = 4k^2 + 4k + 1 = 2(2k^2 + 2k) + 1$, an odd number, contradicting the fact that n^2 is assumed to be even.

The next proposition collects a list of equivalences involving conjunction and disjunction that are used all the time. Proofs of these propositions are left as exercises (see the problems).

Proposition 2.5. All the propositions below are provable intuitionistically:

$$P \lor P \equiv P$$
$$P \land P \equiv P$$
$$P \lor Q \equiv Q \lor P$$
$$P \land Q \equiv Q \land P$$

The last two assert the commutativity of \lor and \land . We have distributivity of \land over \lor and \lor over \land :

$$P \land (Q \lor R) \equiv (P \land Q) \lor (P \land R)$$
$$P \lor (Q \land R) \equiv (P \lor Q) \land (P \lor R).$$

We have associativity of \land and \lor :

$$P \land (Q \land R) \equiv (P \land Q) \land R$$
$$P \lor (Q \lor R) \equiv (P \lor Q) \lor R.$$

2.10 Formal Versus Informal Proofs

As we said before, *it is practically impossible to write formal proofs* (i.e., proofs written as proof trees using the rules of one of the systems presented earlier) of "real" statements that are not "toy propositions." This is because it would be extremely tedious and timeconsuming to write such proofs and these proofs would be huge and thus, very hard to read.

What we do instead is to construct "informal" proofs, in which we still make use of the logical rules that we have presented but we take shortcuts and sometimes we even omit proof steps (some elimination rules, such as \wedge -elimination and some introduction rules, such as \vee -introduction) and we use a natural language (here, presumably, English) rather than formal symbols (we say "and" for \wedge , "or" for \vee , etc.). We refer the reader to Section 1.8 for a discussion of these issues. We also urge our reader to read Chapter 3 of Gowers [31], which contains very illuminating remarks about the notion of proof in mathematics.

Here is a concrete example illustrating the usefulness of auxiliary lemmas in constructing informal proofs.

Say, we wish to prove the implication

$$\neg (P \land Q) \Rightarrow ((\neg P \land \neg Q) \lor (\neg P \land Q) \lor (P \land \neg Q)).$$
(*)

It can be shown that the above proposition is not provable intuitionistically, so we have to use the proof-by-contradiction method in our proof. One quickly realizes that any proof ends up re-proving basic properties of \land and \lor , such as associativity, commutativity, idempotence, distributivity, and so on, some of the de Morgan laws, and that the complete proof is very large. However, if we allow ourselves to use the de Morgan laws, as well as various basic properties of \land and \lor , such as distributivity,

$$(A \land B) \lor C \equiv (A \land C) \lor (B \land C),$$

commutativity of \land and \lor $(A \land B \equiv B \land A, A \lor B \equiv B \lor A)$, associativity of \land and \lor $(A \land (B \land C) \equiv (A \land B) \land C, A \lor (B \lor C) \equiv (A \lor B) \lor C)$, and the idempotence of \land and \lor

 $(A \land A \equiv A, A \lor A \equiv A)$, then we get

$$\begin{split} (\neg P \land \neg Q) \lor (\neg P \land Q) \lor (P \land \neg Q) \\ &\equiv (\neg P \land \neg Q) \lor (\neg P \land \neg Q) \lor (\neg P \land Q) \lor (P \land \neg Q) \\ &\equiv (\neg P \land \neg Q) \lor (\neg P \land Q) \lor (\neg P \land \neg Q) \lor (P \land \neg Q) \\ &\equiv (\neg P \land (\neg Q \lor Q)) \lor (\neg P \land \neg Q) \lor (P \land \neg Q) \\ &\equiv \neg P \lor (\neg P \land \neg Q) \lor (P \land \neg Q) \equiv \neg P \lor ((\neg P \lor P) \land \neg Q) \equiv \neg P \lor \neg Q, \end{split}$$

where we make implicit uses of commutativity and associativity, and the fact that $R \wedge (P \vee \neg P) \equiv R$, and by de Morgan,

$$\neg (P \land Q) \equiv \neg P \lor \neg Q,$$

using auxiliary lemmas, we end up proving (*) without too much pain.

2.11 Truth-Value Semantics for Classical Logic Soundness and Completeness

In Section 1.9, we introduced the truth-value semantics for classical propositional logic. The logical connectives \Rightarrow , \land , \lor , \neg and \equiv can be interpreted as Boolean functions, that is, functions whose arguments and values range over the set of *truth values*,

$$BOOL = \{true, false\}.$$

P	Q	$P \Rightarrow Q$	$P \wedge Q$	$P \lor Q$	$\neg P$	$P \equiv Q$
true	true	true	true	true	false	true
true	false	false	false	true	false	false
false	true	true	false	true	true	false
false	false	true	false	false	true	true

These functions are given by the following *truth table*.

Now, any proposition P built up over the set of atomic propositions **PS** (our propositional symbols) contains a finite set of propositional letters, say

$$\{P_1,\ldots,P_m\}.$$

If we assign some truth value (from **BOOL**) to each symbol P_i , then we can "compute" the *truth value* of P under this assignment by using recursively using the truth table above.

For example, the proposition $\mathbf{P}_1 \Rightarrow (\mathbf{P}_1 \Rightarrow \mathbf{P}_2)$, under the truth assignment v given by

$$\mathbf{P}_1 = \mathbf{true}, \ \mathbf{P}_2 = \mathbf{false},$$

evaluates to **false**; see Section 1.9.

The values of a proposition can be determined by creating a *truth table*, in which a proposition is evaluated by computing recursively the truth values of its subexpressions. See Section 1.9.

The truth table of a proposition containing m variables has 2^m rows. When m is large, 2^m is very large, and computing the truth table of a proposition P may not be practically feasible. Even the problem of finding whether there is a truth assignment that makes P true is hard.

Definition 2.9. We say that a proposition P is *satisfiable* iff it evaluates to **true** for *some* truth assignment (taking values in **BOOL**) of the propositional symbols occurring in P, and otherwise we say that it is *unsatisfiable*. A proposition P is *valid* (or a *tautology*) iff it evaluates to **true** for *all* truth assignments of the propositional symbols occurring in P.

Observe that a proposition P is valid if in the truth table for P all the entries in the column corresponding to P have the value **true**. The proposition P is satisfiable if some entry in the column corresponding to P has the value **true**.

The problem of deciding whether a proposition is satisfiable is called the *satisfiability problem* and is sometimes denoted by SAT. The problem of deciding whether a proposition is valid is called the *validity problem*.

Example 2.3. For example, the proposition

$$P = (\mathbf{P}_1 \lor \neg \mathbf{P}_2 \lor \neg \mathbf{P}_3) \land (\neg \mathbf{P}_1 \lor \neg \mathbf{P}_3) \land (\mathbf{P}_1 \lor \mathbf{P}_2 \lor \mathbf{P}_4) \land (\neg \mathbf{P}_3 \lor \mathbf{P}_4) \land (\neg \mathbf{P}_1 \lor \mathbf{P}_4) \land (\neg \mathbf{P}_4 \lor \mathbf{P}_4) \land (\neg \mathbf{P}_4) \land (\neg \mathbf{P}_4 \lor \mathbf{P}_4) \land (\neg \mathbf{P}_4) \land (\neg$$

is satisfiable because it evaluates to **true** under the truth assignment $\mathbf{P}_1 = \mathbf{true}, \mathbf{P}_2 = \mathbf{false}, \mathbf{P}_3 = \mathbf{false}, \text{ and } \mathbf{P}_4 = \mathbf{true}.$

Example 2.4. On the other hand, the proposition

$$Q = (\mathbf{P}_1 \lor \mathbf{P}_2 \lor \mathbf{P}_3) \land (\neg \mathbf{P}_1 \lor \mathbf{P}_2) \land (\neg \mathbf{P}_2 \lor \mathbf{P}_3) \land (\mathbf{P}_1 \lor \neg \mathbf{P}_3) \land (\neg \mathbf{P}_1 \lor \neg \mathbf{P}_2 \lor \neg \mathbf{P}_3)$$

is unsatisfiable, as one can verify by trying all eight truth assignments for $\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3$.

The reader should also verify that the proposition

$$R = (\neg \mathbf{P}_1 \land \neg \mathbf{P}_2 \land \neg \mathbf{P}_3) \lor (\mathbf{P}_1 \land \neg \mathbf{P}_2) \lor (\mathbf{P}_2 \land \neg \mathbf{P}_3) \lor (\neg \mathbf{P}_1 \land \mathbf{P}_3) \lor (\mathbf{P}_1 \land \mathbf{P}_2 \land \mathbf{P}_3)$$

is valid (observe that the proposition R is the negation of the proposition Q).

The satisfiability problem is a famous problem in computer science because of its complexity. Try it; solving it is not as easy as you think. The difficulty is that if a proposition P contains n distinct propositional letters, then there are 2^n possible truth assignments and checking all of them is practically impossible when n is large.

In fact, the satisfiability problem turns out to be an *NP-complete* problem, a very important concept that you will learn about in a course on the theory of computation and complexity. Very good expositions of this kind of material are found in Hopcroft, Motwani,

and Ullman [37] and Lewis and Papadimitriou [50]. The validity problem is also important and it is related to SAT. Indeed, it is easy to see that a proposition P is valid iff $\neg P$ is unsatisfiable.

What's the relationship between validity and provability in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$)?

Remarkably, in classical logic, *validity and provability are equivalent*. In order to prove the above claim, we need to do two things:

- (1) Prove that if a proposition P is provable in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or the system $\mathcal{N}\mathcal{G}_c^{\Rightarrow,\wedge,\vee,\perp}$), then it is valid. This is known as *soundness* or *consistency* (of the proof system).
- (2) Prove that if a proposition P is valid, then it has a proof in the system $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_{c}^{\Rightarrow,\wedge,\vee,\perp}$). This is known as the *completeness* (of the proof system).

In general, it is relatively easy to prove (1), but proving (2) can be quite complicated. In fact, some proof systems are *not* complete with respect to certain semantics. For instance, the proof system for intuitionistic logic $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$) is *not complete* with respect to truth-value semantics. As an example, $((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$ (known as *Peirce's law*), is valid but it can be shown that it cannot be proven in intuitionistic logic.

In this book, we content ourselves with soundness.

Proposition 2.6. (Soundness of $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$) If a proposition P is provable in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$), then it is valid (according to the truth-value semantics).

Sketch of Proof. It is enough to prove that if there is a deduction of a proposition P from a set of premises Γ , then for every truth assignment for which all the propositions in Γ evaluate to **true**, then P evaluates to **true**. However, this is clear for the axioms and every inference rule preserves that property.

Now, if P is provable, a proof of P has an empty set of premises and so P evaluates to **true** for all truth assignments, which means that P is valid.

Theorem 2.7. (Completeness of $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{N}\mathcal{G}_c^{\Rightarrow,\wedge,\vee,\perp}$) If a proposition P is valid (according to the truth-value semantics), then P is provable in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{N}\mathcal{G}_c^{\Rightarrow,\wedge,\vee,\perp}$).

Proofs of completeness for classical logic can be found in van Dalen [75] or Gallier [24] (but for a different proof system).

Soundness (Proposition 2.6) has a very useful consequence: in order to prove that a proposition P is not provable, it is enough to find a truth assignment for which P evaluates to **false**. We say that such a truth assignment is a *counterexample* for P (or that P can be *falsified*). For example, no propositional symbol \mathbf{P}_i is provable because it is falsified by the truth assignment $\mathbf{P}_i = \mathbf{false}$.

The soundness of the proof system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$) also has the extremely important consequence that \perp cannot be proven in this system, which means that contradictory statements cannot be derived.

This is by no means obvious at first sight, but reassuring. It is also possible to prove that the proof system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ is consistent (*i.e.*, \perp cannot be proven) by purely proof-theoretic means involving proof normalization (see Section 2.13), but this requires a lot more work.

Note that completeness amounts to the fact that *every unprovable formula has a counterexample*. Also, in order to show that a proposition is classically provable, it suffices to compute its truth table and check that the proposition is valid. This may still be a lot of work, but it is a more "mechanical" process than attempting to find a proof.

Example 2.5. For example, here is a truth table showing that $(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) \equiv (\neg \mathbf{P}_1 \lor \mathbf{P}_2)$ is valid.

\mathbf{P}_1	\mathbf{P}_2	$\mathbf{P}_1 \Rightarrow \mathbf{P}_2$	$\neg \mathbf{P}_1 \lor \mathbf{P}_2$	$(\mathbf{P}_1 \Rightarrow \mathbf{P}_2) \equiv (\neg \mathbf{P}_1 \lor \mathbf{P}_2)$
true	true	true	true	true
true	false	false	false	true
false	true	true	true	true
false	false	true	true	true

Remark: Truth-value semantics is not the right kind of semantics for intuitionistic logic; it is too coarse. A more subtle kind of semantics is required. Among the various semantics for intuitionistic logic, one of the most natural is the notion of the *Kripke model*. Then again, soundness and completeness hold for intuitionistic proof systems (see Section 2.12 and van Dalen [75]).

2.12 Kripke Models for Intuitionistic Logic; Soundness and Completeness

In this section, we briefly describe the semantics of intuitionistic propositional logic in terms of Kripke models.

This section has been included to quench the thirst of those readers who can't wait to see what kind of decent semantics can be given for intuitionistic propositional logic and it can be safely omitted.

In classical truth-value semantics based on **BOOL** = {**true**, **false**}, we might say that truth is absolute. The idea of Kripke semantics is that there is a set of worlds (or states) W together with a partial ordering \leq on W, and that truth depends on which world we are in. Furthermore, as we "go up" from a world u to a world v with $u \leq v$, truth "can only increase," that is, whatever is true in world u remains true in world v. Also, the truth of some propositions, such as $P \Rightarrow Q$ or $\neg P$, depends on "future worlds." With this type of semantics, which is no longer absolute, we can capture exactly the essence of intuitionistic logic. We now make these ideas precise.

Definition 2.10. A Kripke model for intuitionistic propositional logic is a pair $\mathcal{K} = (W, \varphi)$, where W is a partially ordered (nonempty) set called a set of worlds and φ is a function



Figure 2.3: Saul Kripke, 1940–.

 $\varphi: W \to \mathbf{BOOL}^{\mathbf{PS}}$, such that for every $u \in W$, the function $\varphi(u): \mathbf{PS} \to \mathbf{BOOL}$ is an assignment of truth values to the propositional symbols in \mathbf{PS} satisfying the following property. For all $u, v \in W$, for all $\mathbf{P}_i \in \mathbf{PS}$,

if $u \leq v$ and $\varphi(u)(\mathbf{P}_i) = \mathbf{true}$, then $\varphi(v)(\mathbf{P}_i) = \mathbf{true}$.

As we said in our informal comments, truth can't decrease when we move from a world u to a world v with $u \leq v$ but truth can increase; it is possible that $\varphi(u)(\mathbf{P}_i) =$ **false** and yet $\varphi(v)(\mathbf{P}_i) =$ **true**.

Example 2.6. If $W = \{0, 1\}$ ordered so that $0 \le 1$ and if φ is given by

$$\varphi(0)(\mathbf{P}_i) = \mathbf{false}$$

 $\varphi(1)(\mathbf{P}_i) = \mathbf{true},$

then $\mathcal{K}_{\text{bad}} = (W, \varphi)$ is a Kripke structure.

We use Kripke models to define the semantics of propositions as follows.

Definition 2.11. Given a Kripke model $\mathcal{K} = (W, \varphi)$, for every $u \in W$ and for every proposition P, we say that P is satisfied by \mathcal{K} at u and we write $\varphi(u)(P) =$ true iff

- (a) If $P = \mathbf{P}_i \in \mathbf{PS}$, then $\varphi(u)(\mathbf{P}_i) = \mathbf{true}$.
- (b) If $P = Q \wedge R$, then $\varphi(u)(Q) =$ true and $\varphi(u)(R) =$ true.
- (c) If $P = Q \lor R$, then $\varphi(u)(Q) =$ true or $\varphi(u)(R) =$ true.
- (d) If $P = Q \Rightarrow R$, then for all v such that $u \le v$, if $\varphi(v)(Q) = \mathbf{true}$, then $\varphi(v)(R) = \mathbf{true}$.
- (e) If $P = \neg Q$, then for all v such that $u \leq v$, $\varphi(v)(Q) =$ **false**,
- (f) $\varphi(u)(\perp) =$ **false**; that is, \perp is not satisfied by \mathcal{K} at u (for any \mathcal{K} and any u).

In the above definition, "and" and "or" have their standard classical meaning as specified in the truth table given in Section 2.11. We say that P is valid in \mathcal{K} (or that \mathcal{K} is a model of P) iff P is satisfied by $\mathcal{K} = (W, \varphi)$ at u for all $u \in W$, and we say that P is intuitionistically valid iff P is valid in every Kripke model \mathcal{K} . When P is satisfied by \mathcal{K} at $u \in W$, we also say that P is true at u in \mathcal{K} .
Note that the truth at $u \in W$ of a proposition of the form $Q \Rightarrow R$ or $\neg Q$ depends on the truth of Q and R at all "future worlds" $v \in W$, with $u \leq v$. In the special case of (d) where $R = \bot$, namely $P = Q \Rightarrow \bot$, we see that for any $u \in W$, $\varphi(u)(Q \Rightarrow \bot) =$ **true** iff $\varphi(u)(\neg Q) =$ **true**, so $\neg Q$ and $Q \Rightarrow \bot$ are indeed semantically equivalent. In particular, for any $u \in W$, we have $\varphi(u)(\neg Q) =$ **false** iff there is some $v \in W$, such that $u \leq v$ and $\varphi(v)(Q) =$ **true**.

Also observe that classical truth-value semantics corresponds to the special case where W consists of a single element (a single world).

Example 2.7. Given the Kripke structure \mathcal{K}_{bad} defined earlier, the reader should check that the proposition $P = (\mathbf{P}_i \vee \neg \mathbf{P}_i)$ has the value **false** at 0 because $\varphi(0)(\mathbf{P}_i) =$ **false**, but $\varphi(1)(\mathbf{P}_i) =$ **true**, so Clause (e) fails for $\neg \mathbf{P}_i$ at u = 0. Therefore, $P = (\mathbf{P}_i \vee \neg \mathbf{P}_i)$ is not valid in \mathcal{K}_{bad} and thus, it is not intuitionistically valid. We escaped the classical truth-value semantics by using a universe with two worlds.

The reader should also check that

$$\varphi(u)(\neg \neg P) = \mathbf{true}$$
 iff for all v such that $u \leq v$
there is some w with $v \leq w$ so that $\varphi(w)(P) = \mathbf{true}$.

This shows that in Kripke semantics, $\neg \neg P$ is weaker than P, in the sense that $\varphi(u)(\neg \neg P) =$ **true** does not necessarily imply that $\varphi(u)(P) =$ **true**. The reader should also check that the proposition $\neg \neg \mathbf{P}_i \Rightarrow \mathbf{P}_i$ is not valid in the Kripke structure \mathcal{K}_{bad} .

As we said in the previous section, Kripke semantics is a perfect fit to intuitionistic provability in the sense that soundness and completeness hold.

Proposition 2.8. (Soundness of $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$) If a proposition P is provable in the system $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$), then it is valid in every Kripke model, that is, it is intuitionistically valid.

Proposition 2.8 is not hard to prove. We consider any deduction of a proposition P from a set of premises Γ and we prove that for every Kripke model $\mathcal{K} = (W, \varphi)$, for every $u \in W$, if every premise in Γ is satisfied by \mathcal{K} at u, then P is also satisfied by \mathcal{K} at u. This is obvious for the axioms and it is easy to see that the inference rules preserve this property.

Completeness also holds, but it is harder to prove (see van Dalen [75]).

Theorem 2.9. (Completeness of $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ and $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$) If a proposition P is intuitionistically valid, then P is provable in the system $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$).

Another proof of completeness for a different proof system for propositional intuitionistic logic (a Gentzen-sequent calculus equivalent to $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$) is given in Takeuti [71]. We find this proof more instructive than van Dalen's proof. This proof also shows that if a proposition P is not intuitionistically provable, then there is a Kripke model \mathcal{K} where W is a finite tree in which P is not valid. Such a Kripke model is called a *counterexample* for P.

Several times in this chapter, we have claimed that certain formulae are not provable in some logical system. What kind of reasoning do we use to validate such claims? In the next section, we briefly address this question as well as related ones.



Figure 2.4: Alonzo Church, 1903–1995 (left) and Alan Turing, 1912–1954 (right).

2.13 Decision Procedures, Proof Normalization

In the previous sections, we saw how the rules of mathematical reasoning can be formalized in various natural deduction systems and we defined a precise notion of proof. We observed that finding a proof for a given proposition was not a simple matter, nor was it to ascertain that a proposition is unprovable. Thus, it is natural to ask the following question.

The Decision Problem: Is there a general procedure that takes any arbitrary proposition P as input, always terminates in a finite number of steps, and tells us whether P is provable?

Clearly, it would be very nice if such a procedure existed, especially if it also produced a proof of P when P is provable.

Unfortunately, for rich enough languages, such as first-order logic (discussed in Section 2.17) it is impossible to find such a procedure. This deep result known as the *undecidability of* the decision problem or Church's theorem was proven by A. Church in 1936 (actually, Church proved the undecidability of the validity problem but, by Gödel's completeness theorem, validity and provability are equivalent).

Proving Church's theorem is hard and a lot of work. One needs to develop a good deal of what is called the *theory of computation*. This involves defining models of computation such as *Turing machines* and proving other deep results such as the *undecidability of the halting problem* and the *undecidability of the Post correspondence problem*, among other things; see Hopcroft, Motwani, and Ullman [37] and Lewis and Papadimitriou [50].

So our hopes to find a "universal theorem prover" are crushed. However, if we restrict ourselves to propositional logic, classical or intuitionistic, it turns out that procedures solving the decision problem do exist and they even produce a proof of the input proposition when that proposition is provable.

Unfortunately, proving that such procedures exist, and are correct in the propositional case is rather difficult, especially for intuitionistic logic. The difficulties have a lot to do with our choice of a natural deduction system. Indeed, even for the system $\mathcal{N}_m^{\Rightarrow}$ (or $\mathcal{NG}_m^{\Rightarrow}$), provable propositions may have infinitely many proofs. This makes the search process impossible; when do we know how to stop, especially if a proposition is not provable? The problem is that proofs may contain redundancies (Gentzen said "detours"). A typical example of redundancy is when an elimination immediately follows an introduction, as in the

following example, in which we abbreviate $(R \Rightarrow R)$ as P.

$$\frac{y \colon (P \Rightarrow Q) \to (P \Rightarrow Q) \qquad x \colon P \to P}{\left[\frac{x \colon (R \Rightarrow R), y \colon ((R \Rightarrow R) \Rightarrow Q) \to Q}{x \colon (R \Rightarrow R) \to ((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q} \qquad \qquad \frac{z \colon R \to R}{\Rightarrow R \Rightarrow R} \right]}$$

$$\frac{(R \Rightarrow R) \Rightarrow (((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q) \qquad \qquad \frac{z \colon R \to R}{\Rightarrow R \Rightarrow R}$$

The blue deduction already has $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ as conclusion but it is not a proof because the assumption $x: (R \Rightarrow R)$ is present. However, we have a proof of $R \Rightarrow R$, namely

$$\frac{z \colon R \to R}{\to R \Rightarrow R}.$$

We can obtain a proof of $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ from the blue deduction tree by replacing the leaf labeled $x: (R \Rightarrow R) \rightarrow (R \Rightarrow R)$ by the proof tree for $R \Rightarrow R$, obtaining

$$\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to ((R \Rightarrow R) \Rightarrow Q)}{\frac{x \colon (R \Rightarrow R), y \colon ((R \Rightarrow R) \Rightarrow Q)}{x \colon (R \Rightarrow R) \to ((R \Rightarrow R) \Rightarrow Q) \to Q}} \xrightarrow{\frac{z \colon R \to R}{R \Rightarrow R}}$$

The above is not quite a proof tree, but it becomes one if we delete the premise $x: (R \Rightarrow R)$, which is now redundant.

$$\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to ((R \Rightarrow R) \Rightarrow Q)}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to Q}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to Q}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q}}$$

The procedure that we just described for eliminating a redundancy can be generalized. Consider the deduction tree below, in which \mathcal{D}_1 denotes a deduction with conclusion $\Gamma, x: A \to B$ and \mathcal{D}_2 denotes a deduction with conclusion $\Delta \to A$.

$$\frac{\mathcal{D}_1}{\Gamma \to A \Rightarrow B} \qquad \qquad \mathcal{D}_2 \\
\frac{\Gamma \to A \Rightarrow B}{\Gamma \cup \Delta \to B} \qquad \qquad \Delta \to A$$

It should be possible to construct a deduction for $\Gamma \to B$ from the two deductions \mathcal{D}_1 and \mathcal{D}_2 without using at all the hypothesis x: A. This is indeed the case. If we look closely at the deduction \mathcal{D}_1 , from the shape of the inference rules, assumptions are never created, and the leaves must be labeled with expressions of the form either

(1) $\Gamma, \Lambda, x \colon A \to A$, or

(2) $\Gamma', \Lambda, x \colon A, y \colon C \to C$ if $\Gamma = \Gamma', y \colon C$ and $y \neq x$, or

(3) $\Gamma, \Lambda, x: A, y: C \to C$ if $y: C \notin \Gamma$ and $y \neq x$.

We can form a new deduction for $\Gamma \to B$ as follows. In \mathcal{D}_1 , wherever a leaf of the form $\Gamma, \Lambda, x \colon A \to A$ occurs, replace it by the deduction obtained from \mathcal{D}_2 by adding Λ to the premise of each sequent in \mathcal{D}_2 .

In our previous example, we have $A = (R \Rightarrow R)$, $B = ((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$, $C = (R \Rightarrow R) \Rightarrow Q$, $\Gamma = \Delta = \Lambda = \emptyset$.

Actually, one should be careful to first make a fresh copy of \mathcal{D}_2 by renaming all the variables so that clashes with variables in \mathcal{D}_1 are avoided. Finally, delete the assumption x: A from the premise of every sequent in the resulting proof. The resulting deduction is obtained by a kind of substitution and may be denoted as $\mathcal{D}_1[\mathcal{D}_2/x]$, with some minor abuse of notation. Note that the assumptions x: A occurring in the leaves of type (2) or (3) were never used anyway. The step that consists of transforming the above redundant proof figure into the deduction $\mathcal{D}_1[\mathcal{D}_2/x]$ is called a *reduction step* or *normalization step*.

The idea of *proof normalization* goes back to Gentzen ([25], 1935). Gentzen noted that (formal) proofs can contain redundancies, or "detours," and that most complications in the analysis of proofs are due to these redundancies. Thus, Gentzen had the idea that the analysis of proofs would be simplified if it were possible to show that every proof can be converted to an equivalent irredundant proof, a proof in *normal form*. Gentzen proved a technical result to that effect, the "cut-elimination theorem," for a sequent-calculus formulation of first-order logic [25]. Cut-free proofs are direct, in the sense that they never use auxiliary lemmas via the cut rule.

Remark: It is important to note that Gentzen's result gives a particular algorithm to produce a proof in normal form. Thus, we know that every proof can be reduced to some normal form using a specific strategy, but there may be more than one normal form, and certain normalization strategies may not terminate.

About 30 years later, Prawitz ([60], 1965) reconsidered the issue of proof normalization, but in the framework of natural deduction rather than the framework of sequent calculi.¹ Prawitz explained very clearly what redundancies are in systems of natural deduction, and he proved that every proof can be reduced to a normal form. Furthermore, this normal form is *unique*. A few years later, Prawitz ([61], 1971) showed that in fact, every reduction sequence terminates, a property also called *strong normalization*.

A remarkable connection between proof normalization and the notion of computation must also be mentioned. Curry (1958) made the remarkably insightful observation that certain typed combinators can be viewed as representations of proofs (in a Hilbert system) of certain propositions. (See Curry and Feys [8] (1958), Chapter 9E, pages 312–315.)

Building up on this observation, Howard ([38], 1969) described a general correspondence among propositions and types, proofs in natural deduction and certain typed λ -terms, and

¹This is somewhat ironical, inasmuch as Gentzen began his investigations using a natural deduction system, but decided to switch to sequent calculi (known as Gentzen systems) for technical reasons.



Figure 2.5: Haskell B. Curry, 1900–1982.

proof normalization and β -reduction (the simply-typed λ -calculus was invented by Church, 1940). This correspondence, usually referred to as the *Curry–Howard isomorphism* or *formulae-as-types principle*, is fundamental and very fruitful.

Let us elaborate on this correspondence.

2.14 The Simply-Typed λ -Calculus

First, we need to define the simply-typed λ -calculus and the first step is to define simple types. We assume that we have a countable set $\{\mathbf{T}_0, \mathbf{T}_1, \ldots, \mathbf{T}_n, \ldots\}$ of *base types* (or *atomic types*).

For example, the base types may include types such as Nat for the natural numbers, Bool for the booleans, String for strings, Tree for trees, *etc.* In the Curry–Howard isomorphism, they correspond to the propositional symbols $\{\mathbf{P}_0, \mathbf{P}_1, \ldots, \mathbf{P}_n, \ldots\}$.

Definition 2.12. The simple types σ are defined inductively as follows.

- (1) If \mathbf{T}_i is a base type, then \mathbf{T}_i is a simple type.
- (2) If σ and τ are simple types, then $(\sigma \to \tau)$ is a simple type.

Thus, $(\mathbf{T}_1 \to \mathbf{T}_1)$, $(\mathbf{T}_1 \to (\mathbf{T}_2 \to \mathbf{T}_1))$, $((\mathbf{T}_1 \to \mathbf{T}_2) \to \mathbf{T}_1)$, are simple types.

The standard abbreviation for $(\sigma_1 \to (\sigma_2 \to (\cdots \to \sigma_n)))$ is $\sigma_1 \to \sigma_2 \to \cdots \to \sigma_n$.

There is obviously a bijection between propositions and simple types. Every propositional symbol \mathbf{P}_i can be viewed as a base type, and the proposition $(P \Rightarrow Q)$ corresponds to the simple type $(P \rightarrow Q)$. The only difference is that the custom is to use \Rightarrow to denote logical implication and \rightarrow for simple types. The reason is that intuitively a simple type $(\sigma \rightarrow \tau)$ corresponds to a set of functions from a domain of type σ to a range of type τ .

The next crucial step is to define simply-typed λ -terms. This is done in two stages. First, we define raw simply-typed λ -terms. They have a simple inductive definition but they do not necessarily type-check, so we define some type-checking rules that turn out to be the Gentzen-style deduction proof rules annotated with simply-typed λ -terms. These simply-typed λ -terms are representations of natural deductions.

We have a countable set of variables $\{x_0, x_1, \ldots, x_n \ldots\}$ that correspond to the atomic raw λ -terms. These are also the variables that are used for tagging assumptions when constructing deductions.

Definition 2.13. The raw simply-typed λ -terms (for short raw terms or λ -terms) M are defined inductively as follows.

- (1) If x_i is a variable, then x_i is a raw term.
- (2) If M and N are raw terms, then (MN) is a raw term called an *application*.
- (3) If M is a raw term, σ is a simple type, and x is a variable, then the expression $(\lambda x: \sigma, M)$ is a raw term called a λ -abstraction.

Matching parentheses may be dropped or added for convenience.

Definition 2.14. In a raw λ -term M, a variable x appearing in an expression $\lambda x : \sigma$ is said to be *bound* in M. The other variables in M (if any), are said to be *free* in M. A λ -term M is *closed* if it has no free variables.

Example 2.8. For example, in the term $\lambda x : \sigma$. (yx), the variable x is bound and the variable y is free. This term is not closed.

The term $\lambda y \colon \sigma \to \sigma. (\lambda x \colon \sigma. (yx))$ is closed.

The intuition is that a term of the form $\lambda x : \sigma$. *M* represents a function. How such a function operates will be defined in terms of β -reduction.

Definition 2.15. The depth d(M) of a raw λ -term M is defined inductively as follows.

- 1. If M is a variable x, then d(x) = 0.
- 2. If M is an application (M_1M_2) , then $d(M) = \max\{d(M_1), d(M_2)\} + 1$.
- 3. If M is a λ -abstraction ($\lambda x : \sigma . M_1$), then $d(M) = d(M_1) + 1$.

It is pretty clear that raw λ -terms have representations as (ordered) labeled trees.

Definition 2.16. Given a raw λ -term M, the tree tree(M) representing M is defined inductively as follows.

- 1. If M is a variable x, then tree(M) is the one-node tree labeled x.
- 2. If M is an application (M_1M_2) , then tree(M) is the tree with a binary root node labeled . and with a left subtree tree (M_1) and a right subtree tree (M_2) .
- 3. If M is a λ -abstraction ($\lambda x : \sigma . M_1$), then tree(M) is the tree with a unary root node labeled $\lambda x : \sigma$ and with one subtree tree(M_1).



Figure 2.6: The tree tree(M) associated with a raw λ -term M.

Definition 2.16 is illustrated in Figure 2.6.

Obviously, the depth d(M) of raw λ -term is the depth of its tree representation tree(M). Definition 2.16 could be used to deal with bound variables. For every leaf labeled with a bound variable x, we draw a backpointer to an ancestor of x determined as follows. Given a leaf labeled with a bound variable x, climb up to the closest ancestor labeled $\lambda x: \sigma$, and draw a backpointer to this node. Then all bound variables can be erased. See Figure 2.7 for an example.



Figure 2.7: Using backpointers to deal with bound variables.

Definition 2.13 allows the construction of undesirable terms, such as (xx) or $(\lambda x: \sigma. (xx))(\lambda x: \sigma. (xx))$ because no type-checking is done. Part of the problem is that the

variables occurring in a raw term have not been assigned types. This can be done using a context (or type assignment).

Definition 2.17. A context (or type assignment) is a set of pairs $\Gamma = \{x_1: \sigma_1, \ldots, x_n: \sigma_n\}$, where the σ_i are simple types and the variables x_i are pairwise distinct. The domain of Γ , denoted dom(Γ), is the set of variables $\{x_1, \ldots, x_n\}$.

Once a type assignment has been provided, the type-checking rules are basically the proof rules of natural deduction in Gentzen-style.

Definition 2.18. The fact that a raw term M has type σ given a type assignment Γ that assigns types to all the free variables in M is written as

$$\Gamma \triangleright M : \sigma$$

Such an expression is called a *judgement*. The symbol \triangleright is used instead of the symbol \rightarrow because \rightarrow occurs in simple types.

Here are the typing-checking rules.

Definition 2.19. The *type-checking rules* of the simply-typed λ -calculus λ^{\rightarrow} are listed below:

$$\Gamma, x: \sigma \triangleright x: \sigma \quad (axioms)$$

$$\frac{\Gamma, x: \sigma \triangleright M: \tau}{\Gamma \triangleright (\lambda x: \sigma, M): \sigma \to \tau} \quad (abstraction)$$

$$\frac{\Gamma \triangleright M: \sigma \to \tau \quad \Delta \triangleright N: \sigma}{\Gamma \cup \Delta \triangleright (MN): \tau} \quad (application)$$

In the axioms and in the (*abstraction*) rule, it is assumed that $x: \sigma \notin \Gamma$. In the (*application*) rule, it is assumed that Γ and Δ are consistent, which means that if $x: \sigma_1 \in \Gamma$ and $x: \sigma_2 \in \Delta$, then $\sigma_1 = \sigma_2$. We write $\vdash \Gamma \triangleright M: \sigma$ to express that the judgement $\Gamma \triangleright M: \sigma$ is provable. Given a raw simply-typed λ -term M, if there is a type-assignment Γ and a simple type σ such that the judgement $\Gamma \triangleright M: \sigma$ is provable, we say that M type-checks with type σ .

It can be shown by induction on the depth of raw terms that for a fixed type-assignment Γ , if a raw simply-typed λ -term M type-checks with some simple type σ , then σ is unique.

The correspondence between proofs in natural deduction and simply-typed λ -terms (the Curry–Howard isomorphism) is now clear: the abstraction rule corresponds to implication-introduction, the application rule corresponds to implication elimination, and the blue term is a *representation of the deduction* of the sequents $\Gamma, x: \sigma \to \sigma, \Gamma \to \sigma \Rightarrow \tau$, and $\Gamma \cup \Delta \to \tau$, with the types $\sigma, \sigma \to \tau$ and τ viewed as propositions. Note that proofs correspond to closed λ -terms.

Example 2.9. For example, we have the type-checking proof

$$\frac{z \colon R \triangleright z \colon R}{y \colon ((R \to R) \to Q) \triangleright y \colon ((R \to R) \to Q)} \xrightarrow{[> \lambda z \colon R. z \colon R \to R]}{p \setminus \lambda z \colon R. z \colon R \to R}$$
$$\frac{y \colon ((R \to R) \to Q) \triangleright y(\lambda z \colon R. z) \colon Q}{p \setminus \lambda y \colon ((R \to R) \to Q). y(\lambda z \colon R. z) \colon ((R \to R) \to Q) \to Q}$$

which shows that the simply-typed λ -term

$$M = \lambda y \colon ((R \to R) \to Q) \colon y(\lambda z \colon R \colon z)$$

represents the proof

$$\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to ((R \Rightarrow R) \Rightarrow Q)}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to Q}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \to Q}{\frac{y \colon ((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q}}$$

The proposition $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ being proven corresponds to the type $((R \Rightarrow R) \Rightarrow Q) \Rightarrow Q$ of the λ -term M.

The tree representing the λ -term $M = \lambda y : ((R \Rightarrow R) \Rightarrow Q) \cdot y(\lambda z : R. z)$ is shown in Figure 2.8.



Figure 2.8: The tree representation of the λ -term M.

Furthermore, and this is the deepest aspect of the Curry–Howard isomorphism, proof normalization corresponds to β -reduction in the simply-typed λ -calculus.

The notion of β -reduction is defined in terms of substitutions.

Definition 2.20. A substitution φ is a finite set of pairs $\varphi = \{(x_1, N_1), \dots, (x_n, N_n)\}$, where the x_i are distinct variables and the N_i are raw λ -terms. We write

$$\varphi = [N_1/x_1, \dots, N_n/x_n]$$
 or $\varphi = [x_1 := N_1, \dots, x_n := N_n].$

The second notation indicates more clearly that each term N_i is substituted for the variable x_i and it seems to have been almost universally adopted.

Given a substitution $\varphi = [x_1 := N_1, \dots, x_n := N_n]$, for any variable x_i , we denote by φ_{-x_i} the new substitution where the pair (x_i, N_i) is replaced by the pair (x_i, x_i) (that is, the new substitution leaves x_i unchanged).

Definition 2.21. Given any raw λ -term M and any substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$, we define the raw λ -term $M[\varphi]$, the result of applying the substitution φ to M, as follows:

(1) If M = y, with $y \neq x_i$ for i = 1, ..., n, then $M[\varphi] = y = M$.

(2) If
$$M = x_i$$
 for some $i \in \{1, \ldots, n\}$, then $M[\varphi] = N_i$

- (3) If M = (PQ), then $M[\varphi] = (P[\varphi]Q[\varphi])$.
- (4) If $M = \lambda x : \sigma$. N and $x \neq x_i$ for i = 1, ..., n, then $M[\varphi] = \lambda x : \sigma$. $N[\varphi]$.
- (5) If $M = \lambda x : \sigma$. N and $x = x_i$ for some $i \in \{1, \ldots, n\}$, then $M[\varphi] = \lambda x : \sigma$. $N[\varphi]_{-x_i}$.

There is a problem with the present definition of a substitution in Cases (4) and (5), which is that the result of substituting a term N_i containing the free variable x causes this variable to become bound after the substitution. We say that x is *captured*.

To remedy this problem, Church defined α -conversion.

Definition 2.22. The idea of α -conversion is that in a raw term M, any subterm of the form $\lambda x : \sigma$. P can be replaced by the subterm $\lambda z : \sigma$. P[x := z], where z is a new variable not occurring at all (free or bound) in M to obtain a new term M'. We write $M \equiv_{\alpha} M'$ and we view M and M' as equivalent.

Example 2.10. For example, $\lambda x : \sigma \cdot yx \equiv_{\alpha} \lambda z : \sigma \cdot yz$ and

$$\lambda y \colon \sigma \to \sigma. (\lambda x \colon \sigma. yx) \equiv_{\alpha} \lambda w \colon \sigma \to \sigma. (\lambda z \colon \sigma. wz).$$

The variables x and y are just place-holders.

Then, given a raw λ -term M and a substitution $\varphi = [x_1 := N_1 \dots, x_n := N_n]$, before applying φ to M, we first apply some α -conversion to rename all bound variables in Mobtaining $M' \equiv_{\alpha} M$, so that they do not occur in any of the N_i , and then safely apply the substitution φ to M' without any capture of variables. We say that the term M' is *safe* for the substitution φ .

The details are a bit tedious and we omit them. We refer the interested reader to Section 6.1 and to Gallier [22] for a comprehensive discussion.

The following result shows that substitutions behave well with respect to type-checking. Given a context $\Gamma = \{x_1: \sigma_1, \ldots, x_n: \sigma_n\}$, we let $\Gamma(x_i) = \sigma_i$. **Proposition 2.10.** For any raw λ -term M and any substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$, whose domain contains the set of free variables of M, if the judgement $\Gamma \triangleright M : \tau$ is provable for some context Γ and some simple type τ , and if there is some context Δ such that for every free variable x_j in M the judgement $\Delta \triangleright N_j : \Gamma(x_j)$ is provable, then there is some $M' \equiv_{\alpha} M$ such that the judgement $\Delta \triangleright M'[\varphi] : \tau$ is provable.

Finally, we define β -reduction and β -conversion as follows.

Definition 2.23. The relation \longrightarrow_{β} , called *immediate* β -reduction, is the smallest relation satisfying the following properties for all raw λ -terms M, N, P, Q:

$$(\lambda x : \sigma. M) N \longrightarrow_{\beta} M[x := N]$$

provided that M is safe for [x := N];

$$\frac{M \longrightarrow_{\beta} N}{MQ \longrightarrow_{\beta} NQ} \qquad \frac{M \longrightarrow_{\beta} N}{PM \longrightarrow_{\beta} PN}, \quad \text{for all } P, Q \quad (congruence)$$

$$\frac{M \longrightarrow_{\beta} N}{\lambda x \colon \sigma. M \longrightarrow_{\beta} \lambda x \colon \sigma. N}, \quad \text{for all } \sigma.$$
 (ξ)

The transitive closure of \longrightarrow_{β} is denoted by $\stackrel{+}{\longrightarrow}_{\beta}$, the reflexive and transitive closure of \longrightarrow_{β} is denoted by $\stackrel{*}{\longrightarrow}_{\beta}$, and we define β -conversion, denoted by $\stackrel{*}{\longleftrightarrow}_{\beta}$, as the smallest equivalence relation $\stackrel{*}{\longleftrightarrow}_{\beta} = (\longrightarrow_{\beta} \cup \longrightarrow_{\beta}^{-1})^*$ containing \longrightarrow_{β} .

Example 2.11. For example, we have

$$\begin{aligned} (\lambda u: \sigma. (vu)) \big((\lambda x: \sigma \to \sigma. (xy)) (\lambda z: \sigma. z) \big) &\longrightarrow_{\beta} \\ (\lambda u: \sigma. (vu)) (\lambda x: \sigma \to \sigma. (xy)) [x := (\lambda z: \sigma. z)] &= (\lambda u: \sigma. (vu)) \big((\lambda z: \sigma. z)y \big) \\ &\longrightarrow_{\beta} (\lambda u: \sigma. (vu)) z[z := y] = (\lambda u: \sigma. (vu)) y \longrightarrow_{\beta} (vu) [u := y] = vy. \end{aligned}$$

In the above, β -reduction steps are applied to the blue subterms.

The following result shows that β -reduction (and β -conversion) behave well with respect to type-checking.

Proposition 2.11. For any two raw λ -terms M and N, if there is a proof of the judgement $\Gamma \triangleright M : \sigma$ for some context Γ and some simple type σ , and if $M \xrightarrow{+}_{\beta} N$ (or $M \xleftarrow{*}_{\beta} N$), then the judgement $\Gamma \triangleright N : \sigma$ is provable. Thus β -reduction and β -conversion preserve type-checking.

Definition 2.24. We say that a λ -term M is β -irreducible or a β -normal form if there is no term N, such that $M \longrightarrow_{\beta} N$.

The fundamental result about the simply-typed λ -calculus is this.

Theorem 2.12. For every raw λ -term M, if M type-checks, which means that there is a provable judgement $\Gamma \triangleright M : \sigma$ for some context Γ and some simple type σ , then the following results hold.

- (1) If $M \xrightarrow{*}_{\beta} M_1$ and $M \xrightarrow{*}_{\beta} M_2$, then there is some M_3 such that $M_1 \xrightarrow{*}_{\beta} M_3$ and $M_2 \xrightarrow{*}_{\beta} M_3$. We say that $\xrightarrow{*}_{\beta}$ is confluent.
- (2) Every reduction sequence $M \xrightarrow{+}_{\beta} N$ is finite. We say that the simply-typed λ -calculus is strongly normalizing (for short, SN).

As a consequence of (1) and (2), there is a unique β -irreducible term N (called a β -normal form) such that $M \xrightarrow{*}_{\beta} N$.

A proof of Theorem 2.12 can be found in Gallier [19]. See also Gallier [22] which contains a thorough discussion of the techniques involved in proving these results.

In Theorem 2.12, the fact that the term M type-checks is crucial. Indeed, the term

 $(\lambda x. (xx))(\lambda x. (xx)),$

which does not type-check (we omitted the type tags σ of the variable x since they do not play any role), gives rise to an infinite β -reduction sequence!

In summary, the correspondence between proofs in intuitionistic logic and typed λ -terms on one hand and between proof normalization and β -reduction, can be used to translate results about typed λ -terms into results about proofs in intuitionistic logic. These results can be generalized to typed λ -calculi with product types and union types; see Section 7.5 and Gallier [19].

Since certain raw terms type check but others do not, three natural questions arise.

- (1) Given a raw term M and a simple type σ , is there a type assignment $\Gamma = \{x_1 : \sigma_1, \ldots, x_n : \sigma_n\}$ of the set $\{x_1, \ldots, x_n\}$ of free variables in M, such that $\Gamma \triangleright M : \sigma$ is provable, that is, M type checks with type σ . This is the *type checking problem*.
- (2) Given a raw term M, is there a type assignment $\Gamma = \{x_1: \sigma_1, \ldots, x_n: \sigma_n\}$ of the set $\{x_1, \ldots, x_n\}$ of free variables in M and some type σ , such that $\Gamma \triangleright M: \sigma$ is provable. This is the typability problem (or type inferencing problem).
- (3) Given a type σ , is there a closed term M, such that $\triangleright M : \sigma$ is provable. This is the *inhabitation problem*.

Observe that the inhabitation problem is equivalent to deciding whether a proposition is provable in propositional intuitionistic logic. Using some suitable intuitionistic sequent calculi and Gentzen's cut elimination theorem or some suitable typed λ -calculi and (strong) normalization results about them, it is possible to prove that there is a decision procedure for propositional intuitionistic logic. However, it can also be shown that the time-complexity of any such procedure is very high. As a matter of fact, it was shown by Statman (1979) that deciding whether a proposition is intuitionistically provable is P-space complete; see [68] and Section 16.4. Here, we are alluding to *complexity theory*, another active area of computer science; see Hopcroft, Motwani, and Ullman [37] and Lewis and Papadimitriou [50].

2.15 An Algorithm To Solve The Typability Problem

There is an algorithm to solve the typability problem that makes use of well-known concepts of theorem-proving, namely *unification* and *most general unifiers*; see Chapter 3, Gallier [24], and Selinger [66].

To understand where unification comes in, consider typing the raw term

$$\lambda x : \sigma_1 . \lambda y : \sigma_2 . yx,$$

where σ_1 and σ_2 are unknown types. To deduce a proof of $\lambda x: \sigma_1. \lambda y: \sigma_2. yx: \tau$ where σ_1, σ_2, τ are unknown types, in order to respect the type checking rules, the derivation constructed from the bottom-up must be of the following form:

$$\frac{y: \sigma_2 \triangleright y: X \to Y \qquad x: \sigma_1 \triangleright x: X}{x: \sigma_1, y: \sigma_2 \triangleright yx: Y}$$

$$\frac{\overline{x: \sigma_1 \triangleright \lambda y: \sigma_2 \cdot yx: Z = (\sigma_2 \to Y)}}{\triangleright \lambda x: \sigma_1 \cdot \lambda y: \sigma_2 \cdot yx: \tau = (\sigma_1 \to Z)}$$

for some unknown types X, Y, Z. For the leaf nodes to be axioms, we must have $\sigma_1 = X$, $\sigma_2 = (X \to Y)$, which implies that $Z = ((X \to Y) \to Y)$ and

$$\tau = (X \to ((X \to Y) \to Y)).$$

So, we have an infinite number of solutions, among which we have

$$\sigma_{1} \to ((\sigma_{1} \to \sigma_{1}) \to \sigma_{1})$$

$$(\sigma_{1} \to \sigma_{2}) \to (((\sigma_{1} \to \sigma_{2}) \to \sigma_{2}) \to \sigma_{2})$$

$$\sigma_{1} \to ((\sigma_{1} \to (\sigma_{1} \to \sigma_{2})) \to (\sigma_{1} \to \sigma_{2})).$$

The most general solution is $X \to ((X \to Y) \to Y)$, where X and Y are variables ranging over all types, in the sense that all possible solutions (including those listed above) are obtained by applying a substitution to the most general solution.

To make all this precise, we allow type variables in the construction of simple types and we introduce type substitutions of the form $\varphi = \{X_1 := \sigma_1, \ldots, X_n := \sigma_n\}$, where X_1, \ldots, X_n are type variables and $\sigma_1, \ldots, \sigma_n$ are simple types possibly containing type variables. Technically, a type substitution is a map φ from the countable set of all type variables to the set of simple types built up from base types and type variables using \rightarrow , such that $\varphi(X_i) \neq X_i$ for only finitely many variables. With this convention, when defining a substitution φ as a set of pairs $\varphi = [X_1 := \sigma_1, \ldots, X_n := \sigma_n]$, we assume that $\sigma_i \neq X_i$ for $i = 1, \ldots, n$, so we do not include pairs for all the other variables X_i for which $\varphi(X_i) = X_i$.

The other key concepts used for solving the type inferencing problem are the concept of *unifer* of two terms and the notion of *most general unifier*, for short, *mgu*.

A rigorous and rather extensive presentation of unification theory is given in Chapter 3. In this section, we content ouselves with a more informal presentation.

Definition 2.25. Given any simple type σ (possibly containing type variables) and any type substitution $\varphi = [X_1 := \sigma_1, \ldots, X_n := \sigma_n]$, where X_1, \ldots, X_n are type variables and $\sigma_1, \ldots, \sigma_n$ are simple types, we define the type $\sigma[\varphi]$, the result of applying the substitution φ to σ , as follows.

- (1) If $\sigma = Y$ (where Y is a type variable) with $Y \neq X_i$ for i = 1, ..., n, then $\sigma[\varphi] = Y = \sigma$.
- (2) If $\sigma = X_i$ for some $i \in \{1, \ldots, n\}$, then $\sigma[\varphi] = \sigma_i$.
- (3) If $\sigma = \mathbf{T}_i$ (a base type), then $\sigma[\varphi] = \mathbf{T}_i = \sigma$.
- (4) If $\sigma = (\sigma_1 \to \sigma_2)$, then $\sigma[\varphi] = (\sigma_1[\varphi] \to \sigma_2[\varphi])$.

A type substitution φ has a unique extension $\hat{\varphi}$ to all simple types defined by

$$\widehat{\varphi}(\sigma) = \sigma[\varphi]$$

for all simple types σ . Given two substitutions φ and ψ , the substitution $\widehat{\psi} \circ \varphi$ is denoted $\varphi; \psi$, so

$$(\varphi;\psi)(X_i) = \psi(\varphi(X_i)) = (\varphi(X_i))[\psi] = \sigma_i[\psi] = (X_i[\varphi])[\psi].$$

It is easy to prove by induction on the size of σ that

$$\sigma[\varphi;\psi] = (\sigma[\varphi])[\psi] = \widehat{\psi}(\sigma[\varphi]) = (\widehat{\psi} \circ \widehat{\varphi})(\sigma),$$

namely $\widehat{\varphi}; \psi = \widehat{\psi} \circ \widehat{\varphi}$. Note that when the substitution $\varphi; \psi$ is applied to a term σ , the substitution φ is applied *first*, and then the substitution ψ is applied. Beware that $\varphi; \psi$ is *not* the composition $\psi \circ \varphi$, which does not make any sense.

Example 2.12. Consider the substitutions φ and ψ given by

$$\varphi = [X_1 := (\sigma_1 \to X_4), X_3 := (\sigma_1 \to X_1), X_4 := X_5]$$

$$\psi = [X_2 := \sigma_3, X_4 := (\sigma_2 \to X_2), X_5 := X_4],$$

where X_1, X_2, X_3, X_4, X_5 are type variables and $\sigma_1, \sigma_2, \sigma_3$ are base types. Then we have

$$\varphi; \psi = [X_1 := (\sigma_1 \to (\sigma_2 \to X_2)), X_2 := \sigma_3, X_3 := (\sigma_1 \to X_1), X_5 := X_4].$$

Since $\varphi(X_4) = X_5$ and $\psi(X_5) = X_4$, we have

$$\varphi; \psi(X_4) = (\varphi(X_4))[X_5 := X_4] = X_5[X_5 := X_4] = X_4,$$

which is why we did not include a pair with left-hand side X_4 in $\varphi\psi$.

If

$$\sigma = (X_2 \to X_3) \to ((X_1 \to X_1) \to (X_4 \to X_5)),$$

then

$$\sigma[\varphi] = (X_2 \to (\sigma_1 \to X_1)) \to \big(((\sigma_1 \to X_4) \to (\sigma_1 \to X_4)) \to (X_5 \to X_5)\big),$$

and

$$(\sigma[\varphi])[\psi] = (\sigma_3 \to (\sigma_1 \to X_1)) \to (((\sigma_1 \to (\sigma_2 \to X_2)) \to (\sigma_1 \to (\sigma_2 \to X_2))) \to (X_4 \to X_4)).$$

We verify immediately that $(\sigma[\varphi])[\psi]$ is indeed equal to $\sigma[\varphi; \psi]$.

The key notion of unifier is given below. A more extensive discussion is given in Section 3.3.

Definition 2.26. Given two types σ_1 and σ_2 , a *unifier* of σ_1 and σ_2 is a substitution φ defined on the type variables in σ_1 and σ_2 such that

$$\sigma_1[\varphi] = \sigma_2[\varphi].$$

For example, if $\sigma_1 = ((X_4 \to X_4) \to X_5)$ and $\sigma_2 = (X_1 \to (X_2 \to X_3))$, then

$$\varphi = [X_1 := (X_4 \to X_4), X_5 := (X_2 \to X_3)]$$

is a unifier since

$$\sigma_1[\varphi] = \sigma_2[\varphi] = ((X_4 \to X_4) \to (X_2 \to X_3))$$

It turns out that if two types σ_1 and σ_2 are unifiable, then there is some most general unifier (or mgu) φ , which means that for every other unifier ψ of σ_1 and σ_2 there is some other substitution θ such that $\psi = \varphi$; θ .

Note that mgu's are not unique, but they are, up to a bijective substitution that renames variables. Again, a thorough discussion of mgu's is given in Section 3.3.

Using an algorithm mgu(σ_1, σ_2) to find a most general unifiers of σ_1 and σ_2 if it exists (and return failure otherwise), we can design an algorithm typesub deciding whether a raw term M is typable. Algorithms for finding mgu's are outlined in Sections 3.3 and 3.4.

We biefly describe the method presented in Selinger [66] (Section 9.5). Other methods can be found in Hindley [36] and Milner [54].

This algorithm takes as input a judgement $\Gamma \triangleright M : \tau$ where $\Gamma = \{x_1 : \sigma_1, \ldots, x_n : \sigma_n\}$ is a type assignment of the free variables in M. The types σ_i , τ and the types of the bound variables in M, may contain type variables.

Given a type substitution φ , we denote by $\Gamma[\varphi]$ the type assignment

$$\Gamma[\varphi] = \{ x_1 \colon \sigma_1[\varphi], \dots, x_n \colon \sigma_n[\varphi] \}.$$

Given $\Gamma \triangleright M : \tau$, the algorithm either returns failure if M is not typable, or typesub returns a type substitution φ of the type variables occurring in the types σ_i, τ , and the types of the bound variables in M, denoted typesub($\Gamma \triangleright M : \tau$), such that $\Gamma[\varphi] \triangleright M[\varphi] : \tau[\varphi]$ is provable and φ is a most general substitution, which means that for any other type substitution ψ with the above property, we have $\psi = \varphi; \theta$ for some substitution θ .

The algorithm typesub has three cases.

(1) If $M = x_i$, then

$$typesub(x_1: \sigma_1, \dots, x_n: \sigma_n \triangleright x_i: \tau) = mgu(\sigma_i, \tau).$$

- (2) If $M = M_1 N_1$, then in order to compute typesub $(\Gamma \triangleright (M_1 N_1): \tau)$, for any splitting of Γ as $\Gamma = \Gamma_1 \cup \Gamma_2$ for two consistent contexts Γ_1 and Γ_2 , such that $FV(M_1) \subseteq \operatorname{dom}(\Gamma_1)$ and $FV(N_1) \subseteq \operatorname{dom}(\Gamma_2)$, first we find $\varphi_1 = \operatorname{typesub}(\Gamma_1 \triangleright M_1: X \to \tau)$ for some new type variable X, then we find the substitution $\varphi_2 = \operatorname{typesub}(\Gamma_2[\varphi_1] \triangleright N_1[\varphi_1]: X[\varphi_1])$, and then typesub $(\Gamma \triangleright (M_1 N_1): \tau) = \varphi_1; \varphi_2$.
- (3) If $M = (\lambda x : \sigma. M_1)$, then in order to compute typesub $(\Gamma \triangleright (\lambda x : \sigma. M_1) : \tau)$, first we find $\varphi_1 = \text{mgu}(\tau, \sigma \to X)$, where X is a new type variable, then we find $\varphi_2 =$ typesub $(\Gamma[\varphi_1], x : \sigma[\varphi_1] \triangleright M_1[\varphi_1] : X[\varphi_1])$, and then typesub $(\Gamma \triangleright (\lambda x : \sigma. M_1) : \tau) =$ $\varphi_1; \varphi_2.$

Peter Selinger explained to the first author that in the case of an application M_1N_1 , all we know is that M_1 must have an arrow type of the form $X \to \tau$ for some new type variable X, and no other candidate for the type of M_1 is provided. However, in the case of a λ -abstraction $\lambda x : \sigma$. M_1 , the term $\lambda x : \sigma$. M_1 must have an arrow type of the form $\sigma \to X$ for some new type variable X, and since it already has the type τ , it is natural to unify τ and $\sigma \to X$.

If the algorithm succeeds, it returns a type substitution $\varphi = \text{typesub}(\Gamma \triangleright M : \tau)$ such that $\tau[\varphi]$ is a type of $M[\varphi]$ with respect to the type assignment $\Gamma[\varphi]$ of the free variables in M that we call a *principal type* (also known as *principal type scheme*).

Example 2.13. Let us apply the algorithm to the judgement

 $\triangleright \lambda x \colon X_1. \lambda y \colon (X_1 \to X_2). yx \colon ((U \to U) \to V),$

where X_1, X_2, U, V are type variables.

We are in Case 3, so we have to find $mgu(((U \to U) \to V), X_1 \to X)$, for a new variable X. We obtain the substitution

$$[X_1 := (U \to U), X := V].$$

The next step is to apply the algorithm to the result of applying the above substitution to

$$\lambda x \colon X_1 \triangleright \lambda y \colon (X_1 \to X_2). \, yx \colon X,$$

namely

$$\lambda x \colon (U \to U) \triangleright \ \lambda y \colon ((U \to U) \to X_2). \ yx \colon V,$$

so we are again in Case 3. We need to find $mgu((((U \to U) \to X_2) \to Z), V))$, for a new variable Z. We obtain the substitution

$$[V := (((U \to U) \to X_2) \to Z)].$$

The next step is to apply the algorithm to the result of applying the above substitution to

$$\lambda x \colon (U \to U), y \colon ((U \to U) \to X_2) \triangleright yx \colon Z,$$

which yields the same judgement

$$\lambda x \colon (U \to U), y \colon ((U \to U) \to X_2) \triangleright yx \colon Z.$$

This time we are in Case 2, so we need to consider

$$y: ((U \to U) \to X_2) \triangleright y: Y \to Z,$$

where Y is a new variable. We need to find $mgu(((U \to U) \to X_2), Y \to Z)$, which yield the substitution

$$[Y := (U \to U), \ Z := X_2].$$

Then we consider the result of applying the above substitution to

$$x\colon (U\to U) \triangleright \ x\colon Y,$$

namely

$$x\colon (U\to U) \triangleright \ x\colon (U\to U),$$

which is OK. So by back-substitution,

$$[Y := (U \to U), \ Z := X_2, \ V := ((U \to U) \to X_2) \to X_2, X_1 := (U \to U), \ X := ((U \to U) \to X_2) \to X_2],$$

and the most general type is obtained by applying the above substitution to $(X_1 \to X)$, namely

$$(U \to U) \to (((U \to U) \to X_2) \to X_2).$$

The type checking problem reduces to the typability problem. First, we use the algorithm to decide whether M is typable. If so, we find a principal type τ , and then we check that τ and σ (which has no type variables) are unifiable.

Readers who wish to learn more about these topics can read Selinger [66], Pierce [58], and the two survey papers Gallier [19] (On the Correspondence Between Proofs and λ -Terms) and Gallier [18] (A Tutorial on Proof Systems and Typed λ -Calculi), both available on the website http://www.seas.upenn.edu/~jean/gbooks/logic.html, and the excellent introduction to proof theory by Troelstra and Schwichtenberg [73].

Anybody who really wants to understand logic should of course take a look at Kleene [42] (the famous "I.M."), but this is not recommended to beginners.



Figure 2.9: Stephen C. Kleene, 1909–1994.

2.16 Completeness and Counter-Examples

Let us return to the question of deciding whether a proposition is not provable. To simplify the discussion, let us restrict our attention to propositional classical logic. So far, we have presented a very *proof-theoretic* view of logic, that is, a view based on the notion of provability as opposed to a more *semantic* view based on the notions of truth and models. A possible excuse for our bias is that, as Peter Andrews (from CMU) puts it, "truth is elusive." Therefore, it is simpler to understand what truth is in terms of the more "mechanical" notion of provability. (Peter Andrews even gave the subtitle *To Truth Through Proof* to his logic book Andrews [2].)



Figure 2.10: Peter Andrews, 1937-.

However, mathematicians are not mechanical theorem provers (even if they prove lots of stuff). Indeed, mathematicians almost always think of the objects they deal with (functions, curves, surfaces, groups, rings, etc.) as rather concrete objects (even if they may not seem concrete to the uninitiated) and not as abstract entities solely characterized by arcane axioms.

It is indeed natural and fruitful to try to interpret formal statements semantically. For propositional classical logic, this can be done quite easily if we interpret atomic propositional letters using the truth values **true** and **false**, as explained in Section 2.11. Then, the crucial point is that every provable proposition (say in $\mathcal{NG}_c^{\Rightarrow,\vee,\wedge,\perp}$) has the value **true** no matter how we assign truth values to the letters in our proposition. In this case, we say that P is valid.

The fact that provability implies validity is called *soundness* or *consistency* of the proof system. The soundness of the proof system $\mathcal{NG}_c^{\Rightarrow,\vee,\wedge,\perp}$ is easy to prove, as sketched in Section 2.11.

We now have a method to show that a proposition P is not provable: find some truth assignment that makes P false.

Such an assignment falsifying P is called a *counterexample*. If P has a counterexample, then it can't be provable because if it were, then by soundness it would be **true** for all possible truth assignments.

But now, another question comes up. If a proposition is not provable, can we always find a counterexample for it? Equivalently, *is every valid proposition provable*? If every valid proposition is provable, we say that our proof system is *complete* (this is the *completeness* of our system).

The system $\mathcal{NG}_c^{\Rightarrow,\vee,\wedge,\perp}$ is indeed complete. In fact, *all* the classical systems that we have discussed are sound and complete. Completeness is usually a lot harder to prove than soundness. For first-order classical logic, this is known as *Gödel's completeness theorem* (1929). Again, we refer our readers to Gallier [24], van Dalen [75], or Huth and Ryan [41] for a thorough discussion of these matters. In the first-order case, one has to define *first-order structures* (or *first-order models*).

What about intuitionistic logic?

Well, one has to come up with a richer notion of semantics because it is no longer true that if a proposition is valid (in the sense of our two-valued semantics using **true**, **false**), then it is provable. Several semantics have been given for intuitionistic logic. In our opinion, the most natural is the notion of the *Kripke model*, presented in Section 2.12. Then, again, soundness and completeness hold for intuitionistic proof systems, even in the first-order case (see Section 2.12 and van Dalen [75]).

In summary, semantic models can be used to provide *counterexamples* of unprovable propositions. This is a quick method to establish that a proposition is not provable.

We close this section by repeating something we said earlier: there isn't just one logic but instead, *many* logics. In addition to classical and intuitionistic logic (propositional and first-order), there are modal logics, higher-order logics, and *linear logic*, a logic due to Jean-Yves Girard, attempting to unify classical and intuitionistic logic (among other goals).



Figure 2.11: Jean-Yves Girard, 1947–.

An excellent introduction to these logics can be found in Troelstra and Schwichtenberg [73]. We warn our readers that most presentations of linear logic are (very) difficult to follow. This is definitely true of Girard's seminal paper [29]. A more approachable version can be

found in Girard, Lafont, and Taylor [26], but most readers will still wonder what hit them when they attempt to read it.

In computer science, there is also *dynamic logic*, used to prove properties of programs and *temporal logic* and its variants (originally invented by A. Pnueli), to prove properties of real-time systems. So logic is alive and well.

We now add quantifiers to our language and give the corresponding inference rules.

2.17 Adding Quantifiers; First-Order Languages

As we mentioned in Section 2.1, atomic propositions may contain variables. The intention is that such variables correspond to arbitrary objects. An example is

 $human(x) \Rightarrow needs-to-drink(x).$

Now in mathematics, we usually prove universal statements, that is statements that hold for all possible "objects," or existential statements, that is, statements asserting the existence of some object satisfying a given property. As we saw earlier, we assert that every human needs to drink by writing the proposition

 $\forall x (\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x)).$

Observe that once the quantifier \forall (pronounced "for all" or "for every") is applied to the variable x, the variable x becomes a placeholder and replacing x by y or any other variable does not change anything. What matters is the locations to which the outer x points in the inner proposition. We say that x is a bound variable (sometimes a "dummy variable").

If we want to assert that some human needs to drink, we write

$$\exists x(\operatorname{human}(x) \Rightarrow \operatorname{needs-to-drink}(x));$$

again, once the quantifier \exists (pronounced "there exists") is applied to the variable x, the variable x becomes a placeholder. However, the intended meaning of the second proposition is very different and weaker than the first. It only asserts the existence of some object satisfying the statement

$$human(x) \Rightarrow needs-to-drink(x).$$

Statements may contain variables that are not bound by quantifiers.

Example 2.14. For example, in

 $\exists x \operatorname{parent}(x, y)$

the variable x is bound but the variable y is not. Here the intended meaning of parent(x, y) is that x is a parent of y, and the intended meaning of $\exists x \text{ parent}(x, y)$ is that any given y has some parent x.

Variables that are not bound are called *free*. The proposition

 $\forall y \exists x \operatorname{parent}(x, y),$

which contains only bound variables, is meant to assert that every y has some parent x. Typically, in mathematics, we only prove statements without free variables. However, statements with free variables may occur during intermediate stages of a proof.

The intuitive meaning of the statement $\forall xP$ is that P holds for all possible objects x, and the intuitive meaning of the statement $\exists xP$ is that P holds for some object x. Thus, we see that it would be useful to use symbols to denote various objects.

Example 2.15. For example, if we want to assert some facts about the "parent" predicate, we may want to introduce some *constant symbols* (for short, constants), such as "Jean," "Mia," and so on and write

parent(Jean, Mia)

to assert that Jean is a parent of Mia.

Often, we also have to use *function symbols* (or *operators, constructors*), for instance, to write a statement about numbers: +, *, and so on. Using constant symbols, function symbols, and variables, we can form *terms*, such as

$$(x * x + 1) * (3 * y + 2).$$

In addition to function symbols, we also use *predicate symbols*, which are names for atomic properties. We have already seen several examples of predicate symbols: "human," "parent." So, in general, when we try to prove properties of certain classes of objects (people, numbers, strings, graphs, and so on), we assume that we have a certain *alphabet* consisting of constant symbols, function symbols, and predicate symbols. Using these symbols and an infinite supply of variables (assumed distinct from the variables we use to label premises), we can form *terms* and *predicate terms*. We say that we have a *(logical) language*. Using this language, we can write compound statements.

Let us be a little more precise.

Definition 2.27. In a *first-order language* **L** in addition to the logical connectives \Rightarrow , $\land, \lor, \neg, \bot, \forall$, and \exists , we have a set **L** of *nonlogical symbols* consisting of

- (i) A set **CS** of constant symbols, c_1, c_2, \ldots
- (ii) A set **FS** of *function symbols*, f_1, f_2, \ldots Each function symbol f has a rank $n_f \ge 1$, which is the number of arguments of f.
- (iii) A set **PS** of *predicate symbols*, P_1, P_2, \ldots Each predicate symbol P has a rank $n_P \ge 0$, which is the number of arguments of P. Predicate symbols of rank 0 are *propositional symbols* as in earlier sections.

- (iv) The *equality predicate* = is added to our language when we want to deal with equations.
- (v) First-order variables t_1, t_2, \ldots used to form quantified formulae.

The difference between function symbols and predicate symbols is that function symbols are interpreted as functions defined on a structure (e.g., addition, +, on \mathbb{N}), whereas predicate symbols are interpreted as properties of objects, that is, they take the value **true** or **false**.

Example 2.16. An example is the language of *Peano arithmetic*, $\mathbf{L} = \{0, S, +, *, =\}$, where 0 is a constant symbol, S is a function symbol with one argument, and +, * are function symbols with two arguments. Here, the intended structure is \mathbb{N} , 0 is of course zero, S is interpreted as the function S(n) = n + 1, the symbol + is addition, * is multiplication, and = is equality.

Using a first-order language L, we can form terms, predicate terms, and formulae.

Definition 2.28. The *terms over* **L** are the following expressions.

- (i) Every variable t is a term.
- (ii) Every constant symbol $c \in \mathbf{CS}$, is a term.
- (iii) If $f \in \mathbf{FS}$ is a function symbol taking *n* arguments and τ_1, \ldots, τ_n are terms already constructed, then $f(\tau_1, \ldots, \tau_n)$ is a term.

Definition 2.29. The *predicate terms over* **L** are the following expressions.

- (i) If $P \in \mathbf{PS}$ is a predicate symbol taking *n* arguments and τ_1, \ldots, τ_n are terms already constructed, then $P(\tau_1, \ldots, \tau_n)$ is a predicate term. When n = 0, the predicate symbol P is a predicate term called a propositional symbol.
- (ii) When we allow the equality predicate, for any two terms τ_1 and τ_2 , the expression $\tau_1 = \tau_2$ is a predicate term. It is usually called an *equation*.

Definition 2.30. The *(first-order) formulae over* **L** are the following expressions.

- (i) Every predicate term $P(\tau_1, \ldots, \tau_n)$ is an atomic formula. This includes all propositional letters. We also view \perp (and sometimes \top) as an atomic formula.
- (ii) When we allow the equality predicate, every equation $\tau_1 = \tau_2$ is an atomic formula.
- (iii) If P and Q are formulae already constructed, then $P \Rightarrow Q, P \land Q, P \lor Q, \neg P$ are compound formulae. We treat $P \equiv Q$ as an abbreviation for $(P \Rightarrow Q) \land (Q \Rightarrow P)$, as before.
- (iv) If P is a formula already constructed and t is any variable, then $\forall tP$ and $\exists tP$ are *quantified* compound formulae.

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All this can be made very precise but this is quite tedious. Our primary goal is to explain the basic rules of logic and not to teach a full-fledged logic course. We hope that our intuitive explanations will suffice, and we now come to the heart of the matter, the inference rules for the quantifiers. Once again, for a complete treatment, readers are referred to Gallier [24], van Dalen [75], or Huth and Ryan [41].

Unlike the rules for \Rightarrow , \lor , \land and \bot , which are rather straightforward, the rules for quantifiers are more subtle due to the presence of variables (occurring in terms and predicates). We have to be careful to forbid inferences that would yield "wrong" results and for this we have to be very precise about the way we use free variables. More specifically, we have to exercise care when we make substitutions of terms for variables in propositions.

Example 2.17. For example, say we have the predicate "odd," intended to express that a number is odd. Now, we can substitute the term $(2y + 1)^2$ for x in odd(x) and obtain

$$odd((2y+1)^2).$$

Definition 2.31. More generally, if $P(t_1, t_2, ..., t_n)$ is a statement containing the free variables $t_1, ..., t_n$ and if $\tau_1, ..., \tau_n$ are terms, we can form the new statement

$$P[\tau_1/t_1,\ldots,\tau_n/t_n]$$

obtained by substituting the term τ_i for all free occurrences of the variable t_i , for $i = 1, \ldots, n$.

By the way, we denote terms by the Greek letter τ because we use the letter t for a variable, and using t for both variables and terms would be confusing.

However, if $P(t_1, t_2, \ldots, t_n)$ contains quantifiers, some bad things can happen; namely, some of the variables occurring in some term τ_i may become quantified when τ_i is substituted for t_i .

Example 2.18. For example, consider

$$\forall x \exists y P(x, y, z)$$

which contains the free variable z and substitute the term x + y for z; we get

$$\forall x \exists y P(x, y, x+y).$$

We see that the variables x and y occurring in the term x + y become bound variables after substitution. We say that there is a "capture of variables."

This is not what we intended to happen. To fix this problem, we recall that bound variables are really placeholders, so they can be renamed without changing anything. Therefore, we can rename the bound variables x and y in $\forall x \exists y P(x, y, z)$ to u and v, getting the statement $\forall u \exists v P(u, v, z)$ and now, the result of the substitution is

$$\forall u \exists v P(u, v, x+y).$$

Again, all this needs to be explained very carefully but this can be done.

Finally, here are the inference rules for the quantifiers, first stated in a natural deduction style and then in sequent style.

2.18 The Proof Systems $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\forall,\exists,\perp}$ and $\mathcal{N}\mathcal{G}_{c}^{\Rightarrow,\wedge,\vee,\forall,\exists,\perp}$

It is assumed that we use two disjoint sets of variables for labeling premises (x, y, ...) and free variables (t, u, v, ...). As we show, the \forall -introduction rule and the \exists -elimination rule involve a *crucial restriction* on the occurrences of certain variables. Remember, *variables are terms*.

Definition 2.32. The inference rules for the quantifiers are

\forall -introduction:

If \mathcal{D} is a deduction tree for P[u/t] from the premises Γ , then

is a deduction tree for $\forall tP$ from the premises Γ . Here, u must be a variable that does not occur free in any of the propositions in Γ or in $\forall tP$. The notation P[u/t] stands for the result of substituting u for all free occurrences of t in P.

Recall that Γ denotes the multiset of premises of the deduction tree \mathcal{D} , so if \mathcal{D} only has one node, then $\Gamma = \{P[u/t]\}$ and t should not occur in P. See Example 2.20, which illustrates why this restriction is necessary.

\forall -elimination:

If \mathcal{D} is a deduction tree for $\forall tP$ from the premises Γ , then

$$\Gamma \\ \mathcal{D} \\ \frac{\forall tP}{P[\tau/t]}$$

is a deduction tree for $P[\tau/t]$ from the premises Γ . Here, τ is an arbitrary term and it is assumed that bound variables in P have been renamed so that none of the variables in τ are captured after substitution.

\exists -introduction:

If \mathcal{D} is a deduction tree for $P[\tau/t]$ from the premises Γ , then

is a deduction tree for $\exists tP$ from the premises Γ . As in \forall -elimination, τ is an arbitrary term and the same proviso on bound variables in P applies (no capture of variables when τ is substituted).

\exists -elimination:

If \mathcal{D}_1 is a deduction tree for $\exists t P$ from the premises Γ , and if \mathcal{D}_2 is a deduction tree for C from the premises in the multiset Δ and one or more occurrences of P[u/t], then

$$\frac{\Gamma}{D_1} \qquad \begin{array}{c} \Delta, P[u/t]^x \\ \mathcal{D}_1 \\ \exists tP \\ \hline C \end{array} \qquad \begin{array}{c} C \end{array} \qquad \begin{array}{c} x \end{array}$$

is a deduction tree of C from the set of premises in the multiset Γ, Δ . Here, u must be a variable that *does not occur free in any of the propositions in* Δ , $\exists tP$, or C, and all premises P[u/t] labeled x are discharged.

In the \forall -introduction and the \exists -elimination rules, the variable u is called the *eigenvariable* of the inference.

In the above rules, Γ or Δ may be empty; P, C denote arbitrary propositions constructed from a first-order language \mathbf{L} ; $\mathcal{D}, \mathcal{D}_1, \mathcal{D}_2$ are deductions, possibly a one-node tree; and t is *any* variable.

Definition 2.33. The system of *first-order classical logic* $\mathcal{N}_c^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$ is obtained by adding the above rules to the system of propositional classical logic $\mathcal{N}_c^{\Rightarrow,\vee,\wedge,\perp}$. The system of *first-order intuitionistic logic* $\mathcal{N}_i^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$ is obtained by adding the above rules to the system of propositional intuitionistic logic $\mathcal{N}_i^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$. Deduction trees and proof trees are defined as in the propositional case, except that the quantifier rules are also allowed.

Using sequents, the quantifier rules in first-order logic are expressed as follows:

Definition 2.34. The inference rules for the quantifiers in Gentzen-sequent style are

$$\frac{\Gamma \to P[u/t]}{\Gamma \to \forall tP} \quad (\forall \text{-intro}) \qquad \frac{\Gamma \to \forall tP}{\Gamma \to P[\tau/t]} \quad (\forall \text{-elim}),$$

where in $(\forall$ -intro), u does not occur free in Γ or $\forall tP$;

$$\frac{\Gamma \to P[\tau/t]}{\Gamma \to \exists t P} \quad (\exists \text{-intro}) \qquad \frac{\Gamma \to \exists t P \quad z \colon P[u/t], \Delta \to C}{\Gamma \cup \Delta \to C} \quad (\exists \text{-elim})$$

where in $(\exists \text{-elim})$, $z \colon P[u/t] \notin \Delta$, and u does not occur free in Δ , $\exists tP$, or C. Again, t is any variable.

The variable u is called the *eigenvariable* of the inference.

Definition 2.35. The systems $\mathcal{NG}_{c}^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$ and $\mathcal{NG}_{i}^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$ are defined from the systems $\mathcal{NG}_{c}^{\Rightarrow,\vee,\wedge,\perp}$ and $\mathcal{NG}_{i}^{\Rightarrow,\vee,\wedge,\perp}$, respectively, by adding the above rules. As usual, a *deduction tree* is either a one-node tree or a tree constructed using the above rules and a *proof tree* is a deduction tree whose conclusion is a sequent with an empty set of premises (a sequent of the form $\emptyset \to P$).

When we say that a proposition P is provable from Γ , we mean that we can construct a proof tree whose conclusion is P and whose set of premises is Γ in one of the systems $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ or $\mathcal{N}\mathcal{G}_c^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$. Therefore, as in propositional logic, when we use the word "provable" unqualified, we mean provable in *classical logic*. Otherwise, we say *intuitionistically provable*.

It is not hard to show that the proof systems $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ and $\mathcal{N}\mathcal{G}_{c}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ are equivalent (and similarly, for $\mathcal{N}_{i}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ and $\mathcal{N}\mathcal{G}_{i}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$). We leave the details as Problem 2.16.

A first look at the above rules shows that universal formulae $\forall tP$ behave somewhat like infinite conjunctions and existential formulae $\exists tP$ behave somewhat like infinite disjunctions.

The \forall -introduction rule looks a little strange but the idea behind it is actually very simple: because u is totally unconstrained, if P[u/t] is provable (from Γ), then intuitively, P[u/t] holds for any arbitrary object, and so, the statement $\forall tP$ should also be provable (from Γ). Note that the tree

$$\frac{P[u/t]}{\forall tP}$$

is generally not a deduction, because the deduction tree above $\forall tP$ is a one-node tree consisting of the single premise P[u/t], and u occurs in P[u/t] unless t does not occur in P.

The meaning of the \forall -elimination is that if $\forall tP$ is provable (from Γ), then P holds for all objects and so, in particular for the object denoted by the term τ ; that is, $P[\tau/t]$ should be provable (from Γ).

The \exists -introduction rule is dual to the \forall -elimination rule. If $P[\tau/t]$ is provable (from Γ), this means that the object denoted by τ satisfies P, so $\exists tP$ should be provable (this latter formula asserts the existence of some object satisfying P, and τ is such an object).

The \exists -elimination rule is reminiscent of the \lor -elimination rule and is a little more tricky. It goes as follows. Suppose that we proved $\exists tP$ (from Γ). Moreover, suppose that for every possible case P[u/t] we were able to prove C (from Γ). Then, as we have "exhausted" all possible cases and as we know from the provability of $\exists tP$ that some case must hold, we can conclude that C is provable (from Γ) without using P[u/t] as a premise.

Like the \lor -elimination rule, the \exists -elimination rule is not very constructive. It allows making a conclusion (C) by considering alternatives without knowing which one actually occurs.

Remark: Analogously to disjunction, in (first-order) intuitionistic logic, if an existential statement $\exists tP$ is provable, then from any proof of $\exists tP$, some term τ can be extracted so that $P[\tau/t]$ is provable. Such a term τ is called a *witness*. The witness property is not easy to prove. It follows from the fact that intuitionistic proofs have a normal form (see Section 2.13). However, no such property holds in classical logic.

We can illustrate, again, the fact that classical logic allows for nonconstructive proofs by re-examining the example at the end of Section 2.6.

There we proved that if $\sqrt{2}^{\sqrt{2}}$ is rational, then $a = \sqrt{2}$ and $b = \sqrt{2}$ are both irrational numbers such that a^b is rational, and if $\sqrt{2}^{\sqrt{2}}$ is irrational, then $a = \sqrt{2}^{\sqrt{2}}$ and $b = \sqrt{2}$ are

both irrational numbers such that a^b is rational. By \exists -introduction, we deduce that if $\sqrt{2}^{\sqrt{2}}$ is rational, then there exist some irrational numbers a, b so that a^b is rational, and if $\sqrt{2}^{\sqrt{2}}$ is irrational, then there exist some irrational numbers a, b so that a^b is rational. In classical logic, as $P \lor \neg P$ is provable, by \lor -elimination, we just proved that there exist some irrational numbers a and b so that a^b is rational.

However, this argument does not give us explicitly numbers a and b with the required properties. It only tells us that such numbers must exist. Now it turns out that $\sqrt{2}^{\sqrt{2}}$ is indeed irrational (this follows from the Gelfond–Schneider theorem, a hard theorem in number theory). Furthermore, there are also simpler explicit solutions such as $a = \sqrt{2}$ and $b = \log_2 9$, as the reader should check.

The following proposition lists some basic properties of substitutions. The easy proof is left as an exercise.

Proposition 2.13. The following properties of substitution in a first-order formula hold.

$$\begin{aligned} (P \wedge Q)[\tau/t] &= P[\tau/t] \wedge Q[\tau/t] \\ (P \vee Q)[\tau/t] &= P[\tau/t] \vee Q[\tau/t] \\ (P \Rightarrow Q)[\tau/t] &= P[\tau/t] \Rightarrow Q[\tau/t] \\ (\neg P)[\tau/t] &= \neg P[\tau/t] \\ (\forall sP)[\tau/t] &= \forall sP[\tau/t] \\ (\exists sP)[\tau/t] &= \exists sP[\tau/t], \end{aligned}$$

for any term τ such that no variable in τ is captured during the substitution (in particular, in the last two cases, the variable s does not occur in τ).

Example 2.19. Here is an example of a proof in the system $\mathcal{N}_c^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$ (actually, in the system $\mathcal{N}_i^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$) of the formula $\forall t(P \land Q) \Rightarrow \forall tP \land \forall tQ$.

$\forall t (P \land Q)^x$	$\forall t (P \land Q)^x$
$\overline{P[u/t] \wedge Q[u/t]}$	$\overline{P[u/t] \wedge Q[u/t]}$
P[u/t]	Q[u/t]
$\forall tP$	$\forall tQ$
$\forall tP$ /	$\wedge \forall tQ$
$\forall t(P \land Q) =$	$\Rightarrow \forall tP \land \forall tQ$

In the above proof, u is a new variable, that is, a variable that does not occur free in P or Q.

The reader should show that $\forall tP \land \forall tQ \Rightarrow \forall t(P \land Q)$ is also provable in the system $\mathcal{N}_i^{\Rightarrow,\vee,\wedge,\perp,\forall,\exists}$. However, in general, one can't just replace \forall by \exists (or \land by \lor) and still obtain provable statements. For example, $\exists tP \land \exists tQ \Rightarrow \exists t(P \land Q)$ is not provable at all. We leave

it as an exercise to find an interpretation of the predicate symbols P and Q that yields a counter-example.

Example 2.20. Here is an example in which the \forall -introduction rule is applied illegally, and thus, yields a statement that is actually false (not provable). In the incorrect "proof" below, P is an atomic predicate symbol taking two arguments (e.g., "parent") and 0 is a constant denoting zero.

$$\begin{array}{c} \displaystyle \frac{P(u,0)^x}{\forall tP(t,0)} & \text{illegal step!} \\ \\ \displaystyle \frac{P(u,0) \Rightarrow \forall tP(t,0)}{P(u,0) \Rightarrow \forall tP(t,0)} & \text{Implication-Intro } x \\ \hline \\ \displaystyle \frac{\forall s(P(s,0) \Rightarrow \forall tP(t,0))}{P(0,0) \Rightarrow \forall tP(t,0)} & \text{Forall-Intro} \\ \end{array}$$

The problem is that the variable u occurs free in the premise P[u/t, 0] = P(u, 0) and therefore, the application of the \forall -introduction rule in the first step is illegal. However, note that this premise is discharged in the second step and so, the application of the \forall introduction rule in the third step is legal. The (false) conclusion of this faulty proof is that $P(0,0) \Rightarrow \forall tP(t,0)$ is provable. Indeed, there are plenty of properties such that the fact that the single instance P(0,0) holds does not imply that P(t,0) holds for all t.

Remark: The above example shows why *it is desirable to have premises that are universally* quantified. A premise of the form $\forall tP$ can be instantiated to P[u/t], using \forall -elimination, where u is a brand new variable. Later on, it may be possible to use \forall -introduction without running into trouble with free occurrences of u in the premises. But, we still have to be very careful when we use \forall -introduction or \exists -elimination.

Here are some useful equivalences involving quantifiers. The first two are analogous to the de Morgan laws for \wedge and \vee .

Proposition 2.14. The following equivalences are provable in classical first-order logic.

$$\neg \forall tP \equiv \exists t \neg P$$
$$\neg \exists tP \equiv \forall t \neg P$$
$$\forall t(P \land Q) \equiv \forall tP \land \forall tQ$$
$$\exists t(P \lor Q) \equiv \exists tP \lor \exists tQ.$$

In fact, the last three and $\exists t \neg P \Rightarrow \neg \forall tP$ are provable intuitionistically. Moreover, the formulae

$$\exists t(P \land Q) \Rightarrow \exists tP \land \exists tQ \quad and \quad \forall tP \lor \forall tQ \Rightarrow \forall t(P \lor Q)$$

are provable in intuitionistic first-order logic (and thus, also in classical first-order logic).

Proof. Left as an exercise to the reader.

Before concluding this section, let us give a few more examples of proofs using the rules for the quantifiers.

2.19 Examples of First-Order Proof Trees

Example 2.21. First, let us prove that

 $\forall tP \equiv \forall uP[u/t],$

where u is any variable not free in $\forall tP$ and such that u is not captured during the substitution. This rule allows us to rename bound variables (under very mild conditions). We have the proofs

$$\frac{\frac{(\forall tP)^{\alpha}}{P[u/t]}}{\forall uP[u/t]} \quad \alpha$$

$$\frac{\forall tP \Rightarrow \forall uP[u/t]}{\forall tP \Rightarrow \forall uP[u/t]} \quad \alpha$$

and

$$\frac{\frac{(\forall u P[u/t])^{\alpha}}{\frac{P[u/t]}{\forall tP}}}{\frac{\forall u P[u/t] \Rightarrow \forall tP}{}} \quad \alpha$$

Example 2.22. Next, we give intuitionistic proofs of

$$(\exists t P \land Q) \Rightarrow \exists t (P \land Q)$$

and

 $\exists t(P \land Q) \Rightarrow (\exists tP \land Q),$

where t does not occur (free or bound) in Q.

Here is an intuitionistic proof of the first implication.

$$\frac{(\exists tP \land Q)^{x}}{\exists tP} \qquad \frac{P[u/t]^{y}}{Q} \qquad \frac{Q}{Q}}{\exists t(P \land Q)} \\
\frac{(\exists tP \land Q)^{x}}{\exists tP} \qquad \frac{P[u/t] \land Q}{\exists t(P \land Q)}}{(\exists tP \land Q) \Rightarrow \exists t(P \land Q)} \qquad y \ (\exists \text{-elim})$$

In the above proof, u is a new variable that does not occur in $\exists tP$ or Q. Because t does not occur in Q, we have

$$(P \wedge Q)[u/t] = P[u/t] \wedge Q.$$

Here is an intuitionistic proof of the converse in which $(P \land Q)$ is abbreviated as A.

$$\frac{(\exists tA)^{x}}{\exists tP} \xrightarrow{\begin{array}{c} P[u/t] \land Q)^{y} \\ \hline P[u/t] \\ \hline \exists tP \end{array}} & (\exists tA)^{x} \xrightarrow{\begin{array}{c} (P[u/t] \land Q)^{z} \\ \hline Q \end{array}} \\ y (\exists \text{-elim}) \xrightarrow{\begin{array}{c} (\exists tA)^{x} \end{array}} Q \end{array} z (\exists \text{-elim}) \\ \hline \hline Q \\ \hline \hline \exists tP \land Q \\ \hline \exists t(P \land Q) \Rightarrow (\exists tP \land Q) \end{array}$$

Example 2.23. Here is now a proof (intuitionistic) of

$$\exists t(P \Rightarrow Q) \Rightarrow (\forall tP \Rightarrow Q),$$

•

•

where t does not occur (free or bound) in Q.

$$\begin{array}{c} \displaystyle \frac{(\exists t(P \Rightarrow Q))^z}{(\exists t(P \Rightarrow Q))^z} & \frac{(P[u/t] \Rightarrow Q)^x}{Q} \\ \hline \\ \hline \\ \displaystyle \frac{Q}{\forall tP \Rightarrow Q} & x \ (\exists \text{-elim}) \\ \hline \\ \hline \\ \displaystyle \frac{Q}{\forall tP \Rightarrow Q} & z \\ \hline \\ \hline \\ \displaystyle \exists t(P \Rightarrow Q) \Rightarrow (\forall tP \Rightarrow Q) & z \end{array}$$

In the above proof, u is a new variable that does not occur in Q, $\forall tP$, or $\exists t(P \Rightarrow Q)$. Because t does not occur in Q, we have

$$(P \Rightarrow Q)[u/t] = P[u/t] \Rightarrow Q.$$

The converse requires (RAA) and is a bit more complicated.

Example 2.24. Here is a classical proof in which $(P \Rightarrow Q)$ is abbreviated as A.

		$\neg P[u/t]^d$	$\delta P[u/t]$	γ
		-	$\frac{\perp}{Q}$	
$\frac{P[u/t]^{\alpha},Q^{\beta}}{}$		P[u/t]	$t] \Rightarrow Q$	γ
α	$(\neg \exists tA)^y$	$\exists t(P$	$\Rightarrow Q)$	
$\underline{P[u/t] \Rightarrow Q}$		\perp	δ (RAA	<i>-</i>)
$(\neg \exists tA)^y \exists t(P \Rightarrow Q)$		P[u/t]	X	/
$\underline{\qquad} \qquad \underline{\qquad} \qquad \qquad} \qquad \underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad \underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad \underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad \underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad \underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad} \qquad} \qquad\underline{\qquad}\qquad} \qquad \underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\underline{\qquad}\qquad} \qquad\qquad\underline{\qquad}\qquad} \qquad\qquad \underline{\qquad}\qquad} \qquad\qquad\underline{\qquad}\qquad}\qquad\qquad\underline{\qquad}\qquad}\qquad\qquad\underline{\qquad}\qquad}\qquad\qquad}$		$\forall tP$		
$- \neg Q$	Q			
$\frac{\bot}{\exists t(P \Rightarrow Q)}$	y (RA)	AA)		
$\overline{(\forall tP \Rightarrow Q) \Rightarrow \exists t}$	$(P \Rightarrow Q)$	x		

Example 2.25. Finally, we give a proof (intuitionistic) of

$$(\forall tP \lor Q) \Rightarrow \forall t(P \lor Q),$$

where t does not occur (free or bound) in Q.

$$\frac{\frac{(\forall tP)^{x}}{P[u/t]}}{(\forall tP \lor Q)^{z}} \frac{\frac{Q^{y}}{P[u/t] \lor Q}}{\forall t(P \lor Q)} \qquad \frac{Q^{y}}{P[u/t] \lor Q}}{\frac{P[u/t] \lor Q}{\forall t(P \lor Q)}} \quad x,y \text{ (\forall-elim$)}}{(\forall tP \lor Q) \Rightarrow \forall t(P \lor Q)}^{z} \qquad .$$

In the above proof, u is a new variable that does not occur in $\forall tP$ or Q. Because t does not occur in Q, we have

$$(P \lor Q)[u/t] = P[u/t] \lor Q.$$

The converse requires (RAA).

The useful above equivalences (and more) are summarized in the following propositions. **Proposition 2.15.** (1) The following equivalences are provable in classical first-order logic,

.

provided that t does not occur (free or bound) in Q.

$$\forall tP \land Q \equiv \forall t(P \land Q) \\ \exists tP \lor Q \equiv \exists t(P \lor Q) \\ \exists tP \land Q \equiv \exists t(P \land Q) \\ \forall tP \lor Q \equiv \forall t(P \lor Q).$$

Furthermore, the first three are provable intuitionistically and so is $(\forall t P \lor Q) \Rightarrow \forall t (P \lor Q)$.

(2) The following equivalences are provable in classical logic, provided that t does not occur (free or bound) in P.

$$\forall t(P \Rightarrow Q) \equiv (P \Rightarrow \forall tQ)$$
$$\exists t(P \Rightarrow Q) \equiv (P \Rightarrow \exists tQ).$$

Furthermore, the first one is provable intuitionistically and so is $\exists t(P \Rightarrow Q) \Rightarrow (P \Rightarrow \exists tQ)$.

(3) The following equivalences are provable in classical logic, provided that t does not occur (free or bound) in Q.

$$\forall t(P \Rightarrow Q) \equiv (\exists tP \Rightarrow Q)$$
$$\exists t(P \Rightarrow Q) \equiv (\forall tP \Rightarrow Q).$$

Furthermore, the first one is provable intuitionistically and so is $\exists t(P \Rightarrow Q) \Rightarrow (\forall tP \Rightarrow Q)$.

Proofs that have not been supplied are left as exercises.

Obviously, every first-order formula that is provable intuitionistically is also provable classically, and we know that there are formulae that are provable classically but *not* provable intuitionistically. Therefore, it appears that classical logic is more general than intuitionistic logic. However, this is not quite so because there is a way of translating classical logic into intuitionistic logic. To be more precise, every classical formula A can be translated into a formula A^* , where A^* is classically equivalent to A and A is provable classically iff A^* is provable intuitionistically. Various translations are known, all based on a "trick" involving double-negation (this is because $\neg \neg \neg A$ and $\neg A$ are intuitionistically equivalent). Translations were given by Kolmogorov (1925), Gödel (1933), and Gentzen (1933).

For example, Gödel used the following negative translation.

$$A^* = \neg \neg A, \quad \text{if } A \text{ is atomic}$$
$$(\neg A)^* = \neg A^*$$
$$(A \land B)^* = (A^* \land B^*)$$
$$(A \Rightarrow B)^* = \neg (A^* \land \neg B^*)$$
$$(A \lor B)^* = \neg (\neg A^* \land \neg B^*)$$
$$(\forall x A)^* = \forall x A^*$$
$$(\exists x A)^* = \neg \forall x \neg A^*.$$



Figure 2.12: Andrey N. Kolmogorov, 1903–1987 (left) and Kurt Gödel, 1906–1978 (right).

Actually, if we restrict our attention to propositions (i.e., formulae without quantifiers), a theorem of V. Glivenko (1929) states that if a proposition A is provable classically, then $\neg \neg A$ is provable intuitionistically. In view of these results, the proponents of intuitionistic logic claim that classical logic is really a special case of intuitionistic logic. However, the above translations have some undesirable properties, as noticed by Girard. For more details on all this; see Gallier [18].

2.20 First-Order Theories; Peano Arithmetic

The way we presented deduction trees and proof trees may have given our readers the impression that the set of premises Γ was just an auxiliary notion. Indeed, in all of our examples, Γ ends up being empty. However, nonempty Γ s are *crucially needed* if we want to develop theories about various kinds of structures and objects, such as the natural numbers, groups, rings, fields, trees, graphs, sets, and the like. Indeed, we need to make definitions about the objects we want to study and we need to state some axioms asserting the main properties of these objects. We do this by putting these definitions and axioms in Γ .

Actually, we have to allow Γ to be *infinite* but we still require that our deduction trees be *finite*; they can only use finitely many of the formulae in Γ .

Definition 2.36. Given a (possibly infinite) set of premises Γ , the set of all formulae P such that $\Delta \to P$ is provable, where Δ is any finite subset of Γ , is called a *theory* (or *first-order theory*).

Of course we have the usual problem of consistency: if we are not careful, our theory may be inconsistent, that is, it may consist of all formulae.

Let us give two examples of theories.

Example 2.26. Our first example is the *theory of equality*. Indeed, our readers may have noticed that we have avoided dealing with the equality relation. In practice, we can't do that.

Given a language L with a given supply of constant, function, and predicate symbols,

the theory of equality consists of the following formulae taken as axioms.

$$\begin{aligned} \forall x(x=x) \\ \forall x_1 \cdots \forall x_n \forall y_1 \cdots \forall y_n [(x_1 = y_1 \land \cdots \land x_n = y_n) \\ \Rightarrow f(x_1, \dots, x_n) &= f(y_1, \dots, y_n)] \\ \forall x_1 \cdots \forall x_n \forall y_1 \cdots \forall y_n [(x_1 = y_1 \land \cdots \land x_n = y_n) \land P(x_1, \dots, x_n) \\ \Rightarrow P(y_1, \dots, y_n)], \end{aligned}$$

for all function symbols (of n arguments) and all predicate symbols (of n arguments), including the equality predicate, =, itself.

It is not immediately clear from the above axioms that = is symmetric and transitive but this can be shown easily.

Example 2.27. Our second example is the first-order theory of the natural numbers known as *Peano arithmetic* (for short, *PA*). In this case, the language **L** consists of the nonlogical symbols $\{0, S, +, *, =\}$. Here, we have the constant 0 (zero), the unary function symbol S (for successor function; the intended meaning is S(n) = n + 1) and the binary function symbols + (for addition) and * (for multiplication). In addition to the axioms for the theory of equality, we have the following axioms:

$$\begin{aligned} \forall x \neg (S(x) = 0) \\ \forall x \forall y (S(x) = S(y) \Rightarrow x = y) \\ \forall x (x + 0 = x) \\ \forall x \forall y (x + S(y) = S(x + y)) \\ \forall x (x * 0 = 0) \\ \forall x \forall y (x * S(y) = x * y + x) \\ [A(0) \land \forall x (A(x) \Rightarrow A(S(x)))] \Rightarrow \forall n A(n), \end{aligned}$$

where A is any first-order formula with one free variable.



Figure 2.13: Giuseppe Peano, 1858–1932.

This last axiom is the *induction axiom*. Observe how + and * are defined recursively in terms of 0 and S and that there are *infinitely many* induction axioms (countably many).



Figure 2.14: Kurt Gödel with Albert Einstein.

Many properties that hold for the natural numbers (i.e., are true when the symbols 0, S, +, * have their usual interpretation and all variables range over the natural numbers) can be proven in this theory (Peano arithmetic), but not all. This is another very famous result of Gödel known as Gödel's incompleteness theorem (1931). However, the topic of incompleteness is definitely outside the scope of this book, so we do not say any more about it.

However, we feel that it should be instructive for the reader to see how simple properties of the natural numbers can be derived (in principle) in Peano arithmetic.

First, it is convenient to introduce abbreviations for the terms of the form $S^n(0)$ (where S^n denotes the *n*-fold composition of S with itself), which represent the natural numbers. Thus, we add a countable supply of constants, $0, 1, 2, 3, \ldots$, to denote the natural numbers and add the axioms

$$n = S^n(0),$$

for all natural numbers n. We also write n + 1 for S(n).

Let us illustrate the use of the quantifier rules involving terms (\forall -introduction, \forall -elimination, and \exists -introduction) by proving some simple properties of the natural numbers, namely, being even or odd. We also prove a property of the natural number that we used before (in the proof that $\sqrt{2}$ is irrational), namely, that every natural number is either even or odd. For this, we add the predicate symbols "even" and "odd" to our language, and assume the following axioms defining these predicates:

$$\forall n(\operatorname{even}(n) \equiv \exists k(n = 2 * k)) \\ \forall n(\operatorname{odd}(n) \equiv \exists k(n = 2 * k + 1)).$$

Consider the term, 2 * (m + 1) * (m + 2) + 1, where m is any given natural number. We need a few preliminary results.

Proposition 2.16. The statement odd(2 * (m + 1) * (m + 2) + 1) is provable in Peano arithmetic.

As an auxiliary lemma, we first prove

Proposition 2.17. The formula

 $\forall x \operatorname{odd}(2 * x + 1)$

is provable in Peano arithmetic.

Proof. Let p be a variable not occurring in any of the axioms of Peano arithmetic (the variable p stands for an arbitrary natural number). From the axiom,

$$\forall n (\text{odd}(n) \equiv \exists k (n = 2 * k + 1)),$$

by \forall -elimination where the term 2 * p + 1 is substituted for the variable n, we get

$$odd(2*p+1) \equiv \exists k(2*p+1 = 2*k+1).$$
(*)

Now we can think of the provable equation 2 * p + 1 = 2 * p + 1 as

$$(2*p+1 = 2*k+1)[p/k],$$

so by \exists -introduction, we can conclude that

$$\exists k(2*p+1 = 2*k+1),$$

which, by (*), implies that

$$\mathrm{odd}(2*p+1).$$

But now, because p is a variable not occurring free in the axioms of Peano arithmetic, by \forall -introduction, we conclude that

$$\forall x \operatorname{odd}(2 * x + 1),$$

as claimed.

Proof of Proposition 2.16. If we use \forall -elimination in the formula of Proposition 2.17, where we substitute the term $\tau = (m+1) * (m+2)$ for x, we get

$$odd(2 * (m+1) * (m+2) + 1),$$

as claimed

Now we wish to prove

Proposition 2.18. The formula

$$\forall n(\operatorname{even}(n) \lor \operatorname{odd}(n))$$

is provable in Peano arithmetic.
Proof. We use the induction principle of Peano arithmetic with

$$A(n) = \operatorname{even}(n) \lor \operatorname{odd}(n).$$

For the base case, n = 0, because 0 = 2 * 0 (which can be proven from the Peano axioms), we see that even(0) holds and so even(0) \lor odd(0) is proven.

For n = 1, because 1 = 2 * 0 + 1 (which can be proven from the Peano axioms), we see that odd(1) holds and so even(1) \lor odd(1) is proven.

For the induction step, we may assume that A(n) has been proven and we need to prove that A(n+1) holds.

So, assume that $even(n) \lor odd(n)$ holds. We do a proof by cases.

(a) If even(n) holds, by definition this means that n = 2k for some k and then, n + 1 = 2k+1, which again, by definition means that odd(n+1) holds and thus, $even(n+1)\vee odd(n+1)$ holds.

(b) If odd(n) holds, by definition this means that n = 2k + 1 for some k and then, n+1 = 2k+2 = 2(k+1), which again, by definition means that even(n+1) holds and thus, $even(n+1) \lor odd(n+1)$ holds.

By \vee -elimination, we conclude that $even(n + 1) \vee odd(n + 1)$ holds, establishing the induction step.

Therefore, using induction, we have proven that

$$\forall n (\operatorname{even}(n) \lor \operatorname{odd}(n)),$$

as claimed.

Actually, we can show that even(n) and odd(n) are mutually exclusive as we now prove.

Proposition 2.19. The formula

$$\forall n \neg (\operatorname{even}(n) \land \operatorname{odd}(n))$$

is provable in Peano arithmetic.

Proof. We prove this by induction. For n = 0, the statement odd(0) means that 0 = 2k+1 = S(2k), for some k. However, the first axiom of Peano arithmetic states that $S(x) \neq 0$ for all x, so we get a contradiction.

For the induction step, assume that $\neg(\operatorname{even}(n) \land \operatorname{odd}(n))$ holds. We need to prove that $\neg(\operatorname{even}(n+1) \land \operatorname{odd}(n+1))$ holds, and we can do this by using our constructive proof-bycontradiction rule. So, assume that $\operatorname{even}(n+1) \land \operatorname{odd}(n+1)$ holds. At this stage, we realize that if we could prove that

$$\forall n(\operatorname{even}(n+1) \Rightarrow \operatorname{odd}(n)) \tag{(*)}$$

and

$$\forall n (\text{odd}(n+1) \Rightarrow \text{even}(n)), \tag{**}$$

then $\operatorname{even}(n+1) \wedge \operatorname{odd}(n+1)$ would imply $\operatorname{even}(n) \wedge \operatorname{odd}(n)$, contradicting the assumption $\neg(\operatorname{even}(n) \wedge \operatorname{odd}(n))$. Therefore, the proof is complete if we can prove (*) and (**).

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Let's consider the implication (*) leaving the proof of (**) as an exercise.

Assume that even(n + 1) holds. Then n + 1 = 2k, for some natural number k. We can't have k = 0 because otherwise we would have n + 1 = 0, contradicting one of the Peano axioms. But then k is of the form k = h + 1 for some natural number h, so

$$n + 1 = 2k = 2(h + 1) = 2h + 2 = (2h + 1) + 1.$$

By the second Peano axiom, we must have

$$n = 2h + 1,$$

which proves that n is odd, as desired.

In that last proof, we made implicit use of the fact that every natural number n different from zero is of the form n = m + 1, for some natural number m which is formalized as

$$\forall n((n \neq 0) \Rightarrow \exists m(n = m + 1)).$$

This is easily proven by induction.

Having done all this work, we have finally proven (*) and after proving (**), we will have proven that

$$\forall n \neg (\operatorname{even}(n) \land \operatorname{odd}(n)),$$

as claimed.

It is also easy to prove that

 $\forall n(\operatorname{even}(n) \lor \operatorname{odd}(n))$

and

$$\forall n \neg (\operatorname{even}(n) \land \operatorname{odd}(n))$$

together imply that

$$\forall n(\operatorname{even}(n) \equiv \neg \operatorname{odd}(n)) \quad \text{and} \quad \forall n(\operatorname{odd}(n) \equiv \neg \operatorname{even}(n))$$

are provable, facts that we used several times in Section 2.10. This is because, if

$$\forall x(P \lor Q) \text{ and } \forall x \neg (P \land Q)$$

can be deduced intuitionistically from a set of premises Γ , then

$$\forall x (P \equiv \neg Q) \text{ and } \forall x (Q \equiv \neg P)$$

can also be deduced intuitionistically from Γ . In this case, it also follows that $\forall x(\neg \neg P \equiv P)$ and $\forall x(\neg \neg Q \equiv Q)$ can be deduced intuitionistically from Γ .

Remark: Even though we proved that every nonzero natural number n is of the form n = m + 1, for some natural number m, the expression n - 1 does not make sense because

the predecessor function $n \mapsto n-1$ has not been defined yet in our logical system. We need to define a function symbol "pred" satisfying the axioms

$$pred(0) = 0$$
$$\forall n(pred(n+1) = n).$$

For simplicity of notation, we write n-1 instead of pred(n). Then we can prove that if $k \neq 0$, then 2k-1 = 2(k-1)+1 (which really should be written as pred(2k) = 2pred(k)+1). This can indeed be done by induction; we leave the details as an exercise. We can also define substraction, -, as a function, sastisfying the axioms

$$\forall n(n-0=n)$$

$$\forall n \forall m(n-(m+1) = \operatorname{pred}(n-m)).$$

It is then possible to prove the usual properties of subtraction (by induction).

These examples of proofs in the theory of Peano arithmetic illustrate the fact that constructing proofs in an axiomatized theory is a very laborious and tedious process. Many small technical lemmas need to be established from the axioms, which renders these proofs very lengthy and often unintuitive. It is therefore important to build up a database of useful basic facts if we wish to prove, with a certain amount of comfort, properties of objects whose properties are defined by an axiomatic theory (such as the natural numbers). However, when in doubt, we can always go back to the formal theory and try to prove rigorously the facts that we are not sure about, even though this is usually a tedious and painful process. Human provers navigate in a "spectrum of formality," most of the time constructing informal proofs containing quite a few (harmless) shortcuts, sometimes making extra efforts to construct more formalized and rigorous arguments if the need arises.

Now, what if the theory of Peano arithmetic were inconsistent! How do we know that Peano arithmetic does not imply any contradiction? This is an important and hard question that motivated a lot of the work of Gentzen. An easy answer is that the *standard model* \mathbb{N} of the natural numbers under addition and multiplication validates all the axioms of Peano arithmetic. Therefore, if both P and $\neg P$ could be proven from the Peano axioms, then both P and $\neg P$ would be true in \mathbb{N} , which is absurd. To make all this rigorous, we need to define the notion of *truth in a structure*, a notion explained in every logic book. It should be noted that the constructivists will object to the above method for showing the consistency of Peano arithmetic, because it assumes that the infinite set \mathbb{N} exists as a completed entity. Until further notice, we have faith in the consistency of Peano arithmetic (so far, no inconsistency has been found).

Another very interesting theory is *set theory*. There are a number of axiomatizations of set theory and we discuss one of them (ZFC) briefly in Section 2.21.

2.21 Basics Concepts of Set Theory

This section takes the very "naive" point of view that a set is an unordered collection of objects, without duplicates, the collection being regarded as a single object. Having first-

order logic at our disposal, we could formalize set theory very rigorously in terms of axioms. This was done by Zermelo first (1908) and in a more satisfactory form by Zermelo and Fraenkel in 1921, in a theory known as the "Zermelo–Fraenkel" (ZF) axioms. Another axiomatization was given by John von Neumann in 1925 and later improved by Bernays in 1937. A modification of Bernay's axioms was used by Kurt Gödel in 1940. This approach is now known as "von Neumann–Bernays" (VNB) or "Gödel–Bernays" (GB) set theory. There are many books that give an axiomatic presentation of set theory. Among them, we recommend Enderton [15], which we find remarkably clear and elegant, Suppes [70] (a little more advanced), and Halmos [32], a classic (at a more elementary level).



Figure 2.15: Ernst F. Zermelo, 1871–1953 (left), Adolf A. Fraenkel, 1891–1965 (middle left), John von Neumann, 1903–1957 (middle right) and Paul I. Bernays, 1888–1977 (right).

However, it must be said that set theory was first created by Georg Cantor (1845–1918) between 1871 and 1879. However, Cantor's work was not unanimously well received by all mathematicians.



Figure 2.16: Georg F. L. P. Cantor, 1845–1918.

Cantor regarded infinite objects as objects to be treated in much the same way as finite sets, a point of view that was shocking to a number of very prominent mathematicians who bitterly attacked him (among them, the powerful Kronecker). Also, it turns out that some paradoxes in set theory popped up in the early 1900s, in particular, Russell's paradox.

Russell's paradox (found by Russell in 1902) has to do with the

"set of all sets that are not members of themselves,"

which we denote by

$$R = \{ x \mid x \notin x \}.$$



Figure 2.17: Bertrand A. W. Russell, 1872–1970.

(In general, the notation $\{x \mid P\}$ stand for the set of all objects satisfying the property P.) Now classically, either $R \in R$ or $R \notin R$. However, if $R \in R$, then the definition of R says

that $R \notin R$; if $R \notin R$, then again, the definition of R says that $R \in R$.

So we have a contradiction and the existence of such a set is a paradox. The problem is that we are allowing a property (here, $P(x) = x \notin x$), which is "too wild" and circular in nature. As we show, the way out, as found by Zermelo, is to place a restriction on the property P and also make sure that P picks out elements from some already given set (see the subset axioms below).

The apparition of these paradoxes prompted mathematicians, with Hilbert among its leaders, to put set theory on firmer ground. This was achieved by Zermelo, Fraenkel, von Neumann, Bernays, and Gödel, to name only the major players.

In what follows, we are assuming that we are working in classical logic. The language **L** of set theory consists of the symbols $\{\emptyset, \in, =\}$, where \emptyset is a constant symbol (corresponding to the empty set) and \in is binary predicate symbol (denoting set membership).

In set theory formalized in first-order logic, every object is a set. Instead of writing the membership relation as $\in (X, Y)$, we write $X \in Y$, which expresses that the set X belongs to the set Y. To reduce the level of formality, we often denote sets using capital letters and members of sets using lowercase letters, and so we write $a \in A$ for a belongs to the set A (even though a is also a set). Instead of $\neg(a \in A)$, we write

 $a \notin A$.

We introduce various operations on sets using definitions involving the logical connectives $\land, \lor, \neg, \forall$, and \exists .

In order to ensure the existence of some of these sets requires some of the *axioms of set* theory, but we are rather casual about that.

When are two sets A and B equal? This corresponds to the first axiom of set theory, called the

Extensionality Axiom

Two sets A and B are equal iff they have exactly the same elements; that is,

$$\forall x (x \in A \Rightarrow x \in B) \land \forall x (x \in B \Rightarrow x \in A).$$

The above says: every element of A is an element of B and conversely.

There is a special set having no elements at all, the *empty set*, denoted \emptyset . This is the following.

Empty Set Axiom

There is a set having no members. This set is denoted \emptyset and it is characterized by the property

 $\forall x (x \notin \emptyset).$

Remark: Beginners often wonder whether there is more than one empty set. For example, is the empty set of professors distinct from the empty set of potatoes?

The answer is, by the extensionality axiom, there is only *one* empty set.

Given any two objects a and b, we can form the set $\{a, b\}$ containing exactly these two objects. Amazingly enough, this must also be an axiom.

Pairing Axiom

Given any two objects a and b (think sets), there is a set $\{a, b\}$ having as members just a and b.

Observe that if a and b are identical, then we have the set $\{a, a\}$, which is denoted by $\{a\}$ and is called a *singleton set* (this set has a as its only element).

To form bigger sets, we use the union operation. This too requires an axiom.

Union Axiom (Version 1)

For any two sets A and B, there is a set $A \cup B$ called the union of A and B defined by

$$x \in A \cup B$$
 iff $(x \in A) \lor (x \in B)$.

This reads x is a member of $A \cup B$ if either x belongs to A or x belongs to B (or both). We also write

$$A \cup B = \{ x \mid x \in A \quad \text{or} \quad x \in B \}$$

Using the union operation, we can form bigger sets by taking unions with singletons. For example, we can form

$$\{a, b, c\} = \{a, b\} \cup \{c\}.$$

Remark: We can systematically construct bigger and bigger sets by the following method. Given any set A, let

$$A^+ = A \cup \{A\}.$$

If we start from the empty set, we obtain sets that can be used to define the natural numbers and the + operation corresponds to the successor function on the natural numbers (i.e., $n \mapsto n+1$).

Another operation is the power set formation. It is indeed a "powerful" operation, in the sense that it allows us to form very big sets. For this, it is helpful to define the notion of inclusion between sets. **Definition 2.37.** Given any two sets A and B, we say that A is a subset of B (or that A is included in B), denoted $A \subseteq B$, iff every element of A is also an element of B, that is,

$$\forall x (x \in A \Rightarrow x \in B).$$

We say that A is a proper subset of B iff $A \subseteq B$ and $A \neq B$. This implies that there is some $b \in B$ with $b \notin A$. We usually write $A \subset B$.

Observe that the equality of two sets can be expressed by

A = B iff $A \subseteq B$ and $B \subseteq A$.

Power Set Axiom

Given any set A, there is a set $\mathcal{P}(A)$ (also denoted 2^A), called the *power set of* A, whose members are exactly the subsets of A; that is,

$$X \in \mathcal{P}(A)$$
 iff $X \subseteq A$

For example, if $A = \{a, b, c\}$, then

$$\mathcal{P}(A) = \{\emptyset, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\}\},\$$

a set containing eight elements. Note that the empty set and A itself are always members of $\mathcal{P}(A)$.

Remark: If A has n elements, it is not hard to show that $\mathcal{P}(A)$ has 2^n elements. For this reason, many people, including us, prefer the notation 2^A for the power set of A.

At this stage, we define intersection and complementation. For this, given any set A and given a property P (specified by a first-order formula), we need to be able to define the subset of A consisting of those elements satisfying P. This subset is denoted by

$$\{x \in A \mid P\}$$

Unfortunately, there are problems with this construction. If the formula P is somehow a circular definition and refers to the subset that we are trying to define, then some paradoxes may arise.

The way out is to place a restriction on the formula used to define our subsets, and this leads to the subset axioms, first formulated by Zermelo. These axioms are also called *comprehension axioms* or *axioms of separation*.

Subset Axioms

For every first-order formula P, we have the axiom

$$\forall A \exists X \forall x (x \in X \quad \text{iff} \quad (x \in A) \land P),$$

where P does not contain X as a free variable. (However, P may contain x free.)

The subset axioms says that for every set A, there is a set X consisting exactly of those elements of A so that P holds. For short, we usually write

$$X = \{ x \in A \mid P \}.$$

As an example, consider the formula

$$P(B, x) = x \in B.$$

Then the subset axiom says

$$\forall A \exists X \forall x (x \in A \land x \in B).$$

which means that X is the set of elements that belong both to A and B.

This is called the *intersection of* A and B, denoted by $A \cap B$. Note that

$$A \cap B = \{ x \mid x \in A \text{ and } x \in B \}.$$

We can also define the relative complement of B in A, denoted A - B, given by the formula $P(B, x) = x \notin B$, so that

$$A - B = \{ x \mid x \in A \text{ and } x \notin B \}.$$

In particular, if A is any given set and B is any subset of A, the set A - B is also denoted \overline{B} and is called the *complement of B*.

The algebraic properties of union, intersection, and complementation are inherited from the properties of disjunction, conjunction, and negation. The following proposition lists some of the most important properties of union, intersection, and complementation.

Proposition 2.20. The following equations hold for all sets A, B, C.

$$A \cup \emptyset = A$$
$$A \cap \emptyset = \emptyset$$
$$A \cup A = A$$
$$A \cap A = A$$
$$A \cup B = B \cup A$$
$$A \cap B = B \cap A$$

The last two assert the commutativity of \cup and \cap . We have distributivity of \cap over \cup and \cup over \cap .

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$
$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C).$$

We have associativity of \cap and \cup .

$$A \cap (B \cap C) = (A \cap B) \cap C$$
$$A \cup (B \cup C) = (A \cup B) \cup C.$$

Proof. Use Proposition 2.5.

Because \land, \lor , and \neg satisfy the de Morgan laws (remember, we are dealing with classical logic), for any set X, the operations of union, intersection, and complementation on subsets of X satisfy the de Morgan laws.

Proposition 2.21. For every set X and any two subsets A, B of X, the following identities (de Morgan laws) hold.

$$\overline{\overline{A}} = A$$
$$\overline{(A \cap B)} = \overline{A} \cup \overline{B}$$
$$\overline{(A \cup B)} = \overline{A} \cap \overline{B}.$$

So far, the union axiom only applies to two sets but later on we need to form infinite unions. Thus, it is necessary to generalize our union axiom as follows.

Union Axiom (Final Version)

Given any set X (think of X as a set of sets), there is a set $\bigcup X$ defined so that

$$x \in \bigcup X$$
 iff $\exists B(B \in X \land x \in B).$

This says that $\bigcup X$ consists of all elements that belong to some member of X.

If we take $X = \{A, B\}$, where A and B are two sets, we see that

$$\bigcup \{A, B\} = A \cup B,$$

and so, our final version of the union axiom subsumes our previous union axiom, which we now discard in favor of the more general version.

Observe that

$$\bigcup \{A\} = A, \quad \bigcup \{A_1, \dots, A_n\} = A_1 \cup \dots \cup A_n.$$

and in particular, $\bigcup \emptyset = \emptyset$.

Using the subset axioms, we can also define infinite intersections. For every nonempty set X, there is a set $\bigcap X$ defined by

$$x \in \bigcap X$$
 iff $\forall B(B \in X \Rightarrow x \in B).$

The existence of $\bigcap X$ is justified as follows. Because X is nonempty, it contains some set, A; let

$$P(X, x) = \forall B(B \in X \Rightarrow x \in B).$$

Then, the subset axioms asserts the existence of a set Y so that for every x,

$$x \in Y$$
 iff $x \in A$ and $P(X, x)$,

which is equivalent to

$$x \in Y$$
 iff $P(X, x)$.

Therefore, the set Y is our desired set, $\bigcap X$.

Observe that

$$\bigcap \{A, B\} = A \cap B, \quad \bigcap \{A_1, \dots, A_n\} = A_1 \cap \dots \cap A_n.$$

Note that $\bigcap \emptyset$ is not defined. Intuitively, it would have to be the set of all sets, but such a set does not exist, as we now show. This is basically a version of Russell's paradox.

Theorem 2.22. (Russell) There is no set of all sets, that is, there is no set to which every other set belongs.

Proof. Let A be any set. We construct a set B that does not belong to A. If the set of all sets existed, then we could produce a set that does not belong to it, a contradiction. Let

$$B = \{ a \in A \mid a \notin a \}.$$

We claim that $B \notin A$. We proceed by contradiction, so assume $B \in A$. However, by the definition of B, we have

$$B \in B$$
 iff $B \in A$ and $B \notin B$.

Because $B \in A$, the above is equivalent to

$$B \in B$$
 iff $B \notin B$,

which is a contradiction. Therefore, $B \notin A$ and we deduce that there is no set of all sets. \Box

Remarks:

- (1) We should justify why the equivalence $B \in B$ iff $B \notin B$ is a contradiction. What we mean by "a contradiction" is that if the above equivalence holds, then we can derive \perp (falsity) and thus, all propositions become provable. This is because we can show that for any proposition P if $P \equiv \neg P$ is provable, then every proposition is provable. We leave the proof of this fact as an easy exercise for the reader. By the way, this holds classically as well as intuitionistically.
- (2) We said that in the subset axioms, the variable X is not allowed to occur free in P. A slight modification of Russell's paradox shows that allowing X to be free in P leads to paradoxical sets. For example, pick A to be any nonempty set and set $P(X, x) = x \notin X$. Then, look at the (alleged) set

$$X = \{ x \in A \mid x \notin X \}.$$

As an exercise, the reader should show that X is empty iff X is nonempty,



Figure 2.18: John von Neumann.

This is as far as we can go with the elementary notions of set theory that we have introduced so far. In order to proceed further, we need to define relations and functions, as we did in Chapter 13.3.

The reader may also wonder why we have not yet discussed infinite sets. This is because we don't know how to show that they exist. Again, perhaps surprisingly, this takes another axiom, the *axiom of infinity*. We also have to define when a set is infinite. However, we do not go into this right now. Instead, we accept that the set of natural numbers \mathbb{N} exists and is infinite. Once we have the notion of a function, we are able to show that other sets are infinite by comparing their "size" with that of \mathbb{N} . (This is also the purpose of *cardinal numbers*, but this would lead us too far afield).

Remark: In an axiomatic presentation of set theory, the natural numbers can be defined from the empty set using the operation $A \mapsto A^+ = A \cup \{A\}$ introduced just after the union axiom. The idea due to von Neumann is that the natural numbers, $0, 1, 2, 3, \ldots$, can be viewed as concise notations for the following sets.

$$0 = \emptyset$$

$$1 = 0^{+} = \{\emptyset\} = \{0\}$$

$$2 = 1^{+} = \{\emptyset, \{\emptyset\}\} = \{0, 1\}$$

$$3 = 2^{+} = \{\emptyset, \{\emptyset\}, \{\emptyset, \{\emptyset\}\}\} = \{0, 1, 2\}$$

:

$$n + 1 = n^{+} = \{0, 1, 2, \dots, n\}$$

:

However, the above subsumes induction. Thus, we have to proceed in a different way to avoid circularities.

Definition 2.38. We say that a set X is *inductive* iff

- (1) $\emptyset \in X$.
- (2) For every $A \in X$, we have $A^+ \in X$.

Axiom of Infinity

There is some inductive set.

Having done this, we make the following.

Definition 2.39. A *natural number* is a set that belongs to every inductive set.

Using the subset axioms, we can show that there is a set whose members are exactly the natural numbers. The argument is very similar to the one used to prove that arbitrary intersections exist. By the axiom of infinity, there is some inductive set, say A. Now consider the property P(x) which asserts that x belongs to every inductive set. By the subset axioms applied to P, there is a set \mathbb{N} , such that

$$x \in \mathbb{N}$$
 iff $x \in A$ and $P(x)$,

and because A is inductive and P says that x belongs to every inductive set, the above is equivalent to

$$x \in \mathbb{N}$$
 iff $P(x);$

that is, $x \in \mathbb{N}$ iff x belongs to every inductive set. Therefore, the set of all natural numbers \mathbb{N} does exist. The set \mathbb{N} is also denoted ω . We can now easily show the following.

Theorem 2.23. The set \mathbb{N} is inductive and it is a subset of every inductive set.

Proof. Recall that \emptyset belongs to every inductive set; so \emptyset is a natural number (0). As \mathbb{N} is the set of natural numbers, $\emptyset (= 0)$ belongs to \mathbb{N} . Secondly, if $n \in \mathbb{N}$, this means that n belongs to every inductive set (n is a natural number), which implies that $n^+ = n + 1$ belongs to every inductive set, which means that n + 1 is a natural number, that is, $n + 1 \in \mathbb{N}$. Because \mathbb{N} is the set of natural numbers and because every natural number belongs to every inductive set, we conclude that \mathbb{N} is a subset of every inductive set. \Box

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It would be tempting to view \mathbb{N} as the intersection of the family of inductive sets, but unfortunately, this family is not a set; it is too "big" to be a set.

As a consequence of the above fact, we obtain the following.

Induction Principle for \mathbb{N} : Any inductive subset of \mathbb{N} is equal to \mathbb{N} itself.

Now, in our setting, $0 = \emptyset$ and $n^+ = n + 1$, so the above principle can be restated as follows.

Induction Principle for \mathbb{N} (Version 2): For any subset, $S \subseteq \mathbb{N}$, if $0 \in S$ and $n + 1 \in S$ whenever $n \in S$, then $S = \mathbb{N}$.

This induction principle can be restated a little more conveniently in terms of the notion of function.

Remark: Zermelo–Fraenkel set theory (+ Choice) has three more axioms. The *axiom of choice*, the *replacement axioms*, and the *regularity axiom*. For our purposes, only the axiom of choice is needed, and we introduced it in Chapter 13.3.

The replacement axioms are needed to deal with ordinals and cardinals. The intuition behind these axioms is that the image of a set under a functional relation should be a set. **Definition 2.40.** Given any set A, if $\varphi(x, y)$ is a first-order formula, we say that φ is *functional on* A if

$$(\forall x \in A) \forall y_1 \forall y_2 (\varphi(x, y_1) \land \varphi(x, y_2) \Rightarrow y_1 = y_2).$$

The following question arises: is

$$B = \{ y \mid (\exists x \in A)\varphi(x, y) \},\$$

intuitively the image of A by φ , a set?

With the axioms introduced so far, it can be proven that the answer is **no**; see Enderton [15], Chapter 9.

The axioms of replacement fix this problem by declaring that B is a set. This implies that

$$H = \{(x, y) \mid (x \in A) \land \varphi(x, y)\}$$

is a subset of $A \times B$. Without these axioms, this can't be proven.

The replacement axioms are used to prove the validity of transfinite recursion. In turn, transfinite recursion is used to define the ordinals; see Enderton [15], Chapter 7.

The regularity axiom (also known as foundation axiom) states that for any nonempty set A, there is some element $m \in A$ such that $m \cap A = \emptyset$.

The regularity axiom prevents certain undesirable properties. Among other things, no set can be a member of itself, and there are no sets A and B, such that $A \in B$ and $B \in A$.

But this axiom goes beyond. It is possible to define a hierarchy of sets V_{α} indexed by the ordinals, and the axiom of regularity is equivalent to the fact that for every set A, there is some α , such that $A \subseteq V_{\alpha}$. We say that every set is grounded. See Enderton [15], Chapter 7.

As we said at the beginning of this section, set theory can be axiomatized in first-order logic. To illustrate the generality and expressiveness of first-order logic, we conclude this section by stating nine (out of ten) of the axioms of Zermelo-Fraenkel set theory (for short, ZFC) as first-order formulae. The language of Zermelo-Fraenkel set theory consists of the constant \emptyset (for the empty set), the equality symbol, and the binary predicate symbol \in for set membership. It is convenient to abbreviate $\neg(x = y)$ as $x \neq y$ and $\neg(x \in y)$ as $x \notin y$. The axioms are the equality axioms, the axiom of choice, and the following nine axioms.

- (1) $\forall A \forall B (\forall x (x \in A \equiv x \in B) \Rightarrow A = B)$
- (2) $\forall x (x \notin \emptyset)$
- (3) $\forall a \forall b \exists Z \forall x (x \in Z \equiv (x = a \lor x = b))$
- (4) $\forall X \exists Y \forall x (x \in Y \equiv \exists B (B \in X \land x \in B))$
- (5) $\forall A \exists Y \forall X (X \in Y \equiv \forall z (z \in X \Rightarrow z \in A))$
- (6) $\forall A \exists X \forall x (x \in X \equiv (x \in A) \land P)$
- (7) $\exists X (\emptyset \in X \land \forall y (y \in X \Rightarrow y \cup \{y\} \in X))$

(8)
$$\forall t_1 \cdots \forall t_k \forall A[(\forall x \in A) \forall y_1 \forall y_2 (\varphi(x, y_1) \land \varphi(x, y_2) \Rightarrow y_1 = y_2) \Rightarrow \exists B \forall y (y \in B \equiv (\exists x \in A) \varphi(x, y))]$$

(9) $(\forall A)((A \neq \emptyset) \Rightarrow (\exists m \in A)(m \cap A = \emptyset)),$

where P is any first-order formula that does not contain X free and $\varphi(x, y)$ is any first-order formula, whose free variables are x, y, t_1, \ldots, t_k and does not contain B free.

- Axiom (1) is the extensionality axiom.
- Axiom (2) is the empty set axiom.
- Axiom (3) asserts the existence of a set Y, whose only members are a and b. By extensionality, this set is unique and it is denoted $\{a, b\}$. We also denote $\{a, a\}$ by $\{a\}$.
- Axiom (4) asserts the existence of set Y, which is the union of all the sets that belong to X. By extensionality, this set is unique and it is denoted $\bigcup X$. When $X = \{A, B\}$, we write $\bigcup \{A, B\} = A \cup B$.
- Axiom (5) asserts the existence of set Y, which is the set of all subsets of A (the power set of A). By extensionality, this set is unique and it is denoted $\mathcal{P}(A)$ or 2^A .
- Axioms (6) are the subset axioms (or axioms of separation).
- Axiom (7) is the infinity axiom, stated using the abbreviations introduced above.
- Axioms (8) are replacement axioms.
- Axiom (9) is the regularity (or foundation) axiom.

For a comprehensive treatment of axiomatic set theory, see Enderton [15] and Suppes [70].

2.22 Summary

The main goal of this chapter is to describe precisely the logical rules used in mathematical reasoning and the notion of a mathematical proof. A brief introduction to set theory is also provided. We decided to describe the rules of reasoning in a formalism known as a natural deduction system because the logical rules of such a system mimic rather closely the informal rules that (nearly) everybody uses when constructing a proof in everyday life. Another advantage of natural deduction systems is that it is very easy to present various versions of the rules involving negation and thus, to explain why the "proof-by-contradiction" proof rule or the "law of the excluded middle" allow for the derivation of "nonconstructive" proofs. This is a subtle point often not even touched in traditional presentations of logic. However, inasmuch as most of our readers write computer programs and expect that their programs will not just promise to give an answer but will actually produce results, we feel that they will grasp rather easily the difference between constructive and nonconstructive proofs and appreciate the former, even if they are harder to find.

- We describe the syntax of *propositional logic*.
- The proof rules for *implication* are defined in a *natural deduction system* (Prawitz-style).
- Deductions proceed from assumptions (or premises) using inference rules.
- The process of *discharging* (or *closing*) a premise is explained. A *proof* is a deduction in which all the premises have been discharged.
- We explain how we can *search* for a proof using a combined bottom-up and top-down process.
- We propose another mechanism for describing the process of discharging a premise and this leads to a formulation of the rules in terms of *sequents* and a *Gentzen system*.
- We introduce falsity \perp and negation $\neg P$ as an abbreviation for $P \Rightarrow \perp$. We describe the inference rules for conjunction, disjunction, and negation, in both Prawitz-style and Gentzen-sequent-style *natural deduction systems*.
- One of the rules for negation is the *proof-by-contradiction* rule (also known as *RAA*).
- We define *intuitionistic* and *classical* logic.
- We introduce the notion of a *constructive* (or *intuitionistic*) proof and discuss the two nonconstructive culprits: $P \lor \neg P$ (the *law of the excluded middle*) and $\neg \neg P \Rightarrow P$ (*double-negation rule*).
- We show that $P \lor \neg P$ and $\neg \neg P \Rightarrow P$ are provable in classical logic

- We clear up some potential confusion involving the various versions of the rules regarding negation.
 - 1. RAA is not a special case of \neg -introduction.
 - 2. RAA is not equivalent to \perp -elimination; in fact, it implies it.
 - 3. Not all propositions of the form $P \vee \neg P$ are provable in intuitionistic logic. However, RAA holds in intuitionistic logic plus all propositions of the form $P \vee \neg P$.
 - 4. We define *double-negation elimination*.
- We present the *de Morgan laws* and prove their validity in classical logic.
- We present the *proof-by-contrapositive rule* and show that it is valid in classical logic.
- We give some examples of proofs of "real" statements.
- We give an example of a nonconstructive proof of the statement: there are two irrational numbers, *a* and *b*, so that *a^b* is rational.
- We explain the *truth-value semantics* of propositional logic.
- We define the *truth tables* for the propositional connectives
- We define the notions of *satisfiability*, *unsatisfiability*, *validity*, and *tautology*.
- We define the *satisfiability problem* and the *validity problem* (for classical propositional logic).
- We mention the *NP-completeness* of satisfiability.
- We discuss *soundness* (or *consistency*) and *completeness*.
- We state the *soundness and completeness theorems* for propositional classical logic formulated in natural deduction.
- We explain how to use *counterexamples* to prove that certain propositions are not provable.
- We give a brief introduction to *Kripke semantics* for propositional intuitionistic logic.
- We define *Kripke models* (based on a *set of worlds*).
- We define *validity* in a Kripke model.
- We state the *soundness and completeness theorems* for propositional intuitionistic logic formulated in natural deduction.

- We add *first-order quantifiers* ("for all" \forall and "there exists" \exists) to the language of propositional logic and define *first-order logic*.
- We describe *free* and *bound* variables.
- We give inference rules for the quantifiers in Prawitz-style and Gentzen-sequent-style *natural deduction systems*.
- We explain the *eigenvariable restriction* in the \forall -introduction and \exists -elimination rules.
- We prove some "de Morgan"-type rules for the quantified formulae valid in classical logic.
- We discuss the nonconstructiveness of proofs of certain existential statements.
- We explain briefly how classical logic can be translated into intuitionistic logic (the Gödel translation).
- We define *first-order theories* and give the example of *Peano arithmetic*.
- We revisit the *decision problem* and mention the *undecidability of the decision problem* for first-order logic (*Church's theorem*).
- We discuss the notion of *detours* in proofs and the notion of *proof normalization*.
- We mention *strong normalization*.
- We mention the correspondence between propositions and types and proofs and typed λ-terms (the *Curry–Howard isomorphism*).
- We mention *Gödel's completeness theorem* for first-order logic.
- Again, we mention the use of *counterexamples*.
- We mention Gödel's incompleteness theorem.
- We present informally the axioms of Zermelo-Fraenkel set theory (ZFC).
- We present *Russell's paradox*, a warning against "self-referential" definitions of sets.
- We define the *empty set* \emptyset , the set $\{a, b\}$ whose elements are a and b, the union $A \cup B$ of two sets A and B, and the *power set* 2^A of A.
- We state carefully Zermelo's subset axioms for defining the subset $\{x \in A \mid P\}$ of elements of a given set A satisfying a property P.
- Then, we define the *intersection* $A \cap B$ and the *relative complement* A B of two sets A and B.

- We also define the union $\bigcup A$ and intersection $\bigcap A$ of a set of sets A.
- We show that one should avoid sets that are "too big"; in particular, we prove that there is no set of all sets.
- We define the *natural numbers* "a la Von Neumann."
- We define *inductive sets* and state the *axiom of infinity*.
- We show that the natural numbers form an inductive set N, and thus, obtain an *induction principle for* N.
- We summarize the axioms of Zermelo–Fraenkel set theory in first-order logic.

2.23 Problems

Problem 2.1. (a) Give a proof of the proposition $P \Rightarrow (Q \Rightarrow P)$ in the system $\mathcal{N}_m^{\Rightarrow}$.

(b) Prove that if there are deduction trees of $P \Rightarrow Q$ and $Q \Rightarrow R$ from the set of premises Γ in the system $\mathcal{N}_m^{\Rightarrow}$, then there is a deduction tree for $P \Rightarrow R$ from Γ in $\mathcal{N}_m^{\Rightarrow}$.

Problem 2.2. Give a proof of the proposition $(P \Rightarrow Q) \Rightarrow ((P \Rightarrow (Q \Rightarrow R)) \Rightarrow (P \Rightarrow R))$ in the system $\mathcal{N}_m^{\Rightarrow}$.

Problem 2.3. (a) Prove the "de Morgan" laws in classical logic.

$$\neg (P \land Q) \equiv \neg P \lor \neg Q$$
$$\neg (P \lor Q) \equiv \neg P \land \neg Q.$$

(b) Prove that $\neg (P \lor Q) \equiv \neg P \land \neg Q$ is also provable in intuitionistic logic.

(c) Prove that the proposition $(P \land \neg Q) \Rightarrow \neg (P \Rightarrow Q)$ is provable in intuitionistic logic and $\neg (P \Rightarrow Q) \Rightarrow (P \land \neg Q)$ is provable in classical logic.

Problem 2.4. (a) Show that $P \Rightarrow \neg \neg P$ is provable in intuitionistic logic.

(b) Show that $\neg \neg \neg P$ and $\neg P$ are equivalent in intuitionistic logic.

Problem 2.5. Recall that an integer is *even* if it is divisible by 2, that is, if it can be written as 2k, where $k \in \mathbb{Z}$. An integer is *odd* if it is not divisible by 2, that is, if it can be written as 2k + 1, where $k \in \mathbb{Z}$. Prove the following facts.

- (a) The sum of even integers is even.
- (b) The sum of an even integer and of an odd integer is odd.
- (c) The sum of two odd integers is even.
- (d) The product of odd integers is odd.

(e) The product of an even integer with any integer is even.

Problem 2.6. (a) Show that if we assume that all propositions of the form

$$P \Rightarrow (Q \Rightarrow R)$$

are axioms (where P, Q, R are arbitrary propositions), then *every proposition* is provable.

(b) Show that if P is provable (intuitionistically or classically), then $Q \Rightarrow P$ is also provable for *every* proposition Q.

Problem 2.7. (a) Give intuitionistic proofs for the equivalences listed below.

$$P \lor P \equiv P$$
$$P \land P \equiv P$$
$$P \lor Q \equiv Q \lor P$$
$$P \land Q \equiv Q \land P.$$

(b) Give intuitionistic proofs for the equivalences listed below.

$$P \land (P \lor Q) \equiv P$$
$$P \lor (P \land Q) \equiv P.$$

Problem 2.8. Give intuitionistic proofs for the propositions listed below.

$$P \Rightarrow (Q \Rightarrow (P \land Q))$$
$$(P \Rightarrow Q) \Rightarrow ((P \Rightarrow \neg Q) \Rightarrow \neg P)$$
$$(P \Rightarrow R) \Rightarrow ((Q \Rightarrow R) \Rightarrow ((P \lor Q) \Rightarrow R))$$

Problem 2.9. Prove that the following equivalences are provable intuitionistically.

$$P \land (P \Rightarrow Q) \equiv P \land Q$$

$$Q \land (P \Rightarrow Q) \equiv Q$$

$$(P \Rightarrow (Q \land R)) \equiv ((P \Rightarrow Q) \land (P \Rightarrow R)).$$

Problem 2.10. Give intuitionistic proofs for

$$(P \Rightarrow Q) \Rightarrow \neg \neg (\neg P \lor Q)$$
$$\neg \neg (\neg \neg P \Rightarrow P).$$

Problem 2.11. Give an intuitionistic proof for $\neg \neg (P \lor \neg P)$.

Problem 2.12. Give intuitionistic proofs for the propositions

$$(P \vee \neg P) \Rightarrow (\neg \neg P \Rightarrow P) \quad \text{and} \quad (\neg \neg P \Rightarrow P) \Rightarrow (P \vee \neg P).$$

Hint. For the second implication, you may want to use Problem 2.11.

Problem 2.13. Give intuitionistic proofs for the propositions

$$(P \Rightarrow Q) \Rightarrow \neg \neg (\neg P \lor Q) \text{ and } (\neg P \Rightarrow Q) \Rightarrow \neg \neg (P \lor Q).$$

Problem 2.14. (1) Design an algorithm for converting a deduction of a proposition P in the system $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ into a deduction in the system $\mathcal{N}\mathcal{G}_i^{\Rightarrow,\wedge,\vee,\perp}$.

(2) Design an algorithm for converting a deduction of a proposition P in the system $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp}$ into a deduction in the system $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp}$.

(3) Design an algorithm for converting a deduction of a proposition P in the system $\mathcal{NG}_{i}^{\Rightarrow,\wedge,\vee,\perp}$ into a deduction in the system $\mathcal{N}_{i}^{\Rightarrow,\wedge,\vee,\perp}$.

(4) Design an algorithm for converting a deduction of a proposition P in the system $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$ into a deduction in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$.

Hint. Use induction on deduction trees.

Problem 2.15. Prove that the following version of the \lor -elimination rule formulated in Gentzen-sequent style is a consequence of the rules of intuitionistic logic.

$$\frac{\Gamma, x \colon P \to R \quad \Gamma, y \colon Q \to R}{\Gamma, z \colon P \lor Q \to R}$$

Conversely, if we assume that the above rule holds, then prove that the \lor -elimination rule

$$\frac{\Gamma \to P \lor Q \quad \Gamma, x \colon P \to R \quad \Gamma, y \colon Q \to R}{\Gamma \to R} \quad (\lor \text{-elim})$$

follows from the rules of intuitionistic logic (of course, excluding the \lor -elimination rule).

Problem 2.16. (1) Give algorithms for converting a deduction in $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ to a deduction in $\mathcal{N}_{c}^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ and vice-versa.

(2) Give algorithms for converting a deduction in $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ to a deduction in $\mathcal{N}\mathcal{G}_i^{\Rightarrow,\wedge,\vee,\perp,\forall,\exists}$ and vice-versa.

Problem 2.17. (a) Give intuitionistic proofs for the distributivity of \land over \lor and of \lor over \land :

$$P \land (Q \lor R) \equiv (P \land Q) \lor (P \land R)$$
$$P \lor (Q \land R) \equiv (P \lor Q) \land (P \lor R).$$

(b) Give intuitionistic proofs for the associativity of \land and \lor :

$$P \land (Q \land R) \equiv (P \land Q) \land R$$
$$P \lor (Q \lor R) \equiv (P \lor Q) \lor R.$$

Problem 2.18. Recall that in Problem 2.1 we proved that if $P \Rightarrow Q$ and $Q \Rightarrow R$ are provable, then $P \Rightarrow R$ is provable. Deduce from this fact that if $P \equiv Q$ and $Q \equiv R$ hold, then $P \equiv R$ holds (intuitionistically or classically).

Prove that if $P \equiv Q$ holds, then $Q \equiv P$ holds (intuitionistically or classically). Finally, check that $P \equiv P$ holds (intuitionistically or classically).

Problem 2.19. Prove (intuitionistically or classically) that if $P_1 \Rightarrow Q_1$ and $P_2 \Rightarrow Q_2$, then

- 1. $(P_1 \wedge P_2) \Rightarrow (Q_1 \wedge Q_2)$
- 2. $(P_1 \lor P_2) \Rightarrow (Q_1 \lor Q_2).$
- (b) Prove (intuitionistically or classically) that if $Q_1 \Rightarrow P_1$ and $P_2 \Rightarrow Q_2$, then

1.
$$(P_1 \Rightarrow P_2) \Rightarrow (Q_1 \Rightarrow Q_2)$$

- 2. $\neg P_1 \Rightarrow \neg Q_1$.
- (c) Prove (intuitionistically or classically) that if $P \Rightarrow Q$, then
- 1. $\forall tP \Rightarrow \forall tQ$
- 2. $\exists tP \Rightarrow \exists tQ$.

(d) Prove (intuitionistically or classically) that if $P_1 \equiv Q_1$ and $P_2 \equiv Q_2$, then

- 1. $(P_1 \land P_2) \equiv (Q_1 \land Q_2)$ 2. $(P_1 \lor P_2) \equiv (Q_1 \lor Q_2)$ 3. $(P_1 \Rightarrow P_2) \equiv (Q_1 \Rightarrow Q_2)$ 4. $\neg P_1 \equiv \neg Q_1$ 5. $\forall tP_1 \equiv \forall tQ_1$
- 6. $\exists t P_1 \equiv \exists t Q_1.$

Problem 2.20. (a) Show that the following are provable in classical first-order logic:

$$\neg \forall tP \equiv \exists t \neg P$$
$$\neg \exists tP \equiv \forall t \neg P$$
$$\forall t(P \land Q) \equiv \forall tP \land \forall tQ$$
$$\exists t(P \lor Q) \equiv \exists tP \lor \exists tQ$$

(b) Moreover, show that the propositions $\exists t(P \land Q) \Rightarrow \exists tP \land \exists tQ$ and $\forall tP \lor \forall tQ \Rightarrow \forall t(P \lor Q)$ are provable in intuitionistic first-order logic (and thus, also in classical first-order logic).

(c) Prove intuitionistically that

$$\exists x \forall y P \Rightarrow \forall y \exists x P.$$

Give an informal argument to the effect that the converse, $\forall y \exists x P \Rightarrow \exists x \forall y P$, is not provable, even classically.

Problem 2.21. (a) Assume that Q is a formula that does **not** contain the variable t (free or bound). Give a classical proof of

$$\forall t(P \lor Q) \Rightarrow (\forall tP \lor Q).$$

(b) If P is a proposition, write P(x) for P[x/t] and P(y) for P[y/t], where x and y are distinct variables that do not occur in the orginal proposition P. Give an intuitionistic proof for

$$\neg \forall x \exists y (\neg P(x) \land P(y)).$$

(c) Give a classical proof for

$$\exists x \forall y (P(x) \lor \neg P(y)).$$

Hint. Negate the above, then use some identities we've shown (such as de Morgan) and reduce the problem to Part (b).

Problem 2.22. (a) Let $X = \{X_i \mid 1 \leq i \leq n\}$ be a finite family of sets. Prove that if $X_{i+1} \subseteq X_i$ for all i, with $1 \leq i \leq n-1$, then

$$\bigcap X = X_n.$$

Prove that if $X_i \subseteq X_{i+1}$ for all i, with $1 \leq i \leq n-1$, then

$$\bigcup X = X_n.$$

(b) Recall that $\mathbb{N}_+ = \mathbb{N} - \{0\} = \{1, 2, 3, \dots, n, \dots\}$. Give an example of an infinite family of sets $X = \{X_i \mid i \in \mathbb{N}_+\}$, such that

1. $X_{i+1} \subseteq X_i$ for all $i \ge 1$.

- 2. X_i is infinite, for every $i \ge 1$.
- 3. $\bigcap X$ has a single element.

(c) Give an example of an infinite family of sets, $X = \{X_i \mid i \in \mathbb{N}_+\}$, such that

- 1. $X_{i+1} \subseteq X_i$ for all $i \ge 1$.
- 2. X_i is infinite, for every $i \ge 1$.

3. $\bigcap X = \emptyset$.

Problem 2.23. Prove that the following propositions are provable intuitionistically:

$$(P \Rightarrow \neg P) \equiv \neg P, \qquad (\neg P \Rightarrow P) \equiv \neg \neg P.$$

Use these to conclude that if the equivalence $P \equiv \neg P$ is provable intuitionistically, then *every* proposition is provable (intuitionistically).

Problem 2.24. (1) Prove that if we assume that all propositions of the form

$$((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$$

are axioms (Peirce's law), then $\neg \neg P \Rightarrow P$ becomes provable in intuitionistic logic. Thus, another way to get classical logic from intuitionistic logic is to add Peirce's law to intuitionistic logic.

Hint. Pick Q in a suitable way and use Problem 2.23.

(2) Prove $((P \Rightarrow Q) \Rightarrow P) \Rightarrow P$ in classical logic. *Hint*. Use the de Morgan laws.

Problem 2.25. Let A be any nonempty set. Prove that the definition

$$X = \{a \in A \mid a \notin X\}$$

yields a "set" X, such that X is empty iff X is nonempty and therefore does not define a set, after all.

Problem 2.26. Prove the following fact: if

$$\begin{array}{ccc}
\Gamma & \Gamma, R \\
\mathcal{D}_1 & \mathcal{D}_2 \\
P \lor Q & Q
\end{array}$$

are deduction trees provable intuitionistically, then there is a deduction tree

$$\begin{array}{c} \Gamma, P \Rightarrow R \\ \mathcal{D} \\ Q \end{array}$$

for Q from the premises in $\Gamma \cup \{P \Rightarrow S\}$.

Problem 2.27. Recall that the constant \top stands for **true**. So, we add to our proof systems (intuitionistic and classical) all axioms of the form

$$\underbrace{\frac{k_1}{P_1,\ldots,P_1},\ldots,\overline{P_i,\ldots,P_i},\ldots,\overline{P_n,\ldots,P_n}}_{\top}$$

where $k_i \ge 1$ and $n \ge 0$; note that n = 0 is allowed, which amounts to the one-node tree \top . (a) Prove that the following equivalences hold intuitionistically.

$$P \lor \top \equiv \top$$
$$P \land \top \equiv P.$$

Prove that if P is intuitionistically (or classically) provable, then $P \equiv \top$ is also provable intuitionistically (or classically). In particular, in classical logic, $P \lor \neg P \equiv \top$. Also prove that

$$P \lor \bot \equiv P$$
$$P \land \bot \equiv \bot$$

hold intuitionistically.

(b) In the rest of this problem, we are dealing only with classical logic. The connective *exclusive or*, denoted \oplus , is defined by

$$P \oplus Q \equiv (P \land \neg Q) \lor (\neg P \land Q).$$

In solving the following questions, you will find that constructing proofs using the rules of classical logic is very tedious because these proofs are very long. Instead, use some identities from previous problems.

Prove the equivalence

$$\neg P \equiv P \oplus \top.$$

(c) Prove that

$$P \oplus P \equiv \bot$$
$$P \oplus Q \equiv Q \oplus P$$
$$(P \oplus Q) \oplus R \equiv P \oplus (Q \oplus R).$$

(d) Prove the equivalence

$$P \lor Q \equiv (P \land Q) \oplus (P \oplus Q).$$

Problem 2.28. Give a classical proof of

$$\neg (P \Rightarrow \neg Q) \Rightarrow (P \land Q).$$

Problem 2.29. (a) Prove that the rule

$$\begin{array}{ccc}
\Gamma & \Delta \\
\mathcal{D}_1 & \mathcal{D}_2 \\
P \Rightarrow Q & \neg Q \\
\hline
\neg P
\end{array}$$

can be derived from the other rules of intuitionistic logic.

(b) Give an intuitionistic proof of $\neg P$ from $\Gamma = \{\neg(\neg P \lor Q), P \Rightarrow Q\}$ or equivalently, an intuitionistic proof of

$$\left(\neg(\neg P \lor Q) \land (P \Rightarrow Q)\right) \Rightarrow \neg P.$$

Problem 2.30. (a) Give intuitionistic proofs for the equivalences

$$\exists x \exists y P \equiv \exists y \exists x P \quad \text{and} \quad \forall x \forall y P \equiv \forall y \forall x P.$$

(b) Give intuitionistic proofs for

$$(\forall tP \land Q) \Rightarrow \forall t(P \land Q) \text{ and } \forall t(P \land Q) \Rightarrow (\forall tP \land Q),$$

where t does not occur (free or bound) in Q.

(c) Give intuitionistic proofs for

$$(\exists t P \lor Q) \Rightarrow \exists t (P \lor Q) \text{ and } \exists t (P \lor Q) \Rightarrow (\exists t P \lor Q),$$

where t does not occur (free or bound) in Q.

Problem 2.31. An integer $n \in \mathbb{Z}$ is divisible by 3 iff n = 3k, for some $k \in \mathbb{Z}$. Thus (by the division theorem), an integer $n \in \mathbb{Z}$ is not divisible by 3 iff it is of the form n = 3k+1, 3k+2, for some $k \in \mathbb{Z}$ (you don't have to prove this).

Prove that for any integer $n \in \mathbb{Z}$, if n^2 is divisible by 3, then n is divisible by 3.

Hint. Prove the contrapositive. If n of the form n = 3k + 1, 3k + 2, then so is n^2 (for a different k).

Problem 2.32. Use Problem 2.31 to prove that $\sqrt{3}$ is irrational, that is, $\sqrt{3}$ can't be written as $\sqrt{3} = p/q$, with $p, q \in \mathbb{Z}$ and $q \neq 0$.

Problem 2.33. Give an intuitionistic proof of the proposition

$$((P \Rightarrow R) \land (Q \Rightarrow R)) \equiv ((P \lor Q) \Rightarrow R).$$

Problem 2.34. Give an intuitionistic proof of the proposition

$$((P \land Q) \Rightarrow R) \equiv (P \Rightarrow (Q \Rightarrow R)).$$

Problem 2.35. (a) Give an intuitionistic proof of the proposition $(P \land Q) \Rightarrow (P \lor Q)$.

(b) Prove that the proposition $(P \lor Q) \Rightarrow (P \land Q)$ is not valid, where P, Q, are propositional symbols.

(c) Prove that the proposition $(P \lor Q) \Rightarrow (P \land Q)$ is not provable in general and that if we assume that *all* propositions of the form $(P \lor Q) \Rightarrow (P \land Q)$ are axioms, then *every* proposition becomes provable intuitionistically. **Problem 2.36.** Give the details of the proof of Proposition 2.6; namely, if a proposition P is provable in the system $\mathcal{N}_c^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_c^{\Rightarrow,\wedge,\vee,\perp}$), then it is valid (according to the truth-value semantics).

Problem 2.37. Give the details of the proof of Theorem 2.8; namely, if a proposition P is provable in the system $\mathcal{N}_i^{\Rightarrow,\wedge,\vee,\perp}$ (or $\mathcal{NG}_i^{\Rightarrow,\wedge,\vee,\perp}$), then it is valid in every Kripke model; that is, it is intuitionistically valid.

Problem 2.38. Prove that $b = \log_2 9$ is irrational. Then prove that $a = \sqrt{2}$ and $b = \log_2 9$ are two irrational numbers such that a^b is rational.

Problem 2.39. (1) Prove that if $\forall x \neg (P \land Q)$ can be deduced intuitionistically from a set of premises Γ , then $\forall x(P \Rightarrow \neg Q)$ and $\forall x(Q \Rightarrow \neg P)$ can also be deduced intuitionistically from Γ .

(2) Prove that if $\forall x (P \lor Q)$ can be deduced intuitionistically from a set of premises Γ , then $\forall x (\neg P \Rightarrow Q)$ and $\forall x (\neg Q \Rightarrow P)$ can also be deduced intuitionistically from Γ .

Conclude that if

 $\forall x (P \lor Q)$ and $\forall x \neg (P \land Q)$

can be deduced intuitionistically from a set of premises Γ , then

$$\forall x (P \equiv \neg Q) \text{ and } \forall x (Q \equiv \neg P)$$

can also be deduced intuitionistically from Γ .

(3) Prove that if $\forall x(P \Rightarrow Q)$ can be deduced intuitionistically from a set of premises Γ , then $\forall x(\neg Q \Rightarrow \neg P)$ can also be deduced intuitionistically from Γ . Use this to prove that if

$$\forall x (P \equiv \neg Q) \text{ and } \forall x (Q \equiv \neg P)$$

can be deduced intuitionistically from a set of premises Γ , then the formulae $\forall x(\neg \neg P \equiv P)$ and $\forall x(\neg \neg Q \equiv Q)$ can be deduced intuitionistically from Γ .

Problem 2.40. Prove that the formula

$$\forall x \operatorname{even}(2 * x)$$

is provable in Peano arithmetic. Prove that

$$even(2 * (n + 1) * (n + 3))$$

is provable in Peano arithmetic for any natural number n.

Problem 2.41. A first-order formula A is said to be in *prenex-form* if either

- (1) A is a quantifier-free formula.
- (2) $A = \forall tB$ or $A = \exists tB$, where B is in prenex-form.

In other words, a formula is in prenex form iff it is of the form

$$Q_1 t_1 Q_2 t_2 \cdots Q_m t_m P,$$

where P is quantifier-free and where $Q_1 Q_2 \cdots Q_m$ is a string of quantifiers, $Q_i \in \{\forall, \exists\}$.

Prove that every first-order formula A is classically equivalent to a formula B in prenex form.

Problem 2.42. Let A and be B be any two sets of sets.

(1) Prove that

$$\left(\bigcup A\right) \cup \left(\bigcup B\right) = \bigcup (A \cup B).$$

(2) Assume that A and B are nonempty. Prove that

$$\left(\bigcap A\right) \cap \left(\bigcap B\right) = \bigcap (A \cup B).$$

(3) Assume that A and B are nonempty. Prove that

$$\bigcup (A \cap B) \subseteq \left(\bigcup A\right) \cap \left(\bigcup B\right),$$

and give a counterexample of the inclusion

$$\left(\bigcup A\right)\cap\left(\bigcup B\right)\subseteq\bigcup(A\cap B).$$

Hint. Reduce the above questions to the provability of certain formulae that you have already proved in a previous assignment (you need **not** re-prove these formulae).

Problem 2.43. A set A is said to be *transitive* iff for all $a \in A$ and all $x \in a$, then $x \in A$, or equivalently, for all $a \in A$,

$$a \in A \Rightarrow a \subseteq A.$$

(1) Check that a set A is transitive iff

$$\bigcup A \subseteq A$$

 iff

$$A \subseteq 2^A$$
.

(2) Recall the definition of the von Neumann successor of a set A given by

$$A^+ = A \cup \{A\}.$$

Prove that if A is a transitive set, then

$$\bigcup (A^+) = A.$$

(3) Recall the von Neumann definition of the natural numbers. Check that for every natural number m

$$m \in m^+$$
 and $m \subseteq m^+$.

Prove that every natural number is a transitive set.

Hint. Use induction.

(4) Prove that for any two von Neumann natural numbers m and n, if $m^+ = n^+$, then m = n.

(5) Prove that the set \mathbb{N} of natural numbers is a transitive set.

Hint. Use induction.

Problem 2.44. Even though natural deduction proof systems for classical propositional logic are complete (with respect to the truth-value semantics), they are not adequate for designing algorithms searching for proofs (because of the amount of nondeterminism involved).

Gentzen designed a different kind of proof system using *sequents* (later refined by Kleene, Smullyan, and others) that is far better suited for the design of automated theorem provers. Using such a proof system (a *sequent calculus*), it is relatively easy to design a procedure that terminates for all input propositions P and either certifies that P is (classically) valid or else returns some (or all) falsifying truth assignment(s) for P. In fact, if P is valid, the tree returned by the algorithm can be viewed as a proof of P in this proof system.

For this mini project, we describe a *Gentzen sequent-calculus* G' for propositional logic that lends itself well to the implementation of algorithms searching for proofs or falsifying truth assignments of propositions.

Such algorithms build trees whose nodes are labeled with pairs of sets called sequents. A *sequent* is a pair of sets of propositions denoted by

$$P_1,\ldots,P_m\to Q_1,\ldots,Q_n,$$

with $m, n \ge 0$. Symbolically, a sequent is usually denoted $\Gamma \to \Delta$, where Γ and Δ are two finite sets of propositions (not necessarily disjoint).

For example,

$$\rightarrow P \Rightarrow (Q \Rightarrow P), \qquad P \lor Q \rightarrow, \qquad P, Q \rightarrow P \land Q$$

are sequents. The sequent \rightarrow , where both $\Gamma = \Delta = \emptyset$ corresponds to falsity.

The choice of the symbol \rightarrow to separate the two sets of propositions Γ and Δ is commonly used and was introduced by Gentzen but there is nothing special about it. If you don't like it, you may replace it by any symbol of your choice, as long as that symbol does not clash with the logical connectives ($\Rightarrow, \land, \lor, \neg$). For example, you could denote a sequent

$$P_1,\ldots,P_m;Q_1,\ldots,Q_n,$$

using the semicolon as a separator.

Given a truth assignment v to the propositional letters in the propositions P_i and Q_j , we say that v satisfies the sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ iff

$$v((P_1 \wedge \cdots \wedge P_m) \Rightarrow (Q_1 \vee \cdots \vee Q_n)) = \mathbf{true},$$

or equivalently, v falsifies the sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ iff

$$v(P_1 \wedge \cdots \wedge P_m \wedge \neg Q_1 \wedge \cdots \wedge \neg Q_n) = \mathbf{true},$$

 iff

 $v(P_i) =$ **true**, $1 \le i \le m$, and $v(Q_j) =$ **false**, $1 \le j \le n$.

A sequent is *valid* iff it is satisfied by all truth assignments iff it cannot be falsified.

Note that a sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ can be falsified iff some truth assignment satisfies all of P_1, \ldots, P_m and falsifies all of Q_1, \ldots, Q_n . In particular, if $\{P_1, \ldots, P_m\}$ and $\{Q_1, \ldots, Q_n\}$ have some common proposition (they have a nonempty intersection), then the sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ is valid. On the other hand, if all the P_i s and Q_j s are propositional letters and $\{P_1, \ldots, P_m\}$ and $\{Q_1, \ldots, Q_n\}$ are disjoint (they have no symbol in common), then the sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ is falsified by the truth assignment v, where $v(P_i) = \mathbf{true}$, for $i = 1, \ldots, m$, and $v(Q_j) = \mathbf{false}$, for $j = 1, \ldots, n$.

The main idea behind the design of the proof system G' is to systematically try to falsify a sequent. If such an attempt fails, the sequent is valid and a proof tree is found. Otherwise, all falsifying truth assignments are returned. In some sense,

failure to falsify is success (in finding a proof).

The rules of G' are designed so that the conclusion of a rule is falsified by a truth assignment v iff its single premise of one of its two premises is falsified by v. Thus, these rules can be viewed as *two-way* rules that can either be read bottom-up or top-down.

Here are the axioms and the rules of the sequent calculus G':

Axioms: $\Gamma, P \to P, \Delta$ Inference rules:

where Γ, Δ, Λ are any finite sets of propositions, possibly the empty set.

A deduction tree is either a one-node tree labeled with a sequent or a tree constructed according to the rules of system G'. A proof tree (or proof) is a deduction tree whose leaves are all axioms. A proof tree for a proposition P is a proof tree for the sequent $\rightarrow P$ (with an empty left-hand side).

For example,

$$P, Q \to P$$

is a proof tree.

Here is a proof tree for $(P \Rightarrow Q) \Rightarrow (\neg Q \Rightarrow \neg P)$:

$$\begin{array}{c} \begin{array}{c} P, \neg Q \rightarrow P \\ \hline \neg Q \rightarrow \neg P, P \\ \hline \rightarrow P, (\neg Q \Rightarrow \neg P) \end{array} & \begin{array}{c} \begin{array}{c} Q \rightarrow Q, \neg P \\ \hline \neg Q, Q \rightarrow \neg P \\ \hline Q \rightarrow (\neg Q \Rightarrow \neg P) \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \begin{array}{c} (P \Rightarrow Q) \rightarrow (\neg Q \Rightarrow \neg P) \\ \hline \hline \rightarrow (P \Rightarrow Q) \Rightarrow (\neg Q \Rightarrow \neg P) \\ \hline \rightarrow (P \Rightarrow Q) \Rightarrow (\neg Q \Rightarrow \neg P) \end{array} \end{array}$$

The following is a deduction tree but not a proof tree

$$\begin{array}{c} \displaystyle \frac{P,R \rightarrow P}{R \rightarrow \neg P,P} & \displaystyle \frac{R,Q,P \rightarrow }{R,Q \rightarrow \neg P} \\ \hline \rightarrow P,(R \Rightarrow \neg P) & \displaystyle \frac{Q \rightarrow (R \Rightarrow \neg P)}{Q \rightarrow (R \Rightarrow \neg P)} \\ \hline \hline \\ \displaystyle \frac{(P \Rightarrow Q) \rightarrow (R \Rightarrow \neg P)}{\rightarrow (P \Rightarrow Q) \Rightarrow (R \Rightarrow \neg P)} \end{array}$$

because its rightmost leaf, $R, Q, P \rightarrow$, is falsified by the truth assignment v(P) = v(Q) = v(R) =true, which also falsifies $(P \Rightarrow Q) \Rightarrow (R \Rightarrow \neg P)$.

Let us call a sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ finished if either it is an axiom $(P_i = Q_j$ for some *i* and some *j*) or all the propositions P_i and Q_j are atomic and $\{P_1, \ldots, P_m\} \cap \{Q_1, \ldots, Q_n\} = \emptyset$. We also say that a deduction tree is finished if all its leaves are finished sequents.

The beauty of the system G' is that for every sequent

$$P_1,\ldots,P_m\to Q_1,\ldots,Q_n,$$

the process of building a deduction tree from this sequent always terminates with a tree where all leaves are finished independently of the order in which the rules are applied. Therefore, we can apply any strategy we want when we build a deduction tree and we are sure that we will get a deduction tree with all its leaves finished. If all the leaves are axioms, then we have a proof tree and the sequent is valid, or else all the leaves that are not axioms yield a falsifying assignment, and all falsifying assignments for the root sequent are found this way.

If we only want to know whether a proposition (or a sequent) is valid, we can stop as soon as we find a finished sequent that is not an axiom because in this case, the input sequent is falsifiable. (1) Prove that for every sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$, any sequence of applications of the rules of G' terminates with a deduction tree whose leaves are all finished sequents (a finished deduction tree).

Hint. Define the number of connectives c(P) in a proposition P as follows.

(1) If P is a propositional symbol, then

$$c(P) = 0.$$

(2) If $P = \neg Q$, then

$$c(\neg Q) = c(Q) + 1.$$

(3) If P = Q * R, where $* \in \{\Rightarrow, \lor, \land\}$, then

$$c(Q * R) = c(Q) + c(R) + 1.$$

Given a sequent,

$$\Gamma \to \Delta = P_1, \dots, P_m \to Q_1, \dots, Q_n$$

define the number of connectives, $c(\Gamma \to \Delta)$, in $\Gamma \to \Delta$ by

$$c(\Gamma \to \Delta) = c(P_1) + \dots + c(P_m) + c(Q_1) + \dots + c(Q_n).$$

Prove that the application of every rule decreases the number of connectives in the premise(s) of the rule.

(2) Prove that for every sequent $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$, for every finished deduction tree T constructed from $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ using the rules of G', every truth assignment v satisfies $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ iff v satisfies every leaf of T. Equivalently, a truth assignment v falsifies $P_1, \ldots, P_m \to Q_1, \ldots, Q_n$ iff v falsifies some leaf of T.

Deduce from the above that a sequent is valid iff all leaves of every finished deduction tree T are axioms. Furthermore, if a sequent is not valid, then for every finished deduction tree T, for that sequent, every falsifying assignment for that sequent is a falsifying assignment of some leaf of the tree T.

(3) **Programming Project**:

Design an algorithm taking any sequent as input and constructing a finished deduction tree. If the deduction tree is a proof tree, output this proof tree in some fashion (such a tree can be quite big so you may have to find ways of "flattening" these trees). If the sequent is falsifiable, stop when the algorithm encounters the first leaf that is not an axiom and output the corresponding falsifying truth assignment.

I suggest using a *depth-first expansion strategy* for constructing a deduction tree. What this means is that when building a deduction tree, the algorithm will proceed recursively as follows. Given a nonfinished sequent

$$A_1,\ldots,A_p\to B_1,\ldots,B_q,$$

if A_i is the *leftmost* nonatomic proposition if such proposition occurs on the left, or if B_j is the leftmost nonatomic proposition if all the A_i s are atomic, then (1) The sequent is of the form

$$\Gamma, A_i, \Delta \to \Lambda,$$

with A_i the leftmost nonatomic proposition. Then either

(a) $A_i = C_i \wedge D_i$ or $A_i = \neg C_i$, in which case, either we recursively construct a (finished) deduction tree

$$\mathcal{D}_1$$

 $\Gamma, C_i, D_i, \Delta \to \Lambda$

to get the deduction tree

$$\frac{\mathcal{D}_1}{\Gamma, C_i, D_i, \Delta \to \Lambda}$$
$$\frac{\Gamma, C_i \land D_i, \Delta \to \Lambda}{\Gamma, C_i \land D_i, \Delta \to \Lambda}$$

,

,

or we recursively construct a (finished) deduction tree

$$\mathcal{D}_1$$
$$\Gamma, \Delta \to C_i, \Lambda$$

to get the deduction tree

$$\frac{\mathcal{D}_1}{\Gamma, \Delta \to C_i, \Lambda} \\
\frac{\Gamma, \neg C_i, \Delta \to \Lambda}{\Gamma, \neg C_i, \Delta \to \Lambda}$$

or

(b) $A_i = C_i \lor D_i$ or $A_i = C_i \Rightarrow D_i$, in which case, either we recursively construct two (finished) deduction trees

$$\begin{array}{ccc} \mathcal{D}_1 & \mathcal{D}_2 \\ \Gamma, C_i, \Delta \to \Lambda & \text{and} & \Gamma, D_i, \Delta \to \Lambda \end{array}$$

to get the deduction tree

$$\frac{\begin{array}{ccc} \mathcal{D}_1 & \mathcal{D}_2 \\ \Gamma, C_i, \Delta \to \Lambda & \Gamma, D_i, \Delta \to \Lambda \end{array}}{\Gamma, C_i \lor D_i, \Delta \to \Lambda} \quad ,$$

or we recursively construct two (finished) deduction trees

$$\mathcal{D}_1 \qquad \mathcal{D}_2 \\ \Gamma, \Delta \to C_i, \Lambda \quad \text{and} \quad D_i, \Gamma, \Delta \to \Lambda$$

to get the deduction tree

$$\frac{\begin{array}{ccc} \mathcal{D}_1 & \mathcal{D}_2 \\ \Gamma, \Delta \to C_i, \Lambda & D_i, \Gamma, \Delta \to \Lambda \end{array}}{\Gamma, C_i \Rightarrow D_i, \Delta \to \Lambda}$$

(2) The nonfinished sequent is of the form

$$\Gamma \to \Delta, B_i, \Lambda,$$

with B_j the leftmost nonatomic proposition. Then either

(a) $B_j = C_j \vee D_j$ or $B_j = C_j \Rightarrow D_j$, or $B_j = \neg C_j$, in which case, either we recursively construct a (finished) deduction tree

$$\mathcal{D}_1$$
$$\Gamma \to \Delta, C_j, D_j, \Lambda$$

to get the deduction tree

$$\frac{\mathcal{D}_1}{\Gamma \to \Delta, C_j, D_j, \Lambda}$$
$$\frac{\Gamma \to \Delta, C_j \lor D_j, \Lambda}{\Gamma \to \Delta, C_j \lor D_j, \Lambda}$$

,

,

,

or we recursively construct a (finished) deduction tree

$$\mathcal{D}_1$$
$$C_j, \Gamma \to D_j, \Delta, \Lambda$$

to get the deduction tree

$$\frac{\mathcal{D}_1}{C_j, \Gamma \to D_j, \Delta, \Lambda} \\
\frac{\Gamma \to \Delta, C_j \Rightarrow D_j, \Lambda}{\Gamma \to \Delta, C_j \Rightarrow D_j, \Lambda}$$

or we recursively construct a (finished) deduction tree

$$\mathcal{D}_1 \\ C_j, \Gamma \to \Delta, \Lambda$$

to get the deduction tree

$$\frac{\mathcal{D}_1}{C_j, \Gamma \to \Delta, \Lambda}$$
$$\frac{\Gamma \to \Delta, \neg C_j, \Lambda}{\Gamma \to \Delta, \neg C_j, \Lambda}$$

or

(b) $B_j = C_j \wedge D_j$, in which case, we recursively construct two (finished) deduction trees

$$\mathcal{D}_1 \qquad \mathcal{D}_2 \\ \Gamma \to \Delta, C_j, \Lambda \qquad \text{and} \qquad \Gamma \to \Delta, D_j, \Lambda$$

to get the deduction tree

$$\frac{\begin{array}{ccc} \mathcal{D}_1 & \mathcal{D}_2 \\ \Gamma \to \Delta, C_j, \Lambda & \Gamma \to \Delta, D_j, \Lambda \end{array}}{\Gamma \to \Delta, C_j \wedge D_j, \Lambda}$$

If you prefer, you can apply a $\mathit{breadth-first\ expansion\ strategy}}$ for constructing a deduction tree.

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Chapter 3 Unification

3.1 Introduction

Unification is a very general computational paradigm that plays an important role in many different areas of symbolic computation. For example, unification plays a central role in

- (1) Automated Deduction (First-order logic with or without equality, higher-order logic);
- (2) Logic Programming (Prolog, λ -Prolog);
- (3) Constraint-based Programming;
- (4) Type Inferencing (ML, ML⁺, etc.);
- (5) Knowledge-Base Systems, Feature structures; and
- (6) Computational Linguistics (Unification grammars).

Here, we shall focus on unification problems arising in methods for automated theorem proving and type inferencing. This covers at least the kind of unification arising in resolution. For a comprehensive exposition, see Gallier [24].

These unification problems will be tackled using the *method of transformations* on term systems, already anticipated in Herbrand's thesis [34] (1930), and revived very effectively by Martelli and Montanari [53] for standard unification. In a nutshell, the method is as follows:

A unification problem is gradually transformed into one whose solution is (almost) obvious.

This approach is an instance of a very old method in mathematics, but a fairly recent trend in computer science, namely, the specification of procedures and algorithms in terms of inference rules. There are a number of significant advantages to this method.

(1) A clean separation of logic and control is achieved.

- (2) The correctness of the procedure obtained this way is often easier to establish, and irrelevant implementation issues are avoided.
- (3) The actual design of algorithms from the procedure specified by rules can be viewed as an optimization process.

Another benefit of this approach to the design of algorithms is that one often gains a deeper understanding of the problem being solved, and one understands more easily the differences between algorithms solving a same problem.

3.2 Algebraic Background

We begin with a brief review of algebraic background material. The purpose of this section is to establish the notation and the terminology used throughout this chapter. As much as possible, we follow Huet [40] and Gallier [24].

Definition 3.1. Let $\longrightarrow \subseteq A \times A$ be a binary relation on a set A. The *converse* (or *inverse*) of the relation \longrightarrow is the relation denoted as \longrightarrow^{-1} or \longleftarrow , defined such that $u \leftarrow v$ iff $v \longrightarrow u$. The symmetric closure of \longrightarrow , denoted by \longleftrightarrow , is the relation $\longrightarrow \cup \leftarrow$. The transitive closure, reflexive and transitive closure, and the reflexive, symmetric, and transitive closure of \longrightarrow are denoted respectively by $\xrightarrow{+}$, $\xrightarrow{*}$, and $\xleftarrow{*}$.

Definition 3.2. A relation \longrightarrow on a set A is *Noetherian* iff there are no infinite sequences $\langle a_0, \ldots, a_n, a_{n+1}, \ldots \rangle$ of elements in A such that $a_n \longrightarrow a_{n+1}$, for all $n \ge 0$. A relation \longrightarrow on A is *well founded* iff there are no infinite sequences $\langle a_0, \ldots, a_n, a_{n+1}, \ldots \rangle$ of elements in A such that $a_{n+1} \longrightarrow a_n$ for all $n \ge 0$.

Definition 3.3. Terms are built up inductively from a ranked alphabet (or signature) Σ of constant and function symbols, and a countably infinite set \mathcal{X} of variables. For simplicity of exposition, we assume that Σ is a one-sorted ranked alphabet, i.e., that there is a rank function $r: \Sigma \to \mathbb{N}$ assigning a rank (or arity) r(f) to every symbol $f \in \Sigma$ (\mathbb{N} denotes the set of natural numbers). The rank function is extended to variables by setting r(x) = 0 for all $x \in \mathcal{X}$. We let $\Sigma_n = \{f \in \Sigma \mid r(f) = n\}$. Symbols in Σ_0 (of rank zero) are called constants.

Definition 3.4. We let $T_{\Sigma}(\mathcal{X})$ denote the set of terms built up inductively from Σ and \mathcal{X} . Thus, $T_{\Sigma}(\mathcal{X})$ is the smallest set with the following properties:

- (1) $x \in T_{\Sigma}(\mathcal{X})$, for every $x \in \mathcal{X}$;
- (2) $c \in T_{\Sigma}(\mathcal{X})$, for every $c \in \Sigma_0$;
- (3) $f(t_1,\ldots,t_n) \in T_{\Sigma}(\mathcal{X})$, for every $f \in \Sigma_n$ and all $t_1,\ldots,t_n \in T_{\Sigma}(\mathcal{X})$.

Given a term of the form $t = f(t_1, \ldots, t_n)$, we denote t_i as t/i and we call f the root symbol of t.
Definition 3.5. Given a term $t \in T_{\Sigma}(\mathcal{X})$, the set Var(t) of variables occurring in t is defined inductively as follows.

$$Var(t) = \begin{cases} \emptyset, & \text{if } t \in \Sigma_0\\ \{x\}, & \text{if } t = x \in \mathcal{X}\\ \bigcup_{j=1}^n Var(t_j), & \text{if } t = f(t_1, \dots, t_n) \text{ and } n = r(f) \ge 1. \end{cases}$$

A term t is a ground term iff $Var(t) = \emptyset$.

The size of a term is defined inductively as follows.

Definition 3.6. Given a term $t \in T_{\Sigma}(\mathcal{X})$, the *size* size(t) of t is defined inductively as follows.

$$size(t) = \begin{cases} 1, & \text{if } t \in \Sigma_0 \\ 1, & \text{if } t = x \in \mathcal{X} \\ 1 + \sum_{j=1}^n size(t_j), & \text{if } t = f(t_1, \dots, t_n) \text{ and } n = r(f) \ge 1. \end{cases}$$

The notion of subterm is also defined inductively as follows.

Definition 3.7. Given a term $t \in T_{\Sigma}(\mathcal{X})$, the set SUBTERMS(t) of subterms of t is defined as follows:

$$\text{SUBTERMS}(t) = \begin{cases} \{t\}, & \text{if } t \in \mathcal{X} \text{ or } t \in \Sigma_0 \\ \{t\} \cup \bigcup_{j=1}^n \text{SUBTERMS}(t_j), & \text{if } t = f(t_1, \dots, t_n) \text{ and } n = r(f) \ge 1. \end{cases}$$

Example 3.1. Given the term t = f(g(x), f(x, g(x))), we have

SUBTERMS
$$(t) = \{ f(g(x), f(x, g(x))), g(x), x, f(x, g(x))) \}$$

Observe that in the terms t, the subterm x occurs three times and the subterm g(x) occurs twice.

It is well known that $T_{\Sigma}(\mathcal{X})$ is the term algebra freely generated by \mathcal{X} , and this allows us to define substitutions.

Definition 3.8. A substitution is a function $\varphi \colon \mathcal{X} \to T_{\Sigma}(\mathcal{X})$ such that $\varphi(x) \neq x$ for only finitely many $x \in \mathcal{X}$. The set $D(\varphi) = \{x \in \mathcal{X} \mid \varphi(x) \neq x\}$ is the domain of φ , and the set $I(\varphi) = \bigcup_{x \in D(\varphi)} Var(\varphi(x))$ is the set of variables introduced by φ .

A substitution $\varphi \colon \mathcal{X} \to T_{\Sigma}(\mathcal{X})$ with domain $D(\varphi) = \{x_1, \ldots, x_n\}$ and such that $\varphi(x_i) = t_i$ for $i = 1, \ldots, n$, is denoted as $[x_1 := t_1, \ldots, x_n := t_n]$.

Since $T_{\Sigma}(\mathcal{X})$ is freely generated by \mathcal{X} , every substitution $\varphi \colon \mathcal{X} \to T_{\Sigma}(\mathcal{X})$ has a unique homomorphic extension $\widehat{\varphi} \colon T_{\Sigma}(\mathcal{X}) \to T_{\Sigma}(\mathcal{X})$.

For every term $t \in T_{\Sigma}(\mathcal{X})$, we denote $\widehat{\varphi}(t)$ as $t[\varphi]$ or even as $\varphi(t)$ (with an intentional identification of φ and $\widehat{\varphi}$).

Example 3.2. Consider the substitution

$$\sigma = [x := f(g(z)), y := g(z)].$$

If we apply σ to both terms in the pair

$$S = \{ \langle g(x), g(f(y)) \rangle, \langle f(y), f(g(z)) \rangle \}$$

we obtain the pair

$$S[\sigma] = \{ \langle g(f(g(z))), g(f(g(z))) \rangle, \langle f(g(z)), f(g(z)) \rangle \} \}$$

which shows that σ is a unifier of S (see Definition 3.11).

Definition 3.9. Given two substitutions φ and ψ , their composition denoted $\varphi; \psi$ is the substitution defined such that $\varphi; \psi(x) = \widehat{\psi}(\varphi(x))$ for all $x \in \mathcal{X}$. Thus, note that $\varphi; \psi = \widehat{\psi} \circ \varphi$, but not $\psi \circ \varphi$, where \circ denotes the composition of functions.

A substitution φ is *idempotent* iff $\varphi; \varphi = \varphi$. It is easily seen that a substitution φ is idempotent iff $I(\varphi) \cap D(\varphi) = \emptyset$.

A substitution φ is a renaming iff $\varphi(x)$ is a variable for every $x \in D(\varphi)$, and φ is injective over its domain. Given a set V of variables and a substitution φ , the restriction of φ to V is the substitution denoted $\varphi|_V$ defined such that, $\varphi|_V(x) = \varphi(x)$ for all $x \in V$, and $\varphi|_V(x) = x$ for all $x \notin V$.

3.3 Standard Unification

Historically, unification was brought to the fore as a seminal component of automated deduction systems by Robinson in 1964 [63], and has been studied by numerous researchers since that time. In this section we present an abstract view of unification as a set of nondeterministic rules for transforming a unification problem into an explicit representation of its solution, if such exists. This elegant approach is due to Martelli and Montanari [53], but was in fact implicit in Herbrand's thesis (1930).¹ For a very good historical account and technical details on standard unification, the reader is referred to Knight's survey article [44], and Lassez, Maher, and Marriot [47].

It is natural to define a unification problem as a set $\{\langle u_1, v_1 \rangle, \ldots, \langle u_n, v_n \rangle\}$ of ordered pairs of terms. This is fine, but it turns out that it is more convenient to allow repetitions of pairs $\langle u_i, v_i \rangle$, and to allow $\langle u_i, v_i \rangle$ to be unordered. Thus, we adopt the following definition of a unification problem.

¹It is remarkable that in his thesis, Herbrand gave all the steps of a (nondeterministic) unification algorithm based on transformations on systems of equations. These transformations are given at the end of the section on property A, page 148 of Herbrand [34].

Definition 3.10. A term pair, or just a pair, is a multiset of two terms, denoted $\langle u, v \rangle$. A term system (or system) is a (finite) multiset of term pairs. In denoting term systems, we will often drop the curly brackets and simply write $\langle u_1, v_1 \rangle, \ldots, \langle u_n, v_n \rangle$ instead of $\{\langle u_1, v_1 \rangle, \ldots, \langle u_n, v_n \rangle\}$.

The reason why multisets are more convenient than sets is that they lead to a simpler statement of the transformations. This shows up in two ways.

Firstly, since multiset union is not idempotent (contrary to set union), when we write $S \cup \{\langle u, v \rangle\}$, we mean the multiset consisting of all pairs in S distinct from $\langle u, v \rangle$, and of the m+1 pairs $\langle u, v \rangle$, where m is the number of occurrences of $\langle u, v \rangle$ in S (the same convention for multisets of premises is used in Section 2.3). Thus, in a transformation $S \cup \{\langle u, v \rangle\} \Longrightarrow S \cup R$, where S and R are multisets of (unordered pairs) and $\langle u, v \rangle$ does not belong to R, there are fewer occurrences of the pair $\langle u, v \rangle$ on the right-hand side of the transformations than there are on the left-hand side. If S, R were interpreted as sets, and \cup as set union, we would have to stipulate that $\langle u, v \rangle$ does not belong to S, or explicitly remove it from S on the right-hand side.

Secondly, if pairs $\langle u, v \rangle$ are considered ordered, then a special transformation switching pairs $\langle u, x \rangle$ to $\langle x, u \rangle$ is needed when x is a variable but u is not. If we treat $\langle u, v \rangle$ as unordered, such a transformation is unnecessary.

We can now state the *(standard)* unification problem:

Definition 3.11. Given a term system $S = \{\langle u_1, v_1 \rangle, \dots, \langle u_n, v_n \rangle\}$, the (standard) unification problem is to find some substitution σ , called a *(standard) unifier of S*, such that $u_i[\sigma] = v_i[\sigma]$ for every $i, 1 \le i \le n$.

We let U(S) denote the set of all unifiers of S, if they exist. If S has no unifier, we say that S is not unifiable.

Example 3.3. The substitution $\sigma = [x := a, y := a]$ is a unifier of the pair

$$\{\langle f(x,g(a,y)), f(x,g(y,x))\rangle\}.$$

In fact, σ is the only unifier of this pair.

Example 3.4. For every term t, the substitution $\sigma = [x := a, y := a, z := t]$ is a unifier of the pair $\langle f(z, g(a, y)), f(z, g(y, x)) \rangle$.

Example 3.5. The system $S = \{\langle f(x, g(y)), f(g(z), h(z)) \rangle, \langle g(x), g(z) \rangle\}$ is not unifiable, because the subterms g(y) and h(z) are not unifiable, since $g \neq h$.

Example 3.6. The system $S = \{\langle x, g(x) \rangle, \langle y, g(z) \rangle\}$ is not unifiable, because x and g(x) are not unifiable.

Observe that in Example 3.4, there is an infinite number of unifiers. This leads us to the following question.

Question: How do we compare unifiers?

Answer: Define a preorder \leq on substitutions.

Definition 3.12. Let V be a set of variables. For any two substitutions σ and θ , we write $\sigma = \theta[V]$ iff $\sigma(x) = \theta(x)$ for all $x \in V$, and we write $\sigma \leq \theta[V]$ (σ is more general than θ over V) iff there exists a substitution η such that $\theta = \sigma$; $\eta[V]$.

The intuitive idea behind the definition $\sigma \leq \theta[V]$ is that σ is more general than θ (over V) when each $\theta(x)$ can be obtained from $\sigma(x)$ by instantiating some of the variables occurring in $\sigma(x)$.

Example 3.7. Consider the substitutions

$$\sigma = [x := f(g(z)), y := g(z)].$$

and

$$\theta = [x := f(g(g(z))), y := g(g(z))].$$

We have $\sigma \leq \theta[\{x, y\}]$, since if $\eta = [z := g(z)]$, then $\theta = \sigma; \eta$.

The reason for relativizing the definition of \leq to a set V of variables is technical. For one thing, some of the results are incorrect if V is left out. Also, in theorem proving applications, it is often desirable to compare substitutions with respect to a "protected set" of variables V.

A crucial concept in unification theory is that of a most general unifier.

Definition 3.13. Given a term system S and a finite set V of "protected" variables, a substitution σ is a most general unifier for S away from V (or mgu away from V) iff:

- (i) $D(\sigma) \subseteq Var(S)$ and $I(\sigma) \cap (V \cup D(\sigma)) = \emptyset$;
- (ii) σ is a unifier of S, i.e. $\sigma \in U(S)$;
- (iii) For every unifier θ of S, $\sigma \leq \theta[Var(S)]$.

Note that Condition (i) implies that σ is idempotent. When V is not significant, we just call σ an mgu.

A number of questions now arise naturally.

Some Questions:

(1) Is \leq well-founded?

- (2) Given S, can we decide whether S is unifiable?
- (3) Given S, if S is unifiable, is there a mgu?

The answer to all questions is YES.

That \leq is well-founded is shown in Huet [39]. The decidability of standard unification is implicit in Herbrand's thesis [34] (1930), and it is also settled by Robinson [63] (1965), who gives the first algorithm to find mgu's.

We will now show that Questions (1)-(3) have a positive answer. A key point is the similarity between solving a unification problem

$$u_1 = v_1$$
$$\vdots$$
$$u_n = v_n$$

and and solving a system of linear equations,

$$x_1 = a_{11}x_1 + \dots + a_{1n}x_n$$
$$\vdots$$
$$x_m = a_{m1}x_1 + \dots + a_{mn}x_n$$

However, there are some major differences.

- (1) In unification, we cannot assume that the algebraic structure is a field.
- (2) The u_i may not be variables.
- (3) We may have $u_i = v_j$ for $i \neq j$.

Nevertheless, the basic idea of variable elimination (as in Gaussian elimination) applies. If u_i is a variable that does not occur in v_i , we can substitute v_i for u_i in the rest of the system, and preserve the set of solutions:

$$u_1[u_i := v_i] = v_1[u_i := v_i]$$

$$\vdots$$

$$u_i = v_i$$

$$\vdots$$

$$u_n[u_i := v_i] = v_n[u_i := v_i].$$

This leads to the idea of the *method of transformations* on term systems:

Attempt to transform S into a system S' which is obviously solved.

One of the critical issues is to decide what we mean by a solved system. Quite obviously, a solved system is one that should represent a unifying substitution. Since we are dealing with multisets of unordered pairs, we have to be a little careful in formalizing this idea. **Definition 3.14.** A term pair $\langle u, v \rangle$ is in solved form in a system S iff either u or v is a variable, say x, and this variable x does not occur anywhere else in S; in particular, if x = u then $x \notin Var(v)$ (and similarly if x = v then $x \notin Var(u)$). A variable x is called a solved variable if x occurs in a pair $\langle x, v \rangle$ in S and x does occur anywhere else in S.² Thus, to say that a variable is unsolved means that if it occurs in some pair $\langle x, v \rangle$ in S, then it occurs somewhere else in S. A system is in solved form if all its pairs are in solved form.

Note that a system in solved form is always a *set* of solved pairs. Also, note that in a solved pair $\langle u, v \rangle$, it is possible that both u and v are variables, and in this case, it may be that only one of the two is solved in S, or that both are solved in S.

Example 3.8. Given $S = \{\langle x, y \rangle, \langle f(a, x), f(z, a) \rangle\}$, the pair $\langle x, y \rangle$ is solved because the variable y is solved, but the variable x is not solved.

Thus, ignoring the order in term pairs, a system is *solved* iff it is of the form

$$S = \{ \langle x_1, v_1 \rangle, \dots, \langle x_n, v_n \rangle \},\$$

where x_1, \ldots, x_n are **distinct variables**, and $x_i \notin Var(v_j)$ for all $i, j, 1 \leq i, j \leq n$.

A system in solved form defines essentially a unique substitution as shown in the definition below.

Definition 3.15. Given a system S in solved form, we define the substitution σ_S as follows: if $S = \{\langle x_1, v_1 \rangle, \ldots, \langle x_n, v_n \rangle\}$, then $\sigma_S = [x_1 := v_1, \ldots, x_n := v_n]$.

Actually, the above definition is ambiguous, and this is the one place where we might regret our definition of a term system where pairs $\langle u, v \rangle$ are unordered.

Let us explain where the difficulty lies. There is no problem with a solved pair $\langle u, v \rangle$ in which **only one** of u, v, say u, is a solved variable, because then the substitution component must be [u := v]. But when **both** u and v are solved variables, we can use [v := u] or [u := v] interchangeably as a substitution component. Thus, σ_S is not uniquely defined. However, note for any two σ'_S and σ''_S obtained from S, there is a renaming permutation ρ such that $\sigma'_S = \sigma''_S$; ρ (where ρ is determined by the pairs $\langle u, v \rangle$ where both u and v are solved in S). Thus, σ_S is uniquely defined, modulo some inessential renaming permutation. The important fact is that σ_S is an idempotent mgu of S, as we now show.

Proposition 3.1. Let $S = \{\langle x_1, t_1 \rangle, \dots, \langle x_n, t_n \rangle\}$ be in solved form, where x_1, \dots, x_n are solved variables. If $\sigma_S = [x_1 := t_1, \dots, x_n := t_n]$, then σ_S is an idempotent mgu of S. Furthermore, for any unifier θ of S, we have $\theta = \sigma_S; \theta$.

Proof. We simply observe that for any θ , $\theta(x_i) = \theta(t_i) = \theta(\sigma_S(x_i))$ for $1 \le i \le n$, and $\theta(x) = \theta(\sigma_S(x))$ otherwise. Clearly σ_S is an mgu, and since $D(\sigma_S) \cap I(\sigma_S) = \emptyset$ by the definition of solved forms, it is idempotent.

²Recall that $\langle x, v \rangle$ is a multiset, so it can equivalently be written as $\langle v, x \rangle$.

The next question is to find sets of transformations for solving unification problems. The following properties of such a set \mathcal{T} of transformations are desirable:

- (1) (Soundness) Whenever $S \stackrel{*}{\Longrightarrow}_{\mathcal{T}} S'$, then $U(S') \subseteq U(S)$.
- (2) (Completeness) For any unifier θ of S, there is some solved S' s.t. $S \stackrel{*}{\Longrightarrow}_{\mathcal{T}} S'$, and $\sigma_{S'} \leq \theta[Var(S)]$.

When \mathcal{T} satisfies (1) and (2), we say that \mathcal{T} is a complete set of transformations. We also want the transformations to be as *deterministic as possible*, to reduce the search space.

The set of transformations given in the next definition is a variant of the Herbrand–Martelli–Montanari transformations.

Definition 3.16. (The Set of Transformations ST) Let S be any term system (possibly empty), and u, v two terms. The set ST consists of the following transformations:

{

$$\langle u, u \rangle \} \cup S \Longrightarrow S \tag{triv}$$

$$\{\langle f(u_1,\ldots,u_k), f(v_1,\ldots,v_k)\rangle\} \cup S \Longrightarrow \{\langle u_1,v_1\rangle,\ldots,\langle u_k,v_k\rangle\} \cup S$$
(dec)

$$\{\langle x, v \rangle\} \cup S \Longrightarrow \{\langle x, v \rangle\} \cup S[x := v], \tag{vel}$$

where x is a variable s.t. $\langle x, v \rangle$ is **not** solved in $\{\langle x, v \rangle\} \cup S$, and $x \notin Var(v)$. The rules are labeled (triv) for deletion of trivial rules, (dec) for decomposition, and (vel) for variable elimination.

To deal with systems that are not unifiable, we also have the following rules, where \perp is a special symbol indicating that the system $\{\perp\}$ is not unifiable:

$$\{\langle f(u_1,\ldots,u_k), g(v_1,\ldots,v_k)\rangle\} \cup S \Longrightarrow \{\bot\}, \quad f \neq g \tag{\bot_1}$$

$$\{\langle x, v \rangle\} \cup S \Longrightarrow \{\bot\}, \quad x \in Var(v). \tag{L}_2$$

It should be noted that in transformation (vel), one should not relax the condition " $\langle x, v \rangle$ is **not** solved" to "x is not solved". If this were allowed, one could eliminate the variable x even when v is also a solved variable, and this could have the effect that v could then become unsolved again, leading to an infinite (cyclic) sequence of transformations.

Example 3.9. Given $S = \{\langle x, y \rangle, \langle f(a, x), f(z, a) \rangle\}$, the pair $\langle x, y \rangle$ is solved because the variable y is solved but the variable x is not solved. If we allowed the transformation (vel) to apply to x, we would get the infinite sequence

$$\{\langle x, y \rangle, \langle f(a, x), f(z, a) \rangle\} \Longrightarrow \{\langle x, y \rangle, \langle f(a, y), f(z, a) \rangle\} \Longrightarrow \{\langle x, y \rangle, \langle f(a, x), f(z, a) \rangle\} \cdots,$$

since in the first step, (vel) is applied to x, which becomes solved, and the solved variable y becomes unsolved, in the second step, (vel) is applied to y, which becomes solved, and x becomes unsolved, and so on.

Remark: If we prefer to work with ordered pairs $\langle u, v \rangle$ instead of multisets (but still with multisets of pairs S), we add the extra rule

$$\{\langle t, x \rangle\} \cup S \Longrightarrow \{\langle x, t \rangle\} \cup S, \qquad (switch)$$

where x is a variable and t is not a variable. Also, a pair $\langle u, v \rangle$ is solved in a system S if it is of the form $\langle x, v \rangle$, where x is a variable that does not occur anywhere else in S. Such a variable is called a solved variable in S. Then, in the transformation (vel), we require that x is not solved in S and $x \notin Var(v)$. A system $\{\langle x_1, t_1 \rangle, \cdots, \langle x_n, t_n \rangle\}$ in solved form uniquely determines the unifier (in fact, an mgu) $\sigma = [x_1 := t_1, \cdots, x_n := t_n]$.

The set ST is a complete set of transformations for standard unification. The basic idea of the transformations is to transform the original problem into a solved form which represents its own solution.

Example 3.10.

$$\begin{aligned} \{ \langle f(x, g(a, y)), f(x, g(y, x)) \rangle \} \Longrightarrow_{dec} \{ \langle x, x \rangle, \langle g(a, y), g(y, x) \rangle \} \\ \Longrightarrow_{triv} \{ \langle g(a, y), g(y, x) \rangle \} \\ \Longrightarrow_{dec} \{ \langle a, y \rangle, \langle y, x \rangle \} \\ \Longrightarrow_{vel} \{ \langle a, y \rangle, \langle a, x \rangle \}. \end{aligned}$$

The reader can immediately verify that the substitution [y := a, x := a] is a unifier of the original system (in fact, it is an mgu).

Example 3.11.

$$\begin{aligned} \left\{ \left\langle f(h(x), h(g(v))) \right\rangle, \left\langle f(h(g(u))), h(f(u, w)) \right\rangle \right\} \Longrightarrow_{dec} \left\{ \left\langle h(x), h(g(u)) \right\rangle, \left\langle h(g(v)), h(f(u, w)) \right\rangle \right\} \\ \Longrightarrow_{dec} \left\{ \left\langle h(x), h(g(u)) \right\rangle, \left\langle g(v), f(u, w) \right\rangle \right\} \\ \Longrightarrow_{\perp_1} \left\{ \bot \right\}. \end{aligned}$$

Thus, the system $\{\langle f(h(x), h(g(v))) \rangle, \langle f(h(g(u))), h(f(u, w)) \rangle\}$ is not unifiable.

Example 3.12.

$$\begin{aligned} \{ \langle f(x, g(x)), f(y, y) \rangle \} \Longrightarrow_{dec} \{ \langle x, y \rangle, \langle g(x), y) \rangle \} \\ \Longrightarrow_{vel} \{ \langle x, y \rangle, \langle g(y), y) \rangle \} \\ \Longrightarrow_{\perp_2} \{ \bot \}. \end{aligned}$$

Thus, the system $\{\langle f(x, g(x)), f(y, y) \rangle\}$ is not unifiable.

The sense in which these transformations preserve the logically invariant properties of a unification problem is shown in the next lemma.

Proposition 3.2. Let the set of all standard unifiers of a system S be denoted by U(S). If $S \implies S'$ using any transformation from ST, then U(S) = U(S').

Proof. The only difficulty concerns (vel). Suppose $\{\langle x, v \rangle\} \cup S \Longrightarrow_{vel} \{\langle x, v \rangle\} \cup \sigma(S)$ with $\sigma = [x := v]$. For any substitution θ , if $\theta(x) = \theta(v)$, then $\theta = \sigma; \theta$, since $\sigma; \theta$ differs from θ only at x, but $\theta(x) = \theta(v) = \sigma; \theta(x)$. Thus,

$$\theta \in U(\{\langle x, v \rangle\} \cup S)$$
iff $\theta(x) = \theta(v)$ and $\theta \in U(S)$
iff $\theta(x) = \theta(v)$ and $\sigma; \theta \in U(S)$
iff $\theta(x) = \theta(v)$ and $\theta \in U(\sigma(S))$
iff $\theta \in U(\{\langle x, v \rangle\} \cup \sigma(S)).$

Remark: Proposition 3.2 also holds if we use ordered pairs and the transformation (switch).

The point here is that the most important feature of a unification problem is that its set of solutions is preserved under these transformations. Hence, we are justified in our method of attempting to transform such problems into a trivial (solved) form in which the existence of an mgu is evident.

We may now show the soundness and completeness of these transformations following Martelli and Montanari [53].

Theorem 3.3. (Soundness) If $S \stackrel{*}{\Longrightarrow} S'$ with S' in solved form, then $\sigma_{S'} \in U(S)$.

Proof. Using the previous lemma and a trivial induction on the length of transformation sequences, we see that U(S) = U(S'), and so, clearly $\sigma_{S'} \in U(S)$.

Theorem 3.4. (Completeness) Every sequence of transformations

$$S = S_0 \implies S_1 \implies S_2 \implies \dots$$

must eventually terminate. Furthermore, S is unifiable iff the system $\{\bot\}$ is not derivable, in which case every system S' derivable from S is in solved form, and for every $\theta \in U(S)$, $\sigma_{S'} \leq \theta$.

Proof. We first show that every transformation sequence terminates. For any system S, let us define a complexity measure $\mu(S) = \langle n, m \rangle$ where n is the number of *unsolved* variables in the system, and m is the sum of the sizes of all the terms in the system. Since the lexicographic ordering on $\mathbb{N} \times \mathbb{N}$ is well-founded (where (m, n) < (m', n') if either m < m'or m = m' and n < n'), each transformation produces a new system with a measure strictly smaller under this ordering: (triv) and (dec) must decrease m and cannot increase n, and (vel) must decrease n.

Therefore, the relation \implies is Noetherian, and every transformation sequence must end in some system to which no transformation applies. Suppose a given sequence ends in a system S'.

Observe that no transformation applies to a system S' if either $S' = \{\bot\}$ or S' is in solved form. By Proposition 3.2, S is unifiable iff S' is unifiable. Therefore, S is not unifiable iff $S' = \{\bot\}$, or S' is in solved form and S is unifiable. Now since $\theta_{S'} \in U(S')$, for every unifier $\theta \in U(S)$, by Proposition 3.1, we must have $\sigma_{S'} \leq \theta$. Putting these two theorems together, we have that the set ST can always find an mgu for a unifiable system of terms. As remarked in Martelli and Montanari [53], this abstract formulation can be used to model many different unification algorithms, by simply specifying data structures and a control strategy.

Remark: Theorem 3.3 still holds if we use ordered pairs and allow the transformation (switch). To prove that every transformation sequence terminates, we use the complexity measure $\mu(S) = \langle n, m, p \rangle$, where m, n are as before, and p is the number of pairs $\langle t, x \rangle$ where x is a variable and t is not.

The first published unification algorithm due to Robinson ([63]) can run in exponential time. A variant of Robinson's unification algorithm using disagreement sets is given in Gallier [24] (Section 8.4). An example of an exponential size mgu is given in Problem 8.4.4.

Since Robinson's seminal discovery, several polynomial-time algorithms for standard unification have been given, including one by Robinson himself.

Among them, we single out a quasi-linear algorithm due to Huet [39] (1976), a linear-time algorithm due to Paterson and Wegman [57] (1978), and quasi-linear and linear algorithms due to Martelli and Montanari [53] (1982).

For an excellent account of standard unification, the reader is referred to Knight's survey article [44]. Martelli and Montanari's important contribution ([53]), perhaps even more than their algorithm itself,³ is to have demonstrated with perfect clarity that the method of transformations is remarkably well suited for tackling unification problems. In some sense, Martelli and Montanari revived Herbrand's approach, which led to new important work by Kirchner and others.

In the next section, we sketch some versions of fast unification algorithms.

3.4 Fast (Standard) Unification

If one looks closely at the set of transformations ST, one realizes that the complexity of unification algorithms is related to explicit variable elimination. Thus, a main concern in designing fast unification algorithms is to avoid explicit variable elimination. We first give the intuition behind a fast unification algorithm due to Martelli and Montanari [53].

Starting from a system S, suppose we only apply decomposition (dec) and deletion (triv) of trivial rules. If no failure takes place and there are still pairs left, we must reach a system S' such that every pair is of the form $\langle x, v \rangle$, where x is a variable.

We can group all pairs sharing some common term (two pairs $\langle u, v \rangle$ and $\langle u', v' \rangle$ share a common term if $\{u, v\} \cap \{u', v'\} \neq \emptyset$; remember, a pair $\langle u, v \rangle$) is a multiset), to form equivalence classes. Thus, S' can be viewed as a partition, where every class with more than one element is of the form

$$\{x_1,\ldots,x_k,t_1,\ldots,t_m\},\$$

³Their algorithm is not so different from Paterson and Wegman's algorithm.

where x_1, \ldots, x_k are variables (k > 0) and t_1, \ldots, t_m are nonvariable terms $(m \ge 0)$.

Clearly, S' is unifiable only if for every class, all nonvariable terms have the same root symbol.

The other basic idea is to **analyze dependencies among variables** (analogy with solving systems of linear equations).

A precedence relation on classes can be defined as follows: C < C' iff C' contains some variable x that occurs in some nonvariable term t in C.

Intuitively, the class of C needs the value of the variable x. The following is easily shown.

Proposition 3.5. If $<^+$ is reflexive, then S' is not unifiable.

From now on, we are dealing with sets of the form

$$\{x_1,\ldots,x_k,t_1,\ldots,t_m\},\$$

that Martelli and Montanari call *multiequations*, and write in the form

$$\{x_1,\ldots,x_k\} := \{t_1,\ldots,t_m\}.$$

Since eliminating duplicate terms may be costly, they allow both sides to be multisets.

If $<^+$ is acyclic (irreflexive), roughly speaking, Martelli and Montanari do the following:

Pick some class $\{x_1, \ldots, x_k, t_1, \ldots, t_m\}$ where m > 0 and the t_i are not constants. Since all the t_i have the same root symbol, say f, form the new system in which the above class is replaced by the sets

 $\{x_1,\ldots,x_k,f(y_1,\ldots,y_n)\},\{y_1,t_1/1,\ldots,t_m/1\},\ldots,\{y_n,t_1/n,\ldots,t_m/n\},\$

where y_1, \ldots, y_m are new variables.

Again, group blocks together to form a partition, and check for acyclicity of the new $<^+$. Continue this process until failure, or no new classes are formed. If the last $<^+$ obtained is acyclic, we can form a *mgu* in *triangular form*, by using any total ordering of the classes extending $<^+$.

Formally, a triangular form is defined as follows.

Definition 3.17. Given an idempotent substitution σ (i.e., $D(\sigma) \cap I(\sigma) = \emptyset$) with domain $D(\sigma) = \{x_1, \ldots, x_k\}$, a triangular form for σ is a finite set T of pairs $\langle x, t \rangle$, where $x \in D(\sigma)$ and t is a term, such that this set T can be sorted (possibly in more than one way) into a sequence $\langle \langle x_1, t_1 \rangle, \ldots, \langle x_k, t_k \rangle \rangle$ satisfying the following properties: for every $i, 1 \leq i \leq k$,

(1)
$$\{x_1, \ldots, x_i\} \cap Var(t_i) = \emptyset$$
, and

(2)
$$\sigma = [x_1 := t_1]; \ldots; [x_k := t_k].$$

The set of variables $\{x_1, \ldots, x_k\}$ is called the *domain* of T.

Note that in particular $x_i \notin Var(t_i)$ for every $i, 1 \leq i \leq k$, but variables in the set $\{x_{i+1},\ldots,x_k\}$ may occur in t_1,\ldots,t_i . It is easily seen that σ is an (idempotent) mgu of the term system T.

Example 3.13. Consider the substitution $\sigma = [x_1 := f(f(x_3, x_3), f(x_3, x_3)), x_2 := f(x_3, x_3)].$ The system $T = \{ \langle x_1, f(x_2, x_2) \rangle, \langle x_2, f(x_3, x_3) \rangle \}$ is a triangular form of σ since it can be ordered as $\langle \langle x_1, f(x_2, x_2) \rangle, \langle x_2, f(x_3, x_3) \rangle \rangle$ and $\sigma = [x_1 := f(x_2, x_2)]; [x_2 := f(x_3, x_3)].$

It turns out that we have computed a certain relation on terms, a *forward closure*. We now define this concept, due to Paterson and Wegman [57] (1978), and give a fast algorithm based on it.

Definition 3.18. Let Σ be a finite ranked alphabet (signature) and \mathcal{X} a set of variables. A unification graph is finite node-labeled directed graph $G = (V, \delta, \Lambda)$, where $\Lambda: V \to \Sigma \cup \mathcal{X}$ is a function assigning a label in $\Sigma \cup \mathcal{X}$ to the nodes, and where the edges are determined by a transition function $\delta \colon \bigcup_{u \in V, 1 \leq j \leq r(\Lambda(u))} \{(u, j)\} \to V$, so that if $\Lambda(u)$ is a function symbol of rank $r(\Lambda(u)) = k \ge 1,^4$ then u has k immediate successors $\delta(u, 1), \ldots, \delta(u, k)$. In particular, if k = 0, then there are no outgoing edges from u, and we say that u is a *leaf* (or *sink*). We also denote $\delta(u, i)$ as u[i].

Observe that a unification graph is analogous to a sort of DFA, but the number $r(\Lambda(u))$ of outgoing transitions from a node u can vary, and some nodes may be sink nodes.

Definition 3.19. An equivalence relation $R \subseteq V \times V$ on a unification graph $G = (V, \delta, \Lambda)$ is forward-closed iff for every pair (u, v) of nodes in V^2 , whenever uRv and $\Lambda(u) = \Lambda(v)$, then u[i] R v[i] for every $i, 1 \leq i \leq n$, where $n = r(\Lambda(u))$. A forward-closed equivalence relation R is consistent (or has no bad pair), if for every $(u, v) \in R$, either $\Lambda(u) = \Lambda(v)$, or one of $\Lambda(u), \Lambda(v)$ is a variable. So a bad pair is pair (u, v) such that neither $\Lambda(u)$ nor $\Lambda(v)$ is a variable, and $\Lambda(u) \neq \Lambda(v)$.

Graphically, if u and v are two nodes labeled with the same symbol f of rank n, if $u[1], \ldots, u[n]$ are the successors of u and $v[1], \ldots, v[n]$ are the successors of v,

u . v . \dots u[n] v[1] \dots v[n]

if u and v are equivalent then u[i] and v[i] are equivalent for all $i, 1 \leq i \leq n$.

To compute the smallest forward-closed relation containing a relation R, we construct a sequence of relations R_i by alternating between stages during which we add missing pairs

u[1].

⁴Recall that variables and constants have rank 0.

(u[i], v[i]) in R_i , where $(u, v) \in R_i$ and $\Lambda(u) = \Lambda(v)$, and stages where make the evolving relation into an equivalence relation. Recall that if R is a relation, the smallest equivalence relation R_{\approx} containing R is given by $R_{\approx} = (R \cup R^{-1})^*$, the reflexive and transitive closure of $R \cup R^{-1}$, with $R^{-1} = \{(v, u) \mid (u, v) \in R\}$.

We define the sequence R_i of equivalence relations as follows.

$$R_0 = R_{\approx}$$

$$R_{i+1} = (R_i \cup \{(u[j], v[j]) \mid (u, v) \in R_i, \ \Lambda(u) = \Lambda(v), \ 1 \le j \le r(\Lambda(u))\})_{\approx}$$

The following proposition is easily shown.

Proposition 3.6. Given any relation R on a finite unification graph G, there is a smallest integer $i_0 \geq 0$, such that $R_{i_0+1} = R_{i_0}$ and R_{i_0} is the smallest forward-closed equivalence relation containing R. We denote R_{i_0} by R^{\dagger} .

Given a system $S = \{ \langle u_1, v_1 \rangle, \ldots, \langle u_m, v_m \rangle \}$, the process of computing S^{\dagger} is equivalent to the following procedure that uses the transformations (triv) and (vel) as well as a slight generalization of (dec).

First, compute the system S' obtained by applying only the transformations (triv) and (dec) until no longer possible,

$$S \Longrightarrow S_1 \Longrightarrow \cdots \Longrightarrow S_i \Longrightarrow \cdots \Longrightarrow S'.$$

In S', all pairs are the form $\langle x, v \rangle$, where x is a variable. Then, find the smallest equivalence relation S'_{\approx} . If S'_{\approx} is forward-closed, then S^{\dagger} is the smallest equivalence relation containing the pairs occurring in all the S_i .

Otherwise, there is some class of the form

$$\{x_1,\ldots,x_k, f(t'_1,\ldots,t'_n), f(t''_1,\ldots,t''_n), t_3,\ldots,t_m\}.$$

We extend the rule (dec) to apply to multisets of equivalence classes as follows:

$$\{x_1, \dots, x_k, f(t'_1, \dots, t'_n), f(t''_1, \dots, t''_n), t_3, \dots, t_m\} \cup S \Longrightarrow \{x_1, \dots, x_k, t_3, \dots, t_m\} \cup \{t'_1, t''_1\} \cup \dots \cup \{t'_n, t''_n\} \cup S.$$
 (dec')

Now, we apply the rules (dec') and (triv) to S'_{\approx} until it no longer possible, obtaining S'', and then we compute the smallest equivalence S''_{\approx} . If S''_{\approx} is forward-closed, we are done. Otherwise, we repeat the above steps.

At this stage, if the system is unifiable, we need to find a total order (not necessarily unique) on the variables to obtain an mgu in triangular form. This is achieved by computing a directed graph G_S and its quotient graph G_S/S^{\dagger} , both defined below. If the directed graph G_S/S^{\dagger} is acyclic, instead of applying (vel) to obtain a system in solved form, we can use the graph G_S/S^{\dagger} to obtain an mgu in triangular form, and this prevents creating terms of exponential size, which could arise when (vel) is used.

In order to test whether a system $S = \{\langle u_1, v_1 \rangle, \ldots, \langle u_m, v_m \rangle\}$ is unifiable, we compute the unification closure of the relation S on the graph G_S defined below.

Definition 3.20. Given a term system S, the directed graph G_S is defined as follows.

- (i) The set of nodes V_S of G_S is the set of all subterms of terms in S.
- (ii) Every subterm that is either a constant or a variable is a sink node labeled with that symbol.
- (iii) For every subterm of the form $f(s_1, \ldots, s_k)$, the label is f, and $\delta(f(s_1, \ldots, s_k), i) = s_i$, for each $i, 1 \le i \le k$. In other words, there is an edge from $f(s_1, \ldots, s_k)$ to s_i .

Observe the graph G_S is acyclic, but identical subterms are collapsed to a single node. Also, since the label of a node is equal to this node if it is a variable or a constant, or to the symbol f if this node is the term $f(t_1, \ldots, t_n)$, we may omit the labels when drawing the graphs.

Example 3.14. Consider the system

$$S = \{ \langle g(x), g(f(y)) \rangle, \langle f(y), f(g(z)) \rangle \}.$$

The set of nodes is

$$V_S = \{g(x), g(f(y)), x, f(y), y, f(g(z)), g(z), z\},\$$

and the edges are given by

$$\begin{split} \delta(g(x),1) &= x, & \delta(g(f(y)),1) = f(y), & \delta(f(y),1) = y, \\ \delta(f(g(z)),1) &= g(z), & \delta(g(z),1) = z. \end{split}$$

The graph G_S is shown in Figure 3.1.

Let S^{\dagger} be the least forward-closed equivalence relation containing the relation S on the graph G_S . If S^{\dagger} contains a bad pair, S is not unifiable. Otherwise, a new directed graph G_S/S^{\dagger} is constructed,

Definition 3.21. The directed graph G_S/S^{\dagger} (without parallel edges) is defined as follows.

- (i) The nodes of G_S/S^{\dagger} are the equivalence classes of S^{\dagger} .
- (ii) There is an edge from a class C to a class C' iff there is some edge in G_S from some node s in class C to some node t in class C'.

The edges of G_S/S^{\dagger} are well-defined because S^{\dagger} is forward-closed.

Example 3.15. The smallest forward-closed equivalence relation of the system

$$S = \{ \langle g(x), g(f(y)) \rangle, \langle f(y), f(g(z)) \rangle \}$$



Figure 3.1: The graph G_S .

associated with the graph of Example 3.14 consists of the following equivalence classes:

$$\{g(x), g(f(y))\}, \{x, f(y), f(g(z))\}, \{y, g(z)\}, \{z\}$$

The graph G_S/S^{\dagger} is a tree which induces the ordering x < y < z on the variables, and we immediately read a mgu in triangular form,

$$\sigma = [x := f(y)]; [y := g(z)],$$

and in soved form,

$$\sigma = [x := f(g(z)), y := g(z)].$$

The graphs G_S and G_S/S^{\dagger} are shown in Figure 3.2. We have the following sequence of transformations:

$$\{ \langle g(x), g(f(y)) \rangle, \langle f(y), f(g(z)) \rangle \} \Longrightarrow \{ \langle x, f(y) \rangle, \langle f(y), f(g(z)) \rangle \} \\ \Longrightarrow \{ \langle x, f(y) \rangle, \langle y, g(z) \rangle \},$$

and the smallest equivalence relation containing all the pairs in this derivation is indeed the forward closure of S.

The following result is essentially due to Paterson and Wegman [57] (1978).

Theorem 3.7. The system S is unifiable iff the unification closure S^{\dagger} has no bad pairs and the graph G_S/S^{\dagger} is acyclic.

When S is unifiable, let $\langle C_1, \ldots, C_n \rangle$ be some sequence of all equivalence classes containing some variable, ordered such that, if there is a path from C_i to C_j , then i < j (such a



Figure 3.2: The graph G_S and the corresponding quotient graph.

sequence may not be unique, but the partial order induced by the graph G_S/S^{\dagger} , which is acyclic, can always be extended to a total order).

For each $i, 1 \leq i \leq n$, if C_i contains some nonvariable term, let t_i be any such term, else let t_i be any variable in C_i . Let

$$\sigma_i = [z_1 := t_i, \ldots, z_k := t_i],$$

where $\{z_1, \ldots, z_k\}$ is the set of variables in C_i , and let

$$\sigma = \sigma_1; \ldots; \sigma_n.$$

Then σ is a most general unifier of S. The substitution σ has a triangular representation.

Example 3.16. Consider the pair

$$S = \{ \langle f(f(x_2, x_2), f(x_3, x_3)), f(x_1, x_2) \rangle \}.$$

The classes of the forward closure S^{\dagger} are

$$\{ f(f(x_2, x_2), f(x_3, x_3)), f(x_1, x_2) \}$$

$$\{ f(x_2, x_2), x_1 \}, \{ f((x_3, x_3), x_2) \}$$

$$\{ x_3 \}.$$



Figure 3.3: The graph G_S .

The graphs G_S and G_S/S^{\dagger} are shown in Figure 3.3 and Figure 3.4. Since the graph G_S has an edge from $f(x_2, x_2)$ to x_2 , there is an edge from $\{x_1, f(x_2, x_2)\}$ to $\{x_2, f(x_3, x_3)\}$, so a triangular form of the $mgu \sigma$ is

$$\sigma = [x_1 := f(x_2, x_2)]; [x_2 := f(x_3, x_3)].$$

Note that

$$\sigma = [x_1 := f(f(x_3, x_3), f(x_3, x_3)), x_2 := f(x_3, x_3)].$$

Example 3.17. Consider the system

$$S = \{ \langle g(x), g(f(y)) \rangle, \langle h(x, x), h(f(z), w) \rangle \}$$

We find that the equivalence class of S^{\dagger} are

$$\{g(x),g(f(y))\}, \quad \{h(x,x),h(f(z),w)\}, \quad \{x,w,f(y),f(z)\}, \quad \{y,z\}.$$

The graphs G_S and G_S/S^{\dagger} are shown in Figure 3.5 and Figure 3.6. Since there is an edge from $\{x, w, f(y), f(z)\}$ to $\{y, z\}$, we can order the variables as x < w < y < z, and we have the mgu in triangular form

$$\sigma = [x := f(y)]; [w := f(y)]; [y := z].$$

Example 3.18. Consider the system

$$S = \{ \langle g(x), g(f(y)) \rangle, \langle h(f(x), x), h(z, w) \rangle \}$$



Figure 3.4: The graph G_S and the corresponding quotient graph.

We find that the equivalence class of S^{\dagger} are

$$\{g(x), g(f(y))\}, \{h(f(x), x), h(z, w)\}, \{x, w, f(y)\}, \{z, f(x)\}, \{y\}$$

The graphs G_S and G_S/S^{\dagger} are shown in Figure 3.7 and Figure 3.8. Since there is an edge from $\{z, f(x)\}$ to $\{x, w, f(y)\}$ and an edge from $\{x, w, f(y)\}$ to $\{y\}$, we can order the variables as z < x < w < y, and we have the mgu in triangular form

$$\sigma = [z := f(x)]; [x := f(y)]; [w := f(y)].$$

We now give a simple fast algorithm, assuming for simplicity that every symbol in Σ is either a constant or binary. This algorithm is basically Ravi Sethi's algorithm, in [1]. A variant of it is a fast algorithm for testing whether two states in a DFA are equivalent due to Knurh, Hopcroft, and Karp.



Figure 3.5: The graph G_S .



Figure 3.6: The graph G_S and the corresponding quotient graph.



Figure 3.7: The graph G_S .



Figure 3.8: The graph G_S and the corresponding quotient graph.

Graph-Based Fast Unification Algorithm

```
procedure unif(u, v : node; var R : partition; var flag : bool);
  var s, t : node; flag1, flag2 : bool;
  begin
     flaq1 := false; flaq2 := false;
    s := find(R, u); t := find(R, v);
    if s = t then
       flaq := \mathbf{true}
    else
      if nonvar(u) and nonvar(v) and root(u) = root(v) then
         union(R, s, t);
         unif(left(u), left(v), R, flag1);
         unif(right(u), right(v), R, flag2);
         flaq := flaq1 and flaq2
      else
         if var(u) or var(v) then
           union(R, s, t);
           flag := \mathbf{true}
         else
           flag := false
         endif
      endif
    endif:
    if flaq and acyclic(R) then
      printsubst(R)
    else
       failure(R)
    endif
  end
```

Using Tarjan's fast version of *union* and *find*, where equivalence classes are represented by trees, the algorithm runs in time $O(n\alpha(n))$, where $\alpha(n)$ is a sort of inverse of Ackermann's function that grows extremely slowly.

We conclude this section with some comments on Paterson and Wegman's fast algorithm [57] (1978). Paterson and Wegman's algorithm is a unification closure algorithm, and it uses the concept of a "root class". A root class is an equivalence class of nodes containing only terms corresponding to nodes of the DAG that have no parents. It is immediately seen that if a system S is unifiable, then every class that is mimimal in the ordering defined such that C < C' iff there is a path from C to C' in the DAG is a root class.

Paterson and Wegman's algorithm processes root classes first. A root class has the property that no further nodes can be added to it as the result of computing a unification closure, because propagation proceeds from parent to children. Thus, once a root class has been processed, it can be deleted.

It should be noted that Paterson and Wegman's original algorithm contains bugs. The bugs were reported and fixed by De Champeaux [13]. One of the bugs is a trivial typo. The other bug is more subtle. In the Paterson-Wegman's algorithm, the equivalence of two elements is represented by the existence of a special (undirected) edge between these two elements (not to be confused with the edges of the DAG). The problem is that multiple edges can be created by the algorithm, but this is not taken into account by the algorithm.

Chapter 4

RAM Programs, Turing Machines, and the Partial Computable Functions

In this chapter we address the fundamental question

What is a computable function?

Nowadays computers are so pervasive that such a question may seem trivial. Isn't the answer that a function is computable if we can write a program computing it!

This is basically the answer so what more can be said that will shed more light on the question?

The first issue is that we should be more careful about the kind of functions that we are considering. Are we restricting ourselves to total functions or are we allowing partial functions that may not be defined for some of their inputs? It turns out that if we consider functions computed by programs, then partial functions must be considered. In fact, we will see that "deciding" whether a program terminates for all inputs is impossible. But what does deciding mean?

To be mathematically precise requires a fair amount of work. One of the key technical points is the ability to design a program U that takes other programs P as input, and then executes P on any input x. In particular, U should be able to take U itself as input!

Of course a compiler does exactly the above task. But fully describing a compiler for a "real" programming language such as JAVA, PYTHON, C++, *etc.* is a complicated and lengthy task. So a simpler (still quite complicated) way to proceed is to develop a toy programming language and a toy computation model (some kind of machine) capable of executing programs written in our toy language. Then we show how programs in this toy language can be coded so that they can be given as input to other programs. Having done this we need to demonstrate that our language has *universal computing power*. This means that we need to show that a "real" program, say written in JAVA, could be translated into a possibly much longer program written in our toy language. This step is typically an act of faith, in the sense that the details that such a translation can be performed are usually not provided.

A way to be precise regarding universal computing power is to define mathematically a family of functions that should be regarded as "obviously computable," and then to show that the functions computed by the programs written either in our toy programming language or in any modern progamming language are members of this mathematically defined family of computable functions. This step is usually technically very involved, because one needs to show that executing the instructions of a program can be mimicked by functions in our family of computable functions. Conversely, we should prove that every computable function in this family is indeed computable by a program written in our toy programming language or in any modern programming language. Then we will be have the assurance that we have captured the notion of universal computing power.

Remarkably, Herbrand, Gödel, and Kleene defined such a family of functions in 1934-1935. This is a family of numerical functions $f: \mathbb{N}^m \to \mathbb{N}$ containing a subset of very simple functions called base functions, and this family is the smallest family containing the base functions closed under three operations:

- 1. Composition
- 2. Primitive recursion
- 3. Minimization.

Historically, the first two models of computation are the λ -calculus of Church (1935) and the *Turing machine* (1936) of Turing. Kleene proved that the λ -definable functions are exactly the (total) computable functions in the sense of Herbrand–Gödel–Kleene in 1936, and Turing proved that the functions computed by Turing machines are exactly the computable functions in the sense of Herbrand–Gödel–Kleene in 1937. Therefore, the λ -calculus and Turing machines have the same "computing power," and both compute exactly the class of computable functions in the sense of Herbrand–Gödel–Kleene. In those days these results were considered quite surprising because the formalism of the λ -calculus has basically nothing to do with the formalism of Turing machines.

Once again we should be more precise about the kinds of functions that we are dealing with. Until Turing (1936), only numerical functions $f \colon \mathbb{N}^m \to \mathbb{N}$ were considered. In order to compute numerical functions in the λ -calculus, Church had to encode the natural numbers as certain λ -terms, which can be viewed as iterators.

Turing assumes that what he calls his *a*-machines (for automatic machines) make use of the symbols 0 and 1 for the purpose of input and output, and if the machine stops, then the output is a string of 0s and 1s. Thus a Turing machine can be viewed as computing a function $f: (\{0,1\}^*)^m \to \{0,1\}^*$ on strings. By allowing a more general alphabet Σ , we see that a Turing machine computes a function $f: (\Sigma^*)^m \to \Sigma^*$ on strings over Σ . At first glance it appears that Turing machines compute a larger class of functions, but this is not so because there exist mutually invertible computable coding functions $C: \Sigma^* \to \mathbb{N}$ and decoding functions $D: \mathbb{N} \to \Sigma^*$. Using these coding and decoding functions, it suffices to consider numerical functions.

However, Turing machines can also very naturally be viewed as devices for defining computable languages in terms of acceptance and rejection; some kinds of generalized DFA's or NFA's. In this role, it would be very awkward to limit ourselves to sets of natural numbers, although this is possible in theory.

We should also point out that the notion of computable language can be handled in terms of a computation model for functions by considering the characteristic functions of languages. Indeed, a language A is computable (we say decidable) iff its characteristic function χ_A is computable.

The above considerations motivate the definition of the computable functions in the sense of Herbrand–Gödel–Kleene to functions $f: (\Sigma^*)^m \to \Sigma^*$ operating on strings. However, it is technically simpler to work out all the undecidability results for numerical functions or for subsets of N. Since there is no loss of generally in doing so in view of the computable bijections $C: \Sigma^* \to \mathbb{N}$ and $D: \mathbb{N} \to \Sigma^*$, we will do so.

Nevertherless, in order to deal with languages, it is important to develop a fair amount of computability theory about functions computing on strings, so we will present another computation model, the *RAM program model*, which computes functions defined on strings. This model was introduced around 1963 (although it was introduced earlier by Post in a different format). It has the advantage of being closer to actual computer architecture, because the RAM model consists of programs operating on a fixed set of registers. This model is equivalent to the Turing machine model, and the translations, although tedious, are not that bad.

The RAM program model also has the technical advantage that coding up a RAM program as a natural number is not that complicated.

The λ -calculus is a very elegant model but it is more abstract than the RAM program model and the Turing machine model so we postpone discussing it until Chapter 6.

Another very interesting computation model particularly well suited to deal with decidable sets of natural numbers is *Diophantine definability*. This model, arising from the work involved in proving that Hilbert's tenth problem is undecidable, will be discussed in Chapter 11.

In the following sections we will define the RAM program model, the Turing machine model, and then argue without proofs (relegated to Chapter 5) that there are algorithms to convert RAM programs into Turing machines, and conversely. Then we define the class of computable functions in the sense of Herbrand–Gödel–Kleene, both for numerical functions (defined on \mathbb{N}) and functions defined on strings. This will require explaining what is primitive recursion, which is a restricted form of recursion which guarantees that if it is applied to total

functions, then the resulting function is total. Intuitively, primitive recursion corresponds to writing programs that only use **for** loops (loops where the number of iterations is known ahead of time and fixed).

4.1 Partial Functions and RAM Programs

In this section we define an abstract machine model for computing functions

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{n} \to \Sigma^*,$$

where $\Sigma = \{a_1, \ldots, a_k\}$ is some input alphabet.

Numerical functions $f: \mathbb{N}^n \to \mathbb{N}$ can be viewed as functions defined over the one-letter alphabet $\{a_1\}$, using the bijection $m \mapsto a_1^m$.

Since programs are not guaranteed to terminate for all inputs, we are forced to deal with partial functions, so we recall their definition.

Definition 4.1. A binary relation $R \subseteq A \times B$ between two sets A and B is *functional* iff, for all $x \in A$ and $y, z \in B$,

 $(x, y) \in R$ and $(x, z) \in R$ implies that y = z.

A partial function is a triple $f = \langle A, G, B \rangle$, where A and B are arbitrary sets (possibly empty) and G is a functional relation (possibly empty) between A and B, called the graph of f.

Hence, a partial function is a functional relation such that every argument has at most one image under f.

The graph of a function f is denoted as graph(f). When no confusion can arise, a function f and its graph are usually identified.

A partial function $f = \langle A, G, B \rangle$ is often denoted as $f \colon A \to B$.

The *domain dom*(f) of a partial function $f = \langle A, G, B \rangle$ is the set

$$dom(f) = \{x \in A \mid \exists y \in B, (x, y) \in G\}.$$

For every element $x \in dom(f)$, the unique element $y \in B$ such that $(x, y) \in graph(f)$ is denoted as f(x). We say that f(x) is defined, also denoted as $f(x) \downarrow$.

If $x \in A$ and $x \notin dom(f)$, we say that f(x) is undefined, also denoted as $f(x) \uparrow$.

Intuitively, if a function is partial, it does not return any output for any input not in its domain. This corresponds to an *infinite computation*.

It is important to define precisely the notion of equality of partial functions.

Definition 4.2. Two partial functions $f: A \to B$ and $f': A' \to B'$ are equal iff A = A', B = B', and graph(f) = graph(f'), which means that for all $a \in A$, either both f(a) and f'(a) are defined and f(a) = f'(a), or both f(a) and f'(a) are undefined.

This definition implies that when we write f(a) = f'(a) for some $a \in A$, we mean that either both f(a) and f'(a) are defined and f(a) = f'(a), or f and f' are both undefined at a (equivalently, $a \notin dom(f) = dom(f')$). There is a slight abuse of notation since f(a) (and f'(a)) may not be defined, but this is the customary notation.

Definition 4.3. A partial function $f: A \to B$ is a total function iff dom(f) = A. It is customary to call a total function simply a function.

We now define a model of computation know as the *RAM programs* or *Post machines*.

RAM programs are written in a sort of assembly language involving simple instructions manipulating strings stored into registers.

Every RAM program uses a fixed and finite number of *registers* denoted as $R1, \ldots, Rp$, with no limitation on the size of strings held in the registers.

RAM programs can be defined either in flowchart form or in linear form. Since the linear form is more convenient for the purpose of encoding programs as numbers (a process known as Gödel numbering), we focus primarily on RAM programs in linear form. However, the flowchart form tends to be more intuitive and is useful to describe certain constructions (such as primitive recursion and minimization) so we will also describe it.

A RAM program P (in linear form) consists of a finite sequence of *instructions* using a finite number of registers $R1, \ldots, Rp$.

Instructions may optionally be labeled with line numbers denoted as $N1, \ldots, Nq$.

It is neither mandatory to label all instructions, nor to use distinct line numbers! Thus the same line number can be used in more than one line. As we will see later on, this makes it easier to concatenate two different programs without performing a renumbering of line numbers.

Every instruction has *four fields*, not necessarily all used. The main field is the **op-code**.

Definition 4.4. *RAM programs* are constructed from seven types of *instructions* shown below.

(1_{j})	N		add_j	Y
(2)	N		tail	Y
(3)	N		clr	Y
(4)	N	Y	\leftarrow	X
(5a)	N		jmp	N1a
(5b)	N		jmp	N1b
$(6_j a)$	N	Y	jmp_i	N1a
$(6_j b)$	N	Y	jmp_j	N1b
(7)	N		continue	

1. An instruction of type (1_j) concatenates the letter a_j to the right of the string held by register Y $(1 \le j \le k)$. The effect is the assignment

$$Y := Y a_i$$
.

2. An instruction of type (2) deletes the leftmost letter of the string held by the register Y. This corresponds to the function *tail*, defined such that

$$tail(\epsilon) = \epsilon,$$

$$tail(a_j u) = u$$

for all $u \in \Sigma^*$. The effect is the assignment

$$Y := tail(Y).$$

3. An instruction of type (3) clears register Y, i.e., sets its value to the empty string ϵ . The effect is the assignment

$$Y := \epsilon.$$

4. An instruction of type (4) assigns the value of register X to register Y. The effect is the assignment

$$Y := X$$

5. An instruction of type (5a) or (5b) is an unconditional jump.

The effect of (5a) is to jump to the closest line number N1 occurring above the instruction being executed, and the effect of (5b) is to jump to the closest line number N1 occurring below the instruction being executed.

6. An instruction of type $(6_j a)$ or $(6_j b)$ is a conditional jump. Let *head* be the function defined as follows:

$$head(\epsilon) = \epsilon,$$
$$head(a_{j}u) = a_{j}$$

for all $u \in \Sigma^*$. The effect of $(6_j a)$ is to jump to the closest line number N1 occurring above the instruction being executed iff $head(Y) = a_j$, else to execute the next instruction (the one immediately following the instruction being executed).

The effect of $(6_j b)$ is to jump to the closest line number N1 occurring below the instruction being executed iff $head(Y) = a_j$, else to execute the next instruction.

When computing over \mathbb{N} , instructions of type $(6_j a)$ or $(6_j b)$ jump to the closest N1 above or below iff Y is nonnull.

7. An instruction of type (7) is a no-op, i.e., the registers are unaffected. If there is a next instruction, then it is executed, else the program stops.

When computing over \mathbb{N} , which corresponds to the case where $\Sigma = \{a_1\}$, an instruction of type (1) computes the successor function S (or **Succ**) given by S(n) = n+1, an instruction of type (2) computes the predecessor function *pred* given by pred(n+1) = n and pred(0) = 0, and an instruction of type (3) computes the zero function Z given by Z(n) = 0.

Obviously, a program is syntactically correct only if certain conditions hold.

Definition 4.5. A *RAM program* P is a finite sequence of instructions as in Definition 4.4, and satisfying the following conditions:

- (1) For every jump instruction (conditional or not), the line number to be jumped to must exist in P.
- (2) The last instruction of a RAM program is a continue.

The reason for allowing multiple occurences of line numbers is to make it easier to concatenate programs without having to perform a renaming of line numbers.

The technical choice of jumping to the closest address N1 above or below comes from the fact that it is easy to search up or down using primitive recursion, as we will see later on.

For the purpose of computing a function $f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{r} \to \Sigma^*$ using a RAM program

P, we assume that P has at least n registers called *input registers*, and that these registers $R1, \ldots, Rn$ are initialized with the input values of the function f. We also assume that the output is returned in register R1.

Example 4.1. The following RAM program concatenates two strings x_1 and x_2 held in registers R1 and R2. Since $\Sigma = \{a, b\}$, for more clarity, we wrote jmp_a instead of jmp_1 , jmp_b instead of jmp_2 , add_a instead of add_1 , and add_b instead of add_2 .

	R3	\leftarrow	R1
	R4	\leftarrow	R2
N0	R4	\mathtt{jmp}_a	N1b
	R4	\mathtt{jmp}_b	N2b
		jmp	N3b
N1		add_a	R3
		tail	R4
		jmp	N0a
N2		add_b	R3
		tail	R4
		jmp	N0a
N3	R1	\leftarrow	R3
		continue	

The instructions of a RAM program in flowchart form are shown in Figure 4.1.



Schematic Representations of RAM Instructions

Figure 4.1: RAM instructions in flowchart form.

They are all self-explanatory except perhaps the test statements which behave as follows. If the leftmost symbol head(y) is the letter a_i , then follow the arrow labeled a_i (to the instruction to be executed next). Otherwise $y = \epsilon$ and then follow the arrow labeled ϵ .

Remark: The instructions of a RAM program in flowchart form are very similar to the instructions of the Post machines discussed in Manna [52]. However, Post machines use a single register. Nevertheless, it can be shown that the two models are equivalent.

Definition 4.6. A *RAM flowchart program* is a directed graph obtained by interconnecting statements in such a way that:

- (1) There is a single START.
- (2) There is a single STOP.

(3) Every entry point of a statement is connected to an exit point of some statement and every exit point of a statement is connected to the entry point of some statement.

As in the case of a RAM program in linear form, a RAM program in flowchart form is assumed to have prescribed input variables. A flowchart form representation of the RAM program of Example 4.1 is shown in Figure 4.2.

Figure 4.2: A RAM program in flowchart form for computing concatenation.

Remark: The reader may have noticed that the definition of a RAM program, either in flowchart form or linear form, does not exclude undesirable programs such as disconnected programs consisting of several connected components. We could fix the definitions to avoid such pathological cases, but they are exceptional and we will not go into such trouble now. The reader is invited to think about pathological cases that should be ruled out and ways of fixing the definitions to avoid them.

Definition 4.7. A RAM program P computes the partial function $\varphi: (\Sigma^*)^n \to \Sigma^*$ if the following conditions hold: for every input $(x_1, \ldots, x_n) \in (\Sigma^*)^n$, having initialized the input registers $R1, \ldots, Rn$ with x_1, \ldots, x_n , the program eventually halts iff $\varphi(x_1, \ldots, x_n)$ is defined, and if and when P halts, the value of R1 is equal to $\varphi(x_1, \ldots, x_n)$. A partial function φ is *RAM-computable* iff it is computed by some RAM program.

Example 4.2. The following program computes the *erase function* E defined such that

$$E(u) = \epsilon$$

for all $u \in \Sigma^*$:

Example 4.3. The following program computes the *j*th successor function S_j defined such that

 $S_i(u) = ua_i$

for all $u \in \Sigma^*$:

 add_j R1continue

Example 4.4. The following program (with *n* input variables) computes the *projection* $function P_i^n$ defined such that

$$P_i^n(u_1,\ldots,u_n)=u_i$$

where $n \ge 1$, and $1 \le i \le n$:

 $R1 \leftarrow Ri$ continue

Note that P_1^1 is the identity function.

The equivalence of the flowchart form and the linear form of RAM programs is straightforward. Translating a program in linear form to the flowchart form is almost immediate and is left as an exercise. In the other direction, first we assign distinct labels to all the statements in the flowchart except START. The only translation which is not immediately obvious is the case of a test statement. If the target labels of the arrows labeled $a_1, \ldots, a_k, \epsilon$ are $N1, \ldots, Nk, N(k+1)$, we create the following piece of code

$$\begin{array}{lll} Y & \texttt{jmp}_1 & N1c \\ & \vdots & \\ Y & \texttt{jmp}_k & Nkc \\ Y & \texttt{jmp} & N(k+1)c \end{array}$$

where c is a or b depending on the location of Ni in the linear RAM program. Extra unconditional jumps may also be needed to mimic the flow of control of the program in flowchart form. The details are left as an exercise.

Having a programming language, we would like to know how powerful it is, that is, we would like to know what kind of functions are RAM-computable. At first glance, it seems that RAM programs don't do much, but this is not so. Indeed, we will see shortly that the class of RAM-computable functions is quite extensive.

One way of getting new programs from previous ones is via composition. Another one is by primitive recursion. We will investigate these constructions after introducing another model of computation, *Turing machines*.

Remarkably, the classes of (partial) functions computed by RAM programs and by Turing machines are identical. This is the class of *partial computable functions* in the sense of Herbrand–Gödel–Kleene, also called *partial recursive functions*, a term which is now considered old-fashion. We will present the definition of the so-called μ -recursive functions (due to Kleene).

The following proposition will be needed to simplify the encoding of RAM programs as numbers.

Proposition 4.1. Every RAM program can be converted to an equivalent program only using the following type of instructions.

(1_j)	N		add_j	Y
(2)	N		tail	Y
$(6_j a)$	N	Y	jmp_i	N1a
$(6_j b)$	N	Y	jmp_j	N1b
(7)	N		continue	

The proof is fairly simple. For example, instructions of the form

$$Ri \leftarrow Rj$$

can be eliminated by transferring the contents of Rj into an auxiliary register Rk, and then by transferring the contents of Rk into Ri and Rj.

4.2 Definition of a Turing Machine

We define a Turing machine model for computing functions

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{n} \to \Sigma^*,$$

where $\Sigma = \{a_1, \ldots, a_k\}$ is some input alphabet. In this section, since we are primarily interested in computing functions we only consider deterministic Turing machines.

There are many variants of the Turing machine model. The main decision that needs to be made has to do with the kind of tape used by the machine. We opt for a single *finite tape* that is both an input and a storage mechanism. This tape can be viewed as a string over *tape alphabet* Γ such that $\Sigma \subseteq \Gamma$. There is a read/write head pointing to some symbol on the tape, symbols on the tape can be overwritten, and the read/write head can move one symbol to the left or one symbol to the right, also causing a state transition. When the write/read head attempts to move past the rightmost or the leftmost symbol on the tape, the tape is allowed to grow. To accomodate such a move, the tape alphabet contains some special symbol $B \notin \Sigma$, the *blank*, and this symbol is added to the tape as the new leftmost or rightmost symbol on the tape.

A common variant uses a tape which is infinite at both ends, but only has finitely many symbols not equal to B, so effectively it is equivalent to a finite tape allowed to grow at either ends. Another variant uses a semi-infinite tape infinite to the right, but with a left end. We find this model cumbersome because it requires shifting right the entire tape when a left move is attempted from the left end of the tape.

Another decision that needs to be made is the format of the instructions. Does an instruction cause *both* a state transition *and* a symbol overwrite, or do we have separate instructions for a state transition and a symbol overwrite. In the first case, an instruction can be specified as a quintuple, and in the second case by a quadruple. We opt for quintuples. Here is our definition.

Definition 4.8. A (deterministic) *Turing machine* (or *TM*) *M* is a sextuple $M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0)$, where

- *K* is a finite set of *states*;
- Σ is a finite *input alphabet*;
- Γ is a finite *tape alphabet*, s.t. $\Sigma \subseteq \Gamma$, $K \cap \Gamma = \emptyset$, and with blank $B \notin \Sigma$;
- $q_0 \in K$ is the start state (or initial state);
- δ is the *transition function*, a (finite) set of quintuples

$$\delta \subseteq K \times \Gamma \times \Gamma \times \{L, R\} \times K,$$

such that for all $(p, a) \in K \times \Gamma$, there is at most one triple $(b, m, q) \in \Gamma \times \{L, R\} \times K$ such that $(p, a, b, m, q) \in \delta$.

A quintuple $(p, a, b, m, q) \in \delta$ is called an *instruction*. It is also denoted as

$$p, a \to b, m, q.$$

The effect of an instruction is to switch from state p to state q, overwrite the symbol currently scanned a with b, and move the read/write head either left or right, according to m.

Example 4.5. Here is an example of a Turing machine specified by

 $K = \{q_0, q_1, q_2, q_3\}; \Sigma = \{a, b\}; \Gamma = \{a, b, B\}.$

The instructions in δ are

$$\begin{array}{l} q_{0}, B \to B, R, q_{3}, \\ q_{0}, a \to b, R, q_{1}, \\ q_{0}, b \to a, R, q_{1}, \\ q_{1}, a \to b, R, q_{1}, \\ q_{1}, b \to a, R, q_{1}, \\ q_{1}, B \to B, L, q_{2}, \\ q_{2}, a \to a, L, q_{2}, \\ q_{2}, b \to b, L, q_{2}, \\ q_{2}, B \to B, R, q_{3}. \end{array}$$

-

4.3 Computations of Turing Machines

To explain how a Turing machine works, we describe its action on *instantaneous descriptions*. We take advantage of the fact that $K \cap \Gamma = \emptyset$ to define instantaneous descriptions.

Definition 4.9. Given a Turing machine

$$M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0),$$

an *instantaneous description* (for short an ID) is a (nonempty) string in $\Gamma^*K\Gamma^+$, that is, a string of the form

upav,

where $u, v \in \Gamma^*, p \in K$, and $a \in \Gamma$.

The intuition is that an ID upav describes a snapshot of a TM in the current state p, whose tape contains the string uav, and with the read/write head pointing to the symbol a. Thus, in upav, the state p is just to the left of the symbol presently scanned by the read/write head.

We explain how a TM works by showing how it acts on ID's.

Definition 4.10. Given a Turing machine

$$M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0),$$

the *yield relation (or compute relation)* \vdash is a binary relation defined on the set of ID's as follows. For any two ID's ID_1 and ID_2 , we have $ID_1 \vdash ID_2$ iff either

(1) $(p, a, b, R, q) \in \delta$, and either

(a) $ID_1 = upacv, c \in \Gamma$, and $ID_2 = ubqcv$, or

(b)
$$ID_1 = upa$$
 and $ID_2 = ubqB$;

or

(2) $(p, a, b, L, q) \in \delta$, and either

- (a) $ID_1 = ucpav, c \in \Gamma$, and $ID_2 = uqcbv$, or
- (b) $ID_1 = pav$ and $ID_2 = qBbv$.

See Figure 4.3.



Figure 4.3: Moves of a Turing machine.

Note how the tape is extended by one blank after the rightmost symbol in Case (1)(b), and by one blank before the leftmost symbol in Case (2)(b).

As usual, we let \vdash^+ denote the transitive closure of \vdash , and we let \vdash^* denote the reflexive and transitive closure of \vdash . We can now explain how a Turing machine computes a partial function

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_n \to \Sigma^*.$$

Since we allow functions taking $n \ge 1$ input strings, we assume that Γ contains the special delimiter, not in Σ , used to separate the various input strings.

It is convenient to assume that a Turing machine "cleans up" its tape when it halts before returning its output. What this means is that when the Turing machine halts, the output should be clearly identifiable, so all symbols not in $\Sigma \cup \{B\}$ that may have been used during
the computation must be erased. Thus when the TM stops the tape must consist of a string $w \in \Sigma^*$ possibly surrounded by blanks (the symbol *B*). Actually, if the output is ϵ , the tape must contain a nonempty string of blanks. To achieve this technically, we define proper ID's.

Definition 4.11. Given a Turing machine

$$M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0)$$

where Γ contains some delimiter , not in Σ in addition to the blank *B*, a *starting ID* is of the form

$$q_0 w_1, w_2, \ldots, w_n$$

where $w_1, \ldots, w_n \in \Sigma^*$ and $n \ge 2$, or $q_0 w$ with $w \in \Sigma^+$, or $q_0 B$.

A blocking (or halting) ID is an ID upav such that there are no instructions $(p, a, b, m, q) \in \delta$ for any $(b, m, q) \in \Gamma \times \{L, R\} \times K$.

A *proper ID* is a halting ID of the form

$$B^h pw B^l$$
,

where $w \in \Sigma^*$, and $h, l \ge 0$ (with $l \ge 1$ when $w = \epsilon$).

Computation sequences are defined as follows.

Definition 4.12. Given a Turing machine

$$M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0),$$

a computation sequence (or computation) is a finite or infinite sequence of ID's

$$ID_0, ID_1, \ldots, ID_i, ID_{i+1}, \ldots,$$

such that $ID_i \vdash ID_{i+1}$ for all $i \ge 0$.

A computation sequence *halts* iff it is a finite sequence of ID's, so that

$$ID_0 \vdash^* ID_n$$
,

and ID_n is a halting ID.

A computation sequence *diverges* if it is an infinite sequence of ID's.

We now explain how a Turing machine computes a partial function.

Definition 4.13. A Turing machine

$$M = (K, \Sigma, \Gamma, \{L, R\}, \delta, q_0)$$

computes the partial function

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_n \to \Sigma^*$$

iff the following conditions hold:

(1) For every $w_1, \ldots, w_n \in \Sigma^*$, given the starting ID

$$ID_0 = q_0 w_1, w_2, \dots, w_n$$

or q_0w with $w \in \Sigma^+$, or q_0B , the computation sequence of M from ID_0 halts in a proper ID iff $f(w_1, \ldots, w_n)$ is defined.

(2) If $f(w_1, \ldots, w_n)$ is defined, then M halts in a proper ID of the form

$$ID_n = B^h p f(w_1, \dots, w_n) B^l,$$

which means that it computes the right value.

A function f (over Σ^*) is *Turing computable* iff it is computed by some Turing machine M.

Note that by (1), the TM M may halt in an improper ID, in which case $f(w_1, \ldots, w_n)$ must be undefined. This corresponds to the fact that we only accept to retrieve the output of a computation if the TM has cleaned up its tape, i.e., produced a proper ID. In particular, intermediate calculations have to be erased before halting.

Example 4.6. Consider the Turing machine of Example 4.5 specified by $K = \{q_0, q_1, q_2, q_3\};$ $\Sigma = \{a, b\}; \Gamma = \{a, b, B\}.$

The instructions in δ are

$$\begin{array}{l} q_0, B \rightarrow B, R, q_3, \\ q_0, a \rightarrow b, R, q_1, \\ q_0, b \rightarrow a, R, q_1, \\ q_1, a \rightarrow b, R, q_1, \\ q_1, b \rightarrow a, R, q_1, \\ q_1, B \rightarrow B, L, q_2, \\ q_2, a \rightarrow a, L, q_2, \\ q_2, b \rightarrow b, L, q_2, \\ q_2, B \rightarrow B, R, q_3. \end{array}$$

The reader can easily verify that this machine exchanges the *a*'s and *b*'s in a string. For example, on input w = aaababb, the output is *bbbabaa*. The computation is given by the following sequence of ID's.

The last ID $Bq_3 bbbabaaB$ is a proper ID and the output is bbbabaa.

4.4 Equivalence of RAM Programs And Turing Machines

Turing machines can simulate RAM programs, and as a result, we have the following theorem.

Theorem 4.2. Every RAM-computable function is Turing-computable. Furthermore, given a RAM program P, we can effectively construct a Turing machine M computing the same function.

The idea of the proof is to represent the contents of the registers $R1, \ldots Rp$ on the Turing machine tape by the string

$$\#r1\#r2\#\cdots \#rp\#$$

where # is a special marker and ri represents the string held by Ri. We also use Proposition 4.1 to reduce the number of instructions to be dealt with.

The Turing machine M is built of blocks, each block simulating the effect of some instruction of the program P. The details are a bit tedious, and can be found in Section 5.1 or in Machtey and Young [51].

RAM programs can also simulate Turing machines.

Theorem 4.3. Every Turing-computable function is RAM-computable. Furthermore, given a Turing machine M, one can effectively construct a RAM program P computing the same function.

The idea of the proof is to design a RAM program containing an encoding of the current ID of the Turing machine M in register R1, and to use other registers R2, R3 to simulate the effect of executing an instruction of M by updating the ID of M in R1.

The details are tedious and can be found in Section 5.2.

Another proof can be obtained by proving that the class of Turing computable functions coincides with the class of *partial computable functions* (formerly called *partial recursive functions*), to be defined shortly. Indeed, it turns out that both RAM programs and Turing machines compute precisely the class of partial recursive functions. For this, we will need to define the *primitive recursive functions*.

Informally, a primitive recursive function is a *total* recursive function that can be computed using only **for** loops, that is, loops in which the number of iterations is fixed (unlike a **while** loop). A formal definition of the primitive functions is given in Section 4.7. For the time being we make the following provisional definition.

Definition 4.14. Let $\Sigma = \{a_1, \ldots, a_k\}$. The class of *partial computable functions*, also called *partial recursive functions*, is the class of partial functions (over Σ^*) that can be computed by RAM programs (or equivalently by Turing machines).

The class of *computable functions*, also called *recursive functions*, is the subset of the class of partial computable functions consisting of functions defined for every input (i.e., total functions).

Turing machines can also be used as acceptors to define languages so we introduce the basic relevant definitions. A more detailed study of these languages will be provided in Chapter 9.

4.5 Listable Languages and Computable Languages

We define the computably enumerable languages, also called listable languages, and the computable languages. The old-fashion terminology for listable languages is recursively enumerable languages, and for computable languages is recursive languages.

When operating as an acceptor, a Turing machine takes a single string as input and either goes on forever or halts with the answer "accept" or "reject." One way to deal with acceptance or rejection is to assume that the TM has a set of final states. Another way more consistent with our view that machines compute functions is to assume that the TM's under consideration have a tape alphabet containing the special symbols 0 and 1. Then acceptance is signaled by the output 1, and rejection is signaled by the output 0.

Note that with our convention that in order to produce an output a TM must halt in a proper ID, the TM must erase the tape before outputing 0 or 1.

Definition 4.15. Let $\Sigma = \{a_1, \ldots, a_k\}$. A language $L \subseteq \Sigma^*$ is *(Turing) listable* or *(Turing) computably enumerable (for short, a c.e. set)* (or *recursively enumerable (for short, a r.e. set)*) iff there is some TM M such that for every $w \in L$, M halts in a proper ID with the output 1, and for every $w \notin L$, either M halts in a proper ID with the output 0 or it runs forever.

A language $L \subseteq \Sigma^*$ is *(Turing) computable* (or *recursive*) iff there is some TM M such that for every $w \in L$, M halts in a proper ID with the output 1, and for every $w \notin L$, M halts in a proper ID with the output 0.

Thus, given a computably enumerable language L, for some $w \notin L$, it is possible that a TM accepting L runs forever on input w. On the other hand, for a computable (recursive) language L, a TM accepting L always halts in a proper ID.

When dealing with languages, it is often useful to consider *nondeterministic Turing machines*. Such machines are defined just like deterministic Turing machines, except that their transition function δ is just a (finite) set of quintuples

$$\delta \subseteq K \times \Gamma \times \Gamma \times \{L, R\} \times K,$$

with no particular extra condition.

It can be shown that every nondeterministic Turing machine can be simulated by a deterministic Turing machine, and thus, nondeterministic Turing machines also accept the class of c.e. sets. This is a very tedious simulation, and very few books actually provide all the details!

It can be shown that a computably enumerable language is the *range* of some computable (recursive) function; see Section 9.4. It can also be shown that a language L is computable (recursive) iff both L and its complement are computably enumerable; see Section 9.4. There are computably enumerable languages that are not computable (recursive); see Section 9.4.

4.6 A Simple Function Not Known to be Computable

The "3n + 1 problem" proposed by Collatz around 1937 is the following:

Given any positive integer $n \ge 1$, construct the sequence $c_i(n)$ as follows starting with i = 1:

$$c_1(n) = n$$

$$c_{i+1}(n) = \begin{cases} c_i(n)/2, & \text{if } c_i(n) \text{ is even} \\ 3c_i(n) + 1, & \text{if } c_i(n) \text{ is odd.} \end{cases}$$

Observe that for n = 1, we get the infinite periodic sequence

$$1 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1 \Longrightarrow \cdots,$$

so we may assume that we stop the first time that the sequence $c_i(n)$ reaches the value 1 (if it actually does). Such an index *i* is called the *stopping time* of the sequence. And this is the problem:

Conjecture (Collatz):

For any starting integer value $n \ge 1$, the sequence $(c_i(n))$ always reaches 1.

Starting with n = 3, we get the sequence

 $3 \Longrightarrow 10 \Longrightarrow 5 \Longrightarrow 16 \Longrightarrow 8 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1.$

Starting with n = 5, we get the sequence

 $5 \Longrightarrow 16 \Longrightarrow 8 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1.$

Starting with n = 6, we get the sequence

 $6 \Longrightarrow 3 \Longrightarrow 10 \Longrightarrow 5 \Longrightarrow 16 \Longrightarrow 8 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1.$

Starting with n = 7, we get the sequence

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$$7 \Longrightarrow 22 \Longrightarrow 11 \Longrightarrow 34 \Longrightarrow 17 \Longrightarrow 52 \Longrightarrow 26 \Longrightarrow 13 \Longrightarrow 40$$
$$\Longrightarrow 20 \Longrightarrow 10 \Longrightarrow 5 \Longrightarrow 16 \Longrightarrow 8 \Longrightarrow 4 \Longrightarrow 2 \Longrightarrow 1.$$

One might be surprised to find that for n = 27, it takes 111 steps to reach 1, and for n = 97, it takes 118 steps. We computed the stopping times for n up to 10^7 and found that the largest stopping time, 686 (685 steps) is obtained for n = 8400511. The terms of this sequence reach values over 1.5×10^{11} . The graph of the sequence c(8400511) is shown in Figure 4.4.



Figure 4.4: Graph of the sequence for n = 8400511.

We can define the partial computable function C (with positive integer inputs) defined by

C(n) = the smallest *i* such that $c_i(n) = 1$ if it exists.

Then the Collatz conjecture is equivalent to asserting that the function C is (total) computable. The graph of the function C for $1 \le n \le 10^7$ is shown in Figure 4.5.



Figure 4.5: Graph of the function C for $1 \le n \le 10^7$.

So far, the conjecture remains open. It has been checked by computer for all integers less than or equal to 87×2^{60} .

We now return to the computability of functions. Our goal is to define the partial computable functions in the sense of Herbrand–Gödel–Kleene. This class of functions is defined from some base functions in terms of three closure operations:

- 1. Composition
- 2. Primitive recursion
- 3. Minimization.

The first two operations preserve the property of a function to be total, and this subclass of total computable functions called *primitive recursive functions* plays an important technical role.

4.7 The Primitive Recursive Functions

Historically the primitive recursive functions were defined for numerical functions (computing on the natural numbers). Since one of our goals is to show that the RAM-computable functions are partial recursive, we define the primitive recursive functions as functions $f: (\Sigma^*)^m \to \Sigma^*$, where $\Sigma = \{a_1, \ldots, a_k\}$ is a finite alphabet. As usual, by assuming that $\Sigma = \{a_1\}$, we can deal with numerical functions $f: \mathbb{N}^m \to \mathbb{N}$.

The class of primitive recursive functions is defined in terms of base functions and two closure operations.

Definition 4.16. Let $\Sigma = \{a_1, \ldots, a_k\}$. The *base functions* over Σ are the following functions:

- (1) The erase function E, defined such that $E(w) = \epsilon$, for all $w \in \Sigma^*$;
- (2) For every $j, 1 \leq j \leq k$, the *j*-successor function S_j , defined such that $S_j(w) = wa_j$, for all $w \in \Sigma^*$;
- (3) The projection functions P_i^n , defined such that

$$P_i^n(w_1,\ldots,w_n)=w_i,$$

for every $n \ge 1$, every $i, 1 \le i \le n$, and for all $w_1, \ldots, w_n \in \Sigma^*$.

Note that P_1^1 is the identity function on Σ^* . Projection functions can be used to permute, duplicate, or drop the arguments of another function.

Definition 4.17. In the special case where we are only considering numerical functions $(\Sigma = \{a_1\})$, the function $E \colon \mathbb{N} \to \mathbb{N}$ is the zero function given by E(n) = 0 for all $n \in \mathbb{N}$, and it is often denoted by Z. There is a single successor function $S_{a_1} \colon \mathbb{N} \to \mathbb{N}$ usually denoted S (or **Succ**) given by S(n) = n + 1 for all $n \in \mathbb{N}$.

Even though in this section we are primarily interested in total functions, later on, the same closure operations will be applied to partial functions so we state the definition of the closure operations in the more general case of partial functions. The first closure operation is (extended) composition.

Definition 4.18. Let $\Sigma = \{a_1, \ldots, a_k\}$. For any partial or total function

$$g\colon \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_m \to \Sigma^*,$$

and any $m \ge 1$ partial or total functions

$$h_i: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_n \to \Sigma^*, \quad n \ge 1,$$

the composition of g and the h_i is the partial function

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_n \to \Sigma^*,$$

denoted as $g \circ (h_1, \ldots, h_m)$, such that

$$f(w_1,\ldots,w_n) = g(h_1(w_1,\ldots,w_n),\ldots,h_m(w_1,\ldots,w_n))$$

for all $w_1, \ldots, w_n \in \Sigma^*$. If g and all the h_i are total functions, then $g \circ (h_1, \ldots, h_m)$ is obviously a total function. But if g or any of the h_i is a partial function, then the value $(g \circ (h_1, \ldots, h_m))(w_1, \ldots, w_n)$ is defined if and only if all the values $h_i(w_1, \ldots, w_n)$ are defined for $i = 1, \ldots, m$, and $g(h_1(w_1, \ldots, w_n), \ldots, h_m(w_1, \ldots, w_n))$ is defined.

Thus even if g "ignores" some of its inputs, in computing $g(h_1(w_1,\ldots,w_n),\ldots,h_m(w_1,\ldots,w_n))$, all arguments $h_i(w_1,\ldots,w_n)$ must be evaluated.

As an example of a composition, $f = g \circ (P_2^2, P_1^2)$ is such that

$$f(w_1, w_2) = g(P_2^2(w_1, w_2), P_1^2(w_1, w_2)) = g(w_2, w_1).$$

The second closure operation is *primitive recursion*. First we define primitive recursion for numerical functions because it is simpler.

Definition 4.19. Given any two partial or total functions $g: \mathbb{N}^{m-1} \to \mathbb{N}$ and $h: \mathbb{N}^{m+1} \to \mathbb{N}$ $(m \geq 2)$, the partial or total function $f: \mathbb{N}^m \to \mathbb{N}$ is defined by *primitive recursion from g* and h if f is given by

$$f(0, x_2, \dots, x_m) = g(x_2, \dots, x_m)$$

$$f(n+1, x_2, \dots, x_m) = h(n, f(n, x_2, \dots, x_m), x_2, \dots, x_m),$$

for all $n, x_2, \ldots, x_m \in \mathbb{N}$. When m = 1, we have

$$f(0) = b$$

$$f(n+1) = h(n, f(n)), \text{ for all } n \in \mathbb{N},$$

for some fixed natural number $b \in \mathbb{N}$.

If g and h are total functions, it is easy to show that f is also a total function. If g or h is partial, obviously $f(0, x_2, \ldots, x_m)$ is defined iff $g(x_2, \ldots, x_m)$ is defined, and $f(n + 1, x_2, \ldots, x_m)$ is defined iff $f(n, x_2, \ldots, x_m)$ is defined and $h(n, f(n, x_2, \ldots, x_m), x_2, \ldots, x_m)$ is defined.

Definition 4.19 is quite a straightjacket in the sense that n+1 must be the first argument of f, and the definition only applies if h has m+1 arguments, but in practice a "natural" definition often ignores the argument n and some of the arguments x_2, \ldots, x_m . This is where the projection functions come into play to drop, duplicate, or permute arguments. Example 4.7. For example, a "natural" definition of the predecessor function pred is

$$pred(0) = 0$$
$$pred(m+1) = m,$$

but this is not a legal primitive recursive definition. To make it a legal primitive recursive definition we need the function $h = P_1^2$, and a legal primitive recursive definition for *pred* is

$$pred(0) = 0$$

$$pred(m+1) = P_1^2(m, pred(m)).$$

Example 4.8. Addition, multiplication, exponentiation, and super-exponentiation, can be defined by primitive recursion as follows (being a bit loose, for supexp we should use some projections ...):

$$\begin{aligned} add(0,n) &= P_1^1(n) = n \\ add(m+1,n) &= S \circ P_2^3(m, add(m,n), n) \\ &= S(add(m,n)) \\ mult(0,n) &= E(n) = 0 \\ mult(m+1,n) &= add \circ (P_2^3, P_3^3)(m, mult(m,n), n) \\ &= add(mult(m,n), n) \\ rexp(0,n) &= S \circ E(n) = 1 \\ rexp(m+1,n) &= mult \circ (P_2^3, P_3^3)(m, rexp(m,n), n) \\ exp(m,n) &= rexp \circ (P_2^2, P_1^2)(m,n) \\ supexp(0,n) &= 1 \\ supexp(m+1,n) &= exp(n, supexp(m,n)). \end{aligned}$$

We usually write m + n for add(m, n), m * n or even mn for mult(m, n), and m^n for exp(m, n).

Example 4.9. The recursive definition of m^n is $m^{(n+1)} = m^n * m$, which corresponds to

$$exp(m, n+1) = mult(exp(m, n), m).$$

Unfortunately, the recursion is on the second argument n, so we have to create the auxiliary function rexp given by

$$rexp(m,n) = n^m$$

write the primitive recusive definition of rexp in m, and then

$$exp(m, n) = rexp(n, m) = rexp \circ (P_2^2, P_1^2)(m, n).$$

Example 4.10. There is a minus operation on \mathbb{N} named *monus*. This operation denoted by $\dot{-}$ is defined by

$$m \div n = \begin{cases} m - n, & \text{if } m \ge n \\ 0, & \text{if } m < n. \end{cases}$$

Then *monus* is defined by

$$\begin{aligned} m \dot{-} 0 &= m \\ m \dot{-} (n+1) &= pred(m \dot{-} n), \end{aligned}$$

except that the above is not a legal primitive recursion. For one thing, recursion should be performed on m, not n. We can define rmonus as

$$rmonus(n,m) = m - n$$

and then $m \doteq n = (rmonus \circ (P_2^2, P_1^2))(m, n)$, and

$$rmonus(0 \div m) = P_1^1(m)$$

$$rmonus(n+1,m) = pred \circ P_2^2(n, rmonus(n,m))$$

Example 4.11. The following functions are also primitive recursive:

$$sg(n) = \begin{cases} 1, & \text{if } n > 0\\ 0, & \text{if } n = 0, \end{cases}$$
$$\overline{sg}(n) = \begin{cases} 0, & \text{if } n > 0\\ 1, & \text{if } n = 0, \end{cases}$$

as well as

$$abs(m,n) = |m-n| = m \div n + n \div m,$$

and

$$eq(m,n) = \begin{cases} 1, & \text{if } m = n \\ 0, & \text{if } m \neq n. \end{cases}$$

Indeed

$$\begin{split} sg(0) &= 0\\ sg(n+1) &= S \circ E \circ P_1^2(n, sg(n))\\ \overline{sg}(n) &= S(E(n)) \div sg(n) = 1 \div sg(n), \end{split}$$

and

$$eq(m,n) = \overline{sg}(|m-n|).$$

Example 4.12. Finally, the function

$$cond(m, n, p, q) = \begin{cases} p, & \text{if } m = n \\ q, & \text{if } m \neq n, \end{cases}$$

is primitive recursive, since

$$cond(m, n, p, q) = eq(m, n) * p + \overline{sg}(eq(m, n)) * q.$$

Example 4.13. We can also design more general version of *cond*. For example, define $compare_{\leq}$ as

$$compare_{\leq}(m,n) = \begin{cases} 1, & \text{if } m \leq n \\ 0, & \text{if } m > n, \end{cases}$$

which is given by

$$compare_{\leq}(m,n) = 1 \div sg(m \div n)$$

Then we can define

$$cond_{\leq}(m,n,p,q) = \begin{cases} p, & \text{if } m \leq n \\ q, & \text{if } m > n, \end{cases}$$

with

$$cond_{\leq}(m, n, n, p) = compare_{\leq}(m, n) * p + \overline{sg}(compare_{\leq}(m, n)) * q.$$

The above allows to define functions by cases.

We now generalize primitive recursion to functions defined on strings (in Σ^*). The new twist is that instead of the argument n + 1 of f, we need to consider the k arguments ua_i of f for $i = 1, \ldots, k$ (with $u \in \Sigma^*$), so instead of a single function h, we need k functions h_i to define primitive recursively what $f(ua_i, w_2, \ldots, w_m)$ is.

Definition 4.20. Let $\Sigma = \{a_1, \ldots, a_k\}$. For any partial or total function

$$g\colon \underbrace{\Sigma^*\times\cdots\times\Sigma^*}_{m-1}\to\Sigma^*,$$

where $m \ge 2$, and any k partial or total functions

$$h_i: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{m+1} \to \Sigma^*,$$

the partial function

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{m} \to \Sigma^*$$

is defined by *primitive recursion from* g and h_1, \ldots, h_k , if

$$f(\boldsymbol{\epsilon}, w_2, \dots, w_m) = g(w_2, \dots, w_m)$$

$$f(\boldsymbol{ua_1}, w_2, \dots, w_m) = h_1(\boldsymbol{u}, f(\boldsymbol{u}, w_2, \dots, w_m), w_2, \dots, w_m)$$

$$\dots = \dots$$

$$f(\boldsymbol{ua_k}, w_2, \dots, w_m) = h_k(\boldsymbol{u}, f(\boldsymbol{u}, w_2, \dots, w_m), w_2, \dots, w_m),$$

for all $u, w_2, \ldots, w_m \in \Sigma^*$.

When m = 1, for some fixed $w \in \Sigma^*$, we have

$$f(\epsilon) = w$$

$$f(ua_1) = h_1(u, f(u))$$

$$\cdots = \cdots$$

$$f(ua_k) = h_k(u, f(u)),$$

for all $u \in \Sigma^*$.

Again, if g and the h_i are total, it is easy to see that f is total.

Example 4.14. As an example over $\{a, b\}^*$, the following function $g: \Sigma^* \times \Sigma^* \to \Sigma^*$, is defined by primitive recursion:

$$g(\epsilon, v) = P_1^1(v)$$

$$g(ua_i, v) = S_i \circ P_2^3(u, g(u, v), v),$$

where $1 \leq i \leq k$. It is easily verified that g(u, v) = vu. Then,

$$con = g \circ (P_2^2, P_1^2)$$

computes the concatenation function, *i.e.*, con(u, v) = uv. The extended concatenation con_{n+1} $(n \ge 1)$ defined by

$$con_{n+1}(x_1, \ldots, x_{n+1}) = x_1 \cdots x_{n+1}$$

is primitive recursive because $con_2 = con$ and

$$con_{n+1}(x_1,\ldots,x_{n+1}) = con(con_n(P_1^{n+1}(x_1,\ldots,x_{n+1}),\ldots,P_n^{n+1}(x_1,\ldots,x_{n+1})),$$
$$P_{n+1}^{n+1}(x_1,\ldots,x_{n+1})).$$

Here are some primitive recursive functions that often appear as building blocks for other primitive recursive functions. Example 4.15. The *delete last* function *dell* given by

$$dell(\epsilon) = \epsilon$$

$$dell(ua_i) = u, \quad 1 \le i \le k, \ u \in \Sigma^*$$

is defined primitive recursively by

$$dell(\epsilon) = \epsilon$$

$$dell(ua_i) = P_1^2(u, dell(u)), \quad 1 \le i \le k, \ u \in \Sigma^*$$

Example 4.16. For every string $w \in \Sigma^*$, the constant function c_w given by

$$c_w(u) = w$$
, for all $u \in \Sigma^*$

is defined primitive recursively by induction on the length of w by

$$c_{\epsilon} = E$$

$$c_{va_i} = S_i \circ c_v, \quad 1 \le i \le k.$$

Example 4.17. The sign function sg given by

$$sg(x) = \begin{cases} \epsilon, & \text{if } x = \epsilon \\ a_1, & \text{if } x \neq \epsilon \end{cases}$$

is defined primitive recursively by

$$sg(\epsilon) = \epsilon$$

$$sg(ua_i) = (c_{a_1} \circ P_1^2)(u, sg(u)).$$

Example 4.18. The anti-sign function \overline{sg} given by

$$\overline{sg}(x) = \begin{cases} a_1, & \text{if } x = \epsilon \\ \epsilon, & \text{if } x \neq \epsilon \end{cases}$$

is primitive recursive. The proof is left an an exercise.

Example 4.19. The function end_j $(1 \le j \le k)$ given by

$$end_j(x) = \begin{cases} a_1, & \text{if } x \text{ ends with } a_j \\ \epsilon, & \text{otherwise} \end{cases}$$

is primitive recursive. The proof is left an an exercise.

Example 4.20. The reverse function $rev: \Sigma^* \to \Sigma^*$ given by $rev(u) = u^R$ is primitive recursive because

$$rev(\epsilon) = \epsilon$$

$$rev(ua_i) = (con \circ (c_{a_i} \circ P_1^2, P_2^2))(u, rev(u)), \quad 1 \le i \le k.$$

Example 4.21. The *tail function tail* given by

$$tail(\epsilon) = \epsilon$$
$$tail(a_i u) = u$$

is primitive recursive because

 $tail = rev \circ dell \circ rev.$

Example 4.22. The *last function last* given by

$$last(\epsilon) = \epsilon$$
$$last(ua_i) = a_i$$

is primitive recursive because

$$last(\epsilon) = \epsilon$$

$$last(ua_i) = c_{a_i} \circ P_1^2(u, last(u)).$$

Example 4.23. The *head function head* given by

$$head(\epsilon) = \epsilon$$
$$head(a_i u) = a_i$$

is primitive recursive because

$$head = last \circ rev.$$

We are now ready to define the class of primitive recursive functions.

Definition 4.21. Let $\Sigma = \{a_1, \ldots, a_k\}$. The class of *primitive recursive functions* is the smallest class of (total) functions (over Σ^*) which contains the base functions and is closed under composition and primitive recursion.

In the special where k = 1, we obtain the class of numerical primitive recursive functions. **Example 4.24.** The function f given by $f(x_1, x_2) = x_1^{|x_2|}$ is defined by primitive recursion as follows. First we introduce g given by $g(x_1, x_2) = x_2^{|x_1|}$, with

$$g(\epsilon, x_2) = \epsilon$$

$$g(x_1a_i, x_2) = con(g(x_1, x_2), x_2).$$

Then $f(x_1, x_2) = g(x_2, x_1)$. A RAM program in flowchart form computing f is shown in Figure 4.6. Observe how this program makes use of the program for computing concatenation.



Figure 4.6: Computing $f(x_1, x_2) = x_1^{|x_2|}$ by primitive recursion.

4.8 Primitive Recursive Functions are RAM Computable

The class of primitive recursive functions may not seem very big, but it contains all the total functions that we would ever want to compute. Although it is rather tedious to prove, the following theorem can be shown.

Theorem 4.4. For any alphabet $\Sigma = \{a_1, \ldots, a_k\}$, every primitive recursive function is RAM computable, and thus Turing computable.

Proof. We showed just after Definition 4.7 that the base functions are RAM-computable.

Let us first show closure of the class of RAM programs under composition. Let R, P_1, \ldots ,

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 P_m be RAM programs computing g, h_1, \ldots, h_m , and assume that h_1, \ldots, h_m are functions of n variables. The idea is to use P_1, \ldots, P_m as subroutines to R. Let q be least integer greater than m and n and such that no register of index past q is used in R, P_1, \ldots, P_m . The program computing $g \circ (h_1, \ldots, h_m)$ is designed as follows. First, we save the contents of the input registers.

$$\begin{array}{rcrcr} R(q+1) &\leftarrow R1\\ &\vdots\\ R(q+n) &\leftarrow Rn \end{array}$$

Next we initialize the noninput registers and compute $h_1(x_1, \ldots, x_n)$ by "calling" P1 as a subroutine. The output is stored in R(q + n + 1).

$$\begin{array}{ccc} \texttt{clr} & R(n+1) \\ \vdots \\ \texttt{clr} & Rq \\ P_1 \\ R(q+n+1) & \leftarrow & R1 \end{array}$$

We have similar pieces of RAM code to execute P_2, \ldots, P_m , the *m*th piece of code being

At this stage, the values $h_1(x_1, \ldots, x_n), \ldots, h_m(x_1, \ldots, x_n)$ have been computed and are stored in the registers $R(q+n+1), \ldots, R(q+n+m)$, or one of the P_i diverged. We finally call the subroutine R to compute $g(h_1(x_1, \ldots, x_n), \ldots, h_m(x_1, \ldots, x_n))$.

$$\begin{array}{rcl} R1 & \leftarrow & R(q+n+1) \\ & \vdots & \\ Rn & \leftarrow & R(q+n+m) \\ & \texttt{clr} & R(m+1) \\ & \vdots & \\ & \texttt{clr} & Rq \\ & R \end{array}$$

The output is in register R1 (or the program diverged). Now the reader should understand why we are using relative addresses in the jumps-this allows us to simply plug in the programs acting as subroutines in the right places. The other instructions simply make sure that these programs are correctly initialized.

Next we show closure of the class of RAM programs under primitive recursion.

Suppose g, h_1, \ldots, h_k are some total functions computable by some RAM programs, with $g: (\Sigma^*)^{m-1} \to \Sigma^*$, and $h_i: (\Sigma^*)^{m+1} \to \Sigma^*$, for $i = 1, \ldots, k$. If we write \overline{x} for (x_2, \ldots, x_m) , for any $y \in \Sigma^*$, where $y = a_{i_1} \cdots a_{i_n}$ (with $a_{i_j} \in \Sigma$), let f be defined by primitive recursion from g and the h_i 's, that is,

$$f(\epsilon, \overline{x}) = g(\overline{x})$$

$$f(ya_1, \overline{x}) = h_1(y, f(y, \overline{x}), \overline{x})$$

$$\vdots$$

$$f(ya_i, \overline{x}) = h_i(y, f(y, \overline{x}), \overline{x})$$

$$\vdots$$

$$f(ya_k, \overline{x}) = h_k(y, f(y, \overline{x}), \overline{x}),$$

for all $y \in \Sigma^*$ and all $\overline{x} \in (\Sigma^*)^{m-1}$. Define the following sequences, u_j and v_j , for $j = 0, \ldots, n+1$:

$$u_0 = \epsilon$$

$$u_1 = u_0 a_{i_1}$$

$$\vdots$$

$$u_j = u_{j-1} a_{i_j}$$

$$\vdots$$

$$u_n = u_{n-1} a_{i_n}$$

$$u_{n+1} = u_n a_i,$$

and

$$v_0 = g(\overline{x})$$

$$v_1 = h_{i_1}(u_0, v_0, \overline{x})$$

$$\vdots$$

$$v_j = h_{i_j}(u_{j-1}, v_{j-1}, \overline{x})$$

$$\vdots$$

$$v_n = h_{i_n}(u_{n-1}, v_{n-1}, \overline{x})$$

$$v_{n+1} = h_i(y, v_n, \overline{x}).$$

We leave it as an exercise to prove by induction that

$$v_j = f(u_j, \overline{x})$$

for $j = 0, \ldots, n + 1$. It follows that

$$f(u_n a_i, \overline{x}) = h_i(u_n, f(u_n, \overline{x}), \overline{x}),$$

so $f(u_n a_i, \overline{x})$ is defined and the function f is total. The RAM program in flowchart form shown in Figure 4.7 implements the computation of the v_j .



Figure 4.7: Closure under primitive recursion.

A statement such as

$$v \leftarrow g(x_1, \ldots, x_{m-1})$$

is an abbreviation for a RAM program R computing g, in which it is assumed that the variables used by R, except the variables x_1, \ldots, x_{m-1} , are not used elsewhere in the program implementing primitive recursion. The same convention applies to the statement

$$v \leftarrow h_i(x_1, \dots, x_{m+1}).$$

In order to define new functions it is also useful to use predicates.

4.9 Primitive Recursive Predicates

Primitive recursive predicates will be used in Section 8.3.

Definition 4.22. An *n*-ary predicate P over \mathbb{N} is any subset of \mathbb{N}^n . We write that a tuple (x_1, \ldots, x_n) satisfies P as $(x_1, \ldots, x_n) \in P$ or as $P(x_1, \ldots, x_n)$. The characteristic function of a predicate P is the function $C_P \colon \mathbb{N}^n \to \{0, 1\}$ defined by

$$C_p(x_1,\ldots,x_n) = \begin{cases} 1, & \text{iff } P(x_1,\ldots,x_n) \text{ holds} \\ 0, & \text{iff not } P(x_1,\ldots,x_n). \end{cases}$$

A predicate P (over \mathbb{N}) is *primitive recursive* iff its characteristic function C_P is primitive recursive.

More generally, an *n*-ary predicate P (over Σ^*) is any subset of $(\Sigma^*)^n$. We write that a tuple (x_1, \ldots, x_n) satisfies P as $(x_1, \ldots, x_n) \in P$ or as $P(x_1, \ldots, x_n)$.

Definition 4.23. The *characteristic function* of a predicate P is the function $C_P \colon (\Sigma^*)^n \to \{a_1\}^*$ defined by

$$C_p(x_1,\ldots,x_n) = \begin{cases} a_1, & \text{iff } P(x_1,\ldots,x_n) \text{ holds} \\ \epsilon, & \text{iff not } P(x_1,\ldots,x_n). \end{cases}$$

A predicate P (over Σ^*) is *primitive recursive* iff its characteristic function C_P is primitive recursive.

Since we will only need to use primitive recursive predicates over \mathbb{N} in the following chapters, for simplicity of exposition we will restrict ourselves to such predicates. The general case in treated in Machtey and Young [51].

It is easily shown that if P and Q are primitive recursive predicates (over \mathbb{N}^n), then $P \lor Q$, $P \land Q$ and $\neg P$ are also primitive recursive.

As an exercise, the reader may want to prove that the predicate,

prime(n) iff n is a prime number,

is a primitive recursive predicate.

For any fixed $k \ge 1$, the function

 $\operatorname{ord}(k, n) =$ exponent of the kth prime in the prime factorization of n,

is a primitive recursive function.

We can also define functions by cases.

Proposition 4.5. If P_1, \ldots, P_m are pairwise disjoint primitive recursive n-ary predicates (which means that $P_i \cap P_j = \emptyset$ for all $i \neq j$) and f_1, \ldots, f_{m+1} are primitive recursive functions on \mathbb{N}^n , the function $g: \mathbb{N}^n \to \mathbb{N}$ defined below is also primitive recursive:

$$g(\overline{x}) = \begin{cases} f_1(\overline{x}), & \text{iff } P_1(\overline{x}) \\ \vdots \\ f_m(\overline{x}), & \text{iff } P_m(\overline{x}) \\ f_{m+1}(\overline{x}), & \text{otherwise.} \end{cases}$$

Here we write \overline{x} for (x_1, \ldots, x_n) .

Proposition 4.5 also applies to functions and predicates with string arguments.

It is also useful to have bounded quantification and bounded minimization. Recall that we are restricting our attention to numerical predicates and functions, so all variables range over \mathbb{N} . Proofs of the results stated below can be found in Machtey and Young [51].

Definition 4.24. If P is an (n + 1)-ary predicate, then the bounded existential predicate $(\exists y \leq x) P(y, \overline{z})$ holds iff some $y \leq x$ makes $P(y, \overline{z})$ true.

The bounded universal predicate $(\forall y \leq x)P(y,\overline{z})$ holds iff every $y \leq x$ makes $P(y,\overline{z})$ true.

Both $(\exists y \leq x) P(y, \overline{z})$ and $(\forall y \leq x) P(y, \overline{z})$ are (n + 1)-ary predicates; that is, the input arguments are x and \overline{z} .

Proposition 4.6. If P is an (n+1)-ary primitive recursive predicate, then $(\exists y \leq x)P(y,\overline{z})$ and $(\forall y \leq x)P(y,\overline{z})$ are also primitive recursive predicates.

As an application, we can show that the equality predicate u = v is primitive recursive. The following slight generalization of Proposition 4.6 will be needed in Section 8.3.

Proposition 4.7. If P is an (n + 1)-ary primitive recursive predicate and $f : \mathbb{N}^n \to \mathbb{N}$ is a primitive recursive function, then $(\exists y \leq f(\overline{z}))P(y,\overline{z})$ and $(\forall y \leq f(\overline{z}))P(y,\overline{z})$ are also primitive recursive predicates.

Definition 4.25. If P is an (n + 1)-ary predicate, then the bounded minimization of P, min $(y \le x) P(y, \overline{z})$, is the function defined such that min $(y \le x) P(y, \overline{z})$ is the least natural number $y \le x$ such that $P(y, \overline{z})$ if such a y exists, x + 1 otherwise.

The bounded maximization of P, $\max(y \leq x) P(y, \overline{z})$, is the function defined such that $\max(y \leq x) P(y, \overline{z})$ is the largest natural number $y \leq x$ such that $P(y, \overline{z})$ if such a y exists, x + 1 otherwise.

Both $\min(y \leq x) P(y, \overline{z})$ and $\max(y \leq x) P(y, \overline{z})$ are functions from \mathbb{N}^{n+1} to \mathbb{N} ; that is, the input arguments are x and \overline{z} .

Proposition 4.8. If P is an (n+1)-ary primitive recursive predicate, then $\min(y \le x) P(y, \overline{z})$ and $\max(y \le x) P(y, \overline{z})$ are primitive recursive functions. Bounded existential predicates and bounded universal predicates can also be defined for predicates with string arguments.

Definition 4.26. The bounded existential predicate $(\exists y/x)P(y,\overline{z})$ holds iff some prefix y of x makes $P(y,\overline{z})$ true. The bounded universal predicate $(\forall y/x)P(y,\overline{z})$ holds iff every prefix y of x makes $P(y,\overline{z})$ true. In both cases the input arguments are x and \overline{z} .

Again, if P is primitive recursive, then so are $(\exists y/x)P(y,\overline{z})$ and $(\forall y/x)P(y,\overline{z})$.

Bounded universal quantification can be used to prove that the equality predicate eq(x, y) for strings is primitive recursive. This is surprisingly tricky. One needs a version of monus on strings, namely

$$x - y = \begin{cases} \epsilon, & \text{if } |x| \le |y| \\ v, & \text{if } |x| > |y| \text{ and } x = uv \text{ with } |u| = |y|. \end{cases}$$

We leave it as an exercise to show that that the above function is primitive recursive.

One also needs the predicate end(x) = end(y) which holds iff $x = y = \epsilon$ or x and y end with the same letter. It is easy to show that this predicate is primitive recursive. Then the predicate |x| = |y| is primitive recursive since it holds iff $x - y = \epsilon$ and $y - x = \epsilon$.

Finally, the reader should verify that we have eq(x, y) iff |x| = |y| and

$$\forall z/x [end(z) = end(rev(rev(y) - (x - z))].$$

We can also define bounded minimization and maximization for predicates with string arguments.

Definition 4.27. The bounded minimization $\min(y/x) P(y,\overline{z})$ of P is the function defined such that $\min(y/x) P(y,\overline{z})$ is the shortest prefix y of x such that $P(y,\overline{z})$ if such a y exists, xa_1 otherwise.

The bounded maximization $\max(y/x) P(y,\overline{z})$ of P is the function defined such that $\max(y/x) P(y,\overline{z})$ is the longest prefix y of x such that $P(y,\overline{z})$ if such a y exists, xa_1 otherwise.

In both cases the input arguments are x and \overline{z} . If P is primitive recursive, then so are $\min(y/x) P(y,\overline{z})$ and $\max(y/x) P(y,\overline{z})$.

So far the primitive recursive functions do not yield all the Turing-computable functions. The following proposition also shows that restricting ourselves to total functions is too limiting.

Let \mathcal{F} be any set of total functions $(f \colon (\Sigma^*)^n \to \Sigma^*)$ that contains the base functions and is closed under composition and primitive recursion (and thus, \mathcal{F} contains all the primitive recursive functions). **Definition 4.28.** We say that a function $f: \Sigma^* \times \Sigma^* \to \Sigma^*$ is *universal* for the one-argument functions in \mathcal{F} iff for every function $g: \Sigma^* \to \Sigma^*$ in \mathcal{F} , there is some $n \in \mathbb{N}$ such that

$$f(a_1^n, u) = g(u)$$

for all $u \in \Sigma^*$.

Proposition 4.9. For any countable set \mathcal{F} of total functions containing the base functions and closed under composition and primitive recursion, if f is a universal function for the functions $g: \Sigma^* \to \Sigma^*$ in \mathcal{F} , then $f \notin \mathcal{F}$.

Proof. Assume that the universal function f is in \mathcal{F} . Let g be the function such that

$$g(u) = f(a_1^{|u|}, u)a_1$$

for all $u \in \Sigma^*$. We claim that $g \in \mathcal{F}$. It is enough to prove that the function h such that

$$h(u) = a_1^{|u|}$$

is primitive recursive, which is easily shown.

Then, because f is universal, there is some m such that

$$g(u) = f(a_1^m, u)$$

for all $u \in \Sigma^*$. Letting $u = a_1^m$, we get

$$g(a_1^m) = f(a_1^m, a_1^m) = f(a_1^m, a_1^m)a_1$$

a contradiction.

Thus, either a universal function for \mathcal{F} is partial, or it is not in \mathcal{F} .

In order to get a larger class of functions, we need the closure operation known as minimization.

4.10 The Partial Computable Functions

Minimization can be viewed as an abstract version of a while loop. First let us consider the simpler case of numerical functions.

Consider a function $g: \mathbb{N}^{m+1} \to \mathbb{N}$, with $m \ge 0$. We would like to know if for any fixed $n_1, \ldots, n_m \in \mathbb{N}$, the equation

$$g(n, n_1, \ldots, n_m) = 0$$
 with respect to $n \in \mathbb{N}$

has a solution $n \in \mathbb{N}$, and if so, we return the smallest such solution. Thus we are defining a (partial) function $f: \mathbb{N}^m \to \mathbb{N}$ such that

$$f(n_1, \ldots, n_m) = \min\{n \in \mathbb{N} \mid g(n, n_1, \ldots, n_m) = 0\},\$$

with the understanding that $f(n_1, \ldots, n_m)$ is undefined otherwise. If g is computed by a RAM program, computing $f(n_1, \ldots, n_m)$ corresponds to the while loop

n := 0;while $g(n, n_1, ..., n_m) \neq 0$ do n := n + 1;endwhile let $f(n_1, ..., n_m) = n.$

Definition 4.29. For any function $g: \mathbb{N}^{m+1} \to \mathbb{N}$, where $m \ge 0$, the function $f: \mathbb{N}^m \to \mathbb{N}$ is defined by *minimization from* g, if the following conditions hold for all $n_1, \ldots, n_m \in \mathbb{N}$:

(1) $f(n_1, \ldots, n_m)$ is defined iff there is some $n \in \mathbb{N}$ such that $g(p, n_1, \ldots, n_m)$ is defined for all $p, 0 \le p \le n$, and

$$g(n, n_1, \ldots, n_m) = 0.$$

(2) When $f(n_1, \ldots, n_m)$ is defined,

$$f(n_1,\ldots,n_m)=n,$$

where n is such that $g(n, n_1, \ldots, n_m) = 0$ and $g(p, n_1, \ldots, n_m) \neq 0$ for every $p, 0 \leq p \leq n-1$. In other words, n is the smallest natural number such that $g(n, n_1, \ldots, n_m) = 0$.

Following Kleene, we write

$$f(n_1,\ldots,n_m)=\mu n[g(n,n_1,\ldots,n_m)=0].$$

Remark: When $f(n_1, \ldots, n_m)$ is defined, $f(n_1, \ldots, n_m) = n$, where *n* is the smallest natural number such that Condition (1) holds. It is very important to require that *all* the values $g(p, n_1, \ldots, n_m)$ be defined for all $p, 0 \le p \le n$, when defining $f(n_1, \ldots, n_m)$. Failure to do so allows non-computable functions.

Minimization can be generalized to functions defined on strings as follows. Given a function $g: (\Sigma^*)^{m+1} \to \Sigma^*$, for any fixed $w_1, \ldots, w_m \in \Sigma^*$, we wish to solve the equation

$$g(u, w_1, \ldots, w_m) = \epsilon$$
 with respect to $u \in \Sigma^*$,

and return the "smallest" solution u, if any. The only issue is what does smallest solution mean. We resolve this issue by restricting u to be a string of a_j 's, for some fixed letter $a_j \in \Sigma$. Thus there are k variants of minimization corresponding to searching for a shortest string in $\{a_j\}^*$, for a fixed $j, 1 \leq j \leq k$. Let $\Sigma = \{a_1, \ldots, a_k\}$. For any function

$$g\colon \underbrace{\Sigma^*\times\cdots\times\Sigma^*}_{m+1}\to\Sigma^*,$$

where $m \ge 0$, for every $j, 1 \le j \le k$, the function

$$f: \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{m} \to \Sigma^*$$

looks for the shortest string u over $\{a_j\}^*$ (for a fixed j) such that

 $g(u, w_1, \ldots, w_m) = \epsilon.$

This corresponds to the following while loop:

 $u := \epsilon;$ while $g(u, w_1, \dots, w_m) \neq \epsilon$ do $u := ua_j;$ endwhile let $f(w_1, \dots, w_m) = u$

The operation of minimization (sometimes called minimalization) is defined as follows.

Definition 4.30. Let $\Sigma = \{a_1, \ldots, a_k\}$. For any function

$$g\colon \underbrace{\Sigma^* \times \cdots \times \Sigma^*}_{m+1} \to \Sigma^*$$

where $m \ge 0$, for every $j, 1 \le j \le k$, the function

$$f\colon \underbrace{\Sigma^*\times\cdots\times\Sigma^*}_m\to\Sigma^*,$$

is defined by minimization over $\{a_j\}^*$ from g, if the following conditions hold for all $w_1, \ldots, w_m \in \Sigma^*$:

(1) $f(w_1, \ldots, w_m)$ is defined iff there is some $n \ge 0$ such that $g(a_j^p, w_1, \ldots, w_m)$ is defined for all $p, 0 \le p \le n$, and

$$g(a_i^n, w_1, \dots, w_m) = \epsilon.$$

(2) When $f(w_1, \ldots, w_m)$ is defined,

$$f(w_1,\ldots,w_m)=a_i^n,$$

where n is such that

$$g(a_j^n, w_1, \dots, w_m) = \epsilon$$

and

$$g(a_j^p, w_1, \dots, w_m) \neq \epsilon$$

for every $p, 0 \le p \le n - 1$.

We write

$$f(w_1,\ldots,w_m) = \min_j u[g(u,w_1,\ldots,w_m) = \epsilon].$$

Remark: When $f(w_1, \ldots, w_m)$ is defined,

$$f(w_1,\ldots,w_m)=a_i^n$$

where n is the smallest natural number such that Condition (1) holds. It is very important to require that all the values $g(a_j^p, w_1, \ldots, w_m)$ be defined for all $p, 0 \le p \le n$, when defining $f(w_1, \ldots, w_m)$. Failure to do so allows non-computable functions.

Remark: Inspired by Kleene's notation in the case of numerical functions, we may use the μ -notation:

$$f(w_1,\ldots,w_m) = \mu_j u[g(u,w_1,\ldots,w_m) = \epsilon].$$

The class of partial computable functions is defined as follows.

Definition 4.31. Let $\Sigma = \{a_1, \ldots, a_k\}$. The class of *partial computable functions* (in the sense of Herbrand–Gödel–Kleene), also called *partial recursive functions* is the smallest class of partial functions (over Σ^*) which contains the base functions and is closed under composition, primitive recursion, and minimization.

The class of *computable functions* also called *recursive functions* is the subset of the class of partial computable functions consisting of functions defined for every input (i.e., total functions).

One of the major results of computability theory is the following theorem.

Theorem 4.10. For an alphabet $\Sigma = \{a_1, \ldots, a_k\}$, every partial computable function (partial recursive function) is RAM-computable, and thus Turing-computable. Conversely, every RAM-computable function (or Turing-computable function) is a partial computable function (partial recursive function). Similarly, the class of computable functions (recursive functions) is equal to the class of Turing-computable functions that halt in a proper ID for every input, and to the class of RAM programs that halt for all inputs.

Sketch of proof. First we prove that every partial computable function is RAM-computable. Since we already know from Theorem 4.4 that the RAM programs contain the base functions and are closed under composition and primitive recursion, it suffices to show that minimization can be implemented by a RAM program. The RAM program in flowchart form shown in Figure 4.8 implements minimization.

By Theorem 4.2, every RAM program can be converted to a Turing machine, so every partial computable function is Turing-computable.

For the converse, one can show that given a Turing machine, there is a primitive recursive function describing how to go from one ID to the next. Then minimization is used to guess whether a computation halts. The proof shows that every partial computable function needs minimization *at most once*. The characterization of the computable functions in terms of TM's follows easily. Details are given in Section 5.3. See also Machtey and Young [51] and Kleene I.M. [42] (Chapter XIII).



Figure 4.8: Closure under minimization.

We will prove directly in Section 8.3 that every RAM-computable function (over \mathbb{N}) is partial computable. This will be done by encoding RAM programs as natural numbers.

There are computable functions (recursive functions) that are not primitive recursive. Such an example is given by Ackermann's function.

Example 4.25. Ackermann's function is the function $A: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$ which is defined by the following recursive clauses:

$$A(0, y) = y + 1$$

$$A(x + 1, 0) = A(x, 1)$$

$$A(x + 1, y + 1) = A(x, A(x + 1, y)).$$

It turns out that A is a computable function which is **not** primitive recursive. This is

not easy to prove. It can be shown that

$$A(0, x) = x + 1$$

$$A(1, x) = x + 2$$

$$A(2, x) = 2x + 3$$

$$A(3, x) = 2^{x+3} - 3,$$

and

$$A(4,x) = 2^{2^{x^{2^{16}}}} \Big\}^x - 3,$$

with A(4,0) = 16 - 3 = 13.

For example

$$A(4,1) = 2^{16} - 3, \quad A(4,2) = 2^{2^{16}} - 3.$$

Actually, it is not so obvious that A is a total function, but it is.

Proposition 4.11. Ackermann's function A is a total function.

Proof. This is shown by induction, using the lexicographic ordering \leq on $\mathbb{N} \times \mathbb{N}$, which is defined as follows:

$$(m, n) \preceq (m', n')$$
 iff either
 $m = m'$ and $n = n'$, or
 $m < m'$, or
 $m = m'$ and $n < n'$.

We write $(m, n) \prec (m', n')$ when $(m, n) \preceq (m', n')$ and $(m, n) \neq (m', n')$.

We prove that A(m, n) is defined for all $(m, n) \in \mathbb{N} \times \mathbb{N}$ by complete induction over the lexicographic ordering on $\mathbb{N} \times \mathbb{N}$.

In the base case, (m, n) = (0, 0), and since A(0, n) = n + 1, we have A(0, 0) = 1, and A(0, 0) is defined.

For $(m, n) \neq (0, 0)$, the induction hypothesis is that A(m', n') is defined for all $(m', n') \prec (m, n)$. We need to conclude that A(m, n) is defined.

If m = 0, since A(0, n) = n + 1, A(0, n) is defined.

If $m \neq 0$ and n = 0, since

$$(m-1,1) \prec (m,0),$$

by the induction hypothesis, A(m-1,1) is defined, but A(m,0) = A(m-1,1), and thus A(m,0) is defined.

If $m \neq 0$ and $n \neq 0$, since

$$(m, n-1) \prec (m, n),$$

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by the induction hypothesis, A(m, n-1) is defined. Since

$$(m-1, A(m, n-1)) \prec (m, n),$$

by the induction hypothesis, A(m-1, A(m, n-1)) is defined. But A(m, n) = A(m-1, A(m, n-1)), and thus A(m, n) is defined.

Thus, A(m, n) is defined for all $(m, n) \in \mathbb{N} \times \mathbb{N}$.

It is possible to show that A is a computable (recursive) function, although the quickest way to prove it requires some fancy machinery (the recursion theorem; see Section 10.1). Proving that A is *not* primitive recursive is even harder.

A further study of the partial recursive functions requires the notions of pairing functions and of universal functions (or universal Turing machines).

Chapter 5

Equivalence of the Models of Computation

5.1 Simulation of a RAM Program by a Turing Machine

It is convenient to describe Turing machines using diagrams. We can use a labeled graph representation where each transition (p, a, b, m, q) is represented by the diagrams shown in Figure 5.1.



Figure 5.1: Representation of a Turing machine instruction.

There is another convenient notation which can be used, if for each state, all transitions entering that state cause the head to move in the same direction. If this condition is not satisfied, by splitting states, an equivalent Turing machine can be effectively constructed and we leave the construction as an exercise. The situation is now the following. Given an instruction $(p, a, b, m, q) \in \delta$, we have the diagram shown in Figure 5.2.

There is a sight problem if p is not entered by any transition. But then, either p is the start state, in which case we use the notation shown in Figure 5.3, or else p is inaccessible and we can get rid of quintuples starting with p. Otherwise, all transitions entering p cause the tape to move in the same direction m', and we draw the diagram shown in Figure 5.4.



Figure 5.2: Representation of a Turing machine instruction.



Figure 5.3: Transition from the start state.



Figure 5.4: A typical transition.

Further simplifications are possible. When no confusion arises, we can omit state names. Transitions (p, a, a, m, q) are represented by the diagram of Figure 5.5, and transitions



Figure 5.5: A simplified transition.

(p, a, a, m, p) are simply omitted. In other words, loops from a state to itself that do not change the current symbol being scanned are omitted.

For all blocking pairs (p, a), that is, pairs such that no quintuple in δ begins with (p, a), we draw an outgoing arrow from state p labeled a as shown in Figure 5.6.



Figure 5.6: A blocking transition.

Example 5.1. Consider the Turing machine M with $K = \{q_0, q_1, q_2, q_3\}$, $\Gamma = \{a, b, B\}$, and δ consisting of the following quintuples:

$$\begin{split} q_0, B &\rightarrow B, R, q_3, \\ q_0, a &\rightarrow b, R, q_1, \\ q_0, b &\rightarrow a, R, q_1, \\ q_1, a &\rightarrow b, R, q_1, \\ q_1, b &\rightarrow a, R, q_1, \\ q_1, B &\rightarrow B, L, q_2, \\ q_2, a &\rightarrow a, L, q_2, \\ q_2, b &\rightarrow b, L, q_2, \\ q_2, B &\rightarrow B, R, q_3. \end{split}$$

The diagram (using the above conventions) corresponding to the Turing machine M is shown in Figure 5.7.



Figure 5.7: Diagram of the Turing machine M.

For any input $u \in \{a, b\}^*$, the output of the computation is the string v obtained from u by changing each "a" into a "b" and each "b" into an "a".

We now describe a construction which takes a RAM program as input and produces as output a Turing machine computing the same function as the function computed by the RAM program. This construction provides a proof for Theorem 4.2 that we repeat for the convenience of the reader.

Theorem 5.1. Every RAM-computable function is Turing-computable. Furthermore, given a RAM program P, we can effectively construct a Turing machine M computing the same function.

Proof. Let P be a RAM program using m registers $R1, \ldots Rm$ and having n instructions. The contents r_1, \ldots, r_m of the registers are represented on the Turing machine tape by the string

 $\#r1\#r2\#\cdots \#rm\#,$

where # is a special marker and ri represents the string held by Ri. We also use Proposition 4.1, which allows us to restrict ourselves to RAM programs that use only instructions of the form

(1_{j})	N		add_j	Y
(2)	N		tail	Y
$(6_j a)$	N	Y	jmp_i	N1a
$(6_j b)$	N	Y	jmp_j	N1b
(7)	N		continue	

The simulating Turing machine M is built of n blocks connected for the same flow of control as the n instructions in P. The *j*th block of the Turing machine simulates the *j*th instruction in P.

The machine M begins with some initialization whose purpose is to make sure that the simulation starts with a tape of the form

$$\#r1\#r2\#\cdots\#rm\#$$

representing *m* registers, with m+1 symbols #. Since the RAM program could have a number of input variables t < m, and it is necessary to add m + 2 - t symbols #. If the input is x_1, x_2, \dots, x_t , the t-1 commas are changed to #, and we add m + 1 - (t-1) = m + 2 - tsymbols #. For example, if m = 5 and t = 3, the Turing input tape ab, bb, a becomes #ab#bb#a###. See Figure 5.8 for the Turing machine achieving this step.

To simplify our diagrams, let us assume that the RAM alphabet is $\Sigma = \{0, 1\}$. Then the alphabet of the Turing machine is $\Gamma = \{0, 1, \#, B\}$. Each RAM statement is translated as a Turing machine block as follows. We have four blocks, one for each instruction.

- (a) $\operatorname{add}_i Rq$. See Figure 5.9.
- (b) tail Rq. See Figure 5.10.



Figure 5.8: Initialization.



Figure 5.9: Simulation of an instruction $add_i Rq$.



Figure 5.10: Simulation of an instruction tail Rq.

(c) $jmp_i Z$

There are two variants of this case, since Z is either a jump above or a jump below. These two cases are handled similarly, the only difference being the address of the block to jump to. See Figure 5.11.



Figure 5.11: Simulation of an instruction $jmp_i Z$.

Finally, we clean up the tape by erasing all but the contents of R1 from the tape. This block corresponds to the last continue statement.

(d) Clean up phase. See Figure 5.12.



Figure 5.12: Clean up phase.

Also note that a continue statement which is not the last continue statement in the RAM program is translated as an arrow from the exit of the *j*th block to the entry of the (j + 1)th block.

Notice that the Turing machine produced by the construction has the nice property that it never moves left of the blank square immediately to the left of its leftmost #. In other
words, the tape need only be unbounded to the right. We leave as an exercise to prove that every Turing-computable function is computable by a Turing machine which never moves more than one square to the left of its starting position. \Box

Example 5.2. Here is an example of the simulation for a RAM program with two input registers and a total of four registers. The input values are 101 in R1 and 00 in R2. The initialization phase is shown in Figure 5.13.



Figure 5.13: Initialization phase.

The simulation of the instruction $add_0 R1$ is shown in Figure 5.14. The simulation of the instruction tail R2 is shown in Figure 5.15.

Next we show that every Turing computable function is RAM-computable.

5.2 Simulation of Turing Machine by a RAM Program

In this section we provide a proof of Theorem 4.3 which we repeat for the reader's convenience.



Figure 5.14: Simulation of the instruction $add_0 R1$.



Proof. Recall that we showed that the concatenation function *con* and the extended concatenation function con_n defined such that $con_n(x_1, \ldots, x_n) = x_1 \cdots x_n$ are primitive recursive and consequently RAM-computable. Also, RAM programs are closed under composition. This allows to write a RAM program as a composition of blocks, avoiding the tedious task of writing the program in full.

Let $M = (K, \Gamma, \Delta, \delta, q_0)$ be a Turing machine with $K = \{q_0, \ldots, q_m\}$ and $\Gamma = \{a_1, \ldots, a_k, B, ", '\}$, and let φ be the partial function of n arguments computed by M.

The idea of the proof is to design a RAM program P containing an encoding of the



Figure 5.15: Simulation of the instruction tail R2.

current ID of the Turing machine M in register R1, and to use other registers R2, R3 to simulate the effect of executing an instruction of M by updating the ID of M in R1. After some initialization, the program P contains the current ID of M in register R1. For each move of M, the program P updates the current ID to the next ID.

Initially, P takes the n input strings x_1, \ldots, x_n and creates

$$\#ID_0\# = \#q_0x_1, x_2, \cdots, x_n\#$$

in register R1 and then simulates M. If and when M halts in a halting ID of the form $B^k q w B^{\ell}$, the program P places w in R1 and stops. If the ID is improper, then P loops forever.

The alphabet for P is $\Sigma = \Gamma \cup K \cup \{\#\}$, and it is assumed that $\Gamma \cap K = \emptyset$ and that #

is neither in Γ nor K. We let $a_{k+1} = B$ and $a_{k+2} = #$.

When P simulates a move of M by updating the ID, register R1 contains the current ID, which is of the form ua_jpa_iv and satisfies the following properties: if $u = \epsilon$, then $a_j = \#$, and if v consists of single symbol, then v = #.

During the first phase in which P updates the ID, P transfers u into register R2, a_j into register R3, and pa_iv is left in R1. Then it reads a_i and, depending on (p, a_i) , it simulates the action of M. In order to remember p and a_i , the program P has labels of the form jpand jpi. Right moves are accomplished at the addresses jpiR and jpiR#. Left moves are accomplished at the addresses jpiL and jpiL#. The updated ID is placed back into R1. When a halting ID is found, P checks that this ID is proper. If the halting ID is proper, then the output is returned in R1, otherwise P loops forever. For simplicity we adopt a subroutine notation. We also omit the suffix a or b in the target labels of jumps, which is not a problem since all jumps in P are uniquely defined.

We initialize P with the following commands:

$$R1 = con_{2n+2}(\#, q_0, x_1, ", ", \cdots, ", ", x_n, \#)$$

The subroutine Ai is the following program:

To remember $a_j p$, for each $p, 0 \le p \le m$, we have

$$\begin{array}{cccc} Qp & R3 & \texttt{jmp}_1 & 1p \\ \vdots & & \\ R3 & \texttt{jmp}_{k+2} & (k+2)p \end{array}$$

To remember $a_j p a_i$, for each $p, 0 \le p \le m$, we have

$$\begin{array}{cccc} jp & \texttt{tail} & R1 \\ R1 & \texttt{jmp}_1 & jp1 \\ & \vdots \\ R1 & \texttt{jmp}_{k+1} & jp(k+1) \end{array}$$

Next we have three cases.

(1) (Right move) To simulate the instruction (p, a, b, R, q) corresponding to the transition on ID's given by

$$ua_j pa_i v \to ua_j bq v, \quad v \neq \#$$

we have the program

$$\begin{array}{ccccc} jpi & \texttt{tail} & R1 \\ R1 & \texttt{jmp}_1 & jpiR \\ \vdots \\ R1 & \texttt{jmp}_{k+1} & jpiR \\ R1 & \texttt{jmp}_{k+2} & jpiR \\ jpiR & R1 = con_3(R2, a_j bq, R1) \\ & \texttt{jmp} & BEGIN \end{array}$$

To simulate the transition

$$ua_i pa_i \rightarrow ua_i bqB$$

corresponding to the case where v = #, in which case a blank needs to be inserted as the rightmost symbol on the tape, we have the program

$$jpiR\#$$
 $R1 = con_2(R2, a_j bqB\#)$
jmp $BEGIN$

(2) (Left move) To simulate the instruction (p, a, b, L, q), corresponding to the transition on ID's given by

$$ua_j pa_i v \to uqa_j bv, \quad u \neq e$$

we have the program

$$\begin{array}{ccccc} jpi & \mbox{tail} & R1 \\ R1 & \mbox{jmp}_1 & \mbox{jpiL} \\ \vdots & & \\ R1 & \mbox{jmp}_{k+1} & \mbox{jpiL} \\ R1 & \mbox{jmp}_{k+2} & \mbox{jpiL} \# \\ jpiL & R1 = con_3(R2,qa_jb,R1) \\ & \mbox{jmp} & BEGIN \end{array}$$

To simulate the transition

$$pa_i v \to qBbv$$

corresponding to the case where $u = \epsilon$, in which case a blank needs to be inserted as the lefmost symbol on the tape, we have the program

$$jpiL\#$$
 $R1 = con_2(\#qBb, R1)$
jmp $BEGIN$

(3) If no quintuple begins with (p, a_i) , then $upa_i v$ is a halting ID. We test if it is proper. For each such jpi, we have the program shown below.

$$jpi$$
 tail $R1$
jmp $PROPER$

The program PROPER checks that an ID is proper. It should be noted that this is unnecessary if the Turing machine has the property that if it halts, then the ID is proper. This can be achieved by modifying the Turing machine so that if it halts in an improper ID, then it loops.

First, the program PROPER checks that the ID starts with a string of the form $\#B^kq$. Next it places the output in R1, and finally it checks that the ID ends with $B^{\ell}\#$.

PROPER	R1 = cc	$m_3(R2,$	$a_j p a_i, I$	R1)		
	R2		U -		\leftarrow	R1
	R2				$\mathtt{jmp}_{\#}$	В
	jmp					LOOP
HEAD	R2				jmp_B	В
	R2				jmp_{q_0}	Q
	:					
	R2				jmp _a	Q
	jmp				- 4m	LOOP
В	tail				R2	
	jmp					HEAD
Q	clr				R1	
	MORE	tail	R2			
		R2	\mathtt{jmp}_1	RES	51	
		:				
		R2	jmp _k	RES	Sk	
		R2	jmp _B	BTA	ΛIL	
		R2	jmp _#	STO	P	
		jmp	#	LOC	PP	
		0 1				

For each $i, 1 \leq i \leq k$, we have the program

RESi	add_i	R1	
	jmp		MORE
BTAIL	tail	R2	
	R2	\mathtt{jmp}_B	BTAIL
	R2	$jmp_{\#}^{-}$	STOP
	jmp	11	LOOP
LOOP	jmp		LOOP
STOP	continue		

Example 5.3. Here is an example of the simulation of the Turing machine of Example 4.5 that exchanges *a*'s and *b*'s by a RAM program. The input is *ab*. The simulation of the transition $q_0ab \rightarrow bq_1b$ is shown in Figure 5.16. The simulation of the transition $bq_1b \rightarrow baq_1B$ is shown in Figure 5.17.

We leave the following proposition as an exercise.

Proposition 5.3. Given a Turing machine M computing a function φ , we can effectively construct a Turing machine M' also computing φ with the following additional properties.

- (1) M' halts in a proper ID iff M halts in a proper ID.
- (2) M' loops iff either M loops or M halts in an improper ID.



Figure 5.16: Simulation of the transition $q_0ab \rightarrow bq_1b$.

The construction is possible because a Turing machine is capable of checking whether or not a halting ID of M is proper, and if impoper, it loops forever. The construction is very similar to the program PROPER, as a Turing machine.

5.3 Every Turing Computable Function is Partial Computable a la Herbrand–Gödel–Kleene

The key to the proof that every Turing-computable function is a partial computable function in the sense of Herbrand–Gödel–Kleene is that we can define a primitive recursive function which simulates the transitions of a Turing machine in terms of instantaneous descriptions (ID's).

Instantaneous descriptions are represented as strings #upav#, where p is a state, $a \in \Gamma$, and $u, v \in \Gamma^*$.

Given a Turing machine $M = (K, \Gamma, \Delta, \delta, q_0)$ (with $\Sigma = \{a_1, \ldots, a_k\}$) we define the



Figure 5.17: Simulation of the transition $bq_1b \rightarrow baq_1B$.

following pairs of ID's describing the transitions of M.

(1) For every (move right) instruction $(p, a, b, R, q) \in \delta$, we have the pairs

```
(paa_1, bqa_1)
\vdots
(paa_k, bqa_k)
(pa\#, bqB\#).
```

(2) For every (move left) instruction $(p, a, b, L, q) \in \delta$, we have the pairs

```
(a_1pa, qa_1b)
\vdots
(a_kpa, qa_kb)
(\#pa, \#qBb).
```

The above set of pairs is denoted TRANS, and it is assumed to be ordered in some fashion. As an abbreviation each pair is denoted $\ell_i \to r_i$, for example, $paa_1 \to bqa_1$ and $a_1pa \to qa_1b$. We assume that there are N such pairs (this is the number of quintuples in δ).

We also have a list BLOCKED of strings pa such that no quintuple in δ starts with (p, a), say

$$p_{i_1}a_{i_1},\ldots,p_{i_m}a_{i_m}$$

An illustration of the rules $\ell_i \to r_i$ is shown in Figure 5.18.



Figure 5.18: Illustration of the rules associated to transitions.

We will use a number of primitive recursive functions.

Proposition 5.4. The following functions are primitive recursive.

(1) Occ(x, y), where Occ(x, y) holds iff x is a substring of y.

(2) u(x,z) = the prefix of z the left of the leftmost occurrence of x in z if Occ(x,z).

(3) v(x,z) = the suffix of z the right of the leftmost occurrence of x in z if Occ(x,z).

(4) $\operatorname{rep}(x, y, z) = \text{the result of replacing the leftmost occurrence of } x \text{ by } y \text{ in } z \text{ if } \operatorname{Occ}(x, z).$

Proof. Recall that concatenation and extended concatenation are primitive recursive.

(1) $\operatorname{Occ}(x, y)$ iff $(\exists z/y)(\exists w/y)[z = wx]$.

(2) $u(x,z) = \min y/z(\exists w/z)[yx = w].$

(3) v(x,z) = z - u(x,z)x (here – is the version of monus on strings defined just after Definition 4.26).

(4) $\operatorname{rep}(x, y, z) = u(x, z)yv(x, z).$

Note that for every ID, there is at most one occurrence of ℓ_i or r_i for some $\ell_i \to r_i$ in TRANS. This is why it doesn't hurt to pick the leftmost occurrence.

The predicate Occ is illustrated in Figure 5.19.



Figure 5.19: Illustration of the predicate Occ.

The functions u and v are illustrated in Figure 5.20. The function rep is illustrated in Figure 5.21.

Proposition 5.5. For any Turing machine M, the following functions are primitive recursive.

- (1) The function T such that $T(ID_0, y) = ID$ iff $ID_0 \vdash_{|y|}^* ID$ in |y| steps.
- (2) HALT(ID) iff ID is a halting ID.
- (3) STOP(y, ID) iff M halts in a halting ID after |y| steps.

Proof. Note that we do not actually care what T, HALT, STOP do if ID_0 and ID are not proper representations of ID's.



Figure 5.20: Illustration of the functions u and v.

(1) The function T is defined as follows, which shows that it is primitive recursive.

$$T(x,\epsilon) = x$$

$$T(x,ya_i) = \begin{cases} \operatorname{rep}(\ell_1, r_1, T(x,y)) & \text{iff } \operatorname{Occ}(\ell_1, T(x,y)) \\ \operatorname{rep}(\ell_2, r_2, T(x,y)) & \text{iff } \operatorname{Occ}(\ell_2, T(x,y)) \land \neg \operatorname{Occ}(\ell_1, T(x,y)) \\ \vdots \\ \operatorname{rep}(\ell_N, r_N, T(x,y)) & \text{iff } \operatorname{Occ}(\ell_N, T(x,y)) \land \neg \operatorname{Occ}(\ell_1, T(x,y)) \\ \land \cdots \land \neg \operatorname{Occ}(\ell_{N-1}, T(x,y)) \\ & T(x,y) \text{ otherwise.} \end{cases}$$

The function T is illustrated in Figure 5.22.

If T(x, y) represents the ID #upav# obtained after performing |y| steps starting from the ID x, then $T(x, ya_i)$ represents the ID obtained by applying an instruction starting



Figure 5.21: Illustration of the function rep.

with (p, a), if any. To see if such an instruction applies we test sequentially starting from k = 1 whether the left-hand side ℓ_k of a transition $\ell_k \to r_k$ occurs in T(x, y), which is performed by $Occ(\ell_k, T(x, y))$, the tests $Occ(\ell_{k_1}, T(x, y))$ for all $k_1 < k$ being negative. If so, ℓ_k is replaced by r_k in the ID T(x, y) to mimic the TM transition corresponding to $\ell_r \to r_k$, which is achieved by $rep(\ell_k, r_k, T(x, y))$. Since the purpose of y is to count the number of steps, only |y| matters, so we may assume that y is a string of a_1 s.

(2) The function HALT is defined as follows.

HALT(x) iff $[Occ(p_{i_1}a_{i_1}, x) \lor \cdots \lor Occ(p_{i_m}a_{i_m}, x)].$

(3) STOP(y, ID) iff HALT(T(x, y)).

If M is a Turing machine computing a function of n arguments x_1, \ldots, x_n , the starting ID is defined as

$$ID_0 = \#q_0x_1, x_2, \cdots, x_n \#$$

Let INIT be the function given by

$$INIT(x_1,\ldots,x_n) = \#x_1,\ldots,x_n\#.$$

Obviously INIT is primitive recursive. Then for all $x_1, \ldots, x_n \in \Sigma^*$, we have

$$ID_0 \vdash_{|y|}^* ID$$
 and ID is a halting ID

 iff

$$T(\text{INIT}(x_1,\ldots,x_n),\min_1 y[\text{STOP}(y,\text{INIT}(x_1,\ldots,x_n))]) = ID$$



Figure 5.22: Illustration of the function T.

Let RES be the function that cleans up a halting ID to produce the output. The function RES is defined by primitive recursion as follows (recall that *rev* is the reverse function and *con* is the concatenation function).

$$RES(\epsilon) = \epsilon$$

$$RES(x\#) = RES(x)$$

$$RES(xB) = RES(x)$$

$$RES(xa_i) = con(RES(x), a_i), \quad 1 \le i \le k$$

$$RES(xq) = RES(rev(x)), \quad q \in K.$$

We leave it as an exercise to prove that for any halting ID of the form $\#B^kquB^\ell\#$ with $u \in \Sigma^*$, we have

$$\operatorname{RES}(\#B^k q u B^\ell \#) = u.$$

Combining all the facts we established we obtain the following result.

Theorem 5.6. Every Turing computable function φ of n arguments is partial computable in the sense of Herbrand–Gödel–Kleene. Moreover, given a Turing machine M, we can effectively find a definition of φ of the form

$$\varphi(x_1,\ldots,x_n) = \operatorname{RES}(T(\operatorname{INIT}(x_1,\ldots,x_n),\min_1 y[\operatorname{STOP}(y,\operatorname{INIT}(x_1,\ldots,x_n))]))$$

As a corollary we have the following nontrivial result.

Corollary 5.7. Every partial computable function φ can be effectively obtained in the form $\varphi = f \circ \min_1 g$, where f and g are primitive recursive functions.

Consequently, every partial computable function has a definition in which minimization is applied at most once.

Chapter 6 The Lambda-Calculus

The original motivation of Alonzo Church for inventing the λ -calculus was to provide a type-free foundation for mathematics (alternate to set theory) based on higher-order logic and the notion of *function* in the early 1930's (1932, 1933). This attempt to provide such a foundation for mathematics failed due to a form of Russell's paradox. Church was clever enough to turn the technical reason for this failure, the existence of fixed-point combinators, into a success, namely to view the λ -calculus as a formalism for defining the notion of *computability* (1932,1933,1935). The λ -calculus is indeed one of the first computation models, slightly preceding the Turing machine.

Kleene proved in 1936 that all the computable functions (recursive functions) in the sense of Herbrand and Gödel are definable in the λ -calculus, showing that the λ -calculus has universal computing power. In 1937, Turing proved that Turing machines compute the same class of computable functions. (This paper is very hard to ead, in part, because the definition of a Turing machine is not included in this paper). In short, the λ -calculus and Turing machines have the same computing power. Here we have to be careful. To be precise we should have said that all the total computable functions (total recursive functions) are definable in the λ -calculus. In fact, it is also true that all the partial computable functions (partial recursive functions) are definable in the λ -calculus but this requires more care.

Since the λ -calculus does not have any notion of tape, register, or any other means of storing data, it quite amazing that the λ -calculus has so much computing power.

The λ -calculus is based on three concepts:

- (1) Application.
- (2) Abstraction (also called λ -abstraction).
- (3) β -reduction (and β -conversion).

If f is a function, say the exponential function $f: \mathbb{N} \to \mathbb{N}$ given by $f(n) = 2^n$, and if n a natural number, then the result of applying f to a natural number, say 5, is written as

(f 5)

instead of f(5), and is called an *application*. Here we can agree that f and 5 do not have the same *type*, in the sense that f is a function and 5 is a number, so applications such as (f f) or (5 5) do not make sense, but the λ -calculus is *type-free* so expressions such as (f f)as allowed. This may seem silly, and even possibly undesirable, but allowing self application turns out to a major reason for the computing power of the λ -calculus.

Given an expression M containing a variable x, say

$$M(x) = x^2 + x + 1,$$

as x ranges over \mathbb{N} , we obtain the function represented in standard mathematical notation by $x \mapsto x^2 + x + 1$. If we supply the input value 5 for x, then the value of the function is $5^2 + 5 + 1 = 31$. Church introduced the notation

$$\lambda x.(x^2+x+1)$$

for the function $x \mapsto x^2 + x + 1$. Here, we have an *abstraction*, in the sense that the static expression M(x) for x fixed becomes an "abstract" function denoted λx . M, where x can be instantiated to any input value.

It would be pointless to only have the two concepts of application and abstraction. The glue between these two notions is a form of evaluation called β -reduction.¹ Given a λ -abstraction λx . M and some other term N (thought of as an argument), we have the "evaluation" rule, we say β -reduction,

$$(\lambda x. M)N \xrightarrow{+}_{\beta} M[x := N],$$

where M[x := N] denotes the result of substituting N for all occurrences of x in M. For example, if $M = x^2 + x + 1$ and N = 2y + 1, we have

$$(\lambda x. (x^2 + x + 1))(2y + 1) \xrightarrow{+}_{\beta} (2y + 1)^2 + 2y + 1 + 1.$$

Observe that β -reduction is a *purely formal* operation (plugging N wherever x occurs in M), and that the expression $(2y+1)^2+2y+1+1$ is *not* instantly simplified to $4y^2+6y+3$. In the λ -calculus, the natural numbers as well as the arithmetic operations + and × need to be represented as λ -terms in such a way that they "evaluate" correctly using only β -conversion. In this sense, the λ -calculus is an incredibly low-level programming language. Nevertheless, the λ -calculus is the core of various *functional programming languages* such as *OCaml*, *ML*, *Miranda* and *Haskell*, among others.

We now proceed with precise definitions and results. But first we ask the reader not to think of functions as the functions we encounter in analysis or algebra. Instead think of functions as *rules for computing* (by moving and plugging arguments around), a more combinatory (which does not mean combinatorial) viewpoint.

This chapter relies heavily on the masterly expositions by Barendregt [5, 6]. We also found inspiration from very informative online material by Henk Barendregt, Peter Selinger, and J.R.B. Cockett, whom we thank. Hindley and Seldin [35] and Krivine [46] are also excellent sources (and not as advanced as Barendregt [5]).

¹Apparently, Church was fond of Greek letters.

6.1 Syntax of the Lambda-Calculus

We begin by defining the *lambda-calculus*, also called *untyped lambda-calculus* or *pure lambda-calculus*, to emphasize that the terms of this calculus are not typed. This formal system consists of

- 1. A set of terms, called λ -terms.
- 2. A notion of reduction, called β -reduction, which allows a term M to be transformed into another term N in a way that mimics a kind of evaluation.

First we define (pure) λ -terms. We have a countable set of variables $\{x_0, x_1, \ldots, x_n \ldots\}$ that correspond to the atomic λ -terms.

Definition 6.1. The λ -terms M are defined inductively as follows.

- (1) If x_i is a variable, then x_i is a λ -term.
- (2) If M and N are λ -terms, then (MN) is a λ -term called an *application*.
- (3) If M is a λ -term, and x is a variable, then the expression $(\lambda x, M)$ is a λ -term called a λ -abstraction.

Note that the only difference between the λ -terms of Definition 6.1 and the raw simplytyped λ -terms of Definition 2.13 is that in Clause (3), in a λ -abstraction term ($\lambda x. M$), the variable x occurs without any type information, whereas in a simply-typed λ -abstraction term ($\lambda x: \sigma. M$), the variable x is assigned the type σ . At this stage this is only a cosmetic difference because raw simply-typed λ -terms are not yet assigned types. But there are typechecking rules for assigning types to raw simply-typed λ -terms that *restrict application*, so the set of simply-typed λ -terms that type-check is much more restricted than the set of (untyped) λ -terms. In particular, no simply-typed λ -term that type-checks can be a selfapplication (MM). The fact that self-application is allowed in the untyped λ -calculus is what gives it its computational power (through fixed-point combinators, see Section 6.5).

Definition 6.2. The depth d(M) of a λ -term M is defined inductively as follows.

- 1. If M is a variable x, then d(x) = 0.
- 2. If M is an application (M_1M_2) , then $d(M) = \max\{d(M_1), d(M_2)\} + 1$.
- 3. If M is a λ -abstraction (λx . M_1), then $d(M) = d(M_1) + 1$.

It is pretty clear that λ -terms have representations as (ordered) labeled trees.

Definition 6.3. Given a λ -term M, the tree tree(M) representing M is defined inductively as follows:

1. If M is a variable x, then tree(M) is the one-node tree labeled x.

- 2. If M is an application (M_1M_2) , then tree(M) is the tree with a binary root node labeled ., and with a left subtree tree (M_1) and a right subtree tree (M_2) .
- 3. If M is a λ -abstraction ($\lambda x. M_1$), then tree(M) is the tree with a unary root node labeled λx , and with one subtree tree(M_1).

Definition 6.3 is illustrated in Figure 6.1.



Figure 6.1: The tree tree(M) associated with a pure λ -term M.

Obviously, the depth d(M) of λ -term is the depth of its tree representation tree(M).

Unfortunately λ -terms contain a profusion of parentheses so some conventions are commonly used.

(1) A term of the form

$$(\cdots ((FM_1)M_2)\cdots M_n)$$

is abbreviated (association to the left) as

$$FM_1 \cdots M_n$$
.

(2) A term of the form

$$(\lambda x_1. (\lambda x_2. (\cdots (\lambda x_n. M) \cdots))))$$

is abbreviated (association to the right) as

$$\lambda x_1 \cdots x_n. M.$$

It is also assumed that application binds more strongly that λ -abstraction. So

$$\lambda x_1 \lambda x_2$$
. $M_1 M_2 M_3$

is an abbreviation for

$$\left(\lambda x_1.\left(\lambda x_2.\left((M_1M_2)M_3\right)\right)\right)$$

Matching parentheses may be dropped or added for convenience.

Example 6.1. Here are some examples of λ -terms (and their abbreviation):

y	y
(yx)	yx
$(\lambda x. (yx))$	$\lambda x. yx$
$((\lambda x.(yx))z)$	$(\lambda x.yx)z$
$(((\lambda x.(\lambda y.(yx)))z)w)$	$(\lambda xy. yx)zw.$

Note that $\lambda x. yx$ is an abbreviation for $(\lambda x. (yx))$, not $((\lambda x. y)x)$ (which is abbreviated as $(\lambda x. y)x$).

The variables occurring in a λ -term are free or bound.

Definition 6.4. For any λ -term M, the set FV(M) of *free variables* of M and the set BV(M) of *bound variables* in M are defined inductively as follows.

(1) If M = x (a variable), then

$$FV(x) = \{x\}, \quad BV(x) = \emptyset.$$

(2) If $M = (M_1 M_2)$, then

$$FV(M) = FV(M_1) \cup FV(M_2), \quad BV(M) = BV(M_1) \cup BV(M_2).$$

(3) if $M = (\lambda x. M_1)$, then

$$FV(M) = FV(M_1) - \{x\}, \quad BV(M) = BV(M_1) \cup \{x\}$$

If $x \in FV(M_1)$, we say that the occurrences of the variable x occur in the scope of λ .

A λ -term M is closed or a combinator if $FV(M) = \emptyset$, that is, if it has no free variables.

Example 6.2. We have

$$FV((\lambda x. yx)z) = \{y, z\}, \qquad BV((\lambda x. yx)z) = \{x\},$$

and

$$FV((\lambda xy. yx)zw) = \{z, w\}, \qquad BV((\lambda xy. yx)zw) = \{x, y\}$$

Before proceeding with the notion of substitution we must address an issue with bound variables. The point is that bound variables are really *place-holders* so they can be renamed freely without changing the reduction behavior of the term as long as they do not clash with free variables. For example, the terms $\lambda x. (x(\lambda y. x(yx)))$ and $\lambda x. (x(\lambda z. x(zx)))$ should

be considered as equivalent. Similarly, the terms $\lambda x. (x(\lambda y. x(yx)))$ and $\lambda w. (w(\lambda z. w(zw)))$ should be considered as equivalent.

One way to deal with this issue is to use the tree representation of λ -terms given in Definition 6.3. For every leaf labeled with a bound variable x, we draw a backpointer to an ancestor of x determined as follows. Given a leaf labeled with a bound variable x, climb up to the closest ancestor labeled λx , and draw a backpointer to this node. Then all bound variables can be erased. An example is shown in Figure 6.2 for the term $M = \lambda x. x(\lambda y. (x(yx)))$.



tree($\lambda x \cdot x(\lambda y \cdot x(yx))$)

Figure 6.2: The tree representation of a λ -term with backpointers.

A clever implementation of the idea of backpointers is the formalism of *de Bruijn indices*; see Pierce [58] (Chapter 6) or Barendregt [5] (Appendix C).

Church introduced the notion of α -conversion to deal with this issue. First we need to define substitutions.

Definition 6.5. A substitution φ is a finite set of pairs $\varphi = \{(x_1, N_1), \dots, (x_n, N_n)\}$, where the x_i are distinct variables and the N_i are λ -terms. We write

$$\varphi = [N_1/x_1, \dots, N_n/x_n]$$
 or $\varphi = [x_1 := N_1, \dots, x_n := N_n].$

The second notation indicates more clearly that each term N_i is substituted for the variable x_i , and it seems to have been almost universally adopted.

Definition 6.6. Given a substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$, for any variable x_i , we denote by φ_{-x_i} the new substitution where the pair (x_i, N_i) is replaced by the pair (x_i, x_i) (that is, the new substitution leaves x_i unchanged).

Definition 6.7. Given any λ -term M and any substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$, we define the λ -term $M[\varphi]$, the result of applying the substitution φ to M, as follows.

- (1) If M = y, with $y \neq x_i$ for i = 1, ..., n, then $M[\varphi] = y = M$.
- (2) If $M = x_i$ for some $i \in \{1, \ldots, n\}$, then $M[\varphi] = N_i$.
- (3) If M = (PQ), then $M[\varphi] = (P[\varphi]Q[\varphi])$.
- (4) If $M = \lambda x$. N and $x \neq x_i$ for i = 1, ..., n, then $M[\varphi] = \lambda x$. $N[\varphi]$.
- (5) If $M = \lambda x$. N and $x = x_i$ for some $i \in \{1, \ldots, n\}$, then $M[\varphi] = \lambda x$. $N[\varphi]_{-x_i}$.

The term M is safe for the substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$ if $BV(M) \cap (FV(N_1) \cup \cdots \cup FV(N_n)) = \emptyset$, that is, if the free variables in the substitution terms N_i do not become bound.

Note that Clause (5) ensures that a substitution only substitutes the terms N_i for the variables x_i free in M. Thus if M is a closed term, then for every substitution φ , we have $M[\varphi] = M$. More generally, if none of the variables x_i occurs free in M, then $M[\varphi] = M$.

Example 6.3. Here are some examples of substitution.

$$\begin{split} y[x &:= \lambda x. (xz)(xz)] = y\\ x[x &:= \lambda x. (xz)(xz)] = \lambda x. (xz)(xz)\\ (xz)(yz)[y &:= (vv); z := (\lambda u. v)] = (x(\lambda u. v))((vv)(\lambda u. v))\\ \lambda x. (xz)(yz)[y &:= (vv); z := (\lambda u. v)] = \lambda x. (x(\lambda u. v))((vv)(\lambda u. v))\\ \lambda z. (z(xz))[x &:= (\lambda u. (uu)); z = (uu)] = \lambda z. (z((\lambda u. (uu))z)). \end{split}$$

There is a problem with the present definition of a substitution in Cases (4) and (5), which is that the result of substituting a term N_i containing the variable x free causes this variable to become bound after the substitution. We say that x is *captured*.

Example 6.4. If we make the substitution

$$\lambda x. (xz)(yz)[y := (xx); z := (\lambda u. v)] = \lambda x. (x(\lambda u. v))((xx)(\lambda u. v))$$

the variable x occurring free in the term (xx) now has three bound occurrences in the term $\lambda x. (x(\lambda u. v))((xx)(\lambda u. v))$. We should only apply a substitution φ to a term M if M is safe for φ . We should rename the bound variable x in the term $\lambda x. (xz)(yz)$, say as w, obtaining the term $\lambda w. (wz)(yz)$, and then there is no capture of variable when we make the substitution

$$\lambda w. (wz)(yz)[y := (xx); z := (\lambda u. v)] = \lambda w. (w(\lambda u. v))((xx)(\lambda u. v)).$$

To remedy this problem, Church defined α -conversion.

Definition 6.8. The binary relation \longrightarrow_{α} on λ -terms called *immediate* α -conversion² is the smallest relation satisfying the following properties: for all λ -terms M, N, P, Q.

$$\lambda x. M \longrightarrow_{\alpha} \lambda y. M[x := y], \text{ for all } y \notin FV(M) \cup BV(M)$$

if $M \longrightarrow_{\alpha} N$, then $MQ \longrightarrow_{\alpha} NQ$ and $PM \longrightarrow_{\alpha} PN$
if $M \longrightarrow_{\alpha} N$, then $\lambda x. M \longrightarrow_{\alpha} \lambda x. N.$

The least equivalence relation $\equiv_{\alpha} = (\longrightarrow_{\alpha} \cup \longrightarrow_{\alpha}^{-1})^*$ containing \longrightarrow_{α} (the reflexive and transitive closure of $\longrightarrow_{\alpha} \cup \longrightarrow_{\alpha}^{-1}$) is called α -conversion. Here $\longrightarrow_{\alpha}^{-1}$ denotes the converse of the relation \longrightarrow_{α} , that is, $M \longrightarrow_{\alpha}^{-1} N$ iff $N \longrightarrow_{\alpha} M$.

Example 6.5. We have

 $\lambda fx. f(f(x)) = \lambda f. \lambda x. f(f(x)) \longrightarrow_{\alpha} \lambda f. \lambda y. f(f(y)) \longrightarrow_{\alpha} \lambda g. \lambda y. g(g(y)) = \lambda gy. g(g(y)).$

Now given a λ -term M and a substitution $\varphi = [x_1 := N_1, \ldots, x_n := N_n]$, before applying φ to M, we first perform some α -conversion to obtain a term $M' \equiv_{\alpha} M$ whose set of bound variables BV(M') is disjoint from $FV(N_1) \cup \cdots \cup FV(N_n)$ so that M' is safe for φ , and the result of the substitution is $M'[\varphi]$.

Example 6.6. We have

 $(\lambda yz. (xy)z)[x := yz] \equiv_{\alpha} (\lambda uv. (xu)v)[x := yz] = \lambda uv. ((yz)u)v.$

From now on, we consider two λ -terms M and M' such that $M \equiv_{\alpha} M'$ as identical (to be rigorous, we deal with equivalence classes of terms with respect to α -conversion). Even the experts are lax about α -conversion so we happily go along with them. The convention is that bound variables are always renamed to avoid clashes (with free or bound variables).

Note that the representation of λ -terms as trees with back-pointers also ensures that substitutions are safe. However, this requires some extra effort. No matter what, it takes some effort to deal properly with bound variables.

6.2 β -Reduction and β -Conversion; the Church-Rosser Theorem

The computational engine of the λ -calculus is β -reduction.

Definition 6.9. The relation \longrightarrow_{β} , called *immediate* β -reduction, is the smallest relation satisfying the following properties for all λ -terms M, N, P, Q:

$$(\lambda x. M)N \longrightarrow_{\beta} M[x := N], \text{ where } M \text{ is safe for } [x := N]$$

²We told you that Church was fond of Greek letters.

if $M \longrightarrow_{\beta} N$, then $MQ \longrightarrow_{\beta} NQ$ and $PM \longrightarrow_{\beta} PN$ if $M \longrightarrow_{\beta} N$, then $\lambda x. M \longrightarrow_{\beta} \lambda x. N$.

The transitive closure of \longrightarrow_{β} is denoted by $\stackrel{+}{\longrightarrow_{\beta}}$, the reflexive and transitive closure of \longrightarrow_{β} is denoted by $\stackrel{*}{\longrightarrow_{\beta}}$, and we define β -conversion, denoted by $\stackrel{*}{\longleftrightarrow_{\beta}}$, as the smallest equivalence relation $\stackrel{*}{\longleftrightarrow_{\beta}} = (\longrightarrow_{\beta} \cup \longrightarrow_{\beta}^{-1})^*$ containing \longrightarrow_{β} .

To study properties of β -reduction sequences it is important to define precisely where a subterm occurs inside of a term. This notion is quite clear if we view a term M as the corresponding tree tree(M). Then a subterm N corresponds to a subtree tree(N) of tree(M). Since the same subtree can occur in several places, we need to exercise some care. We use the fact that the root of the subtree tree(N) is reached from the root of the tree tree(M)along a unique path described by a string over the alphabet $\{1, 2\}$.

We have the usual *lexicographic ordering* \leq on the set of strings $\{1, 2\}^*$, where for any two strings $u, v \in \{1, 2\}^*$, $u \leq v$ if either u is a prefix of v, namely v = ux for some $x \in \{1, 2\}^*$, or u = x1y, v = x2z, for some $x, y, z \in \{1, 2\}^*$.

Definition 6.10. Let M be a λ -term. The set of occurrences of subterms in M, Occ(M), is the set of pairs (u, N), with $u \in \{1, 2\}^*$ and N a λ -term, defined as follows.

- (1) If M is the variable x, then $Occ(M) = \{(\epsilon, x)\}.$
- (2) If M is an application $M = (M_1 M_2)$, then

$$Occ(M) = \{(\epsilon, M)\} \cup \{(1u, N_1) \mid (u, N_1) \in Occ(M_1)\} \cup \{(2v, N_2) \mid (v, N_2) \in Occ(M_2)\}$$

(3) If M is an abstraction $M = \lambda x. M_1$, then

$$Occ(M) = \{(\epsilon, M)\} \cup \{(1u, N_1) \mid (u, N_1) \in Occ(M_1)\}.$$

If $(u, N) \in Occ(M)$, we say that the subterm N occurs at u in M. Note that M itself occurs at ϵ in M. If N occurs at u in M and N' occurs at v in M, we say that u is a proper ancestor of v if v = ux for some $x \neq \epsilon$. In this case, we say that N' is a proper subterm of N.

Example 6.7. The term

$$M = \left(\lambda z. \left(\left(\lambda y. \left((zy)y \right) \right) z \right) \right) w$$

has the following set of occurrences of subterms:

$$(111111, z), (111112, y), (11111, (zy)), (11112, y), (1111, ((zy)y)), (111, (\lambda y. ((zy)y))), (112, z), (11, ((\lambda y. ((zy)y))z)), (1, (\lambda z. ((\lambda y. ((zy)y))z))), (2, w), (\epsilon, (\lambda z. ((\lambda y. ((zy)y))z))w).$$

The subterm z occurs at 111111 and 112 and the subterm y occurs at 111112 and 1112. The subterm (zy) (which occurs at 11111) is a proper subterm of the subterm $((\lambda y. ((zy)y))z)$ (which occurs at 11).

Definition 6.11. Given a λ -term M, a subterm R of M of the form $R = (\lambda x. M_1)N_1$ is called a *redex*. If M β -reduces to M', because the redex R occurring at u in M β -reduces, namely

$$R = (\lambda x. M_1) N_1 \longrightarrow_{\beta} M_1[x := N_1],$$

we write

$$M \xrightarrow{*}_{u,R,\beta} M'$$

A λ -term M is a β -normal form if there is no λ -term N such that $M \longrightarrow_{\beta} N$, equivalently if M contains no β -redex.

Example 6.8. The term

$$M = \left(\lambda z. \left(\left(\lambda y. \left((zy)y \right) \right) z \right) \right) w$$

has two β -redexes.

- (1) The term M itself.
- (2) The subterm $\left(\left(\lambda y. \left((zy)y \right) \right) z \right)$ at 11.

Example 6.9. The term

$$M = \left(\lambda z. \left(\left((\lambda x. (xz))u\right)\left((\lambda y. (yz))v\right)\right)\right)u$$

has three β -redexes.

- (1) The term M itself.
- (2) The subterm $((\lambda x. (xz))u)$ at 111.
- (3) The subterm $((\lambda y. (yz))v)$ at 112.

The following characterization of terms in β -normal form is easily shown by induction on the depth of terms.

Proposition 6.1. A λ -term M is a β -normal form if and only if one of the following conditions hold:

- (1) M is a variable x.
- (2) $M = xM_1 \cdots M_n$, where x is variable and M_1, \ldots, M_n are β -normal forms.

(3) $M = \lambda x. M_1$, where M_1 is a β -normal form.

Definition 6.12. We say that a redex R occurring at u in M is maximal if there is no redex R' occurring at v in M such that v is a proper ancestor of u, equivalently R is not a proper subterm of R'. A redex R occurring at u in M is the *leftmost maximal redex in* M if R is maximal and if for any other redex R' at v which is also maximal, then $u \leq v$. This means that in the tree tree(M), the root of tree tree(R) occurs on a path of the form x1y, and the root of tree tree(R') occurs on a path of the form x2z.

Definition 6.13. A reduction sequence such that the leftmost maximal redex is β -reduced at every step is called a *normal reduction* (or *leftmost reduction*).

Normal reductions are important because according to a theorem of Curry, if a term M has a β -normal form M^* , then there is a normal reduction from M to M^* ; see Barendregt [5] (Chapter 13, Theorem 13.2.2). The weaker notion of quasi-leftmost reduction will be considered later in Section 6.6.

In Example 6.8, there is a unique maximal redex, namely M itself, so it is the leftmost maximal redex, and similarly in Example 6.9.

Example 6.10. The term

$$M = w \left(\left(\left(\lambda z. \left(\left(\lambda y. \left((zy)y \right) \right) z \right) \right) u \right) \left(\left(\lambda z. \left(\left(\lambda y. \left(zy \right) \right) z \right) \right) v \right) \right)$$

has two maximal β -redexes

$$\left(\lambda z.\left(\left(\lambda y.\left((zy)y\right)\right)z\right)\right)u, \quad \left(\lambda z.\left(\left(\lambda y.\left(zy\right)\right)z\right)\right)v,$$

and the blue redex is the leftmost maximal redex.

Example 6.11. The subterm $((\lambda x. (\lambda y. x))u)$ is the maximal leftmost β -redex in the term $((\lambda x. (\lambda y. x))u)v$. We have

$$(\lambda xy. x)uv = ((\lambda x. (\lambda y. x))u)v \longrightarrow_{\beta} ((\lambda y. x)[x := u])v = (\lambda y. u)v \longrightarrow_{\beta} u[y := v] = u.$$

The subterm $((\lambda x. (\lambda y. y))u)$ is the maximal leftmost β -redex in the term $((\lambda x. (\lambda y. y))u)v$. We have

$$(\lambda xy. y)uv = \left((\lambda x. (\lambda y. y))u \right) v \longrightarrow_{\beta} ((\lambda y. y)[x := u])v = (\lambda y. y)v \longrightarrow_{\beta} y[y := v] = v.$$

This shows that λxy . x behaves like the projection onto the first argument and λxy . y behaves like the projection onto the second.

Example 6.12. The normal reduction from the term

$$M = \left(\lambda z. \left(\left((\lambda x. (xz))u\right)\left((\lambda y. (yz))v\right)\right)\right)w$$

is shown below:

$$\begin{pmatrix} \lambda z. \left(\left((\lambda x. (xz))u \right) \left((\lambda y. (yz))v \right) \right) \\ w \xrightarrow{+}_{\beta} \left((\lambda x. (xw))u \right) \left((\lambda y. (yw))v \right) \\ \xrightarrow{+}_{\beta} (uw) \left((\lambda y. (yw))v \right) \xrightarrow{+}_{\beta} (uw)(vw). \end{cases}$$

Example 6.13. More interestingly, if we let $\boldsymbol{\omega} = \lambda x. (xx)$, then

$$\boldsymbol{\Omega} = \boldsymbol{\omega}\boldsymbol{\omega} = (\lambda x. (xx))(\lambda x. (xx)) \longrightarrow_{\beta} (xx)[x := \lambda x. (xx)] = \boldsymbol{\omega}\boldsymbol{\omega} = \boldsymbol{\Omega}.$$

The above example shows that β -reduction sequences may be infinite. This is a curse and a miracle of the λ -calculus! The term Ω has no β -normal form.

Example 6.14. There are even β -reductions where the evolving term grows in size.

$$(\lambda x. (xx)x)(\lambda x. (xx)x) \xrightarrow{+}_{\beta} ((\lambda x. (xx)x)(\lambda x. (xx)x))(\lambda x. (xx)x)) \\ \xrightarrow{+}_{\beta} (((\lambda x. (xx)x)(\lambda x. (xx)x))(\lambda x. (xx)x))(\lambda x. (xx)x)) \\ \xrightarrow{+}_{\beta} \cdots$$

There is only one maximal (leftmost) redex shown in blue. This term has no β -normal form.

Example 6.15. The term

 $L = (\lambda x. (xx)y)(\lambda x. (xx)y)$

also does not have a β -normal form. Indeed,

$$L = (\lambda x. (xx)y)(\lambda x. (xx)y) \xrightarrow{+}_{\beta} (\lambda x. (xx)y)(\lambda x. (xx)y)y \xrightarrow{+}_{\beta} (\lambda x. (xx)y)(\lambda x. (xx)y)yy \xrightarrow{+}_{\beta} \cdots,$$

namely

Ş

$$L \xrightarrow{+}_{\beta} Ly \xrightarrow{+}_{\beta} Lyy \xrightarrow{+}_{\beta} \cdots$$

A term M may have a β -normal form, but also some infinite β -reduction sequence. Consider the term

$$P = (\lambda u. v)L = (\lambda u. v) \Big((\lambda x. xxy) (\lambda x. xxy) \Big),$$

which is the unique maximal redex (and thus the leftmost maximal redex). We have the β -reduction

$$P = (\lambda u. v)L \xrightarrow{+}_{\beta} v[u := L] = v,$$

where v is a β -normal form, but also the infinite β -reduction sequence

$$P = (\lambda u. v)L \xrightarrow{+}_{\beta} (\lambda u. v)(Ly) \xrightarrow{+}_{\beta} (\lambda u. v)(Lyy) \xrightarrow{+}_{\beta} \cdots$$

As we will see later, in general, there is no algorithm to decide whether a term has a β -normal form, or whether all β -reduction sequences terminate.

In general, a λ -term contains many different β -redexes. One then might wonder if there is any sort of relationship between any two terms M_1 and M_2 arising through two β -reduction sequences $M \xrightarrow{*}_{\beta} M_1$ and $M \xrightarrow{*}_{\beta} M_2$ starting with the same term M. The answer is given by the following famous theorem.

Theorem 6.2. (Church-Rosser Theorem) The following two properties hold.

(1) The λ -calculus is **confluent**: for any three λ -terms M, M_1, M_2 , if $M \xrightarrow{*}_{\beta} M_1$ and $M \xrightarrow{*}_{\beta} M_2$, then there is some λ -term M_3 such that $M_1 \xrightarrow{*}_{\beta} M_3$ and $M_2 \xrightarrow{*}_{\beta} M_3$. See Figure 6.3.



Figure 6.3: The confluence property.

(2) The λ -calculus has the Church–Rosser property: for any two λ -terms M_1, M_2 , if $M_1 \xleftarrow{*}_{\beta} M_2$, then there is some λ -term M_3 such that $M_1 \xrightarrow{*}_{\beta} M_3$ and $M_2 \xrightarrow{*}_{\beta} M_3$. See Figure 6.4.

Furthermore (1) and (2) are equivalent, and if a λ -term $M \beta$ -reduces to a β -normal form N, then N is unique (up to α -conversion).



Figure 6.4: The Church–Rosser property.

Proof. We are not aware of any easy proof of Part (1) or Part (2) of Theorem 6.2, but the equivalence of (1) and (2) is easily shown by induction.

Assume that (2) holds. Since $\xrightarrow{*}_{\beta}$ is contained in $\xleftarrow{*}_{\beta}$, if $M \xrightarrow{*}_{\beta} M_1$ and $M \xrightarrow{*}_{\beta} M_2$, then $M_1 \xleftarrow{*}_{\beta} M_2$, and since (2) holds, then there is some λ -term M_3 such that $M_1 \xrightarrow{*}_{\beta} M_3$ and $M_2 \xrightarrow{*}_{\beta} M_3$, which is (1).

To prove that (1) implies (2) we need the following observation.

Since $\stackrel{*}{\longleftrightarrow}_{\beta} = (\longrightarrow_{\beta} \cup \longrightarrow_{\beta}^{-1})^*$, we see immediately that $M_1 \stackrel{*}{\longleftrightarrow}_{\beta} M_2$ iff either

- (a) $M_1 = M_2$, or
- (b) there is some M_3 such that $M_1 \longrightarrow_{\beta} M_3$ and $M_3 \stackrel{*}{\longleftrightarrow}_{\beta} M_2$, or
- (c) there is some M_3 such that $M_3 \longrightarrow_{\beta} M_1$ and $M_3 \xleftarrow{*}_{\beta} M_2$.

Assume (1). We proceed by induction on the number of steps in $M_1 \xleftarrow{*}_{\beta} M_2$. If $M_1 \xleftarrow{*}_{\beta} M_2$, as discussed before, there are three cases.

Case a. Base case, $M_1 = M_2$. Then (2) holds with $M_3 = M_1 = M_2$.

Case b. There is some M_3 such that $M_1 \longrightarrow_{\beta} M_3$ and $M_3 \xleftarrow{*}_{\beta} M_2$. Since $M_3 \xleftarrow{*}_{\beta} M_2$ contains one less step than $M_1 \xleftarrow{*}_{\beta} M_2$, by the induction hypothesis there is some M_4 such that $M_3 \xrightarrow{*}_{\beta} M_4$ and $M_2 \xrightarrow{*}_{\beta} M_4$, and then $M_1 \longrightarrow_{\beta} M_3 \xrightarrow{*}_{\beta} M_4$ and $M_2 \xrightarrow{*}_{\beta} M_4$, proving (2). See Figure 6.5.

Case c. There is some M_3 such that $M_3 \longrightarrow_{\beta} M_1$ and $M_3 \xleftarrow{*}_{\beta} M_2$. Since $M_3 \xleftarrow{*}_{\beta} M_2$ contains one less step than $M_1 \xleftarrow{*}_{\beta} M_2$, by the induction hypothesis there is some M_4 such that $M_3 \xrightarrow{*}_{\beta} M_4$ and $M_2 \xrightarrow{*}_{\beta} M_4$. Now $M_3 \longrightarrow_{\beta} M_1$ and $M_3 \xrightarrow{*}_{\beta} M_4$, so by (1) there is some M_5 such that $M_1 \xrightarrow{*}_{\beta} M_5$ and $M_4 \xrightarrow{*}_{\beta} M_5$. Putting derivations together we get $M_1 \xrightarrow{*}_{\beta} M_5$ and $M_2 \xrightarrow{*}_{\beta} M_4$, which proves (2). See Figure 6.6.

Suppose $M \xrightarrow{*}_{\beta} N_1$ and $M \xrightarrow{*}_{\beta} N_2$ where N_1 and N_2 are both β -normal forms. Then by confluence there is some N such that $N_1 \xrightarrow{*}_{\beta} N$ and $N_2 \xrightarrow{*}_{\beta} N$. Since N_1 and N_2 are both β -normal forms, we must have $N_1 = N = N_2$ (up to α -conversion).

Barendregt gives an elegant proof of the confluence property in [5] (Chapter 11). \Box



Figure 6.5: Case b.

Another immediate corollary of the Church–Rosser theorem is that if $M \stackrel{*}{\longleftrightarrow}_{\beta} N$ and if N is a β -normal form, then in fact $M \stackrel{*}{\longrightarrow}_{\beta} N$. We leave this fact as an exerise

This fact will be useful in showing that the recursive functions are computable in the λ -calculus.

Example 6.16. Consider the term

$$M = \left(\lambda z. \left(\left(\lambda y. \left(zyy\right)\right) z \right) \right) w.$$

We have the reductions

$$M = \left(\lambda z. \left(\left(\lambda y. \left(zyy\right)\right) z \right) \right) w \longrightarrow_{\beta} \left(\lambda z. \left(zzz\right) \right) w = M_{1}$$

and

$$M = \left(\lambda z. \left(\left(\lambda y. \left(zyy \right) \right) z \right) \right) w \longrightarrow_{\beta} \left(\left(\lambda y. \left(wyy \right) \right) w \right) = M_2.$$

We have confluence because

$$M_1 = \left(\lambda z. \left(zzz\right)\right) w \longrightarrow_\beta www = M_3$$

and

$$M_2 = \left(\left(\lambda y. \left(wyy \right) \right) w \right) \longrightarrow_{\beta} www = M_3.$$



Figure 6.6: Case c.

Example 6.17. Consider the term

$$M = \left(\lambda z. \left(\left((\lambda x. (xz))u\right)\left((\lambda y. (yz))v\right)\right)\right)w.$$

We have the reduction sequences

$$M = \left(\lambda z. \left(\left((\lambda x. (xz))u\right)\left((\lambda y. (yz))v\right)\right)\right) w \longrightarrow_{\beta} \left(\lambda z. \left((uz)\left((\lambda y. (yz))v\right)\right)\right) w \longrightarrow_{\beta} \left(\lambda z. \left((uz)(vz)\right)\right) w = M_{1}$$

and

$$M = \left(\lambda z. \left(\left((\lambda x. (xz))u\right)((\lambda y. (yz))v\right)\right)\right)w$$
$$\longrightarrow_{\beta} \left(\left((\lambda x. (xw))u\right)((\lambda y. (yw))v\right) = M_{2}.$$

Confluence holds because

$$M_1 = \left(\lambda z. \left((uz)(vz) \right) \right) w \longrightarrow_{\beta} \left((uw)(vw) \right) = M_3$$

and

$$M_{2} = \left(\left((\lambda x. (xw))u \right) \left((\lambda y. (yw))v \right) \right) \longrightarrow_{\beta} \left((uw) \left((\lambda y. (yw))v \right) \right) \\ \longrightarrow_{\beta} ((uw)(vw)) = M_{3}.$$

6.3 Some Useful Combinators

In this section we provide some evidence for the expressive power of the λ -calculus.

First we make a remark about the representation of functions of several variables in the λ -calculus. The λ -calculus makes the implicit assumption that a function has a single argument. This is the idea behind application: given a term M viewed as a function and an argument N, the term (MN) represents the result of applying M to the argument N, except that the actual evaluation is suspended. Evaluation is performed by β -conversion. To deal with functions of several arguments we use a method known as *Currying* (after Haskell Curry). In this method, a function of n arguments is viewed as a function of one argument taking a function of n-1 arguments as argument. Consider the case of two arguments, the general case being similar. Consider a function $f: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$. For any fixed x, we define the function $F_x: \mathbb{N} \to \mathbb{N}$ given by

$$F_x(y) = f(x, y) \qquad y \in \mathbb{N}.$$

Using the λ -notation we can write

$$F_x = \lambda y. f(x, y),$$

and then the function $x \mapsto F_x$, which is a function from \mathbb{N} to the set of functions $[\mathbb{N} \to \mathbb{N}]$ (also denoted $\mathbb{N}^{\mathbb{N}}$), is denoted by the λ -term

$$F = \lambda x. F_x = \lambda x. (\lambda y. f(x, y)).$$

And indeed,

$$(FM)N \xrightarrow{+}_{\beta} F_MN \xrightarrow{+}_{\beta} f(M,N).$$

Remark: Currying is a way to realizing the isomorphism between the sets of functions $[\mathbb{N} \times \mathbb{N} \to \mathbb{N}]$ and $[\mathbb{N} \to [\mathbb{N} \to \mathbb{N}]]$ (or in the standard set-theoretic notation, between $\mathbb{N}^{\mathbb{N} \times \mathbb{N}}$ and $(\mathbb{N}^{\mathbb{N}})^{\mathbb{N}}$. Does this remind you of the identity

$$(m^n)^p = m^{np}?$$

It should.

The function space $[\mathbb{N} \to \mathbb{N}]$ is called an *exponential*. There is a very abstract way to view all this which is to say that we have an instance of a Cartesian closed category (CCC).

Proposition 6.3. If I, K, K_* , and S are the combinators defined by

$$\mathbf{I} = \lambda x. x$$
$$\mathbf{K} = \lambda xy. x$$
$$\mathbf{K}_* = \lambda xy. y$$
$$\mathbf{S} = \lambda xyz. (xz)(yz),$$

then for all λ -terms M, N, P, we have

$$IM \xrightarrow{+}_{\beta} M
 KMN \xrightarrow{+}_{\beta} M
 K_*MN \xrightarrow{+}_{\beta} N
 SMNP \xrightarrow{+}_{\beta} (MP)(NP)
 KI \xrightarrow{+}_{\beta} K_*
 SKK \xrightarrow{+}_{\beta} I.$$

Proof. The first equation is trivial and the second and third equations are shown as in Example 6.11, except that the bound variable y in λxy . x needs to be renamed if it occurs free in M. The fourth equation is shown as follows. We have

$$\mathbf{S}MNP = (\lambda xyz. (xz)(yz))MNP \longrightarrow_{\beta} ((\lambda yz. (xz)(yz))[x := M])NP \\ = (\lambda yz. (Mz)(yz))NP \\ \longrightarrow_{\beta} ((\lambda z. (Mz)(yz))[y := N])P \\ = (\lambda z. (Mz)(Nz))P \\ \longrightarrow_{\beta} ((Mz)(Nz))[z := P] = (MP)(NP).$$

The last equation is shown as follows.

$$\begin{aligned} \mathbf{SKK} &= \left(\lambda xyz. (xz)(yz)\right)\mathbf{KK} \\ &\longrightarrow_{\beta} \left(\left(\lambda yz. (xz)(yz)\right)[x := \mathbf{K}]\right)\mathbf{K} \\ &= \left(\left(\lambda yz. (\mathbf{K}z)(yz)\right)\mathbf{K} \\ &\longrightarrow_{\beta} \left(\left(\lambda z. (\mathbf{K}z)(yz)\right)[y := \mathbf{K}] \\ &= \lambda z. (\mathbf{K}z)(\mathbf{K}z) \\ &\stackrel{+}{\longrightarrow_{\beta}} \lambda z. z = \mathbf{I}, \end{aligned}$$

where we used the fact that $(\mathbf{K}z)(\mathbf{K}z) \xrightarrow{+}_{\beta} z$, since $\mathbf{K}MN = (\mathbf{K}M)N \xrightarrow{+}_{\beta} M$, with M = zand $N = \mathbf{K}z$. The fifth equation is left as an exercise.

The need for a conditional construct if then else such that if **T** then P else Q yields P and if **F** then P else Q yields Q is indispensable to write nontrivial programs. There is a trick to encode the boolean values **T** and **F** in the λ -calculus to mimick the above behavior of if B then P else Q, provided that B is a truth value. Since everything in the λ -calculus is a function, the booleans values **T** and **F** are encoded as λ -terms. At first, this seems quite odd, but what counts is the behavior of if B then P else Q, and it works!

The truth values \mathbf{T}, \mathbf{F} and the conditional construct if *B* then *P* else *Q* can be encoded in the λ -calculus as follows.

Proposition 6.4. Consider the combinators given by $\mathbf{T} = \mathbf{K}, \mathbf{F} = \mathbf{K}_*$, and

if then else $= \lambda b. (\lambda x. (\lambda y. (bx)y)) = \lambda bxy. bxy.$

Then for all λ -terms M, P, Q we have

If
$$M$$
 then P else $Q = (((\mathsf{if} \mathsf{then} \mathsf{else})M)P)Q \xrightarrow{+}_{\beta} (MP)Q = MPQ$

In particular,

if **T** then
$$P$$
 else $Q \xrightarrow{+}_{\beta} P$
if **F** then P else $Q \xrightarrow{+}_{\beta} Q$.

Proof. We have

if
$$M$$
 then P else $Q = (((\text{if then else})M)P)Q$

$$= (((\lambda b. (\lambda x. (\lambda y. (bx)y)))M)P)Q$$

$$\longrightarrow_{\beta} (((\lambda x. (\lambda y. (bx)y))[b := M])P)Q = ((\lambda x. (\lambda y. (Mx)y))P)Q$$

$$\longrightarrow_{\beta} ((\lambda y. (Mx)y)[x := P])Q = (\lambda y. (MP)y))Q$$

$$\longrightarrow_{\beta} ((MP)y)[y := Q] = (MP)Q.$$

The other two reductions follow by Proposition 6.3.

The boolean operations \land, \lor, \neg can be defined in terms of if then else. For example,

Not
$$b = \text{if } b$$
 then \mathbf{F} else \mathbf{T}
And $b_1b_2 = \text{if } b_1$ then (if b_2 then \mathbf{T} else \mathbf{F}) else \mathbf{F}
Or $b_1b_2 = \text{if } b_1$ then \mathbf{T} else (if b_2 then \mathbf{T} else \mathbf{F}).

Remark: If B is a term different from **T** or **F**, then if **B** then P else Q may not reduce at all, or reduce to something different from P or Q. The problem is that the conditional statement that we designed only works properly if the input B is of the correct type, namely a boolean. If we give garbage as input, then we can't expect a correct result. The λ -calculus being type-free, it is unable to check for the validity of the input. In this sense this is a defect, but it also accounts for its power.

The ability to construct ordered pairs is also crucial.

Proposition 6.5. For any two λ -terms M and N consider the combinator $\langle M, N \rangle$ and the combinators π_1 and π_2 given by

$$\langle M, N \rangle = \lambda z. \, zMN = \lambda z. \text{ if } z \text{ then } M \text{ else } N$$

 $\pi_1 = \lambda z. \, z\mathbf{K}$
 $\pi_2 = \lambda z. \, z\mathbf{K}_*.$

Then

$$\pi_1 \langle M, N \rangle \xrightarrow{+}_{\beta} M$$

$$\pi_2 \langle M, N \rangle \xrightarrow{+}_{\beta} N$$

$$\langle M, N \rangle \mathbf{T} \xrightarrow{+}_{\beta} M$$

$$\langle M, N \rangle \mathbf{F} \xrightarrow{+}_{\beta} N.$$

The proof of the first equation is given in Example 6.18 and the proof of the other three is left as an exercise.

Example 6.18. We have

$$\pi_1 \langle M, N \rangle = (\lambda z. z \mathbf{K}) (\lambda z. z M N)$$

$$\longrightarrow_\beta (z \mathbf{K}) [z := \lambda z. z M N] = (\lambda z. z M N) \mathbf{K}$$

$$\longrightarrow_\beta (z M N) [z := \mathbf{K}] = \mathbf{K} M N \stackrel{+}{\longrightarrow}_\beta M,$$

by Proposition 6.3.

Observe that if we define the combinator

$$\mathbf{pair} = \lambda x. \left(\lambda y. \left(\lambda z. \left(zx \right) y \right) \right) = \lambda xyz. \, zxy,$$

then

$$\operatorname{pair} MN \xrightarrow{+}_{\beta} \lambda z. \, zMN = \langle M, N \rangle.$$

The combinator **pair** is very closely related to the combinator if then else = λzxy . zxy. Both combinators contain the term zxy, but in **pair**, the variables are abstracted in the order xyz, and in if then else, they are abstracted in the order zxy. So

$$\operatorname{pair} PQM \xrightarrow{+}_{\beta} MPQ$$
(if then else)MPQ \xrightarrow{+}_{\beta} MPQ.

In the next section we show how to encode the natural numbers in the λ -calculus and how to compute various arithmetical functions.

6.4 Representing the Natural Numbers

Historically the natural numbers were first represented in the λ -calculus by Church in the 1930's. Later in 1976 Barendregt came up with another representation which is more convenient to show that the recursive functions are λ -definable. We start with Church's representation.

First, given any two λ -terms F and M, for any natural number $n \in \mathbb{N}$, we define $F^n(M)$ inductively as follows.

$$F^{0}(M) = M$$

$$F^{n+1}(M) = F(F^{n}(M)).$$

Observe that

$$F^{n}(M) = \underbrace{F\left(F\left(\cdots\left(F\right)M\right)\cdots\right)}_{n}$$

Definition 6.14. (Church Numerals) The *Church numerals* $\mathbf{c}_0, \mathbf{c}_1, \mathbf{c}_2, \ldots$ are defined by

$$\mathbf{c}_n = \lambda f x. f^n(x).$$

So $\mathbf{c}_0 = \lambda f x. x = \mathbf{K}_*, \ \mathbf{c}_1 = \lambda f x. f x, \ \mathbf{c}_2 = \lambda f x. f(fx), \ \mathbf{c}_3 = \lambda f x. f(f(fx)), \ etc.$ The Church numerals are β -normal forms.

Observe that

$$\mathbf{c}_0 F z = (\mathbf{c}_0 F) z = ((\lambda f x. x) F) z \xrightarrow{+}_{\beta} z \tag{(1)}$$

$$\mathbf{c}_n F z = (\mathbf{c}_n F) z = ((\lambda f x. f^n(x)) F) z \xrightarrow{+}_{\beta} F^n(z), \quad n \ge 1.$$
 (†2)

This shows that \mathbf{c}_n iterates *n* times the function represented by the term *F* on initial input *z*. This is the trick behind the definition of the Church numerals. This suggests the following definition.

Definition 6.15. The *iteration combinator* **Iter** is given by

$$\mathbf{Iter} = \lambda n f x. n f x.$$

Observe that

Iter
$$\mathbf{c}_n F X = (\operatorname{Iter} \mathbf{c}_n F) X \xrightarrow{+}_{\beta} (\mathbf{c}_n F) X \xrightarrow{+}_{\beta} F^n X,$$
 (†3)

that is, the result of iterating F for n steps starting with the initial term X.

Remark: The combinator **Iter** is actually equal to the combinator

if then else
$$= \lambda bxy.bxy$$

of Definition 6.4. Remarkably, if n (or b) is a boolean, then this combinator behaves like a conditional, but if n (or b) is a Church numeral, then it behaves like an iterator. A closely related combinator is **Fold**, defined by

$$\mathbf{Fold} = \lambda x fn. \, nxf.$$

The only difference is that the abstracted variables are listed in the order x, f, n, instead of n, f, x. In fact,

Fold = pair,

as defined just after Example 6.18. This version of an iterator is used when the Church numerals are defined as $\lambda x f. f^n(x)$ instead of $\lambda f x. f^n(x)$, where x and f are permuted in the λ -binder.

Let us show how some basic functions on the natural numbers can be defined.

Example 6.19. We begin with the constant function \mathbf{Z} given by $\mathbf{Z}(n) = 0$ for all $n \in \mathbb{N}$. We claim that $\mathbf{Z}_{\mathbf{c}} = \lambda x. \mathbf{c}_{\mathbf{0}}$ works. Indeed, we have

$$\mathbf{Z}_{\mathbf{c}} \mathbf{c}_n = (\lambda x. \mathbf{c}_{\mathbf{0}}) \mathbf{c}_n \longrightarrow_{\beta} \mathbf{c}_{\mathbf{0}} [x := \mathbf{c}_n] = \mathbf{c}_{\mathbf{0}},$$

since $\mathbf{c_0}$ is a closed term.

Example 6.20. The successor function **Succ** is given by

$$\mathbf{Succ}(n) = n+1$$

We claim that

$$\mathbf{Succ}_{\mathbf{c}} = \lambda n f x. f(n f x)$$

computes **Succ**. Indeed we have

Succ_c
$$\mathbf{c}_n = (\lambda n f x. f(n f x)) \mathbf{c}_n$$

 $\longrightarrow_{\beta} (\lambda f x. f(n f x)) [n := \mathbf{c}_n] = \lambda f x. f(\mathbf{c}_n f x)$
 $\longrightarrow_{\beta} \lambda f x. f(f^n(x))$
 $= \lambda f x. f^{n+1}(x) = \mathbf{c}_{n+1}.$

Example 6.21. The function **IsZero** which tests whether a natural number is equal to 0 is defined by the combinator

$$\mathbf{IsZero_c} = \lambda x. \, x(\mathbf{K} \, \mathbf{F}) \mathbf{T}.$$

We have

$$\mathbf{IsZero_c} \mathbf{c}_n = \left(\lambda x. x(\mathbf{K} \mathbf{F})\mathbf{T}\right) \mathbf{c}_n \xrightarrow{+}_{\beta} \left(\lambda x. x(\mathbf{K} \mathbf{F})\mathbf{T}\right) [x := \mathbf{c}_n (\mathbf{K} \mathbf{F})\mathbf{T} \xrightarrow{+}_{\beta} (\mathbf{K} \mathbf{F})^n \mathbf{T},$$

and the rest of the proof is left as an exercise.

Addition and multiplication are a little more tricky to define.

Proposition 6.6. (J.B. Rosser) Define Add and Mult as the combinators given by

$$\mathbf{Add} = \lambda mnfx. mf(nfx)$$
$$\mathbf{Mult} = \lambda mnz. m(nz).$$
We have

$$\operatorname{\mathbf{Add}} \mathbf{c}_m \mathbf{c}_n \xrightarrow{+}_{eta} \mathbf{c}_{m+n}$$
 $\operatorname{\mathbf{Mult}} \mathbf{c}_m \mathbf{c}_n \xrightarrow{+}_{eta} \mathbf{c}_{m*n}$

for all $m, n \in \mathbb{N}$.

Proof. We have

Add
$$\mathbf{c}_m \mathbf{c}_n = (\lambda mnfx. mf(nfx))\mathbf{c}_m \mathbf{c}_n$$

 $\xrightarrow{+}_{\beta} (\lambda fx. \mathbf{c}_m f(\mathbf{c}_n fx))$
 $\xrightarrow{+}_{\beta} \lambda fx. f^m(f^n(x))$
 $= \lambda fx. f^{m+n}(x) = \mathbf{c}_{m+n}.$

For multiplication we need to prove by induction on m that

$$(\mathbf{c}_n x)^m(y) \xrightarrow{*}_{\beta} x^{m*n}(y). \tag{(*)}$$

If m = 0, then both sides are equal to y.

For the induction step, we have

$$(\mathbf{c}_n x)^{m+1}(y) = \mathbf{c}_n x((\mathbf{c}_n x)^m(y))$$

$$\stackrel{*}{\longrightarrow}_{\beta} \mathbf{c}_n x(x^{m*n}(y))$$
 by induction

$$\stackrel{*}{\longrightarrow}_{\beta} x^n(x^{m*n}(y))$$

$$= x^{n+m*n}(y) = x^{(m+1)*n}(y).$$

We now have

Mult
$$\mathbf{c}_m \mathbf{c}_n = (\lambda mnz. m(nz))\mathbf{c}_m \mathbf{c}_n$$

 $\xrightarrow{+}_{\beta} \lambda z. (\mathbf{c}_m(\mathbf{c}_n z))$
 $= \lambda z. ((\lambda fy. f^m(y))(\mathbf{c}_n z))$
 $\xrightarrow{+}_{\beta} \lambda zy. (\mathbf{c}_n z)^m(y),$

and since we proved in (*) that

$$(\mathbf{c}_n z)^m(y) \xrightarrow{*}_{\beta} z^{m*n}(y),$$

we get

Mult
$$\mathbf{c}_m \mathbf{c}_n \xrightarrow{+}_{\beta} \lambda zy. (\mathbf{c}_n z)^m (y) \xrightarrow{+}_{\beta} \lambda zy. z^{m*n}(y) = \mathbf{c}_{m*n},$$

which completes the proof.

As an exercise the reader should prove that addition and multiplication can also be defined in terms of **Iter** (see Definition 6.15) by

 $\mathbf{Add} = \lambda mn. \mathbf{Iter} \, m \, \mathbf{Succ_c} \, n$ $\mathbf{Mult} = \lambda mn. \mathbf{Iter} \, m \, (\mathbf{Add} \, n) \, \mathbf{c}_0.$

The above expressions are close matches to the primitive recursive definitions of addition and multiplication. To check that they work, prove that

 $\operatorname{Add} \mathbf{c}_m \, \mathbf{c}_n \stackrel{+}{\longrightarrow}_{eta} (\operatorname{\mathbf{Succ}}_{\mathbf{c}})^m (\mathbf{c}_n) \stackrel{+}{\longrightarrow}_{eta} \mathbf{c}_{m+n}$

and

$$\operatorname{\mathbf{Mult}} \mathbf{c}_m \, \mathbf{c}_n \stackrel{+}{\longrightarrow}_{\beta} (\operatorname{\mathbf{Add}} \mathbf{c}_n)^m (\mathbf{c}_0) \stackrel{+}{\longrightarrow}_{\beta} \mathbf{c}_{m*n}$$

Example 6.22. Rosser defined the exponential function

$$\exp(m, n) = m^n, \quad m \ge 0, \ n \ge 1,$$

using the combinator

$$\exp = \lambda xy \cdot (yx).$$

Observe that

$$\exp \mathbf{c}_m \, \mathbf{c}_n = (\lambda x y. (y x)) \, \mathbf{c}_m \, \mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{c}_n \mathbf{c}_m = (\lambda f x. f^n(x)) \mathbf{c}_m \\ \xrightarrow{+}_{\beta} \lambda x. (\mathbf{c}_m)^n(x).$$

To finish the proof there is a tricky point, which is that we need to use conversion instead of reduction. We prove that for $n \ge 1$,

$$(\mathbf{c}_m)^n(x) \xleftarrow{*}_{\beta} \mathbf{c}_{m^n}(x).$$

This is done by induction on n, starting from n = 1. For the induction step

$$(\mathbf{c}_m)^{n+1}(x) = \mathbf{c}_m((\mathbf{c}_m)^n(x)) = (\lambda f y. f^m(y))((\mathbf{c}_m)^n(x))$$

$$\stackrel{+}{\longrightarrow}_{\beta} \lambda y. ((\mathbf{c}_m)^n(x))^m(y)$$

$$\stackrel{*}{\longleftrightarrow}_{\beta} \lambda y. (\mathbf{c}_{m^n}(x))^m(y).$$

By (*), we have

$$(\mathbf{c}_p x)^m(y) \xrightarrow{*}_{\beta} x^{m*p}(y),$$

so with $p = m^n$, we get

$$\lambda y. (\mathbf{c}_{m^n}(x))^m(y) \xrightarrow{+}_{\beta} \lambda y. x^{m*m^n}(y) = \lambda y. x^{m^{n+1}}(y) \longleftrightarrow_{\beta} (\lambda f y. f^{m^{n+1}}(y)) x = \mathbf{c}_{n^{m+1}}(x),$$

so finally

$$(\mathbf{c}_m)^{n+1}(x) \xleftarrow{*}_{\beta} \mathbf{c}_{m^{n+1}}(x)$$

Putting everything together, we have

$$\exp \mathbf{c}_m \, \mathbf{c}_n \stackrel{+}{\longrightarrow}_{\beta} \lambda x. \, (\mathbf{c}_m)^n(x) \stackrel{*}{\longleftrightarrow}_{\beta} \lambda x. \, \mathbf{c}_{m^n}(x).$$

This is not exactly what we want! The term on the right-hand should be \mathbf{c}_{m^n} . To finish the proof, we use the following property which is easily shown. If M is a λ -term of the form $M = \lambda y. M'$ and $x \notin FV(M)$, then $\lambda x. (Mx) \xrightarrow{+}_{\beta} M$. In summary, we have

$$\exp \mathbf{c}_m \, \mathbf{c}_n \stackrel{*}{\longleftrightarrow}_{\beta} \mathbf{c}_{m^n}.$$

Since the term on the right-hand side is a β -normal form, by the Church-Rosser theorem, actually

$$\exp \mathbf{c}_m \, \mathbf{c}_n \stackrel{+}{\longrightarrow}_{\beta} \mathbf{c}_{m^n}.$$

Example 6.23. A function that plays an important technical role is the predecessor function **Pred** defined such that

$$\mathbf{Pred}(0) = 0$$
$$\mathbf{Pred}(n+1) = n.$$

It turns out that it is quite tricky to define this function in terms of the Church numerals. Church and his students struggled for a while until Kleene found a solution in his famous 1936 paper. The story goes that Kleene found his solution when he was sitting in the dentist's chair! The trick is to make use of pairs. Kleene's solution is

$$\mathbf{Pred}_{\mathbf{K}} = \lambda n. \, \pi_2(\mathbf{Iter} \, n \, (\lambda z. \, \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle) \, \langle \mathbf{c}_0, \mathbf{c}_0 \rangle).$$

In the above expression, **Iter** is applied to the three arguments n, $(\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle)$, and $\langle \mathbf{c}_0, \mathbf{c}_0 \rangle$. Thus we have

$$\mathbf{Pred}_{\mathbf{K}} \mathbf{c}_n \xrightarrow{+}_{\beta} \pi_2((\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle)^n \langle \mathbf{c}_0, \mathbf{c}_0 \rangle).$$

The reason this works is that we see immediately that

$$(\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle)^0 \langle \mathbf{c}_0, \mathbf{c}_0 \rangle \xrightarrow{+}_{\beta} \langle \mathbf{c}_0, \mathbf{c}_0 \rangle,$$

and we can prove by induction that

$$(\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle)^{n+1} \langle \mathbf{c}_0, \mathbf{c}_0 \rangle \xrightarrow{+}_{\beta} \langle \mathbf{c}_{n+1}, \mathbf{c}_n \rangle.$$

Then we have

$$\operatorname{\mathbf{Pred}}_{\mathbf{K}} \mathbf{c}_0 \stackrel{+}{\longrightarrow}_{\beta} \pi_2(\langle \mathbf{c}_0, \mathbf{c}_0 \rangle) = \mathbf{c}_0$$

and

$$\operatorname{\mathbf{Pred}}_{\mathbf{K}} \mathbf{c}_{n+1} \stackrel{+}{\longrightarrow}_{eta} \pi_2(\langle \mathbf{c}_{n+1}, \mathbf{c}_n \rangle) = \mathbf{c}_n$$

For the base case n = 0 we get

$$\begin{aligned} (\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1}z), \pi_{1}z \rangle) \langle \mathbf{c}_{0}, \mathbf{c}_{0} \rangle &\longrightarrow_{\beta} \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1} \langle \mathbf{c}_{0}, \mathbf{c}_{0} \rangle), \pi_{1} \langle \mathbf{c}_{0}, \mathbf{c}_{0} \rangle \rangle \\ &\stackrel{+}{\longrightarrow}_{\beta} \langle \mathbf{Succ}_{\mathbf{c}}(\mathbf{c}_{0}), \mathbf{c}_{0} \rangle \\ &\stackrel{+}{\longrightarrow}_{\beta} \langle \mathbf{c}_{1}, \mathbf{c}_{0} \rangle. \end{aligned}$$

For the induction step, we have

$$(\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1}z), \pi_{1}z \rangle)^{n+2} \langle \mathbf{c}_{0}, \mathbf{c}_{0} \rangle$$

= $(\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1}z), \pi_{1}z \rangle) ((\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1}z), \pi_{1}z \rangle)^{n+1} \langle \mathbf{c}_{0}, \mathbf{c}_{0} \rangle)$
 $\xrightarrow{+}_{\beta} (\lambda z. \langle \mathbf{Succ}_{\mathbf{c}}(\pi_{1}z), \pi_{1}z \rangle) \langle \mathbf{c}_{n+1}, \mathbf{c}_{n} \rangle$
 $\xrightarrow{+}_{\beta} \langle \mathbf{Succ}_{\mathbf{c}}(\mathbf{c}_{n+1}), \mathbf{c}_{n+1} \rangle \xrightarrow{+}_{\beta} \langle \mathbf{c}_{n+2}, \mathbf{c}_{n+1} \rangle.$

Here is another tricky solution due to J. Velmans (according to H. Barendregt):

$$\mathbf{Pred}_{\mathbf{c}} = \lambda xyz. \ x(\lambda pq. q(py))(\mathbf{K}z)\mathbf{I}.$$

We leave it to the reader to verify that it works.

The ability to construct pairs together with the **Iter** combinator allows the definition of a large class of functions, because **Iter** is "type-free" in its second and third arguments so it really allows higher-order primitive recursion.

Example 6.24. The factorial function defined such that

$$0! = 1$$

(n+1)! = (n+1)n!

can be defined. First we define h by

$$h = \lambda m n.$$
 Mult Succ_c $n m$

and then

$$\mathbf{fact} = \lambda n. \, \pi_1(\mathbf{Iter} \, n \, (\lambda z. \, \langle h(\pi_1 z) \, (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle) \, \langle \mathbf{c}_1, \mathbf{c}_0 \rangle)$$

The above expression, **Iter** is applied to the arguments n, $(\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)$, and $\langle \mathbf{c}_1, \mathbf{c}_0 \rangle$. We have

$$h \mathbf{c}_{n!} \mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{Mult} \operatorname{Succ}_{\mathbf{c}} \mathbf{c}_n \mathbf{c}_{n!} \xrightarrow{+}_{\beta} \mathbf{Mult} \mathbf{c}_{n+1} \mathbf{c}_{n!} \xrightarrow{+}_{\beta} \mathbf{c}_{(n+1)!},$$

and

fact
$$\mathbf{c}_n \xrightarrow{+}_{\beta} \pi_1((\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^n \langle \mathbf{c}_1, \mathbf{c}_0 \rangle).$$

This works because

$$(\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^0 \langle \mathbf{c}_1, \mathbf{c}_0 \rangle \xrightarrow{+}_{\beta} \langle \mathbf{c}_1, \mathbf{c}_0 \rangle = \langle \mathbf{c}_{0!}, \mathbf{c}_0 \rangle,$$

and by induction,

$$(\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^{n+1} \langle \mathbf{c}_1, \mathbf{c}_0 \rangle \xrightarrow{+}_{\beta} \langle \mathbf{c}_{(n+1)!}, \mathbf{c}_{n+1} \rangle.$$

Then we have

$$\begin{aligned} \mathbf{fact} \, \mathbf{c}_n & \xrightarrow{+}_{\beta} \pi_1((\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^n \langle \mathbf{c}_1, \mathbf{c}_0 \rangle) \\ & \xrightarrow{+}_{\beta} \pi_1(\langle \mathbf{c}_{n!}, \mathbf{c}_n \rangle) \xrightarrow{+}_{\beta} \mathbf{c}_{n!}. \end{aligned}$$

For the induction step, we have

$$\begin{aligned} (\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^{n+2} \langle \mathbf{c}_1, \mathbf{c}_0 \rangle \\ &= (\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle) \Big(\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^{n+1} \langle \mathbf{c}_1, \mathbf{c}_0 \rangle \Big) \\ & \stackrel{+}{\longrightarrow}_{\beta} (\lambda z. \langle h(\pi_1 z) (\pi_2 z), \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle) \langle \mathbf{c}_{(n+1)!}, \mathbf{c}_{n+1} \rangle \\ & \stackrel{+}{\longrightarrow}_{\beta} \langle h \, \mathbf{c}_{(n+1)!} \, \mathbf{c}_{n+1}, \mathbf{Succ}_{\mathbf{c}}(\mathbf{c}_{n+1}) \rangle \stackrel{+}{\longrightarrow}_{\beta} \langle \mathbf{c}_{(n+2)!}, \mathbf{c}_{n+2} \rangle. \end{aligned}$$

Barendregt came up with another way of representing the natural numbers that makes things easier.

Definition 6.16. (Barendregt Numerals) The *Barendregt numerals* \mathbf{b}_n are defined as follows:

$$\mathbf{b}_0 = \mathbf{I} = \lambda x. \, x$$
$$\mathbf{b}_{n+1} = \langle \mathbf{F}, \mathbf{b}_n \rangle.$$

The Barendregt numerals are β -normal forms. Barendregt uses the notation $\lceil n \rceil$ instead of \mathbf{b}_n but this notation is also used for the Church numerals by other authors so we prefer using \mathbf{b}_n (which is consistent with the use of \mathbf{c}_n for the Church numerals). The Barendregt numerals are tuples, which makes operating on them simpler than the Church numerals which encode n as the composition f^n .

Proposition 6.7. The functions **Succ**, **Pred** and **IsZero** are defined in terms of the Barendregt numerals by the combinators

$$\mathbf{Succ_b} = \lambda x. \langle \mathbf{F}, x \rangle$$
$$\mathbf{Pred_b} = \lambda x. (x\mathbf{F})$$
$$\mathbf{IsZero_b} = \lambda x. (x\mathbf{T}),$$

and we have

$$\begin{split} \mathbf{Succ_b} \, \mathbf{b}_n & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{b}_{n+1} \\ \mathbf{Pred_b} \, \mathbf{b}_0 & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{b}_0 \\ \mathbf{Pred_b} \, \mathbf{b}_{n+1} & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{b}_n \\ \mathbf{IsZero_b} \, \mathbf{b}_0 & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{T} \\ \mathbf{IsZero_b} \, \mathbf{b}_{n+1} & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{F}. \end{split}$$

The proof is left as an exercise.

Since there is an obvious bijection between the Church combinators and the Barendregt combinators there should be combinators effecting the translations. Indeed we have the following result.

Proposition 6.8. The combinator T given by

$$T = \lambda x. \left(x \mathbf{Succ_b} \right) \mathbf{b}_0$$

has the property that

$$T \mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{b}_n \quad \text{for all } n \in \mathbb{N}.$$

Proof. We proceed by induction on n. For the base case

For the induction step,

Thus we need to prove that

$$\mathbf{Succ}_{\mathbf{b}}^{n}(\mathbf{b}_{0}) \stackrel{+}{\longrightarrow}_{\beta} \mathbf{b}_{n}.$$
(*)

For the base case n = 0, the left-hand side reduces to \mathbf{b}_0 . For the induction step, we have

$$\begin{aligned} \mathbf{Succ_b}^{n+1}(\mathbf{b}_0) &= \mathbf{Succ_b}(\mathbf{Succ_b}^n(\mathbf{b}_0)) \\ & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Succ_b}(\mathbf{b}_n) & \text{by induction} \\ & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{b}_{n+1}, \end{aligned}$$

which concludes the proof.

There is also a combinator defining the inverse map but it is defined recursively and we don't know how to express recursive definitions in the λ -calculus. This is achieved by using fixed-point combinators.

Remark: With some work, it is possible to show that lists and trees can be represented in the λ -calculus.

6.5 Fixed-Point Combinators and Recursively Defined Functions

Fixed-point combinators are the key to the definability of recursive functions in the λ -calculus. We begin with the **Y**-combinator due to Curry.

Proposition 6.9. (Curry Y-combinator) If we define the combinator Y as

 $\mathbf{Y} = \lambda f. \, (\lambda x. \, f(xx))(\lambda x. \, f(xx)),$

then for any λ -term F we have

$$F(\mathbf{Y}F) \xleftarrow{*}_{\beta} \mathbf{Y}F.$$

We say that $\mathbf{Y}F$ is a fixed-point of F.

Proof. Write $W = \lambda x. F(xx)$. We have

$$F(\mathbf{Y}F) = F\Big(\big(\lambda f.\,(\lambda x.\,f(xx))(\lambda x.\,f(xx))\big)F\Big) \longrightarrow_{\beta} F\Big((\lambda x.\,F(xx))(\lambda x.\,F(xx))\big) = F(WW),$$

and

$$\mathbf{Y}F = \left(\lambda f. \left(\lambda x. f(xx)\right)(\lambda x. f(xx))\right)F \longrightarrow_{\beta} (\lambda x. F(xx))(\lambda x. F(xx)) = (\lambda x. F(xx))W \longrightarrow_{\beta} F(WW).$$

Therefore $F(\mathbf{Y}F) \xleftarrow{*}{\longleftrightarrow}_{\beta} \mathbf{Y}F$, as claimed.

Observe that neither $F(\mathbf{Y}F) \xrightarrow{+}_{\beta} \mathbf{Y}F$ nor $\mathbf{Y}F \xrightarrow{+}_{\beta}F(\mathbf{Y}F)$. This is a slight disadvantage of the Curry **Y**-combinator. Turing came up with another fixed-point combinator that does not have this problem.

Proposition 6.10. (Turing Θ -combinator) If we define the combinator Θ as

 $\Theta = (\lambda xy. y(xxy))(\lambda xy. y(xxy)),$

then for any λ -term F we have

$$\boldsymbol{\Theta} F \stackrel{+}{\longrightarrow}_{\beta} F(\boldsymbol{\Theta} F).$$

We say that ΘF is a fixed-point of F.

Proof. If we write $A = (\lambda xy, y(xxy))$, then $\Theta = AA$. We have

$$\Theta F = (AA)F = ((\lambda xy. y(xxy))A)F$$
$$\longrightarrow_{\beta} (\lambda y. y(AAy))F$$
$$\longrightarrow_{\beta} F(AAF)$$
$$= F(\Theta F),$$

as claimed.

	_	_	_	

Both **Y** and Θ have *no* β -normal form.

Now we show how to use the fixed-point combinators to represent recursively-defined functions in the λ -calculus.

Example 6.25. There is a combinator G such that

$$GX \xrightarrow{+}_{\beta} X(XG)$$
 for all X

Informally, the idea is to consider the "functional" $F = \lambda g x. x(xg)$ and to find a fixed-point of this functional. Pick

$$G = \mathbf{\Theta} \lambda g x. \, x(xg) = \mathbf{\Theta} F$$

Since by Proposition 6.10 we have $G = \Theta F \xrightarrow{+}_{\beta} F(\Theta F) = FG$, and we also have

$$FG = (\lambda gx. x(xg))G \longrightarrow_{\beta} \lambda x. x(xG)$$

so $G \xrightarrow{+}_{\beta} FG \xrightarrow{+}_{\beta} \lambda x. x(xG)$, which implies

$$GX \xrightarrow{+}_{\beta} (\lambda x. x(xG))X \longrightarrow_{\beta} X(XG).$$

Example 6.26. In general, if we want to define a function G recursively such that

$$GX \xrightarrow{+}_{\beta} M(X,G)$$

where M(X,G) is λ -term containing recursive calls to G applied to various functions of X, we let $F = \lambda g x. M(x,g)$ and

$$G = \mathbf{\Theta} F.$$

Then we have

$$G \xrightarrow{+}_{\beta} FG = (\lambda gx. M(x, g))G \longrightarrow_{\beta} \lambda x. M(x, g)[g := G] = \lambda x. M(x, G)$$

 \mathbf{SO}

$$GX \xrightarrow{+}_{\beta} (\lambda x. M(x, G)) X \longrightarrow_{\beta} M(x, G)[x := X] = M(X, G),$$

as desired.

Example 6.27. Here is how the factorial function can be defined (using the Church numerals). Let

$$F = \lambda g n$$
. if IsZero_c n then c_1 else Mult $n g(\operatorname{Pred}_{c} n)$

Then the term $G = \Theta F$ defines the factorial function.

Since G is a fixed-point of F we have $G \xrightarrow{+}_{\beta} FG$. If n = 0, we have

$$G \mathbf{c}_{0} \xrightarrow{+}_{\beta} FG \mathbf{c}_{0}$$

$$\xrightarrow{+}_{\beta} \text{ if } \mathbf{IsZero}_{\mathbf{c}} \mathbf{c}_{0} \text{ then } \mathbf{c}_{1} \text{ else } \mathbf{Mult} \mathbf{c}_{0} G(\mathbf{Pred}_{\mathbf{c}} \mathbf{c}_{0})$$

$$\xrightarrow{+}_{\beta} \text{ if } \mathbf{T} \text{ then } \mathbf{c}_{1} \text{ else } \mathbf{Mult} \mathbf{c}_{0} (G \mathbf{c}_{0})$$

$$\xrightarrow{+}_{\beta} \mathbf{c}_{1}.$$

So, $G \mathbf{c}_0 \xrightarrow{+}_{\beta} \mathbf{c}_1$, which corresponds to 0! = 1.

Otherwise, if $n \ge 1$, we have

$$\begin{array}{l} G \, \mathbf{c}_{n} \stackrel{+}{\longrightarrow}_{\beta} \left(FG \right) \mathbf{c}_{n} \\ \stackrel{+}{\longrightarrow}_{\beta} \text{ if } \mathbf{IsZero}_{\mathbf{c}} \, \mathbf{c}_{n} \text{ then } \mathbf{c}_{1} \text{ else } \mathbf{Mult} \, \mathbf{c}_{n} \, G(\mathbf{Pred}_{\mathbf{c}} \, \mathbf{c}_{n}) \\ \stackrel{+}{\longrightarrow}_{\beta} \text{ if } \mathbf{F} \text{ then } \mathbf{c}_{1} \text{ else } \mathbf{Mult} \, \mathbf{c}_{n} \left(G \, \mathbf{c}_{n-1} \right) \\ \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Mult} \, \mathbf{c}_{n} \left(G \, \mathbf{c}_{n-1} \right) \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Mult} \, \mathbf{c}_{n} \left(F \, G \right) \, \mathbf{c}_{n-1} \stackrel{+}{\longrightarrow}_{\beta} \cdots \\ \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Mult} \, \mathbf{c}_{n} \left(\mathbf{Mult} \, \mathbf{c}_{n-1} \left(G \, \mathbf{c}_{n-2} \right) \right) \stackrel{+}{\longrightarrow}_{\beta} \cdots \\ \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Mult} \, \mathbf{c}_{n} \left(\mathbf{Mult} \, \mathbf{c}_{n-1} \left(\mathbf{Mult} \, \mathbf{c}_{n-2} (\cdots \left(\mathbf{Mult} \, \mathbf{c}_{2} \left(\mathbf{Mult} \, \mathbf{c}_{1} (G \, \mathbf{c}_{0}) \right) \right) \cdots \right)) \right) \\ \stackrel{+}{\longrightarrow}_{\beta} \mathbf{Mult} \, \mathbf{c}_{n} \left(\mathbf{Mult} \, \mathbf{c}_{n-1} \left(\mathbf{Mult} \, \mathbf{c}_{n-2} (\cdots \left(\mathbf{Mult} \, \mathbf{c}_{2} \left(\mathbf{Mult} \, \mathbf{c}_{1} (\mathbf{c}_{1}) \right) \right) \cdots \right)) \right) \end{array}$$

As usual with recursive definitions there is no guarantee that the function that we obtain terminates for all input.

Example 6.28. For example, if we consider

$$F = \lambda g n.$$
 if $\mathbf{IsZero}_{\mathbf{c}} n$ then \mathbf{c}_1 else $\mathbf{Mult} n g(\mathbf{Succ}_{\mathbf{c}} n)$,

then for $n \ge 1$, the reduction behavior is

$$G\mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{Mult} \, \mathbf{c}_n \, G \, \mathbf{c}_{n+1},$$

which does not terminate.

We leave it as an exercise to show that the inverse of the function T mapping the Church numerals to the Barendregt numerals is given by the combinator

$$T^{-1} = \Theta(\lambda f x. \text{ if } \mathbf{IsZero}_{\mathbf{b}} x \text{ then } \mathbf{c}_0 \text{ else } \mathbf{Succ}_{\mathbf{c}}(f(\mathbf{Pred}_{\mathbf{b}} x)).$$

It is remarkable that the λ -calculus allows the implementation of *arbitrary recursion* without a stack, just using λ -terms as the data-structure and β -reduction. This does not mean that this evaluation mechanism is efficient but this is another story (as well as evaluation strategies, which have to do with parameter-passing strategies, call-by-name, call-by-value).

Now we have all the ingredients to show that all the total computable functions are definable in the λ -calculus. It is also true that all the partial computable functions are definable in the λ -calculus, but this is significantly harder to prove. The difficulty is that if F is the λ -term computing $f(n_1, \ldots, n_m)$ when it is defined, then if $f(n_1, \ldots, n_m)$ is undefined, we need to prove that $F \mathbf{c}_{n_1} \ldots \mathbf{c}_{n_m}$ does not have a β -normal form. This involves a trick and the use of a deep theorem about quasi-leftmost reductions.

6.6 λ -Definability of the Total Computable Functions

Let us begin by reviewing the definition of the computable functions (recursive functions) (à la Herbrand–Gödel–Kleene). For our purposes it suffices to consider functions (partial or total) $f: \mathbb{N}^n \to \mathbb{N}$ as opposed to the more general case of functions $f: (\Sigma^*)^n \to \Sigma^*$ defined on strings.

Definition 6.17. The base functions are the functions Z, S, P_i^n defined as follows.

(1) The constant zero function Z such that

$$Z(n) = 0,$$
 for all $n \in \mathbb{N}$.

(2) The successor function S such that

S(n) = n + 1, for all $n \in \mathbb{N}$.

(3) For every $n \ge 1$ and every i with $1 \le i \le n$, the projection function P_i^n such that

$$P_i^n(x_1,\ldots,x_n) = x_i, \qquad x_1,\ldots,x_n \in \mathbb{N}.$$

Next comes (extended) composition.

Definition 6.18. Given any partial or total function $g: \mathbb{N}^m \to \mathbb{N}$ $(m \ge 1)$ and any m partial or total functions $h_i: \mathbb{N}^n \to \mathbb{N}$ $(n \ge 1)$, the composition of g and h_1, \ldots, h_m , denoted $g \circ (h_1, \ldots, h_m)$, is the partial or total function function $f: \mathbb{N}^n \to \mathbb{N}$ given by

$$f(x_1,\ldots,x_n) = g(h_1(x_1,\ldots,x_n),\ldots,h_m(x_1,\ldots,x_n)), \qquad x_1,\ldots,x_n \in \mathbb{N}.$$

If g or any of the h_i are partial functions, then $f(x_1, \ldots, x_n)$ is defined if and only if all $h_i(x_1, \ldots, x_n)$ are defined and $g(h_1(x_1, \ldots, x_n), \ldots, h_m(x_1, \ldots, x_n))$ is defined.



Note that even if g "ignores" one of its arguments, say the *i*th one, $g(h_1(x_1, \ldots, x_n), \ldots, h_m(x_1, \ldots, x_n))$ is undefined if $h_i(x_1, \ldots, x_n)$ is undefined.

Definition 6.19. Given any partial or total functions $g: \mathbb{N}^m \to \mathbb{N}$ and $h: \mathbb{N}^{m+2} \to \mathbb{N}$ $(m \ge 1)$, the partial or total function function $f: \mathbb{N}^{m+1} \to \mathbb{N}$ is defined by *primitive recursion* from g and h if f is given by

$$f(0, x_1, \dots, x_m) = g(x_1, \dots, x_m)$$

$$f(n+1, x_1, \dots, x_m) = h(f(n, x_1, \dots, x_m), n, x_1, \dots, x_m)$$

for all $n, x_1, \ldots, x_m \in \mathbb{N}$. If m = 0, then g is some fixed natural number and we have

$$f(0) = g$$

$$f(n+1) = h(f(n), n).$$

It can be shown that if g and h are total functions, then so is f. Note that the second clause of the definition of primitive recursion is

$$f(n+1, x_1, \dots, x_m) = h(f(n, x_1, \dots, x_m), n, x_1, \dots, x_m)$$
(*1)

but in an earlier definition it was

$$f(n+1, x_1, \dots, x_m) = h(n, f(n, x_1, \dots, x_m), x_1, \dots, x_m),$$
(*2)

with the first two arguments of h permuted. Since

$$h \circ (P_2^{m+2}, P_1^{m+2}, P_3^{m+2}, \dots, P_{m+2}^{m+2})(n, f(n, x_1, \dots, x_m), x_1, \dots, x_m) = h(f(n, x_1, \dots, x_m), n, x_1, \dots, x_m)$$

and

$$h \circ (P_2^{m+2}, P_1^{m+2}, P_3^{m+2}, \dots, P_{m+2}^{m+2})(f(n, x_1, \dots, x_m), n, x_1, \dots, x_m) = h(n, f(n, x_1, \dots, x_m), x_1, \dots, x_m),$$

the two definitions are equivalent. In this section we chose version $(*_1)$ because it matches the treatment in Barendregt [5] and will make it easier for the reader to follow Barendregt [5] if they wish.

The last operation is *minimization* (sometimes called minimalization).

Definition 6.20. Given any partial or total function $g: \mathbb{N}^{m+1} \to \mathbb{N}$ $(m \ge 0)$, the partial or total function function $f: \mathbb{N}^m \to \mathbb{N}$ is defined as follow;: for all $x_1, \ldots, x_m \in \mathbb{N}$,

$$f(x_1,\ldots,x_m)$$
 = the least $n \in \mathbb{N}$ such that $g(n,x_1,\ldots,x_m) = 0$,

and undefined if there is no n such that $g(n, x_1, \ldots, x_m) = 0$. We say that f is defined by minimization from g, and we write

$$f(x_1,\ldots,x_m)=\mu x[g(x,x_1,\ldots,x_m)=0].$$

For short, we write $f = \mu g$.

Even if g is a total function, f may be undefined for some (or all) of its inputs.

Definition 6.21. (Herbrand–Gödel–Kleene) The set of *partial computable* (or *partial recursive*) functions is the smallest set of partial functions (defined on \mathbb{N}^n for some $n \ge 1$) which contains the base functions and is closed under

- (1) Composition.
- (2) Primitive recursion.

(3) Minimization.

The set of *computable* (or *recursive*) functions is the subset of partial computable functions that are total functions (that is, defined for all input).

We proved earlier the Kleene normal form, which says that *every* partial computable function $f \colon \mathbb{N}^m \to \mathbb{N}$ is computable as

$$f = g \circ \mu h,$$

for some primitive recursive functions $g: \mathbb{N} \to \mathbb{N}$ and $h: \mathbb{N}^{m+1} \to \mathbb{N}$. The significance of this result is that f is built up from total functions using composition and primitive recursion, and only a single minimization is needed at the end.

Before stating our main theorem, we need to define what it means for a (numerical) function to be definable in the λ -calculus. This requires some care to handle partial functions.

Since there are combinators for translating Church numerals to Barendregt numerals and vice-versa, it does not matter which numerals we pick. We pick the Church numerals because primitive recursion is definable without using a fixed-point combinator.

Definition 6.22. A function (partial or total) $f \colon \mathbb{N}^n \to \mathbb{N}$ is λ -definable if for all $m_1, \ldots, m_n \in \mathbb{N}$, there is a combinator (a closed λ -term) F with the following properties.

- (1) The value $f(m_1, \ldots, m_n)$ is defined if and only if $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ reduces to a β -normal form (necessarily unique by the Church–Rosser theorem).
- (2) If $f(m_1, \ldots, m_n)$ is defined, then

$$F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n} \xleftarrow{}_{\beta} \mathbf{c}_{f(m_1,\dots,m_n)}.$$

In view of the Church–Rosser theorem (Theorem 6.2) and the fact that $\mathbf{c}_{f(m_1,\ldots,m_n)}$ is a β -normal form, we can replace

$$F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n} \xleftarrow{*}_{\beta} \mathbf{c}_{f(m_1,\dots,m_n)}$$

by

$$F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n} \xrightarrow{*}_{\beta} \mathbf{c}_{f(m_1,\dots,m_n)}.$$

Note that the termination behavior of f on inputs m_1, \ldots, m_n has to *match* the reduction behavior of $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$. An equivalent way to state (1) is to assert that if $f(m_1,\ldots,m_n)$ is defined, then $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ reduces to a β -normal form, and if $f(m_1,\ldots,m_n)$ is undefined, then *no* reduction sequence from $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ reaches a β -normal form. Condition (2) ensures that if $f(m_1,\ldots,m_n)$ is defined, then the correct value $\mathbf{c}_{f(m_1,\ldots,m_n)}$ is computed by some reduction sequence from $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$. If we only care about total functions, then (1) requires that $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ reduces to a β -normal for all m_1,\ldots,m_n .

It is important to note that if $f(m_1, \ldots, m_n)$ is defined, then there must be *some* reduction from $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ to a β -normal form equal to $\mathbf{c}_{f(m_1,\ldots,m_m)}$, but this *does not mean that all* reductions from $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ are finite. Some reductions from $F\mathbf{c}_{m_1}\cdots\mathbf{c}_{m_n}$ could be infinite.

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This leads to the question: are there reduction strategies that are guaranteed to terminate with a normal form if it exists?

There are indeed such strategies, for example normal reductions as defined in Definition 6.11. The study of reduction strategies is a beautiful but technically difficult subject. Some key contributors besides Curry are Barendregt, Klop and Levy.

A stronger and more elegant version of λ -definability that better captures when a function is undefined for some input is considered in Section 6.8.

We have the following remarkable theorems.

Theorem 6.11. If a total function $f : \mathbb{N}^n \to \mathbb{N}$ is λ -definable, then it is (total) computable. If a partial function $f : \mathbb{N}^n \to \mathbb{N}$ is λ -definable, then it is partial computable.

Although Theorem 6.11 is intuitively obvious since computation by β -reduction sequences are "clearly" computable, a detailed proof is long and very tedious. One has to define primitive recursive functions to mimick β -conversion, *etc.* Most books sweep this issue under the rug. Barendregt observes that the " λ -calculus is recursively axiomatized," which implies that the graph of the function being defined is recursively enumerable, but no details are provided; see Barendregt [5] (Chapter 6, Theorem 6.3.13). Kleene (1936) provides a detailed and very tedious proof. This is an amazing paper, but very hard to read. If the reader is not content she/he should work out the details over many long lonely evenings.

Theorem 6.12. (Kleene, 1936) If a total function $f \colon \mathbb{N}^n \to \mathbb{N}$ is computable, then it is λ -definable.

Proof. There are several steps.

Step 1. The base functions are λ -definable.

We already showed that $\mathbf{Z}_{\mathbf{c}}$ computes Z and that $\mathbf{Succ}_{\mathbf{c}}$ computes S. Observe that \mathbf{U}_{i}^{n} given by

$$\mathbf{U}_i^n = \lambda x_1 \cdots x_n. x_i$$

computes P_i^n .

Step 2. Closure under composition.

If g is λ -defined by the combinator G and h_1, \ldots, h_m are λ -defined by the combinators H_1, \ldots, H_m , then $g \circ (h_1, \ldots, h_m)$ is λ -defined by

$$F = \lambda x_1 \cdots x_n. G(H_1 x_1 \cdots x_n) \dots (H_m x_1 \cdots x_n).$$

Since the functions are total, there is no problem.

Step 3. Closure under primitive recursion.

We could use a fixed-point combinator but the combinator **Iter** and pairing do the job. If f is defined by primitive recursion from g and h, and if G λ -defines g and H λ -defines h, then f is λ -defined by

$$F = \lambda n x_1 \cdots x_m. \pi_1 \big(\mathbf{Iter} \ n \ \lambda z. \ \langle H \ \pi_1 z \ \pi_2 z \ x_1 \cdots x_m, \ \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle \ \langle G x_1 \cdots x_m, \mathbf{c}_0 \rangle \big).$$

We have

$$F \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \pi_1 \big(\big(\lambda z. \langle H \pi_1 z \pi_2 z \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle \big)^n \langle G \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \mathbf{c}_0 \rangle \big).$$

The reason F works is that we can prove by induction that

$$\left(\lambda z. \left\langle H \, \pi_1 z \, \pi_2 z \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \right\rangle \right)^n \left\langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \right\rangle \xrightarrow{+}_{\beta} \left\langle \mathbf{c}_{f(n,n_1,\dots,n_m)}, \mathbf{c}_n \right\rangle$$

For the base case n = 0,

$$(\lambda z. \langle H \pi_1 z \pi_2 z \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \rangle)^0 \langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \rangle$$

$$\xrightarrow{+}_{\beta} \langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \rangle = \langle \mathbf{c}_{g(n_1, \dots, n_m)}, \mathbf{c}_0 \rangle = \langle \mathbf{c}_{f(0, n_1, \dots, n_m)}, \mathbf{c}_0 \rangle.$$

For the induction step,

$$\begin{aligned} \left(\lambda z. \left\langle H \, \pi_1 z \, \pi_2 z \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \right\rangle \right)^{n+1} \left\langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \right\rangle \\ &= \left(\lambda z. \left\langle H \, \pi_1 z \, \pi_2 z \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \right\rangle \right)^n \left\langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \right\rangle \right) \\ &\left(\lambda z. \left\langle H \, \pi_1 z \, \pi_2 z \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \right\rangle \right)^n \left\langle G \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \mathbf{c}_0 \right\rangle \right) \\ & \stackrel{+}{\longrightarrow}_{\beta} \left(\lambda z. \left\langle H \, \pi_1 z \, \pi_2 z \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}}(\pi_2 z) \right\rangle \right) \left\langle \mathbf{c}_{f(n,n_1,\dots,n_m)}, \mathbf{c}_n \right\rangle \\ & \stackrel{+}{\longrightarrow}_{\beta} \left\langle H \mathbf{c}_{f(n,n_1,\dots,n_m)} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \cdots \mathbf{c}_{n_m}, \, \mathbf{Succ}_{\mathbf{c}} \, \mathbf{c}_n \right\rangle \\ & \stackrel{+}{\longrightarrow}_{\beta} \left\langle \mathbf{c}_{h(f(n,n_1,\dots,n_m),n,n_1,\dots,n_m)}, \, \mathbf{c}_{n+1} \right\rangle = \left\langle \mathbf{c}_{f(n+1,n_1,\dots,n_m)}, \, \mathbf{c}_{n+1} \right\rangle. \end{aligned}$$

Since the functions are total, there is no problem.

We can also show that primitive recursion can be achieved using a fixed-point combinator. Define the combinators J and F by

$$J = \lambda f x x_1 \cdots x_m. \text{ if } \mathbf{IsZero}_{\mathbf{c}} x \text{ then } G x_1 \cdots x_m$$

else $H(f(\mathbf{Pred}_{\mathbf{c}} x) x_1 \cdots x_m)(\mathbf{Pred}_{\mathbf{c}} x) x_1 \cdots x_m,$

and

 $F = \Theta J.$

We proceed by induction on n to prove that $F \lambda$ -defines f.

We leave the base case n = 0 as an exercise. For $n \ge 1$, since $F \xrightarrow{+}_{\beta} JF$, we have

$$F \mathbf{c}_{n} \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}} \xrightarrow{+}_{\beta} (JF) \mathbf{c}_{n} \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

$$\xrightarrow{+}_{\beta} \text{ if } \mathbf{IsZero}_{\mathbf{c}} \mathbf{c}_{n} \text{ then } G\mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

$$\text{ else } H(F(\mathbf{Pred}_{\mathbf{c}} \mathbf{c}_{n}) \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}})(\mathbf{Pred}_{\mathbf{c}} \mathbf{c}_{n}) \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

$$\xrightarrow{+}_{\beta} \text{ if } \mathbf{T} \text{ then } G\mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

$$\text{ else } H(F(\mathbf{Pred}_{\mathbf{c}} \mathbf{c}_{n}) \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}})(\mathbf{Pred}_{\mathbf{c}} \mathbf{c}_{n}) \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

By the induction hypothesis,

$$F \mathbf{c}_{n-1} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_{f(n-1,n_1,\dots,n_m)},$$

so by definition of H,

$$H(F \mathbf{c}_{n-1} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{c}_{n-1} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_{h(f(n-1,n_1,\dots,n_m),n-1,n_1,\dots,n_m)}$$
$$= \mathbf{c}_{f(n,n_1,\dots,n_m)}.$$

Then $F \lambda$ -defines f, and since the functions are total, there is no problem. This method must be used if we use the Barendregt numerals.

Step 4. Closure under minimization.

Suppose f is total and defined by minimization from g and that g is λ -defined by G. Define the combinators J and H by

$$J = \lambda f x x_1 \cdots x_m$$
. if $\mathbf{IsZero}_{\mathbf{c}} G x x_1 \cdots x_m$ then x else $f(\mathbf{Succ}_{\mathbf{c}} x) x_1 \cdots x_m$

and

$$H = \boldsymbol{\Theta} J.$$

Since $H \xrightarrow{+}_{\beta} JH$, we have

$$\begin{array}{ccc} H \, \mathbf{c}_n \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m} & \stackrel{+}{\longrightarrow}_{\beta} (JH) \, \mathbf{c}_n \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m} \\ & \stackrel{+}{\longrightarrow}_{\beta} \text{ if } \mathbf{IsZero}_{\mathbf{c}} \, G \, \mathbf{c}_n \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m} \text{ then } \mathbf{c}_n \text{ else } H(\mathbf{Succ}_{\mathbf{c}} \, \mathbf{c}_n) \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m} \\ & \stackrel{+}{\longrightarrow}_{\beta} \text{ if } \mathbf{IsZero}_{\mathbf{c}} \, G \, \mathbf{c}_n \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m} \text{ then } \mathbf{c}_n \text{ else } H \, \mathbf{c}_{n+1} \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m}. \end{array}$$

Since the combinator G computes g, we deduce that

$$H \mathbf{c}_{n} \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}} \xrightarrow{+}_{\beta} \begin{cases} \mathbf{c}_{n}, & \text{if } g(n, n_{1}, \dots, n_{m}) = 0\\ H \mathbf{c}_{n+1} \mathbf{c}_{n_{1}} \cdots \mathbf{c}_{n_{m}}, & \text{otherwise.} \end{cases}$$
(H)

Let F be the combinator defined by

$$F = \lambda x_1 \dots x_m. H \mathbf{c}_0 x_1 \dots x_m,$$

so that

$$F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} H \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$$

Since we assumed that f is total, there is a least n such that $g(n, n_1, \ldots, n_m) = 0$, and so the definition of $H \mathbf{c}_n \mathbf{c}_{n_1} \ldots \mathbf{c}_{n_m}$ given in (H) shows by induction on $p \leq n$ that since $g(q, n_1, \ldots, n_m) \neq 0$ for q < p,

$$H \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} H \mathbf{c}_p \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m},$$

and thus

 $H \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_n$, if $n \ge 0$ is the smallest integer such that $g(n, n_1, \dots, n_m) = 0$. Since $F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} H \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$, we conclude that $F \lambda$ -defines f. We leave the details as an exercise.

This finishes the proof that every total computable function is λ -definable.

6.7 λ -Definability of the Partial Computable Functions

To prove Theorem 6.12 for the partial computable functions we appeal to the Kleene normal form: every partial computable function $f \colon \mathbb{N}^m \to \mathbb{N}$ is computable as

$$f = \psi \circ \mu g,$$

for some primitive recursive functions $\psi \colon \mathbb{N} \to \mathbb{N}$ and $g \colon \mathbb{N}^{m+1} \to \mathbb{N}$. Thus we are back to the previous case where we are trying to find the least n such that $g(n, n_1, \ldots, n_m) = 0$, if any. Our previous proof yields combinators H and F and it appears that F defines $\varphi(n_1, \ldots, n_m) = \mu x[g(x, n_1, \ldots, n_m) = 0]$. The minimization of g may fail, but since g is a total function, one might think that it should be clear that F computes φ . However this is not obvious because we need to prove that $H\mathbf{c}_0 \mathbf{c}_{n_1} \ldots \mathbf{c}_{n_m}$ has no normal form if $g(n, n_1, \ldots, n_m) \neq 0$ for all $n \in \mathbb{N}$. But H is defined in terms of a fixed-point combinator, so in fact the proof is tricky. We sketch how to proceed, adapting Hindley and Seldin [35] who give a detailed proof (see Chapter 4, Theorems 4.15 and 4.18).

The adaptation has to do with the fact that Hindley and Seldin minimize g with respect to the last argument instead of the first.

Theorem 6.13. If a partial function $f \colon \mathbb{N}^n \to \mathbb{N}$ is partial computable, then it is λ -definable.

Proof. The first step is to define H without using the fixed-point combinator Θ . First we define a variant **D** of the pairing function by

$$\mathbf{D} = \lambda x y z. \, z(\mathbf{K} y) x.$$

Since

$$\mathbf{D}XY\mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{c}_n(\mathbf{K}Y)X \xrightarrow{+}_{\beta} (\mathbf{K}Y)^n X,$$

we can easily check that

$$\mathbf{D}XYZ = \begin{cases} X, & \text{if } Z = \mathbf{c}_0 \\ Y, & \text{if } Z = \mathbf{c}_n, \ n \ge 1. \end{cases}$$
(D)

Assume that the combinator Ψ defines ψ and **G** defines g. Next we define **R** and **P** by

$$\mathbf{R} = \mathbf{D} \mathbf{U}_{2}^{m+1} \left(\lambda u x y_{1} \dots y_{m} . u \left(\mathbf{G} \left(\mathbf{Succ}_{\mathbf{c}} x \right) y_{1} \dots y_{m} \right) u \left(\mathbf{Succ}_{\mathbf{c}} x \right) y_{1} \dots y_{m} \right)$$
$$\mathbf{P} = \lambda x y_{1} \dots y_{m} . \mathbf{R} (\mathbf{G} x y_{1} \dots y_{m}) \mathbf{R} x y_{1} \dots y_{m}.$$

We have

$$\begin{aligned} \mathbf{P} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} & \stackrel{+}{\longrightarrow}_{\beta} \mathbf{R} (\mathbf{G} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{R} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \\ &= \mathbf{D} \, \mathbf{U}_2^{m+1} \left(\lambda u x y_1 \dots y_m . \, u \left(\mathbf{G} \left(\mathbf{Succ}_{\mathbf{c}} x \right) y_1 \dots y_m \right) u \left(\mathbf{Succ}_{\mathbf{c}} x \right) y_1 \dots y_m \right) \\ & \left(\mathbf{G} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \right) \mathbf{R} \, \mathbf{c}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}. \end{aligned}$$

Since the above term is of the form $\mathbf{D}XYZW$ with

$$X = \mathbf{U}_{2}^{m+1}$$

$$Y = \left(\lambda u x y_{1} \dots y_{m} . u \left(\mathbf{G} \left(\mathbf{Succ}_{\mathbf{c}} x\right) y_{1} \dots y_{m}\right) u \left(\mathbf{Succ}_{\mathbf{c}} x\right) y_{1} \dots y_{m}\right)$$

$$Z = \left(\mathbf{G} \mathbf{c}_{n} \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}\right)$$

$$W = \mathbf{R} \mathbf{c}_{n} \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}},$$

we have two cases depending on the result of reducing $\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$.

If $\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_0$, by (**D**), $\mathbf{P} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{D} XY \mathbf{c}_0 W \xrightarrow{+}_{\beta} XW = \mathbf{U}_2^{m+1} \mathbf{R} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_n$. If $\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_p$ with $p \ge 1$, by (**D**), $\mathbf{P} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{D} XY \mathbf{c}_p W$ $\xrightarrow{+}_{\beta} YW = \left(\lambda uxy_1 \dots y_m \cdot u \left(\mathbf{G} \left(\mathbf{Succ}_{\mathbf{c}} x\right) y_1 \dots y_m\right) u \left(\mathbf{Succ}_{\mathbf{c}} x\right) y_1 \dots y_m\right)$ $\mathbf{R} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$ $\xrightarrow{+}_{\beta} \mathbf{R} \left(\mathbf{G} \left(\mathbf{Succ}_{\mathbf{c}} \mathbf{c}_n\right) \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}\right) \mathbf{R} \left(\mathbf{Succ}_{\mathbf{c}} \mathbf{c}_n\right) \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$.

In summary, we proved that

(1) If
$$\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_0$$
, then

$$\mathbf{Pc}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_n.$$

(2) If
$$\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_p \ (p \ge 1)$$
, then

$$\mathbf{Pc}_n \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \stackrel{*}{\longleftrightarrow}_{eta} \mathbf{P}(\mathbf{Succ}_{\mathbf{c}} \, \mathbf{c}_n) \, \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$$

In fact, we proved that

$$\mathbf{P}\mathbf{c}_{n} \, \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}} \xrightarrow{+}_{\beta} \mathbf{R}(\mathbf{G} \, \mathbf{c}_{n} \, \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}) \mathbf{R} \, \mathbf{c}_{n} \, \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}} \xrightarrow{+}_{\beta} \mathbf{R}(\mathbf{G} \, \mathbf{c}_{n+1} \, \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}) \, \mathbf{R} \, \mathbf{c}_{n+1} \, \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}.$$
(*3)

Now if we define F by

$$F = \lambda x_1 \dots x_m. \, \Psi(\mathbf{P} \, \mathbf{c}_0 \, x_1 \dots x_m),$$

we see immediately that F computes f if $f(n_1, \ldots, n_m)$ is defined. Furthermore, it can be shown that F has a β -normal form, which is not the case of the previous F obtained with the Turing fixed-point combinator.

But if $f(n_1, \ldots, n_m)$ is undefined, we have to make sure that F has no β -normal form. A trick to achieve this is to define \tilde{F} by

$$\widetilde{F} = \lambda x_1 \dots x_m \cdot (\mathbf{P} \mathbf{c}_0 x_1 \dots x_m) \mathbf{I} (F x_1 \dots x_m).$$

If $f(n_1, \ldots, n_m)$ is defined, then there is a least $n \ge 0$ such that $g(n, n_1, \ldots, n_m) = 0$, so Case (1) above arises and we have

$$\widetilde{F} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} (\mathbf{P} \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} \mathbf{c}_n \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} \mathbf{I}^n (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} \mathbf{c}_{f(n_1,\dots,n_m)},$$

so $\widetilde{F} \mathbf{c}_{n_1} \ldots \mathbf{c}_{n_m}$ computes $f(n_1, \ldots, n_m)$. The reduction

$$\mathbf{c}_n \mathbf{I}(F \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} \mathbf{I}^n(F \, \mathbf{c}_{n_1} \, \dots \, \mathbf{c}_{n_m})$$

follows from (\dagger_2) just after Definition 6.14 and the reduction

$$\mathbf{I}^{n}(F \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}) \xrightarrow{+}_{\beta} F \mathbf{c}_{n_{1}} \dots \mathbf{c}_{n_{m}}$$

holds by Proposition 6.3(1).

If $f(n_1, \ldots, n_m)$ is undefined, since $g(n, n_1, \ldots, n_m) \neq 0$ for all $n \geq 0$, $\mathbf{G} \mathbf{c}_n \mathbf{c}_{n_1} \ldots \mathbf{c}_{n_m}$ never reduces to \mathbf{c}_0 , so we have the infinite reduction sequence

$$\widetilde{F} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m} \xrightarrow{+}_{\beta} (\mathbf{P} \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} (\mathbf{R} (\mathbf{G} \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{R} \mathbf{c}_0 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} (\mathbf{R} (\mathbf{G} \mathbf{c}_1 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{R} \mathbf{c}_1 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} (\mathbf{R} (\mathbf{G} \mathbf{c}_2 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{R} \mathbf{c}_2 \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \mathbf{I} (F \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}) \xrightarrow{+}_{\beta} \cdots$$

This turns out to be what is known as an infinite quasi-leftmost reduction, and this implies that $\widetilde{F} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$ has no β -normal form.

The reader should review Definition 6.11 in order to understand the next definition.

Definition 6.23. Given a λ -term M_0 , a reduction sequence

$$M_0 \xrightarrow{+}_{u_0,R_0,\beta} M_1 \xrightarrow{+}_{u_1,R_1,\beta} M_2 \xrightarrow{+}_{\beta} \cdots \xrightarrow{+}_{\beta} M_{n-1} \xrightarrow{+}_{u_{n-1},R_{n-1},\beta} M_n \xrightarrow{+}_{\beta} \cdots$$

is a *quasi-leftmost reduction* if the following condition holds:

for all $i \ge 0$, if $M_0 \xrightarrow{+}_{\beta} M_i$ and M_i is not a β -normal form, then there is some $j \ge i$ such that $M_j \xrightarrow{+}_{u_j,R_j,\beta} M_{j+1}$ is a leftmost maximal reduction. (qlr)

If the reduction is finite and ends with M_n , then M_n is a β -normal form, since otherwise Condition (qlr) would require that $M_n \beta$ -reduces in order for a leftmost maximal reduction to occur later. Observe that an infinite reduction is a quasi-leftmost reduction iff it contains infinitely many letfmost maximal steps $M_j \xrightarrow{+}_{u_j,R_j,\beta} M_{j+1}$.

Example 6.29. Let

$$L = (\lambda x. (xx)y)(\lambda x. (xx)y)$$

be the term from Example 6.15. Recall that

$$L \xrightarrow{+}_{\beta} Ly \xrightarrow{+}_{\beta} Lyy \xrightarrow{+}_{\beta} \cdots$$

and that L has no β -normal form. Consider the term

$$M = \left(\left(\lambda u. \left(\lambda v. w \right) \right) L \right) L$$

The redex L occurs at 12 and 2 and neither occurrence is maximal; see Figure 6.7.



Figure 6.7: The tree associated with the term M.

The redex $(\lambda u. (\lambda v. w))L$ is leftmost maximal. The term M has the β -normal form w, but there are infinite reductions from M obtained by reducing either occurrence of L. There are also finite quasi-leftmost reductions such as the following.

$$M = \left(\left(\lambda u. (\lambda v. w) \right) L \right) L \xrightarrow{+}_{\beta} \left(\left(\lambda u. (\lambda v. w) \right) (Ly^p) \right) L \xrightarrow{+}_{\beta} (\lambda v. w) L$$
$$\xrightarrow{+}_{\beta} (\lambda v. w) (Ly^q) \xrightarrow{+}_{\beta} w,$$

where the leftmost maximal redexes are shown in red.

It is easily verified that the reduction above from $\widetilde{F} \mathbf{c}_{n_1} \dots \mathbf{c}_{n_m}$ is a quasi-leftmost reduction.

The importance of quasi-leftmost reductions is captured by the following theorem.

Theorem 6.14. Let M be a λ -term. If M has a β -normal form M^* , then every quasileftmost reduction is finite and terminates with M^* . As a corollary, since a finite quasi-leftmost reduction terminates with a β -normal form, a λ -term M has no β -normal form iff some quasi-leftmost reduction is infinite.

See Hindley and Seldin [35] (Chapters 3, Theorem 3.19, and Corollary 3.19.1). The fact that the existence of an infinite quasi-leftmost reduction implies that there is no β -normal is a consequence of a deep theorem whose proof is hard, the standardization theorem. Full details can be found in Barendregt [5] (Chapter 11, Theorem 11.4.7, Chapter 13, Theorem 13.2.2 and Theorem 13.2.6).

Combining Theorem 6.11, Theorem 6.12 and Theorem 6.13, we have established the remarkable result that the set of λ -definable total functions is exactly the set of (total) computable functions, and similarly for partial functions. So the λ -calculus has universal computing power.

The proof actually shows that every total or partial computable function is computed by a λ -term that has a β -normal form.

Remark: With some work, it is possible to show that lists and trees can be represented in the λ -calculus. Since a Turing machine tape can be viewed as a list, it should be possible (but very tedious) to simulate a Turing machine in the λ -calculus. This simulation should be somewhat analogous to the proof that a Turing machine computes a computable function (defined à la Herbrand–Gödel–Kleene).

Since the λ -calculus has the same power as Turing machines we should expect some undecidabily results analogous to the undecidability of the halting problem or Rice's theorem (see Theorem 9.6). We state the following analog of Rice's theorem without proof. It is a corollary of a theorem known as the Scott–Curry theorem.

Theorem 6.15. (D. Scott) Let \mathcal{A} be any nonempty set of λ -terms not equal to the set of all λ -terms. If \mathcal{A} is closed under β -reduction, then it is not computable (not recursive).

Theorem 6.15 is proven in Barendregt [5] (Chapter 6, Theorem 6.6.2) and Barendregt [6].

As a corollary of Theorem 6.15 it is undecidable whether a λ -term has a β -normal form, a result originally proved by Church. This is an analog of the undecidability of the halting problem, but it seems more spectacular because the syntax of λ -terms is really very simple. The problem is that β -reduction is very powerful and elusive.

In the next section we revisit the problem of defining the partial computable functions.

6.8 Head Normal-Forms and the Partial Computable Functions

One defect of the proof of Theorem 6.12 in the case where a computable function is partial is the use of the Kleene normal form. The difficulty has to do with composition. Given

a partial computable function $g \lambda$ -defined by a closed term G and a partial computable function $h \lambda$ -defined by a closed term H (for simplicity we assume that both g and h have a single argument), it would be nice if the composition $h \circ g$ was represented by $\lambda x. H(Gx)$. This is true if both g and h are total, but false if either g or h is partial as shown by the following example from Barendregt [5] (Chapter 2, §2).

Recall from Definition 6.22 that if a partial function $f: \mathbb{N} \to \mathbb{N}$ is represented by a λ -term F, if f(n) is undefined, then no reduction from $F \mathbf{c}_n$ ends in a β -normal form.

Example 6.30. If g is the function undefined everywhere and h is the constant function 0, then g is λ -defined by $G = \mathbf{K}\Omega$ and h is λ -defined by $H = \mathbf{K}\mathbf{c}_0$, with $\Omega = (\lambda x. (xx))(\lambda x. (xx))$. We have

$$\lambda x. H(Gx) = \lambda x. \mathbf{K} \mathbf{c}_0(\mathbf{K} \mathbf{\Omega} x) \xrightarrow{+}_{\beta} \lambda x. \mathbf{K} \mathbf{c}_0 \mathbf{\Omega} \xrightarrow{+}_{\beta} \lambda x. \mathbf{c}_0,$$

but $h \circ g = g$ is the function undefined everywhere, and $\lambda x. \mathbf{c}_0$ represents the total function h. Consequency, $\lambda x. H(Gx)$ does not λ -define the function undefined everywhere $g = h \circ g$, since there is a reduction $(\lambda x. H(Gx))\mathbf{c}_n \xrightarrow{+}_{\beta} (\lambda x. \mathbf{c}_0)\mathbf{c}_n \xrightarrow{+}_{\beta} \mathbf{c}_0$.

It turns out that the λ -definability of the partial computable functions can be obtained in a more elegant fashion without having recourse to the Kleene normal form by capturing the fact that a function is undefined for some input is a more subtle way. The key notion is the notion of *head normal form*, which is more general than the notion of β -normal form. As a consequence, there are *fewer* λ -terms having *no* head normal form than λ -terms having *no* β -normal form, and we capture a stronger form of divergence.

Recall that a λ -term is either a variable x, or an application (MN), or a λ -abstraction $(\lambda x. M)$. We can sharpen this characterization as follows.

Proposition 6.16. The following properties hold.

(1) Every application term M is of the form

$$M = (N_1 N_2 \cdots N_{n-1}) N_n, \quad n \ge 2,$$

where N_1 is not an application term.

(2) Every abstraction term M is of the form

$$M = \lambda x_1 \cdots x_n. N, \quad n \ge 1,$$

where N is not an abstraction term.

(3) Every λ -term M is of one of the following two forms:

$$M = \lambda x_1 \cdots x_n \cdot x M_1 \cdots M_m, \quad m, n \ge 0 \tag{a}$$

$$M = \lambda x_1 \cdots x_n. (\lambda x. M_0) M_1 \cdots M_m, \quad m \ge 1, n \ge 0,$$
 (b)

where x is a variable.

Proof. (1) Suppose that M is an application $M = M_1M_2$. We proceed by induction on the depth of M_1 . For the base case M_1 must be variables and we are done. For the induction step, if M_1 is a λ -abstraction, we are done. If M_1 is an application, then by the induction hypothesis it is of the form

$$M_1 = (N_1 N_2 \cdots N_{n-1}) N_n, \quad n \ge 2,$$

where N_1 is not an application term, and then

$$M = M_1 M_2 = ((N_1 N_2 \cdots N_{n-1}) N_n) M_2, \quad n \ge 2,$$

where N_1 is not an application term.

The proof of (2) is similar.

(3) We proceed by induction on the depth of M. If M is a variable, then we are in Case (a) with m = n = 0.

If M is an application, then by (1) it is of the form $M = N_1 N_2 \cdots N_p$ with N_1 not an application term. This means that either N_1 is a variable, in which case we are in Case (a) with n = 0, or N_1 is an abstraction, in which case we are in Case (b) also with n = 0.

If M is an abstraction λx . N, then by the induction hypothesis N is of the form (a) or (b), and by adding one more binder λx in front of these expressions we preserve the shape of (a) and (b) by increasing n by 1.

Example 6.31. The terms, **I**, **K**, **K**_{*}, **S**, the Church numerals \mathbf{c}_n , if then else, $\langle M, N \rangle$, π_1, π_2 , **Iter**, **Succ**_c, **Add** and **Mult** as in Proposition 6.6, are λ -terms of type (a). However, **Pred**_K, $\mathbf{\Omega} = (\lambda x. (xx))(\lambda x. (xx))$, **Y** (the Curry **Y**-combinator), $\mathbf{\Theta}$ (the Turing $\mathbf{\Theta}$ -combinator) are of type (b). Regarding

$$\mathbf{Pred}_{\mathbf{K}} = \lambda n. \, \pi_2(\mathbf{Iter} \, n \, (\lambda z. \, \langle \mathbf{Succ}_{\mathbf{c}}(\pi_1 z), \pi_1 z \rangle) \, \langle \mathbf{c}_0, \mathbf{c}_0 \rangle),$$

recall that $\pi_2 = \lambda z. z \mathbf{K}_*$.

Proposition 6.16 motivates the following definition.

Definition 6.24. A λ -term M is a *head normal form* (for short *hnf*) if it is of the form (a), namely

$$M = \lambda x_1 \cdots x_n \cdot x M_1 \cdots M_m, \quad m, n \ge 0,$$

where x is a variable called the *head variable*.

A λ -term M has a head normal form if there is some head normal form N such that $M \xrightarrow{*}_{\beta} N$.

In a term M of the form (b),

$$M = \lambda x_1 \cdots x_n \cdot (\lambda x \cdot M_0) M_1 \cdots M_m, \quad m \ge 1, n \ge 0,$$

the subterm $(\lambda x. M_0)M_1$ is called the *head redex* of M.

Example 6.32. In addition to the terms of type (a) that we listed after Proposition 6.16, the term $\lambda x. x \Omega$ is a head normal form. It is the head normal form of the term $\lambda x. (\mathbf{I}x)\Omega$, which has no β -normal form.

Not every term has a head normal form. For example, the term

$$\mathbf{\Omega} = (\lambda x. (xx))(\lambda x. (xx))$$

has no head normal form. Every β -normal form must be a head normal form, but the converse is false as we saw with

$$M = \lambda x. \, x \mathbf{\Omega},$$

which is a head normal form but has no β -normal form.

Note that a head redex of a term is a leftmost redex, but not conversely, as shown by the term $\lambda x. x((\lambda y. y)x)$, in which the leftmost redex is $(\lambda y. y)x$, which is not a head redex.

A term may have more than one head normal form but here is a way of obtaining a head normal form (if there is one) in a systematic fashion.

Definition 6.25. The relation \longrightarrow_h , called *one-step head reduction*, is defined as follows. For any two terms M and N, if M contains a head redex $(\lambda x. M_0)M_1$, which means that M is of the form

$$M = \lambda x_1 \cdots x_n \cdot (\lambda x \cdot M_0) M_1 \cdots M_m, \quad m \ge 1, n \ge 0,$$

then $M \longrightarrow_h N$ with

$$N = \lambda x_1 \cdots x_n (M_0[x := M_1]) M_2 \cdots M_m.$$

We denote by $\xrightarrow{+}_{h}$ the transitive closure of \longrightarrow_{h} and by $\xrightarrow{*}_{h}$ the reflexive and transitive closure of \longrightarrow_{h} .

Given a term M containing a head redex, the *head reduction sequence of* M is the uniquely determined sequence of one-step head reductions

 $M = M_0 \longrightarrow_h M_1 \longrightarrow_h \cdots \longrightarrow_h M_n \longrightarrow_h \cdots$

If the head reduction sequence reaches a term M_n which is a head normal form we say that the sequence *terminates*, and otherwise we say that M has an *infinite* head reduction.

The following result is shown in Barendregt [5] (Chapter 8, §3).

Theorem 6.17. (Wadsworth) A λ -term M has a head normal form if and only if the head reduction sequence terminates.

In some intuitive sense, a λ -term M that does not have any head normal form has a strong divergence behavior with respect to β -reduction.

Remark: There is a notion more general than the notion of head normal form which comes up in functional languages (for example, Haskell). A λ -term M is a *weak head normal form* if it is of one of the two forms

$$\lambda x. N$$
 or $yN_1 \cdots N_m$

where y is a variable These are exactly the terms that do not have a redex of the form $(\lambda x. M_0)M_1N_1\cdots N_m$. Every head normal form is a weak head normal form, but there are many more weak head normal forms than there are head normal forms since a term of the form $\lambda x. N$ where N is *arbitrary* is a weak head normal form, but not a head normal form unless N is of the form $\lambda x_1 \cdots x_n. xM_1 \cdots M_m$, with $m, n \ge 0$.

Reducing to a weak head normal form is a lazy evaluation strategy.

There is also another useful notion which turns out to be equivalent to having a head normal form.

Definition 6.26. A closed λ -term M is *solvable* if there are closed terms N_1, \ldots, N_n such that

$$MN_1 \cdots N_n \xrightarrow{*}_{\beta} \mathbf{I}$$

A λ -term M with free variables x_1, \ldots, x_m is *solvable* if the closed term $\lambda x_1 \cdots x_m$. M is solvable. A term is *unsolvable* if it is not solvable.

The following result is shown in Barendregt [5] (Chapter 8, §3).

Theorem 6.18. (Wadsworth) A λ -term M has a head normal form if and only if is it solvable.

Actually, the proof that having a head normal form implies solvable is not hard.

We are now ready to revise the notion of λ -definability of numerical functions. Note that Barendregt represents the natural numbers using the Barendregt numerals instead of the Church numerals. This makes the proof technically simpler.

Definition 6.27. A function (partial or total) $f: \mathbb{N}^n \to \mathbb{N}$ is strongly λ -definable if for all $m_1, \ldots, m_n \in \mathbb{N}$, there is a combinator (a closed λ -term) F with the following properties:

- (1) If the value $f(m_1, \ldots, m_n)$ is defined, then $F\mathbf{b}_{m_1}\cdots\mathbf{b}_{m_n}$ reduces to the β -normal form $\mathbf{b}_{f(m_1,\ldots,m_n)}$.
- (2) If $f(m_1, \ldots, m_n)$ is undefined, then $F\mathbf{b}_{m_1}\cdots \mathbf{b}_{m_n}$ has no head normal form, or equivalently, is unsolvable.

Observe that in Case (2), when the value $f(m_1, \ldots, m_n)$ is undefined, the divergence behavior of $F\mathbf{b}_{m_1}\cdots\mathbf{b}_{m_n}$ is stronger than in Definition 6.22. Not only $F\mathbf{b}_{m_1}\cdots\mathbf{b}_{m_n}$ has no β -normal form, but actually it has no head normal form.

The following result is proven in Barendregt [5] (Chapter 8, $\S4$). The proof does not use the Kleene normal form. Instead, it makes clever use of the term **KII**. Another proof is given in Krivine [46] (Chapter II). **Theorem 6.19.** Every partial or total computable function is strongly λ -definable. Conversely, every strongly λ -definable function is partial computable.

Making sure that a composition $g \circ (h_1, \ldots, h_m)$ is defined for some input x_1, \ldots, x_n iff all the $h_i(x_1, \ldots, x_n)$ and $g(h_1(x_1, \ldots, x_n), \ldots, h_m(x_1, \ldots, x_n))$ are defined is tricky. The term **KII** comes to the rescue! The Barendregt numerals have the property that

$$\mathbf{b}_n \mathbf{KII} \xrightarrow{+}_{\beta} \mathbf{I},$$

so they are "uniformly solvable;" see Barendregt [5] (Chapter 8, Lemma 8.4.5). If g is strongly λ -definable by G and the h_i are strongly λ -definable by H_i , then it can be shown that the combinator F given by

$$F = \lambda x_1 \cdots x_n \cdot (H_1 x_1 \cdots x_n \mathbf{KII}) \cdots (H_m x_1 \cdots x_n \mathbf{KII}) (G(H_1 x_1 \cdots x_n) \cdots (G(H_m x_1 \cdots x_n)))$$

strongly λ -defines F; see Barendregt [5] (Chapter 8, Lemma 8.4.6).

To prove closure under minimization, the Turing fixed-point combinator and the combinators

$$J = \lambda f x x_1 \cdots x_n. \text{ if } \mathbf{IsZero}_{\mathbf{b}} G x x_1 \cdots x_n \text{ then } x \text{ else } f(\mathbf{Succ}_{\mathbf{b}} x) x_1 \cdots x_n$$
$$H = \mathbf{\Theta} J$$
$$F = \lambda x_1 \dots x_n. H \mathbf{b}_0 x_1 \dots x_n,$$

can be used, because when $f(m_1, \ldots, m_n)$ is undefined, there is an infinite quasi-leftmost reduction from $F\mathbf{b}_{m_1}\cdots\mathbf{b}_{m_n}$, and this implies that $F\mathbf{b}_{m_1}\cdots\mathbf{b}_{m_n}$ has no β -normal form, which in turn implies that it has no head normal form; see Barendregt [5] (Chapter 8, Lemma 8.4.10 and 8.4.11).

Chapter 7

Definability of Computable Functions in System F

7.1 Definability of Total Computable Functions by Typed λ -Terms

In the pure λ -calculus, some λ -terms have no β -normal form, and worse, it is undecidable whether a λ -term has a β -normal form.

In contrast, by Theorem 2.12, every raw λ -term that type-checks in the simply-typed λ -calculus has a β -normal form. Thus it is natural to ask whether the natural numbers are definable in the simply-typed λ -calculus because if the answer is positive, then the numerical functions definable in the simply-typed λ -calculus are guaranteed to be total.

This indeed possible by defining a typed version of the Church numerals. However, the set of total computable functions definable in the simply-typed λ -calculus is very crude. This class of functions is discussed in Section 7.2.

A much more extensive class of total computable functions is obtained by adding more general types, namely polymorphic second-order types. Such a type system, known as system F, was first invented by Girard [27, 28] (1972) and rediscovered by Reynolds in 1974 (with very different goals). In addition to base types, we allow *type variables* (often denoted X, Y, \ldots) ranging over simple types and new types of the form $\forall X. \sigma$. As in the simply-typed λ -calculus, every reduction sequence terminates (strong normalization holds) and confluence holds. Strong normalization in system F is a deep result that requires a new technique invented by Girard, the candidates of reducibility; see Girard [27, 28] (1972) and Gallier [22]. A version of the Church numerals can be defined in system F, and so a class of computable functions guaranteed to be total can be defined.

This set of functions turns out to be the family of computable functions that can be proven total in a system of intuitionistic second-order arithmetic known as \mathbf{HA}^2 . This remarkable result was proven by Girard [28].

Proving that a computable function provably total in \mathbf{HA}^2 is computable in system F

is achieved by representing proofs in \mathbf{HA}^2 as certain kinds of terms containing the terms of system F as a subsystem. This is an instance of the "Curry–Howard isomorphism," in which propositions correspond to types and proofs correspond to certain kinds of typed λ -terms.

The system \mathbf{HA}^2 is obtained from the proof system of intuitionistic second-order logic \mathbf{Ni}^2 by adding axioms about 0 and S (the successor function S(n) = n+1), and an induction axiom. The term calculus encoding proofs in \mathbf{Ni}^2 is denoted $\lambda \mathbf{Ni}^2$.

Since the term calculus λNi^2 contains terms not in system F, it is necessary to define a map, the collapsing map, converting a term in λNi^2 to a term in system F.

Actually, there is a technical complication because the absurdity proposition \perp is not provable, and thus is not the type of any term in λNi^2 . To circumvent this problem, it is necessary to introduce an auxiliary term system $\lambda 2\Omega$ and to define two maps, one from λNi^2 to $\lambda 2\Omega$, and one from $\lambda 2\Omega$ to system F.

There is also a difficulty in mapping proofs in \mathbf{HA}^2 directly to terms in $\lambda 2\Omega$ because of the induction axiom of \mathbf{HA}^2 , so it is necessary to define the intuitionistic second-order logic proof system \mathbf{HA}^{2*} . Formulae in \mathbf{HA}^2 can be converted to formulae in \mathbf{HA}^{2*} by a process of relativization of quantifiers (the \mathbb{D} -translation), in such a way that the relativization of the induction axiom of \mathbf{HA}^2 is provable in \mathbf{HA}^{2*} , so \mathbf{HA}^{2*} does not not have any induction axiom. As a consequence, if a formula P is provable in \mathbf{HA}^2 , then its \mathbb{D} -translation $P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} without any induction axiom.

The process of quantifier relativization involves a second-order predicate $\mathsf{N}^{\wedge}(v)$ that defines the notion of natural number as Dedekind did in his famous paper of 1888 (Was sind und was sollen die Zallen?). Then the formula $\forall vP$ is replaced by $\forall v(\mathsf{N}^{\wedge}(v) \Rightarrow P^{\mathbb{D}})$.

We follow closely Troelstra and Schwichtenberg [73], but many technical details are omitted in this book, so we filled in some of the missing proofs.

7.2 Definability of Functions in the Simply-Typed Lambda-Calculus

This section relies on material from Section 2.14 that the reader may want to review.

If we pick any base type σ , then we can define typed Church numerals \mathbf{c}_n as terms of type $\mathsf{Nat}_{\sigma} = (\sigma \to \sigma) \to (\sigma \to \sigma)$, by

$$\mathbf{c}_n = \lambda f \colon (\sigma \to \sigma). \, \lambda x \colon \sigma. \, f^n(x).$$

The notion of λ -definable function is defined just as before. Then we can define **Add** and **Mult** as terms of type $\operatorname{Nat}_{\sigma} \to (\operatorname{Nat}_{\sigma} \to \operatorname{Nat}_{\sigma})$ essentially as before, but surprise, not much more is definable. Among other things, strong typing of terms restricts the iterator combinator too much. It was shown by Schwichtenberg and Statman that the numerical functions definable in the simply-typed λ -calculus are the extended polynomials; see Statman [69] and Troelstra and Schwichtenberg [73].

Definition 7.1. The extended polynomials are the smallest class of numerical functions closed under composition containing

- 1. The constant functions 0 and 1.
- 2. The projections.
- 3. Addition and multiplication.
- 4. The function IsZero_c.

Is there a way to get a larger class of total functions?

There are indeed various ways of doing this. One method is to add the natural numbers and the booleans as data types to the simply-typed λ -calculus, and to also add product types, an iterator combinator, and some new reduction rules. This way we obtain a system equivalent to Gödel's system T. A large class of numerical total functions containing the primitive recursive functions is definable in this system; see Girard–Lafond–Taylor [26]. Although theoretically interesting, this is not a practical system.

Another wilder method is to add more general types to the simply-typed λ -calculus, the so-called *second-order types* or *polymorphic types*. In addition to base types, we allow *type variables* (often denoted X, Y, \ldots) ranging over simple types and new types of the form $\forall X. \sigma.^1$

7.3 Polymorphic Types and System F

Definition 7.2. The second-order types (or polymorphic types) σ are defined inductively as follows.

- (1) If \mathbf{T}_i is a base type, then \mathbf{T}_i is a polymorphic type, and if X is a type variable, then X is a polymorphic type.
- (2) If σ and τ are polymorphic types, then $(\sigma \to \tau)$ is a polymorphic type.
- (3) If σ is a polymorphic type and X is a type variable, then $\forall X. \sigma$ is a polymorphic type.

Since second-order types may contain type variables bound by the quantifier \forall , we have a notion of free and bound type variable. Formally, the definition is similar to Definition 6.4

Definition 7.3. For any second-order type σ , the set $FV(\sigma)$ of *free variables* of σ and the set $BV(\sigma)$ of *bound variables* in σ are defined inductively as follows.

(1) If $\sigma = X$ (a type variable), then

$$FV(X) = \{X\}, \quad BV(X) = \emptyset.$$

(2) If $\sigma = \mathbf{T}_i$ (a base type), then

$$FV(\mathbf{T}_i) = \emptyset, \quad BV(\mathbf{T}_i) = \emptyset.$$

¹Barendregt and others used Greek letters to denote type variables but we find this confusing.

(3) If $\sigma = (\sigma_1 \to \sigma_2)$, then

$$FV(\sigma) = FV(\sigma_1) \cup FV(\sigma_2), \quad BV(\sigma) = BV(\sigma_1) \cup BV(\sigma_2)$$

(4) If $\sigma = \forall X. \sigma_1$, then

$$FV(\sigma) = FV(\sigma_1) - \{X\}, \quad BV(\sigma) = BV(\sigma_1) \cup \{X\}.$$

If $X \in FV(\sigma_1)$, we say that the occurrences of the variable X occur in the scope of \forall .

A type σ is *closed* if $FV(\sigma) = \emptyset$, that is, if it has no free variables.

Example 7.1. The type $\forall X. (X \to X)$ is such a new type, and so is

$$\forall X. (X \to ((X \to X) \to X)).$$

Actually, the second-order types that we just defined are special cases of the QBF (quantified boolean formulae) arising in complexity theory restricted to implication and universal quantifiers; see Section 16.3. Remarkably, the other connectives \land, \lor, \neg and \exists are definable in terms of \rightarrow (as a logical connective, \Rightarrow) and \forall ; see Proposition 7.2 and Troelstra and Schwichtenberg [73] (Chapter 11).

The type

$$\mathsf{Nat} = \forall X. \, (X \to ((X \to X) \to X)).$$

can be chosen to represent the type of the natural numbers. The type of the natural numbers can also be chosen to be

 $\forall X. ((X \to X) \to (X \to X)).$

This makes essentially no difference but the first choice has some technical advantages.

Since the new types may contain type variables, we can substitute types for the variables occurring free in a type σ .

Definition 7.4. Given any second-order type σ and any substitution $\varphi = [X_1 := \sigma_1, ..., X_n := \sigma_n]$ where X_1, \ldots, X_n are type variables and $\sigma_1, \ldots, \sigma_n$ are second-order types, we define the second-order type $\sigma[\varphi]$, the result of applying the substitution φ to σ , as follows.

(1) If $\sigma = Y$, with $Y \neq X_i$ for i = 1, ..., n, then $\sigma[\varphi] = Y = \sigma$.

(2) If $\sigma = X_i$ for some $i \in \{1, \ldots, n\}$, then $\sigma[\varphi] = \sigma_i$.

(3) If $\sigma = \mathbf{T}_i$ (a base type), then $\sigma[\varphi] = \mathbf{T}_i = \sigma$.

(4) If $\sigma = (\sigma_1 \to \sigma_2)$, then $\sigma[\varphi] = (\sigma_1[\varphi] \to \sigma_2[\varphi])$.

(5) If $\sigma = \forall X. \sigma_1$ and $X \neq X_i$ for i = 1, ..., n, then $\sigma[\varphi] = \forall X. \sigma_1[\varphi]$,

(6) If $\sigma = \forall X. \sigma_1$ and $X = X_i$ for some $i \in \{1, \ldots, n\}$, then $\sigma[\varphi] = \forall X. \sigma_1[\varphi]_{-X_i}$.

The type σ is safe for the substitution $\varphi = [X_1 := \sigma_1, \ldots, X_n := \sigma_n]$ if $BV(\sigma) \cap (FV(\sigma_1) \cup \cdots \cup FV(\sigma_n)) = \emptyset$, that is, if the free variables in the substitution terms σ_i do not become bound.

As in the case of λ -terms, given a second-order type σ , the bound variables in $BV(\sigma)$ can be renamed so that σ is safe when applying a substitution to it. Technically this can be achieved by adapting the notion of α -conversion given in Definition 6.8 to second-order types. We leave it to the reader to carry out the details.

The new λ terms involving second-order types are defined as follows.

Definition 7.5. The polymorphic raw λ -terms (or second-order raw λ -terms) are defined inductively as follows.

- (1) If x_i is a variable (not a type variable), then x_i is a polymorphic raw term.
- (2) If M and N are polymorphic raw terms, then (MN) is a polymorphic raw term called an *application*.
- (3) If M is a polymorphic raw term, σ is a polymorphic type, and x is a variable, then the expression $(\lambda x : \sigma, M)$ is a polymorphic raw term called a λ -abstraction.
- (4) If M is a polymorphic raw term and X is a type variable, then ΛX . M is a polymorphic raw term called a Λ -abstraction.
- (5) If M is a polymorphic raw term and τ is a polymorphic type, them $(M\tau)$ is a polymorphic raw term called a *type application*.

As usual, to simplify notation, we may omit parentheses. Besides the type-checking rules of Definition 2.19, we need two new type-checking rules having to do with terms of the form $\Lambda X. M$ and $M\tau$.

Since the new λ -terms may contain type variables, the notion of free and bound type variable occurring in a polymorphic λ -term arises.

Definition 7.6. For any polymorphic λ -term M, the set FVT(M) of free type variables of M and the set BVT(M) of bound type variables in M are defined inductively as follows.

(1) If M = x, a variable (not a type variable), then

$$FVT(x) = \emptyset, \quad BVT(x) = \emptyset.$$

(2) If $M = (M_1 M_2)$, then

$$FVT(M) = FVT(M_1) \cup FVT(M_2), \quad BVT(M) = BVT(M_1) \cup BVT(M_2).$$

(3) If $M = (\lambda x : \sigma. M_1)$, then

$$FVT(M) = FVT(M_1) \cup FV(\sigma), \quad BVT(M) = BVT(M_1) \cup BV(\sigma)$$

(4) If $M = (\Lambda X, M_1)$, then

$$FVT(M) = FVT(M_1) - \{X\}, \quad BVT(M) = BVT(M_1) \cup \{X\}.$$

If $X \in FVT(M_1)$, we say that the occurrences of the type variable X occur in the scope of Λ .

(5) If $M = (M_1 \tau)$, then

$$FVT(M) = FVT(M_1) \cup FV(\tau), \quad BVT(M) = BVT(M_1) \cup BV(\tau).$$

We can also substitute types for the type variables occurring free in a polymorphic term M.

Definition 7.7. Given any polymorphic λ -term M and any type substitution $\varphi = [X_1 := \sigma_1, \ldots, X_n := \sigma_n]$, we define the λ -term $M[\varphi]$, the result of applying the substitution φ to M, as follows.

- (1) If M = x, a variable (not a type variable), then $M[\varphi] = x = M$.
- (2) If M = (PQ), then $M[\varphi] = (P[\varphi]Q[\varphi])$.

(3) If $M = \lambda x : \sigma . N$, then $M[\varphi] = \lambda x : \sigma[\varphi] . N[\varphi]$,

(4) If $M = \Lambda X$. N and $X \neq X_i$ for i = 1, ..., n, then $M[\varphi] = \Lambda X$. $N[\varphi]$.

- (5) If $M = \Lambda X$. N and $X = X_i$ for some $i \in \{1, \ldots, n\}$, then $M[\varphi] = \Lambda X$. $N[\varphi]_{-X_i}$.
- (6) If $M = M_1 \tau$, then $M[\varphi] = M_1[\varphi]\tau[\varphi]$.

The term M is safe for the substitution $\varphi = [X_1 := \sigma_1, \ldots, x = X_n := \sigma_n]$ if $BVT(M) \cap (FV(\sigma_1) \cup \cdots \cup FV(\sigma_n)) = \emptyset$, that is, if the free type variables in the substitution terms σ_i do not become bound.

As usual, before applying a type substitution to a polymorphic term M, we rename the bound type variables in M so that M is safe for the type substitution.

Example 7.2. We have

$$\begin{aligned} \big(\lambda f \colon (X \to X). \, \lambda x \colon X. \, \lambda g \colon \forall Y. \, (Y \to Y). \, gX \, (fx) \big) [X := \tau] \\ &= \lambda f \colon (\tau \to \tau). \, \lambda x \colon \tau. \, \lambda g \colon \forall Y. \, (Y \to Y). \, g\tau \, (fx). \end{aligned}$$

Definition 7.8. Besides the type-checking rules of Definition 2.19, we have the following type-checking rules (typing rules) dealing with second-order types of the form $\forall X. \sigma$.

$$\frac{\Gamma \triangleright M : \sigma[X := Y]}{\Gamma \triangleright (\Lambda X. M) : \forall X. \sigma} \quad \text{(type abstraction)}$$

provided that Y does not occur free in any of the types in Γ or in $\forall X. \sigma$, and

$$\frac{\Gamma \triangleright M \colon \forall X. \sigma}{\Gamma \triangleright (M\tau) \colon \sigma[X := \tau]} \quad \text{(type application)},$$

where τ is any type and σ is safe for the substitution $[X := \tau]$, namely $BV(\sigma) \cap FV(\tau) = \emptyset$.

We also have a new reduction rule

$$(\Lambda X. M)\sigma \longrightarrow_{\beta \forall} M[X := \sigma]$$

that corresponds to a new form of redundancy in proofs having to do with a \forall -elimination immediately following a \forall -introduction. Here in the substitution $M[X := \tau]$, we assume that M is safe for the substitution $[X := \tau]$, namely $BVT(M) \cap FV(\tau) = \emptyset$.

The intuition behind terms of type $\forall X. \sigma$ is that a term M of type $\forall X. \sigma$ is a sort of generic function such that for any type τ , the function $M\tau$ is a specialized version of type $\sigma[X := \tau]$ of M.

For example, M could be the function that appends an element to a list, and for specific types such as the natural numbers Nat, strings String, trees Tree, *etc.*, the functions MNat, MString, MTree, are the specialized versions of M to lists of elements having the specific data types Nat, String, Tree.

Definition 7.9. The typed λ -calculus specified by Definitions 7.2, 7.5 and 7.8 is called the second-order polymorphic lambda calculus. It was invented by Girard (1972) who named it system F;² see Girard [27, 28], and it is denoted $\lambda 2$ by Barendregt. We define $\xrightarrow{+}_{\lambda 2}$ and $\xrightarrow{*}_{\lambda 2}$ as the relations

$$\stackrel{+}{\longrightarrow}_{\lambda 2} = (\longrightarrow_{\beta} \cup \longrightarrow_{\beta \forall})^{+}$$
$$\stackrel{*}{\longrightarrow}_{\lambda 2} = (\longrightarrow_{\beta} \cup \longrightarrow_{\beta \forall})^{*}.$$

A variant of system F was also introduced independently by John Reynolds (1974) but for very different reasons.

Observe that self-application terms of the form (MM) do not type-check in system F. The type-checking rules prevent this to happen. In particular, the fixed-point combinators **Y** and Θ do not type-check in system F. However any term M that type-checks can be applied to any type τ .

From the point of view where types are viewed as propositions and λ -terms are viewed as proofs, type abstraction is an introduction rule and type application is an elimination rule, both for the second-order quantifier \forall . Technically, since we are generalizing intuitionistic propositional logic, we need to consider propositions built up using the connectives $\Rightarrow, \land, \lor, \neg, \bot$, and we need to add universally quantified second-order formulae $\forall X. \sigma$ and

²Actually, in Girard's thesis [28], it is denoted F_2 .

existentially quantifed second-order formulae $\exists X. \sigma$, where σ is any second-order formula and X is a type variable. In particular, in order to avoid a clash with the separator symbol \rightarrow used in a sequent, we replace the type constructor \rightarrow by \Rightarrow . The inference rules of this logic consist of the rules of Definition 2.7 and of four proof rules which are analogous to the rules used in first-order logic given in Definition 2.34.

Definition 7.10. Besides the inference rules of Definition 2.7 for intuitionistic propositional logic (for the connectives \Rightarrow , \land , \lor , \neg , \bot), the inference rules dealing with second-order quantified propositions are listed below.

$$\frac{\Gamma \to \sigma[X := Y]}{\Gamma \to \forall X. \sigma} \quad (\forall X \text{-intro}),$$

provided that Y does not occur in any of the propositions in Γ or in $\forall X. \sigma$,

$$\frac{\Gamma \to \forall X. \, \sigma}{\Gamma \to \sigma[X := \tau]} \quad (\forall X \text{-}elim),$$

where τ is any proposition and σ is safe for the substitution $[X := \tau]$,

$$\frac{\Gamma \to \sigma[X := \tau]}{\Gamma \to \exists X. \sigma} \quad (\exists X \text{-intro}),$$

where τ is any proposition and σ is safe for the substitution $[X := \tau]$, and

$$\frac{\Gamma \to \exists X. \, \sigma \quad z \colon \sigma[X := Y], \Delta \to C}{\Gamma \cup \Delta \to C} \quad (\exists X \text{-}elim),$$

where in $(\exists X \text{-}elim)$, $z \colon \sigma[X \coloneqq \tau] \notin \Delta$, and Y does not occur free in Δ , $\exists X \colon \sigma$, or C.

The inference rules of Definition 2.4 together with the rules of Definition 7.10 define the proof system of *intuitionistic second-order propositional logic*.

For more technical details, see Troelstra and Schwichtenberg [73] and Gallier [22].

From the point of view of logic, Girard's system F is a proof system for *intuitionistic* second-order propositional logic restricted to the connectives \Rightarrow and \forall . The Curry–Howard isomorphism extends to system F, in the sense that second-order propositions built up using implication and universal quantification over propositional variables correspond to secondorder types built up using the arrow constructor and universal quantification over type variables. More importantly, a deduction tree of $\Gamma \rightarrow P$ using the proof rules corresponds to a type-checking derivation of $\Gamma \triangleright M : \sigma$ using the type-checking rules, where the type σ is obtained from P by replacing \Rightarrow by \rightarrow , and the polymorphic λ -term M is a term representation of the proof tree of $\Gamma \rightarrow P$. Also, given a type-checking derivation of $\Gamma \triangleright M : \sigma$ using the type-checking rules, a proof of $\Gamma \rightarrow P$ is immediately obtained by erasing the lambda-terms and converting σ to P. By abuse of language, a type-checking derivation is often referred to as a proof. **Example 7.3.** Since $Nat = \forall X. (X \to ((X \to X) \to X))$, for any *n* of type Nat and any second-order type σ , the type application rule of Definition 7.8 yields the following derivation

$$n \colon \mathsf{Nat} \triangleright n \colon \forall X. (X \to ((X \to X) \to X))$$
$$n \colon \mathsf{Nat} \triangleright n\sigma \colon (X \to ((X \to X) \to X))[X := \sigma] = \sigma \to ((\sigma \to \sigma) \to \sigma),$$

which shows that $n\sigma$ has type $\sigma \to ((\sigma \to \sigma) \to \sigma)$.

In particular, nX has type $X \to ((X \to X) \to X)$.

Example 7.4. If σ is any base type, we have the closed term

 $\mathbf{A}_{\sigma} = \lambda x \colon \sigma. \, \lambda f \colon (\sigma \to \sigma). \, f x.$

We determine its type by applying the typing rules. We have the type-checking derivation

$$\frac{\begin{array}{cccc} f: \sigma \to \sigma \rhd f: \sigma \to \sigma & x: \sigma \rhd x: \sigma \\ \hline x: \sigma, f: \sigma \to \sigma \rhd fx: \sigma \\ \hline x: \sigma \rhd \lambda f: (\sigma \to \sigma). fx: (\sigma \to \sigma) \to \sigma \\ \hline \rhd \lambda x: \sigma. \lambda f: (\sigma \to \sigma). fx: \sigma \to ((\sigma \to \sigma) \to \sigma) \end{array}$$

,

which shows that \mathbf{A}_{σ} has type $\sigma \to ((\sigma \to \sigma) \to \sigma)$.

The corresponding proof of the proposition $\sigma \Rightarrow ((\sigma \Rightarrow \sigma) \Rightarrow \sigma)$ is given below.

$$\frac{f: \sigma \Rightarrow \sigma \to \sigma \Rightarrow \sigma \qquad x: \sigma \to \sigma}{\underbrace{\frac{x: \sigma, f: \sigma \Rightarrow \sigma \to \sigma}{x: \sigma \to (\sigma \Rightarrow \sigma) \Rightarrow \sigma}}_{\to \sigma \Rightarrow ((\sigma \Rightarrow \sigma) \Rightarrow \sigma)}}$$

The λ -term $\lambda x : \sigma \cdot \lambda f : (\sigma \to \sigma) \cdot f x$ is a term representation of the above proof of the proposition $\sigma \Rightarrow ((\sigma \Rightarrow \sigma) \Rightarrow \sigma)$.

For every term F of type $\sigma \to \sigma$ and every term a of type σ , we have

$$\mathbf{A}_{\sigma}aF \stackrel{+}{\longrightarrow}_{\boldsymbol{\lambda}\mathbf{2}} Fa.$$

Since \mathbf{A}_{σ} has the same behavior for *all* types σ , it is natural to define the generic function \mathbf{A} given by

$$\mathbf{A} = \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, fx.$$

We have the type checking proof

$$\frac{ \begin{array}{ccc} f \colon X \to X \vartriangleright f \colon X \to X & x \colon X \vartriangleright x \colon X \\ \hline x \colon X, f \colon X \to X \vartriangleright fx \colon X \\ \hline x \colon X \lor \lambda f \colon (X \to X). fx \colon (X \to X) \to X \\ \hline \triangleright \lambda x \colon X. \lambda f \colon (X \to X). fx \colon X \to ((X \to X) \to X) \\ \hline \triangleright \Lambda X. \lambda x \colon X. \lambda f \colon (X \to X). fx \colon \forall X. \left(X \to ((X \to X) \to X) \right) \\ \end{array} \right),$$

which shows that **A** has type $Nat = \forall X. (X \to ((X \to X) \to X)).$

The term $\mathbf{A}\sigma$ has the same behavior as \mathbf{A}_{σ} . We will see shortly that \mathbf{A} is the Church numeral \mathbf{c}_1 in $\lambda \mathbf{2}$ as defined below.

Theorem 7.1. (Girard) Strong normalization holds for system F in the sense that every λ -term typable in system F has a β -normal form. Confluence also holds, so every λ -term typable in system F has a unique β -normal form.

The proof of this theorem is hard and was one of Girard's main accomplishments in his dissertation, Girard [28] (see Part II). The proof technique used to prove that system F is strongly normalizing is thoroughly analyzed in Gallier [22], and a more general framework is discussed in Gallier [20].

We stated earlier that deciding whether a simple type σ is provable, that is, whether there is a closed λ -term M that type-checks in the simply-typed λ -calculus such that the judgement $\triangleright M : \sigma$ is provable is a hard problem. Indeed Statman proved that this problem is P-space complete; see Statman [68] and Section 16.4.

It is natural to ask whether it is decidable whether given any second-order type σ , there is a closed λ -term M that type-checks in system F such that the judgement $\triangleright M : \sigma$ is provable (if σ is viewed as a second-order logical formula, the problem is to decide whether σ is provable). Surprisingly the answer is *no*; this problem (called *inhabitation*) is undecidable. This result was proven by Löb around 1976, see Barendregt [6].

This undecidability result is troubling and at first glance seems paradoxical. Indeed, viewed as a logical formula, a second-order type σ is a QBF (a quantified boolean formula), and if we assign the truth values **F** and **T** to the boolean variables in it, we can decide whether such a proposition is valid in exponential time and polynomial space (in fact, we will see that later QBF validity is P-space complete). this seems in contradiction with the fact that provability is undecidable.

But the proof system corresponding to system F is an *intuitionistic* proof system, so there are (non-quantifed) propositions that are valid in the truth-value semantics but not provable in intuitionistic propositional logic. The set of second-order propositions provable in intuitionistic second-order logic is a *proper* subset of the set of valid QBF (under the truth-value semantics), and it is *not computable*. So there is no paradox after all.

That system F is significantly more complex that the simply-typed λ -calculus is also illustrated by the fact that type checking and typability in system F are equivalent and undecidable; see Wells [77]. These two problems are decidable for the simply-typed λ -calculus; see Section 2.14.

7.4 Church Numerals and Computability in System F

Going back to the issue of computability of numerical functions, a version of the Church numerals can be defined as follows.
Definition 7.11. The *polymorphic Church numerals*, for short the *Church numerals*, are defined by

$$\mathbf{c}_n = \Lambda X. \,\lambda x \colon X. \,\lambda f \colon (X \to X). \,f^n(x). \tag{*}_{c1}$$

From the derivation

$$\frac{f \colon X \to X \triangleright f \colon X \to X \qquad x \colon X \triangleright x \colon X}{x \colon X, f \colon X \to X \triangleright fx \colon X,}$$

we deduce that

$$x: X, f: X \to X \triangleright f^n(x): X,$$

and then we have the type derivation

$$\frac{x \colon X, f \colon X \to X \triangleright f^{n}(x) \colon X}{x \colon X \triangleright \lambda f \colon (X \to X). f^{n}(x) \colon (X \to X) \to X}$$
$$\xrightarrow{\triangleright \lambda x \colon X. \lambda f \colon (X \to X). f^{n}(x) \colon X \to ((X \to X) \to X)}$$
$$\xrightarrow{\triangleright \Lambda X. \lambda x \colon X. \lambda f \colon (X \to X). f^{n}(x) \colon \forall X. (X \to ((X \to X) \to X)),$$

which shows that \mathbf{c}_n has type Nat. Also note that variables x and f now appear in the order x, f in the λ -binder, as opposed to f, x as in Definition 6.14.

Inspired by the definition of **Succ** given in Section 6.4, we can define the successor function on the natural numbers as

Succ =
$$\lambda n$$
: Nat. ΛX . λx : X . λf : $(X \to X)$. $f(nX xf)$.

Abbreviating $X \to X$ as Y, we have the derivation

which shows that **Succ** has type $Nat \rightarrow Nat$.

For every type σ , every term F of type $\sigma \to \sigma$ and every term a of type σ , we have

$$\mathbf{c}_n \sigma \, aF = \left(\Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, f^n(x)\right) \sigma \, aF$$
$$\stackrel{+}{\longrightarrow}_{\lambda 2} \left(\lambda x \colon \sigma. \, \lambda f \colon (\sigma \to \sigma). \, f^n(x)\right) aF$$
$$\stackrel{+}{\longrightarrow}_{\lambda 2} F^n(a);$$

that is,

$$\mathbf{c}_n \sigma \, aF \xrightarrow{+}_{\boldsymbol{\lambda} \mathbf{2}} F^n(a). \tag{*}_{c2}$$

So $\mathbf{c}_n \sigma$ iterates F n times starting with a. As a consequence,

Succ
$$\mathbf{c}_n = (\lambda n: \operatorname{Nat.} \Lambda X. \lambda x: X. \lambda f: (X \to X). f(nX x f))\mathbf{c}_n$$

 $\xrightarrow{+}_{\lambda 2} \Lambda X. \lambda x: X. \lambda f: (X \to X). f(\mathbf{c}_n X x f)$
 $\xrightarrow{+}_{\lambda 2} \Lambda X. \lambda x: X. \lambda f: (X \to X). f(f^n(x))$
 $= \Lambda X. \lambda x: X. \lambda f: (X \to X). f^{n+1}(x) = \mathbf{c}_{n+1}.$

We can also define addition of natural numbers as

$$\mathbf{Add} = \lambda m$$
: Nat. λn : Nat. ΛX . λx : X. λf : $(X \to X)$. $(mX(nXxf))f$

We already proved that the following judgement is provable:

$$n: \mathsf{Nat}, x: X, f: X \to X \triangleright nXxf: X.$$

Abbreviating $X \to X$ as Y, we also have the derivation

$$\begin{array}{c} \underline{m: \ \mathsf{Nat} \triangleright \ m: \ \mathsf{Nat}} \\ \hline \underline{m: \ \mathsf{Nat} \triangleright \ mX: X \rightarrow ((X \rightarrow X) \rightarrow X)} \\ \hline \underline{m: \ \mathsf{Nat}, n: \ \mathsf{Nat}, x: X, f: Y \triangleright \ mX(nXxf): (X \rightarrow X) \rightarrow X} \\ \hline \underline{m: \ \mathsf{Nat}, n: \ \mathsf{Nat}, x: X, f: Y \triangleright \ mX(nXxf): (X \rightarrow X) \rightarrow X} \\ \hline \underline{m: \ \mathsf{Nat}, n: \ \mathsf{Nat}, x: X, f: X \rightarrow X \triangleright \ (mX(nXxf))f: X} \\ \end{array}$$

and by abstraction (four times), we deduce that Add has type $Nat \rightarrow (Nat \rightarrow Nat)$. Using $(*_{c2})$, we have

$$\mathbf{Add} \, \mathbf{c}_m \, \mathbf{c}_n \stackrel{+}{\longrightarrow}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, \left(\mathbf{c}_m X \, (\mathbf{c}_n X \, xf)\right) f$$
$$\stackrel{+}{\longrightarrow}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, \mathbf{c}_m X \, (f^n(x)) f$$
$$\stackrel{+}{\longrightarrow}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, f^m(f^n(x))$$
$$= \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, f^{m+n}(x) = \mathbf{c}_{m+n}.$$

Multiplication is defined by the following term:

 $\mathbf{Mult} = \lambda m \colon \mathsf{Nat.} \ \lambda n \colon \mathsf{Nat.} \ \Lambda X. \ \lambda x \colon X. \ \lambda f \colon (X \to X). \ m X x (\lambda y \colon X. (n X y f)).$

Using $(*_{c2})$, we have the reduction

$$\operatorname{Mult} \mathbf{c}_{m} \mathbf{c}_{n} \xrightarrow{+}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, \mathbf{c}_{m} X x \big(\lambda y \colon X. \, (\mathbf{c}_{n} X y f) \big) \\ \xrightarrow{+}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, \mathbf{c}_{m} X x \big(\lambda y \colon X. \, (f^{n}(y)) \big) \\ \xrightarrow{+}_{\beta} \Lambda X. \, \lambda x \colon X. \, \lambda f \colon (X \to X). \, \big(\lambda y \colon X. \, (f^{n}(y)) \big)^{m}(x).$$

To finish the argument we need to prove that

$$(\lambda y \colon X. (f^n(y)))^m(x) \xrightarrow{+}_{\beta} f^{mn}(x).$$

We leave it as an exercise to finish the proof by induction on m.

Many of the constructions that can be performed in the pure λ -calculus can be mimicked in system F, which explains its expressive power.

Definition 7.12. For any two second-order types σ and τ , we can define a pairing function $\langle -, - \rangle$ (to be very precise, $\langle -, - \rangle_{\sigma,\tau}$) given by

$$\langle -, - \rangle_{\sigma,\tau} = \lambda u \colon \sigma. \, \lambda v \colon \tau. \, \Lambda X. \, \lambda f \colon \sigma \to (\tau \to X). \, fuv.$$

We have the derivation

$$\frac{f: \sigma \to (\tau \to X) \triangleright f: \sigma \to (\tau \to X) \qquad u: \sigma \triangleright u: \sigma}{f: \sigma \to (\tau \to X), u: \sigma \triangleright fu: \tau \to X} \qquad v: \tau \triangleright u: \tau}{f: \sigma \to (\tau \to X), u: \sigma, v: \tau \triangleright fuv: X} \\ \frac{f: \sigma \to (\tau \to X), u: \sigma, v: \tau \triangleright fuv: X}{u: \sigma, v: \tau \triangleright \lambda f: \sigma \to (\tau \to X), fuv: (\sigma \to (\tau \to X)) \to X} \\ \frac{u: \sigma, v: \tau \triangleright \Lambda X. \lambda f: \sigma \to (\tau \to X). fuv: \forall X. ((\sigma \to (\tau \to X)) \to X)}{u: \sigma \triangleright \lambda v: \tau. \Lambda X. \lambda f: \sigma \to (\tau \to X). fuv: \tau \to (\forall X. ((\sigma \to (\tau \to X)) \to X))} \\ \frac{v: \sigma \land v: \tau \land \Lambda X. \lambda f: \sigma \to (\tau \to X). fuv: \tau \to (\forall X. ((\sigma \to (\tau \to X)) \to X)))}{v: \lambda u: \sigma. \lambda v: \tau. \Lambda X. \lambda f: \sigma \to (\tau \to X). fuv: \sigma \to (\tau \to (\forall X. ((\sigma \to (\tau \to X)) \to X)))}$$

It follows that $\langle -, - \rangle_{\sigma,\tau}$ has the type $\sigma \to (\tau \to (\forall X. ((\sigma \to (\tau \to X)) \to X)))$. Given any term M of type σ and any term N of type τ , we have

$$\langle -, - \rangle_{\sigma,\tau} MN \xrightarrow{*}_{\lambda 2} \Lambda X. \lambda f \colon \sigma \to (\tau \to X). f MN.$$

Definition 7.13. We define $\langle M, N \rangle$ as

$$\langle M, N \rangle = \Lambda X. \lambda f: \sigma \to (\tau \to X). fMN,$$

and the type

$$\forall X. \left((\sigma \to (\tau \to X)) \to X \right)$$

of $\langle M, N \rangle$ is denoted by $\sigma \times \tau$.

As a logical formula, the above type is equivalent to $\sigma \wedge \tau$, which means that if we view σ and τ as (second-order) propositions, then

$$\sigma \wedge \tau \equiv \forall X. \left((\sigma \to (\tau \to X)) \to X \right)$$

is provable intuitionistically. This is a special case of the result that we mentioned earlier: the connectives \land, \lor, \neg and \exists are definable in terms of \rightarrow (as a logical connective, \Rightarrow) and \forall .

Proposition 7.2. The connectives \land, \lor, \neg, \bot and \exists are definable in terms of \Rightarrow and \forall , which means that the following equivalences are provable in intuitionistic second-order propositional logic (see Definition 7.10), where X is not free in σ or τ :

$$\sigma \wedge \tau \equiv \forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X)$$

$$\sigma \vee \tau \equiv \forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X))$$

$$\perp \equiv \forall X. X$$

$$\neg \sigma \equiv \sigma \Rightarrow \forall X. X$$

$$\exists Y. \sigma \equiv \forall X. ((\forall Y. (\sigma \Rightarrow X)) \Rightarrow X).$$

Proof. Here is a proof of $(\sigma \land \tau) \Rightarrow (\forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X)).$

$$\begin{array}{l} \displaystyle \frac{y \colon \sigma \land \tau \to \sigma \land \tau}{y \colon \sigma \land \tau \to \sigma} & \displaystyle \frac{y \colon \sigma \land \tau \to \sigma \land \tau}{y \colon \sigma \land \tau \to \sigma} \\ \displaystyle \frac{x \colon (\sigma \Rightarrow (\tau \Rightarrow X)) \to (\sigma \Rightarrow (\tau \Rightarrow X)), y \colon \sigma \land \tau \to (\tau \Rightarrow X))}{x \colon (\sigma \Rightarrow (\tau \Rightarrow X)), y \colon \sigma \land \tau \to X} & \displaystyle \frac{y \colon \sigma \land \tau \to \sigma \land \tau}{y \colon \sigma \land \tau \to \tau} \\ \\ \displaystyle \frac{x \colon (\sigma \Rightarrow (\tau \Rightarrow X)), y \colon \sigma \land \tau \to X}{y \colon \sigma \land \tau \to ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X)} \\ \displaystyle \frac{y \colon \sigma \land \tau \to \forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X))}{\to (\sigma \land \tau) \Rightarrow \forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X)} \end{array}$$

Here is now a deduction of σ from the premise $(\forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X))$ using the $(\forall X \text{-elim})$ rule with the substitution $[X := \sigma]$.

$$\frac{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right)}{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \left((\sigma \Rightarrow (\tau \Rightarrow \sigma)) \Rightarrow \sigma\right)} \qquad \frac{y: \sigma, z: \tau \rightarrow \sigma}{y: \sigma \rightarrow \tau \Rightarrow \sigma}$$
$$\xrightarrow{Y: \sigma \Rightarrow (\tau \Rightarrow \sigma)} x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \sigma$$

Similarly, here is a deduction of τ from the premise $(\forall X. ((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X))$ using the $(\forall X \text{-elim})$ rule with the substitution $[X := \tau]$.

$$\frac{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right)}{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \left((\sigma \Rightarrow (\tau \Rightarrow \tau)) \Rightarrow \tau\right)} \qquad \frac{\frac{y: \sigma, z: \tau \rightarrow \tau}{y: \sigma \rightarrow \tau \Rightarrow \tau}}{\Rightarrow \sigma \Rightarrow (\tau \Rightarrow \tau)} \\
\frac{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right)}{x: \left(\forall X. \left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \rightarrow \tau}.$$

Applying the \wedge -introduction rule to these two deductions, we get

$$\frac{x:\left(\forall X.\left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \to \sigma \qquad x:\left(\forall X.\left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \to \tau}{\frac{x:\left(\forall X.\left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \to \sigma \land \tau}{\to \left(\forall X.\left((\sigma \Rightarrow (\tau \Rightarrow X)) \Rightarrow X\right)\right) \Rightarrow (\sigma \land \tau)}}.$$

Here is now a proof of $(\forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X))) \Rightarrow (\sigma \lor \tau)$. Let us abbreviate $(\forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X)))$ as Y. We use the $(\forall X\text{-elim})$ rule with the substitution $[X := \sigma \lor \tau]$.

$$\frac{x: Y \to \forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X))}{x: Y \to ((\sigma \Rightarrow (\sigma \lor \tau)) \Rightarrow ((\tau \Rightarrow (\sigma \lor \tau)) \Rightarrow (\sigma \lor \tau))} \xrightarrow{\frac{y: \sigma \to \sigma}{y: \sigma \to \sigma \lor \tau}}{\Rightarrow \sigma \Rightarrow (\sigma \lor \tau)} \frac{z: \tau \to \tau}{z: \tau \to \sigma \lor \tau}}{\Rightarrow \tau \Rightarrow (\sigma \lor \tau)}$$

$$\frac{x: Y \to (\tau \Rightarrow (\sigma \lor \tau)) \Rightarrow (\sigma \lor \tau)}{x: Y \to (\sigma \lor \tau)} \xrightarrow{x: Y \to (\sigma \lor \tau)}{\Rightarrow (\forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X)))) \Rightarrow (\sigma \lor \tau)}$$

For the converse, we have the following proof.

$$\frac{y \colon \sigma \Rightarrow X \to \sigma \Rightarrow X \quad u \colon \sigma \to \sigma}{y \colon \sigma \Rightarrow X, u \colon \sigma \to X} \qquad \frac{z \colon \tau \Rightarrow X \to \tau \Rightarrow X \quad v \colon \tau \to \tau}{z \colon \tau \Rightarrow X, v \colon \tau \to X} \\
\frac{x \colon \sigma \lor \tau, y \colon \sigma \Rightarrow X, z \colon \tau \Rightarrow X \to X}{x \colon \sigma \lor \tau, y \colon \sigma \Rightarrow X \to ((\tau \Rightarrow X) \Rightarrow X)} \\
\frac{x \colon \sigma \lor \tau \to (\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X)}{x \colon \sigma \lor \tau \to \forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X))} \\
\frac{x \colon \sigma \lor \tau \to \forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X)))}{(\sigma \lor \tau) \Rightarrow (\forall X. ((\sigma \Rightarrow X) \Rightarrow ((\tau \Rightarrow X) \Rightarrow X)))} \\$$

The equivalence involving the second-order quantifier \exists is handled as follows.

By renaming of variable we may assume that X be a variable distinct from Y and not free in σ .

A proof that $\exists Y. \sigma \Rightarrow \left(\forall X. \left((\forall Y. (\sigma \Rightarrow X)) \Rightarrow X \right) \right)$ is shown below. $\underbrace{\begin{array}{c} z: \forall Y. (\sigma \Rightarrow X) \rightarrow \forall Y. (\sigma \Rightarrow X) \\ \overline{z: \forall Y. (\sigma \Rightarrow X) \rightarrow \sigma[Y := X]} \Rightarrow X \\ \hline z: \forall Y. (\sigma \Rightarrow X) \rightarrow \sigma[Y := X] \Rightarrow X \\ \hline y: \sigma[Y := X], z: \forall Y. (\sigma \Rightarrow X) \rightarrow X \\ \hline y: \exists Y. \sigma, z: \forall Y. (\sigma \Rightarrow X) \rightarrow X \\ \hline x: \exists Y. \sigma \rightarrow (\forall Y. (\sigma \Rightarrow X)) \Rightarrow X \\ \hline x: \exists Y. \sigma \rightarrow \forall X. \left((\forall Y. (\sigma \Rightarrow X)) \Rightarrow X \right) \\ \hline \rightarrow \exists Y. \sigma \Rightarrow \left(\forall X. \left((\forall Y. (\sigma \Rightarrow X)) \Rightarrow X \right) \right) \end{array}}$

To prove the converse we first use the rule $(\forall X \text{-}elim)$ with the substitution $[X := \sigma]$ and then the $(\exists X \text{-}intro)$ rule. The details are left as an exercise as well as the proof of the remaining equivalences.

Remark: Negation can also be defined as

$$\neg \sigma \equiv \forall X. \, (\sigma \Rightarrow X).$$

Definition 7.14. We also have two projections π_1 and π_2 (to be very precise $\pi_1^{\sigma \times \tau}$ and $\pi_2^{\sigma \times \tau}$) given by

$$\pi_1 = \lambda g \colon \sigma \times \tau \colon g\sigma(\lambda x \colon \sigma \colon \lambda y \colon \tau \colon x)$$

$$\pi_2 = \lambda g \colon \sigma \times \tau \colon g\tau(\lambda x \colon \sigma \colon \lambda y \colon \tau \colon y).$$

It is easy to check that π_1 has type $(\sigma \times \tau) \to \sigma$ and that π_2 has type $(\sigma \times \tau) \to \tau$. For any M of type σ and any N of type τ , we have

$$\pi_1 \langle M, N \rangle \xrightarrow{+}_{\lambda 2} M \text{ and } \pi_2 \langle M, N \rangle \xrightarrow{+}_{\lambda 2} N.$$

The proof of the first reduction is shown below and the second one is left as an exercise.

Example 7.5. We have

$$\pi_{1}\langle M, N \rangle = \left(\lambda g \colon \sigma \times \tau. g\sigma(\lambda x \colon \sigma. \lambda y \colon \tau. x)\right) \left(\Lambda X. \lambda f \colon \sigma \to (\tau \to X). fMN\right)$$

$$\stackrel{+}{\longrightarrow}_{\lambda 2} \left(\Lambda X. \lambda f \colon \sigma \to (\tau \to X). fMN\right) \sigma(\lambda x \colon \sigma. \lambda y \colon \tau. x)$$

$$\stackrel{+}{\longrightarrow}_{\lambda 2} \left(\lambda f \colon \sigma \to (\tau \to \sigma). fMN\right) (\lambda x \colon \sigma. \lambda y \colon \tau. x)$$

$$\stackrel{+}{\longrightarrow}_{\lambda 2} (\lambda x \colon \sigma. \lambda y \colon \tau. x) MN$$

$$\stackrel{+}{\longrightarrow}_{\lambda 2} (\lambda y \colon \tau. M) N$$

$$\stackrel{+}{\longrightarrow}_{\lambda 2} M.$$

Definition 7.15. The booleans can be defined as

$$\mathbf{T} = \Lambda X. \, \lambda x \colon X. \, \lambda y \colon X. \, x$$
$$\mathbf{F} = \Lambda X. \, \lambda x \colon X. \, \lambda y \colon X. \, y,$$

both of type $\mathsf{Bool} = \forall X. (X \to (X \to X))$. We also define if then else as

if then else =
$$\Lambda X. \lambda z$$
: Bool. zX

of type $\forall X. (\mathsf{Bool} \to (X \to (X \to X))).$

It is easy that for any type σ and any two terms M and N of type σ we have

(if **T** then
$$M$$
 else N) $\sigma \xrightarrow{+}_{\lambda_2} M$
(if **F** then M else N) $\sigma \xrightarrow{+}_{\lambda_2} N$,

where we write (if **T** then M else N) σ instead of (if then else) σ **T**MN (and similarly for the other term).

Example 7.6. We have

(if **T** then
$$M$$
 else N) $\sigma = (\Lambda X. \lambda z: \text{Bool. } zX)\sigma \mathbf{T}MN$
 $\xrightarrow{+}_{\lambda 2} (\lambda z: \text{Bool. } z\sigma)\mathbf{T}MN$
 $\xrightarrow{+}_{\lambda 2} (\mathbf{T}\sigma)MN$
 $= ((\Lambda X. \lambda x: X. \lambda y: X. x)\sigma)MN$
 $\xrightarrow{+}_{\lambda 2} (\lambda x: \sigma. \lambda y: \sigma. x)MN$
 $\xrightarrow{+}_{\lambda 2} M.$

Lists, trees, and other inductively data stuctures are also representable in system F; see Girard–Lafond–Taylor [26].

Definition 7.16. We can also define an iterator **Iter** given by

Iter =
$$\Lambda X. \lambda u: X. \lambda f: (X \to X). \lambda z:$$
 Nat. $zX uf$

of type $\forall X. (X \to ((X \to X) \to (\mathsf{Nat} \to X))).$

The idea is that given f of type $\sigma \to \sigma$ and u of type σ , the term **Iter** σufc_n iterates f n times over the input u.

It is easy to show that for any term t of type Nat we have

$$\operatorname{Iter} \sigma \, uf\mathbf{c}_0 \xrightarrow{+}_{\lambda \mathbf{2}} u$$
$$\operatorname{Iter} \sigma \, uf(\operatorname{Succ}_{\mathbf{c}} t) \xleftarrow{*}_{\lambda \mathbf{2}} f(\operatorname{Iter} \sigma \, uft),$$

and that

Iter
$$\sigma u f \mathbf{c}_n \xrightarrow{+}{\longrightarrow}_{\lambda 2} f^n(u).$$

Then mimicking what we did in the pure λ -calculus, we can show that the primitive recursive functions are λ -definable in system F (using the iterator operator, not the fixed-point combinator Θ , which does not type-check in system F). Actually, higher-order primitive recursion is definable. So, for example, Ackermann's function is definable.

Remarkably, the class of numerical functions definable in system F is a class of total computable functions much bigger than the class of primitive recursive functions. This class of functions was characterized by Girard as the computable functions that are provably total in a formalization of arithmetic, \mathbf{HA}^2 , known as intuitionistic second-order arithmetic; see Girard [28] (Part III and Part V), Troelstra and Schwichtenberg [73], Girard–Lafond–Taylor [26], and Section 7.6. It can also be shown (using a diagonal argument) that there are (total) computable functions not definable in system F.

From a theoretical point of view, every (total) function that we will ever want to compute is definable in system F. However, from a practical point of view, programming in system F is very tedious and usually leads to very inefficient programs. Nevertheless polymorphism is an interesting paradigm which had made its way in certain programming languages.

Type systems even more powerful than system F have been designed, the ultimate system being the *calculus of constructions* due to Huet and Coquand, but these topics are beyond the scope of these notes.

One last comment has to do with the use of the simply-typed λ -calculus as a the core of a programming language. In the early 1970's Dana Scott defined a system named LCF (Logic for Computable Functions) based on the simply-typed λ -calculus and obtained by adding the natural numbers and the booleans as data types, product types, and a fixed-point operator. The programming language PCF (Programming with Computable Functions) based on LCF was introduced by Plotkin in 1977. A very crisp exposition of PCF is given in Selinger [66]. Robin Milner then extended LCF, and as a by-product, defined a programming language known as ML, which is the ancestor of most functional programming language design is given in Pierce [58].

In the following sections, we explain what are the computable functions provably total in intuitionistic second-order arithmetic.

7.5 Intuitionistic Second-Order Logic Ni²

As we said earlier, because strong normalization holds in system F, namely for every term M in system F, every β -reduction sequence from M terminates in a β -normal form, the functions computable in system F (using the Church numerals) are total computable functions. Then it is natural to wonder whether the fact that these functions are total can be formalized in a proof system dealing with arithmetic properties of the natural numbers. If this is the case,

we say that such a computable function is *provably total*. In particular, such a proof system should be rich enough so that the primitive recursive functions are definable.

What it means for a computable function to be provably total depends on how the computable function f is defined.

If f is defined in system F by a term M, so that n = f(m) iff $M\mathbf{c}_m \xrightarrow{+}_{\beta} \mathbf{c}_n$ (where $\mathbf{c}_m, \mathbf{c}_n$ are Church numerals), then we need to code a term M as a natural number #(M) and define a formula Red expressing β -reduction, in such a way that the formula

$$\forall m \exists ! n \operatorname{Red}(\#(M\mathbf{c}_m), \#(\mathbf{c}_n))$$
(Red)

is provable iff n = f(m).

The proof of strong normalization in system F involves second-order quantification over certain sets (the candidates of reducibility) and induction. In his thesis [28], Girard proved that the proof of strong normalization for formulae of system F with fixed bounded complexity (a bounded number of logical connectives) can be formalized in a logical system, HA^2 , known as intuitionistic second-order arithmetic; see Girard [28] (Part III, Sections 5 and 6).

At first glance, it appears that the proof of strong normalization needs to be formalized in *classical* second-order arithmetic, denoted \mathbf{PA}^2 (in which the proof-by-contradiction rule is allowed). However, a closer examination (see Girard [28], Part III, Page III-5.2) reveals that the proof can be carried out in *intuitionistic* second-order arithmetic, \mathbf{HA}^2 .³

However, by a result of proof theory, a classical proof in \mathbf{PA}^2 of a formula of the form $\exists u P(u, v)$ in second-order arithmetic \mathbf{PA}^2 , where P is a formula defining a primitive recursive predicate, can be converted to an intuitionistic proof in \mathbf{HA}^2 ; see Section 7.14. Then the above formula (Red) is provable in classical second-order arithmetic \mathbf{PA}^2 iff it is provable in intuitionistic second-order arithmetic \mathbf{HA}^2 , so the sets of computable functions provably total in \mathbf{PA}^2 and \mathbf{HA}^2 are identical.

If f is a computable function in the sense of Herbrand–Kleene–Gödel, then in order to explain what it means for a (partial) computable function to be provably total, we use the Kleene T-predicate; see Section 8.6, Definition 8.15. Recall that if φ_e denotes the partial computable function computed by the RAM program P_e coded by e, then the Kleene predicate T(e, x, z) is defined such that

T(e, x, z) = 1 iff x is an input and z codes a halting computation of P_e on input x, else T(e, x, z) = 0.

Using the function Res that extracts the output $y = \varphi_e(x)$ from the encoding z of the computation of the program P_e on input x if this computation terminates (see Section 8.6), we see that if φ_e is a partial computable function, then the graph G_e of the function $f = \varphi_e$ is given by

$$G_e(x,y) \equiv \exists z ((T(e,x,z)=1) \land (y=\operatorname{Res}(z))).$$

³Technically, we need to work with the system of intuitionistic second-order arithmetic $\mathbf{HA}_{\mathbf{PRA}}^2$ equivalent to \mathbf{HA}^2 ; see Section 7.14.

Definition 7.17. Define the predicate $G_e(x, y)$ by

$$G_e(x, y) \equiv \exists z \big((T(e, x, z) = 1) \land (y = \operatorname{Res}(z)) \big).$$

It follows that the partial computable function φ_e is a total function if and only if

$$\forall x \exists y G_e(x, y) \equiv \forall x \exists y \exists z ((T(e, x, z) = 1) \land (y = \operatorname{Res}(z))).$$

Since the predicate G_e is primitive recursive (see Definition 8.16), if we can show that the primitive recursive functions are definable in our formal system, then we can express the fact that a computable function is provably total. Fortunately, the primitive recursive functions are definable in \mathbf{HA}^2 (see Section 7.10), and so G_e is definable by a formula of \mathbf{HA}^2 . Then φ_e is provably total in \mathbf{HA}^2 iff this formula is provable.

The common theme between the above two definitions of a provably total function (in terms of Red and in terms of G_e) is that in some formalization of arithmetic in which the natural numbers are representable in terms of 0 and the successor function S, namely $n \in \mathbb{N}$ is represented by $S^n(0)$ (for example, \mathbf{HA}^2), a function $f \colon \mathbb{N} \to \mathbb{N}$ is said to be *provably total* (in the formal system) is there is a formula $\Psi(x, y)$ (in the language of the formal system) such that the following two properties hold:

- (1) (Functionality and totality) $\forall x \exists ! y \Psi(x, y)$ is provable.
- (2) (Definability) n = f(m) iff $\Psi(m, n)$ is true in the "standard model" \mathbb{N} (that is, when 0 and the successor function S have their obvious interpretation in \mathbb{N}).

In order to define the formal system \mathbf{HA}^2 of intuitionistic second-order arithmetic, we first need to define the proof system of second-order logic. Then, to prove that if a computable function φ_e is provably total in \mathbf{HA}^2 , we show how to extract a term M in system F from a proof in \mathbf{HA}^2 , and to do this, we need to enrich system F to a second-order λ -calculus so that a proof in intuitionictic second-order logic is represented by a λ -term. In other words, we generalize the Curry–Howard isomorphism to intuitionistic second-order logic.

Observe that in Section 7.3, we started by defining a λ -calculus with second-order types, system F, and then in Definition 7.10, we defined the corresponding second-order propositional logic according to the Curry–Howard isomorphism; a type checking derivation $\Gamma \triangleright M : \sigma$ becomes a proof $\Gamma \rightarrow \sigma$ by erasing the λ -term M, where the type σ is viewed as a proposition.

In this section, we proceed in the opposite direction. First we generalize second-order logic (we allow quantification over first-order variables and second-order variables ranging over predicates of any arity), and then we define the corresponding second-order λ -calculus generalizing system F.

We begin with second-order logic, and as a warm up, the reader may want to review Section 2.17. So far we have only considered second-order propositional logic, but to define the notion of provably total function, we need to be able to represent the primitive recursive functions, which requires allowing function symbols and predicate symbols of any rank. We also need to be able to quantify over predicate variables of any rank, not just propositional variables.

The truth of a first-order formula is determined by chosing a *domain*, which is a nonempty set D of elements often called *individuals*. Then every constant symbol c is assigned some fixed element c_D in D, every function symbol f of rank $n \ge 1$ is interpreted as some fixed function f_D from D^n to D, and every predicate symbol P of rank n is assigned some fixed function P_D from D^n to $\{$ **true**, **false** $\}$. This is equivalent to assigning the subset

$$\{(d_1,\ldots,d_n)\in D^n\mid P_D(d_1,\ldots,d_n)=\mathbf{true}\}$$

of D^n to P (a relation), with the convention that when n = 0, $D^0 = \{\star\}$, a one element set, where $\{\star\}$ corresponds to **true** and \emptyset corresponds to **false**. For every assignment of elements in D to the term variables, every atomic formula $P(\tau_1, \ldots, \tau_m)$ has a truth value, and by induction on the number of logical connectives in a formula φ , the truth value of φ can be determined.

Definition 7.18. It is convenient to introduce two special types, ι for indiduals, and \star (sometimes denoted Type or Prop, but we find this practice confusing) for logical formulae. To avoid overloading the term *type*, we call them *kinds*.

We can form more general kinds inductively.

Definition 7.19. A functional kind K is either ι or a kind of the form $\iota \to K_1$, where K_1 is a functional kind. A logical kind K is either \star or a kind of the form $\iota \to K_1$, where K_1 is a logical kind.

Example 7.7. A constant symbol c has the kind ι , and a function symbol f of rank $n \ge 1$ has a functional kind $\iota \to (\iota \to \cdots \to (\iota \to \iota) \cdots)$ (with n occurrences of \to), a predicate symbol P of rank $n \ge 1$ has logical kind $\iota \to (\iota \to \cdots \to (\iota \to \star) \cdots)$ (with n occurrences of \to). The only two predicate symbols of rank 0 are **true** and **false**, both of kind \star . A term τ has kind ι , and an an atomic formula $P(\tau_1, \ldots, \tau_n)$ has kind \star .

Definition 7.20. In addition to the predicate symbols defined in Clause (iii) of Definition 2.27, we also have a countable set of *second-order predicate variables* X_i^n , where *n* is the arity of X_i^n . Predicate variables have logical kind $\iota \to (\iota \to \cdots \to (\iota \to \star) \cdots)$ (with *n* occurrences of \to). In particular, a predicate variable X^0 of arity 0 has kind \star and is just a type variable as in Definition 7.2. In the Curry–Howard isomorphism, X^0 is a propositional variable.

Given a domain D, the predicate variable X^n takes as value any *n*-ary predicate $R: D^n \to \{\text{true}, \text{false}\}$ (equivalently, any *n*-ary relation).

Now we have three kinds of variables.

(1) First-order term variables t_1, \ldots, t_m, \ldots (as in Definition 2.27(v)). Such variables have kind ι , and range over elements of the domain D.

- (2) Variables x_1, \ldots, x_m, \ldots , used to tag premises in a context $\Gamma = \{x_1 : P_1, \ldots, x_m : P_m\}$. Such variables will be assigned some type σ .
- (3) Second-order (predicate) variables $X_1^n, \ldots, X_m^n, \ldots$ Such variables have logical kind $\iota \to (\iota \to \cdots \to (\iota \to \star) \cdots)$, and range over functions $R: D^n \to \{ \text{true}, \text{false} \}$ (in other words, *n*-ary predicates). In the special case n = 0, the variable X^0 has kind \star .

Since we need to denote first-order terms, to avoid too many Greek letters, we propose to rename the first-order terms variables as v_1, \ldots, v_m, \ldots (or u_i 's), so that t_1, \ldots, t_n and $f(t_1, \ldots, t_n)$ can be used to denote first-order terms.

Definition 7.21. Besides the predicate terms defined in Definition 2.29, we also have new predicate terms of the form $X^n(t_1, \ldots, t_n)$, where X^n is a predicate variable and t_1, \ldots, t_n are first-order terms. Such terms have kind \star .

Definition 7.22. In addition to the first-order quantified formulae in (iv) of Definition 2.30, now denoted $\forall vP$ and $\exists vP$ since first-order variables have been renamed v_1, \ldots, v_m, \ldots , we have second-order quantified formulae $\forall X^n$. P and $\exists X^n$. P for arbitrary predicate variables X^n of any arity $n \geq 0$.

Note that we can use a more uniform notation and denote the quantified formulae by $(\forall v: \iota). P, (\exists v: \iota). P, (\forall X: K.) P$ and $(\exists X: K). P$, where K is the logical kind $\iota \to (\iota \to \iota) \to (\iota \to \star) \cdots$ (with n occurrences of \to), and where we write $(\forall X: K). P$ instead of $\forall X^n. P$ and $(\exists X: K). P$ instead of $\exists X^n. P$. When $K = \star$, equivalently n = 0, the variable X^0 (and X) is a propositional variable (type). With this notation, the kind of the quantified formula, ι or a logical kind K, indicates what kind of variable we are dealing with. For simplicity of notation, we often write $\forall v: \iota. P$ instead $(\forall v: \iota). P, \forall X: K. P$ instead $(\forall X: K). P$, and similarly for the existential quantifiers.

Since atomic formulae have kind \star , we also assign the kind \star to arbitrary second-order formulae.

The definition of free and bound variables in a general second-order formula P is an obvious extension of Definition 7.3. Now, both first-order variables (of kind ι) and second-order predicate variables (of logical kind) may occur free or bound in P.

If $\forall X^n$. *P* has no free (first-order or second-order) variables, then X^n is the only variable that may occur free in *P* and we denote this formula by $P(X^n)$ (X^n may not occur free in *P*). Then $\forall X^n$. *P* is true in a structure with domain *D* if $P(X^n)$ evaluates to true for all assignents of a function $R: D^n \to \{ \text{true}, \text{false} \}$ to X^n . Similarly, if $\exists X^n$. *P* has no free (first-order or second-order) variables, then it is true in a structure with domain *D* if $P(X^n)$ evaluates to true for some assignment of a function $R: D^n \to \{ \text{true}, \text{false} \}$ to X^n .

Remark: An even richer logical system involving higher-order kinds and types was defined by Girard in his thesis [28]. This system, F_{ω} , is a formalization of higher-order logic, where quantification over variables of any higher-order kind is allowed; see Girard [28] (Part I, Page I.5.8). Because we now have atomic formulae of the form $X^n(t_1, \ldots, t_n)$, where X^n is a predicate variable, a new type of substitution arises.

Indeed, if φ is a (second-order) formula we may consider substituting φ for X^n in another (second-order) formula ψ .

Definition 7.23. It is convenient to define *formulae of higher kinds* defined inductively as follows.

- (1) Every formula of kind \star is a logical formula of higher kind.
- (2) If φ is a formula of logical kind K, then $\lambda v \colon \iota \varphi$ is of logical kind $\iota \to K$.
- (3) If φ is a formula of logical kind $\iota \to K$ and t is a term of kind ι , then φt is a formula of logical kind K.

Definition 7.24. Given any two formulae φ and ψ of kind \star , for any predicate variable X^n , we define the substitution

$$\psi[X^n := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi]$$

as the result of replacing every occurrence of a subformula of the form $X^n(t_1, \ldots, t_n)$ in ψ by $\varphi[v_1 := t_1, \ldots, v_n := t_n]$, the result of applying the substitution $[v_1 := t_1, \ldots, v_n := t_n]$ to φ . This can obviously be defined by induction on the depth of ψ ; details are left to the reader.

Observe that if n = 0, the variable X^0 is a propositional variable and $\lambda v_1: \iota \cdots \lambda v_n: \iota. \varphi$ is simply the formula φ , so in case, we just have the substitution $\psi[X := \varphi]$ of Definition 7.4, except that in this definition, we write σ for ψ and σ_1 for φ .

Remark: If we replace X^n by $\lambda v_1: \iota \cdots \lambda v_n: \iota. \varphi$ in the atomic formula $X^n(t_1, \ldots, t_n)$, we obtain $(\lambda v_1: \iota \cdots \lambda v_n: \iota. \varphi)t_1 \ldots t_n$, which does β -reduce to $\varphi[v_1:=t_1, \ldots, v_n:=t_n]$.

The proof rules of second-order logic (in natural deduction style) are given below.

Definition 7.25. The axioms and inference rules of *intuitionistic second-order logic, natural* deduction Gentzen-sequent style, denoted Ni^2 , are listed below. In these rules, P, Q, R denote second-order formulae.

$$\begin{array}{l} \Gamma, x \colon P \to P \quad (\text{Axioms}) \\ \frac{\Gamma, x \colon P \to Q}{\Gamma \to P \Rightarrow Q} \quad (\Rightarrow \text{-intro}) \\ \\ \frac{\Gamma \to P \Rightarrow Q \quad \Delta \to P}{\Gamma \cup \Delta \to Q} \quad (\Rightarrow \text{-elim}) \\ \\ \frac{\Gamma \to P \quad \Delta \to Q}{\Gamma \cup \Delta \to P \land Q} \quad (\land \text{-intro}) \\ \\ \\ \frac{\Gamma \to P \land \Delta \to Q}{\Gamma \to P} \quad (\land \text{-elim}) \quad \frac{\Gamma \to P \land Q}{\Gamma \to Q} \quad (\land \text{-elim}) \end{array}$$

$$\begin{array}{ll} \frac{\Gamma \to P}{\Gamma \to P \lor Q} & (\lor \text{-intro}) & \frac{\Gamma \to Q}{\Gamma \to P \lor Q} & (\lor \text{-intro}) \\ \\ \frac{\Gamma \to P \lor Q}{\Gamma \to \Delta, x \colon P \to R} & \Lambda, y \colon Q \to R \\ \Gamma \cup \Delta \cup \Lambda \to R & (\lor \text{-elim}) \\ \\ \frac{\Gamma \to \bot}{\Gamma \to P} & (\bot \text{-elim}) \\ \\ \frac{\Gamma, x \colon P \to \bot}{\Gamma \to \neg P} & (\neg \text{-introduction}) \\ \\ \frac{\Gamma \to \neg P}{\Gamma \cup \Delta \to \bot} & (\neg \text{-elimination}) \end{array}$$

The following restrictions apply. In the axioms and the rule $(\Rightarrow -intro)$, $x \colon P \notin \Gamma$; in the rule $(\lor -elim)$, $x \colon P \notin \Delta$ and $y \colon Q \notin \Lambda$, and in the rule $(\neg -introduction)$, $x \colon P \notin \Gamma$.

The rules for first-order quantifiers in Gentzen-sequent style are

$$\frac{\Gamma \to P[v := u]}{\Gamma \to \forall v \colon \iota. P} \quad (\forall \text{-intro}) \qquad \frac{\Gamma \to \forall v \colon \iota. P}{\Gamma \to P[v := t]} \quad (\forall \text{-elim}),$$

where in $(\forall$ -intro), $u: \iota$ does not occur free in Γ or $\forall v: \iota. P$;

$$\frac{\Gamma \to P[v := t]}{\Gamma \to \exists v : \iota. P} \quad (\exists \text{-intro}) \qquad \frac{\Gamma \to \exists v : \iota. P \quad z : P[v := u], \Delta \to C}{\Gamma \cup \Delta \to C} \quad (\exists \text{-elim}), \Delta \to C \quad (\exists$$

where in $(\exists \text{-elim})$, $z \colon P[v := u] \notin \Delta$, and $u \colon \iota$ does not occur free in Δ , $\exists v \colon \iota. P$, or C. In the above rules, t is any first-order term.

The rules for second-order quantifiers in Gentzen-sequent style are listed below, where K is any logical kind and we write

$$K_n = \iota \to (\iota \to \cdots \to (\iota \to \star) \cdots),$$

with *n* occurrences of \rightarrow .

$$\frac{\Gamma \to P[X := Y]}{\Gamma \to \forall X : K. P} \quad (\forall X \text{-intro}),$$

provided that Y: K does not occur in any of the formulae in Γ or in $\forall X: K. P$,

$$\frac{\Gamma \to \forall X \colon K_n \cdot P}{\Gamma \to P[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota \cdot \varphi]} \quad (\forall X \text{-}elim),$$

where φ is any second order-formula and the substitution is safe,

$$\frac{\Gamma \to P[X := \lambda v_1 : \iota \cdots \lambda v_n : \iota, \varphi]}{\Gamma \to \exists X : K_n. P} \quad (\exists X \text{-intro}),$$

where φ is any second-order formula and the substitution is safe, and

$$\frac{\Gamma \to \exists X \colon K. \ P \quad z \colon P[X := Y], \Delta \to C}{\Gamma \cup \Delta \to C} \quad (\exists X \text{-elim}),$$

where in $(\exists X \text{-}elim)$, $z \colon P[X := Y] \notin \Delta$, and $Y \colon K$ does not occur free in Δ , $\exists X \colon K. P$, or C.

Classical second-order logic, \mathbf{Nc}^2 , also allows the proof-by-contradiction rule

$$\frac{\Gamma, x \colon \neg P \to \bot}{\Gamma \to P} \quad (by\text{-}contra),$$

where $x: \neg P \notin \Gamma$

Recall that $\neg P$ is an abbreviation for $P \Rightarrow \perp$, so the \neg -introduction and \neg -elimination rules are actually redundant.

Observe that when $K_0 = \star$, the variable $X : \star$ is a propositional variable and the substitution $P[X := \lambda v_1 : \iota \cdots \lambda v_n : \iota . \varphi]$ is simply $P[X := \varphi]$, so the rules $(\forall X \text{-intro})$ and $(\forall X \text{-elim})$ are identical to the rules of Definition 7.10, except that in this definition we write σ for Pand τ for φ .

Remark: To be consistent with the notations for proof systems used in Chapter 2, it would be more appropriate to denote the system Ni^2 by \mathcal{NG}_i^2 . We chose the notation Ni^2 because it is the notation used in Troelstra and Schwichtenberg [73] (Chapter 11).

As explained in Van Dalen [75] (Chapter 4), the $(\exists X \text{-intro})$ rule yields the Comprehension Schema

$$\exists X^n \forall v_1 \colon \iota \cdots \forall v_n \colon \iota \left[\varphi(v_1, \ldots, v_n) \equiv X^n(v_1, \ldots, v_n) \right]$$

for every second-order formula φ with free first-order variables among v_1, \ldots, v_n . This asserts the fact that a formula defines a relation. Conversely, the comprehension scheme plus a weak version of the $(\exists X \text{-intro})$ rule (basically the first-order version) yield the $(\exists X \text{-intro})$ rule.

As we saw in Proposition 7.2, the connectives \land, \lor, \neg and $\exists X^0$ are definable in terms of \Rightarrow and second-order \forall applied to propositional variables. This result is easily generalized to full second-order logic.

Proposition 7.3. The connectives $\land, \lor, \neg, \bot, \exists X^n, \exists u \text{ (first-order)} are definable in terms of <math>\Rightarrow$, $\forall v \text{ (first-order)}, and <math>\forall X^n$, which means that the following equivalences are provable in intuitionistic second-order logic, where the propositional variable X^0 (of kind \star) is not free in the second-order formula P or Q:

$$P \wedge Q \equiv \forall X^{0}. ((P \Rightarrow (Q \Rightarrow X^{0})) \Rightarrow X^{0})$$
$$P \vee Q \equiv \forall X^{0}. ((P \Rightarrow X^{0}) \Rightarrow ((Q \Rightarrow X^{0}) \Rightarrow X^{0}))$$
$$\perp \equiv \forall X^{0}. X^{0}$$
$$\neg P \equiv P \Rightarrow \forall X^{0}. X^{0}$$
$$\exists vP \equiv \forall X^{0} ((\forall v(P \Rightarrow X^{0})) \Rightarrow X^{0})$$
$$\exists Y^{n}. P \equiv \forall X^{0}. ((\forall Y^{n}. (P \Rightarrow X^{0})) \Rightarrow X^{0}).$$

The above proposition allows us to restrict ourselves to formulae built up using \Rightarrow , $\forall u$ (first-order), and $\forall X^n$ (second-order).

To denote proofs in this version of second-order logic we need to add terms associated with the introduction and the elimination rules for all the logical connectives. According to the Curry–Howard isomorphism between propositions and types, every second-order formula becomes a type in the new λ -calculus (extending system F) associated with intuitionistic second-order logic. In particular, every predicate variable X of logical kind K is a type of this new λ -calculus. Technically, the logical connectives $\Rightarrow, \wedge, \vee$ correspond to the type constructors $\rightarrow, \times, +$, but in view of the Curry–Howard isomorphism, for simplicity of notation, we will use the logical connectives. Recall that $\neg P$ is an abbreviation for $P \Rightarrow \perp$. In the definition below, we give type checking rules for all the logical connectives, including \perp , but we do not give reduction rules associated with the rule (\perp -elim) since we don't need them in the rest of this chapter. Instead we rely on Proposition 7.3 which states that \perp is equivalent to $\forall X^0$.

Definition 7.26. The type checking rules of the λ -calculus λNi^2 are defined below.

$$\Gamma, x \colon P \triangleright x \colon P \quad (axioms)$$

$$\frac{\Gamma, x \colon P \triangleright M \colon Q}{\Gamma \triangleright (\lambda x \colon P.M) \colon P \Rightarrow Q} \quad (abstraction)$$

$$\frac{\Gamma \triangleright M \colon P \Rightarrow Q \quad \Delta \triangleright N \colon P}{\Gamma \cup \Delta \triangleright (MN) \colon Q} \quad (application)$$

In the axioms and in the (*abstraction*) rule, it is assumed that $x \colon P \notin \Gamma$. In the (*application*) rule, it is assumed that Γ and Δ are consistent, which means that if $x \colon P_1 \in \Gamma$ and $x \colon P_2 \in \Delta$, then $P_1 = P_2$.

$$\begin{array}{l} \frac{\Gamma \triangleright M \colon P \quad \Delta \triangleright N \colon Q}{\Gamma \cup \Delta \triangleright \langle M, N \rangle \colon P \land Q} \quad (\wedge \text{-intro}) \\\\ \frac{\Gamma \triangleright M \colon P \land Q}{\Gamma \triangleright \pi_1(M) \colon P} \quad (\wedge \text{-elim}) \quad \frac{\Gamma \triangleright M \colon P \land Q}{\Gamma \triangleright \pi_2(M) \colon Q} \quad (\wedge \text{-elim}) \\\\ \frac{\Gamma \triangleright M \colon P}{\Gamma \triangleright \operatorname{inl}(M) \colon P \lor Q} \quad (injection) \quad \frac{\Gamma \triangleright M \colon Q}{\Gamma \triangleright \operatorname{inr}(M) \colon P \lor Q} \quad (injection) \\\\ \frac{\Gamma \triangleright L \colon P \lor Q \quad \Delta, x \colon P \triangleright M \colon C \quad \Lambda, y \colon Q \triangleright N \colon C}{\Gamma, \Delta, \Lambda \triangleright \operatorname{case}(L, \lambda x \colon P.M, \lambda y \colon Q.N) \colon C} \quad (by \ cases) \\\\ \frac{\Gamma \triangleright M \colon \bot}{\Gamma \triangleright \nabla_P(M) \colon P} \quad (\bot \text{-elim}) \end{array}$$

with $P \neq \perp$,

We also have the reduction rules

$$\begin{array}{c} (\lambda x \colon P.\,M)N \longrightarrow_{\boldsymbol{\lambda}\mathbf{N}\mathbf{i}^{2}} M[x := N] \\ \pi_{1}(\langle M, N \rangle) \longrightarrow_{\boldsymbol{\lambda}\mathbf{N}\mathbf{i}^{2}} M \\ \pi_{2}(\langle M, N \rangle) \longrightarrow_{\boldsymbol{\lambda}\mathbf{N}\mathbf{i}^{2}} N \end{array}$$

$$\operatorname{case}(\operatorname{inl}(L), \lambda x \colon P.\,M, \lambda y \colon Q.\,N) \longrightarrow_{\boldsymbol{\lambda}\mathbf{N}\mathbf{i}^{2}} M[x := L] \\ \operatorname{case}(\operatorname{inr}(L), \lambda x \colon P.\,M, \lambda y \colon Q.\,N) \longrightarrow_{\boldsymbol{\lambda}\mathbf{N}\mathbf{i}^{2}} N[y := L]. \end{array}$$

Besides the type checking rules for $\Rightarrow, \land, \lor, \bot$, we need type checking rules to deal with first-order and second-order quantified formulae (types). In the inductive definition of polymorphic terms given in Definition 7.5, first we add new terms of the form $\lambda v \colon \iota. M$, where v is a first-order variable, and Mt, where t is a first-order term of kind ι . We also type-checking rules (typing rules), where P denotes an arbitrary second-order formula viewed as a type. The type checking rules for universal first-order quantifiers are

$$\frac{\Gamma \triangleright M \colon P[v := u]}{\Gamma \triangleright (\lambda v \colon \iota. M) \colon (\forall v \colon \iota). P} \quad (\forall \text{-intro})$$

provided that $u: \iota$ does not occur free in any of the formulae in Γ or in $\forall v: \iota. P$, and

$$\frac{\Gamma \triangleright M : (\forall v : \iota). P}{\Gamma \triangleright (Mt) : P[v := t]} \quad (\forall \text{-elim}),$$

where t is any first-order term of kind ι and P is safe for the substitution [v := t], namely $BV(P) \cap FV(t) = \emptyset$. The type checking rules for existential first-order quantifiers are

$$\begin{split} \frac{\Gamma \triangleright \ M \colon P[v:=t]}{\Gamma \triangleright \ \mathrm{inx}(t,M) \colon \exists v \colon \iota. \ P} \quad (\exists \text{-intro}) \\ \frac{\Gamma \triangleright \ M \colon \exists v \colon \iota. \ P \quad z \colon P[v:=u], \Delta \triangleright \ N \colon C}{\Gamma \cup \Delta \triangleright \ \mathrm{casex}(M, \lambda u \colon \iota. \ \lambda z \colon P[v:=u]. \ N) \colon C} \quad (\exists \text{-elim}), \end{split}$$

where in $(\exists \text{-elim})$, $z \colon P[v := u] \notin \Delta$, and $u \colon \iota$ does not occur free in Δ , $\exists v \colon \iota. P$, or C. In the above rules, t is any first-order term.

We have the reduction rules

$$(\lambda v \colon \iota. M)t \longrightarrow_{\lambda N i^2} M[v := t]$$

casex(inx(t, P), M) $\longrightarrow_{\lambda N i^2} (Mt)P.$

Next to deal with the second-order quantifiers, we add the terms $\Lambda X : K.M$ and $M\varphi$, where K is a logical kind and φ is a formula possibly of higher-order kind, and also the following type-checking rules (typing rules). For any logical kinds K and K_n the type checking rules for universal second-order quantifiers are

$$\frac{\Gamma \triangleright M \colon P[X := Y]}{\Gamma \triangleright (\Lambda X \colon K.M) \colon (\forall X \colon K).P} \quad (\forall X \text{-intro})$$

provided that Y: K does not occur free in any of the formulae in Γ or in $\forall X: K. P$, and

$$\frac{\Gamma \triangleright M \colon (\forall X \colon K_n). P}{\Gamma \triangleright (M(\lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi)) \colon P[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi]} \quad (\forall X \text{-elim}),$$

where $\lambda v_1: \iota \cdots \lambda v_n: \iota. \varphi$ is a formula of higher-order logical kind and P is safe for the substitution. The type checking rule for the existential second-order quantifiers are

$$\frac{\Gamma \triangleright M : P[X := \lambda v_1 : \iota \cdots \lambda v_n : \iota . \varphi]}{\Gamma \triangleright \mathsf{inX}(\lambda v_1 : \iota \cdots \lambda v_n : \iota . \varphi, M) : \exists X : K_n . P} \quad (\exists X \text{-intro}),$$

where φ is any second-order formula and the substitution is safe, and

$$\frac{\Gamma \triangleright M : \exists X : K. P \quad z : P[X := Y], \Delta \triangleright N : C}{\Gamma \cup \Delta \triangleright \mathsf{caseX}(M, \Lambda Y : K. \lambda z : P[X := Y]) : C} \quad (\exists X \text{-}elim),$$

where in $(\exists X \text{-}elim)$, $z \colon P[X := Y] \notin \Delta$, and $Y \colon K$ does not occur free in Δ , $\exists X \colon K. P$, or C.

We also have the reduction rules

$$(\Lambda X \colon K_n. M)(\lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi) \longrightarrow_{\lambda N i^2} M[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi]$$

caseX(inX($\lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi, P$), M) $\longrightarrow_{\lambda N i^2} (M(\lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi))P.$

Observe that when $K_0 = \star$, the variable $X : \star$ is a propositional variable, and the ($\forall X$ -intro) and ($\forall X$ -elim) rules are identical to the rules of Definition 7.8, except that in this definition we write σ for P and τ for φ .

We omitted the reduction rules involving terms of the form $\nabla_P(M)$ since we have no need for them (and by Proposition 7.3, \perp is equivalent to $\forall X^0, X^0$). Such reduction rules are given in Gallier [19].

Now that we have the λ -calculus λNi^2 whose terms denote proofs in intuitionistic secondorder logic Ni^2 , we can define normal forms of proofs.

Definition 7.27. The reduction relation $\xrightarrow{*}_{\lambda N i^2}$ in the λ -calculus $\lambda N i^2$ is the reflexive and transitive closure of the relation $\longrightarrow_{\lambda N i^2}$. Every deduction \mathcal{D} of a sequent $\Gamma \to P$ is represented by a type checking proof of a judgement $\Gamma \triangleright M_{\mathcal{D}}$: P in the λ -calculus $\lambda N i^2$, and a proof \mathcal{D} of $\to P$ is is in *normal form* if $M_{\mathcal{D}}$ is irreducible (w.r.t. $\xrightarrow{*}_{\lambda N i^2}$).

Although its proof is beyond the scope of this book, the following important theorem can be shown.

Theorem 7.4. Strong normalization and confluence hold for intuitionistic second-order logic Ni^2 , in the sense that they hold for the associated λ -calculus λNi^2 . In particular, every proof has a unique normal form. Furthermore, intuitionistic second-order logic Ni^2 is consistent, namely \perp is not provable.

One way to prove Theorem 7.4 is to show that strong normalization in λNi^2 reduces to strong normalization in system F, and thus also holds. See Section 11.3 in Troelstra and Schwichtenberg [73], especially Proposition 11.3.1. Another proof consists in combining the proofs in Gallier [19, 22].

7.6 Intuitionistic Second-Order Arithmetic HA²

Intuitionistic second-order arithmetic, also known as *second-order Heyting arithmetic*, is defined as follows. A system equivalent to \mathbf{HA}^2 is also discussed in Troelstra and Van Dalen [74] (Chapter 3, Section 8, especially Section 8.4).

Definition 7.28. Intuitionistic second-order arithmetic, denoted \mathbf{HA}^2 , is the system of intuitionistic second-order logic based on \mathbf{Ni}^2 whose language has the constant 0, the function symbol S, the equality predicate =, the inference rules of Definition 7.25, the basic axioms

$$\forall v(v = v) \forall X^1 \forall u \forall v (((u = v) \land X^1(u)) \Rightarrow X^1(v)) \forall u \forall v ((Su = Sv) \Rightarrow (u = v)) \forall u (\neg (Su = 0)),$$

and the induction axiom

$$\forall X^1 \big(X^1(0) \land \forall x (X^1(x) \Rightarrow X^1(Sx)) \Rightarrow \forall v X^1(v) \big).$$
 (Ind²)

The intended model (the standard model) of these axioms is the set \mathbb{N} of natural numbers. It is easily shown that equality is reflexive and transitive and that

$$\forall u \forall v ((u = v) \Rightarrow (Su = Sv)).$$

Observe that since the language of \mathbf{HA}^2 only contains the function symbols 0 and S and the predicate symbol =, the first-order terms are of the form $S^n(0)$ or $S^n(u)$ (for some firstorder variable u), and the the non-equational atomic formulae are of the form $X^n(t_1, \ldots, t_n)$, where t_1, \ldots, t_n are first-order terms. Every natural number $n \in \mathbb{N}$ is represented by $S^n(0)$, which we denote by \mathbf{n} .

One of the advantages of second-order arithmetic over first-order arithmetic (say as axiomatized in Peano arithmetic) is that the graph of every primitive recursive function is definable by a formula in HA^2 ; see Theorem 7.5. Thus, there is no need to introduce operators such as + and * in the language, or names for the primitive recursive functions (although this might be convenient).

As we explained in Section 7.5, the partial computable function φ_e (in the sense of Herbrand–Kleene–Gödel) is a total function if and only if

$$\forall x \exists y G_e(x, y),$$

where

$$G_e(x,y) \equiv \exists z \big((T(e,x,z) = 1) \land (y = \operatorname{Res}(z)) \big).$$

As shown in Definition 8.16, the Kleene *T*-predicate and the function Res are primitive recursive so G_e is primitive recursive, and fortunately, the graphs of the primitive recursive functions are definable in \mathbf{HA}^2 , as shown below.

Theorem 7.5. The primitive recusive functions are definable in \mathbf{HA}^2 , in the sense that for every primitive recursive function $f \colon \mathbb{N}^m \to \mathbb{N}$, there is a formula $\Phi_f(u_1, \ldots, u_m, v)$ of \mathbf{HA}^2 such that

$$n = f(n_1, \dots, n_m)$$
 iff $\Phi_f(\mathbf{n}_1, \dots, \mathbf{n}_m, \mathbf{n})$ is provable in \mathbf{HA}^2 . (prdef)

Sketch of proof. First, the predecessor function pred(x) = y is definable by the formula

$$\Phi_{pred}(x,y) = ((x=0) \land (y=0)) \lor \exists z ((x=Sz) \land (y=z)).$$

Next, suppose that f is defined by

$$f(0) = m$$

$$f(n+1) = h(n, f(n)),$$

where h is also a primitive recursive function. Assume that h is defined in \mathbf{HA}^2 by Φ_h . Following Troelstra and Schwichtenberg [73] (Section 11.5), we can construct Φ_f as follows. First, let $A(z, X^2, v)$ be the formula

$$A(z, X^{2}, v) := \forall z' \leq z \big([(z'=0) \Rightarrow (X(z', v) \equiv (v=\mathbf{m}))] \land \\ [(z'\neq 0) \Rightarrow \big(X(z', v) \equiv \exists v' z'' (\Phi_{pred}(z', z'') \land X(z'', v') \land \Phi_{h}(z'', v', v)) \big)] \big),$$

where on the right-hand side we wrote X instead of X^2 to simplify notation. Then we define Φ_f by

$$\Phi_f(z,v) := \forall X(A(z,X,v) \Rightarrow X(z,v)).$$

The idea is that for any fixed z, the property A(z, X, v) asserts that the relation X agrees with the partial graph of the function f defined by primitive recursion for inputs $z' \leq z$, namely

$$(v = f(z')) \equiv X(z', v), \text{ for all } z' \leq z.$$

This is because if z' = 0, then $X(z', v) \equiv (v = \mathbf{m})$ is equivalent to $\mathbf{m} = f(0)$, and if $z' \neq 0$, then

$$\exists v' z''(\Phi_{pred}(z', z'') \land X(z'', v') \land \Phi_h(z'', v', v)))$$
^(†)

means that z'' = pred(z'), which is equivalent to z' = S(z''), and also v' = f(z'') and v = h(z'', v'), so v = h(z'', f(z'')) = f(S(v'')) = f(z'), and since X(z', v) is equivalent to (\dagger) , we obtain $X(z', v) \equiv (v = f(v'))$. So if A(z, X, v) holds, then v = f(z) and $X(z, v) \equiv (v = f(z))$, for every X satisfying A(z, X, v). It follows that if the implication $(A(z, X, v) \Rightarrow X(z, v))$ holds for some X, since $X(z, v) \equiv (v = f(z))$ where (z, v) is the same input-ouput pair for all X satisfying A(z, X, v), then $(A(z, X, v) \Rightarrow X(z, v))$ holds for all X, and so $\Phi_f(z, v) \equiv \forall X(A(z, X, v) \Rightarrow X(z, v)) \equiv (v = f(z))$. But it can indeed be shown by induction on z that

$$\exists XA(z,X,v) \quad \text{and} \quad (\forall z' \leq z) \exists ! v(A(z,X,v) \Rightarrow X(z',v)),$$

namely for the partial graph of f for all inputs $z' \leq z$.

The generalization to functions of several inputs is left as an exercise, and as usual, predicates are defined by their characteristic function. $\hfill \Box$

Since G_e is primitive recursive, we can make the following provisional definition.

Definition 7.29. The partial computable function $\varphi_e \colon \mathbb{N} \to \mathbb{N}$ is provably total in \mathbf{HA}^2 if

$$\forall x \exists y \Psi_e(x, y)$$

is provable in \mathbf{HA}^2 , where Ψ_e is a formula defining the primitive recusive predicate G_e .

The problem with the above definition is that x and y really should be natural numbers. This can be fixed, but we still have another problem. To show that a function $f = \varphi_e$ provably total in \mathbf{HA}^2 is computable in system F, we would like to extract a λ -term in system F computing f from a proof in \mathbf{HA}^2 that f is total. But \mathbf{HA}^2 is a richer system which, in particular, has the induction axiom (Ind²), and this is a serious obstacle. Girard– Lafond–Taylor [26] are quite informal about this point, but Troelstra and Schwichtenberg [73] provide details. What we need to do is to define a variant \mathbf{HA}^{2*} of \mathbf{HA}^2 , in which the natural numbers are defined by a predicate, so that the induction axiom (Ind²) can be omitted because it *becomes provable in the system* \mathbf{HA}^{2*} . Every proof in \mathbf{HA}^2 can be translated into a proof in \mathbf{HA}^{2*} , so there is no loss of expressive power, but \mathbf{HA}^{2*} is better suited for the conversion of proofs into terms in system F.

7.7 Intuitionistic Second-Order Arithmetic HA^{2*}

Definition 7.30. Intuitionistic second-order logic with a Dedekind N-predicate, denoted \mathbf{HA}^{2*} , has the constant 0, the function symbol S, the equality predicate =, the inference rules of Definition 7.25, and the predicate $\mathbb{N}^{\wedge}(v)$,⁴ also denoted $v \in \mathbb{N}^{\wedge}$, given by

$$\mathsf{N}^{\wedge}(v) \equiv v \in \mathsf{N}^{\wedge} := \forall X^{1} \big(X^{1}(0) \land \forall u (X^{1}(u) \Rightarrow X^{1}(S(u))) \Rightarrow X^{1}(v) \big), \qquad (\mathsf{N}^{\wedge})$$

where v is a variable of kind ι . Recall that X^1 is a predicate variable of kind $\iota \to \star$ (in the domain \mathbb{N} , it is interpreted as a property of the subsets of \mathbb{N}). We also have the following axioms:

$$\begin{aligned} \forall v(v = v) \\ \forall u \forall v \forall w ((u = v) \Rightarrow ((u \Rightarrow w) \Rightarrow (v = w))) \\ \forall u \forall v ((Su = Sv) \Rightarrow (u = v)) \\ \forall u \forall v ((u = v) \Rightarrow (Su = Sv)) \\ \forall u (\neg (Su = 0)). \end{aligned}$$

Again, we emphasize that \mathbf{HA}^{2*} has no induction axiom.

However, it is also worth noting that using Proposition 2.15, it is easy to show that the induction axiom (Ind²) is equivalent to $\forall v (v \in \mathbb{N}^{\wedge})$.

⁴The superscript \wedge indicates that the formula $\mathsf{N}^{\wedge}(v)$ contains the connective \wedge . We will also define shortly a version $\mathsf{N}(v)$ that only uses the connective \Rightarrow .

Intuitively, the property $N^{\wedge}(v)$ defines the set of natural numbers as the smallest set containing 0 and closed under the successor function S. And indeed, the standard model of the above axioms is the set N of natural numbers. The idea of defining the natural numbers this way goes back to Dedekind in his famous paper of 1888 (Was sind und was sollen die Zallen?).

Observe that the axioms of \mathbf{HA}^{2*} are either axioms of \mathbf{HA}^2 or are provable from the axioms of \mathbf{HA}^2 , but \mathbf{HA}^{2*} does not have the induction axiom (Ind²), so \mathbf{HA}^{2*} is a subsystem of \mathbf{HA}^2 ; every sequent provable in \mathbf{HA}^{2*} is provable in \mathbf{HA}^2 .

The main reason for introducing the Dedekind predicate \mathbb{N}^{\wedge} is that there is a way of translating every formula φ of \mathbf{HA}^2 into a formula $\varphi^{\mathbb{D}}$ in which the quantifiers are relatived (the first order quantifiers $\forall u$ and $\exists u$ being relatived to \mathbb{N}), such that every closed formula φ provable in \mathbf{HA}^2 is mapped to a formula $\varphi^{\mathbb{D}}$ provable in \mathbf{HA}^{2*} , and the induction axiom (Ind²) of Definition 7.28 becomes provable in \mathbf{HA}^{2*} . So in fact, \mathbf{HA}^{2*} is as poweful as \mathbf{HA}^2 .

Later in Section 7.10, we will need to map formulae \mathbf{HA}^{2*} to types in system F and proofs in \mathbf{HA}^{2*} to terms in system F. Technically, the formula $\mathsf{N}^{\wedge}(v)$ needs to be mapped to the type Nat, which only contain the type constructor \rightarrow , but $\mathsf{N}^{\wedge}(v)$ contains the connective \wedge , which causes a problem. The way around this is to use an equivalent definition of $\mathsf{N}^{\wedge}(v)$ that uses only the connective \Rightarrow , namely

$$\mathsf{N}(v) \equiv v \in \mathsf{N} := \forall X^1 \big(X^1(0) \Rightarrow \big(\forall u(X^1(u) \Rightarrow X^1(S(u))) \Rightarrow X^1(v) \big) \big). \tag{N}$$

Proposition 7.6. The predicates $N^{(v)}$ and N(v) are equivalent (in HA^{2*}).

Proof. First we prove the equivalence

$$(P \Rightarrow (Q \Rightarrow R)) \equiv ((P \land Q) \Rightarrow R).$$

The implication $(P \Rightarrow (Q \Rightarrow R)) \Rightarrow ((P \land Q) \Rightarrow R)$ is shown by the following proof tree:

$$\frac{y \colon P \land Q \to P \land Q}{x \colon P \Rightarrow (Q \Rightarrow R) \to P \Rightarrow (Q \Rightarrow R)} \frac{y \colon P \land Q \to P \land Q}{y \colon P \land Q \to P} \qquad \frac{y \colon P \land Q \to P \land Q}{y \colon P \land Q \to Q}$$

$$\frac{x \colon P \Rightarrow (Q \Rightarrow R), y \colon P \land Q \to Q \Rightarrow R}{\frac{x \colon P \Rightarrow (Q \Rightarrow R), y \colon P \land Q \to R}{x \colon P \Rightarrow (Q \Rightarrow R) \to (P \land Q) \Rightarrow R}}$$

$$\frac{y \colon P \land Q \to P \land Q}{y \colon P \land Q \to Q}$$

The implication $((P \land Q) \Rightarrow R) \Rightarrow (P \Rightarrow (Q \Rightarrow R))$ is shown by the following proof tree:

$$\begin{array}{c} \underbrace{x \colon (P \land Q) \Rightarrow R \rightarrow (P \land Q) \Rightarrow R} & \underbrace{y \colon P, z \colon Q \rightarrow P \quad y \colon P, z \colon Q \rightarrow Q}_{y \colon P, z \colon Q \rightarrow P \land Q} \\ \\ \hline \\ \frac{x \colon (P \land Q) \Rightarrow R, y \colon P, z \colon Q \rightarrow R}{x \colon (P \land Q) \Rightarrow R, y \colon P \rightarrow Q \Rightarrow R} \\ \hline \\ \frac{x \colon (P \land Q) \Rightarrow R, y \colon P \rightarrow Q \Rightarrow R}{x \colon (P \land Q) \Rightarrow R \rightarrow P \Rightarrow (Q \Rightarrow R)} \\ \hline \\ \rightarrow ((P \land Q) \Rightarrow R) \Rightarrow (P \Rightarrow (Q \Rightarrow R)) \end{array} .$$

If we set

$$P(X) \equiv X(0), \qquad Q(X) \equiv \forall u(X^{1}(u) \Rightarrow X^{1}(S(u))), \qquad R(X) \equiv X^{1}(v),$$

we have shown that

$$(X^1(0) \land \forall u(X^1(u) \Rightarrow X^1(S(u))) \Rightarrow X^1(v)) \equiv (X^1(0) \Rightarrow (\forall u(X^1(u) \Rightarrow X^1(S(u))) \Rightarrow X^1(v))).$$

Then it is easy to see that we obtain an equivalence by universally quantifying over X, namely

$$\mathsf{N}^{\wedge}(v) \equiv \mathsf{N}(v).$$

The completes the proof of the equivalence of $N^{\wedge}(v)$ and N(v).

From now on, we will use N(v).

Remark: The induction axiom

$$\forall X^1 \big(X^1(0) \land \forall x (X^1(x) \Rightarrow X^1(Sx)) \Rightarrow \forall v X^1(v) \big)$$
 (Ind²)

can be stated by a formula that only uses the connective \Rightarrow , namely

$$\forall X^1 \big(X^1(0) \Rightarrow \big(\forall x (X^1(x) \Rightarrow X^1(Sx)) \Rightarrow \forall v X^1(v) \big) \big).$$
 (Ind^{2'})

The equivalence of these two versions of the induction axiom can be shown using the method used in proving the equivalence of $N^{\wedge}(v) N(v)$. The version Ind^2 seems to be used more often.

A priori, the predicate $v \in \mathbb{N}$ may not be satisfied by any term in the language, but in fact, $S^m(0) \in \mathbb{N}$ for all $m \in \mathbb{N}$, as implied by the following proposition.

Proposition 7.7.

(1) The following formula holds:

$$\forall v((v \in \mathsf{N}) \Rightarrow (S(v) \in \mathsf{N})).$$

(2) We have $S^m(0) \in \mathbb{N}$ for all $m \in \mathbb{N}$. Furthermore, normal proofs of $S^m(0) \in \mathbb{N}$ are shown below, and they are unique.

(3) The following formula holds for all $m \in \mathbb{N}$:

$$\forall v((v \in \mathsf{N}) \Rightarrow (S^m(v) \in \mathsf{N})).$$

Proof. (1) Abbreviating $\forall u(X(u) \Rightarrow X(S(u)))$ as I, we have the following proof:

$$\frac{y \colon v \in \mathbb{N} \to v \in \mathbb{N}}{y \colon v \in \mathbb{N} \to (X(0) \Rightarrow (I \Rightarrow X(v))} \quad z \colon X(0) \to X(0)}$$

$$\frac{x \colon I \to \forall u(X(u) \Rightarrow X(S(u)))}{x \colon I \to X(v) \Rightarrow X(S(v))} \qquad \frac{y \colon v \in \mathbb{N}, z \colon X(0) \to I \Rightarrow X(v)}{x \colon I, y \colon v \in \mathbb{N}, z \colon X(0) \to X(v)} \quad x \colon I \to I$$

$$\frac{x \colon \forall u(X(u) \Rightarrow X(S(u))), y \colon v \in \mathbb{N}, z \colon X(0) \to X(s(v))}{y \colon v \in \mathbb{N}, z \colon X(0) \to \forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(S(v))}$$

$$\frac{y \colon v \in \mathbb{N} \to X(0) \Rightarrow (\forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(S(v)))}{y \colon v \in \mathbb{N} \to \forall X(X(0) \Rightarrow (\forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(S(v))))}$$

$$\frac{y \colon v \in \mathbb{N} \to \forall X(X(0) \Rightarrow (\forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(S(v))))}{y \colon v \in \mathbb{N} \to \forall v((v \in \mathbb{N}) \Rightarrow (S(v) \in \mathbb{N}))}$$

(2) For m = 0, for any X^1 , we have the following normal proof $\mathcal{D}[0]$ of $0 \in \mathbb{N}$:

$$\frac{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(0)}{x \colon X(0) \to \forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(0)}$$
$$\xrightarrow{\rightarrow X(0) \Rightarrow (\forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(0))}$$
$$\xrightarrow{\rightarrow \forall X (X(0) \Rightarrow (\forall u(X(u) \Rightarrow X(S(u))) \Rightarrow X(0)))}$$

Observe that the first step of the proof is a normal deduction of

 $x\colon X(0),y\colon \forall u(X(u)\Rightarrow X(S(u)))\to X(0).$

By induction, if d[m] is a normal deduction of

$$x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(\mathbf{m}),$$

abbreviating $\forall u(X(u) \Rightarrow X(S(u)))$ as *I*, we have the following normal deduction d[m+1] of $x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m})) \in \mathsf{N}$,

$$\frac{y \colon I \to \forall u(X(u) \Rightarrow X(S(u)))}{y \colon I \to X(\mathbf{m}) \Rightarrow X(S(\mathbf{m}))} \frac{d[m]}{x \colon X(0), y \colon I \to X(\mathbf{m})}$$
$$\frac{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m}))}{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m}))},$$

and the proof $\mathcal{D}[m+1]$ of $S(\mathbf{m}) \in \mathsf{N}$ is given by

The proof $\mathcal{D}[m]$ is called the *standard normal proof* in \mathbf{HA}^{2*} of the fact that $\mathbf{m} \in \mathbb{N}$, for every numeral $\mathbf{m} = S^m(0)$. This normalized proof is unique; see Troelstra and Schwichtenberg [73] (Lemma 11.5.6).

(3) The formula $\forall v((v \in \mathsf{N}) \Rightarrow (S^m(v) \in \mathsf{N}))$ is proven by induction using Part (1). Details are left as an exercise.

We now describe the translation that maps a formula φ to a formula $\varphi^{\mathbb{D}}$ in such a way that if φ is provable in \mathbf{HA}^2 , then $\varphi^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} . This translation is achieved by relativization of quantifiers.

7.8 Relativization of Quantifiers; the \mathbb{D} -Translation

Definition 7.31. Define the predicates $Ext(X^n)$, also denoted $X^n \in Ext$, by

$$X^{n} \in \mathsf{Ext} := \forall u_{1} \cdots \forall u_{n} \forall v_{1} \cdots \forall v_{n} \big(\big((u_{1} \in \mathsf{N} \land \cdots \land u_{n} \in \mathsf{N} \land v_{1} \in \mathsf{N} \land \cdots \land v_{n} \in \mathsf{N}) \land (u_{1} = v_{1}) \land \cdots \land (u_{n} = v_{n}) \land X^{n}(u_{1}, \dots, u_{n}) \big) \Rightarrow X^{n}(v_{1}, \dots, v_{n}) \big).$$

Since Ext takes as input a predicate variable of arity n, technically we have a family of n-ary predicates Ext^n , but for simplicity of notation we omit the superscript n in Ext^n . Given any formula φ of HA^2 , the formula $\varphi^{\mathbb{D}}$ of $\operatorname{HA}^{2*}(\mathbb{D})$ in honor of Dedekind) is obtained by relativizing the quantifiers. Technically, the translation is defined as follows, where P and Q denote arbitrary second-order formulae.

$$(P(t_1, \dots, t_m))^{\mathbb{D}} = P(t_1, \dots, t_m) \quad (\text{atomic formulae})$$
$$(\forall u P)^{\mathbb{D}} = \forall u(u \in \mathbb{N} \Rightarrow P^{\mathbb{D}})$$
$$(\exists u P)^{\mathbb{D}} = \exists u(u \in \mathbb{N} \land P^{\mathbb{D}})$$
$$(\forall X^n, P)^{\mathbb{D}} = \forall X^n (X^n \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})$$
$$(\exists X^n, P)^{\mathbb{D}} = \exists X^n ((X^n \in \mathsf{Ext}) \land P^{\mathbb{D}})$$
$$(P \Rightarrow Q)^{\mathbb{D}} = P^{\mathbb{D}} \Rightarrow Q^{\mathbb{D}}$$
$$(P \land Q)^{\mathbb{D}} = P^{\mathbb{D}} \land Q^{\mathbb{D}}$$
$$(P \lor Q)^{\mathbb{D}} = P^{\mathbb{D}} \lor Q^{\mathbb{D}}$$
$$(\neg P)^{\mathbb{D}} = \neg P^{\mathbb{D}}.$$

The Ext-predicate is introduced in Troelstra and Van Dalen [74] (Chapter 3, Section 9), where some of its properties are proven. In particular, see the Theorem in Section 9.2. It can be shown that $N \in Ext$.

We now show that the \mathbb{D} -translation of the induction axiom (Ind²) of Definition 7.28 becomes provable in **HA**^{2*}, which is the main reason why the \mathbb{D} -translation was introduced.

Proposition 7.8. The \mathbb{D} -translation of the induction axiom

$$\forall X^1 \big(X^1(0) \land \forall u (X^1(u) \Rightarrow X^1(S(u))) \Rightarrow \forall v X^1(v) \big)$$
 (Ind²)

is the formula

$$\forall X^1 \Big(X^1 \in \mathsf{Ext} \Rightarrow \Big(X^1(0) \land \forall u \Big[u \in \mathsf{N} \Rightarrow (X^1(u) \Rightarrow X^1(S(u))) \Big] \Rightarrow \forall v [v \in \mathsf{N} \Rightarrow X^1(v)] \Big) \Big), \quad (\mathrm{Ind}^2 \mathbb{D})$$

and the formula (Ind²D) is provable in \mathbf{HA}^{2*} (with the predicate N(v)).

Proof. Since we adopted the version (Ind^2) of the induction axiom that uses the connective \wedge , we find it convenient to use the predicate $\mathsf{N}^{\wedge}(v)$, so we prove that the formula $(\text{Ind}^2\mathbb{D})$ is provable in \mathbf{HA}^{2*} with the predicate $\mathsf{N}^{\wedge}(v)$. Since the predicates $\mathsf{N}^{\wedge}(v)$ and $\mathsf{N}(v)$ are equivalent (in \mathbf{HA}^{2*}) by Proposition 7.6, the formula $(\text{Ind}^2\mathbb{D})$ is also provable in \mathbf{HA}^{2*} with the predicate sinvited to find a proof that uses $\mathsf{N}(v)$ directly. The \mathbb{D} -translation of the axiom (Ind² \mathbb{D}) in terms of the predicate N^{\wedge} is

$$\forall X^1 \Big(X^1 \in \mathsf{Ext} \Rightarrow \Big(X^1(0) \land \forall u \Big[u \in \mathsf{N}^{\land} \Rightarrow (X^1(u) \Rightarrow X^1(S(u))) \Big] \Rightarrow \forall v [v \in \mathsf{N}^{\land} \Rightarrow X^1(v)] \Big) \Big). \quad (\mathrm{Ind}^2 \mathbb{D}^{\land})$$

Since we have the following proof,

$$\begin{split} \frac{x \colon X \in \mathsf{Ext}, y \colon \forall X. \ P(X) \to \forall X. \ P(X)}{x \colon X \in \mathsf{Ext}, y \colon \forall X. \ P(X) \to P(X)} \\ \frac{y \colon \forall X. \ P(X) \to (X \in \mathsf{Ext} \Rightarrow P(X))}{y \colon \forall X. \ P(X) \to \forall X. \ (X \in \mathsf{Ext} \Rightarrow P(X))} \\ \hline \\ \frac{y \colon \forall X. \ P(X) \to \forall X. \ (X \in \mathsf{Ext} \Rightarrow P(X))}{\Rightarrow \forall X. \ P(X) \Rightarrow \forall X(X \in \mathsf{Ext} \Rightarrow P(X))}, \end{split}$$

with

$$P(X) = X^{1}(0) \land \forall u \big[u \in \mathsf{N}^{\wedge} \Rightarrow (X^{1}(u) \Rightarrow X^{1}(S(u))) \big] \Rightarrow \forall v [v \in \mathsf{N}^{\wedge} \Rightarrow X^{1}(v)],$$

we see that if we can prove

$$\forall X \big(X(0) \land \forall u \big[u \in \mathsf{N}^{\land} \Rightarrow (X(u) \Rightarrow X(S(u))) \big] \Rightarrow \forall v [v \in \mathsf{N}^{\land} \Rightarrow X(v)] \big), \qquad (\dagger_{2*})$$

in \mathbf{HA}^{2*} , then the \mathbb{D} -translation $\mathrm{Ind}^2\mathbb{D}$ is also provable in \mathbf{HA}^{2*} .

It is not so obvious why the formula (\dagger_{2*}) is provable in \mathbf{HA}^{2*} , but we can use the following clever trick (thanks to Henry Townser for sharing it with us).

Since

$$v \in \mathsf{N}^{\wedge} \equiv \forall X \big(X(0) \land \forall u (X(u) \Rightarrow X(S(u))) \Rightarrow X(v) \big),$$

we can apply the $(\forall X \text{-elim})$ rule to the axiom

$$x \colon v \in \mathsf{N}^{\wedge} \to v \in \mathsf{N}^{\wedge},$$

namely

$$x \colon v \in \mathbb{N}^{\wedge} \to \forall X \big(X(0) \land \forall u (X(u) \Rightarrow X(S(u))) \Rightarrow X(v) \big)$$

with $X = \lambda u \colon \iota. (Y(u) \land (u \in \mathbb{N}^{\wedge}))$, for an arbitrary unary predicate variable Y. We obtain that

$$\begin{aligned} x \colon v \in \mathbb{N}^{\wedge} \to (Y(0) \land 0 \in \mathbb{N}^{\wedge}) \land \forall u \big((Y(u) \land u \in \mathbb{N}^{\wedge}) \Rightarrow (Y(S(u)) \land S(u) \in \mathbb{N}^{\wedge}) \big) \\ \Rightarrow Y(v) \land v \in \mathbb{N}^{\wedge}. \end{aligned}$$
(†3)

is provable.

From Proposition 7.7, we have $0 \in \mathbb{N}^{\wedge}$, and the implication $(u \in \mathbb{N}^{\wedge}) \Rightarrow (S(u) \in \mathbb{N}^{\wedge})$ is provable. The key point is to prove the formula.

$$\forall u \big(u \in \mathsf{N}^{\wedge} \Rightarrow (Y(u) \Rightarrow Y(S(u))) \big) \Rightarrow \forall u \big((Y(u) \land u \in \mathsf{N}^{\wedge}) \Rightarrow (Y(S(u)) \land S(u) \in \mathsf{N}^{\wedge}) \big). \ (\dagger_4)$$

For this is it convenient to introduce the following notation. Let A, B, C, D be the formulae

$$A \equiv Y(u), \qquad B \equiv u \in \mathbb{N}^{\wedge}, \qquad C \equiv Y(S(u)), \qquad D \equiv S(u) \in \mathbb{N}^{\wedge}$$

Then (\dagger_4) becomes

$$\forall u (B \Rightarrow (A \Rightarrow C)) \Rightarrow \forall u ((A \land B) \Rightarrow (C \land D)).$$
 (†_{4'})

Assuming that (\dagger_4) has been proven (which we will do shortly), with the abbreviations introduced earlier,

$$Y(0) \land \forall u \big[u \in \mathbb{N}^{\wedge} \Rightarrow (Y(u) \Rightarrow Y(S(u))) \big], \tag{\ddagger}_{5}$$

which occurs as a premise in (\dagger_{2*}) with X instead of Y, becomes

$$Y(0) \land \forall u [B \Rightarrow (A \Rightarrow C))], \tag{\dagger}_6$$

and

$$x: v \in \mathbb{N}^{\wedge} \to (Y(0) \land 0 \in \mathbb{N}^{\wedge}) \land \forall u ((Y(u) \land u \in \mathbb{N}^{\wedge}) \Rightarrow (Y(S(u)) \land S(u) \in \mathbb{N}^{\wedge}))$$

$$\Rightarrow Y(v) \land v \in \mathbb{N}^{\wedge}.$$
(†3)

becomes

$$x \colon v \in \mathbb{N}^{\wedge} \to (Y(0) \land 0 \in \mathbb{N}^{\wedge}) \land \forall u ((A \land B) \Rightarrow C \land D)) \Rightarrow Y(v) \land v \in \mathbb{N}^{\wedge}.$$
(†7)

Since

$$\forall u (B \Rightarrow (A \Rightarrow C)) \Rightarrow \forall u ((A \land B) \Rightarrow (C \land D))$$
 (†_{4'})

and $0 \in \mathsf{N}^{\wedge}$ are provable, we see immediately that

$$Y(0) \land \forall u (B \Rightarrow (A \Rightarrow C)) \Rightarrow (Y(0) \land 0 \in \mathbb{N}^{\wedge}) \land \forall u ((A \land B) \Rightarrow (C \land D))$$
([†]₈)

is provable, so (\dagger_7) and (\dagger_8) imply that

$$x \colon v \in \mathsf{N}^{\wedge}, y \colon Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \to Y(v) \land v \in \mathsf{N}^{\wedge}$$

is provable (by transitivity of implication), and then we finish the proof as follows:

$$\begin{split} \frac{x \colon v \in \mathsf{N}^{\wedge}, y \colon Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \to Y(v) \land v \in \mathsf{N}^{\wedge} }{x \colon v \in \mathsf{N}^{\wedge}, y \colon Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \to Y(v) \\ \hline y \colon Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \to v \in \mathsf{N}^{\wedge} \Rightarrow Y(v) \\ \hline y \colon Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \to \forall v (v \in \mathsf{N}^{\wedge} \Rightarrow Y(v)) \\ \hline \to Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \Rightarrow \forall v (v \in \mathsf{N}^{\wedge} \Rightarrow Y(v)) \\ \hline \to \forall Y \big(Y(0) \land \forall u \big(B \Rightarrow (A \Rightarrow C) \big) \Rightarrow \forall v (v \in \mathsf{N}^{\wedge} \Rightarrow Y(v)) \big), \end{split}$$

which shows that

$$\forall Y \big(Y(0) \land \forall u \big[u \in \mathsf{N}^{\land} \Rightarrow (Y(u) \Rightarrow Y(S(u))) \big] \Rightarrow \forall v [v \in \mathsf{N}^{\land} \Rightarrow Y(v)] \big) \qquad (\dagger_{2*})$$

is provable in \mathbf{HA}^{2*} .

We still need to prove $(\dagger_{4'})$, which is done as follow. Since $(u \in \mathsf{N}^{\wedge}) \Rightarrow (S(u) \in \mathsf{N}^{\wedge})$ is provable, $B \Rightarrow D$ is provable.

We have the proof

$$\frac{x \colon B \Rightarrow (A \Rightarrow C) \to B \Rightarrow (A \Rightarrow C)}{x \colon B \Rightarrow (A \Rightarrow C), y \colon A \land B \to A \Rightarrow C} \frac{y \colon A \land B \to A \land B}{y \colon A \land B \to A \Rightarrow C} \quad \frac{y \colon A \land B \to A \land B}{y \colon A \land B \to A}$$
$$\frac{x \colon B \Rightarrow (A \Rightarrow C), y \colon A \land B \to C}{x \colon B \Rightarrow (A \Rightarrow C), y \colon A \land B \to C},$$

since $B \Rightarrow D$ is provable, we also have the proof

$$\frac{\rightarrow B \Rightarrow D}{y: A \land B \rightarrow A \land B}{y: A \land B \rightarrow B},$$

and by combining the above trees, we obtain a proof of

$$x \colon B \Rightarrow (A \Rightarrow C), y \colon A \land B \to C \land D,$$

and then the rest of the proof is

$$\frac{x \colon B \Rightarrow (A \Rightarrow C), y \colon A \land B \to C \land D}{x \colon B \Rightarrow (A \Rightarrow C) \to (A \land B) \Rightarrow (C \land D)}$$
$$\xrightarrow{} (B \Rightarrow (A \Rightarrow C)) \Rightarrow ((A \land B) \Rightarrow (C \land D)).$$

Then it is easy to prove that the above implies that

$$\forall u (B \Rightarrow (A \Rightarrow C)) \Rightarrow \forall u ((A \land B) \Rightarrow (C \land D))$$
([†]₄)

is provable.

This is one of the virtues of the system \mathbf{HA}^{2*} ; a relativized induction axiom (Ind²D) is provable.

More generally, the following result can be shown by induction on the structure of proofs. See Troelstra and Schwichtenberg [73] (Fact 11.5.4).

7.9 The Equivalence of HA^2 and HA^{2*} via the \mathbb{D} -Map

Proposition 7.9. If a closed formula P is provable in \mathbf{HA}^2 , then $P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} . Technically, to prove Proposition 7.9, we need to deal with deductions from premises and we need to allow formulae that contain free first order variables and free predicate variables. So given a sequent $\Gamma \to P$, we prove that if $\Gamma \to P$ is derivable in \mathbf{HA}^2 (possibly using the induction axiom (Ind²)), then there is a sequent

$$\Delta, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}} \tag{(*_{\mathbb{D}})}$$

satisfying the following properties:

- (1) The sequent $(*_{\mathbb{D}})$ is provable in \mathbf{HA}^{2*} (without the axiom (Ind²)).
- (2) If $\Gamma = \{x_1 : P_1, \dots, x_m : P_m\}$, then $\Gamma^{\mathbb{D}} = \{x_1 : P_1^{\mathbb{D}}, \dots, x_m : P_m^{\mathbb{D}}\}$.
- (3) The set Δ is a set of premises of the form $x \colon N(v_i)$ or $x \colon Ext(X_j)$, where the v_i are distinct first-order variables and the X_j are distinct predicate variables (these variables belong to terms and formulae occurring in the proof of $\Gamma \to P$).

If P closed and provable \mathbf{HA}^2 , then $P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} (with $\Delta = \emptyset$).

In the course of proving Proposition 7.9, it is necessary to add new premises of the form $N(v_i)$ or $Ext(X_i)$ to a sequent. To do this, it is convenient to add a weakening rule.

Definition 7.32. The *weakening rule* is the rule

$$\frac{\Gamma \to P}{z \colon Q, \Gamma \to P} \quad (W),$$

for any second-order formulae P and Q (P = Q is allowed), and z is a new variable not in Γ .

The following proposition shows that the weakening rule does not allow proving more formulae.

Proposition 7.10. The following facts hold.

- (1) If $\rightarrow P$ is an axiom, then $\Gamma \rightarrow P$ is provable for any Γ without using the weakening rule.
- (2) If the sequent $\Gamma \to P$ is derivable without using the weakening rule (where $\Gamma = \emptyset$ is allowed), then for any Q (P = Q is possible), $\Gamma, z \colon Q \to P$ is derivable without using the weakening rule, where z is a new variable not occurring in Γ .
- (3) If the sequent $\Gamma \to P$ is derivable using the weakening rule, then $\Gamma \to P$ is derivable without using the weakening rule.

Proof. (1) We have the deduction

$$\frac{\Gamma, P \to P}{\Gamma \to P \Rightarrow P} \to P$$

$$\frac{\Gamma \to P \Rightarrow P}{\Gamma \to P}$$

(2) We use induction on the depth of the derivation. In the base case, if we have an axiom $\Gamma, x: P \to P$, then $\Gamma, x: P, z: Q \to P$ is also an axiom. If $\to P$ is an axiom, then by Part (1), $z: Q \to P$ is provable without using weakening. For the induction step, if $\Delta \to R$ is one of the premises of any rule of Definition 7.25 with conclusion $\Gamma \to P$, by the induction hypothesis, $\Delta, z: Q \to R$ is derivable without using weakening where the *same* new variable used in all of these premises (up to three), and then the shape of these rules implies that $\Gamma, z: Q \to P$ is derivable without using weakening.

(3) We proceed by induction on the number of times that the weakening rule is used. If it is not used, then we have our weakening-free derivation.

If the weakening rule is used as the last inference, then there are two subcases.

(1) The deduction is of the form

$$\frac{\Gamma, x \colon P \to P}{z \colon Q, \Gamma, x \colon P \to P} \quad (\mathbf{W}),$$

where the premise is an axiom. In this case, $z: Q, \Gamma, x: P \to P$ is also an axiom (and the weakening rule is not used). The deduction is of the form

$$\frac{\to P}{z \colon Q \to P} \quad (W),$$

where the premise is an axiom. In this case, by Part (1), $z: Q \to P$ is provable without the weakening rule.

(2) The deduction is of the form

$$\frac{\mathcal{D}}{\frac{\Gamma \to P}{z \colon Q, \Gamma \to P}}, \quad (W)$$

where \mathcal{D} has depth ≥ 1 . In this case, by Part (2), there is a deduction

$$\begin{array}{c} \mathcal{D}'\\ z\colon Q, \Gamma \to P \end{array}$$

that does not use any weakening.

If the weakening rule is used, but *not* as the last inference, then we apply the induction hypothesis to the premises and we obtain a deduction without weakening. \Box

For convenience, we introduce the following special weakening rules:

$$\frac{\Gamma \to P}{z \colon \mathsf{N}(v_i), \Gamma \to P} \quad (W1),$$

and

$$\frac{\Gamma \to P}{z \colon \mathsf{Ext}(X_j), \Gamma \to P} \quad (W2),$$

for a new variable z.

Sketch of proof for Proposition 7.9. There is a preliminary step, which is to extend the definition of Ext to second-order formulae $\varphi(w_1, \ldots, w_n)$ with free first-order-variables w_1, \ldots, w_n , where

$$\mathsf{Ext}(\varphi) := \forall u_1 \cdots \forall u_n \forall v_1 \cdots \forall v_n \big(\big((u_1 \in \mathsf{N} \land \cdots \land u_n \in \mathsf{N} \land v_1 \in \mathsf{N} \land \cdots \land v_n \in \mathsf{N}) \land (u_1 = v_1) \land \cdots \land (u_n = v_n) \land \varphi(w_1 := u_1, \dots, w_n := u_n) \big) \Rightarrow \varphi(w_1 := v_1, \dots, w_n := v_n) \big).$$

If φ contains the free predicate variables X_1, \ldots, X_s , we can prove by induction on the depth of φ that

 $\mathsf{Ext}(X_1) \land \dots \land \mathsf{Ext}(X_s) \Rightarrow \mathsf{Ext}(\varphi).$

In particular, $\mathsf{Ext}(\varphi)$ is provable for every formula φ with no free predicate variables.

As to the proof that the translation works, we proceed by induction on the depth of proofs. A nonequational axiom of the form $\Gamma \to P$ it translated to $\Gamma^{\mathbb{D}} \to P^{\mathbb{D}}$, which is obviously an axiom in \mathbf{HA}^{2*} .

Now that we dealt with the induction axiom (Ind^2) , the other equational axioms are easy to deal with. Except for the second axiom, the other equational axioms of HA^2 are also axioms of HA^{2*} . The method is to use the weakening rule. Let us work out the translation of the axiom

$$\forall u \forall v \big((Su = Sv) \Rightarrow (u = v) \big)$$

which is also an axiom of \mathbf{HA}^{2*} . We have the following proof in \mathbf{HA}^{2*} :

$$\frac{ \rightarrow \forall u \forall v \left((Su = Sv) \Rightarrow (u = v) \right) }{ \rightarrow \forall v \left((Su = Sv) \Rightarrow (u = v) \right) } }{ \rightarrow \forall v \left((Su = Sv) \Rightarrow (u = v) \right) }$$
(W1)
$$\frac{ (W1)}{x : \mathsf{N}(u) \to (Su = Sv) \Rightarrow (u = v) }$$
(W1)
$$\frac{x : \mathsf{N}(u), y : \mathsf{N}(v) \to (Su = Sv) \Rightarrow (u = v) }{x : \mathsf{N}(u) \to v \in \mathsf{N}(v) \Rightarrow \left((Su = Sv) \Rightarrow (u = v) \right) }$$
(W1)
$$\frac{x : \mathsf{N}(u) \to \forall v \left(v \in \mathsf{N}(v) \Rightarrow \left((Su = Sv) \Rightarrow (u = v) \right) \right) }{x : \mathsf{N}(u) \Rightarrow \forall v \left(v \in \mathsf{N}(v) \Rightarrow \left((Su = Sv) \Rightarrow (u = v) \right) \right) }$$
(W1)
$$\frac{x : \mathsf{N}(u) \to \forall v \left(v \in \mathsf{N}(v) \Rightarrow \left((Su = Sv) \Rightarrow (u = v) \right) \right) }{x : \mathsf{N}(u) \Rightarrow \forall v \left(v \in \mathsf{N}(v) \Rightarrow \left((Su = Sv) \Rightarrow (u = v) \right) \right) }$$

Showing that the \mathbb{D} -translation of the second axiom of \mathbf{HA}^2 is provable in \mathbf{HA}^{2*} uses the property of Ext.

The only rules that are slightly tricky are the $(\forall$ -elim) rule

$$\frac{\Gamma \to \forall v \colon \iota. P}{\Gamma \to P[v := t]} \quad (\forall \text{-}elim),$$

where t is a first order term possibly with free variable u, and the $(\forall X$ -elim) rule

$$\frac{\Gamma \to \forall X \colon K_n. P}{\Gamma \to P[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi]} \quad (\forall X \text{-elim}),$$

where φ is any second order-formula and the substitution is safe.

For the $(\forall$ -elim) rule, by the induction hypothesis, we have a proof of

$$\Delta_1, \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})$$

for some Δ_1 . If t is a closed term, then t is of the form $t = S^m(0)$, and we have the proof

$$\frac{\Delta_1, \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}{\Delta_1, \Gamma^{\mathbb{D}} \to (t \in \mathsf{N} \Rightarrow P^{\mathbb{D}}[v := t])}.$$

By Proposition 7.7, $S^m(0) \in \mathbb{N}$ is provable, and since $t = S^m(0)$,

$$\Delta_1, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := t])$$

is provable.

If t contains the free variable u, then t is of the form $t = S^m(u)$, and if N(u) does not occurs in Δ_1 , we have a deduction

$$\frac{\Delta_1, \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}{\Delta_1, x \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}$$
(W1)
$$\overline{\Delta_1, x \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to (t \in \mathsf{N} \Rightarrow P^{\mathbb{D}}[v := t])}.$$

If N(u) occurs in Δ_1 , then Δ_1 is of the form $\Delta_1 = \Delta_2, x \colon N(u)$ where N(u) does not occur in Δ_2 , and then the weakening rule (W1) is omitted and we have

$$\frac{\Delta_2, x \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}{\Delta_2, x \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to (t \in \mathsf{N} \Rightarrow P^{\mathbb{D}}[v := t])}$$

Fortunately, by Proposition 7.7, we also have a proof of $N(u) \to S^m(u) \in \mathbb{N}$, and since $t = S^m(u)$, we can conclude that

$$\Delta_i, x \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := t])$$

is indeed provable, i = 1, 2.

For the $(\forall X \text{-elim})$ rule, by the induction hypothesis, we have a proof of

$$\Delta_1, \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}}).$$

If φ does not have any free predicate variables, we have the deduction

$$\frac{\Delta_1, \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})}{\Delta_1, \Gamma^{\mathbb{D}} \to (\varphi \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}}[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi])}.$$

However, since φ is closed, we know that $\mathsf{Ext}(\varphi)$ is provable, so

$$\Delta_1, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota, \varphi]$$

is provable.

Otherwise, let $\{X_1, \ldots, X_s\}$ be the set of free predicate variables in φ . Then we have following deduction in which the weakening rule (W2) is applied only if $\mathsf{Ext}(X_i)$ does not occur in Δ_1 :

$$\begin{split} & \underbrace{\frac{\Delta_1, \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})}{\vdots} \quad (W2) \\ & \vdots \\ \hline & \overline{\Delta_1, y_1 \colon \mathsf{Ext}(X_1), \dots, y_s \colon \mathsf{Ext}(X_s), \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})} \\ \hline & \overline{\Delta_1, y_1 \colon \mathsf{Ext}(X_1), \dots, y_s \colon \mathsf{Ext}(X_s), \Gamma^{\mathbb{D}} \to (\varphi \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}}[X \coloneqq \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi])}. \end{split}$$

Note that actually, $\Delta_1, y_1 \colon \mathsf{Ext}(X_1), \ldots, y_s \colon \mathsf{Ext}(X_s)$ has the property that none of the $\mathsf{Ext}(X_i)$ occur in Δ_1 .

Since we proved that

$$\mathsf{Ext}(X_1) \land \dots \land \mathsf{Ext}(X_s) \Rightarrow \mathsf{Ext}(\varphi),$$

we conclude that

$$\Delta_1, y_1 \colon \mathsf{Ext}(X_1), \dots, y_s \colon \mathsf{Ext}(X_s), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi]$$

is indeed provable.

We also show how to deal with the $(\forall$ -intro) rule

$$\frac{\Gamma \to P[v := u]}{\Gamma \to \forall v \colon \iota. P} \quad (\forall \text{-intro}),$$

and the $(\forall X \text{-intro})$ rule

$$\frac{\Gamma \to P[X := Y]}{\Gamma \to \forall X \colon K. P} \quad (\forall X \text{-}intro),$$

leaving the rules for $\Rightarrow, \land, \lor, \neg, \exists^2$ as an (easy) exercise. The rules for the first-order and second-order existential quantifiers are handled the same way that we dealt with the universal quantifiers.

For the $(\forall$ -intro) rule, by the induction hypothesis, we have a deduction of

$$\Delta_1, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := u].$$

There are two possibilities. If N(u) does not in Δ_1 , we obtain the deduction

$$\frac{\Delta_{1}, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := u]}{\Delta_{1}, z \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := u]} \qquad (W1)$$

$$\frac{\Delta_{1}, \Gamma^{\mathbb{D}} \to (u \in \mathsf{N} \Rightarrow P^{\mathbb{D}}[v := u])}{\Delta_{1}, \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}.$$

In the original deduction, u is not free in any premise in Γ and not free in $\forall v : \iota. P$, which means that either u = v or u is not free in P. Since a formula Q and its relativization $Q^{\mathbb{D}}$ have exactly the same free and bound variables, u does not occur free in any premise in $\Gamma^{\mathbb{D}}$, or in Δ_1 , or in $\forall v (v \in \mathbb{N} \Rightarrow P^{\mathbb{D}})$. If N(u) occurs in Δ_1 , we have $\Delta_1 = \Delta_2, z \colon N(u)$, where $z \colon N(u)$ does not occur in Δ_2 . We have the following deduction which does not require weakening:

$$\frac{\Delta_2, z \colon \mathsf{N}(u), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[v := u]}{\Delta_2, \Gamma^{\mathbb{D}} \to (u \in \mathsf{N} \Rightarrow P^{\mathbb{D}}[v := u])}{\Delta_2, \Gamma^{\mathbb{D}} \to \forall v (v \in \mathsf{N} \Rightarrow P^{\mathbb{D}})}.$$

By the same reasoning as above, u does not occur free in any premise in $\Gamma^{\mathbb{D}}$, or Δ_2 , or in $\forall v (v \in \mathbb{N} \Rightarrow P^{\mathbb{D}}).$

For the $(\forall X \text{-intro})$ rule, by the induction hypothesis, we have a deduction of

$$\Delta_1, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := Y].$$

There are two possibilities. If Ext(Y) does not occur in Δ_1 , we obtain the deduction

$$\frac{\Delta_{1}, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := Y]}{\Delta_{1}, y : \mathsf{Ext}(Y), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := Y]} \qquad (W2)$$

$$\frac{\Delta_{1}, \Gamma^{\mathbb{D}} \to (Y \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}}[X := Y])}{\Delta_{1}, \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})}.$$

)

As in the previous case, Y does not occur free in any premise in $\Gamma^{\mathbb{D}}$, or in Δ_1 , or in $\forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})$.

If $\mathsf{Ext}(Y)$ occurs in Δ_1 , we have $\Delta_1 = \Delta_2, z \colon \mathsf{Ext}(Y)$, where $z \colon \mathsf{Ext}(Y)$ does not occur in Δ_2 . We have the following deduction which does not require weakening:

$$\frac{\Delta_2, z \colon \mathsf{Ext}(Y), \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}[X := Y]}{\Delta_2, \Gamma^{\mathbb{D}} \to \forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})}.$$

Again, Y does not occur free in any premise in $\Gamma^{\mathbb{D}}$, or in Δ_2 , or in $\forall X (X \in \mathsf{Ext} \Rightarrow P^{\mathbb{D}})$.

The translation of the remaing rules is easy. Details are left to the reader. For example, consider the rule (\Rightarrow -elim):

$$\frac{\Gamma \to P \Rightarrow Q \quad \Delta \to P}{\Gamma \cup \Delta \to Q} \quad (\Rightarrow\text{-elim}).$$

By the induction hypothesis, we have deductions $\Gamma^{\mathbb{D}}, \Delta_1 \to P^{\mathbb{D}} \Rightarrow Q^{\mathbb{D}}$ and $\Delta^{\mathbb{D}}, \Delta_2 \to P^{\mathbb{D}}$. For every variable u such that $\mathsf{N}(u)$ occurs in both Δ_1 and Δ_2 as $x \colon \mathsf{N}(u)$ and $y \colon \mathsf{N}(u)$, we replace these two occurrences by $z \colon \mathsf{N}(u)$ for some fresh variable z, and then we obtain the deduction

$$\frac{\Delta_1, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}} \Rightarrow Q^{\mathbb{D}} \quad \Delta_2, \Delta^{\mathbb{D}} \to P^{\mathbb{D}}}{\Delta_1 \cup \Delta_2, \Gamma^{\mathbb{D}} \cup \Delta^{\mathbb{D}} \to P^{\mathbb{D}}},$$

where Δ_1 and Δ_2 are consistent, so every N(u) occurs once in $\Delta_1 \cup \Delta_2$ if N(u) occurs in Δ_1 and in Δ_2 . Finally, assume that P is closed and provable in \mathbf{HA}^2 . We just proved that there is some context Δ of the form

$$\Delta = \{x_1 \colon \mathsf{N}(v_1), \dots, x_n \colon \mathsf{N}(v_n), y_1 \colon \mathsf{Ext}(X_1), \dots, y_s \colon \mathsf{Ext}(X_s)\},\$$

such that $\Delta \to P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} . Furthermore, $P^{\mathbb{D}}$ is closed, so applying substitutions (first-order or second-order) has no effect. Let $T := \forall X^0$. $(X^0 \Rightarrow X^0)$, a closed provable formula. We can prove using the same method as above that

$$(\forall X_1 \in \mathsf{Ext}) \cdots (\forall X_s \in \mathsf{Ext}) (\forall v_1 \in \mathsf{N}) \cdots (\forall v_n \in \mathsf{N}) P^{\mathbb{D}}$$

is provable in \mathbf{HA}^{2*} . Recall that $(\forall X_1 \in \mathsf{Ext})$ is an abbreviation for $\forall X_1(X_1 \in \mathsf{Ext} \Rightarrow \cdots,$ so if we apply the $(\forall X\text{-elim})$ rule to

$$\forall X_1 (X_1 \in \mathsf{Ext} \Rightarrow (\forall X_s \in \mathsf{Ext}) (\forall v_1 \in \mathsf{N}) \cdots (\forall v_n \in \mathsf{N}) P^{\mathbb{D}})$$

with $X_1 := \lambda v_1 \cdots \lambda v_{k_1} \cdot T$ (where k_1 is the arity of X_1), since the formula just after $X_1 \in \mathsf{Ext} \Rightarrow$ is closed, the substitution has no effect and we get

$$T \in \mathsf{Ext} \Rightarrow (\forall X_s \in \mathsf{Ext})(\forall v_1 \in \mathsf{N}) \cdots (\forall v_n \in \mathsf{N}) P^{\mathbb{D}}$$

Since $T := \forall X^0. (X^0 \Rightarrow X^0)$ is a closed provable formula, $\mathsf{Ext}(T)$ is provable in \mathbf{HA}^{2*} , so we deduce that

$$(\forall X_s \in \mathsf{Ext})(\forall v_1 \in \mathsf{N}) \cdots (\forall v_n \in \mathsf{N})P^{\mathbb{D}}$$

is provable. Thus, by applying the $(\forall X \text{-elim})$ rule s times with $X_j := \lambda v_1 \cdots \lambda v_{k_j} T$ (where k_j is the arity of X_j), we deduce that

$$(\forall v_1 \in \mathsf{N}) \cdots (\forall v_n \in \mathsf{N}) P^{\mathbb{D}}$$

is provable in \mathbf{HA}^{2*} . Similarly, applying the (\forall -elim) rule *n* times with $v_i := 0$, since $\mathsf{N}(0)$ is provable \mathbf{HA}^{2*} , we finally obtain that $P^{\mathbb{D}}$ is provable in \mathbf{HA}^{2*} .

Remark: A closer look at the inductive proof that gives the construction of the \mathbb{D} -translation $\mathcal{D}^{\mathbb{D}}$ of a deduction \mathcal{D} in \mathbf{HA}^2 of a sequent $\Gamma \to P$, shows that the deduction $\mathcal{D}^{\mathbb{D}}$ in \mathbf{HA}^{2*} ends with a sequent $\Delta, \Gamma^{\mathbb{D}} \to P^{\mathbb{D}}$, where Δ is of the form

$$\Delta = \{x_1 \colon \mathsf{N}(v_1), \dots, x_n \colon \mathsf{N}(v_n), y_1 \colon \mathsf{Ext}(X_1), \dots, y_s \colon \mathsf{Ext}(X_s)\},\$$

and the variables v_j and X_k occur free in $P^{\mathbb{D}}$. As a consequence, if P is a closed formula and \mathcal{D} is proof, in which case $\Gamma = \emptyset$, then we must also have $\Delta = \emptyset$, so the end of the above proof is unnecessary.

Remark: It is tempting to view the definition of the predicate N(x) as the definition of a type N, and to view the deductiovn $\mathcal{D}[m]$ of the formula $N(\mathbf{m})$ as a type checking proof that $\mathbf{m} : \mathbf{N}$, namely that \mathbf{m} has type N. However, this is not the case because N really contains the
free variable x, so we would only be able to prove $\mathbf{m} \colon \mathsf{N}(x)$ for every $x \colon \iota$, which is impossible because \mathbf{m} has kind ι , which is not a type (a formula), so \mathbf{m} can't represent a proof. Note that $\mathsf{N}(x)$ is a type, a dependent type, but it can't be viewed as a type the natural numbers represented as the terms \mathbf{m} .

On the other hand, in system F, the Church numeral \mathbf{c}_m (see Definition 7.11) does type check with the type Nat. We will see in the next section that there is a map, called the collapsing map, which maps a proof in \mathbf{HA}^{2*} to a proof in system F, and this map sends the normal deduction $\mathcal{D}[m]$ of $\mathsf{N}(\mathbf{m})$ in \mathbf{HA}^{2*} to the type checking deduction \mathbf{c}_m : Nat in system F.

Having done all this, the predicate $G_e(x, y)$ is represented in \mathbf{HA}^2 by a formula Φ_{G_e} , for simplicity denoted by Ψ_e , and thus in \mathbf{HA}^{2*} by a formula $\Psi_e^{\mathbb{D}}$, such that $\forall x \exists y G_e(x, y)$ holds for all $x, y \in \mathbb{N}$ iff

$$\forall u (u \in \mathsf{N} \Rightarrow \exists v ((v \in \mathsf{N}) \land \Psi_e^{\mathbb{D}}(u, v)))$$

is provable in HA^{2*} . We can now give a correct version of Definition 7.29.

7.10 Provably Total Computable Functions in HA^{2*}

Definition 7.33. The partial computable function $\varphi_e \colon \mathbb{N} \to \mathbb{N}$ is provably total in \mathbf{HA}^{2*} if

$$\forall u \big(u \in \mathsf{N} \Rightarrow \exists v ((v \in \mathsf{N}) \land \Psi_e^{\mathbb{D}}(u, v)) \big)$$

is provable in HA^{2*} .

In order to obtain a λ -term in system F computing the provably total function φ_e we need to map the \mathbf{HA}^{2*} -proof of $\forall u (u \in \mathbb{N} \Rightarrow \exists v ((v \in \mathbb{N}) \land \Psi_e^{\mathbb{D}}(u, v)))$ to a term in system F. For this, it is necessary to define a map, called collapsing map by Troelstra and Schwichtenberg [73], which sends a formula φ to a type $\llbracket \varphi \rrbracket$ in system F, and a λ -term \mathcal{M} representing a proof \mathcal{D} of the formula φ in \mathbf{HA}^{2*} to a term $\llbracket \mathcal{M} \rrbracket$ in system F which type checks with type $\llbracket \varphi \rrbracket$, in such a way that β -reduction is preserved.

But here, we run into a snag. Since negation is encoded as $\neg P \equiv P \Rightarrow \forall X. X$, when we map $\neg P$, the construction requires a term that type-checks with the type $\forall X. X$, but there is no such term since $\forall X. X$ is not provable (since by strong normalization, \mathbf{HA}^{2*} is consistent). The trick is to proceed in two stages.

7.11 The System $\lambda 2\Omega$ and its Encoding in system F

First, a variant of system F known as $\lambda 2\Omega$ is introduced.

Definition 7.34. The λ -calculus $\lambda 2\Omega$ is obtained from system F by adding a "bogus term" Ω of type $\forall X^0, X^0$, so that $\triangleright \Omega : \forall X^0, X^0$ is an axiom of $\lambda 2\Omega$.

It is not hard to prove that strong normalization holds for $\lambda 2\Omega$ and that normal forms are unique; see Troelstra and Schwichtenberg [73].

Then it will be shown that $\lambda 2\Omega$ can be encoded in system F in such a way that β -reduction is preserved.

The following result is shown in Troelstra and Schwichtenberg [73] (Proposition 11.4.1).

Proposition 7.11. There is a map from $\lambda 2\Omega$ to system F, such that every type P is mapped to the type P° and every term M is mapped to the term M° , in such a way that if M reduces to N in $\lambda 2\Omega$, then M° reduces to N° in system F. Furthermore, there are terms W: Nat \rightarrow Nat (weaken) and C: Nat \rightarrow Nat (contract), such that $Wc_n \xrightarrow{*}_{\lambda 2\Omega} c_n^{\circ}$ and $Cc_n^{\circ} \xrightarrow{*}_{\lambda 2\Omega} c_n$. As a consequence, for every closed term M: Nat \rightarrow Nat in $\lambda 2\Omega$, if $Mc_m \xrightarrow{*}_{\lambda 2\Omega} c_n$, then if M^F is the term in system F given by $M^F = \lambda z$: Nat. $C(M^{\circ}(Wz))$, we have $M^Fc_m \xrightarrow{*}_{\lambda 2} c_n$.

The above embedding consists of two steps. First types are encoded, and then terms are encoded. Every type P in $\lambda 2\Omega$ is encoded as a type P° in system F recursively as follows:

$$\begin{aligned} X^{\circ} &= X\\ (Q \to R)^{\circ} &= Q^{\circ} \to R^{\circ}\\ (\forall X^{0}. Q)^{\circ} &= \forall X^{0} (X^{0} \to Q^{\circ}). \end{aligned}$$

As a consequence, we can prove that

$$(P[X := Q])^{\circ} = P^{\circ}[X := Q^{\circ}].$$

To deal with the type $\forall X^0. X^0$ when we encode terms, we need to define some special terms τ_P . Then if the type variables in the type P are contained in the set $\{X_1, \ldots, X_m\}$, we assign bijectively a new first-order variable z_i of type X_i not occurring in P to every type variable X_i $(X_i: \star)$. We define the term τ_P containing the free first-order variables $w_1: X_1, \ldots, w_m: X_m$ and the type variables X_1, \ldots, X_m as follows:

$$\tau_{X_i} = z_i \qquad (z_i: X_i)$$

$$\tau_{Q \to R} = \lambda y: Q^{\circ}. \tau_R \qquad (y \notin FV(\tau_R))$$

$$\tau_{\forall X, Q} = \Lambda X. \lambda z: X. \tau_Q. \qquad (where z is associated with X)$$

We check immediately that for any closed type P, τ_P type checks with type P° .

Example 7.8. For $P = \forall X. X$ we have

$$\tau_{\forall X, X} = \Lambda X. \, \lambda z \colon X. \, z \quad \text{and} \quad \tau_{\forall X, X} \colon \forall X (X \to X).$$

We finally extend our embedding to judgements $\Gamma \triangleright M \colon P$. If $\Gamma = \{u_1 \colon A_1, \ldots, u_m \colon A_m\},\$

then $\Gamma^{\circ} = \{u_1 \colon A_1^{\circ}, \ldots, u_m \colon A_m^{\circ}\}$, and we also have

$$\begin{split} \Gamma \triangleright \ u_i \colon A_i &\mapsto \Gamma^{\circ} \triangleright \ u_i \colon A_i^{\circ} \\ \Gamma \triangleright \ \lambda x \colon P. \ M \colon (P \to Q) \mapsto \Gamma^{\circ} \triangleright \ \lambda x \colon P^{\circ}. \ M^{\circ} \colon (P \to Q)^{\circ} \\ \Gamma \triangleright \ MN \colon Q \mapsto \Gamma^{\circ} \triangleright \ M^{\circ}N^{\circ} \colon Q^{\circ} \\ \Gamma \triangleright \ \Lambda X. \ M \colon (\forall X \colon P) \mapsto \Gamma^{\circ} \triangleright \ \Lambda X. \ \lambda z \colon X. \ M^{\circ} \colon (\forall X \colon P)^{\circ} \\ \Gamma \triangleright \ MQ \colon P[X \coloneqq Q] \mapsto \Gamma^{\circ} \triangleright \ (M^{\circ}Q^{\circ})\tau_Q \colon (P[X \coloneqq Q])^{\circ} \\ \triangleright \ \Omega \colon \forall X. \ X \mapsto \triangleright \Lambda X \colon \lambda z \colon X. \ z \colon \forall X(X \to X). \end{split}$$

It can be verified that the operation $\,^{\circ}$ commutes with substitution, in the sense that

$$(M[y := s])^{\circ} = M^{\circ}[y := s^{\circ}]$$

$$\tau_{A[X:=B]} = \tau_{A}[X := B^{\circ}][z := \tau_{B}]$$

$$(M[X := B])^{\circ} = M^{\circ}[X := B^{\circ}][z := \tau_{B}]$$

and that if $M_1 \xrightarrow{*}_{\lambda 2\Omega} M_2$, then $M_1^{\circ} \xrightarrow{*}_{\lambda 2} M_2^{\circ}$. Some of these steps are given in Troelstra and Schwichtenberg [73] (Section 11.4). It can also be shown that

$$\mathsf{Nat}^{\circ} = \forall X \Big(X \to \big(X \to ((X \to X) \to X) \big) \Big)$$
$$\mathbf{c}_n^{\circ} = \Lambda X. \, \lambda x \colon X. \, \lambda y \colon X. \, \lambda z \colon (X \to X). \, z^n y.$$

Finally, if we define W and C by

$$\begin{split} \mathsf{W} &= \lambda u \colon \mathsf{Nat.} \, \Lambda X. \, \lambda x \colon X. \, \lambda y \colon X. \, \lambda z \colon (X \to X). \, (uXyz) \\ \mathsf{C} &= \lambda u \colon \mathsf{Nat}^{\circ}. \, \Lambda X. \, \lambda y \colon X. \, \lambda z \colon (X \to X). \, uXyyz, \end{split}$$

then $W\mathbf{c}_n \xrightarrow{*}_{\lambda 2\Omega} \mathbf{c}_n^\circ$ and $C\mathbf{c}_n^\circ \xrightarrow{*}_{\lambda 2\Omega} \mathbf{c}_n$.

Second, a collapsing map from \mathbf{HA}^{2*} to $\lambda 2\Omega$ is defined; see Troelstra and Schwichtenberg [73] (Section 11.5, especially Definition 11.5.7 and the proposition following it).

7.12 The Collapsing Map From HA^{2*} to $\lambda 2\Omega$

First we provide more details about the collapsing map (see Troelstra and Schwichtenberg [73] (Definition 11.5.7). By Proposition 7.3, we may assume that we restrict ourselves to the connectives \Rightarrow , \land , \forall^1 , \exists^1 , \forall^2 .

Definition 7.35. Let $M_0 = \Lambda X: \star . \lambda x: X. x$ be the term of system F whose type is $T \equiv \forall X: \star . (X \to X)$ (which is a provable formula in intuitionistic second-order logic). We need to map formulae in \mathbf{HA}^{2*} to types in $\lambda 2\Omega$ and proofs in \mathbf{HA}^{2*} to type checking derivations in $\lambda 2\Omega$. Let us assign bijectively a propositional variable (a type) X^F to every

predicate variable X^n . Then the collapsing map $P \mapsto [\![P]\!]$ is defined inductively on formulae in \mathbf{HA}^{2*} as follows:

$$[s = t] = T$$
$$[X^{n}(t_{1}, \dots t_{n})] = X^{F}$$
$$[P \Rightarrow Q] = [P] \rightarrow [Q]$$
$$[P \land Q] = [P] \land [Q]$$
$$[\forall uP] = [P]$$
$$[\exists uP] = [P]$$
$$[\exists uP] = [P]$$
$$[\forall X^{n}. P] = \forall X^{F}. [P].$$

In the expression $[\![P]\!] \wedge [\![Q]\!]$, the connective \wedge is defined in terms of Proposition 7.3. It can be shown that

$$[\![P[u:=t]]\!] = [\![P]\!], \quad [\![\mathsf{N}(t)]\!] = \mathsf{Nat},$$

for any first-order term t.

Next, the collapsing map is extended to proofs in \mathbf{HA}^{2*} . This is done by induction on the depth of proofs, so we just have describe the effect of the collapsing map on proof rules. If $\Gamma = \{x_1 \colon P_1, \ldots, x_n \colon P_n\}$, then we set $\llbracket \Gamma \rrbracket = \{x_1 \colon \llbracket P_1 \rrbracket, \ldots, x_n \colon \llbracket P_n \rrbracket\}$.

We use the notation rule \mapsto [[rule]] to describe this mapping. Here we are using the proof terms of Definition 7.26.

In the last three rules, on the righthand side of \mapsto , the operators $\langle -, - \rangle$, π_1 and π_2 are the terms of system F defined in Definition 7.13 and Definition 7.14. It is easy to see that $\llbracket P[v := u] \rrbracket = \llbracket (\forall v : \iota) . P \rrbracket = \llbracket P \rrbracket$, so the third and fourth collapsed rules are the identity; first-order information is erased. The rules for the first-order existential quantifiers are collapsed as follows.

$$\begin{array}{cccc} \frac{\Gamma \triangleright \ M \colon P[v := t]}{\Gamma \triangleright \ \operatorname{inx}(t, M) \colon \exists v \colon \iota. \ P} & \mapsto & \frac{\llbracket \Gamma \rrbracket \triangleright \ \llbracket M \rrbracket \colon \llbracket P[v := t] \rrbracket}{\llbracket \Gamma \rrbracket \triangleright \ \llbracket M \rrbracket \colon \llbracket P \rrbracket} \\ \\ \frac{\Gamma \triangleright \ M \colon \exists v \colon \iota. \ P & z \colon P[v := u], \Delta \triangleright \ N \colon C}{\Gamma \cup \Delta \triangleright \ \operatorname{casex}(M, \lambda u \colon \iota. \lambda x \colon P[v := u]. \ N) \colon C} \\ \\ \mapsto & \frac{\llbracket \Gamma \rrbracket \triangleright \ \llbracket M \rrbracket \colon \llbracket P \rrbracket & z \colon \llbracket P[v := u] \rrbracket, \llbracket \Delta \Vdash \ \llbracket N \rrbracket \colon \llbracket C \rrbracket}{\llbracket \Gamma \rrbracket \cup \llbracket \Delta \rrbracket \triangleright \ \llbracket N \rrbracket \colon \llbracket C \rrbracket} \end{array}$$

In the first rule, $\llbracket P[v := t] \rrbracket = \llbracket P \rrbracket$, so this collapsed rule is the identity.

The rules for second-order universal quantifiers are collapsed as follows.

$$\frac{\Gamma \triangleright M : P[X := Y]}{\Gamma \triangleright (\Lambda X : K.M) : (\forall X : K).P} \mapsto \frac{\llbracket \Gamma \rrbracket \triangleright \llbracket M \rrbracket : \llbracket P[X := Y] \rrbracket}{\Gamma \triangleright (\Lambda X^F : \star . \llbracket M \rrbracket) : (\forall X^F : \star). \llbracket P \rrbracket}$$

$$\frac{\Gamma \triangleright M : (\forall X : K_n).P}{\Gamma \triangleright (M(\lambda v_1 : \iota \cdots \lambda v_n : \iota.\varphi)) : P[X := \lambda v_1 : \iota \cdots \lambda v_n : \iota.\varphi]}$$

$$\mapsto \frac{\llbracket \Gamma \rrbracket \triangleright \llbracket M \rrbracket : (\forall X^F : \star). \llbracket P \rrbracket}{\llbracket \Gamma \rrbracket \triangleright (\llbracket M \rrbracket \colon (\forall M^F : \star) . \llbracket P \rrbracket}.$$

Note that it can be shown that

$$\llbracket P[X := \lambda v_1 \colon \iota \cdots \lambda v_n \colon \iota. \varphi] \rrbracket = \llbracket P \rrbracket [X^F := \llbracket \varphi \rrbracket].$$

Recall from Definition 7.35 that $\triangleright \Omega: \forall X^0. X^0$ in $\lambda 2\Omega$, and that $M_0 = \Lambda X: \star .\lambda x: X. x$ is the term of system F whose type is $T \equiv \forall X: \star . (X \to X)$.

The axioms are collapsed as follows:

$$\begin{split} \Gamma, x \colon P \to P \mapsto \llbracket \Gamma \rrbracket, x \colon \llbracket P \rrbracket \to \llbracket P \rrbracket \\ \forall v(v=v) \mapsto M_0 \colon T \\ \forall u \forall v \forall w ((u=v) \Rightarrow ((u \Rightarrow w) \Rightarrow (v=w))) \mapsto \lambda x \colon T. \lambda y \colon T. M_0 \colon T \to (T \to T) \\ \forall u \forall v ((Su=Sv) \Rightarrow (u=v)) \mapsto \lambda x \colon T. M_0 \colon (T \to T) \\ \forall u \forall v ((u=v) \Rightarrow (Su=Sv)) \mapsto \lambda x \colon T. M_0 \colon (T \to T) \\ \forall u \forall v ((u=v) \Rightarrow (Su=Sv)) \mapsto \lambda x \colon T. \Omega \colon (T \to \forall X^0. X^0). \end{split}$$

The following proposition is stated in Troelstra and Schwichtenberg [73] (Proposition 11.5.7A).

Proposition 7.12. The collapsing map from \mathbf{HA}^{2*} to $\lambda 2\Omega$ preserves reduction, in the sense that if a deduction \mathcal{D}_1 reduces to a deduction \mathcal{D}_2 in \mathbf{HA}^{2*} , then the type checking derivation $[\mathcal{D}_1]$ reduces to $[\mathcal{D}_2]$ in $\lambda 2\Omega$. Furthermore, normal forms are mapped to normal forms.

We can also show that the collapsing map sends the λ -term representing the normal deduction $\mathcal{D}[m]$ of $\mathsf{N}(\mathbf{m})$ in \mathbf{HA}^{2*} to the type checking deduction \mathbf{c}_m : Nat in system F, where \mathbf{c}_m is the Church numeral from Definition 7.11. Recall that $\mathbf{0} = 0$, and $\mathbf{m} = S^m(0)$, $m \geq 1$. Indeed, with $I = \forall u(X(u) \Rightarrow X(S(u)))$, we can show by induction that the term $M_{d[m+1]}$ associated with the normal deduction d[m+1]

$$\frac{y \colon I \to \forall u(X(u) \Rightarrow X(S(u)))}{y \colon I \to X(\mathbf{m}) \Rightarrow X(S(\mathbf{m}))} \frac{d[m]}{x \colon X(0), y \colon I \to X(\mathbf{m})}$$
$$\frac{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m}))}{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m}))}$$

of $x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \to X(S(\mathbf{m})) \in \mathsf{N}$ is

$$M_{d[m+1]} = (y\mathbf{m})(y(\mathbf{m}-\mathbf{1}))\cdots(y\mathbf{0})x, \quad m \ge 0.$$

In the special case m = -1, the term associated with the proof d[0] is simply x, and in the special case m = 0, the term associated with the proof d[1] is (y0)x.

Indeed, in the base case m + 1 = 0, we have the type checking proof

$$x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \triangleright x \colon X(0)$$

so $M_{d[0]} = x$. Assuming by induction that

$$M_{d[0]} = x,$$
 $M_{d[m]} = (y(\mathbf{m} - \mathbf{1})) \cdots (y_0)x, \quad m \ge 1,$

the deduction d[m+1] yields the type checking proof

$$\frac{y \colon I \triangleright y \colon \forall u(X(u) \Rightarrow X(S(u)))}{y \colon I \triangleright y\mathbf{m} \colon X(\mathbf{m}) \Rightarrow X(S(\mathbf{m}))} \xrightarrow{D[m]}{x \colon X(0), y \colon I \triangleright M_{d[m]} \colon X(\mathbf{m})}$$
$$\frac{x \colon X(0), y \colon \forall u(X(u) \Rightarrow X(S(u))) \triangleright (y\mathbf{m})M_{d[m]} \colon X(S(\mathbf{m}))}{x \colon X(S(\mathbf{m})) \models (y\mathbf{m})M_{d[m]} \colon X(S(\mathbf{m}))},$$

and so we get

$$M_{d[m+1]} = (y\mathbf{m})M_{d[m]} = (y\mathbf{m})(y(\mathbf{m}-1))\cdots(y0)x,$$

establishing the induction hypothesis.

Then, the term associated with the proof $\mathcal{D}[m]$ is

$$\begin{split} \Lambda X. \, \lambda x \colon X(0). \, \lambda y \colon \forall u(X(u) \Rightarrow X(S(u))). \, (y(\mathbf{m} - \mathbf{1})) \cdots (y0)x, \quad m \geq 1\\ \Lambda X. \, \lambda x \colon X(0). \, \lambda y \colon \forall u(X(u) \Rightarrow X(S(u))). \, x, \quad m = 0, \end{split}$$

and applying the collapsing map, since the fourth rule erases the term \mathbf{j} for each term $y\mathbf{j}$, we get

$$\Lambda X. \,\lambda x \colon X. \,\lambda y \colon (X \Rightarrow X) \colon y^m(x) = \mathbf{c}_m.$$

7.13 A Function Provably Total in HA² is Computable in System F

For the argument below, let us denote the term associated with a proof \mathcal{D} in \mathbf{HA}^{2*} (using the connectives $\Rightarrow, \land, \forall^1, \exists^1, \forall^2$) by $M_{\mathcal{D}}$.

Theorem 7.13. If a computable function is provably total in HA^2 , then it is computable in system *F*.

Proof. We basically follow Troelstra and Schwichtenberg [73] (Theorem 11.5.8), with a few amplifications. First, by Proposition 7.9, a computable function φ_e is provably total in \mathbf{HA}^2 iff there is a proof \mathcal{D} of

$$\forall u (u \in \mathsf{N} \Rightarrow \exists v ((v \in \mathsf{N}) \land \Psi_e^{\mathbb{D}}(u, v)))$$

in \mathbf{HA}^{2*} (see the discussion at the end of Section 7.6 and Definition 7.33). By Proposition 7.12, the collapsing map of yields a term

$$M_1 = \llbracket M_{\mathcal{D}} \rrbracket \quad \text{in} \quad \lambda 2\Omega \tag{\dagger_9}$$

with type

$$\llbracket \forall u \big(u \in \mathsf{N} \Rightarrow \exists v ((v \in \mathsf{N}) \land \Psi_e^{\mathbb{D}}(u, v)) \big) \rrbracket,$$

and close examination of the collapsing map shows that the above type is equal to

$$\mathsf{Nat} \to (\mathsf{Nat} \land \llbracket \Psi_e^{\mathbb{D}} \rrbracket)$$

It follows that if $x \in \mathsf{Nat}$, then

$$M = \lambda x \colon \mathsf{Nat.}\,\pi_1(M_1 x) \tag{\dagger}_M$$

has type $Nat \to Nat$, where π_1 is defined in Definition 7.14, and we claim that M computes φ_e in system F.

We can now specialize the proof \mathcal{D} to $u = \mathbf{m} = S^m(0)$ and we obtain a proof \mathcal{D}_m of the form

$$\frac{\mathcal{D}}{\begin{array}{l} \begin{array}{l} \rightarrow \forall u \left(u \in \mathsf{N} \Rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(u, v)) \right) \\ \hline \rightarrow \left(\mathbf{m} \in \mathsf{N} \Rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(\mathbf{m}, v)) \\ \hline \rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(\mathbf{m}, v)) \\ \end{array}} \qquad \begin{array}{l} \begin{array}{l} \mathcal{D}[m] \\ \rightarrow \mathbf{m} \in \mathsf{N} \\ \hline \end{array}}$$

The corresponding type checking derivation using terms is

$$\frac{\triangleright M_{\mathcal{D}} \colon \forall u \left(u \in \mathsf{N} \Rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(u, v)) \right)}{\triangleright M_{\mathcal{D}}\mathbf{m} \colon \left(\mathbf{m} \in \mathsf{N} \Rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(\mathbf{m}, v)) \right)} \quad \triangleright M_{\mathcal{D}[m]} \colon \mathbf{m} \in \mathsf{N}}$$

$$\frac{\rightarrow M_{\mathcal{D}}\mathbf{m} \colon \left(\mathbf{m} \in \mathsf{N} \Rightarrow \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(\mathbf{m}, v)) \right)}{\triangleright (M_{\mathcal{D}}\mathbf{m}) M_{\mathcal{D}[m]} \colon \exists v (v \in \mathsf{N} \land \Psi_{e}^{\mathbb{D}}(\mathbf{m}, v))}, \quad \forall M_{\mathcal{D}}\mathbf{m} \in \mathsf{N}}$$

and so, the term associated with the proof \mathcal{D}_m is

$$M_{\mathcal{D}_m} = (M_{\mathcal{D}}\mathbf{m})M_{\mathcal{D}[m]} \tag{\dagger}_{10}$$

and the collapsing maps sends it to

$$\llbracket M_{\mathcal{D}_m} \rrbracket = \llbracket (M_{\mathcal{D}} \mathbf{m}) M_{\mathcal{D}[m]} \rrbracket = \llbracket M_{\mathcal{D}} \rrbracket \llbracket M_{\mathcal{D}[m]} \rrbracket = M_1 \mathbf{c}_m,$$

so we have

$$\llbracket M_{\mathcal{D}_m} \rrbracket = M_1 \mathbf{c}_m. \tag{\dagger}_{11}$$

The proof \mathcal{D}_m normalizes to a proof \mathcal{D}'_n whose last step must be an introduction,

$$\begin{aligned} \mathcal{D}''_n \\ & \to \mathbf{n} \in \mathsf{N} \land \Psi^{\mathbb{D}}_e(\mathbf{m}, \mathbf{n}) \\ \hline & \to \exists v (v \in \mathsf{N} \land \Psi^{\mathbb{D}}_e(\mathbf{m}, v)), \end{aligned}$$

for some $n \in \mathbb{N}$. The fact that a normal proof must end with an introduction is a standard fact of proof theory; see Troelstra and Schwichtenberg [73], Proposition 11.1.5. The type checking derivation associated with the proof \mathcal{D}'_n is

so the term associated with the proof \mathcal{D}'_n is

$$M_{\mathcal{D}'_n} = \mathsf{inx}(\mathbf{n}, M_{\mathcal{D}''_n}),$$

which is sent by the collapsing map to

$$\llbracket M_{\mathcal{D}'_n} \rrbracket = \llbracket M_{\mathcal{D}''_n} \rrbracket, \tag{\dagger}_{12}$$

since the collapsed (\exists -intro) rule is the identity. Since $M_{\mathcal{D}_m} \xrightarrow{*}_{\lambda Ni^2} M_{\mathcal{D}'_n}$, by Proposition 7.12, $\llbracket M_{\mathcal{D}_m} \rrbracket \xrightarrow{*}_{\lambda 2\Omega} \llbracket M_{\mathcal{D}'_n} \rrbracket$, namely by (\dagger_{11}) and (\dagger_{12}),

$$M_1 \mathbf{c}_m \xrightarrow{*}_{\lambda 2 \Omega} \llbracket M_{\mathcal{D}_n''} \rrbracket. \tag{\dagger}_{13}$$

Applying \wedge -elimination (on the left) to the conclusion of the proof \mathcal{D}_n'' , we obtain the proof \mathcal{D}_n'''

$$egin{aligned} \mathcal{D}_n'' \ & o \mathbf{n} \in \mathsf{N} \wedge \Psi_e^{\mathbb{D}}(\mathbf{m},\mathbf{n}) \ & o \mathbf{n} \in \mathsf{N} \end{aligned}$$

whose corresponding type checking derivation is

$$\frac{\triangleright M_{\mathcal{D}''_{n}} \colon \mathbf{n} \in \mathsf{N} \land \Psi^{\mathbb{D}}_{e}(\mathbf{m}, \mathbf{n})}{\triangleright \pi_{1}(M_{\mathcal{D}''_{n}}) \colon \mathbf{n} \in \mathsf{N}},$$

which is represented by the term

$$M_{\mathcal{D}_n^{\prime\prime\prime}} = \pi_1(M_{\mathcal{D}_n^{\prime\prime}}),\tag{\dagger}_{14}$$

and this term is sent by the collapsing map to

$$\llbracket M_{\mathcal{D}_{n}^{\prime\prime\prime}} \rrbracket = \llbracket \pi_{1}(M_{\mathcal{D}_{n}^{\prime\prime}}) \rrbracket = \pi_{1}(\llbracket M_{\mathcal{D}_{n}^{\prime\prime}} \rrbracket).$$
 (†15)

Since by (\dagger_{13}) ,

 $M_1 \mathbf{c}_m \xrightarrow{*} \mathbf{\lambda}_{2\Omega} \llbracket M_{\mathcal{D}''_n} \rrbracket,$

by (\dagger_{15}) , we obtain

$$\pi_1(M_1\mathbf{c}_m) \xrightarrow{*}_{\lambda \mathbf{2}\Omega} \pi_1(\llbracket M_{\mathcal{D}_n''} \rrbracket) = \llbracket M_{\mathcal{D}_n'''} \rrbracket.$$
 (†16)

Since the normal proof of $\mathbf{n} \in \mathsf{N}$ is unique, the proof $\mathcal{D}_n^{\prime\prime\prime}$ normalizes to the normal proof $\mathcal{D}[n]$, so

$$M_{\mathcal{D}_{n}^{\prime\prime\prime}} \xrightarrow{*}_{\lambda \mathbf{N}\mathbf{i}^{2}} M_{\mathcal{D}[n]},$$
 (†₁₇)

which implies

$$\llbracket M_{\mathcal{D}_{n}^{\prime\prime\prime}} \rrbracket \xrightarrow{*}_{\lambda 2\Omega} \llbracket M_{\mathcal{D}[n]} \rrbracket = \mathbf{c}_{n}, \qquad (\dagger_{18})$$

so by (\dagger_{16}) , and (\dagger_{18}) , we get

$$\pi_1(M_1\mathbf{c}_m) \xrightarrow{*}_{\lambda \mathbf{2}\Omega} \pi_1(\llbracket M_{\mathcal{D}''_n} \rrbracket) = \llbracket M_{\mathcal{D}'''_n} \rrbracket \xrightarrow{*}_{\lambda \mathbf{2}\Omega} \mathbf{c}_n.$$
 (†19)

Since by definition $M = \lambda x$: Nat. $\pi_1(M_1 x)$, by (\dagger_{19}) , we finally have

$$M\mathbf{c}_m = (\lambda x \colon \mathsf{Nat.} \, \pi_1(M_1 x))\mathbf{c}_m \xrightarrow{*}_{\lambda 2\Omega} \pi_1(M_1 \mathbf{c}_m) \xrightarrow{*}_{\lambda 2\Omega} \mathbf{c}_n, \qquad (\dagger_{20})$$

in $\lambda 2\Omega$. Since $M: \mathsf{Nat} \to \mathsf{Nat}$, by Proposition 7.11, there is a term M^F in system F such that

$$M^F \mathbf{c}_m \xrightarrow{*}_{\lambda \mathbf{2}} \mathbf{c}_n.$$
 (†21)

Finally, if we apply \wedge -elimination (on the right) to the conclusion of the proof \mathcal{D}''_n , we obtain the proof

$$egin{aligned} \mathcal{D}''_n \ & o \mathbf{n} \in \mathsf{N} \wedge \Psi^{\mathbb{D}}_e(\mathbf{m},\mathbf{n}) \ & \overline{ o \Psi^{\mathbb{D}}_e(\mathbf{m},\mathbf{n})} \ \end{aligned}$$

which shows that $\Psi_e^{\mathbb{D}}(\mathbf{m}, \mathbf{n})$ is provable, so it is true in the standard model \mathbb{N} , and thus $n = \varphi_e(m)$, namely M computes φ_e .

In summary, the following fundamental theorem is obtained.

Theorem 7.14. (Girard 1972) If a computable function is provably total in HA^2 , then it is computable in system F.

Theorem 7.14 was first proven by Girard [28] using a very different technique, the functional interpretation of Gödel; see Part V, Section 4, especially Page V.4.3.

The proof that the functions definable in system F are provably total in \mathbf{HA}^2 is complicated. It involves a careful analysis of the proof of strong normalization in F to show that for formulae in F with bounded complexity (a bounded number of logical connectives), such a proof can be carried out in an extension $\mathbf{HA}^2_{\mathbf{PRA}}$ of \mathbf{HA}^2 in which every primitive recursive function is represented by a function symbol. The system $\mathbf{HA}^2_{\mathbf{PRA}}$ is *conservative* over \mathbf{HA}^2 , which means that no new formulae of \mathbf{HA}^2 are provable in $\mathbf{HA}^2_{\mathbf{PRA}}$.

Girard did this in his thesis [28] (Part III), by proving that the β -reduction relation

$$\forall m \exists ! n \operatorname{Red}(\#(M\mathbf{c}_m), \#(\mathbf{c}_n))$$
(Red)

expressing that the term M of system F computes the function f (with n = f(m)) is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$. This result is stated as Theorem 7, in Part III, Section 6, on a single page. This is deceptive because the proof is actually spread over Sections IV-V and involves a reflection schema first introduced by Kreisel around 1959.

Beware that the proof of strong normalization for system F *cannot* be formalized in \mathbf{HA}^2 , as explained in Girard [28] (Part III, Section 5). However, as stressed by Girard, the proof of strong normalization for any *finite* subset of formulae of system F *can* be formalized in \mathbf{HA}^2 .

We obtain the following converse of Theorem 7.14.

Theorem 7.15. (Girard 1972) If a computable function is computable in system F, then it is provably total in $\mathbf{HA}^2_{\mathbf{PRA}}$, and thus in \mathbf{HA}^2 .

Remark: Similar formalizations of normalization proofs are given in Troelstra [72] (Chapter 4, Sections 4 and 5). These proofs include many details.

If we add the proof-by-contradiction rule to $\mathbf{HA}^2_{\mathbf{PRA}}$, we obtain the system of classical second-order arithmetic \mathbf{PA}^2 . As we said in Section 7.5, if a formula (a Π^0_2 -formula) of the form $\forall x \exists y A(x, y)$, where A is a quantifier-free primitive recursive formula, is provable in \mathbf{PA}^2 , then it is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$. This implies that the sets of computable functions provably total in \mathbf{PA}^2 and $\mathbf{HA}^2_{\mathbf{PRA}}$ are identical. Some details of the proof of this result are provided in the next section.

7.14 The Provably Total Functions in HA_{PRA}^2 and PA^2

We begin by defining $\mathbf{HA}_{\mathbf{PRA}}^2$.

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Definition 7.36. The proof system $\mathbf{HA}_{\mathbf{PRA}}^2$ of *intutionistic second-order logic with primitive* recursive arithmetic is obtained by adding for every primitive recursive function $f: \mathbb{N}^n \to \mathbb{N}$ a new function symbol \mathbf{f} , so that if Φ_f is the formula of \mathbf{HA}^2 defining f as in Theorem 7.5, then we have the axiom

$$\forall x_1 \cdots \forall x_n \Phi_f(x_1, \dots, x_n, \mathbf{f}(x_1, \dots, x_n)).$$

It is shown in Troelstra and Schwichtenberg [73] (Theorem 4.3.13) that $\mathbf{HA}_{\mathbf{PRA}}^2$ is conservative over \mathbf{HA}^2 , which means that if a formula of \mathbf{HA}^2 (not involving any new symbol representing a primitive recursive function) is provable in $\mathbf{HA}_{\mathbf{PRA}}^2$, then it is provable in \mathbf{HA}^2 (so no new formulae of \mathbf{HA}^2 are provable in $\mathbf{HA}_{\mathbf{PRA}}^2$).

The system $\mathbf{HA}_{\mathbf{PRA}}^2$ is more convenient than \mathbf{HA}^2 in terms of dealing with the primitive recursive functions, since they all have a name and defining equations.

Definition 7.37. The proof system \mathbf{PA}^2 of *(classical) second-order logic with primitive recursive arithmetic* is obtained from $\mathbf{HA}^2_{\mathbf{PBA}}$ by adding the proof-by-contradiction rule.

Of course, there are formulae provable in \mathbf{PA}^2 that are not provable in $\mathbf{HA}^2_{\mathbf{PRA}}$, but the following remarkable theorem holds.

Theorem 7.16. For any Π_2^0 -formula of the form $\varphi := \forall x \exists y A(x, y)$, where A is a quantifierfree primitive recursive formula, if φ is provable in \mathbf{PA}^2 , then it is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$.

Since the formula

$$\forall x \exists y \Psi_e(x, y)$$

expressing that the computable function φ_e is total, where Ψ_e is a formula defining the primitive recusive predicate G_e (see Definition 7.17), we obtain the following desired corollary.

Theorem 7.17. The sets of computable functions provably total in \mathbf{PA}^2 , $\mathbf{HA}^2_{\mathbf{PRA}}$, and \mathbf{HA}^2 , are identical. They are equal to the set of total computable functions definable in system F.

The proof of Theorem 7.16 uses three facts.

(1) The Gödel negative translation defined in Section 2.19 can be extended to a translation $A \mapsto A^g$ from \mathbf{PA}^2 to $\mathbf{HA}^2_{\mathbf{PRA}}$ so that the following theorem holds.

Theorem 7.18.

- (1) For every formula A of \mathbf{PA}^2 , the equivalence $A \equiv A^g$ is provable in \mathbf{PA}^2 .
- (2) For any formula A in \mathbf{PA}^2 , A is provable in \mathbf{PA}^2 iff A^g is provable in $\mathbf{HA}^2_{\mathbf{PBA}}$.

For a proof of Theorem 7.18, see Troelstra and Schwichtenberg [73] (Chapter 2, Section 2.3) and Troelstra and Van Dalen [74] (Chapter 2, Section 3).

The g-translation is defined as follows.

$$A^{g} = \neg \neg A, \quad \text{if } A \text{ is atomic}$$

$$P(t_{1}, \dots, t_{n})^{g} = \neg \neg P(t_{1} \dots, t_{n})$$

$$\bot^{g} = \bot$$

$$(\neg A)^{g} = \neg A^{g}$$

$$(A \land B)^{g} = (A^{g} \land B^{g})$$

$$(A \Rightarrow B)^{g} = \neg (A^{g} \land \neg B^{g})$$

$$(A \lor B)^{g} = \neg (\neg A^{g} \land \neg B^{g})$$

$$(\forall xA)^{g} = \forall xA^{g}$$

$$(\exists xA)^{g} = \neg \forall x \neg A^{g}$$

$$(\forall X^{m} \cdot A)^{g} = \forall X^{m} \cdot A^{g}$$

$$(\exists X^{m} \cdot A)^{g} = \neg \forall X^{m} \cdot \neg A^{g}.$$

(2) The g-translation of the formula $\varphi := \forall x \exists y A(x, y)$, is

$$\varphi^g := \forall x \neg \forall y \neg \neg \neg A(x, y) \equiv \forall x \neg \forall y \neg A(x, y),$$

and

$$\forall y \neg B \equiv \neg \neg \exists y B \tag{(*)}$$

is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$, for any *B*. Here we used the fact that in $\mathbf{HA}^2_{\mathbf{PRA}}$, $\neg B \equiv \neg \neg \neg B$ for any *B*.

(3) The system $\mathbf{HA}^2_{\mathbf{PRA}}$ is closed under "Markov's rule" for primitive recursive predicates, which means that if B is a primitive recursive predicate, then

if $\neg \neg \exists x B(x)$ is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$, then $\exists x B(x)$ is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$.

This result due to Friedman (1978) and Dragalin (1980) is proven in Troelstra and Van Dalen [74] (Chapter 3, Section 5).

Then by (2),

$$\varphi^g \equiv \forall x \neg \neg \exists y A(x, y),$$

and by Theorem 7.18(2), if $\forall x \exists y A(x, y)$ is provable in \mathbf{PA}^2 , then $\varphi^g \equiv \forall x \neg \neg \exists y A(x, y)$ is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$, and by (3), $\forall x \exists y A(x, y)$ is also provable in $\mathbf{HA}^2_{\mathbf{PRA}}$.

The key to the proof of Theorem 7.18 is to show that the proof-by-contraduction rule can be avoided. We make use of the fact that in classical logic, \lor , \exists , \exists^2 can be expressed in terms of \land , \Rightarrow , \bot , \forall , \forall^2 , so we can restrict ourselves to translating formulae expressed in terms of \land , \Rightarrow , \bot , \forall , \forall^2 . Then if we define a negative formula as a formula that does not conain \lor , \exists , \exists^2 and such that every atomic formula other than \bot appears negated, the following proposition can be shown; see Troelstra and Schwichtenberg [73] (Chapter 2, Lemma 2.3.2). **Proposition 7.19.** For any negative formulae A, the equivalence $A \equiv \neg \neg A$ is provable in $\mathbf{HA}^2_{\mathbf{PRA}}$.

The proof of Theorem 7.18(1) is a tedious exercise. To prove (2), we use induction on the depth of deductions. Since we may restrict ourselves to the connectives $\land, \Rightarrow, \bot, \forall, \forall^2$, we find that the only nontrivial case involves the proof-by-contradiction rule.

We translate the proof using the proof-by-contradiction rule

$$\frac{\mathcal{D}}{\frac{\Gamma, x: \neg A \to \bot}{\Gamma \to A}}$$

by applying the induction hypothesis to \mathcal{D} and we obtain the proof

$$\frac{\mathcal{D}^{g}}{\stackrel{\longrightarrow}{\rightarrow} \neg \neg A^{g} \Rightarrow A^{g}} \frac{\Gamma^{g}, x \colon \neg A^{g} \rightarrow \bot}{\Gamma^{g} \rightarrow \neg \neg A^{g}} \quad (\neg \text{-intro}) = \Gamma^{g} \rightarrow A^{g} \quad (\neg \text{-intro})$$

where the proof \mathcal{D}_A in $\mathbf{HA}^2_{\mathbf{PRA}}$ of $\neg \neg A^g \Rightarrow A^g$ is given by Proposition 7.19, since A^g is a negative formula.

To prove the equivalence

$$\neg \forall y \neg B \equiv \neg \neg \exists y B, \tag{*}_{\dagger}$$

by the fourth fact in Proposition 7.20, it suffices to prove that

$$\forall y \neg B \equiv \neg \exists y B \tag{(*_{\dagger'})}$$

is provable in $\mathbf{HA}_{\mathbf{PRA}}^2.$ The following proposition takes care of this.

Proposition 7.20. The following facts are provable in HA_{PBA}^2 .

$$\begin{array}{c} A \Rightarrow \neg \neg A \\ \neg \neg \neg A \Rightarrow \neg A \\ \neg A \equiv \neg \neg \neg A \end{array}$$

if $A \Rightarrow B$ then $\neg B \Rightarrow \neg A \\ \forall y \neg B \Rightarrow \neg \exists y B \\ \neg \exists y B \Rightarrow \forall y \neg B \\ \neg \forall y \neg B \equiv \neg \neg \exists y B. \end{array}$

Proof. We prove the fifth and the sixth implications, leaving the other formulae as exercises. First we have the proof

$$\frac{u : \forall y \neg B \to \forall y \neg B}{u : \forall y \neg B \to \neg B[x := y]} \quad v : B[x := y] \to B[x := y]}$$
$$\frac{w : \exists y B \to \exists y B}{u : \forall y \neg B, v : B[x := y] \to \bot}$$
$$\frac{u : \forall y \neg B, w : \exists y B \to \bot}{\underbrace{u : \forall y \neg B, w : \exists y B \to \bot}}$$
$$\frac{u : \forall y \neg B \to \neg \exists y B}{\to \forall y \neg B \Rightarrow \neg \exists y B}$$

Next we have the proof

$$\frac{u: \neg \exists y B \rightarrow \neg \exists y B}{\underbrace{u: \neg \exists y B \rightarrow \neg \exists y B}} \frac{v: B[x := y] \rightarrow B[x := y]}{v: B[x := y] \rightarrow \exists y B}$$
$$\frac{u: \neg \exists y B, v: B[x := y] \rightarrow \bot}{\underbrace{u: \neg \exists y B \rightarrow \neg B[x := y]}_{\underbrace{u: \neg \exists y B \rightarrow \forall y \neg B}_{\xrightarrow{\rightarrow} \neg \exists y B \Rightarrow \forall y \neg B}}$$

The other formulae are left as exercises.

Remark: Peano arithmetic, **PA**, is basically the restriction of **PA**² to first-order quantifiers, with a first-order version of the induction axiom. Similarly, Heyting arithmetic, **HA**¹, is basically the restriction of $\mathbf{HA}_{\mathbf{PRA}}^2$ to first-order quantifiers, with a first-order version of the induction axiom. For a detailed presentation, see Troelstra and Van Dalen [74] (Chapter 3, Sections 1-3). Girard proves in [28] that the computable functions provably total in \mathbf{HA}^1 are exactly the functions computable in Gödel system T, denoted F_1 by Girard (Part V, Section 2, Theorem 2). Weiermann [76] gives an ordinal-theoretic characterization of the computable functions that are provably total in **PA**. Roughly speaking, this is the class of functions defined by primitive recursive operators (as in Gödel system T) that can be defined by recursion along an ordinal $\alpha < \epsilon_0$.

Chapter 8

Universal RAM Programs and Undecidability of the Halting Problem

The goal of this chapter is to prove three of the main results of computability theory:

- (1) The undecidability of the halting problem for RAM programs (and Turing machines).
- (2) The existence of universal RAM programs.
- (3) The existence of the Kleene T-predicate.

All three require the ability to code a RAM program as a natural number. Gödel pioneered the technique of encoding objects such as proofs as natural numbers in his famous paper on the (first) incompleteness theorem (1931). One of the technical issues is to code (pack) a tuple of natural numbers as a single natural number, so that the numbers being packed can be retrieved. Gödel designed a fancy function whose definition does not involve recursion (Gödel's β function; see Kleene [42] or Shoenfield [67]). For our purposes, a simpler function J due to Cantor packing two natural numbers m and n as a single natural number J(m, n) suffices.

Another technical issue is the fact it is possible to reduce most of computability theory to numerical functions $f: \mathbb{N}^m \to \mathbb{N}$, and even to functions $f: \mathbb{N} \to \mathbb{N}$. Indeed, there are primitive recursive coding and decoding functions $D_k: \Sigma^* \to \mathbb{N}$ and $C_k: \mathbb{N} \to \Sigma^*$ such that $C_k \circ D_k = \mathrm{id}_{\Sigma^*}$, where $\Sigma = \{a_1, \ldots, a_k\}$. It is simpler to code programs (or Turing machines) taking natural numbers as input.

Unfortunately, these coding techniques are very tedious so we advise the reader not to get bogged down with technical details upon first reading.

8.1 Pairing Functions

Pairing functions are used to encode pairs of integers into single integers, or more generally, finite sequences of integers into single integers. We begin by exhibiting a bijective pairing

function $J: \mathbb{N}^2 \to \mathbb{N}$. The function J has the graph partially showed below:



The function J corresponds to a certain way of enumerating pairs of integers (x, y). Note that the value of x + y is constant along each descending diagonal, and consequently, we have

$$J(x,y) = 1 + 2 + \dots + (x + y) + x,$$

= $((x + y)(x + y + 1) + 2x)/2,$
= $((x + y)^2 + 3x + y)/2,$

that is,

$$J(x,y) = ((x+y)^2 + 3x + y)/2.$$

For example, J(0,3) = 6, J(1,2) = 7, J(2,2) = 12, J(3,1) = 13, J(4,0) = 14.

If we can prove can J is a bijection, then we can define $K \colon \mathbb{N} \to \mathbb{N}$ and $L \colon \mathbb{N} \to \mathbb{N}$ as the projection functions onto the axes, that is, the unique functions such that

$$K(J(a,b)) = a$$
 and $L(J(a,b)) = b$,

for all $a, b \in \mathbb{N}$. For example, K(11) = 1, and L(11) = 3; K(12) = 2, and L(12) = 2; K(13) = 3 and L(13) = 1.

Definition 8.1. The pairing function $J: \mathbb{N}^2 \to \mathbb{N}$ is defined by

$$J(x,y) = ((x+y)^2 + 3x + y)/2$$
 for all $x, y \in \mathbb{N}$.

The functions $K \colon \mathbb{N} \to \mathbb{N}$ and $L \colon \mathbb{N} \to \mathbb{N}$ are the projection functions onto the axes, that is, the unique functions such that

$$K(J(a,b)) = a$$
 and $L(J(a,b)) = b$,

for all $a, b \in \mathbb{N}$.

The functions J, K, L are called *Cantor's pairing functions*. They were used by Cantor to prove that the set \mathbb{Q} of rational numbers is countable.

Clearly, J is primitive recursive, since it is given by a polynomial. In Definition 8.1, we implicitly assumed that J is bijective in order to define K and L.

Neither injectivity nor surjectivity of J are easy to prove.

Theorem 8.1. The pairing function $J: \mathbb{N}^2 \to \mathbb{N}$ defined by

$$J(x,y) = ((x+y)^2 + 3x + y)/2$$
 for all $x, y \in \mathbb{N}$

is a bijection. There are unique functions $K \colon \mathbb{N} \to \mathbb{N}$ and $L \colon \mathbb{N} \to \mathbb{N}$ such that

$$K(J(a, b)) = a$$
$$L(J(a, b)) = b$$
$$J(K(z), L(z)) = z.$$

for all $a, b, z \in \mathbb{N}$.

Sketch of proof. We follow Martin Davis [10]. The first step is to prove that for any $z \in \mathbb{N}$, if J(m, n) = z, then

$$8z + 1 = (2m + 2n + 1)^2 + 8m.$$
 (a)

From the above equation we can deduce that

$$2m + 2n + 1 \le \sqrt{8z + 1} < 2m + 2n + 3.$$
 (b)

If $x \mapsto \lfloor x \rfloor$ is the function from \mathbb{R} to \mathbb{N} (the *floor function*), where $\lfloor x \rfloor$ is the largest integer $\leq x$ (for example, $\lfloor 2.3 \rfloor = 2$, $\lfloor \sqrt{2} \rfloor = 1$), we can prove that

$$\lfloor \sqrt{8z+1} \rfloor + 1 = 2m + 2n + 2$$
 or $\lfloor \sqrt{8z+1} \rfloor + 1 = 2m + 2n + 3$,

so that

$$\lfloor (\lfloor \sqrt{8z+1} \rfloor + 1)/2 \rfloor = m + n + 1.$$
 (c)

From Equation (c) we obtain

$$m + n = \lfloor (\lfloor \sqrt{8z + 1} \rfloor + 1)/2 \rfloor - 1.$$
 (d)

Since J(m, n) = z means that

$$2z = (m+n)^2 + 3m + n,$$

that is,

$$3m + n = 2z - (m + n)^2,$$
 (e)

we deduce from (d) and (e) that m and n are solutions of the system

$$m + n = \lfloor (\lfloor \sqrt{8z + 1} \rfloor + 1)/2 \rfloor - 1$$

$$3m + n = 2z - (\lfloor (\lfloor \sqrt{8z + 1} \rfloor + 1)/2 \rfloor - 1)^2.$$

If we let

$$Q_1(z) = \lfloor (\lfloor \sqrt{8z+1} \rfloor + 1)/2 \rfloor - 1$$

$$Q_2(z) = 2z - (\lfloor (\lfloor \sqrt{8z+1} \rfloor + 1)/2 \rfloor - 1)^2 = 2z - (Q_1(z))^2,$$

then we can prove that the number $Q_2(z) - Q_1(z)$ is even and that

$$m = \frac{1}{2}(Q_2(z) - Q_1(z)) = K(z)$$

$$n = Q_1(z) - \frac{1}{2}(Q_2(z) - Q_1(z)) = L(z).$$

Consequently, if z = J(m, n), then m = K(z) and n = L(z) as above, showing that m and n are unique and thus that J is injective. The above also proves that J, K, L satisfy the equations.

$$m = K(J(m, n))$$
$$n = L(J(m, n)).$$

It remains to prove that J is surjective. Let $z \in \mathbb{N}$ be any natural number and let $r \in \mathbb{N}$ be the largest number such that

$$1+2+\cdots+r \leq z.$$

If we let

$$x = z - (1 + 2 + \dots + r),$$
 (f)

then $x \leq r$, since otherwise $x \geq r+1$, and then (f) implies that $1+2+\cdots+r+(r+1) \leq z$, contradicting the maximality of r. Let $y = r - x \geq 0$. Then we have

$$z = (1 + 2 + \dots + r) + x$$

= (1 + 2 + \dots + x + y) + x
= $\frac{1}{2}(x + y)(x + y + 1) + x$
= $J(x, y)$.

Therefore J is surjective. But

$$x = K(J(x, y)) = K(z)$$
$$y = L(J(x, y)) = L(z),$$

 \mathbf{SO}

$$J(K(z), L(z)) = z,$$

as claimed.

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Theorem 8.1 yields explicit formulae for K and L. If we define

$$Q_1(z) = \lfloor (\lfloor \sqrt{8z+1} \rfloor + 1)/2 \rfloor - 1$$

$$Q_2(z) = 2z - (Q_1(z))^2,$$

then we have

$$K(z) = \frac{1}{2}(Q_2(z) - Q_1(z))$$
$$L(z) = Q_1(z) - \frac{1}{2}(Q_2(z) - Q_1(z))$$

In the above formula, the function $m \mapsto \lfloor \sqrt{m} \rfloor$ yields the largest integer s such that $s^2 \leq m$. These formulae also show that K and L are primitive recursive. An easier way to see this is to observe that since J is a bijection,

$$x \le J(x, y)$$
 and $y \le J(x, y)$,

we have

$$K(z) = \min(x \le z) (\exists y \le z) [J(x, y) = z]$$

and

$$L(z) = \min(y \le z) (\exists x \le z) [J(x, y) = z]$$

Therefore, by the results of Section 4.9, K and L are primitive recursive.

Observe that the equations K(J(a, b)) = a and L(J(a, b)) = b assert that J is injective and that the equation J(K(z), L(z)) = z assert that J is surjective, but the problem is that the definition of J does not obviously imply these properties so it is necessary to construct K and L as done in the proof of Theorem 8.1.

The pairing function J(x, y) is also denoted as $\langle x, y \rangle$, and K and L are also denoted as Π_1 and Π_2 . The notation $\langle x, y \rangle$ is "intentionally ambiguous," in the sense that it can be interpreted as the actual ordered pair consisting of the two numbers x and y, or as the number $\langle x, y \rangle = J(x, y)$ that encodes the pair consisting of the two numbers x and y. The context should make it clear which interpretation is intended. In this chapter and the next, it is the number (code) interpretation.

We can define bijections between \mathbb{N}^n and \mathbb{N} by induction for all $n \geq 1$.

Definition 8.2. The function $\langle -, \ldots, - \rangle_n \colon \mathbb{N}^n \to \mathbb{N}$ called an *extended pairing function* is defined as follows. We let

$$\langle z \rangle_1 = z$$

 $\langle x_1, x_2 \rangle_2 = \langle x_1, x_2 \rangle_2$

and

$$\langle x_1, \ldots, x_n, x_{n+1} \rangle_{n+1} = \langle x_1, \ldots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n,$$

for all $z, x_2, \ldots, x_{n+1} \in \mathbb{N}$.

Again we stress that $\langle x_1, \ldots, x_n \rangle_n$ is a *natural number*. For example.

$$\langle x_1, x_2, x_3 \rangle_3 = \langle x_1, \langle x_2, x_3 \rangle \rangle_2 = \langle x_1, \langle x_2, x_3 \rangle \rangle \langle x_1, x_2, x_3, x_4 \rangle_4 = \langle x_1, x_2, \langle x_3, x_4 \rangle \rangle_3 = \langle x_1, \langle x_2, \langle x_3, x_4 \rangle \rangle \rangle \langle x_1, x_2, x_3, x_4, x_5 \rangle_5 = \langle x_1, x_2, x_3, \langle x_4, x_5 \rangle \rangle_4 = \langle x_1, \langle x_2, \langle x_3, \langle x_4, x_5 \rangle \rangle \rangle.$$

It can be shown by induction on n that

$$\langle x_1, \dots, x_n, x_{n+1} \rangle_{n+1} = \langle x_1, \langle x_2, \dots, x_{n+1} \rangle_n \rangle.$$
(*)

Observe that if $z = \langle x_1, \ldots, x_n \rangle_n$, then $x_1 = \Pi_1(z)$, $x_2 = \Pi_1(\Pi_2(z))$, $x_3 = \Pi_1(\Pi_2(\Pi_2(z)))$, $x_4 = \Pi_1(\Pi_2(\Pi_2(\Pi_2(z))))$, $x_5 = \Pi_2(\Pi_2(\Pi_2(Z)))$.

We can also define a uniform projection function $\Pi \colon \mathbb{N}^3 \to \mathbb{N}$ with the following property: if $z = \langle x_1, \ldots, x_n \rangle_n$, with $n \ge 2$, then

$$\Pi(i, n, z) = x_i$$
 for all i , where $1 \le i \le n$.

The idea is to view z as an n-tuple, and $\Pi(i, n, z)$ as the *i*-th component of that n-tuple, but if z, n and *i* do not fit this interpretation, the function must be still be defined and we give it a "crazy" value by default using some simple primitive recursive clauses.

Definition 8.3. The uniform projection function $\Pi \colon \mathbb{N}^3 \to \mathbb{N}$ is defined by cases as follows:

$$\Pi(i, 0, z) = 0, \quad \text{for all } i \ge 0, \\ \Pi(i, 1, z) = z, \quad \text{for all } i \ge 0, \\ \Pi(i, 2, z) = \Pi_1(z), \quad \text{if } 0 \le i \le 1, \\ \Pi(i, 2, z) = \Pi_2(z), \quad \text{for all } i \ge 2, \end{cases}$$

and for all $n \geq 2$,

$$\Pi(i, n+1, z) = \begin{cases} \Pi(i, n, z) & \text{if } 0 \le i < n, \\ \Pi_1(\Pi(n, n, z)) & \text{if } i = n, \\ \Pi_2(\Pi(n, n, z)) & \text{if } i > n. \end{cases}$$

By the results of Section 4.9, this is a legitimate primitive recursive definition. If z is the code $\langle x_1, \ldots, x_{n+1} \rangle_{n+1}$ for the (n+1)-tuple (x_1, \ldots, x_{n+1}) with $n \ge 2$, then for $0 \le i < n$, the clause of Definition 8.3 that applies is

$$\Pi(i, n+1, z) = \Pi(i, n, z),$$

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and since

$$\langle x_1, \ldots, x_n, x_{n+1} \rangle_{n+1} = \langle x_1, \ldots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n$$

we have

$$\Pi(i, n+1, \langle x_1, \dots, x_n, x_{n+1} \rangle_{n+1}) = \Pi(i, n+1, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n)$$
$$= \Pi(i, n, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n),$$

and since $\langle x_1, \ldots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n$ codes an *n*-tuple, for $i = 1, \ldots, n-1$, the value returned is indeed x_i . If i = n, then the clause that applies is

$$\Pi(n, n+1, z) = \Pi_1(\Pi(n, n, z)),$$

so we have

$$\Pi(n, n+1, \langle x_1, \dots, x_n, x_{n+1} \rangle_{n+1}) = \Pi(n, n+1, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n)$$
$$= \Pi_1(\Pi(n, n, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n))$$
$$= \Pi_1(\langle x_n, x_{n+1} \rangle)$$
$$= x_n.$$

Finally, if i = n + 1, then the clause that applies is

$$\Pi(n+1, n+1, z) = \Pi_2(\Pi(n, n, z)),$$

so we have

$$\Pi(n+1, n+1, \langle x_1, \dots, x_n, x_{n+1} \rangle_{n+1}) = \Pi(n+1, n+1, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n)$$
$$= \Pi_2(\Pi(n, n, \langle x_1, \dots, x_{n-1}, \langle x_n, x_{n+1} \rangle \rangle_n))$$
$$= \Pi_2(\langle x_n, x_{n+1} \rangle)$$
$$= x_{n+1}.$$

When i = 0 or i > n + 1, we get "bogus" values.

Remark: One might argue that it would have been preferable to order the arguments of Π as (n, i, z) rather than (i, n, z). We use the order (i, n, z) in conformity with Machtey and Young [51].

Some basic properties of Π are given as exercises. In particular, the following properties are easily shown:

(a)
$$\langle 0, \ldots, 0 \rangle_n = 0, \ \langle x, 0 \rangle = \langle x, 0, \ldots, 0 \rangle_n;$$

- (b) $\Pi(0, n, z) = \Pi(1, n, z)$ and $\Pi(i, n, z) = \Pi(n, n, z)$, for all $i \ge n$ and all $n, z \in \mathbb{N}$;
- (c) $\langle \Pi(1, n, z), \dots, \Pi(n, n, z) \rangle_n = z$, for all $n \ge 1$ and all $z \in \mathbb{N}$;
- (d) $\Pi(i, n, z) \leq z$, for all $i, n, z \in \mathbb{N}$;

(e) There is a primitive recursive function Large, such that,

$$\Pi(i, n+1, \text{Large}(n+1, z)) = z,$$

for $i, n, z \in \mathbb{N}$.

As a first application, we observe that we need only consider partial computable functions (partial recursive functions)¹ of a single argument. Indeed, let $\varphi \colon \mathbb{N}^n \to \mathbb{N}$ be a partial computable function of $n \geq 2$ arguments. Let $\overline{\varphi} \colon \mathbb{N} \to \mathbb{N}$ be the function given by

$$\overline{\varphi}(z) = \varphi(\Pi(1, n, z), \dots, \Pi(n, n, z)),$$

for all $z \in \mathbb{N}$. Then $\overline{\varphi}$ is a partial computable function of a single argument, and φ can be recovered from $\overline{\varphi}$, since

$$\varphi(x_1,\ldots,x_n) = \overline{\varphi}(\langle x_1,\ldots,x_n \rangle_n).$$

Thus, using $\langle -, \cdots, - \rangle_n$ and Π as coding and decoding functions, we can restrict our attention to functions of a single argument.

From now on, since the context usually makes it clear we abbreviate $\langle x_1, \ldots, x_n \rangle_n$ as $\langle x_1, \ldots, x_n \rangle$.

Pairing functions can also be used to prove that certain functions are primitive recursive, even though their definition is not a legal primitive recursive definition. For example, consider the *Fibonacci function* defined as follows:

$$f(0) = 1,$$

 $f(1) = 1,$
 $f(n+2) = f(n+1) + f(n),$

for all $n \in \mathbb{N}$. This is not a legal primitive recursive definition, since f(n+2) depends both on f(n+1) and f(n). In a primitive recursive definition, $g(y+1,\overline{x})$ is only allowed to depend upon $g(y,\overline{x})$, where \overline{x} is an abbreviation for (x_2,\ldots,x_m) .

Definition 8.4. Given any function $f: \mathbb{N}^n \to \mathbb{N}$, the function $\overline{f}: \mathbb{N}^{n+1} \to \mathbb{N}$ defined such that $\overline{f}(-\overline{f}) = f(-\overline{f})$

$$f(y,\overline{x}) = \langle f(0,\overline{x}), \dots, f(y,\overline{x}) \rangle_{y+1}$$

is called the *course-of-value function* for f.

The following proposition holds.

Proposition 8.2. Given any function $f \colon \mathbb{N}^n \to \mathbb{N}$, if f is primitive recursive, then so is \overline{f} .

¹The term *partial recursive* is now considered old-fashion. Many researchers have switched to the term *partial computable*.

Proof. First it is necessary to define a function *con* such that if $x = \langle x_1, \ldots, x_m \rangle$ and $y = \langle y_1, \ldots, y_n \rangle$, where $m, n \ge 1$, then

$$con(m, x, y) = \langle x_1, \dots, x_m, y_1, \dots, y_n \rangle$$

This fact is left as an exercise. Now, if f is primitive recursive, let

$$f(0,\overline{x}) = f(0,\overline{x}),$$

$$\overline{f}(y+1,\overline{x}) = con(y+1,\overline{f}(y,\overline{x}), f(y+1,\overline{x})),$$

showing that \overline{f} is primitive recursive. Conversely, if \overline{f} is primitive recursive, then

$$f(y,\overline{x}) = \Pi(y+1, y+1, \overline{f}(y,\overline{x})),$$

and so, f is primitive recursive.

Remark: Why is it that

$$\overline{f}(y+1,\overline{x}) = \langle \overline{f}(y,\overline{x}), f(y+1,\overline{x}) \rangle$$

does not work? Check the definition of $\langle x_1, \ldots, x_n \rangle_n$.

We define *course-of-value recursion* as follows.

Definition 8.5. Given any two functions $g: \mathbb{N}^n \to \mathbb{N}$ and $h: \mathbb{N}^{n+2} \to \mathbb{N}$, the function $f: \mathbb{N}^{n+1} \to \mathbb{N}$ is defined by *course-of-value recursion* from g and h if

$$f(0,\overline{x}) = g(\overline{x}),$$

$$f(y+1,\overline{x}) = h(y,\overline{f}(y,\overline{x}),\overline{x}).$$

The following proposition holds.

Proposition 8.3. If $f: \mathbb{N}^{n+1} \to \mathbb{N}$ is defined by course-of-value recursion from g and h and g, h are primitive recursive, then f is primitive recursive.

Proof. We prove that \overline{f} is primitive recursive. Then by Proposition 8.2, f is also primitive recursive. To prove that \overline{f} is primitive recursive, observe that

$$\overline{f}(0,\overline{x}) = g(\overline{x}),$$

$$\overline{f}(y+1,\overline{x}) = con(y+1,\overline{f}(y,\overline{x}),h(y,\overline{f}(y,\overline{x}),\overline{x})).$$

When we use Proposition 8.3 to prove that a function is primitive recursive, we rarely bother to construct a formal course-of-value recursion. Instead, we simply indicate how the value of $f(y + 1, \overline{x})$ can be obtained in a primitive recursive manner from $f(0, \overline{x})$ through $f(y, \overline{x})$. Thus, an informal use of Proposition 8.3 shows that the Fibonacci function is primitive recursive. A rigorous proof of this fact is left as an exercise.

Next we show that there exist coding and decoding functions between Σ^* and $\{a_1\}^*$, and that partial computable functions over Σ^* can be recoded as partial computable functions over $\{a_1\}^*$. Since $\{a_1\}^*$ is isomorphic to \mathbb{N} , this shows that we can restrict out attention to functions defined over \mathbb{N} .

8.2 Equivalence of Alphabets

Given an alphabet $\Sigma = \{a_1, \ldots, a_k\}$, strings over Σ can be ordered by viewing strings as numbers in a number system where the digits are a_1, \ldots, a_k . In this number system, which is almost the number system with base k, the string a_1 corresponds to zero, and a_k to k-1. Hence, we have a kind of shifted number system in base k. The total order on Σ^* induced by this number system is defined so that u precedes v if |u| < |v|, and if |u| = |v|, then u comes before v in the lexicographic ordering. For example, if $\Sigma = \{a, b, c\}$, a listing of Σ^* in the ordering corresponding to the number system begins with

> a, b, c, aa, ab, ac, ba, bb, bc, ca, cb, cc, $aaa, aab, aac, aba, abb, abc, \ldots$

This ordering induces a function from Σ^* to \mathbb{N} which is a bijection. Indeed, if $u = a_{i_1} \cdots a_{i_n}$, this function $f \colon \Sigma^* \to \mathbb{N}$ is given by

$$f(u) = i_1 k^{n-1} + i_2 k^{n-2} + \dots + i_{n-1} k + i_n.$$

Since we also want a decoding function, we define the coding function $C_k \colon \Sigma^* \to \Sigma^*$ as follows:

 $C_k(\epsilon) = \epsilon$, and if $u = a_{i_1} \cdots a_{i_n}$, then

$$C_k(u) = a_1^{i_1k^{n-1} + i_2k^{n-2} + \dots + i_{n-1}k + i_n}.$$

The function C_k is primitive recursive, because

$$C_k(\epsilon) = \epsilon,$$

$$C_k(xa_i) = C_k(x)^k a_1^i.$$

The inverse of C_k is a function $D_k \colon \{a_1\}^* \to \Sigma^*$. However, primitive recursive functions are total, and we need to extend D_k to Σ^* . This is easily done by letting

$$D_k(x) = D_k(a_1^{|x|})$$

for all $x \in \Sigma^*$. It remains to define D_k by primitive recursion over $\Sigma^* = \{a_1, \ldots, a_k\}^*$. For this, we introduce three auxiliary functions p, q, r, defined as follows. Let

$$p(\epsilon) = \epsilon,$$

$$p(xa_i) = xa_i, \text{ if } i \neq k,$$

$$p(xa_k) = p(x).$$

Note that p(x) is the result of deleting consecutive a_k 's in the tail of x. Let

$$q(\epsilon) = \epsilon,$$

$$q(xa_i) = q(x)a_1.$$

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Note that $q(x) = a_1^{|x|}$. Finally, let

$$r(\epsilon) = a_1,$$

$$r(xa_i) = xa_{i+1}, \quad \text{if } i \neq k,$$

$$r(xa_k) = xa_k.$$

The function r is almost the successor function for the ordering. Then the trick is that $D_k(xa_i)$ is the successor of $D_k(x)$ in the ordering so usually $D_k(xa_i) = r(D_k(x))$, except if

$$D_k(x) = ya_j a_k^n$$

with $j \neq k$, since the successor of $ya_ja_k^n$ is $ya_{j+1}a_1^n$. Thus, we have

$$D_k(\epsilon) = \epsilon,$$

$$D_k(xa_i) = r(p(D_k(x)))q(D_k(x) - p(D_k(x))), \quad a_i \in \Sigma.$$

Then both C_k and D_k are primitive recursive, and $D_k \circ C_k = id$. Here

$$u - v = \begin{cases} \epsilon & \text{if } |u| \le |v| \\ w & \text{if } u = xw \text{ and } |x| = |v|. \end{cases}$$

In other words, u - v is u with its first |v| letters deleted. We can show that this function can be defined by primitive recursion by first defining $\operatorname{rdiff}(u, v)$ as v with its first |u| letters deleted, and then

$$u - v = \operatorname{rdiff}(v, u).$$

To define rdiff, we use tail given by

$$tail(\epsilon) = \epsilon$$
$$tail(a_i u) = u, \quad a_i \in \Sigma, \ u \in \Sigma^*.$$

We proved in Section 4.7 that *tail* is primitive recursive. Then

$$rdiff(\epsilon, v) = v$$

$$rdiff(ua_i, v) = rdiff(u, tail(v)), \quad a_i \in \Sigma.$$

We leave as an exercise to put all these definitions into the proper format of primitive recursion using projections.

Let $\varphi \colon (\Sigma^*)^n \to \Sigma^*$ be a partial function over Σ^* , and let $\varphi^+ \colon (\{a_1\}^*)^n \to \{a_1\}^*$ be the function given by

$$\varphi^+(x_1,\ldots,x_n)=C_k(\varphi(D_k(x_1),\ldots,D_k(x_n)))$$

Also, for any partial function $\psi \colon (\{a_1\}^*)^n \to \{a_1\}^*$, let $\psi^{\sharp} \colon (\Sigma^*)^n \to \Sigma^*$ be the function given by

$$\psi^{\sharp}(x_1,\ldots,x_n) = D_k(\psi(C_k(x_1),\ldots,C_k(x_n))).$$

We claim that if ψ is a partial computable function over $(\{a_1\}^*)^n$, then ψ^{\sharp} is partial computable over $(\Sigma^*)^n$, and that if φ is a partial computable function over $(\Sigma^*)^n$, then φ^+ is partial computable over $(\{a_1\}^*)^n$.

The function ψ can be extended to $(\Sigma^*)^n$ by letting

$$\psi(x_1, \dots, x_n) = \psi(a_1^{|x_1|}, \dots, a_1^{|x_n|})$$

for all $x_1, \ldots, x_n \in \Sigma^*$, and so, if ψ is partial computable, then so is the extended function, by composition. It follows that if ψ is partial (or primitive) recursive, then so is ψ^{\sharp} .

This seems equally obvious for φ and φ^+ , but there is a difficulty. The problem is that φ^+ is defined as a composition of functions over Σ^* . We have to show how φ^+ can be defined directly over $\{a_1\}^*$ without using any additional alphabet symbols. This is done in Machtey and Young [51], see Section 2.2, Lemma 2.2.3.

8.3 Coding of RAM Programs; The Halting Problem

In this section we present a specific encoding of RAM programs which allows us to treat programs as integers. This encoding will allow us to prove one of the most important results of computability theory first proven by Turing for Turing machines (1936-1937), the undecidability of the halting problem for RAM programs (and Turing machines).

Encoding programs as integers also allows us to have programs that take other programs as input, and we obtain a *universal program*. Universal programs have the property that given two inputs, the first one being the code of a program and the second one an input data, the universal program simulates the actions of the encoded program on the input data. A coding scheme is also called an indexing or a Gödel numbering, in honor to Gödel, who invented this technique.

From results of the previous chapter, without loss of generality, we can restrict out attention to RAM programs computing partial functions of one argument over \mathbb{N} . Furthermore, we only need the following kinds of instructions, each instruction being coded as shown below. Since we are considering functions over the natural numbers, which corresponds to a one-letter alphabet, there is only one kind of instruction of the form add and jmp (add increments by 1 the contents of the specified register R_j).

Recall that a conditional jump causes a jump to the closest address Nk above or below iff Rj is nonzero, and if Rj is null, the next instruction is executed. We assume that all lines in a RAM program are numbered. This is always feasible, by labeling unnamed instructions with a new and unused line number.

Ni		add	Rj	$code = \langle 1, i, j, 0 \rangle$
Ni		tail	Rj	$code = \langle 2, i, j, 0 \rangle$
Ni		continue		$code = \langle 3, i, 1, 0 \rangle$
Ni	Rj	jmp	Nka	$code = \langle 4, i, j, k \rangle$
Ni	Rj	jmp	Nkb	$code = \langle 5, i, j, k \rangle$

Definition 8.6. Instructions of a RAM program (operating on \mathbb{N}) are coded as follows:

The code of an instruction I is denoted as #I.

To simplify the notation, we introduce the following notation.

Definition 8.7. The decoding primitive recursive functions Typ, LNum, Reg, and Jmp, are defined as follows:

$$Typ(x) = \Pi(1, 4, x)$$
$$LNum(x) = \Pi(2, 4, x)$$
$$Reg(x) = \Pi(3, 4, x)$$
$$Jmp(x) = \Pi(4, 4, x).$$

The functions yield the type, line number, register name, and line number jumped to, if any, for an instruction coded by x. Note that we have no need to interpret the values of these functions if x does not code an instruction.

We can define the primitive recursive predicate INST, such that INST(x) holds iff x codes an instruction. First, we need the connective \Rightarrow (*implies*), defined such that

$$P \Rightarrow Q$$
 iff $\neg P \lor Q$.

Definition 8.8. The predicate INST(x) is defined primitive recursively as follows:

$$[1 \le \operatorname{Typ}(x) \le 5] \land [1 \le \operatorname{Reg}(x)] \land$$

$$[\operatorname{Typ}(x) \le 3 \Rightarrow \operatorname{Jmp}(x) = 0] \land$$

$$[\operatorname{Typ}(x) = 3 \Rightarrow \operatorname{Reg}(x) = 1].$$

The predicate INST(x) says that if x is the code of an instruction, say $x = \langle c, i, j, k \rangle$, then $1 \le c \le 5$, $j \ge 1$, if $c \le 3$, then k = 0, and if c = 3, then we also have j = 1.

Definition 8.9. Program are coded as follows. If P is a RAM program composed of the n instructions I_1, \ldots, I_n , the code of P, denoted as #P, is

$$\#P = \langle n, \#I_1, \dots, \#I_n \rangle.$$

Recall from Property (*) in Section 8.1 that

$$\langle n, \#I_1, \ldots, \#I_n \rangle = \langle n, \langle \#I_1, \ldots, \#I_n \rangle \rangle.$$

Also recall from Definition 8.1 that

$$\langle x, y \rangle = ((x+y)^2 + 3x + y)/2.$$

Example 8.1. Consider the following program Padd2 computing the function add2: $\mathbb{N} \to \mathbb{N}$ given by

$$\operatorname{add2}(n) = n + 2.$$

Padd2:

$I_1:$	1	add	R1
I_2 :	2	add	R1
I_3 :	3	continue	

We have

$$#I1 = \langle 1, 1, 1, 0 \rangle_4 = \langle 1, \langle 1, \langle 1, 0 \rangle \rangle = 37$$

$$#I2 = \langle 1, 2, 1, 0 \rangle_4 = \langle 1, \langle 2, \langle 1, 0 \rangle \rangle = 92$$

$$#I3 = \langle 3, 3, 1, 0 \rangle_4 = \langle 3, \langle 3, \langle 1, 0 \rangle \rangle = 234$$

and

$$#Padd2 = \langle 3, \#I1, \#I2, \#I3 \rangle_4 = \langle 3, \langle 37, \langle 92, 234 \rangle \rangle$$

= 1018 748 519 973 070 618.

The codes get big fast!

Definition 8.10. We define the primitive recursive functions Ln, Pg, and Line, such that:

$$Ln(x) = \Pi(1, 2, x)$$

$$Pg(x) = \Pi(2, 2, x)$$

$$Line(i, x) = \Pi(i, Ln(x), Pg(x)).$$

The function Ln yields the length of the program (the number of instructions), Pg yields the sequence of instructions in the program (really, a code for the sequence), and Line(i, x) yields the code of the *i*th instruction in the program.

Again, if x does not code a program, there is no need to interpret these functions. However, note that by a previous exercise, it happens that

$$\operatorname{Line}(0, x) = \operatorname{Line}(1, x), \quad \text{and}$$
$$\operatorname{Line}(\operatorname{Ln}(x), x) = \operatorname{Line}(i, x), \quad \text{for all } i \ge \operatorname{Ln}(x).$$

The primitive recursive predicate PROG is defined such that PROG(x) holds iff x codes a program. Thus, PROG(x) holds if each line codes an instruction, each jump has an instruction to jump to, and the last instruction is a **continue**. **Definition 8.11.** The primitive recursive predicate PROG(x) is given by

$$\begin{aligned} \forall i \leq \operatorname{Ln}(x) [i \geq 1 \Rightarrow \\ [\operatorname{INST}(\operatorname{Line}(i, x)) \wedge \operatorname{Typ}(\operatorname{Line}(\operatorname{Ln}(x), x)) &= 3 \\ & \wedge [\operatorname{Typ}(\operatorname{Line}(i, x)) = 4 \Rightarrow \\ \exists j \leq i - 1 [j \geq 1 \wedge \operatorname{LNum}(\operatorname{Line}(j, x)) &= \operatorname{Jmp}(\operatorname{Line}(i, x))]] \wedge \\ [\operatorname{Typ}(\operatorname{Line}(i, x)) &= 5 \Rightarrow \\ \exists j \leq \operatorname{Ln}(x) [j > i \wedge \operatorname{LNum}(\operatorname{Line}(j, x)) &= \operatorname{Jmp}(\operatorname{Line}(i, x))]]]] \end{aligned}$$

Note that we have used Proposition 4.7 which states that if f is a primitive recursive function and if P is a primitive recursive predicate, then $\exists x \leq f(y)P(x)$ is primitive recursive.

The last instruction Line(Ln(x), x) in the program must be a **continue**, which means that Typ(Line(Ln(x), x)) = 3. When the *i*th instruction coded by Line(i, x) of the program coded by x has its first field Typ(Line(i, x)) = 4, this instruction is a jump above, and there must be an instruction in line j above instruction in line i, which means that $1 \le j \le i - 1$, and the line number LNum(Line(j, x)) of the jth instruction must be equal to the jump address Jmp(Line(i, x)) of the *i*th instruction. When Typ(Line(i, x)) = 5, this instruction is a jump below, and the analysis is similar.

We are now ready to prove a fundamental result in the theory of algorithms. This result points out some of the limitations of the notion of algorithm.

Theorem 8.4. (Undecidability of the halting problem) There is no RAM program **Decider** which halts for all inputs and has the following property when started with input x in register R1 and with input i in register R2 (the other registers being set to zero):

(1) **Decider** halts with output 1 iff i codes a program that eventually halts when started on input x (all other registers set to zero).

(2) **Decider** halts with output 0 in R1 iff i codes a program that runs forever when started on input x in R1 (all other registers set to zero).

(3) If i does not code a program, then **Decider** halts with output 2 in R1.

Proof. Assume that **Decider** is such a RAM program, and let Q be the following program with a single input:

$$\operatorname{Program} Q \left(\operatorname{code} q \right) \left\{ \begin{array}{ccc} R2 \leftarrow & R1 \\ & P \\ N1 & \texttt{continue} \\ & R1 \; \texttt{jmp} & N1a \\ & & \texttt{continue} \end{array} \right.$$

Let *i* be the code of some program *P*. The key point is that the termination behavior of Q on input *i* is exactly the opposite of the termination behavior of **Decider** on input *i* and code *i*.

- (1) If **Decider** says that program P coded by *i* halts on input *i*, then R1 just after the continue in line N1 contains 1, and Q loops forever.
- (2) If **Decider** says that program P coded by *i loops forever* on input *i*, then R1 just after continue in line N1 contains 0, and Q halts.

The program Q can be translated into a program using only instructions of type 1, 2, 3, 4, 5, described previously, and let q be the code of the program Q.

Let us see what happens if we run the program Q on input q in R1 (all other registers set to zero).

Just after execution of the assignment $R2 \leftarrow R1$, the program **Decider** is started with q in both R1 and R2. Since **Decider** is supposed to halt for all inputs, it eventually halts with output 0 or 1 in R1. If **Decider** halts with output 1 in R1 (which means that Q halts on input q), then Q goes into an infinite loop, while if **Decider** halts with output 0 in R1 (which means that Q loops forever on input q), then Q halts. But then, we see that **Decider** says that Q halts when started on input q iff Q loops forever on input q, a contradiction. Therefore, **Decider** cannot exist.

The argument used in the proof of 8.4 is quite similar in spirit to "Russell's Paradox." If we identify the notion of algorithm with that of a RAM program which halts for all inputs, the above theorem says that there is *no* algorithm for deciding whether a RAM program eventually halts for a given input. We say that the halting problem for RAM programs is *undecidable* (or *unsolvable*).

The above theorem also implies that the halting problem for Turing machines is undecidable. Indeed, if we had an algorithm for solving the halting problem for Turing machines, we could solve the halting problem for RAM programs as follows: first, apply the algorithm for translating a RAM program into an equivalent Turing machine, and then apply the algorithm solving the halting problem for Turing machines.

The argument is typical in computability theory and is called a "reducibility argument."

Our next goal is to define a primitive recursive function that describes the computation of RAM programs.

8.4 Universal RAM Programs

To describe the computation of a RAM program, we need to code not only RAM programs but also the contents of the registers. Assume that we have a RAM program P using nregisters $R1, \ldots, Rn$, whose contents are denoted as r_1, \ldots, r_n . We can code r_1, \ldots, r_n into a single integer $\langle r_1, \ldots, r_n \rangle$. Conversely, every integer x can be viewed as coding the contents of $R1, \ldots, Rn$, by taking the sequence $\Pi(1, n, x), \ldots, \Pi(n, n, x)$. Actually, it is not necessary to know n, the number of registers, if we make the following observation:

$$\operatorname{Reg}(\operatorname{Line}(i, x)) \le \operatorname{Line}(i, x) \le \operatorname{Pg}(x) < x$$

for all $i, x \in \mathbb{N}$. If x codes a program, then $R1, \ldots, Rx$ certainly include all the registers in the program. Also note that from a previous exercise,

$$\langle r_1, \ldots, r_n, 0, \ldots, 0 \rangle = \langle r_1, \ldots, r_n, 0 \rangle.$$

We now define the primitive recursive functions Nextline, Nextcont, and Comp, describing the computation of RAM programs. There are a lot of tedious technical details that the reader should skip upon first reading. However, to be rigorous, we must spell out all these details.

Definition 8.12. Let x code a program and let i be such that $1 \le i \le Ln(x)$. The following functions are defined:

(1) Nextline(i, x, y) is the number of the next instruction to be executed after executing the *i*th instruction (the current instruction) in the program coded by x, where the contents of the registers is coded by y.

(2) Nextcont(i, x, y) is the code of the contents of the registers after executing the *i*th instruction in the program coded by x, where the contents of the registers is coded by y.

(3) $\operatorname{Comp}(x, y, m) = \langle i, z \rangle$, where *i* and *z* are defined such that after running the program coded by *x* for *m* steps, where the initial contents of the program registers are coded by *y*, the next instruction to be executed is the *i*th one, and *z* is the code of the current contents of the registers.

Proposition 8.5. The functions Nextline, Nextcont, and Comp are primitive recursive.

Proof. (1) Nextline(i, x, y) = i + 1, unless the *i*th instruction is a jump and the contents of the register being tested is nonzero:

 $\begin{aligned} \operatorname{Nextline}(i, x, y) &= \\ \max j \leq \operatorname{Ln}(x)[j < i \wedge \operatorname{LNum}(\operatorname{Line}(j, x)) = \operatorname{Jmp}(\operatorname{Line}(i, x))] \\ & \text{if Typ}(\operatorname{Line}(i, x)) = 4 \wedge \Pi(\operatorname{Reg}(\operatorname{Line}(i, x)), x, y) \neq 0 \\ & \min j \leq \operatorname{Ln}(x)[j > i \wedge \operatorname{LNum}(\operatorname{Line}(j, x)) = \operatorname{Jmp}(\operatorname{Line}(i, x))] \\ & \text{if Typ}(\operatorname{Line}(i, x)) = 5 \wedge \Pi(\operatorname{Reg}(\operatorname{Line}(i, x)), x, y) \neq 0 \\ & i + 1 \text{ otherwise.} \end{aligned}$

For example, if the *i*th instruction of the program coded by x is a jump above, namely $\operatorname{Typ}(\operatorname{Line}(i, x)) = 4$, then the register being tested is $\operatorname{Reg}(\operatorname{Line}(i, x))$, and its contents must be nonzero for a jump to occur, so the contents of this register, which is obtained from the code y of all registers as $\Pi(\operatorname{Reg}(\operatorname{Line}(i, x)), x, y)$ (remember that we may assume that there are x registers, by padding with zeros) must be nonzero.

Note that according to this definition, if the *i*th line is the final continue, then Nextline signals that the program has halted by yielding

(2) We need two auxiliary functions Add and Sub defined as follows.

Add(j, x, y) is the number coding the contents of the registers used by the program coded by x after register Rj coded by $\Pi(j, x, y)$ has been increased by 1, and

 $\operatorname{Sub}(j, x, y)$ codes the contents of the registers after register Rj has been decremented by 1 (y codes the previous contents of the registers). It is easy to see that

$$\begin{aligned} \operatorname{Sub}(j, x, y) &= \min z \leq y [\Pi(j, x, z) = \Pi(j, x, y) - 1 \\ &\wedge \forall k \leq x [0 < k \neq j \Rightarrow \Pi(k, x, z) = \Pi(k, x, y)]]. \end{aligned}$$

The definition of Add is slightly more tricky. We leave as an exercise to the reader to prove that:

$$\begin{aligned} \operatorname{Add}(j, x, y) &= \min z \leq \operatorname{Large}(x, y + 1) \\ & [\Pi(j, x, z) = \Pi(j, x, y) + 1 \land \forall k \leq x [0 < k \neq j \Rightarrow \Pi(k, x, z) = \Pi(k, x, y)]], \end{aligned}$$

where the function Large is the function defined in an earlier exercise. Then

$$\begin{split} \operatorname{Nextcont}(i, x, y) &= \\ & \operatorname{Add}(\operatorname{Reg}(\operatorname{Line}(i, x), x, y) \quad \text{if} \quad \operatorname{Typ}(\operatorname{Line}(i, x)) = 1 \\ & \operatorname{Sub}(\operatorname{Reg}(\operatorname{Line}(i, x), x, y) \quad \text{if} \quad \operatorname{Typ}(\operatorname{Line}(i, x)) = 2 \\ & y \quad \text{if} \quad \operatorname{Typ}(\operatorname{Line}(i, x)) \geq 3. \end{split}$$

(3) Recall that $\Pi_1(z) = \Pi(1, 2, z)$ and $\Pi_2(z) = \Pi(2, 2, z)$. The function Comp is defined by primitive recursion as follows:

$$Comp(x, y, 0) = \langle 1, y \rangle$$

$$Comp(x, y, m + 1) = \langle Nextline(\Pi_1(Comp(x, y, m)), x, \Pi_2(Comp(x, y, m))), x, \Pi_2(Comp(x, y, m))) \rangle.$$

$$Nextcont(\Pi_1(Comp(x, y, m)), x, \Pi_2(Comp(x, y, m))) \rangle.$$

If $\operatorname{Comp}(x, y, m) = \langle i, z \rangle$, then $\Pi_1(\operatorname{Comp}(x, y, m)) = i$ is the number of the next instruction to be executed and $\Pi_2(\operatorname{Comp}(x, y, m)) = z$ codes the current contents of the registers, so

$$Comp(x, y, m+1) = \langle Nextline(i, x, z), Nextcont(i, x, z) \rangle,$$

as desired.

We can now reprove that every RAM computable function is partial computable. Indeed, assume that x codes a program P.

We would like to define the partial function End so that for all x, y, where x codes a program and y codes the contents of its registers, End(x, y) is the number of steps for which the computation runs before halting, if it halts. If the program does not halt, then End(x, y) is undefined.

If y is the value of the register R1 before the program P coded by x is started, recall that the contents of the registers is coded by $\langle y, 0 \rangle$. Noticing that 0 and 1 do not code programs, we note that if x codes a program, then $x \ge 2$, and $\Pi_1(z) = \Pi(1, x, z)$ is the contents of R1 as coded by z.

Since $\operatorname{Comp}(x, y, m) = \langle i, z \rangle$, we have

 $\Pi_1(\operatorname{Comp}(x, y, m)) = i,$

where *i* is the number (index) of the instruction reached after running the program *P* coded by *x* with initial values of the registers coded by *y* for *m* steps. Thus, *P* halts if *i* is the last instruction in *P*, namely Ln(x), iff

$$\Pi_1(\operatorname{Comp}(x, y, m)) = \operatorname{Ln}(x).$$

This suggests the following definition.

Definition 8.13. The partial function End(x, y) is defined by

 $\operatorname{End}(x, y) = \min m[\Pi_1(\operatorname{Comp}(x, y, m)) = \operatorname{Ln}(x)].$

Note that End is a partial computable function; it can be computed by a RAM program involving *only one while loop* searching for the number of steps m. The function involved in the minimization is *primitive recursive*. However, in general, End is not a total function.

If φ is the partial computable function computed by the program P coded by x, then we claim that

$$\varphi(y) = \Pi_1(\Pi_2(\operatorname{Comp}(x, \langle y, 0 \rangle, \operatorname{End}(x, \langle y, 0 \rangle))))$$

This is because if $m = \text{End}(x, \langle y, 0 \rangle)$ is the number of steps after which the program P coded by x halts on input y, then

$$\operatorname{Comp}(x, \langle y, 0 \rangle, m)) = \langle \operatorname{Ln}(x), z \rangle,$$

where z is the code of the register contents when the program stops. Consequently

$$z = \Pi_2(\text{Comp}(x, \langle y, 0 \rangle, m))$$

$$z = \Pi_2(\text{Comp}(x, \langle y, 0 \rangle, \text{End}(x, \langle y, 0 \rangle)))$$

The value of the register R1 is $\Pi_1(z)$, that is

$$\varphi(y) = \Pi_1(\Pi_2(\operatorname{Comp}(x, \langle y, 0 \rangle, \operatorname{End}(x, \langle y, 0 \rangle))).$$

The above fact is worth recording as the following proposition which is a variant of a result known as the *Kleene normal form*

Proposition 8.6. (Kleene normal form for RAM programs) If φ is the partial computable function computed by the program P coded by x, then we have

$$\varphi(y) = \Pi_1(\Pi_2(\operatorname{Comp}(x, \langle y, 0 \rangle, \operatorname{End}(x, \langle y, 0 \rangle))) \quad \text{for all } y \in \mathbb{N}.$$

Observe that φ is written in the form $\varphi = g \circ \min f$, for some primitive recursive functions f and g. It will be convenient to denote the function φ computed by the RAM program P coded by x as φ_x . We also denote the program P coded by x as P_x .

We can also exhibit a partial computable function which enumerates all the unary partial computable functions. It is a *universal function*.

Abusing the notation slightly, we will write $\varphi(x, y)$ for $\varphi(\langle x, y \rangle)$, viewing φ as a function of two arguments (however, φ is really a function of a single argument). We define the function φ_{univ} as follows:

$$\varphi_{univ}(x,y) = \begin{cases} \Pi_1(\Pi_2(\operatorname{Comp}(x,\langle y,0\rangle,\operatorname{End}(x,\langle y,0\rangle))) & \text{if } \operatorname{PROG}(x), \\ \text{undefined} & \text{otherwise.} \end{cases}$$

The function φ_{univ} is a partial computable function with the following property: for every x coding a RAM program P, for every input y,

$$\varphi_{univ}(x,y) = \varphi_x(y),$$

the value of the partial computable function φ_x computed by the RAM program P coded by x. If x does not code a program, then $\varphi_{univ}(x, y)$ is undefined for all y.

By Proposition 4.9, the partial function φ_{univ} is not computable (recursive).² Indeed, being an enumerating function for the partial computable functions, it is an enumerating function for the total computable functions, and thus, it cannot be computable. Being a partial function saves us from a contradiction.

The existence of the universal function φ_{univ} is sufficiently important to be recorded in the following proposition.

Proposition 8.7. (Universal RAM program) For the indexing of RAM programs defined earlier, there is a universal partial computable function φ_{univ} such that, for all $x, y \in \mathbb{N}$, if φ_x is the partial computable function computed by the program P_x coded by x, then

$$\varphi_x(y) = \varphi_{univ}(\langle x, y \rangle).$$

The program UNIV computing φ_{univ} can be viewed as an *interpreter* for RAM programs. By giving the universal program UNIV the "program" x and the "data" y, we get the result

 $^{^{2}}$ The term *recursive function* is now considered old-fashion. Many researchers have switched to the term *computable function*.

of executing program P_x on input y. We can view the RAM model as a stored program computer.

By Theorem 8.4 and Proposition 8.7, the halting problem for the single program UNIV is undecidable. Otherwise, the halting problem for RAM programs would be decidable, a contradiction. It should be noted that the program UNIV can actually be written (with a certain amount of pain).

The existence of the function φ_{univ} leads us to the notion of an *indexing* of the RAM programs.

8.5 Indexing of RAM Programs

We can define a listing of the RAM programs as follows. If x codes a program (that is, if PROG(x) holds) and P is the program that x codes, we call this program P the xth RAM program and denote it as P_x . If x does not code a program, we let P_x be the program that diverges for every input:

N1		add	R1
N1	R1	jmp	N1a
N1		continue	

Therefore, in all cases, P_x stands for the *x*th RAM program. Thus, we have a listing of RAM programs, $P_0, P_1, P_2, P_3, \ldots$, such that every RAM program (of the restricted type considered here) appears in the list exactly once, except for the "infinite loop" program. For example, the program Padd2 (adding 2 to an integer) appears as

$P_{1\,018\,748\,519\,973\,070\,618}.$

In particular, note that φ_{univ} being a partial computable function, it is computed by some RAM program UNIV that has a code *univ* and is the program P_{univ} in the list.

Having an indexing of the RAM programs, we also have an indexing of the partial computable functions.

Definition 8.14. For every integer $x \ge 0$, we let P_x be the RAM program coded by x as defined earlier, and φ_x be the partial computable function computed by P_x .

For example, the function add2 (adding 2 to an integer) appears as

$\varphi_{1\,018\,748\,519\,973\,070\,618}.$

Remark: Kleene used the notation $\{x\}$ for the partial computable function coded by x. Due to the potential confusion with singleton sets, we follow Rogers, and use the notation φ_x ; see Rogers [64], page 21. It is important to observe that different programs P_x and P_y may compute the same function, that is, while $P_x \neq P_y$ for all $x \neq y$, it is possible that $\varphi_x = \varphi_y$. For example, the program P_y coded by y may be the program obtained from the program P_x coded by x obtained by adding and subtracting 1 a million times to a register not in the program P_x . In fact, it is undecidable whether $\varphi_x = \varphi_y$.

The object of the next section is to show the existence of Kleene's T-predicate. This will yield another important normal form. In addition, the T-predicate is a basic tool in recursion theory.

8.6 Kleene's *T*-Predicate

In Section 8.3, we have encoded programs. The idea of this section is to also encode *computations* of RAM programs. Assume that x codes a program, that y is some input (not a code), and that z codes a computation of P_x on input y.

Definition 8.15. The predicate T(x, y, z) is defined as follows:

T(x, y, z) holds iff x codes a RAM program, y is an input, and z codes a halting computation of P_x on input y.

The code z of a computation packs the consecutive "states" of the computation, namely the pairs $\langle i_j, y_j \rangle$, where i_j is the physical location of the next instruction to be executed and each y_j codes the contents of the registers just before execution of this instruction. We will show that T is primitive recursive.

First we need to *encode computations*. We say that z codes a computation of length $n \ge 1$ if

$$z = \langle n+2, \langle 1, y_0 \rangle, \langle i_1, y_1 \rangle, \dots, \langle i_n, y_n \rangle \rangle,$$

where each i_j is the physical location of the next instruction to be executed and each y_j codes the contents of the registers just before execution of the instruction at the location i_j . Also, y_0 codes the initial contents of the registers, that is, $y_0 = \langle y, 0 \rangle$, for some input y.

We let $Lz(z) = \Pi_1(z)$ (not to be confused with Ln(x)).

Note that i_j denotes the physical location of the next instruction to be executed in the sequence of instructions constituting the program coded by x, and not the line number (label) of this instruction. Thus, the first instruction to be executed is in location $1, 1 \leq i_j \leq \text{Ln}(x)$, and $i_{n-1} = \text{Ln}(x)$. Since the last instruction which is executed is the last physical instruction in the program, namely, a **continue**, there is no next instruction to be executed after that, and i_n is irrelevant. Writing the definition of T is a little simpler if we let $i_n = \text{Ln}(x) + 1$.
Definition 8.16. The *T*-predicate is the primitive recursive predicate defined as follows:

$$\begin{split} T(x,y,z) & \text{iff} \quad \mathrm{PROG}(x) \text{ and } (\mathrm{Lz}(z) \geq 3) \text{ and} \\ \forall j \leq \mathrm{Lz}(z) - 3[0 \leq j \Rightarrow \\ \mathrm{Nextline}(\Pi_1(\Pi(j+2,\mathrm{Lz}(z),z)), x, \Pi_2(\Pi(j+2,\mathrm{Lz}(z),z))) = \Pi_1(\Pi(j+3,\mathrm{Lz}(z),z)) \text{ and} \\ \mathrm{Nextcont}(\Pi_1(\Pi(j+2,\mathrm{Lz}(z),z)), x, \Pi_2(\Pi(j+2,\mathrm{Lz}(z),z))) = \Pi_2(\Pi(j+3,\mathrm{Lz}(z),z)) \text{ and} \\ \Pi_1(\Pi(\mathrm{Lz}(z) - 1,\mathrm{Lz}(z),z)) = \mathrm{Ln}(x) \text{ and} \\ \Pi_1(\Pi(2,\mathrm{Lz}(z),z)) = 1 \text{ and} \\ y = \Pi_1(\Pi_2(\Pi(2,\mathrm{Lz}(z),z))) \text{ and } \Pi_2(\Pi_2(\Pi(2,\mathrm{Lz}(z),z))) = 0]. \end{split}$$

The reader can verify that T(x, y, z) holds iff x codes a RAM program, y is an input, and z codes a halting computation of P_x on input y. For example, since

$$z = \langle n+2, \langle 1, y_0 \rangle, \langle i_1, y_1 \rangle, \dots, \langle i_n, y_n \rangle \rangle,$$

we have $\Pi(j + 2, \operatorname{Lz}(z), z) = \langle i_{j-1}, y_{j-1} \rangle$ and $\Pi(j + 3, \operatorname{Lz}(z), z) = \langle i_j, y_j \rangle$, so $\Pi_1(\Pi(j + 2, \operatorname{Lz}(z), z)) = \Pi_1(\langle i_{j-1}, y_{j-1} \rangle) = i_{j-1}, \Pi_2(\Pi(j + 2, \operatorname{Lz}(z), z)) = \Pi_2(\langle i_{j-1}, y_{j-1} \rangle) = y_{j-1},$ and similarly $\Pi_1(\Pi(j + 3, \operatorname{Lz}(z), z)) = i_j, \Pi_2(\Pi(j + 3, \operatorname{Lz}(z), z)) = y_j$, so the *T* predicate expresses that Nextline $(i_{j-1}, y_{j-1}) = i_j$ and Nextcont $(i_{j-1}, y_{j-1}) = y_j$.

In order to extract the output of P_x from z, we define the primitive recursive function Res as follows:

$$\operatorname{Res}(z) = \Pi_1(\Pi_2(\Pi(\operatorname{Lz}(z), \operatorname{Lz}(z), z))).$$

The explanation for this formula is that if $\Pi(\text{Lz}(z), \text{Lz}(z), z) = \langle i_n, y_n \rangle$, then $\Pi_2(\Pi(\text{Lz}(z), \text{Lz}(z), z)) = y_n$, the code of the registers, and since the output is returned in Register R1, Res(z) is the contents of register R1 when P_x halts, that is, $\Pi_1(y_{\text{Lz}(z)})$. Using the *T*-predicate, we get the so-called Kleene normal form.

Theorem 8.8. (Kleene Normal Form) Using the indexing of the partial computable functions defined earlier, we have

 $\varphi_x(y) = \operatorname{Res}[\min z(T(x, y, z))],$

where T(x, y, z) and Res are primitive recursive.

Note that the universal function φ_{univ} can be defined as

$$\varphi_{univ}(x, y) = \operatorname{Res}[\min z(T(x, y, z))].$$

There is another important property of the partial computable functions, namely, that composition is effective (computable). We need two auxiliary primitive recursive functions. The function Conprogs creates the code of the program obtained by concatenating the programs P_x and P_y , and for $i \ge 2$, Cumclr(i) is the code of the program which clears registers $R2, \ldots, Ri$. To get Cumclr, we can use the function clr(i) such that clr(i) is the code of the program

N1		tail	Ri
N1	Ri	jmp	N1a
N		continue	

We leave it as an exercise to prove that clr, Conprogs, and Cumclr, are primitive recursive.

Theorem 8.9. There is a primitive recursive function c such that

$$\varphi_{c(x,y)} = \varphi_x \circ \varphi_y.$$

Proof. If both x and y code programs, then $\varphi_x \circ \varphi_y$ can be computed as follows: Run P_y , clear all registers but R1, then run P_x . Otherwise, let loop be the index of the infinite loop program:

$$c(x,y) = \begin{cases} \operatorname{Conprogs}(y, \operatorname{Conprogs}(\operatorname{Cumclr}(y), x)) & \text{if } \operatorname{PROG}(x) \text{ and } \operatorname{PROG}(y) \\ \text{loop} & \text{otherwise.} \end{cases} \qquad \Box$$

8.7 A Non-Computable Function; Busy Beavers

Total functions that are not computable must grow very fast and thus are very complicated. Yet, in 1962, Radó published a paper in which he defined two functions Σ and S (involving computations of Turing machines) that are total and not computable.

Consider Turing machines with a tape alphabet $\Gamma = \{1, B\}$ with two symbols (*B* being the blank). We also assume that these Turing machines have a special final state q_F , which is a blocking state (there are no transitions from q_F). We do not count this state when counting the number of states of such Turing machines. The game is to run such Turing machines with a fixed number of states *n* starting on a blank tape, with the goal of producing the maximum number of (not necessarily consecutive) ones (1).

Definition 8.17. The function Σ (defined on the positive natural numbers) is defined as the maximum number $\Sigma(n)$ of (not necessarily consecutive) 1's written on the tape after a Turing machine with $n \ge 1$ states started on the blank tape halts. The function S is defined as the maximum number S(n) of moves that can be made by a Turing machine of the above type with n states before it halts, started on the blank tape.³

Definition 8.18. A Turing machine with n states that writes the maximum number $\Sigma(n)$ of 1's when started on the blank tape is called a *busy beaver*.

Busy beavers are hard to find, even for small n. First, it can be shown that the number of distinct Turing machines of the above kind with n states is $(4(n+1))^{2n}$. Second, since

³The function S defined here is obviously not the successor function from Definition 4.16.

it is undecidable whether a Turing machine halts on a given input, it is hard to tell which machines loop or halt after a very long time.

Here is a summary of what is known for $1 \le n \le 6$. Observe that the exact value of $\Sigma(6)$ and S(6) is unknown.

n	$\Sigma(n)$	S(n)
1	1	1
2	4	6
3	6	21
4	13	107
5	4098	47, 176, 870
6	$\geq 95, 524, 079$	$\geq 8,690,333,381,690,951$
6	$\geq 3.515 \times 10^{18267}$	$\geq 7.412 \times 10^{36534}$

The first entry in the table for n = 6 corresponds to a machine due to Heiner Marxen (1999). This record was surpassed by Pavel Kropitz in 2010, which corresponds to the second entry for n = 6. The machines achieving the record in 2017 for n = 4, 5, 6 are shown below, where the blank is denoted Δ instead of B, and where the special halting state is denoted H:

4-state busy beaver:

	A	В	C	D
Δ	(1, R, B)	(1, L, A)	(1, R, H)	(1, R, D)
1	(1,L,B)	(Δ, L, C)	(1,L,D)	(Δ, R, A)

The above machine output 13 ones in 107 steps. In fact, the output is

$1 \Delta 1 1 1 1 1 1 1 1 1 1 1 1 1$.

5-state busy beaver:

	A	В	C	D	E
Δ	(1, R, B)	(1, R, C)	(1, R, D)	(1, L, A)	(1, R, H)
1	(1,L,C)	(1, R, B)	(Δ, L, E)	(1, L, D)	(Δ, L, A)

The above machine output 4098 ones in 47, 176, 870 steps. The tape actually contains a total of 12289 symbols, 4098 if which are 1's, and the other the blank Δ .

The fact that this machine is a busy beaver was established in 2024 with the help of the Coq proof assistant. The proof is an enumeration of roughly 180 million machines, which are checked for termination with specialized deciders that recognize specific behaviors. This is quite a "tour de force."

6-state contender (Heiner Marxen):

	A	В	C	D	E	F
Δ	(1, R, B)	(1,L,C)	(Δ, R, F)	(1, R, A)	(1, L, H)	(Δ, L, A)
1	(1, R, A)	(1,L,B)	(1,L,D)	(Δ, L, E)	(1, L, F)	(Δ, L, C)

The above machine outputs 96, 524, 079 ones in 8, 690, 333, 381, 690, 951 steps. 6-state best contender (Pavel Kropitz):

	A	В	C	D	E	F
Δ	(1, R, B)	(1, R, C)	(1,L,D)	(1, R, E)	(1, L, A)	(1, L, H)
1	(1,L,E)	(1, R, F)	(Δ, R, B)	(Δ, L, C)	(Δ, R, D)	(1, R, C)

The above machine output at least 3.515×10^{18267} ones!

The reason why it is so hard to compute Σ and S is that they are not computable!

Theorem 8.10. The functions Σ and S are total functions that are not computable (not recursive).

Proof sketch. The proof consists in showing that Σ (and similarly for S) eventually outgrows any computable function. More specifically, we claim that for every computable function f, there is some positive integer k_f such that

$$\Sigma(n+k_f) \ge f(n)$$
 for all $n \ge 0$.

We simply have to pick k_f to be the number of states of a Turing machine M_f computing f. Then we can create a Turing machine $M_{n,f}$ that works as follows. Using n of its states, it writes n ones on the tape, and then it simulates M_f with input 1^n . Since the ouput of $M_{n,f}$ started on the blank tape consists of f(n) ones, and since $\Sigma(n + k_f)$ is the maximum number of ones that a turing machine with $n + k_f$ states will ouput when it stops, we must have

$$\Sigma(n+k_f) \ge f(n)$$
 for all $n \ge 0$.

Next observe that $\Sigma(n) < \Sigma(n+1)$, because we can create a Turing machine with n+1 states which simulates a busy beaver machine with n states, and then writes an extra 1 when the busy beaver stops, by making a transition to the (n+1)th state. It follows immediately that if m < n then $\Sigma(m) < \Sigma(n)$. If Σ was computable, then so would be the function g given by $g(n) = \Sigma(2n)$. By the above, we would have

$$\Sigma(n+k_g) \ge g(n) = \Sigma(2n)$$
 for all $n \ge 0$,

and for $n > k_g$, since $2n > n + k_g$, we would have $\Sigma(n + n_g) < \Sigma(2n)$, contradicting the fact that $\Sigma(n + n_g) \ge \Sigma(2n)$.

Since by definition S(n) is the maximum number of moves that can be made by a Turing machine of the above type with n states before it halts, $S(n) \ge \Sigma(n)$. Then the same reasoning as above shows that S is not a computable function.

The zoo of computable and non-computable functions is illustrated in Figure 8.1.



Figure 8.1: Computability Classification of Functions.

Chapter 9

Elementary Recursive Function Theory

9.1 Acceptable Indexings

In Chapter 8, we have exhibited a specific indexing of the partial computable functions by encoding the RAM programs. Using this indexing, we showed the existence of a universal function φ_{univ} and of a computable function c, with the property that for all $x, y \in \mathbb{N}$,

$$\varphi_{c(x,y)} = \varphi_x \circ \varphi_y.$$

It is natural to wonder whether the same results hold if a different coding scheme is used or if a different model of computation is used, for example, Turing machines. In other words, we would like to know if our results depend on a specific coding scheme or not.

Our previous results showing the characterization of the partial computable functions being independent of the specific model used, suggests that it might be possible to pinpoint certain properties of coding schemes which would allow an axiomatic development of recursive function theory. What we are aiming at is to find some simple properties of "nice" coding schemes that allow one to proceed without using explicit coding schemes, as long as the above properties hold.

Remarkably, such properties exist. Furthermore, any two coding schemes having these properties are equivalent in a strong sense (called effectively equivalent), and so, one can pick any such coding scheme without any risk of losing anything else because the wrong coding scheme was chosen. Such coding schemes, also called indexings, or Gödel numberings, or even programming systems, are called *acceptable indexings*.

Definition 9.1. An *indexing* of the partial computable functions is an infinite sequence $\varphi_0, \varphi_1, \ldots$, of partial computable functions that includes *all* the partial computable functions of one argument (there might be repetitions, this is why we are not using the term enumeration). An indexing is *universal* if it contains the partial computable function φ_{univ}

such that

$$\varphi_{univ}(i,x) = \varphi_i(x) \quad \text{for all } i, x \in \mathbb{N}.$$
 (*univ)

An indexing is *acceptable* if it is universal and if there is a total computable function c for composition, such that

$$\varphi_{c(i,j)} = \varphi_i \circ \varphi_j \quad \text{for all } i, j \in \mathbb{N}.$$
 (*_{compos})

An indexing may fail to be universal because it is not "computable enough," in the sense that it does not yield a function φ_{univ} satisfying ($*_{univ}$). It may also fail to be acceptable because it is not "computable enough," in the sense that it does not yield a function φ_{univ} satisfying ($*_{compos}$).

From Chapter 8, we know that the specific indexing of the partial computable functions given for RAM programs is acceptable. Another characterization of acceptable indexings left as an exercise is the following: an indexing $\psi_0, \psi_1, \psi_2, \ldots$ of the partial computable functions is acceptable iff there exists a total computable function f translating the RAM indexing of Section 8.3 into the indexing $\psi_0, \psi_1, \psi_2, \ldots$, that is,

$$\varphi_i = \psi_{f(i)} \quad \text{for all } i \in \mathbb{N}.$$

A very useful property of acceptable indexings is the so-called "s-m-n Theorem". Using the slightly loose notation $\varphi(x_1, \ldots, x_n)$ for $\varphi(\langle x_1, \ldots, x_n \rangle)$, the s-m-n Theorem says the following. Given a function φ considered as having m + n arguments, if we fix the values of the first m arguments and we let the other n arguments vary, we obtain a function ψ of narguments. Then the index of ψ depends in a computable fashion upon the index of φ and the first m arguments x_1, \ldots, x_m . We can "pull" the first m arguments of φ into the index of ψ .

Theorem 9.1. (The "s-m-n Theorem") For any acceptable indexing $\varphi_0, \varphi_1, \ldots$, there is a total computable function $s: \mathbb{N}^{n+2} \to \mathbb{N}$, such that, for all $i, m, n \ge 1$, for all x_1, \ldots, x_m and all y_1, \ldots, y_n , we have

$$\varphi_{s(i,m,x_1,\ldots,x_m)}(y_1,\ldots,y_n)=\varphi_i(x_1,\ldots,x_m,y_1,\ldots,y_n).$$

Proof. First, note that the above identity is really

$$\varphi_{s(i,m,\langle x_1,\ldots,x_m\rangle)}(\langle y_1,\ldots,y_n\rangle) = \varphi_i(\langle x_1,\ldots,x_m,y_1,\ldots,y_n\rangle).$$

Recall that there is a primitive recursive function Con such that

$$\operatorname{Con}(m, \langle x_1, \dots, x_m \rangle, \langle y_1, \dots, y_n \rangle) = \langle x_1, \dots, x_m, y_1, \dots, y_n \rangle$$

for all $x_1, \ldots, x_m, y_1, \ldots, y_n \in \mathbb{N}$. Hence, a computable function s such that

$$\varphi_{s(i,m,x)}(y) = \varphi_i(\operatorname{Con}(m,x,y))$$

will do. We define some auxiliary primitive recursive functions as follows:

$$P(y) = \langle 0, y \rangle$$
 and $Q(\langle x, y \rangle) = \langle x + 1, y \rangle$.

Since we have an indexing of the partial computable functions, there are indices p and q such that $P = \varphi_p$ and $Q = \varphi_q$. Let R be defined such that

$$R(0) = p,$$

$$R(x+1) = c(q, R(x)),$$

where c is the computable function for composition given by the indexing. We prove by induction of x that

$$\varphi_{R(x)}(y) = \langle x, y \rangle$$
 for all $x, y \in \mathbb{N}$.

For this we use the existence of the universal function φ_{univ} .

For the base case x = 0, we have

$$\varphi_{R(0)}(y) = \varphi_{univ}(\langle R(0), y \rangle)$$
$$= \varphi_{univ}(\langle p, y \rangle)$$
$$= \varphi_p(y) = P(y) = \langle 0, y \rangle$$

For the induction step, we have

$$\varphi_{R(x+1)}(y) = \varphi_{univ}(\langle R(x+1), y \rangle)$$

= $\varphi_{univ}(\langle c(q, R(x)), y \rangle)$
= $\varphi_{c(q,R(x))}(y)$
= $(\varphi_q \circ \varphi_{R(x)})(y)$
= $\varphi_q(\langle x, y \rangle) = Q(\langle x, y \rangle) = \langle x+1, y \rangle.$

Also, recall that $\langle x, y, z \rangle = \langle x, \langle y, z \rangle \rangle$, by definition of pairing. Then we have

$$\varphi_{R(x)} \circ \varphi_{R(y)}(z) = \varphi_{R(x)}(\langle y, z \rangle) = \langle x, y, z \rangle.$$

Finally, let k be an index for the function Con, that is, let

$$\varphi_k(\langle m, x, y \rangle) = \operatorname{Con}(m, x, y).$$

Define s by

$$s(i, m, x) = c(i, c(k, c(R(m), R(x)))).$$

Then we have

$$\varphi_{s(i,m,x)}(y) = \varphi_i \circ \varphi_k \circ \varphi_{R(m)} \circ \varphi_{R(x)}(y) = \varphi_i(\operatorname{Con}(m,x,y)),$$

as desired. Notice that if the composition function c is primitive recursive, then s is also primitive recursive. In particular, for the specific indexing of the RAM programs given in Section 8.3, the function s is primitive recursive.

In practice, when using the s-m-n Theorem we usually denote the function s(i, m, x) simply as s(x).

As a first application of the s-m-n Theorem, we show that any two acceptable indexings are effectively inter-translatable, that is, computably inter-translatable.

Theorem 9.2. Let $\varphi_0, \varphi_1, \ldots$, be a universal indexing, and let ψ_0, ψ_1, \ldots , be any indexing with a total computable s-1-1 function, that is, a function s such that

$$\psi_{s(i,1,x)}(y) = \psi_i(x,y)$$

for all $i, x, y \in \mathbb{N}$. Then there is a total computable function t such that $\varphi_i = \psi_{t(i)}$.

Proof. Let φ_{univ} be a universal partial computable function for the indexing $\varphi_0, \varphi_1, \ldots$. Since ψ_0, ψ_1, \ldots , is also an indexing φ_{univ} occurs somewhere in the second list, and thus, there is some k such that $\varphi_{univ} = \psi_k$. Then we have

$$\psi_{s(k,1,i)}(x) = \psi_k(i,x) = \varphi_{univ}(i,x) = \varphi_i(x),$$

for all $i, x \in \mathbb{N}$. Therefore, we can take the function t to be the function defined such that

$$t(i) = s(k, 1, i)$$

for all $i \in \mathbb{N}$.

Using Theorem 9.2, if we have two acceptable indexings $\varphi_0, \varphi_1, \ldots$, and ψ_0, ψ_1, \ldots , there exist total computable functions t and u such that

$$\varphi_i = \psi_{t(i)}$$
 and $\psi_i = \varphi_{u(i)}$

for all $i \in \mathbb{N}$.

Also note that if the composition function c is primitive recursive, then any s-m-n function is primitive recursive, and the translation functions are primitive recursive. Actually, a stronger result can be shown. It can be shown that for any two acceptable indexings, there exist total computable *injective* and *surjective* translation functions. In other words, any two acceptable indexings are recursively isomorphic (Roger's isomorphism theorem); see Machtey and Young [51]. Next we turn to algorithmically unsolvable, or *undecidable*, problems.

9.2 Undecidable Problems

We saw in Section 8.3 that the halting problem for RAM programs is undecidable. In this section, we take a slightly more general approach to study the undecidability of problems, and give some tools for resolving decidability questions.

First, we prove again the undecidability of the halting problem, but this time, for *any* indexing of the partial computable functions.

Theorem 9.3. (Halting Problem, Abstract Version) Let ψ_0, ψ_1, \ldots , be any indexing of the partial computable functions. Then the function f defined such that

$$f(x,y) = \begin{cases} 1 & \text{if } \psi_x(y) \text{ is defined,} \\ 0 & \text{if } \psi_x(y) \text{ is undefined,} \end{cases}$$

is not computable.

Proof. Assume that f is computable, and let g be the function defined such that

$$g(x) = f(x, x)$$

for all $x \in \mathbb{N}$. Then g is also computable. Let θ be the function defined such that

$$\theta(x) = \begin{cases} 0 & \text{if } g(x) = 0, \\ \text{undefined} & \text{if } g(x) = 1. \end{cases}$$

We claim that θ is not even partial computable. Observe that θ is such that

$$\theta(x) = \begin{cases} 0 & \text{if } \psi_x(x) \text{ is undefined,} \\ \text{undefined} & \text{if } \psi_x(x) \text{ is defined.} \end{cases}$$

If θ was partial computable, it would occur in the list as some ψ_i , and we would have

$$\theta(i) = \psi_i(i) = 0$$
 iff $\psi_i(i)$ is undefined,

a contradiction. Therefore, f and g can't be computable.

Observe that the proof of Theorem 9.3 *does not* use the fact that the indexing is universal or acceptable, and thus, the theorem holds for *any indexing* of the partial computable functions.

Given any set, X, for any subset, $A \subseteq X$, of X, recall that the *characteristic function*, C_A (or χ_A), of A is the function, $C_A: X \to \{0, 1\}$, defined so that, for all $x \in X$,

$$C_A(x) = \begin{cases} 1 & \text{if } x \in A, \\ 0 & \text{if } x \notin A. \end{cases}$$

The function g defined in the proof of Theorem 9.3 is the characteristic function of an important set denoted as K.

Definition 9.2. Given any indexing (ψ_i) of the partial computable functions, the set K is defined by

$$K = \{ x \mid \psi_x(x) \text{ is defined} \}.$$

The set K is an abstract version of the halting problem. It is example of a set which is *not* computable (or not recursive). Since this fact is quite important, we give the following definition:

Definition 9.3. A subset A of Σ^* (or a subset A of \mathbb{N}) is *computable*, or *recursive*,¹ or *decidable* iff its characteristic function, C_A , is a total computable function.

Using Definition 9.3, Theorem 9.3 can be restated as follows.

Proposition 9.4. For any indexing $\varphi_0, \varphi_1, \ldots$ of the partial computable functions (over Σ^* or \mathbb{N}), the set $K = \{x \mid \varphi_x(x) \text{ is defined}\}$ is not computable (not recursive).

Computable (recursive) sets allow us to define the concept of a decidable (or undecidable) problem. The idea is to generalize the situation described in Section 8.3 and Section 8.6, where a set of objects, the RAM programs, is encoded into a set of natural numbers, using a coding scheme. For example, we would like to discuss the notion of computability of sets of trees or sets of graphs.

Definition 9.4. Let C be a countable set of objects, and let P be a property of objects in C. We view P as the set

$$\{a \in C \mid P(a)\}.$$

A coding-scheme is an injective function $\#: C \to \mathbb{N}$ that assigns a unique code to each object in C. The property P is decidable (relative to #) iff the set $\{\#(a) \mid a \in C \text{ and } P(a)\}$ is computable (recursive). The property P is undecidable (relative to #) iff the set $\{\#(a) \mid a \in C \text{ and } P(a)\}$ is not computable (not recursive).

Observe that the decidability of a property P of objects in C depends upon the coding scheme #. Thus, if we are cheating in using a non-effective (*i.e* not computable by a computer program) coding scheme, we may declare that a property is decidable even though it is not decidable in some reasonable coding scheme. Consequently, we require a coding scheme # to be *effective* in the following sense. Given any object $a \in C$, we can effectively (*i.e.* algorithmically) determine its code #(a). Conversely, given any integer $n \in \mathbb{N}$, we should be able to tell effectively if n is the code of some object in C, and if so, to find this object. In practice, it is always possible to describe the objects in C as strings over some (possibly complex) alphabet Σ (sets of trees, graphs, etc). In such cases, the coding schemes are computable functions from Σ^* to $\mathbb{N} = \{a_1\}^*$.

For example, let $C = \mathbb{N} \times \mathbb{N}$, where the property P is the equality of the partial functions φ_x and φ_y . We can use the pairing function $\langle -, - \rangle$ as a coding function, and the problem is formally encoded as the computability (recursiveness) of the set

$$\{\langle x, y \rangle \mid x, y \in \mathbb{N}, \, \varphi_x = \varphi_y\}.$$

¹Since 1996, the term *recursive* has been considered old-fashioned by many researchers, and the term *computable* has been used instead.

In most cases, we don't even bother to describe the coding scheme explicitly, knowing that such a description is routine, although perhaps tedious.

We now show that most properties about programs (except the trivial ones) are undecidable.

9.3 Reducibility and Rice's Theorem

First, we show that it is undecidable whether a RAM program halts for every input. In other words, it is undecidable whether a procedure is an algorithm. We actually prove a more general fact.

Proposition 9.5. For any acceptable indexing $\varphi_0, \varphi_1, \ldots$ of the partial computable functions, the set

 $TOTAL = \{x \mid \varphi_x \text{ is a total function}\}\$

is not computable (not recursive).

Proof. The proof uses a technique known as reducibility. We try to reduce a set A known to be *noncomputable (nonrecursive)* to TOTAL via a computable function $f: A \to \text{TOTAL}$, so that

$$x \in A$$
 iff $f(x) \in \text{TOTAL}$.

If TOTAL were computable (recursive), its characteristic function g would be computable, and thus, the function $g \circ f$ would be computable, a contradiction, since A is assumed to be noncomputable (nonrecursive). In the present case, we pick A = K. To find the computable function $f: K \to \text{TOTAL}$, we use the s-m-n Theorem. Let θ be the function defined below: for all $x, y \in \mathbb{N}$,

$$\theta(x,y) = \begin{cases} \varphi_x(x) & \text{if } x \in K, \\ \text{undefined} & \text{if } x \notin K. \end{cases}$$

Note that θ does not depend on y. The function θ is partial computable. Indeed, we have

$$\theta(x,y) = \varphi_x(x) = \varphi_{univ}(x,x).$$

Thus, θ has some index j, so that $\theta = \varphi_j$, and by the s-m-n Theorem, we have

$$\varphi_{s(j,1,x)}(y) = \varphi_j(x,y) = \theta(x,y).$$

Let f be the computable function defined such that

$$f(x) = s(j, 1, x)$$

for all $x \in \mathbb{N}$. Then we have

$$\varphi_{f(x)}(y) = \begin{cases} \varphi_x(x) & \text{if } x \in K, \\ \text{undefined} & \text{if } x \notin K, \end{cases}$$

for all $y \in \mathbb{N}$. Thus, observe that $\varphi_{f(x)}$ is a total function iff $x \in K$, that is,

$$x \in K$$
 iff $f(x) \in \text{TOTAL}$,

where f is computable. As we explained earlier, this shows that TOTAL is not computable (not recursive).

The above argument can be generalized to yield a result known as Rice's theorem. Let $\varphi_0, \varphi_1, \ldots$ be any indexing of the partial computable functions, and let C be any set of partial computable functions. We define the set P_C as

$$P_C = \{ x \in \mathbb{N} \mid \varphi_x \in C \}.$$

We can view C as a property of some of the partial computable functions. For example

 $C = \{ \text{all total computable functions} \}.$

Observe that if $\varphi_i \in C$ for some partial computable function φ_i , equivalently $i \in P_C$, then $j \in P_C$ for all $j \in \mathbb{N}$ such that $\varphi_j = \varphi_i$. In other words, if P_C contains the code i of some program P_i computing a partial computable function $\varphi_i \in C$, then P_C contains the code of every program computing φ_i . Steve Cook calls such a set P_C a function index set. Note that P_C is always infinite, unless $P_C = \emptyset$.

Definition 9.5. We say that a set C of partial computable functions (over \mathbb{N}) is *nontrivial* if C is neither empty nor the set of all partial computable functions. Equivalently C is nontrivial iff $P_C \neq \emptyset$ and $P_C \neq \mathbb{N}$. We also say that C is *trivial* if $P_C = \emptyset$ or $P_C = \mathbb{N}$.

Theorem 9.6. (*Rice's Theorem, 1953*) For any acceptable indexing $\varphi_0, \varphi_1, \ldots$ of the partial computable functions, for any set C of partial computable functions, the set

$$P_C = \{ x \in \mathbb{N} \mid \varphi_x \in C \}$$

is not computable (not recursive) unless C is trivial.

Proof. Assume that C is nontrivial. A set is computable (recursive) iff its complement is computable (recursive) (the proof is trivial). Hence, we may assume that the totally undefined function is not in C, and since $C \neq \emptyset$, let ψ be some other function in C. We produce a computable function f such that

$$\varphi_{f(x)}(y) = \begin{cases} \psi(y) & \text{if } x \in K, \\ \text{undefined} & \text{if } x \notin K, \end{cases}$$

for all $y \in \mathbb{N}$. We get f by using the s-m-n Theorem. Let $\psi = \varphi_i$, and define θ as follows:

$$\theta(x,y) = \varphi_{univ}(i,y) + (\varphi_{univ}(x,x) \div \varphi_{univ}(x,x)),$$

where $\dot{-}$ is the primitive recursive function monus for truncated subtraction; see Section 4.7. Recall that $\varphi_{univ}(x, x) \dot{-} \varphi_{univ}(x, x)$ is defined iff $\varphi_{univ}(x, x)$ is defined iff $x \in K$, and so

$$\theta(x,y) = \varphi_{univ}(i,y) = \varphi_i(y) = \psi(y) \quad \text{iff} \quad x \in K$$

and $\theta(x, y)$ is undefined otherwise. Clearly θ is partial computable, and we let $\theta = \varphi_j$. By the s-m-n Theorem, we have

$$\varphi_{s(j,1,x)}(y) = \varphi_j(x,y) = \theta(x,y)$$

for all $x, y \in \mathbb{N}$. Letting f be the computable function such that

$$f(x) = s(j, 1, x),$$

by definition of θ , we get

$$\varphi_{f(x)}(y) = \theta(x, y) = \begin{cases} \psi(y) & \text{if } x \in K, \\ \text{undefined} & \text{if } x \notin K. \end{cases}$$

Thus, f is the desired reduction function. Now we have

$$x \in K$$
 iff $f(x) \in P_C$,

and thus, the characteristic function C_K of K is equal to $C_P \circ f$, where C_P is the characteristic function of P_C . Therefore, P_C is not computable (not recursive), since otherwise, K would be computable, a contradiction.

Rice's theorem shows that all nontrivial properties of the input/output behavior of programs are undecidable!

It is important to understand that Rice's theorem says that the set P_C of indices of all partial computable functions equal to some function in a given set C of partial computable functions is not computable if C is nontrivial, not that the set C is not computable if Cis nontrivial. The second statement does not make any sense because our machinery only applies to sets of natural numbers (or sets of strings). For example, the set $C = \{\varphi_{i_0}\}$ consisting of a single partial computable function is nontrivial, and being finite, under the second wrong interpretation it would be computable. But we need to consider the set

$$P_C = \{ n \in \mathbb{N} \mid \varphi_n = \varphi_{i_0} \}$$

of indices of all partial computable functions φ_n that are equal to φ_{i_0} , and by Rice's theorem, this set is not computable. In other words, it is undecidable whether an arbitrary partial computable function is equal to some fixed partial computable function.

The scenario to apply Rice's theorem to a class C of partial functions is to show that some partial computable function belongs to C (C is not empty), and that some partial computable function does not belong to C (C is not all the partial computable functions). This demonstrates that C is nontrivial.

In particular, the following properties are undecidable.

Proposition 9.7. The following properties of partial computable functions are undecidable.

- (a) A partial computable function is a constant function.
- (b) Given any integer $y \in \mathbb{N}$, is y in the range of some partial computable function.
- (c) Two partial computable functions φ_x and φ_y are identical. More precisely, the set $\{\langle x, y \rangle \mid \varphi_x = \varphi_y\}$ is not computable.
- (d) A partial computable function φ_x is equal to a given partial computable function φ_a .
- (e) A partial computable function yields output z on input y, for any given $y, z \in \mathbb{N}$.
- (f) A partial computable function diverges for some input.
- (g) A partial computable function diverges for all input.

The above proposition is left as an easy exercise. For example, in (a), we need to exhibit a constant (partial) computable function, such as zero(n) = 0, and a nonconstant (partial) computable function, such as the identity function (or succ(n) = n + 1).

A property may be undecidable although it is partially decidable. By partially decidable, we mean that there exists a computable function g that enumerates the set $P_C = \{x \mid \varphi_x \in C\}$. This means that there is a computable function g whose range is P_C . We say that P_C is *listable*, or *computably enumerable*, or *recursively enumerable*. Indeed, g provides a recursive enumeration of P_C , with possible repetitions. Listable sets are the object of the next section.

9.4 Listable (Recursively Enumerable) Sets

In this section and the next our focus is on subsets of \mathbb{N} rather than on numerical functions. Consider the set

 $A = \{k \in \mathbb{N} \mid \varphi_k(a) \text{ is defined}\},\$

where $a \in \mathbb{N}$ is any fixed natural number. By Rice's theorem, A is not computable (not recursive); check this. We claim that A is the range of a computable function g. For this, we use the T-predicate introduced in Definition 8.15. Recall that the predicate T(i, y, z) is defined as follows:

T(i, y, z) holds iff i codes a RAM program, y is an input, and z codes a halting computation of program P_i on input y.

We produce a function which is actually primitive recursive. First, note that A is nonempty (why?), and let x_0 be any index in A. We define g by primitive recursion as follows:

$$g(0) = x_0,$$

$$g(x+1) = \begin{cases} \Pi_1(x) & \text{if } T(\Pi_1(x), a, \Pi_2(x)), \\ x_0 & \text{otherwise.} \end{cases}$$

Since this type of argument is new, it is helpful to explain informally what g does. For every input x, the function g tries finitely many steps of a computation on input a for some partial computable function φ_i computed by the RAM program P_i . Since we need to consider all pairs (i, z) but we only have one variable x at our disposal, we use the trick of packing iand z into $x = \langle i, z \rangle$. Then the index i of the partial function is given by $i = \Pi_1(x)$ and the guess for the code of the computation is given by $z = \Pi_2(x)$. Since Π_1 and Π_2 are projection functions, when x ranges over \mathbb{N} , both $i = \Pi_1(x)$ and $z = \Pi_2(x)$ also range over \mathbb{N} . Thus every partial function φ_i and every code for a computation z will be tried, and whenever $\varphi_i(a)$ is defined, which means that there is a correct guess for the code z of the halting computation of P_i on input a, $T(\Pi_1(x), a, \Pi_2(x)) = T(i, a, z)$ is true, and g(x + 1) returns i.

Such a process is called a *dovetailing* computation. This type of argument will be used over and over again.

Definition 9.6. A subset X of \mathbb{N} is *listable*, or *computably enumerable*, or *recursively enumerable*² iff either $X = \emptyset$, or X is the range of some total computable function (total recursive function). Similarly, a subset X of Σ^* is *listable* or *computably enumerable*, or *recursively enumerable* iff either $X = \emptyset$, or X is the range of some total computable function (total recursive function).

We will often abbreviate computably enumerable as c.e, (and recursively enumerable as r.e.). A computably enumerable set is sometimes called a *partially decidable* or *semidecidable* set.

Remark: It should be noted that the definition of a *listable set* (*c.e set* or *r.e. set*) given in Definition 9.6 is *different* from an earlier definition given in terms of acceptance by a Turing machine and it is by no means obvious that these two definitions are equivalent. This equivalence will be proven in Proposition 9.9 ((1) \iff (4)).

The following proposition relates computable sets and listable sets (recursive sets and recursively enumerable sets).

Proposition 9.8. A set A is computable (recursive) iff both A and its complement A are listable (computably enumerable, recursively enumerable).

Proof. Assume that A is computable. Then it is trivial that its complement is also computable. Hence, we only have to show that a computable set is listable. The empty set is listable by definition. Otherwise, let $y \in A$ be any element. Then the function f defined such that

$$f(x) = \begin{cases} x & \text{iff } C_A(x) = 1, \\ y & \text{iff } C_A(x) = 0, \end{cases}$$

for all $x \in \mathbb{N}$ is computable and has range A.

²Since 1996, the term *recursively enumerable* has been considered old-fashioned by many researchers, and the terms *listable* and *computably enumerable* have been used instead.

Conversely, assume that both A and \overline{A} are listable. If either A or \overline{A} is empty, then A is computable. Otherwise, let $A = f(\mathbb{N})$ and $\overline{A} = g(\mathbb{N})$, for some computable functions f and g. We define the function C_A as follows:

$$C_A(x) = \begin{cases} 1 & \text{if } f(\min y[f(y) = x \lor g(y) = x]) = x, \\ 0 & \text{otherwise.} \end{cases}$$

The function C_A lists A and \overline{A} in parallel, waiting to see whether x turns up in A or in \overline{A} . Note that x must eventually turn up either in A or in \overline{A} , so that C_A is a total computable function.

Our next goal is to show that the listable (recursively enumerable) sets can be given several equivalent definitions.

Proposition 9.9. For any subset A of \mathbb{N} , the following properties are equivalent:

- (1) A is empty or A is the range of a primitive recursive function (Rosser, 1936).
- (2) A is listable (computably enumerable, recursively enumerable).
- (3) A is the range of a partial computable function.
- (4) A is the domain of a partial computable function.

Proof. The implication $(1) \Rightarrow (2)$ is trivial, since A is listable iff either it is empty or it is the range of a (total) computable function.

To prove the implication $(2) \Rightarrow (3)$, it suffices to observe that the empty set is the range of the totally undefined function (computed by an infinite loop program), and that a computable function is a partial computable function.

The implication $(3) \Rightarrow (4)$ is shown as follows. Assume that A is the range of φ_i . Define the function f such that

$$f(x) = \min k[T(i, \Pi_1(k), \Pi_2(k)) \land \operatorname{Res}(\Pi_2(k)) = x]$$

for all $x \in \mathbb{N}$. Since $A = \varphi_i(\mathbb{N})$, we have $x \in A$ iff there is some input $y \in \mathbb{N}$ and some computation coded by z such that the RAM program P_i on input y has a halting computation coded by z and produces the output x. Using the T-predicate, this is equivalent to T(i, y, z)and $\operatorname{Res}(z) = x$. Since we need to search over all pairs (y, z), we pack y and z as $k = \langle y, z \rangle$ so that $y = \Pi_1(k)$ and $z = \Pi_2(k)$, and we search over all $k \in \mathbb{N}$. If the search succeeds, which means that T(i, y, z) and $\operatorname{Res}(z) = x$, we set $f(x) = k = \langle y, z \rangle$, so that f is a function whose domain in the range of φ_i (namely A). Note that the value f(x) is irrelevant, but it is convenient to pick k. Clearly, f is partial computable and has domain A.

The implication (4) \Rightarrow (1) is shown as follows. The only nontrivial case is when A is nonempty. Assume that A is the domain of φ_i . Since $A \neq \emptyset$, there is some $a \in \mathbb{N}$ such that

 $a \in A$, which means that for some input y the RAM program P_i has a halting computation coded by z on input a, so if we pack y and z as $k = \langle y, z \rangle$, the quantity

$$\min k[T(i, \Pi_1(k), \Pi_2(k))] = \min \langle y, z \rangle [T(i, y, z)]$$

is defined. We can pick a to be

$$a = \Pi_1(\min k[T(i, \Pi_1(k), \Pi_2(k))]).$$

We define the primitive recursive function f as follows:

$$f(0) = a,$$

$$f(x+1) = \begin{cases} \Pi_1(x) & \text{if } T(i, \Pi_1(x), \Pi_2(x)), \\ a & \text{if } \neg T(i, \Pi_1(x), \Pi_2(x)). \end{cases}$$

Some $y \in \mathbb{N}$ is in the domain of φ_i (namely A) iff the RAM program P_i has a halting computation coded by z on input y iff T(i, y, z) is true. If we pack y and z as $x = \langle y, z \rangle$, then $T(i, y, z) = T(i, \Pi_1(x), \Pi_2(x))$, so if we search over all $x = \langle y, z \rangle$ we search over all y and all z. Whenever $T(i, y, z) = T(i, \Pi_1(x), \Pi_2(x))$ holds, we set f(x + 1) = y since $y \in A$, and if $T(i, y, z) = T(i, \Pi_1(x), \Pi_2(x))$ is false, we return the default value $a \in A$. Our search will find all y such that $T(i, y, z) = T(i, \Pi_1(x), \Pi_2(x))$ holds for some z, which means that all $y \in A$ will be in the range of f. By construction, f only has values in A. Clearly, f is primitive recursive.

More intuitive proofs of the implications $(3) \Rightarrow (4)$ and $(4) \Rightarrow (1)$ can be given. Assume that $A \neq \emptyset$ and that A = range(g), where g is a partial computable function. Assume that g is computed by a RAM program P. To compute f(x), we start computing the sequence

$$g(0), g(1), \ldots$$

looking for x. If x turns up as say g(n), then we output n. Otherwise the computation diverges. Hence, the domain of f is the range of g.

Assume now that A is the domain of some partial computable function g, and that g is computed by some Turing machine M. Since the case where $A = \emptyset$ is trivial, we may assume that $A \neq \emptyset$, and let $n_0 \in A$ be some chosen element in A. We construct another Turing machine performing the following steps: On input n,

(0) Do one step of the computation of g(0)

. . .

. . .

(n) Do n + 1 steps of the computation of g(0)Do n steps of the computation of g(1)

Do 2 steps of the computation of g(n-1)

Do 1 step of the computation of g(n)

During this process, whenever the computation of g(m) halts for some $m \leq n$, we output m. Otherwise, we output n_0 .

In this fashion, we will enumerate the domain of g, and since we have constructed a Turing machine that halts for every input, we have a total computable function.

The following proposition can easily be shown using the proof technique of Proposition 9.9.

Proposition 9.10. The following facts hold.

(1) There is a computable function h such that

$$range(\varphi_x) = dom(\varphi_{h(x)}) \text{ for all } x \in \mathbb{N}.$$

(2) There is a computable function k such that

$$dom(\varphi_x) = range(\varphi_{k(x)})$$

and $\varphi_{k(x)}$ is total computable, for all $x \in \mathbb{N}$ such that $dom(\varphi_x) \neq \emptyset$.

The proof of Proposition 9.10 is left as an exercise.

Using Proposition 9.9, we can prove that K is a listable set. Indeed, we have K = dom(f), where

$$f(x) = \varphi_{univ}(x, x)$$
 for all $x \in \mathbb{N}$.

The set

$$K_0 = \{ \langle x, y \rangle \mid \varphi_x(y) \text{ is defined} \}$$

is also a listable set, since $K_0 = dom(g)$, where

$$g(z) = \varphi_{univ}(\Pi_1(z), \Pi_2(z)),$$

which is partial computable. It worth recording these facts in the following proposition.

Proposition 9.11. The sets K and K_0 are listable (c.e., r.e.) sets that are not computable sets (not recursive).

We can now prove that there are sets that are not listable (not c.e., not r.e.).

Proposition 9.12. For any indexing of the partial computable functions, the complement \overline{K} of the set

$$K = \{ x \in \mathbb{N} \mid \varphi_x(x) \text{ is defined} \}$$

is not listable (not computably enumerable, not recursively enumerable).

Proof. If \overline{K} was listable, since K is also listable, by Proposition 9.8, the set K would be computable, a contradiction.

The sets \overline{K} and $\overline{K_0}$ are examples of sets that are not listable (not c.e., not r.e.). This shows that the listable (c.e., r.e.) sets are not closed under complementation. However, we leave it as an exercise to prove that the listable (c.e., r.e.) sets are closed under union and intersection.

We will prove later on that TOTAL is not listable (not c.e., not r.e.). This is rather unpleasant. Indeed, this means that there is no way of effectively listing all algorithms (all total computable functions). Hence, in a certain sense, the concept of partial computable function (procedure) is more natural than the concept of a (total) computable function (algorithm).

The next two propositions give other characterizations of the listable (c.e., r.e. sets) and of the computable sets (recursive sets). The proofs are left as an exercise.

Proposition 9.13. The following facts hold.

- (1) A set A is listable (c.e., r.e.) iff either it is finite or it is the range of an injective computable function.
- (2) A set A is listable (c.e., r.e.) if either it is empty or it is the range of a monotonic partial computable function.
- (3) A set A is listable (c.e., r.e.) iff there is a Turing machine M such that, for all $x \in \mathbb{N}$, M halts on x iff $x \in A$.

Proposition 9.14. A set A is computable (recursive) iff either it is finite or it is the range of a strictly increasing computable function.

Another important result relating the concept of partial computable function and that of a listable (c.e., r.e.) set is given below.

Theorem 9.15. For every unary partial function f, the following properties are equivalent:

- (1) f is partial computable.
- (2) The set

$$\{\langle x, f(x) \rangle \mid x \in dom(f)\}$$

is listable (c.e., r.e.).

Proof. Let $g(x) = \langle x, f(x) \rangle$. Clearly, g is partial computable, and

$$range(g) = \{ \langle x, f(x) \rangle \mid x \in dom(f) \}.$$

Conversely, assume that

 $range(g) = \{ \langle x, f(x) \rangle \mid x \in dom(f) \}$

for some computable function g. Then we have

$$f(x) = \Pi_2(g(\min y[\Pi_1(g(y)) = x)])) \quad \text{for all } x \in \mathbb{N},$$

so that f is partial computable.

Using our indexing of the partial computable functions and Proposition 9.9, we obtain an indexing of the listable (c.e., r.e.) sets.

Definition 9.7. For any acceptable indexing $\varphi_0, \varphi_1, \ldots$ of the partial computable functions, we define the enumeration W_0, W_1, \ldots of the listable (c.e., r.e.) sets by setting

$$W_x = dom(\varphi_x).$$

We now describe a technique for showing that certain sets are listable (c.e., r.e.) but not computable (not recursive), or complements of listable (c.e., r.e.) sets that are not computable (not recursive), or not listable (not c.e., not r.e.), or neither listable (not c.e., not r.e.) nor the complement of a listable (c.e., r.e.) set. This technique is known as *reducibility*.

9.5 Reducibility and Complete Sets

We already used the notion of reducibility in the proof of Proposition 9.5 to show that TOTAL is not computable (not recursive).

Definition 9.8. Let A and B be subsets of \mathbb{N} (or Σ^*). We say that the set A is many-one reducible to the set B if there is a total computable function (or total recursive function) $f: \mathbb{N} \to \mathbb{N}$ (or $f: \Sigma^* \to \Sigma^*$) such that

```
x \in A iff f(x) \in B for all x \in \mathbb{N}.
```

We write $A \leq B$, and for short, we say that A is *reducible* to B. Sometimes, the notation $A \leq_m B$ is used to stress that this is a many-to-one reduction (that is, f is not necessarily injective).

Intuitively, deciding membership in B is as hard as deciding membership in A. This is because any method for deciding membership in B can be converted to a method for deciding membership in A by first applying f to the number (or string) to be tested.

Remark: Besides many-to-one reducibility, there is a also a notion of *one-one reducibility* defined as follows: the set A is *one-one reducible* to the set B if there is a *total* **injective** *computable* function $f: \mathbb{N} \to \mathbb{N}$ such that

 $x \in A$ iff $f(x) \in B$ for all $x \in \mathbb{N}$.

We write $A \leq_1 B$. Obviously $A \leq_1 B$ implies $A \leq_m B$ so one-one reducibility is a stronger notion. We do not need one-one reducibility for our purposes so we will not discuss it. We refer the interested reader to Rogers [64] (especially Chapter 7) for more on reducibility.

The following simple proposition is left as an exercise to the reader.

Proposition 9.16. Let A, B, C be subsets of \mathbb{N} (or Σ^*). The following properties hold:

- (1) If $A \leq B$ and $B \leq C$, then $A \leq C$.
- (2) If $A \leq B$ then $\overline{A} \leq \overline{B}$.
- (3) If $A \leq B$ and B is listable (c.e., r.e.), then A is listable (c.e., r.e.).
- (4) If $A \leq B$ and A is not listable (not c.e., not r.e.), then B is not listable (not c.e., not r.e.).
- (5) If $A \leq B$ and B is computable, then A is computable.
- (6) If $A \leq B$ and A is not computable, then B is not computable.

Part (4) of Proposition 9.16 is often useful for proving that some set B is not listable. It suffices to reduce some set known to be nonlistable to B, for example \overline{K} . Similarly, Part (6) of Proposition 9.16 is often useful for proving that some set B is not computable. It suffices to reduce some set known to be noncomputable to B, for example K.

Observe that $A \leq B$ implies that $\overline{A} \leq \overline{B}$, but not that $\overline{B} \leq \overline{A}$.

Part (3) of Proposition 9.16 may be useful for proving that some set A is listable. It suffices to reduce A to some set known to be listable, for example K. Similarly, Part (5) of Proposition 9.16 may be useful for proving that some set A is computable. It suffices to reduce A to some set known to be computable. In practice, it is often easier to prove directly that A is computable by showing that both A and \overline{A} are listable.

Another important concept is the concept of a complete set.

Definition 9.9. A listable (c.e., r.e.) set A is complete w.r.t. many-one reducibility iff every listable (c.e., r.e.) set B is reducible to A, *i.e.*, $B \leq A$.

For simplicity, we will often say *complete* for *complete w.r.t. many-one reducibility*. Intuitively, a complete listable (c.e., r.e.) set is a "hardest" listable (c.e., r.e.) set as far as membership is concerned.

Theorem 9.17. The following properties hold:

- (1) If A is complete, B is listable (c.e, r.e.), and $A \leq B$, then B is complete.
- (2) K_0 is complete.

(3) K_0 is reducible to K. Consequently, K is also complete.

Proof. (1) This is left as a simple exercise.

(2) Let W_x be any listable set (recall Definition 9.7). Then

$$y \in W_x$$
 iff $\langle x, y \rangle \in K_0$,

and the reduction function is the computable function f such that

$$f(y) = \langle x, y \rangle$$
 for all $y \in \mathbb{N}$.

(3) We use the s-m-n Theorem. First, we leave it as an exercise to prove that there is a computable function f such that

$$\varphi_{f(x)}(y) = \begin{cases} 1 & \text{if } \varphi_{\Pi_1(x)}(\Pi_2(x)) \text{ is defined,} \\ \text{undefined} & \text{otherwise,} \end{cases}$$

for all $x, y \in \mathbb{N}$. Then for every $z \in \mathbb{N}$,

 $z \in K_0$ iff $\varphi_{\Pi_1(z)}(\Pi_2(z))$ is defined,

iff $\varphi_{f(z)}(y) = 1$ for all $y \in \mathbb{N}$. However,

$$\varphi_{f(z)}(y) = 1$$
 iff $\varphi_{f(z)}(f(z)) = 1$,

since $\varphi_{f(z)}$ is a constant function. This means that

$$z \in K_0$$
 iff $f(z) \in K$,

and f is the desired function.

As a corollary of Theorem 9.17, the set K is also complete.

Definition 9.10. Two sets A and B have the same degree of unsolvability or are equivalent iff $A \leq B$ and $B \leq A$.

Since K and K_0 are both complete, they have the same degree of unsolvability in the set of listable sets.

We will now investigate the reducibility and equivalence of various sets.

Recall that

 $TOTAL = \{ x \in \mathbb{N} \mid \varphi_x \text{ is total} \}.$

We define EMPTY and FINITE, as follows:

 $EMPTY = \{ x \in \mathbb{N} \mid \varphi_x \text{ is undefined for all input} \}, \\ FINITE = \{ x \in \mathbb{N} \mid \varphi_x \text{ is defined only for finitely many input} \}.$

Obviously, $EMPTY \subset FINITE$, and since

FINITE = { $x \in \mathbb{N} \mid \varphi_x$ has a finite domain},

we have

 $\overline{\text{FINITE}} = \{ x \in \mathbb{N} \mid \varphi_x \text{ has an infinite domain} \},\$

and thus, $TOTAL \subset \overline{FINITE}$. Since

 $EMPTY = \{x \in \mathbb{N} \mid \varphi_x \text{ is undefined for all input}\}\$

we have

 $\overline{\text{EMPTY}} = \{ x \in \mathbb{N} \mid \varphi_x \text{ is defined for some input} \},\$

we have $\overline{\text{FINITE}} \subseteq \overline{\text{EMPTY}}$.

Proposition 9.18. We have $K_0 \leq \overline{\text{EMPTY}}$.

The proof of Proposition 9.18 follows from the proof of Theorem 9.17. We also have the following proposition.

Proposition 9.19. The following properties hold:

- (1) EMPTY is not listable (not c.e., not r.e.).
- (2) $\overline{\text{EMPTY}}$ is listable (c.e., r.e.).
- (3) \overline{K} and EMPTY are equivalent.
- (4) $\overline{\text{EMPTY}}$ is complete.

Proof. We prove (1) and (3), leaving (2) and (4) as an exercise (Actually, (2) and (4) follow easily from (3)). First, we show that $\overline{K} \leq \text{EMPTY}$. By the s-m-n Theorem, there exists a computable function f such that

$$\varphi_{f(x)}(y) = \begin{cases} \varphi_x(x) & \text{if } \varphi_x(x) \text{ is defined,} \\ \text{undefined} & \text{if } \varphi_x(x) \text{ is undefined,} \end{cases}$$

for all $x, y \in \mathbb{N}$. Note that for all $x \in \mathbb{N}$,

$$x \in \overline{K}$$
 iff $f(x) \in \text{EMPTY}$,

and thus, $\overline{K} \leq \text{EMPTY}$. Since \overline{K} is not listable, EMPTY is not listable.

We now prove (3). By the s-m-n Theorem, there is a computable function g such that

$$\varphi_{g(x)}(y) = \min z[T(x, \Pi_1(z), \Pi_2(z))], \text{ for all } x, y \in \mathbb{N}.$$

Note that

 $x \in \text{EMPTY}$ iff $g(x) \in \overline{K}$ for all $x \in \mathbb{N}$.

Therefore, EMPTY $\leq \overline{K}$, and since we just showed that $\overline{K} \leq$ EMPTY, the sets \overline{K} and EMPTY are equivalent.

Proposition 9.20. The following properties hold:

- (1) TOTAL and $\overline{\text{TOTAL}}$ are not listable (not c.e., not r.e.).
- (2) FINITE and $\overline{\text{FINITE}}$ are not listable (not c.e, not r.e.).

Proof. Checking the proof of Theorem 9.17, we note that $K_0 \leq \text{TOTAL}$ and $K_0 \leq \overline{\text{FINITE}}$. Hence, we get $\overline{K_0} \leq \overline{\text{TOTAL}}$ and $\overline{K_0} \leq \overline{\text{FINITE}}$, and neither $\overline{\text{TOTAL}}$ nor $\overline{\text{FINITE}}$ is listable. If TOTAL was listable, then there would be a computable function f such that TOTAL = range(f). Define g as follows:

$$g(x) = \varphi_{f(x)}(x) + 1 = \varphi_{univ}(f(x), x) + 1$$

for all $x \in \mathbb{N}$. Since f is total and $\varphi_{f(x)}$ is total for all $x \in \mathbb{N}$, the function g is total computable. Let e be an index such that

$$g = \varphi_{f(e)}.$$

Since g is total, g(e) is defined. Then we have

$$g(e) = \varphi_{f(e)}(e) + 1 = g(e) + 1$$

a contradiction. Hence, TOTAL is not listable. Finally, we show that TOTAL \leq FINITE. This also shows that $\overline{\text{FINITE}}$ is not listable. By the s-m-n Theorem, there is a computable function f such that

$$\varphi_{f(x)}(y) = \begin{cases} 1 & \text{if } \forall z \le y(\varphi_x(z) \downarrow), \\ \text{undefined} & \text{otherwise,} \end{cases}$$

for all $x, y \in \mathbb{N}$. It is easily seen that

$$x \in \text{TOTAL}$$
 iff $f(x) \in \overline{\text{FINITE}}$ for all $x \in \mathbb{N}$.

From Proposition 9.20, we have TOTAL \leq FINITE. It turns out that FINITE \leq TOTAL, and TOTAL and FINITE are equivalent.

Proposition 9.21. The sets TOTAL and FINITE are equivalent.

Proof. We show that $\overline{\text{FINITE}} \leq \text{TOTAL}$. By the s-m-n Theorem, there is a computable function f such that

$$\varphi_{f(x)}(y) = \begin{cases} 1 & \text{if } \exists z \ge y(\varphi_x(z) \downarrow), \\ \text{undefined} & \text{if } \forall z \ge y(\varphi_x(z) \uparrow), \end{cases}$$

for all $x, y \in \mathbb{N}$. It is easily seen that

$$x \in \overline{\text{FINITE}}$$
 iff $f(x) \in \text{TOTAL}$ for all $x \in \mathbb{N}$.

More advanced topics such that the recursion theorem, the extended Rice Theorem, and creative and productive sets will be discussed in Chapter 10.

Chapter 10

Recursion Theory; More Advanced Topics

This chapter is devoted to three advanced topics of recursion theory:

- (1) The recursion theorem.
- (2) The extended Rice theorem.
- (3) Creative and productive sets and their use in proving a strong version of Gödel's first incompleteness theorem.

The recursion theorem is a deep result and an important technical tool in recursion theory.

The extended Rice theorem gives a characterization of the sets of partial computable functions that are listable in terms of extensions of partial computable functions with finite domains.

Productive and creative sets arise when dealing with truth and provability in arithmetic. The "royal road" to Gödel's first incompleteness theorem is to first prove that for any proof system for arithmetic that only proves true statements (and is rich enough), the set of true sentences of arithmetic is productive. Productive sets are *not* listable in a strong sense, so we deduce that it is impossible to axiomatize the set of true sentences of arithmetic in a computable manner. The set of provable sentences of arithmetic is creative, which implies that it is impossible to decide whether a sentence of arithmetic is provable. This also implies that there are true sentences F such that neither F nor $\neg F$ are provable.

10.1 The Recursion Theorem

The recursion theorem, due to Kleene, is a fundamental result in recursion theory. Let f be a total computable function. Then it turns out that there is some n such that

$$\varphi_n = \varphi_{f(n)}.$$

To understand why such a mysterious result is interesting, consider the recursive definition of the factorial function fact(n) = n! given by

$$fact(0) = 1$$
$$fact(n+1) = (n+1)fact(n)$$

The trick is to define the partial computable computable function g (defined on \mathbb{N}^2) given by

$$g(m, 0) = 1$$

$$g(m, n+1) = (n+1)\varphi_m(n)$$

for all $m, n \in \mathbb{N}$. By the s-m-n Theorem, there is a computable function f such that

$$g(m,n) = \varphi_{f(m)}(n) \quad \text{for all } m, n \in \mathbb{N}.$$

Then the equations above become

$$\varphi_{f(m)}(0) = 1$$

$$\varphi_{f(m)}(n+1) = (n+1)\varphi_m(n)$$

Since f is (total) recursive, there is some m_0 such that $\varphi_{m_0} = \varphi_{f(m_0)}$, and for m_0 we get

$$\varphi_{m_0}(0) = 1$$

$$\varphi_{m_0}(n+1) = (n+1)\varphi_{m_0}(n)$$

so the partial recursive function φ_{m_0} satisfies the recursive definition of factorial, which means that it is a fixed point of the recursive equations defining factorial. Since factorial is a total function, $\varphi_{m_0} = fact$, that is, factorial is a total computable function.

More generally, if a function h (over $\mathbb{N}^k)$ is defined in terms of recursive equations of the form

$$h(z_1,\ldots,z_k)=t(h(y_1,\ldots,y_k))$$

where $y_1, \ldots, y_k, z_1, \ldots, z_k$ are expressions in some variables x_1, \ldots, x_k ranging over \mathbb{N} and where t is an expression containing recursive occurrences of h, if we can show that the equations

$$g(m, z_1, \ldots, z_k) = t(\varphi_m(y_1, \ldots, y_k))$$

define a partial computable function g, then we can use the above trick to put them in the form

$$\varphi_{f(m)}(z_1,\ldots,z_k)=t(\varphi_m(y_1,\ldots,y_k)).$$

for some computable function f. Such a formalism is described in detail in Chapter XI of Kleene I.M [42]. By the recursion theorem, there is some m_0 such that $\varphi_{m_0} = \varphi_{f(m_0)}$, so φ_{m_0} satisfies the recursive equations

$$\varphi_{m_0}(z_1,\ldots,z_k)=t(\varphi_{m_0}(y_1,\ldots,y_k)),$$

and φ_{m_0} is a fixed point of these recursive equations. If we can show that φ_{m_0} is total, then we found *the* fixed point of this set of recursive equations and $h = \varphi_{m_0}$ is a total computable function. If φ_{m_0} is a partial function, it is still a fixed point. However in general there is more than one fixed point and we don't which one φ_{m_0} is (it could be the partial function undefined everywhere).

Theorem 10.1. (Recursion Theorem, Version 1) Let $\varphi_0, \varphi_1, \ldots$ be any acceptable indexing of the partial computable functions. For every total computable function f, there is some n such that

$$\varphi_n = \varphi_{f(n)}.$$

Proof. Consider the function θ defined such that

$$\theta(x,y) = \varphi_{univ}(\varphi_{univ}(x,x),y) \text{ for all } x, y \in \mathbb{N}.$$

The function θ is partial computable, and there is some index j such that $\varphi_j = \theta$. By the s-m-n Theorem, there is a computable function g such that

$$\varphi_{q(x)}(y) = \theta(x, y)$$

Consider the function $f \circ g$. Since it is computable, there is some index m such that $\varphi_m = f \circ g$. Let

$$n = g(m).$$

Since φ_m is total, $\varphi_m(m)$ is defined, and we have

$$\varphi_n(y) = \varphi_{g(m)}(y) = \theta(m, y) = \varphi_{univ}(\varphi_{univ}(m, m), y) = \varphi_{\varphi_{univ}(m, m)}(y)$$
$$= \varphi_{\varphi_m(m)}(y) = \varphi_{f \circ g(m)}(y) = \varphi_{f(g(m))}(y) = \varphi_{f(n)}(y),$$

for all $y \in \mathbb{N}$. Therefore, $\varphi_n = \varphi_{f(n)}$, as desired.

The recursion theorem can be strengthened as follows.

Theorem 10.2. (Recursion Theorem, Version 2) Let $\varphi_0, \varphi_1, \ldots$ be any acceptable indexing of the partial computable functions. There is a total computable function h such that for all $x \in \mathbb{N}$, if φ_x is total, then

$$\varphi_{\varphi_x(h(x))} = \varphi_{h(x)}.$$

Proof. The computable function g obtained in the proof of Theorem 10.1 satisfies the condition

$$\varphi_{g(x)} = \varphi_{\varphi_x(x)},$$

and it has some index i such that $\varphi_i = g$. Recall that c is a computable composition function such that

$$\varphi_{c(x,y)} = \varphi_x \circ \varphi_y$$

It is easily verified that the function h defined such that

$$h(x) = g(c(x, i)) \text{ for all } x \in \mathbb{N}$$

does the job.

A third version of the recursion Theorem is given below.

Theorem 10.3. (Recursion Theorem, Version 3) For all $n \ge 1$, there is a total computable function h of n + 1 arguments, such that for all $x \in \mathbb{N}$, if φ_x is a total computable function of n + 1 arguments, then

$$\varphi_{\varphi_x(h(x,x_1,\ldots,x_n),x_1,\ldots,x_n)} = \varphi_{h(x,x_1,\ldots,x_n)},$$

for all $x_1, \ldots, x_n \in \mathbb{N}$.

Proof. Let θ be the function defined such that

$$\theta(x, x_1, \dots, x_n, y) = \varphi_{\varphi_x(x, x_1, \dots, x_n)}(y) = \varphi_{univ}(\varphi_{univ}(x, x, x_1, \dots, x_n), y)$$

for all $x, x_1, \ldots, x_n, y \in \mathbb{N}$. By the s-m-n Theorem, there is a computable function g such that

$$\varphi_{g(x,x_1,\dots,x_n)} = \varphi_{\varphi_x(x,x_1,\dots,x_n)}.$$

It is easily shown that there is a computable function c such that

$$\varphi_{c(i,j)}(x, x_1, \dots, x_n) = \varphi_i(\varphi_j(x, x_1, \dots, x_n), x_1, \dots, x_n)$$

for any two partial computable functions φ_i and φ_j (viewed as functions of n+1 arguments) and all $x, x_1, \ldots, x_n \in \mathbb{N}$. Let $\varphi_i = g$, and define h such that

$$h(x, x_1, \ldots, x_n) = g(c(x, i), x_1, \ldots, x_n),$$

for all $x, x_1, \ldots, x_n \in \mathbb{N}$. We have

$$\varphi_{h(x,x_1,\ldots,x_n)} = \varphi_{g(c(x,i),x_1,\ldots,x_n)} = \varphi_{\varphi_{c(x,i)}(c(x,i),x_1,\ldots,x_n)}$$

and using the fact that $\varphi_i = g$,

$$\begin{aligned} \varphi_{\varphi_{c(x,i)}(c(x,i),x_{1},\ldots,x_{n})} &= \varphi_{\varphi_{x}(\varphi_{i}(c(x,i),x_{1},\ldots,x_{n}),x_{1},\ldots,x_{n}),} \\ &= \varphi_{\varphi_{x}(g(c(x,i),x_{1},\ldots,x_{n}),x_{1},\ldots,x_{n}),} \\ &= \varphi_{\varphi_{x}(h(x,x_{1},\ldots,x_{n}),x_{1},\ldots,x_{n})}. \end{aligned}$$

As a first application of the recursion theorem, we can show that there is an index n such that φ_n is the constant function with output n. Loosely speaking, φ_n prints its own name. Let f be the computable function such that

$$f(x,y) = x$$

for all $x, y \in \mathbb{N}$. By the s-m-n Theorem, there is a computable function g such that

$$\varphi_{g(x)}(y) = f(x, y) = x$$

for all $x, y \in \mathbb{N}$. By the Theorem 10.1, there is some n such that

$$\varphi_{g(n)} = \varphi_n,$$

the constant function with value n.

As a second application, we get a very short proof of Rice's theorem. Let C be such that $P_C \neq \emptyset$ and $P_C \neq \mathbb{N}$, and let $j \in P_C$ and $k \in \mathbb{N} - P_C$. Define the function f as follows:

$$f(x) = \begin{cases} j & \text{if } x \notin P_C, \\ k & \text{if } x \in P_C, \end{cases}$$

If P_C is computable, then f is computable. By the recursion theorem (Theorem 10.1), there is some n such that

$$\varphi_{f(n)} = \varphi_n$$

But then we have

$$n \in P_C$$
 iff $f(n) \notin P_C$

by definition of f, and thus,

 $\varphi_{f(n)} \neq \varphi_n,$

a contradiction. Hence, P_C is not computable.

As a third application, we prove the following proposition.

Proposition 10.4. Let C be a set of partial computable functions and let

$$A = \{ x \in \mathbb{N} \mid \varphi_x \in C \}.$$

The set A is not reducible to its complement \overline{A} .

Proof. Assume that $A \leq \overline{A}$. Then there is a computable function f such that

$$x \in A$$
 iff $f(x) \in \overline{A}$

for all $x \in \mathbb{N}$. By the recursion theorem, there is some n such that

$$\varphi_{f(n)} = \varphi_n.$$

But then,

$$\varphi_n \in C$$
 iff $n \in A$ iff $f(n) \in \overline{A}$ iff $\varphi_{f(n)} \in \overline{C}$,

contradicting the fact that

$$\varphi_{f(n)} = \varphi_n. \qquad \qquad \square$$

The recursion theorem can also be used to show that functions defined by recursive definitions other than primitive recursion are partial computable, as we discussed a the beginning of this section. This is the case for the function known as *Ackermann's function* discussed in Section 4.10 and defined recursively as follows:

$$f(0, y) = y + 1,$$

$$f(x + 1, 0) = f(x, 1),$$

$$f(x + 1, y + 1) = f(x, f(x + 1, y)).$$

It can be shown that this function is not primitive recursive. Intuitively, it outgrows all primitive recursive functions. However, f is computable, but this is not so obvious. We can use the recursion theorem to prove that f is computable. Using the technique described at the beginning of this section consider the following definition by cases:

$$g(n, 0, y) = y + 1,$$

$$g(n, x + 1, 0) = \varphi_{univ}(n, x, 1),$$

$$g(n, x + 1, y + 1) = \varphi_{univ}(n, x, \varphi_{univ}(n, x + 1, y)).$$

Clearly, g is partial computable. By the s-m-n Theorem, there is a computable function h such that

$$\varphi_{h(n)}(x,y) = g(n,x,y)$$

The equations defining g yield

$$\varphi_{h(n)}(0, y) = y + 1,$$

$$\varphi_{h(n)}(x + 1, 0) = \varphi_n(x, 1),$$

$$\varphi_{h(n)}(x + 1, y + 1) = \varphi_n(x, \varphi_n(x + 1, y)).$$

By the recursion theorem, there is an m such that

$$\varphi_{h(m)} = \varphi_m$$

Therefore, the partial computable function $\varphi_m(x,y)$ satisfies the equations

$$\varphi_m(0, y) = y + 1,$$

$$\varphi_m(x + 1, 0) = \varphi_m(x, 1),$$

$$\varphi_m(x + 1, y + 1) = \varphi_m(x, \varphi_m(x + 1, y))$$

defining Ackermann's function. We showed in Section 4.10 that $\varphi_m(x, y)$ is a total function, and thus, $f = \varphi_m$ and Ackermann's function is a total computable function.

Hence, the recursion theorem justifies the use of certain recursive definitions. However, note that there are some recursive definitions that are only satisfied by the completely undefined function.

In the next section, we prove the extended Rice theorem.

10.2 Extended Rice Theorem

The extended Rice theorem characterizes the sets of partial computable functions C such that P_C is listable (c.e., r.e.). First, we need to discuss a way of indexing the partial computable functions that have a finite domain. Using the uniform projection function Π (see Definition 8.3), we define the primitive recursive function F such that

$$F(x,y) = \Pi(y+1, \Pi_1(x) + 1, \Pi_2(x)).$$

We also define the sequence of partial functions P_0, P_1, \ldots as follows:

$$P_x(y) = \begin{cases} F(x,y) - 1 & \text{if } 0 < F(x,y) \text{ and } y < \Pi_1(x) + 1, \\ \text{undefined} & \text{otherwise.} \end{cases}$$

Proposition 10.5. Every P_x is a partial computable function with finite domain, and every partial computable function with finite domain is equal to some P_x .

The proof is left as an exercise. The easy part of the extended Rice theorem is the following lemma. Recall that given any two partial functions $f: A \to B$ and $g: A \to B$, we say that g extends f iff $f \subseteq g$, which means that g(x) is defined whenever f(x) is defined, and if so, g(x) = f(x).

Proposition 10.6. Let C be a set of partial computable functions. If there is a listable (c.e., r.e.) set A such that $\varphi_x \in C$ iff there is some $y \in A$ such that φ_x extends P_y , then $P_C = \{x \mid \varphi_x \in C\}$ is listable (c.e., r.e.).

Proof. Proposition 10.6 can be restated as

$$P_C = \{ x \mid \exists y \in A, \, P_y \subseteq \varphi_x \}$$

is listable. If A is empty, so is P_C , and P_C is listable. Otherwise, let f be a computable function such that

$$A = range(f).$$

Let ψ be the following partial computable function:

$$\psi(z) = \begin{cases} \Pi_1(z) & \text{if } P_{f(\Pi_2(z))} \subseteq \varphi_{\Pi_1(z)}, \\ \text{undefined} & \text{otherwise.} \end{cases}$$

It is clear that

$$P_C = range(\psi).$$

To see that ψ is partial computable, write $\psi(z)$ as follows:

$$\psi(z) = \begin{cases} \Pi_1(z) & \text{if } \forall w \leq \Pi_1(f(\Pi_2(z))) \\ & [F(f(\Pi_2(z)), w) > 0 \Rightarrow \varphi_{\Pi_1(z)}(w) = F(f(\Pi_2(z)), w) - 1], \\ \text{undefined} & \text{otherwise.} \end{cases}$$

This completes the proof.

To establish the converse of Proposition 10.6, we need two propositions.

Proposition 10.7. If P_C is listable (c.e., r.e.) and $\varphi \in C$, then there is some $P_y \subseteq \varphi$ such that $P_y \in C$.

Proof. Assume that P_C is listable and that $\varphi \in C$. By an s-m-n construction, there is a computable function g such that

$$\varphi_{g(x)}(y) = \begin{cases} \varphi(y) & \text{if } \forall z \le y[\neg T(x, x, z)], \\ \text{undefined} & \text{if } \exists z \le y[T(x, x, z)], \end{cases}$$

for all $x, y \in \mathbb{N}$. Observe that if $x \in K$, then $\varphi_{g(x)}$ is a finite subfunction of φ , and if $x \in \overline{K}$, then $\varphi_{g(x)} = \varphi$. Assume that no finite subfunction of φ is in C. Then

$$x \in \overline{K}$$
 iff $g(x) \in P_C$

for all $x \in \mathbb{N}$, that is, $\overline{K} \leq P_C$. Since P_C is listable, \overline{K} would also be listable, a contradiction.

As a corollary of Proposition 10.7, we note that TOTAL is not listable.

Proposition 10.8. If P_C is listable (c.e., r.e.), $\varphi \in C$, and $\varphi \subseteq \psi$, where ψ is a partial computable function, then $\psi \in C$.

Proof. Assume that P_C is listable. We claim that there is a computable function h such that

$$\varphi_{h(x)}(y) = \begin{cases} \psi(y) & \text{if } x \in K, \\ \varphi(y) & \text{if } x \in \overline{K}, \end{cases}$$

for all $x, y \in \mathbb{N}$. Assume that $\psi \notin C$. Then

$$x \in K$$
 iff $h(x) \in P_C$

for all $x \in \mathbb{N}$, that is, $\overline{K} \leq P_C$, a contradiction, since P_C is listable. Therefore, $\psi \in C$. To find the function h we proceed as follows: Let $\varphi = \varphi_j$ and define Θ such that

$$\Theta(x, y, z) = \begin{cases} \varphi(y) & \text{if } T(j, y, z) \land \neg T(x, y, w), \text{ for } 0 \le w < z \\ \psi(y) & \text{if } T(x, x, z) \land \neg T(j, y, w), \text{ for } 0 \le w < z \\ \text{undefined} & \text{otherwise.} \end{cases}$$

Observe that if x = y = j, then $\Theta(j, j, z)$ is multiply defined, but since ψ extends φ , we get the same value $\psi(y) = \varphi(y)$, so Θ is a well defined partial function. Clearly, for all $(m, n) \in \mathbb{N}^2$, there is at most one $z \in \mathbb{N}$ so that $\Theta(x, y, z)$ is defined, so the function σ defined by

$$\sigma(x,y) = \begin{cases} z & \text{if } (x,y,z) \in \text{dom}(\Theta) \\ \text{undefined} & \text{otherwise} \end{cases}$$

is a partial computable function. Finally, let

$$\theta(x,y) = \Theta(x,y,\sigma(x,y)),$$

a partial computable function. It is easy to check that

$$\theta(x,y) = \begin{cases} \psi(y) & \text{if } x \in K, \\ \varphi(y) & \text{if } x \in \overline{K}, \end{cases}$$

for all $x, y \in \mathbb{N}$. By the s-m-n Theorem, there is a computable function h such that

$$\varphi_{h(x)}(y) = \theta(x, y)$$

for all $x, y \in \mathbb{N}$.

Observe that Proposition 10.8 yields a new proof that $\overline{\text{TOTAL}}$ is not listable (not c.e., not r.e.). Finally we can prove the extended Rice theorem.

Theorem 10.9. (Extended Rice Theorem) The set P_C is listable (c.e., r.e.) iff there is a listable (c.e., r.e) set A such that

$$\varphi_x \in C \quad iff \quad \exists y \in A \left(P_y \subseteq \varphi_x \right)$$

Proof. Let $P_C = dom(\varphi_i)$. Using the s-m-n Theorem, there is a computable function k such that

$$\varphi_{k(y)} = P_y \quad \text{for all } y \in \mathbb{N}$$

Define the listable set A such that

$$A = dom(\varphi_i \circ k).$$

Then

$$y \in A$$
 iff $\varphi_i(k(y)) \downarrow$ iff $P_y \in C$.

Next, using Proposition 10.7 and Proposition 10.8, it is easy to see that

 $\varphi_x \in C$ iff $\exists y \in A (P_y \subseteq \varphi_x).$

Indeed, if $\varphi_x \in C$, by Proposition 10.7, there is a finite subfunction $P_y \subseteq \varphi_x$ such that $P_y \in C$, but

$$P_y \in C \quad \text{iff} \quad y \in A_y$$

as desired. On the other hand, if

 $P_y \subseteq \varphi_x$

for some $y \in A$, then

$$P_y \in C$$
,

and by Proposition 10.8, since φ_x extends P_y , we get

$$\varphi_x \in C.$$

10.3 Creative and Productive Sets; Incompleteness in Arithmetic

In this section, we discuss some special sets that have important applications in logic: creative and productive sets. These notions were introduced by Post and Dekker (1944, 1955). The concepts to be described are illustrated by the following situation. Assume that

$$W_x \subseteq \overline{K}$$

for some $x \in \mathbb{N}$ (recall that W_x was introduced in Definition 9.7). We claim that

$$x \in \overline{K} - W_x$$

Indeed, if $x \in W_x$, then $\varphi_x(x)$ is defined, and by definition of K, we get $x \notin \overline{K}$, a contradiction. Therefore, $\varphi_x(x)$ must be undefined, that is,

$$x \in \overline{K} - W_x$$

The above situation can be generalized as follows.

Definition 10.1. A set $A \subseteq \mathbb{N}$ is *productive* iff there is a total computable function f such that for every listable set W_x ,

if
$$W_x \subseteq A$$
 then $f(x) \in A - W_x$ for all $x \in \mathbb{N}$.

The function f is called the *productive function of* A. A set A is *creative* if it is listable (c.e., r.e.) and if its complement \overline{A} is productive.

As we just showed, K is creative and \overline{K} is productive. It is also easy to see that TOTAL is productive. But TOTAL is worse than \overline{K} , because by Proposition 9.20, TOTAL is not listable.

The following facts are immediate consequences of the definition.

- (1) A productive set is not listable (not c.e., not r.e.), since $A \neq W_x$ for all listable sets W_x (the image of the productive function f is a subset of $A W_x$, which can't be empty since f is total).
- (2) A creative set is not computable (not recursive).

Productiveness is a technical way of saying that a nonlistable set A is not listable in a rather strong and constructive sense. Indeed, there is a computable function f such that no matter how we attempt to approximate A with a listable set $W_x \subseteq A$, then f(x) is an element in A not in W_x .
ection 3), the definition of a productive set on

Remark: In Rogers [64] (Chapter 7, Section 3), the definition of a productive set only requires the productive function f to be *partial computable*. However, it is proven in Theorem XI of Rogers that this weaker requirement is equivalent to the stronger requirement of Definition 10.1.

Creative and productive sets arise in logic. The set of theorems of a logical theory is often creative. For example, the set of theorems in Peano's arithmetic is creative, and the set of true sentences of Peano's arithmetic is productive. This yields incompleteness results. We will return to this topic at the end of this section.

Proposition 10.10. If a set A is productive, then it has an infinite listable (c.e., r.e.) subset.

Proof. We first give an informal proof. Let f be the computable productive function of A. We define a computable function g as follows: Let x_0 be an index for the empty set, and let

$$g(0) = f(x_0).$$

Assuming that

$$\{g(0), g(1), \dots, g(y)\}$$

is known, let x_{y+1} be an index for this finite set, and let

$$g(y+1) = f(x_{y+1}).$$

Since $W_{x_{y+1}} \subseteq A$, we have $f(x_{y+1}) \in A$.

For the formal proof, following Rogers [64] (Chapter 7, Section 7, Theorem X), we use the following facts whose proof is left as an exercise:

(1) There is a computable function u such that

$$W_{u(x,y)} = W_x \cup W_y$$

(2) There is a computable function t such that

$$W_{t(x)} = \{x\}.$$

Letting x_0 be an index for the empty set, we define the function h as follows:

$$h(0) = x_0,$$

 $h(y+1) = u(t(f(y)), h(y))$

We define g such that

$$g = f \circ h$$

It is easily seen that g does the job.

Another important property of productive sets is the following.

Proposition 10.11. If a set A is productive, then $\overline{K} \leq A$.

Proof. Let f be a productive function for A. Using the s-m-n Theorem, we can find a computable function h such that

$$W_{h(y,x)} = \begin{cases} \{f(y)\} & \text{if } x \in K, \\ \emptyset & \text{if } x \in \overline{K}, \end{cases}$$

The above can be restated as follows:

$$\varphi_{h(y,x)}(z) = \begin{cases} 1 & \text{if } x \in K \text{ and } z = f(y), \\ \text{undefined} & \text{if } x \in \overline{K}, \end{cases}$$

for all $x, y, z \in \mathbb{N}$. By the third version of the recursion theorem (Theorem 10.3), there is a computable function g such that

$$W_{g(x)} = W_{h(g(x),x)}$$
 for all $x \in \mathbb{N}$.

Let

 $k = f \circ q.$

We claim that

$$x \in K$$
 iff $k(x) \in A$ for all $x \in \mathbb{N}$.

Subtituting g(x) for y in the equation for $W_{h(y,x)}$ and using the fact that $W_{g(x)} = W_{h(g(x),x)}$ and k(x) = f(g(x)), we get

$$W_{g(x)} = \begin{cases} \{f(g(x))\} = \{k(x)\} & \text{if } x \in K, \\ \emptyset & \text{if } x \in \overline{K}. \end{cases}$$

Because f is a productive function for A, if $x \in \overline{K}$, then $W_{g(x)} = \emptyset \subseteq A$, so $k(x) = f(g(x)) \in A$. A. Conversely, assume that $k(x) = f(g(x)) \in A$. If $x \in K$, then $W_{g(x)} = \{f(g(x))\}$, so $W_{g(x)} \subseteq A$, and since f is a productive function for A, we have $f(g(x)) \in A - W_{g(x)} = A - \{f(g(x))\}$, a contradiction. Therefore, $x \notin \overline{K}$ and the reduction is achieved. Thus, $\overline{K} \leq A$.

Using Part (1) of Proposition 10.12 stated next we obtain the converse of Proposition 10.11. Thus a set A is productive iff $\overline{K} \leq A$. This fact is recorded in the next proposition.

The following results can also be shown.

Proposition 10.12. The following facts hold.

- (1) If A is productive and $A \leq B$, then B is productive.
- (2) A is creative iff A is complete.

(3) A is creative iff A is equivalent to K.

(4) A is productive iff $\overline{K} \leq A$.

Part (1) is easy to prove; see Rogers [64] (Chapter 7, Theorem V(b)). Part (2) is proven in Rogers [64] (Chapter 11, Corollary V). Part (3) follows from Part (2) since K is complete. Part (4) follows from Proposition 10.11 and Part (1).

We conclude with a discussion of the significance of the notions of productive and creative sets to logic. A more detailed discussion can be found in Rogers [64] (Chapter 7, Section 8). In Section 2.20 we discussed Peano arithmetic and the reader is invited to review it. It is convenient to add a countable set of constants $0, 1, 2, \ldots$, denoting the natural numbers to the language of arithmetic, and the new axioms

$$S^n(0) = n, \quad n \in \mathbb{N}.$$

By a now fairly routine process (using a pairing function and an extended pairing function), it is possible to assign a Gödel number #(A) to every first-order sentence A in the language of arithmetic; see Enderton [16] (Chapter III) or Kleene I.M. [42] (Chapter X). With some labor, it is possible to construct a formula F_x with one free variable x having the following property:

> $n \in K$ iff $(F_n \text{ is true in } \mathbb{N})$ $n \notin K$ iff $(F_n \text{ is false in } \mathbb{N})$ iff $(\neg F_x \text{ is true in } \mathbb{N}).$

One should not underestimate the technical difficulty of this task. One of Gödel's most original steps in proving his first incompleteness theorem was to define a variant of the formula F_x . Later on, simpler proofs were given, but they are still very technical. The brave reader should attempt to solve Exercises 7.64 and 7.65 in Rogers [64].

Observe that the sentences F_n are special kinds of sentences of arithmetic but of couse there are many more sentences of arithmetic. The following "basic lemma" from Rogers [64] (Chapter 7, Section 8) is easily shown.

Proposition 10.13. For any two subsets S and T of \mathbb{N} , if T is listable and if $S \cap T$ is productive, then S is productive. In particular, if T is computable and if $S \cap T$ is productive, then S is productive.

With a slight abuse of notation, we say that a set T is sentences of arithmetic is computable (*resp.* listable) iff the set of Gödel numbers #(A) of sentences A in T is computable (*resp.* listable). Then the following remarkable (historically shocking) facts hold.

Theorem 10.14. (Unaxiomatizability of arithmetic) The following facts hold.

(1) The set of sentences of arithmetic true in \mathbb{N} is a productive set. Consequently, the set of true sentences is not listable.

(2) The set of sentences of arithmetic false in \mathbb{N} is a productive set. Consequently, the set of false sentences is not listable.

Proof sketch. (1) It is easy to show that the set $\{\neg F_x \mid x \in \mathbb{N}\}$ is computable. Since

 $\{n \in \mathbb{N} \mid \neg F_n \text{ is true in } \mathbb{N}\} = \overline{K}$

is productive and

$$\{A \mid A \text{ is true in } \mathbb{N}\} \cap \{\neg F_x \mid x \in \mathbb{N}\} = \{\neg F_x \mid \neg F_x \text{ is true in } \mathbb{N}\} \\ = \{\neg F_x \mid x \in \overline{K}\},\$$

by Proposition 10.13, the set $\{A \mid A \text{ is true in } \mathbb{N}\}$ is also productive.

(2) It is also easy to show that the set $\{F_x \mid x \in \mathbb{N}\}$ is computable. Since

 $\{n \in \mathbb{N} \mid F_n \text{ is false in } \mathbb{N}\} = \overline{K}$

is productive and

$$\{A \mid A \text{ is false in } \mathbb{N}\} \cap \{F_x \mid x \in \mathbb{N}\} = \{F_x \mid F_x \text{ is false in } \mathbb{N}\} \\ = \{F_x \mid x \in \overline{K}\},\$$

by Proposition 10.13, the set $\{A \mid A \text{ is false in } \mathbb{N}\}$ is also productive.

Definition 10.2. A proof system for arithmetic is *axiomatizable* if the set of provable sentences is listable.

Since the set of provable sentences of an axiomatizable proof system is listable, Theorem 10.14 annihilates any hope of finding an axiomatization of arithmetic. Theorem 10.14 also shows that it is impossible to decide effectively (algorithmically) whether a sentence of arithmetic is true. In fact the set of true sentences of arithmetic is *not even listable*.

If we consider proof systems for arithmetic, such as Peano arithmetic, then creative sets show up.

Definition 10.3. A proof system for arithmetic is *sound* if every provable sentence is true (in \mathbb{N}). A proof system is *consistent* if there is no sentence A such that both A and $\neg A$ are provable.

Clearly, a sound proof system is consistent.

Assume that a proof system for arithmetic is sound and strong enough so that the formula F_x with the free variable x introduced just before Proposition 10.13 has the following properties:

$$n \in K$$
 iff $(F_n \text{ is provable})$
 $n \notin K$ iff $(F_n \text{ is not provable}).$

Peano arithmetic is such a proof system. Then we have the following theorem.

Theorem 10.15. (Undecidability of provability in arithmetic) Consider any axiomatizable proof system for arithmetic satisfying the hypotheses stated before the statement of the theorem. The following facts hold.

- (1) The set of unprovable sentences of arithmetic is a productive set. Consequently, the set of unprovable sentences is not listable.
- (2) The set of provable sentences of arithmetic is a creative set. Consequently, the set of provable sentences is not computable.

Proof sketch. (1) It is easy to show that the set $\{F_x \mid x \in \mathbb{N}\}$ is computable. Since

 $\{n \in \mathbb{N} \mid F_n \text{ is not provable}\} = \overline{K}$

is productive and

$$\{A \mid A \text{ is not provable}\} \cap \{F_x \mid x \in \mathbb{N}\} = \{F_x \mid F_x \text{ is not provable}\}\$$
$$= \{F_x \mid x \in \overline{K}\},\$$

by Proposition 10.13, the set $\{A \mid A \text{ is not provable}\}$ is also productive.

(2) Since our proof system is axiomatizable, the set of provable sentences is listable, and by (1), its complement is productive, so the set of provable sentences is creative. \Box

As a corollary of Theorem 10.15, there is no algorithm to decide whether a sentence of arithmetic is provable or not. But things are worse. Because the set of unprovable sentences of arithmetic is productive, there is a recursive function f, which for any attempt to find a listable subset W of the nonprovable sentences of arithmetic, produces another nonprovable sentence not in W.

Theorem 10.15 also implies Gödel's first incompleteness theorem. Indeed, it is immediately seen that the set $\{F_x \mid \neg F_x \text{ is provable}\}$ is listable (because $\{\neg F_x \mid x \in \mathbb{N}\}$ is computable and $\{A \mid A \text{ is provable}\}$ is listable). But since our proof system is assumed to be sound, $\neg F_x$ provable implies that F_x is *not* provable, so by

 $n \notin K$ iff (F_n is not provable),

we have

$$\{x \in \mathbb{N} \mid \neg F_x \text{ is provable}\} \subseteq \{x \in \mathbb{N} \mid F_x \text{ is not provable}\} = K$$

Since \overline{K} is productive and $\{x \in \mathbb{N} \mid \neg F_x \text{ is provable}\}$ is listable, we have

$$W_y = \{x \in \mathbb{N} \mid \neg F_x \text{ is provable}\}$$

for some y, and if f is the productive function associated with \overline{K} , then for $x_0 = f(y)$ we have

 $F_{x_0} \in \{F_x \mid F_x \text{ is not provable}\} - \{\neg F_x \mid \neg F_x \text{ is provable}\},\$

that is, both F_{x_0} and $\neg F_{x_0}$ are not provable. Furthermore, since

 $n \notin K$ iff (F_n is not provable)

and

$$n \notin K$$
 iff $(F_n \text{ is false in } \mathbb{N})$

we see that F_{x_0} is false in \mathbb{N} , and so $\neg F_{x_0}$ is true in \mathbb{N} . In summary, we proved the following result.

Theorem 10.16. (Incompleteness in arithmetic (Gödel 1931)) Consider any axiomatizable proof system for arithmetic satisfying the hypotheses stated earlier. Then there exists a sentence F of arithmetic ($F = \neg F_{x_0}$) such that neither F nor $\neg F$ are provable. Furthermore, F is true in \mathbb{N} .

Theorem 10.15 holds under the weaker assumption that the proof system is *consistent* (as opposed to sound), and that there is a formula G with one free variable x such that

$$n \in K$$
 iff $(G_n \text{ is provable}).$

The formula G is due to Rosser. The incompleteness theorem (Theorem 10.16) also holds under the weaker assumption of consistency. See also Kleene [43] (Chapter 5, Theorem VIII and Corollary 1).

To summarize informally the above negative results:

- 1. No (effective) axiomatization of mathematics can exactly capture all true statements of arithmetic.
- 2. From any (effective) axiomatization which yields only true statements of arithmetic, a new true statement can be found *not provable* in that axiomatization.

Fact (2) is what inspired Post to use the term *creative* for the type of sets arising in Definition 10.1. Indeed, one has to be creative to capture truth in arithmetic.

Another (relatively painless) way to prove incompleteness results in arithmetic is to use Diophantine definability; see Section 11.8.

Chapter 11

Listable Sets and Diophantine Sets; Hilbert's Tenth Problem

11.1 Diophantine Equations and Hilbert's Tenth Problem

There is a deep and a priori unexpected connection between the theory of computable and listable sets and the solutions of polynomial equations involving polynomials in several variables with integer coefficients. These are polynomials in $n \ge 1$ variables x_1, \ldots, x_n which are finite sums of *monomials* of the form

$$ax_1^{k_1}\cdots x_n^{k_n},$$

where $k_1, \ldots, k_n \in \mathbb{N}$ are nonnegative integers, and $a \in \mathbb{Z}$ is an integer (possibly negative). The natural number $k_1 + \cdots + k_n$ is called the *degree* of the monomial $ax_1^{k_1} \cdots x_n^{k_n}$.

For example, if n = 3, then

- 1. 5, -7, are monomials of degree 0.
- 2. $3x_1$, $-2x_2$, are monomials of degree 1.
- 3. x_1x_2 , $2x_1^2$, $3x_1x_3$, $-5x_2^2$, are monomials of degree 2.
- 4. $x_1x_2x_3$, $x_1^2x_3$, $-x_2^3$, are monomials of degree 3.
- 5. x_1^4 , $-x_1^2x_3^2$, $x_1x_2^2x_3$, are monomials of degree 4.

It is convenient to introduce multi-indices, where an *n*-dimensional multi-index is an *n*-tuple $\alpha = (k_1, \ldots, k_n)$ with $n \ge 1$ and $k_i \in \mathbb{N}$. Let $|\alpha| = k_1 + \cdots + k_n$. Then we can write

$$x^{\alpha} = x_1^{k_1} \cdots x_n^{k_n}$$

For example, for n = 3,

$$x^{(1,2,1)} = x_1 x_2^2 x_3, \ x^{(0,2,2)} = x_2^2 x_3^2.$$

Definition 11.1. A polynomial $P(x_1, \ldots, x_n)$ in the variables x_1, \ldots, x_n with integer coefficients is a finite sum of monomials of the form

$$P(x_1,\ldots,x_n)=\sum_{\alpha}a_{\alpha}x^{\alpha},$$

where the α 's are *n*-dimensional multi-indices, and with $a_{\alpha} \in \mathbb{Z}$. The maximum of the degrees $|\alpha|$ of the monomials $a_{\alpha}x^{\alpha}$ is called the *total degree* of the polynomial $P(x_1, \ldots, x_n)$. The set of all such polynomials is denoted by $\mathbb{Z}[x_1, \ldots, x_n]$.

Sometimes, we write P instead of $P(x_1, \ldots, x_n)$. We also use variables x, y, z etc. instead of x_1, x_2, x_3, \ldots

For example, 2x - 3y - 1 is a polynomial of total degree 1, $x^2 + y^2 - z^2$ is a polynomial of total degree 2, and $x^3 + y^3 + z^3 - 29$ is a polynomial of total degree 3, and $2x^4 + xyz - 1$ is a polynomial of total degree 4.

Mathematicians have been interested for a long time in the problem of solving equations of the form

$$P(x_1,\ldots,x_n)=0$$

with $P \in \mathbb{Z}[x_1, \ldots, x_n]$, seeking only *integer solutions* for x_1, \ldots, x_n . What this means is that we try to find *n*-tuples of integers $(a_1, \ldots, a_n) \in \mathbb{Z}^n$ such that when we assign the value a_i to the variable x_i for $i = 1, \ldots, n$ in the polynomial $P(x_1, \ldots, x_n)$ and evaluate $P(a_1, \ldots, a_n)$ we obtain $P(a_1, \ldots, a_n) = 0$.

Diophantus of Alexandria, a Greek mathematician of the 3rd century, was one of the first to investigate such equations. For this reason, seeking integer solutions of polynomials in $\mathbb{Z}[x_1, \ldots, x_n]$ is referred to as solving Diophantine equations.

This problem is not as simple as it looks. The equation

$$2x - 3y - 1 = 0$$

obviously has the solution x = 2, y = 1, and more generally x = -1 + 3a, y = -1 + 2a, for any integer $a \in \mathbb{Z}$.

The equation

$$x^2 + y^2 - z^2 = 0$$

has the solution x = 3, y = 4, z = 5, since $3^2 + 4^2 = 9 + 16 = 25 = 5^2$. More generally, the reader should check that

$$x = t^2 - 1, y = 2t, z = t^2 + 1$$

is a solution for all $t \in \mathbb{Z}$.

Even solving quadratic Diophantine equations can be harder than it looks. For example, it can be shown that the smallest positive solution to the equation

$$x^2 - 73y^2 - 1 = 0$$

is

$$x = 2,281,249, \quad y = 267,000,$$

See Niven, Zuckermann and Montgomery [55], Section 7.8. The above equation is a special case of what is known as *Pell's equation*, $x^2 - d^2y^2 = 1$. It plays a crucial role in the negative solution of Hilbert's tenth problem (see below).

The equation

$$x^3 + y^3 + z^3 - 29 = 0$$

has the solution x = 3, y = 1, z = 1.

What about the equation

$$x^3 + y^3 + z^3 - 30 = 0$$

Amazingly, the only known integer solution is

$$(x, y, z) = (-283059965, -2218888517, 2220422932),$$

discovered in 1999 by E. Pine, K. Yarbrough, W. Tarrant, and M. Beck, following an approach suggested by N. Elkies.

And what about solutions of the equation

$$x^3 + y^3 + z^3 - 33 = 0?$$

Until 2019 it was still an open problem but Andrew Booker found the following amazing solution:

 $(8, 866, 128, 975, 287, 528)^3 + (-8, 778, 405, 442, 862, 239)^3 + (-2, 736, 111, 468, 807, 040)^3 = 33.$

In 1900, at the International Congress of Mathematicians held in Paris, the famous mathematician David Hilbert presented a list of ten open mathematical problems. Soon after, Hilbert published a list of 23 problems. The tenth problem is this:

Hilbert's tenth problem (H10)

Find an algorithm that solves the following problem:

Given as input a polynomial $P \in \mathbb{Z}[x_1, \ldots, x_n]$ with integer coefficients, return YES or NO, according to whether there exist integers $a_1, \ldots, a_n \in \mathbb{Z}$ so that $P(a_1, \ldots, a_n) = 0$; that is, the Diophantine equation $P(x_1, \ldots, x_n) = 0$ has a solution.

It is important to note that at the time Hilbert proposed his tenth problem, a rigorous mathematical definition of the notion of algorithm did not exist. In fact, the machinery needed to even define the notion of algorithm did not exist. It is only around 1930 that precise definitions of the notion of computability due to Turing, Church, and Kleene were formulated, and soon after shown to be all equivalent.

So to be precise, the above statement of Hilbert's tenth should say: find a RAM program (or equivalently a Turing machine) that solves the following problem: ...

In 1970, the following somewhat surprising resolution of Hilbert's tenth problem was reached:

Theorem (Davis-Putnam-Robinson-Matiyasevich)

Hilbert's tenth problem is undecidable; that is, there is no algorithm for solving Hilbert's tenth problem.

In 1962, Davis, Putnam and Robinson had shown that if a fact known as *Julia Robinson* hypothesis could be proven, then Hilbert's tenth problem would be undecidable. At the time, the Julia Robinson hypothesis seemed implausible to many, so it was a surprise when in 1970 Matiyasevich found a set satisfying the Julia Robinson hypothesis, thus completing the proof of the undecidability of Hilbert's tenth problem. It is also a bit startling that Matiyasevich's set involves the Fibonacci numbers.

A detailed account of the history of the proof of the undecidability of Hilbert's tenth problem can be found in Martin Davis' classical paper Davis [11].

Even though Hilbert's tenth problem turned out to have a negative solution, the knowledge gained in developing the methods to prove this result is very significant. What was revealed is that polynomials have considerable expressive powers. This is what we discuss in the next section.

11.2 Diophantine Sets and Listable Sets

We begin by showing that if we can prove that the version of Hilbert's tenth problem *with* solutions restricted to belong to \mathbb{N} is undecidable, then Hilbert's tenth problem (with solutions in \mathbb{Z} is undecidable).

Proposition 11.1. If we had an algorithm for solving Hilbert's tenth problem (with solutions in \mathbb{Z}), then we would have an algorithm for solving Hilbert's tenth problem with solutions restricted to belong to \mathbb{N} (that is, nonnegative integers).

Proof. The above statement is not at all obvious, although its proof is short with the help of some number theory. Indeed, by a theorem of Lagrange (Lagrange's four square theorem), *every* natural number m can be represented as the sum of four squares,

$$m = a_0^2 + a_1^2 + a_2^2 + a_3^2, \quad a_0, a_1, a_2, a_3 \in \mathbb{Z}.$$

For a proof, see Niven, Zuckermann and Montgomery [55] (Section 6.4, Theorem 6.26) and Davenport [9] (Chapter V, Section 4). Davenport's proof is more elementary.

We reduce Hilbert's tenth problem restricted to solutions in \mathbb{N} to Hilbert's tenth problem (with solutions in \mathbb{Z}). Given a Diophantine equation $P(x_1, \ldots, x_n) = 0$, we can form the polynomial

$$Q = P(u_1^2 + v_1^2 + y_1^2 + z_1^2, \dots, u_n^2 + v_n^2 + y_n^2 + z_n^2)$$

in the 4n variables u_i, v_i, y_i, z_i $(1 \le i \le n)$ obtained by replacing x_i by $u_i^2 + v_i^2 + y_i^2 + z_i^2$ for $i = 1, \ldots, n$. If Q = 0 has a solution $(p_1, q_1, r_1, s_1, \ldots, p_n, q_n, r_n, s_n)$ with $p_i, q_i, r_i, s_i \in \mathbb{Z}$, then if we set $a_i = p_i^2 + q_i^2 + r_i^2 + s_i^2$, obviously $P(a_1, \ldots, a_n) = 0$ with $a_i \in \mathbb{N}$. Conversely, if $P(a_1, \ldots, a_n) = 0$ with $a_i \in \mathbb{N}$, then by Lagrange's theorem there exist some $p_i, q_i, r_i, s_i \in \mathbb{Z}$ (in fact \mathbb{N}) such that $a_i = p_i^2 + q_i^2 + r_i^2 + s_i^2$ for $i = 1, \ldots, n$, and the equation Q = 0 has the solution $(p_1, q_1, r_1, s_1, \ldots, p_n, q_n, r_n, s_n)$ with $p_i, q_i, r_i, s_i \in \mathbb{Z}$. Therefore Q = 0 has a solution $(p_1, q_1, r_1, s_1, \ldots, p_n, q_n, r_n, s_n)$ with $p_i, q_i, r_i, s_i \in \mathbb{Z}$ iff P = 0 has a solution (a_1, \ldots, a_n) with $a_i \in \mathbb{N}$. If we had an algorithm to decide whether Q has a solution with its components in \mathbb{N} .

As consequence, the contrapositive of Proposition 11.1 shows that if the version of Hilbert's tenth problem restricted to solutions in \mathbb{N} is undecidable, so is Hilbert's original problem (with solutions in \mathbb{Z}).

In fact, the Davis-Putnam-Robinson-Matiyasevich theorem establishes the undecidability of the version of Hilbert's tenth problem restricted to solutions in \mathbb{N} . From now on, we restrict our attention to this version of Hilbert's tenth problem.

A key idea is to use Diophantine equations with parameters to *define* sets of numbers.

Example 11.1. For example, consider the polynomial

$$P_1(a, y, z) = (y+2)(z+2) - a.$$

For $a \in \mathbb{N}$ fixed, the equation (y+2)(z+2) - a = 0, equivalently

$$a = (y+2)(z+2),$$

has a solution for some $y, z \in \mathbb{N}$ iff a is composite. The variables a, y, z do not play the same role. When we try to solve the equation (y + 2)(z + 2) - a = 0, we assume that a is fixed and we look for values of y and z that solve the equation. To distinguish between the roles of a and y, z we call y and z parameters. If no solution exists for y, z, then we reject a, that is, we do not include it in the set that we are trying to define. Otherwise we include a in the set that we are defining, namely the set of composites.

Example 11.2. If we now consider the polynomial

$$P_2(a, y, z) = y(2z + 3) - a,$$

for $a \in \mathbb{N}$ fixed, the equation y(2z+3) - a = 0, equivalently

$$a = y(2z+3),$$

has a solution for some $y, z \in \mathbb{N}$ iff a is not a power of 2. Thus the equation of this example, where y and z are parameters defines the natural numbers that are not a power of 2.

Example 11.3. For a slightly more complicated example, consider the polynomial

$$P_3(a, y) = 3y + 1 - a^2$$

where y is the parameter. We leave it as an exercise to show that the natural numbers a for which there is some $y \in \mathbb{N}$ such that $3y + 1 - a^2 = 0$, equivalently

$$(a-1)(a+1) = 3y_1$$

are of the form a = 3k + 1 or a = 3k + 2, for any $k \in \mathbb{N}$.

In the first case, if we let S_1 be the set of composite natural numbers, then we can write

$$S_1 = \{ a \in \mathbb{N} \mid (\exists y, z)((y+2)(z+2) - a = 0) \},\$$

where it is understood that the existentially quantified variables y, z take their values in N.

In the second case, if we let S_2 be the set of natural numbers that are not powers of 2, then we can write

$$S_2 = \{ a \in \mathbb{N} \mid (\exists y, z)(y(2z+3) - a = 0) \}.$$

In the third case, if we let S_3 be the set of natural numbers that are congruent to 1 or 2 modulo 3, then we can write

$$S_3 = \{a \in \mathbb{N} \mid (\exists y)(3y + 1 - a^2 = 0)\}.$$

A more explicit Diophantine definition for S_3 is

$$S_3 = \{ a \in \mathbb{N} \mid (\exists y)((a - 3y - 1)(a - 3y - 2)) = 0) \}.$$

The natural generalization is as follows.

Definition 11.2. A set $S \subseteq \mathbb{N}$ of natural numbers is *Diophantine* (or *Diophantine definable*) if there is a polynomial $P(x, y_1, \ldots, y_n) \in \mathbb{Z}[x, y_1, \ldots, y_n]$, with $n \ge 0^1$ such that

$$S = \{a \in \mathbb{N} \mid (\exists y_1, \dots, y_n) (P(a, y_1, \dots, y_n) = 0)\},\$$

where it is understood that the existentially quantified variables y_1, \ldots, y_n (the parameters) take their values in \mathbb{N} . Thus $a \in S$ iff there exist some natural numbers $(b_1, \ldots, b_n) \in \mathbb{N}^n$ such that $P(a, b_1, \ldots, b_n) = 0$. More generally, a relation $R \subseteq \mathbb{N}^m$ is Diophantine $(m \ge 2)$ if there is a polynomial $P(x_1, \ldots, x_m, y_1, \ldots, y_n) \in \mathbb{Z}[x_1, \ldots, x_m, y_1, \ldots, y_n]$, with $n \ge 0$, such that

$$R = \{ (a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists y_1, \dots, y_n) (P(a_1, \dots, a_m, y_1, \dots, y_n) = 0) \},\$$

where it is understood that the existentially quantified variables y_1, \ldots, y_n (parameters) take their values in N. Thus $(a_1, \ldots, a_m) \in R$ iff there exist some natural numbers $(b_1, \ldots, b_n) \in \mathbb{N}^n$ such that $P(a_1, \ldots, a_m, b_1, \ldots, b_n) = 0$.

¹We have to allow n = 0. Otherwise singleton sets would not be Diophantine.

It is important to note that the simpler definition in which n = 0 (there are no parameters) yields a notion which is far too restrictive. Indeed, given a polynomial P(x) of a single variable x, there are only finitely many $a \in \mathbb{N}$ such that P(a) = 0. Thus we only obtain finite sets. Similarly, given a polynomial $P(x_1, \ldots, x_n)$ with $n \ge 2$, for any $a_1, \ldots, a_{n-1} \in \mathbb{N}$, there there are only finitely many $a_n \in \mathbb{N}$ such that $P(a_1, \ldots, a_n) = 0$. Again, this class of relations is too restrictive.

The definition of Diophantine definability has the following interpretation as a computational mechanism for defining a set $S \subseteq \mathbb{N}$ in terms of acceptance or rejection. Given $a \in \mathbb{N}$, we can view the search for natural numbers $(b_1, \ldots, b_m) \in \mathbb{N}^m$ such that $P(a, b_1, \ldots, b_m) = 0$ as a computation. If a solution (b_1, \ldots, b_m) is found (making $P(a, b_1, \ldots, b_m) = 0$), then a is accepted, and by definition $a \in S$. If either it can be established that the equation $P(a, y_1, \ldots, y_m) = 0$ has no solution (for y_1, \ldots, y_m) or if the search goes on forever, then ais rejected and $a \notin S$. The undecidability of Hilbert's tenth implies that we can't decide if the second alternative arises. Mathematically it is appealing that we obtain a model of computability with universal power that does not require any machine model for its definition.

In Definition 11.2, to define when a set $S \subseteq \mathbb{N}$ is Diophantine we used the variables y_1, \ldots, y_n to denote the parameters occurring in the polynomial $P(x, y_1, \ldots, y_n)$. We did this because in generalizing this notion to *m*-ary relations it is natural to replace the single variable x by x_1, \ldots, x_m , so the use of the variables y_1, \ldots, y_n prevents a clash with the variables x_1, \ldots, x_m . However, when we define a set S to be Diophantine we often use the variables x_1, \ldots, x_n instead of y_1, \ldots, y_n since there is very little risk of confusing the variable x with the variables x_1, \ldots, x_m .

Example 11.4. The strict order relation $a_1 < a_2$ is defined as follows:

$$a_1 < a_2$$
 iff $(\exists y)(a_1 + 1 + y - a_2 = 0),$

and the divisibility relation $a_1 \mid a_2 \ (a_1 \text{ divides } a_2)$ is defined as follows:

$$a_1 \mid a_2$$
 iff $(\exists z)(a_1z - a_2 = 0).$

Example 11.5. What about the ternary relation $R \subseteq \mathbb{N}^3$ given by

$$(a_1, a_2, a_3) \in R$$
 if $a_1 \mid a_2$ and $a_1 < a_3$?

At first glance it is not obvious how to "convert" a conjunction of Diophantine definitions into a single Diophantine definition, but we can do this using the following squaring trick: given any $n \ge 2$ Diophantine equations in the variables x_1, \ldots, x_m ,

$$P_1 = 0, P_2 = 0, \dots, P_n = 0,$$
 (*)

observe that (*) has a solution (a_1, \ldots, a_m) , which means that $P_i(a_1, \ldots, a_m) = 0$ for $i = 1, \ldots, n$, iff the single equation

$$P_1^2 + P_2^2 + \dots + P_n^2 = 0 \tag{**}$$

also has the solution (a_1, \ldots, a_m) , namely

$$(P_1^2 + P_2^2 + \dots + P_n^2)(a_1, \dots a_m) = P_1(a_1, \dots a_m)^2 + \dots + P_n(a_1, \dots a_m)^2 = 0.$$

This is because, since the $P_1(a_1, \ldots, a_m)^2$ for $i = 1, \ldots, n$, are all nonnegative, their sum is equal to zero iff they are all equal to zero, that is $P_i(a_1, \ldots, a_m)^2 = 0$ for $i = 1, \ldots, n$, which is equivalent to $P_i(a_1, \ldots, a_m) = 0$ for $i = 1, \ldots, n$.

As a consequence, the set $S \subseteq \mathbb{N}$ defined by *n* polynomials P_1, \ldots, P_n in $\mathbb{Z}[x, y_1, \ldots, y_p]$ as

 $\{a \in \mathbb{N} \mid (\exists y_1, \dots, y_p)(P_1(a, y_1, \dots, y_p) = 0, \dots, P_n(a, y_1, \dots, y_p) = 0)\}$

is actually the Diophantine set defined by

$$\{a \in \mathbb{N} \mid (\exists y_1, \dots, y_p)(P_1(a, y_1, \dots, y_p)^2 + \dots + P_n(a, y_1, \dots, y_p)^2 = 0)\}.$$

This method also applies to relations $R \subseteq \mathbb{N}^m$ with $m \geq 2$, where we use polynomials $P_1(x_1, \ldots, x_m, y_1, \ldots, y_p), \ldots, P_n(x_1, \ldots, x_m, y_1, \ldots, y_p)$ in $\mathbb{Z}[x_1, \ldots, x_m, y_1, \ldots, y_p]$.

Using this trick, we see that

$$(a_1, a_2, a_3) \in R$$
 iff $(\exists u, v)((a_1u - a_2)^2 + (a_1 + 1 + v - a_3)^2 = 0).$

We can use the above technique to show that the Diophantine sets are closed under intersection.

Since $(P_1P_2)(a_1, \ldots, a_m) = 0$ iff $P_1(a_1, \ldots, a_m) = 0$ or $P_2(a_1, \ldots, a_m) = 0$, using this fact it is easily shown that the Diophantine sets are closed under union. However, they are *not* closed under complementation. This is not easy to show directly but it is an immediate consequence of Theorem 11.8 which asserts that the family of Diophantine sets and the family of listable sets coincide.

We can also define the notion of Diophantine function.

11.3 Diophantine Functions

Definition 11.3. A partial function $f: \mathbb{N}^n \to \mathbb{N}$ is *Diophantine* iff its graph $\{(a_1, \ldots, a_n, a_{n+1}) \subseteq \mathbb{N}^{n+1} \mid a_{n+1} = f(a_1, \ldots, a_n)\}$ is Diophantine. This means that there is a polynomial $P(x_1, \ldots, x_{n+1}, y_1, \ldots, y_p) \in \mathbb{Z}[x_1, \ldots, x_{n+1}, y_1, \ldots, y_p]$, with $p \ge 0$, such that $a_{n+1} = f(a_1, \ldots, a_n)$ iff there exist some natural numbers $(b_1, \ldots, b_p) \in \mathbb{N}^p$ such that $P(a_1, \ldots, a_{n+1}, b_1, \ldots, b_p) = 0$. A function $f: \mathbb{N}^n \to \mathbb{N}$ is *Diophantine* iff it is Diophantine as a partial function and if it is total, that is, for all $(a_1, \ldots, a_n) \in \mathbb{N}^n$, if $a_{n+1} = f(a_1, \ldots, a_n)$, then the equation $P(a_1, \ldots, a_{n+1}, y_1, \ldots, y_p) = 0$ has a solution (in the variables y_1, \ldots, y_p).

Example 11.6. The pairing function J and the projection functions K, L due to Cantor introduced in Section 8.1 are Diophantine, since

$$z = J(x, y) \quad \text{iff} \quad (x+y)(x+y+1) + 2x - 2z = 0$$

$$x = K(z) \quad \text{iff} \quad (\exists y)((x+y)(x+y+1) + 2x - 2z = 0)$$

$$y = L(z) \quad \text{iff} \quad (\exists x)((x+y)(x+y+1) + 2x - 2z = 0).$$

The definition of J uses no parameter but the definitions of K and L use one parameter.

How extensive is the family of Diophantine sets? The remarkable fact proven by Davis-Putnam-Robinson-Matiyasevich is that they coincide with the listable sets (the recursively enumerable sets). This is a highly nontrivial result. Actually, the crucial point is that a total function is Diophantine iff it is computable. Then this result can be used to prove that a set is Diophantine iff it is listable.

The proof that a total function is Diophantine iff it is computable uses a bit of arithmetic that we now review.

11.4 GCD's, Bezout Identity, Chinese Remainder Theorem

Recall the notion of divisibility from Example 11.4.

Definition 11.4. Given any two integers $m, n \in \mathbb{Z}$, we say that m divides n, often written $m \mid n$, if there is some $q \in \mathbb{Z}$ such that n = mq. In this case, we call n a multiple of m. If $m \neq 0$, the integer q such that n = mq is unique and it is called the *quotient* and it is denoted by n/m.

Observe that if 0 divides n, namely n = 0q for some q, then n = 0. So only 0 is divisible by 0. On the other hand, since 0 = 0q for all $q \in \mathbb{Z}$, 0 is divisible by all integers. So even though 0 is divisible by 0, the quotient 0/0 is undefined since 0 = 0q for all $q \in \mathbb{Z}$. We usually avoid division by 0.

Definition 11.5. Given any two integers $m, n \in \mathbb{Z}$, the greatest nonnegative common divisor (for short gcd) of m and n is the unique natural number $d \in \mathbb{N}$ such that:

- (i) The number d divides both m and n.
- (ii) For any $h \in \mathbb{Z}$, if h divides m and n, then h divides d.

The gcd of m and n is denoted as gcd(m, n).

The reader should check that gcd(0,0) = 0, gcd(a,0) = |a| if $a \neq 0$, and gcd(0,b) = |b| if $b \neq 0$.

Example 11.7. Since $15 = 3 \times 5$ and $21 = 3 \times 7$, we see that gcd(15, 21) = 3.

Since $657 = 9 \times 73$ and $963 = 9 \times 107$, we see that 9 is a divisor of 657 and 963. Since 73 and 107 are prime (check this fact), 9 is the gcd of 657 and 963.

The following result gives a useful characterization of the gcd in terms of a linear equation.

Proposition 11.2. (Bezout Identity) For any two integers $m, n \in \mathbb{Z}$, there is a unique natural number $d \in \mathbb{N}$ and some integers $a, b \in \mathbb{Z}$, such that d divides both m and n and

$$am + bn = d.$$

We have d = 0 iff m = 0 and n = 0. Furthermore, d is the nonnegative gcd of m and n.

Proof. If d = 0, since d divides both m and m, we must have m = n = 0, and a, b can be chosen arbitrarily. Conversely, if m = n = 0, then for any $a, b \in \mathbb{Z}$, we have d = a0 + b0 = 0.

Let us now assume that $m \neq 0$ or $n \neq 0$. Consider the set of integers

$$\mathfrak{J} = \{hm + kn \mid h, k \in \mathbb{Z}\}.$$

For h = 1 and k = 0 we have $m \in \mathfrak{J}$, and for h = 0 and k = 1 we have $n \in \mathfrak{J}$. Since either $m \neq 0$ or $n \neq 0$, we see that \mathfrak{J} contains some positive natural number (if m > 0 we are done, else if m < 0 then $(-1)m \in \mathfrak{J}$, with a similar reasoning with $n \neq 0$). Since \mathfrak{J} contains some positive natural number, it contains a smallest one, say d.

We claim that

$$\mathfrak{J} = d\mathbb{Z} = \{ dk \mid k \in \mathbb{Z} \}. \tag{\dagger}_B$$

Since $d \in \mathfrak{J}$, by definition of \mathfrak{J} , we have $d\mathbb{Z} \subseteq \mathfrak{J}$.

Conversely pick any $s \in \mathfrak{J}$. If we divide s by d, we obtain

$$s = dq + r_s$$

for some $q \in \mathbb{Z}$ and some r such that $0 \leq r < d$. If r > 0, since $s \in \mathfrak{J}$ and $d \in \mathfrak{J}$, they can be expressed as $s = h_1m + k_1n$ and $d = h_2m + k_2n$ for some $h_1, h_2, k_1, k_2 \in \mathbb{Z}$. Then we have

$$r = s - dq = h_1 m + k_1 n - (h_2 m + k_2 n)q = (h_1 - h_2 q)m + (k_1 - k_2 q)n$$

which shows that $r \in \mathfrak{J}$. But then we have $r \in \mathfrak{J}$ with r > 0 and r < d, contradicting the fact that d is the smallest positive integer in \mathfrak{J} . Therefore r = 0, and we proved that $s \in d\mathbb{Z}$. Consequently, (\dagger_B) holds. Since $m, n \in \mathfrak{J} = d\mathbb{Z}$, we see that d divides both m and n. Since $d \in \mathfrak{J}$, there exist $a, b \in \mathbb{Z}$ such that

$$am + bn = d.$$

By construction, $d \in \mathbb{N}$ divides m and n. If any $d' \in \mathbb{Z}$ divides both m and n, since d = am + bn, d' also divides d. Therefore d is the nonnegative gcd of m and n.

Example 11.8. We saw in Example 11.7 that gcd(15, 21) = 3. We see immediately that

$$3 \times 15 + (-2) \times 21 = 3$$

We also found that gcd(657, 963) = 9. The reader will check that

$$22 \times 657 + (-15) \times 963 = 9$$

A good algorithmic method for finding gcd's and numbers a, b such that am + bn = gcd(m, n) is the Euclidean algorithm; see Niven, Zuckermann and Montgomery [55], Theorem 1.11. For example, we find that

$$gcd(42823, 6409) = 17$$

and that

$$(-22) \times 42823 + 147 \times 6409 = 17.$$

Definition 11.6. Given any two integers $m, n \in \mathbb{Z}$, not both zero, we say that m and n are relatively prime if gcd(m, n) = 1.

Proposition 11.2 has the following very useful corollary.

Proposition 11.3. (Bezout Criterion) Given any two integers $m, n \in \mathbb{Z}$, not both zero, m and n are relatively prime if and only if there exists some integers $a, b \in \mathbb{Z}$ such that

$$am + bn = 1.$$

Proof. If $m \neq 0$ or $n \neq 0$ and d = gcd(m, n) = 1, then Proposition 11.2 implies that exists some integers $a, b \in \mathbb{Z}$ such that

$$am + bn = 1.$$

Conversely, any integer d dividing both m and n must divide 1, so gcd(m, n) = 1.

Example 11.9. It is easy to check that $42823 = 17 \times 2519$ and $6409 = 17 \times 377$. Since gcd(42823, 6409) = 17, we must have gcd(2519, 377) = 1, so 2519 and 377 are relatively prime. We also have

 $(-22) \times 2519 + 147 \times 377 = 1.$

Neither 2519 nor 377 is prime, as the reader should check.

We now prove a classical result (and a gem) of elementary number theory.

Theorem 11.4. (Chinese Remainder Theorem) Let n_1, \ldots, n_m $(m \ge 1)$ be any positive integers that are pairwise relatively prime (which means that n_i and n_j are relatively prime for all i < j), and let a_1, \ldots, a_m be any integers $(a_i \in \mathbb{Z})$. Then there is some $x \in \mathbb{Z}$ such that

$$x \equiv a_i \pmod{n_i} \quad i = 1, \dots, m. \tag{C}$$

If x_0 is any solution of the system of congruences (C), then $x \in \mathbb{Z}$ is a solution of the system (C) iff $x \equiv x_0 \pmod{n}$, where $n = n_1 \cdots n_m$.

Proof. The proof given in Niven, Zuckermann and Montgomery [55] is one of the simplest proofs we are aware of; see Section 2.3, Theorem 2.18. It relies on two simple facts about gcd's:

- (1) If m, p, q are positive natural numbers and if m is relatively prime with p and q, then m is relatively prime with pq. This follows easily from Proposition 11.3. See Niven, Zuckermann and Montgomery [55], Theorem 1.8.
- (2) If m and n are positive natural numbers and if m and n are relatively prime, then there is some integer x such that $mx \equiv 1 \pmod{n}$. Again, this follows immediately from Proposition 11.3. See Niven, Zuckermann and Montgomery [55], Theorem 2.9.

The case where m = 1 is trivial since we can can pick $x = a_1$, so we assume that $m \ge 2$. Let $n = n_1 \cdots n_m$. Each n/n_i is a natural number, and by induction using (1), we see that $gcd(n/n_j, n_j) = 1$ for $j = 1, \ldots, m$. Hence by (2), there is some integer b_j such that

$$(n/n_j)b_j \equiv 1 \pmod{n_j}, \quad j = 1, \dots, m.$$
 (1)

Since n/n_i contains n_i for $i \neq j$, we have

$$(n/n_i)b_i \equiv 0 \pmod{n_i}, \quad i \neq j.$$

We claim that a solution of the system of congruences (C) is given by

$$x_0 = \sum_{j=1}^m \frac{n}{n_j} b_j a_j,\tag{3}$$

as we now verify. By (1), we have $(n/n_j)b_ja_j \equiv a_j \pmod{n_j}$ for $j = 1, \ldots, m$, and by (2) $(n/n_j)b_ja_j \equiv 0 \pmod{n_i}$ if $i \neq j$, so from (3) by taking the residue modulo n_i we get

$$x_0 \equiv \frac{n}{n_i} b_i a_i \equiv a_i \pmod{n_i},$$

which means that x_0 is a solution of the system (C).

If $x \in \mathbb{Z}$ is another solution of the system

$$x \equiv a_i \pmod{n_i} \quad i = 1, \dots, m,\tag{C}$$

then by subtraction we obtain

$$x \equiv x_0 \pmod{n_i}, \quad i = 1, \dots, m,$$

which is easily seen to be equivalent to $x \equiv x_0 \pmod{n}$. Finally, if $x \equiv x_0 \pmod{n}$, then we deduce immediately that x is a solution of the system (C).

Remark: If m, n > 0 and gcd(m, n) = 1, an inverse x of m modulo n, namely an integer x such that $mx \equiv 1 \pmod{n}$, can be computed using the Euclidean algorithm; see Niven, Zuckermann and Montgomery [55], Theorem 1.11. Thus the proof of Theorem 11.4 is constructive.

Example 11.10. Consider the system of congruences

$$x \equiv 5 \pmod{7}$$
$$x \equiv 7 \pmod{11}$$
$$x \equiv 3 \pmod{13}.$$

We easily check that $n_1 = 7, n_2 = 11, n_3 = 13$ are pairwise relatively prime. We also have $a_1 = 5, a_2 = 7, a_3 = 3$, and $n = 7 \times 11 \times 13 = 1001$. The reader should check that

$$(-2) \times n_2 n_3 + 21 \times n_1 = 1$$

$$4 \times n_1 n_3 + (-33) \times n_2 = 1$$

$$(-1) \times n_1 n_2 + 6 \times n_3 = 1.$$

Consequently, we can pick $b_1 = -2$ as the inverse of n_2n_3 modulo n_1 , $b_2 = 4$ as the inverse of n_1n_3 modulo n_2 , and $b_3 = -1$ as the inverse of n_1n_2 modulo n_3 . Theorem 11.4 tells us that a solution is given by

$$x_0 = 11 \times 13 \times (-2) \times 5 + 7 \times 13 \times 4 \times 7 + 7 \times 11 \times (-1) \times 3 = 887.$$

We can then check that $x_0 = 887$ works, and since 887 < 1001, it is the smallest positive solution.

11.5 Proof of the DPRM: Main Steps

The easier direction is the following result.

Proposition 11.5. Every Diophantine (total) function is computable. Every Diophantine subset of \mathbb{N} is listable (recursively enumerable).

Proof sketch. First we propose an informal argument for the second statement. Suppose S is given as

$$S = \{ a \in \mathbb{N} \mid (\exists x_1, \dots, x_n) (P(a, x_1, \dots, x_n) = 0) \},\$$

Using the extended pairing function $\langle x_1, \ldots, x_n \rangle_n$ of Section 8.1, we enumerate all *n*-tuples $(x_1, \ldots, x_n) \in \mathbb{N}^n$, and during this process we compute $P(a, x_1, \ldots, x_n)$. If $P(a, x_1, \ldots, x_n)$ is zero, then we output a, else we go on. This way, S is the range of a computable function, and it is listable.

A more rigorous argument of Proposition 11.5 presented by Martin Davis in [11] proceeds by first proving that if a total function is Diophantine, then it is computable. Then in a second step it is shown that a Diophantine set is listable. To prove this it is necessary to tweak the characterization of a listable set as follows. **Proposition 11.6.** A set $S \subseteq \mathbb{N}$ is listable iff there are two (total) computable functions $f, g: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$ such that

$$S = \{a \in \mathbb{N} \mid (\exists x)(f(a, x) = g(a, x))\}.$$

Proof. If $S = \emptyset$, then we let f be the constant function equal to 0 and g be the constant function equal to 1. If $S \neq \emptyset$ is listable, then by Definition 9.6 (see also Proposition 9.9), there is a total computable function $h: \mathbb{N} \to \mathbb{N}$ such that S is equal to the range of h. If we let f be given by f(a, x) = a and g(a, x) = h(x) for all $a, x \in \mathbb{N}$, then

 $S = \operatorname{range}(h) = \{ a \in \mathbb{N} \mid (\exists x)(a = h(x)) \} = \{ a \in \mathbb{N} \mid (\exists x)(f(a, x) = g(a, x)) \}.$

Conversely, assume that

$$S = \{a \in \mathbb{N} \mid (\exists x)(f(a, x) = g(a, x))\}$$

with f, g total computable. Observe that for any fixed $a \in \mathbb{N}$, the equation f(a, x) = g(a, x) has a solution $x \in \mathbb{N}$ iff the function

$$h(x) = \min x(f(a, x) = g(a, x))$$

is defined, so S is equal to the domain of h. Since f and g are computable and the equality predicate is primitive recursive, the function h is partial computable and by Proposition 9.9, its domain dom(h) = S is listable.

A key technical result used in the proof of Proposition 11.5 and Theorem 11.8 is the sequence number theorem. This is a variant of a result that Gödel proved to establish his first incompleteness theorem.

Theorem 11.7. (Sequence Number Theorem) There is a (total) Diophantine function $(i, u) \mapsto S(i, u)$ such that

- (1) $S(i, u) \leq u$ for all $i, u \in \mathbb{N}$.
- (2) For any $N \in \mathbb{N} \{0\}$ and any sequence $(a_1, \ldots, a_n) \in \mathbb{N}^N$, there is some $u \in \mathbb{N}$ such that

$$S(i, u) = a_i \quad for \quad 1 \le i \le N.$$

We have w = S(i, u) iff w is the remainder of the division of K(u) by 1 + iL(u).

Sketch of proof. Theorem 11.7 is Theorem 1.3 in Davis [11]. The proof needs a slight adjustment because Davis assumes that all numbers in question are *positive* natural numbers, but we don't. The function $(i, u) \mapsto w = S(i, u)$ is defined by the following set of equations where z, v are the parameters:

$$2u = (x + y)(x + y + 1) + 2x$$
$$x = w + z(1 + iy)$$
$$1 + iy = w + v + 1.$$

In view of Example 11.6, we have u = J(x, y), so

$$x = K(u)$$
 and $y = L(u)$.

The third equation asserts that w < 1 + iy, so together with the second equation x = w + z(1 + iy), we deduce that w is the remainder of the division of x by $1 + iy \neq 0$. Thus the above equations define a total function S. The second equation implies that $w \leq x = K(u) \leq u$, which is (1).

To prove Condition (2) we use the Chinese remainder theorem, Theorem 11.4.

One might worry that Davis assumes that the numbers a_i are strictly positive, but as we just saw the Chinese remainder theorem is valid even if $a_i = 0$, so there is no problem.

We can now prove that Condition (2) holds as follows. Consider any sequence $(a_1, \ldots, a_N) \in \mathbb{N}^N$. If N = 1, pick $y = a_1 + 1$ and proceed to the step where the Chinese remainder theorem is used. If $N \ge 2$, choose $y \in \mathbb{N}$ so that $y > a_i$ for $i = 1, \ldots, N$ and y is divisible by i for $i = 1, \ldots, N - 1$. For example $y = (\max\{a_i\} + 1)(N - 1)!$ will do. We claim that the natural numbers $1 + y, 1 + 2y, \ldots, 1 + Ny$ are pairwise relatively prime.

If not, some natural number $d \ge 1$ divides both 1 + iy and 1 + jy for some i, j such that $1 \le i < j \le N$. Then d divides j(1 + iy) - i(1 + jy) = j - i, which implies that $1 \le d < N$. However y was chosen so that it is divisible by k for $k = 1, \ldots, N - 1$, so d would divide y, and since d also divides 1 + iy, we must have d = 1.

We can now apply the Chinese remainder theorem with $n_i = 1 + id$ for i = 1, ..., N. Therefore there is some $x \in \mathbb{N}$ such that

$$x \equiv a_1 \pmod{1+y}$$
$$x \equiv a_2 \pmod{1+2y}$$
$$\vdots$$
$$x \equiv a_N \pmod{1+Ny}$$

Let u = J(x, y) so that x = K(u) and y = L(u). We have

$$K(u) \equiv a_i \pmod{1 + iL(u)}, \quad i = 1, \dots, N.$$

By definition of y, we also have $a_i < y = L(u) < 1 + iL(u)$, and then we see that a_i is the remainder of the division of K(u) by 1 + iL(u), which is equal to S(i, u) by definition of S.

Interestingly, Davis states that the function S is primitive recursive, but does not provide a proof. However, a proof can be extracted from his book Davis [10]; see Chapter 3, Sections 1 and 2.

The proof that S is primitive recursive uses the remainder function $rem \colon \mathbb{N} \times \mathbb{N} \to \mathbb{N}$ defined such that if n > 0, then rem(m, n) = r is the remainder of the division of m by n, namely the unique $r \in \mathbb{N}$ such that r < n and m = nq+r for some $q \in \mathbb{N}$, else rem(m, 0) = m. We leave it as an exercise to prove that rem is primitive recursive. Using rem we define S as

$$S(i, u) = rem(K(u), 1 + iL(u)).$$

See the proof of Theorem 2.4 in Davis [10], observing that since here the index *i* ranges from 1 to N, the term 1 + L(u)(i+1) of Davis' proof can be replaced by 1 + iL(u).

Let us now assume that the total function $f: \mathbb{N}^m \to \mathbb{N}$ is Diophantine, so that there is a polynomial $P(x_1, \ldots, x_n, z, y_1, \ldots, y_p)$ such that

$$c = f(a_1, \dots, a_n)$$
 iff $(\exists b_1, \dots, b_p)(P(a_1, \dots, a_m, c, b_1, \dots, b_p) = 0).$

By grouping the monomials with positive coefficients together and the monomials with negative coefficients together we can write

$$P(x_1, \dots, x_n, z, y_1, \dots, y_p) = Q(x_1, \dots, x_n, z, y_1, \dots, y_p) - R(x_1, \dots, x_n, z, y_1, \dots, y_p),$$

where $Q(x_1, \ldots, x_n, z, y_1, \ldots, y_p)$ and $R(x_1, \ldots, x_n, z, y_1, \ldots, y_p)$ have positive integer coefficients. Using Q and R we can express the definition of f as

$$c = f(a_1, \ldots, a_n)$$
 iff $(\exists b_1, \ldots, b_p)(Q(a_1, \ldots, a_m, c, b_1, \ldots, b_p) = R(a_1, \ldots, a_m, c, b_1, \ldots, b_p)).$

Using the sequence number theorem we we can find $u \in \mathbb{N}$ such that $c = S(1, u), b_1 = S(2, u), \ldots, b_p = S(p+1, u)$, and we deduce that

$$f(a_1, \dots, a_n) = S(1, \min_u [Q(a_1, \dots, a_m, S(1, u), S(2, u), \dots, S(p+1, u))]$$

= $R(a_1, \dots, a_m, S(1, u), S(2, u), \dots, S(p+1, u))]).$

Now we explained before that the polynomials Q and R having positive integer coefficients compute *primitive recursive* functions, which are special kinds of total functions. Since Sis also primitive recursive, using the fact that the computable functions are closed under composition and minimization if it yields a total function (which is the case since f is assumed to be total), we deduce that f is computable.

We can now tackle Diophantine sets. Assume that S is Diophantine so that there is a polynomial $P(x, y_1, \ldots, y_p)$ such that

$$a \in S$$
 iff $(\exists b_1, \ldots, b_p)(P(a, b_1, \ldots, b_p) = 0).$

As above, we can write

$$P(x, y_1, \dots, y_p) = Q(x, y_1, \dots, y_p) - R(x, y_1, \dots, y_p),$$

where $Q(x, y_1, \ldots, y_p)$ and $R(x, y_1, \ldots, y_p)$ have positive integer coefficients. Then we have

$$a \in S$$
 iff $(\exists b_1, \ldots, b_p)(Q(a, b_1, \ldots, b_p) = R(a, b_1, \ldots, b_p)),$

and by the sequence number theorem we can find $u \in \mathbb{N}$ such that $b_1 = S(1, u), \ldots, b_p = S(p, u)$, so

$$a \in S$$
 iff $(\exists u)(Q(a, S(1, u), \dots, S(p, u))) = R(a, S(1, u), \dots, S(p, u))).$

Since Q and R compute primitive recursive functions and S is primitive recursive, by Proposition 11.6, S is listable

The main theorem of the theory of Diophantine sets and functions is the following deep result.

Theorem 11.8. (Davis-Putnam-Robinson-Matiyasevich, 1970) Every total computable function is Diophantine. Every listable subset of \mathbb{N} is Diophantine.

Theorem 11.8 is often referred to as the *DPRM theorem*. A complete proof of Theorem 11.8 is provided in Davis [11]. We provide all the steps except the most technical one, the fact that the exponential function $h(n,k) = n^k$ is Diophantine.

Almost complete proof. As noted by Davis, although the proof is certainly long and nontrivial, it only uses elementary facts of number theory, nothing more sophisticated than the Chinese remainder theorem. Nevetherless, the proof is a tour de force.

One of the most difficult steps is to show that the exponential function $h(n,k) = n^k$ is Diophantine. This is done using the Pell equation. According to Martin Davis, the proof given in Davis [11] uses a combination of ideas from Matiyasevich and Julia Robinson. Matiyasevich's proof used the Fibonacci numbers.

We now provide details for all the steps of the proof, except the first one.

Step 1. The most difficult and most technical step is to prove that the exponential function $(n,k) \mapsto n^k$ is Diophantine. This involves proving twenty four "easy lemmas," which takes six pages (this is Section 2). The fact that the exponential function is Diophantine is established in Section 3; this is Theorem 3.3 (Section 3 has four pages).

There is a small issue, which is that Davis [11] assumes that all variables range over *positive integers*, so his proof that the exponential function $h(n, k) = n^k$ is Diophantine works only for n, k > 0. However, as in the 1976 survey paper by Davis, Matiyasevich and Robinson [12], we assume that the variables may take the value 0, that is, belong to \mathbb{N} . This problem is easily taken care of. If E is the set of Equations I-XII (with parameters) listed on Pages 244 and 247 of Davis [11] in which the variables (n, k, m) define the exponential function h in the sense that there are values of the parameters that satisfy E iff $m = h(n, k) = n^k$, create the new equation with the extra new parameters n', k', k'',

$$((n - n' - 1)^{2} + (k - k' - 1)^{2} + E^{2})(k^{2} + (m - 1)^{2})(n^{2} + (k - k'' - 1)^{2} + m^{2}) = 0.$$
(*)

The above equation has a solution with respect to the parameters iff

$$(n - n' - 1)^{2} + (k - k' - 1)^{2} + E^{2} = 0$$
(*1)

or

$$k^2 + (m-1)^2 = 0 \tag{(*2)}$$

or

$$n^{2} + (k - k'' - 1)^{2} + m^{2} = 0.$$
(*3)

The Equation $(*_1)$ is equivalent to

$$n = n' + 1$$
$$k = k' + 1$$
$$E = 0,$$

which are equivalent to

$$n > 0, \ k > 0, \ E = 0.$$
 (*4)

These equations have a solution in the parameters iff n, k > 0 and $m = n^k$.

The Equation $(*_2)$ is equivalent to

$$k = 0, \ m = 1,$$
 (*5)

which defines the exponential for k = 0 since $n^0 = 1$ for all $n \in \mathbb{N}$.

The Equation $(*_3)$ is equivalent to

$$n = 0$$

$$k = k'' + 1$$

$$m = 0,$$

which is equivalent to

$$n = 0, \ k > 0, \ m = 0,$$
 (*₆)

which define the exponential for n = 0 and k > 0 since $0^k = 0$ for all k > 0. In summary, the Equation (*) defines the exponential function $m = n^k$ for all $m, k \in \mathbb{N}$.

Step 2. Use the fact that the exponential is Diophantine to prove that two crucial functions are Diophantine:

$$f(n,k) = \binom{n}{k}$$
$$g(n) = n!.$$

This is proven in Theorem 4.1. We prove that the functions f and g are Diophantine provided that the exponential function is Diophantine in Section 11.7.

At this stage we know that the Diophantine relations are closed under conjunction, disjunction, and existential quantifiers. In order to prove that the Diophantine functions are closed under primitive recursion and minimization (if the function obtained by minimization is total) it is critical to prove closure under bounded universal quantification. This is the next step.

Step 3.

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Definition 11.7. Call a predicate (relation) φ a *Diophantine predicate* if it is of the form

$$\varphi(x_1,\ldots,x_n) \equiv (\exists y_1,\ldots,y_p)(P(x_1,\ldots,x_m,y_1,\ldots,y_p)=0)$$

where $P(x_1, \ldots, x_m, y_1, \ldots, y_p)$ is a polynomial with integer coefficients.

Of course, for any $(a_1, \ldots, a_m) \in \mathbb{N}^m$, $\varphi(a_1, \ldots, a_m)$ holds (equivalently $(a_1, \ldots, a_m) \in \varphi$) iff there is some $(b_1, \ldots, b_p) \in \mathbb{N}^p$ such that $P(a_1, \ldots, a_m, b_1, \ldots, b_p) = 0$.

It is convenient to abbreviate $(\exists y_1, \ldots, y_p)$ as $(\exists \overline{y})$. Given two Diophantine predicates $\varphi = (\exists \overline{u})(P(x_1, \ldots, x_m, \overline{u}) = 0)$ and $\psi = (\exists \overline{v})(Q(x_1, \ldots, x_m, \overline{v}) = 0)$ over the same variables x_1, \ldots, x_m , we define the predicates

$$\varphi \wedge \psi \equiv (\exists \overline{u})(P(x_1, \dots, x_m, \overline{u}) = 0) \wedge (\exists \overline{v})(Q(x_1, \dots, x_m, \overline{v}) = 0)$$

$$\varphi \vee \psi \equiv (\exists \overline{u})(P(x_1, \dots, x_m, \overline{u}) = 0) \vee (\exists \overline{v})(Q(x_1, \dots, x_m, \overline{v}) = 0)$$

$$\exists z \varphi \equiv \exists z (\exists \overline{u})(P(x_1, \dots, x_m, \overline{u}) = 0),$$

where z is any variable occurring or not in φ . We may rename variables so that \overline{u} and \overline{v} are disjoint and that z does not occur in \overline{u} .

The above predicates are Diophantine (using the squaring trick and the product trick) because

$$\varphi \wedge \psi \equiv (\exists \overline{u})(\exists \overline{v})(P(x_1, \dots, x_m, \overline{u})^2 + Q(x_1, \dots, x_m, \overline{v})^2 = 0)$$

$$\varphi \vee \psi \equiv (\exists \overline{u})(\exists \overline{v})(P(x_1, \dots, x_m, \overline{u})Q(x_1, \dots, x_m, \overline{v}) = 0)$$

$$\exists z \varphi \equiv \exists z (\exists \overline{u})(P(x_1, \dots, x_m, \overline{u}) = 0).$$

Observe that if $z = x_i$ for some variable x_i , then $m \ge 2$ and $\exists z\varphi$ is a predicate only involving the variables $x_1, \ldots, x_{i-1}, x_{i+1}, \ldots, x_m$, so that it defines a subset of \mathbb{N}^{m-1} . We will use these closure properties when constructing Diophantine predicates.

In general universal quantification applied to a Diophantine predicate does not yield a Diophantine predicate, but bounded universal quantification does.

Definition 11.8. Given a polynomial $P(y, z, x_1, \ldots, x_m, y_1, \ldots, y_p)$ with integer coefficients, the bounded existentially quantified predicate

$$(\exists z \le y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds iff for any $a_1, \ldots, a_m \in \mathbb{N}$ and any $b \in \mathbb{N}$, there is some $c \leq b$ and some $b_1, \ldots, b_p \in \mathbb{N}$ such that $P(b, c, a_1, \ldots, a_m, b_1, \ldots, b_p) = 0$ holds. The bounded universally quantified predicate

$$(\forall z \leq y)(\exists y_1, \ldots, y_p)(P(y, z, x_1, \ldots, x_m, y_1, \ldots, y_p) = 0)$$

holds iff for any $a_1, \ldots, a_m \in \mathbb{N}$ and any $b \in \mathbb{N}$, for every $c \leq b$, there are some $b_1, \ldots, b_p \in \mathbb{N}$ such that $P(b, c, a_1, \ldots, a_m, b_1, \ldots, b_p) = 0$ holds.

Proposition 11.9. Given a polynomial $P(y, z, x_1, \ldots, x_m, y_1, \ldots, y_p)$ with integer coefficients, the predicate

$$(\forall z \le y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds iff the predicate

$$(\exists u)(\forall z \le y)(\exists y_1 \le u) \cdots (\exists y_p \le u)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds.

Proof. The second statement obviously implies the first. If the predicate

$$(\forall z \le y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds, then for any $b \in \mathbb{N}$ and any $a_1, \ldots, a_m \in \mathbb{N}$, for each $k = 0, \ldots, b$, there exist $b_1^{(k)}, \ldots, b_p^{(k)} \in \mathbb{N}$ such that $P(b, k, a_1, \ldots, a_m, b_1^{(k)}, \ldots, b_p^{(k)}) = 0$ for $k = 0, \ldots, b$. If we pick

$$u = \max\{b_j^{(k)} \mid 0 \le k \le b, \ 1 \le j \le p\},\$$

then

$$(\exists u)(\forall z \leq y)(\exists y_1 \leq u) \cdots (\exists y_p \leq u)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds.

We have the following key theorem.

Theorem 11.10. (Bounded Quantifier Theorem) Given any polynomial $P(y, z, x_1, ..., x_m, y_1, ..., y_p)$ with integer coefficients, the bounded existentially quantified predicate

 $(\exists z \leq y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$

and the bounded universally quantified predicate

$$(\forall z \leq y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

are also Diophantine.

Recall that $x \leq y$ is Diophantine definable as y = x + x'. The first statement is easy to prove since

$$(\exists z \le y)(\exists y_1, \dots, y_p)(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0)$$

holds iff

$$(\exists z, y_1, \dots, y_p)[(P(y, z, x_1, \dots, x_m, y_1, \dots, y_p) = 0) \land (z \le y)].$$

The proof of the second statement is far more complicated. In particular is uses the fact that the factorial function $n \mapsto n!$ and the binomial $\binom{n}{k}$ are Diophantine (both of which use the fact that the exponential function $(n, k) \mapsto n^k$ is Diophantine). One proof is given in Davis [11]; see Theorem 5.1. A slightly shorter proof is given in Davis, Matiyasevich and Robinson [12]; see Section 4. Here is this crucial result and its very beautiful and clever proof.

Proposition 11.11. Let $P(x, y, k, z_1, ..., z_{\nu})$ be a polynomial with x, y and k among its parameters and $z_1, ..., z_{\nu}$ its variables. Then

$$(\forall k \le x)(\exists z_1 \le y) \cdots (\exists z_\nu \le y)(P(x, y, k, z_1, \dots, z_\nu) = 0)$$
([†]₁)

holds if and only if

$$(\exists b_1, \dots, b_{\nu}) \left[\begin{pmatrix} b_1 \\ y+1 \end{pmatrix} \equiv \dots \equiv \begin{pmatrix} b_{\nu} \\ y+1 \end{pmatrix} \equiv P(x, y, Q! - 1, b_1, \dots, b_{\nu}) \\ \equiv 0 \left(\mod \begin{pmatrix} Q! - 1 \\ x+1 \end{pmatrix} \right) \right] \quad (\dagger_2)$$

holds, where Q(x, y) is a polynomial such that

$$Q(x,y) > |P(x,y,k,z_1,\ldots,z_{\nu})| + 2x + y + 1, \qquad (*_1)$$

for all $k \leq x$ and all $z_1 \leq y, \ldots, z_{\nu} \leq y$. Also b_1, \ldots, b_{ν} may be chosen such that $b_i \leq \binom{Q!-1}{x+1}$. *Proof.* Consider the product

$$\binom{Q!-1}{x+1} = \frac{(Q!-1)!}{(x+1)!(Q!-1-(x+1))!} = \frac{(Q!-1)(Q!-2)\cdots(Q!-1-(x+1)+1)}{(x+1)!}$$
$$= (Q!-1)\left(\frac{Q!}{2}-1\right)\cdots\left(\frac{Q!}{x+1}-1\right).$$

Since $Q(x,y) > |P(x,y,k,z_1,\ldots,z_\nu)| + 2x + y + 1 \ge 2x + 2 > x + 1$, all the factors on the right-hand side are integers.

Claim 1. If a prime p divides $\binom{Q!-1}{x+1}$, then p > Q.

For this we prove that every prime $p \leq Q$ divides Q!/(k+1) for all $k \leq x$. Indeed, since $Q \geq 2x+2$ and $k \leq x$, we have $2(k+1) \leq 2x+2$, so

$$Q! = Q(Q-1)\cdots(2x+2)\cdots 2(k+1)\cdots(k+1)k!.$$

If p = k + 1, then k + 1 still occurs in Q!/(k + 1), and if $p \le Q$ and $p \ne k + 1$, then p occurs in Q!/(k + 1).

Now if a prime p divides $\binom{Q!-1}{x+1}$, then p divides some factor $\frac{Q!}{k+1} - 1$ (with $k \leq x$), so if $p \leq Q$, then from the previous fact p divides $\frac{Q!}{k+1}$, which implies that p divides 1, a contradiction.

Claim 2. Any two distinct factors $\frac{Q!}{i+1} - 1$ and $\frac{Q!}{j+1} - 1$ $(i, j \le x)$ are relatively prime.

If a prime p divides both $\frac{Q!}{i+1} - 1$ and $\frac{Q!}{j+1} - 1$, then $\frac{Q!}{i+1} - 1 = k_1 p$ and $\frac{Q!}{j+1} - 1 = k_2 p$ for some natural numbers k_1, k_2 , so

$$Q! - i - 1 = k_1(i+1)p, \quad Q! - j - 1 = k_2(j+1)p,$$

and by substraction

$$j - i = (k_1(i+1) - k_2(j+1))p_2$$

which means that p divides |j - i|. However, $i, j \leq Q$ and by Claim 1, p > Q, so i = j, which means that $\frac{Q!}{i+1} - 1$ and $\frac{Q!}{j+1} - 1$ $(i, j \leq x)$ are relatively prime if $i \neq j$.

Claim 3. If a prime p_k divides $\frac{Q!}{k+1} - 1$ $(k \le x)$, then

$$Q! - 1 \equiv k \pmod{p_k}.$$

Since $\frac{Q!}{k+1} - 1 = qp_k$ for some natural number q, we have $Q! - k - 1 = q(k+1)p_k$, so

$$Q! - 1 = k + q(k+1)p_k,$$

namely $Q! - 1 \equiv k \pmod{p_k}$.

Claim 4. For any choice of a prime p_k dividing $\frac{Q!}{k+1} - 1$ for $k \leq x$, we have

$$P(x, y, Q! - 1, b_1, \dots, b_{\nu}) \equiv P(x, y, k, \operatorname{Rem}(b_1, p_k), \dots, \operatorname{Rem}(b_{\nu}, p_k)) \pmod{p_k}, \ k \le x, \ (*_2)$$

where $\operatorname{Rem}(b_i, p_k)$ is the remainder of the division of b_i by p_k .

Claim 4 follows immediately from Claim 3 by taking residues modulo p_k in the polynomial $P(x, y, Q! - 1, b_1, \ldots, b_{\nu})$.

We are now ready for the proof itself.

Step a. First we prove that (\dagger_2) implies (\dagger_1) . Assume that there exists some natural numbers b_1, \ldots, b_{ν} such that

$$\binom{b_1}{y+1} \equiv \cdots \equiv \binom{b_\nu}{y+1} \equiv P(x, y, Q! - 1, b_1, \dots, b_\nu) \equiv 0 \left(\operatorname{mod} \binom{Q! - 1}{x+1} \right).$$

Since any chosen prime p_k dividing $\frac{Q!}{k+1} - 1$ also divides divides $\binom{Q!-1}{x+1}$, we deduce from the congruence

$$\binom{b_i}{y+1} \equiv 0 \left(\mod \binom{Q!-1}{x+1} \right)$$

that p_k divides $b_i(b_i - 1) \cdots (b_i - y)$ for $i = 1, \dots, \nu$, so p_k divides some factor $b_i - h$ with $h \leq y$, which implies that $\text{Rem}(b_i, p_k) \leq y$ for $i = 1, \dots, \nu$. By $(*_1)$ and Claim 1, we have

$$|P(x, y, k, \operatorname{Rem}(b_1, p_k), \dots, \operatorname{Rem}(b_\nu, p_k))| \le Q < p_k.$$
(*3)

By hypothesis, since p_k divides $\binom{Q!-1}{x+1}$, we have

$$P(x, y, Q! - 1, b_1, \dots, b_\nu) \equiv 0 \pmod{p_k},$$

for all $k \leq x$, and by $(*_2)$ and $(*_3)$, we deduce that

$$P(x, y, k, \operatorname{Rem}(b_1, p_k), \dots, \operatorname{Rem}(b_\nu, p_k)) = 0,$$

which is (\dagger_1) of our proposition with $z_i = \text{Rem}(b_i, p_k)$. Step b. Now we prove that (\dagger_i) implies (\dagger_i) . Suppose that there are

Step b. Now we prove that (\dagger_1) implies (\dagger_2) . Suppose that there are some natural numbers $z_{1k} \leq y, \ldots, z_{\nu k} \leq y$ such that

$$P(x, y, k, z_{1k}, \dots, z_{\nu k}) = 0, \text{ for all } k \le x.$$
 (*4)

Since there are finitely many tuples of natural numbers $(k, z_1, \ldots, z_{\nu})$ such that $k \leq x$ and $z_i \leq y$ for $i = 1, \ldots, \nu$, we can find a polynomial Q(x, y) satisfying $(*_1)$. For example, we can choose Q(x, y) = 2x + y + 2 + C, for $C \geq 0$ large enough. By Claim 2, since the distinct factors $\frac{Q!}{i+1} - 1$ and $\frac{Q!}{j+1} - 1$ $(i, j \leq x)$ are relatively prime, by the Chinese remainder theorem (Theorem 11.4) there exist $b_1, \ldots, b_{\nu} < \binom{Q!-1}{x+1}$ such that

$$b_i \cong z_{ik} \left(\mod \frac{Q!}{k+1} - 1 \right), \quad k \le x.$$
 (*5)

Since $z_{ik} \leq y$, one of the factors in the product $z_{ik}(z_{ik}-1)\cdots(z_{ik}-y)$ is zero, so $(*_5)$ implies that

$$b_i(b_i - 1) \cdots (b_i - y) \cong 0 \left(\mod \frac{Q!}{k+1} - 1 \right), \quad 1 \le i \le \nu.$$
 (*6)

By Claim 2, since the divisors $\frac{Q!}{k+1} - 1$ are pairwise relatively prime, their product $\binom{Q!-1}{x+1}$ divides $b_i(b_i-1)\cdots(b_i-y)$, that is,

$$b_i(b_i-1)\cdots(b_i-y) \equiv 0\left(\operatorname{mod}\binom{Q!-1}{x+1}\right), \quad 1 \le i \le \nu, x \le k.$$

By Claim 1 and $(*_1)$, since all the primes dividing $\binom{Q!-1}{x+1}$ $(k \leq x)$ are greater than Q > y+1, we deduce that

$$\binom{b_i}{y+1} \equiv 0 \left(\mod \binom{Q!-1}{x+1} \right), \quad 1 \le i \le \nu.$$
 (*7)

Finally, since

$$Q! - 1 - k = (k+1)\left(\frac{Q!}{k+1} - 1\right)$$

we have

$$Q! - 1 \equiv k \left(\mod \frac{Q!}{k+1} - 1 \right),$$

so by $(*_5)$, we have

$$P(x, y, Q! - 1, b_1, \dots, b_{\nu}) \equiv P(x, y, k, z_{1k}, \dots, z_{\nu k}) \left(\mod \frac{Q!}{k+1} - 1 \right).$$
(*8)

Since by hypothesis (*4), $P(x, y, k, z_{1k}, ..., z_{\nu k}) = 0$, and the moduli $\frac{Q!}{k+1} - 1$ are pairwise relatively prime, we conclude that

$$P(x, y, Q! - 1, b_1, \dots, b_{\nu}) \equiv 0 \left(\mod \begin{pmatrix} Q! - 1 \\ x + 1 \end{pmatrix} \right).$$
(*9)

But $(*_7)$ and $(*_9)$ are the conjuncts in (\dagger_2) of our proposition, and this finishes the proof. \Box

Since by Step 2 the factorial function and the binomial coefficient functions are Diophantine, and since the divisibility relation $n \equiv 0 \pmod{m}$ is Diophantine (since $n \equiv 0 \pmod{m}$) iff $(\exists k)(n = km)$), the right-hand side (\dagger_2) in Proposition 11.11 is Diophantine. This proves the hard part of Theorem 11.10, namely that applying bounded universal quantification to a Diophantine predicate yields a Diophantine predicate.

Davis et al. [12] (Section 4) show how Theorem 11.10 can be used to construct a Diophantine polynomial F with one parameter a such that the equation F = 0 has a solution for any fixed a > 0 iff some planar graph *cannot* be colored with a colors. The positive solution of the four color conjecture implies that the equation F = 0 has no solution for a = 4 (for sure, it has no solution for a = 5).

We have completed the hard work and the next step is relatively simple in comparison.

Step 4. To prove that every (total) computable function is Diophantine, we simply have to prove that the base functions are Diophantine and that the Diophantine functions are closed under (extended) composition, primitive recursion, and minimization (yielding total functions). Since the class of computable functions is the smallest class with these properties, it is contained in the class of Diophantine functions.

(1) The zero function y = Z(x) is defined by the Diophantine equation

y = 0.

The successor function $y = \mathbf{Succ}(x) = x + 1$ is defined by the Diophantine equation

y = x + 1.

The projection function $y = P_i^n(x_1, \ldots, x_n)$ is defined by the Diophantine equation

 $y = x_i$.

(2) Suppose that the *m* functions $g_i \colon \mathbb{N}^n \to \mathbb{N}$ are Diophantine and that $f \colon \mathbb{N}^m \to \mathbb{N}$ is also Diophantine. This means that each g_i has a Diophantine definition

$$(\exists \overline{y}_i)(P_i(x_1,\ldots,x_n,z_i,\overline{y}_i)=0)$$

which holds iff $z_i = g_i(x_1, \ldots, x_n)$, where \overline{y}_i denotes a sequence of parameters, and f has a Diophantine definition

$$(\exists \overline{t})(Q(u_1,\ldots,u_m,v,\overline{t})=0)$$

which holds iff $v = f(u_1, \ldots, v_m)$, where \overline{t} denotes a sequence of parameters. By renaming the parameters we may assume that they are disjoint and also disjoint from the variables \overline{z} . Then the Diophantine definition

$$(\exists \overline{z})(\exists \overline{y}_1) \cdots (\exists \overline{y}_m)(\exists \overline{t})[(P_1(x_1, \dots, x_n, z_1, \overline{y}_1) = 0) \land \dots \land (P_m(x_1, \dots, x_n, z_m, \overline{y}_m) = 0) \land (Q(z_1, \dots, z_m, v, \overline{t}) = 0)]$$

holds iff

$$v = f(g_1(x_1, \ldots, x_n), \ldots, g_m(x_1, \ldots, x_n)).$$

We can use the squaring trick to convert the conjunction of equations into a single equation. This proves closure under composition.

(3) Suppose $g: \mathbb{N}^m \to \mathbb{N}$ and $h: \mathbb{N}^{m+2} \to \mathbb{N}$ are Diophantine. We wish to define $f: \mathbb{N}^{m+1} \to \mathbb{N}$ by primitive recursion by

$$f(0, x_1, \dots, x_m) = g(x_1, \dots, x_m)$$

$$f(x+1, x_1, \dots, x_m) = h(x, f(x, x_1, \dots, x_m), x_1, \dots, x_m).$$

This is achieved using the sequence number theorem and the bounded quantifier theorem as follows. Assume that g has a Diophantine definition

$$(\exists \overline{s})(P(x_1,\ldots,x_m,v,\overline{s})=0)$$

which holds iff $v = g(x_1, \ldots, x_m)$, where \overline{s} denotes a sequence of parameters, and h has a Diophantine definition

$$(\exists \overline{z})(Q(t_1, t_2, x_1, \dots, x_m, w, \overline{z}) = 0)$$

which holds iff $w = h(t_1, t_2, x_1, \ldots, x_m)$, where \overline{z} denotes a sequence of parameters. We rename variables so that \overline{s} and \overline{z} are disjoint. Theorem 11.7 shows that S is Diophantine, so we claim that the Diophantine definition

$$\exists u \left[\exists v \left((v = S(1, u)) \land (\exists \overline{s}) (P(x_1, \dots, x_m, v, \overline{s}) = 0) \right) \\ \land (\forall t \le x) [(t = x) \lor \exists w ((w = S(t + 2, u)) \\ \land (\exists \overline{z}) (Q(t, S(t + 1, u), x_1, \dots, x_m, w, \overline{z}) = 0))] \\ \land (y = S(x + 1, u))]$$

holds iff

$$y = f(x, x_1, \dots, x_m).$$

We used the fact that the Diophantine predicates are closed under conjunction, disjunction, existential quantification, and composition. The equations v = S(1, u), w = S(t + 2, u) and y = S(x + 1, u) should be replaced by the Diophantine definition of S from Theorem 11.7, and the equation $Q(t, S(t + 1, u), x_1, \ldots, x_m, w, \overline{z}) = 0$ involves a composition so it should also use the Diophantine definition of S. We leave the details and the verification that this works to the reader. The idea is that u is used to record the values $f(0, x_1, \ldots, x_m), \ldots, f(x, x_1, \ldots, x_m)$ as $S(1, u), \ldots, S(x + 1, u)$. Since in Theorem 11.7 the index i used to index sequences starts from 1 and not 0, as t ranges from 0 to x have to use the index t + 1 which ranges from 1 to x + 1. This is also the reason why we have to compute $S(t + 2, u) = f(t + 1, x_1 \ldots, x_m)$ from $S(t + 1, u) = f(t, x_1, \ldots, x_m)$. Since $A \implies B$ is logically equivalent to $\neg A \lor B$, the formula

$$(\forall t \le x)[(t=x) \lor \exists w((w=S(t+2,u)) \land (\exists \overline{z})(Q(t,S(t+1,u),x_1,\ldots,x_m,w,\overline{z})=0))]$$

asserts that for all t such that $0 \le t \le x$, if $t \ne x$, so in fact if $0 \le t < x$, then

$$[\exists w((w = S(t+2, u)) \land (\exists \overline{z})(Q(t, S(t+1, u), x_1, \dots, x_m, w, \overline{z}) = 0))]$$

holds. Since $S(t+1, u) = f(t, x_1, \dots, x_m)$, the Diophantine definition

$$(\exists \overline{z})(Q(t, S(t+1, u), x_1, \dots, x_m, w, \overline{z}) = 0))]$$

computes $w = h(t, f(t, x_1, ..., x_m), x_1, ..., x_m) = f(t+1, x_1, ..., x_m)$, which is saved in S(t+2, u).

(4) Assume that $g: \mathbb{N}^{m+1} \to \mathbb{N}$ is Diophantine and that for all $(a_1, \ldots, a_m) \in \mathbb{N}^m$ there is some $a \in \mathbb{N}$ such that $g(a, a_1, \ldots, a_m) = 0$. We wish to show that the function $f: \mathbb{N}^m \to \mathbb{N}$ given by minimization as

$$f(a_1,\ldots,a_m) = \min x \left(g(x,a_1,\ldots,a_m) = 0\right)$$

is also Diophantine. Assume that g has a Diophantine definition

$$(\exists \overline{s})(P(x, x_1, \dots, x_m, z, \overline{s}) = 0)$$

which holds iff $z = g(x, x_1, \ldots, x_m)$, where \overline{s} denotes a sequence of parameters. We claim that the Diophantine definition

$$(\exists \overline{s})(P(y, x_1, \dots, x_m, 0, \overline{s}) = 0) \land [(\forall t \le y)[(t = y) \lor \exists z (\exists \overline{u}) ((P(t, x_1, \dots, x_m, z, \overline{u}) = 0) \land (z > 0)]]$$

holds if

$$y = f(a_1, \dots, a_m) = \min x (g(x, a_1, \dots, a_m)) = 0).$$

The predicate

$$(\exists \overline{s})(P(y, x_1, \dots, x_m, 0, \overline{s}) = 0)$$

asserts that $g(y, x_1, \ldots, x_m) = 0$, and the predicate

$$(\forall t \le y)[(t=y) \lor \exists z (\exists \overline{u}) ((P(t, x_1, \dots, x_m, z, \overline{u}) = 0) \land (z > 0)]$$

asserts that $g(t, x_1, \ldots, x_m) > 0$ for all t < y, so y is indeed the smallest number for which $g(y, x_1, \ldots, x_m) = 0$.

Therefore we have finally proven that every (total) computable function is Diophantine.

Step 5. Every listable set is Diophantine.

By Proposition 11.6, a set $S \subseteq \mathbb{N}$ is listable iff there are two (total) computable functions $f, g: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$ such that

$$S = \{a \in \mathbb{N} \mid (\exists x)(f(a, x) = g(a, x))\}.$$

But then

$$a \in S$$
 iff $\exists x \exists z ((z = f(a, x)) \land (z = g(a, x)))$

By Step 4, the computable functions f and g have Diophantine definitions

$$(\exists \overline{u})(P(y, x, z, \overline{u}) = 0)$$

iff z = f(y, x) and

$$(\exists \overline{v})(Q(y, x, z, \overline{v}) = 0)$$

iff z = g(y, x), so $a \in S$ has the Diophantine definition

$$\exists x \exists z [(\exists \overline{u})(P(a, x, z, \overline{u}) = 0) \land (\exists \overline{v})(Q(a, x, z, \overline{v}) = 0)].$$

This is the famous result that we were seeking.

Using some results from the theory of computation it is now easy to deduce that Hilbert's tenth problem is undecidable. To achieve this, recall that there are listable sets that are not computable. For example, it is shown in Lemma 9.11 that $K = \{x \in \mathbb{N} \mid \varphi_x(x) \text{ is defined}\}$ is listable but not computable. Since K is listable, by Theorem 11.8, it is defined by some Diophantine equation

$$P(a, x_1, \ldots, x_n) = 0,$$

which means that

$$K = \{a \in \mathbb{N} \mid (\exists x_1 \dots, x_n) (P(a, x_1, \dots, x_n) = 0)\}.$$

We have the following strong form of the undecidability of Hilbert's tenth problem, in the sense that it shows that Hilbert's tenth problem is already undecidable for a fixed Diophantine equation in one parameter.

Theorem 11.12. There is no algorithm which takes as input the polynomial $P(a, x_1, ..., x_n)$ defining K and any natural number $a \in \mathbb{N}$ and decides whether

$$P(a, x_1, \ldots, x_n) = 0.$$

Consequently, Hilbert's tenth problem is undecidable.

Proof. If there was such an algorithm, then K would be decidable, a contradiction.

Any algorithm for solving Hilbert's tenth problem could be used to decide whether or not $P(a, x_1, \ldots, x_n) = 0$, but we just showed that there is no such algorithm.

It is an open problem whether Hilbert's tenth problem is undecidable if we allow *rational* solutions (that is, $x_1, \ldots, x_n \in \mathbb{Q}$).

Alexandra Shlapentokh proved that various extensions of Hilbert's tenth problem are undecidable. These results deal with some algebraic number theory beyond the scope of these notes. Incidentally, Alexandra was an undergraduate at Penn, and she worked on a logic project for me (finding a Gentzen system for a subset of temporal logic).

Having now settled once and for all the undecidability of Hilbert's tenth problem, we now briefly explore some interesting consequences of Theorem 11.8.

The fact that a set is listable if and only if it is Diophantine also holds for *m*-ary relations.

11.6 The DPRM For Relations

Definition 11.9. A relation $R \subseteq \mathbb{N}^m$ $(m \ge 2)$ is *listable* if the set

$$\widehat{R} = \{ \langle x_1, \dots, x_m \rangle_m \in \mathbb{N} \mid (x_1, \dots, x_m) \in R \}$$

is listable, where $\langle x_1, \ldots, x_m \rangle_m$ is the extended pairing function of Definition 8.2.

Proposition 11.6 is easily generalized to the following characterization of listable relations.

Proposition 11.13. A relation $R \subseteq \mathbb{N}^m$ $(m \geq 2)$ is listable iff there are two (total) computable functions $f, g: \mathbb{N}^{m+1} \to \mathbb{N}$ such that

$$R = \{ (a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists x) (f(a_1, \dots, a_m, x)) = g(a_1, \dots, a_m, x) \} \}.$$

Proof. If $R = \emptyset$, then we let f be the constant function equal to 0 and g be the constant function equal to 1. If $R \neq \emptyset$ is listable, then by Definition 9.6 (see also Proposition 9.9), there is a total computable function $h: \mathbb{N} \to \mathbb{N}$ such that \widehat{R} is equal to the range of h. If we let f be given by $f(a_1, \ldots, a_m, x) = \langle a_1, \ldots, a_m \rangle_m$ (which is primitive recursive) and $g(a_1, \ldots, a_m, x) = h(x)$ for all $a, x \in \mathbb{N}$, then

$$R = \{ (a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists x) (\langle a_1, \dots, a_m \rangle_m = h(x)) \} \\ = \{ (a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists x) (f(a_1, \dots, a_m, x) = g(a_1, \dots, a_m, x)) \}.$$

Conversely, assume that

$$R = \{(a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists x) (f(a_1, \dots, a_m, x)) = g(a_1, \dots, a_m, x))\}$$

with f, g total computable. Using the uniform projection function Π of Definition 8.3, which is primitive recursive, we have

$$\widehat{R} = \{ a \in \mathbb{N} \mid (\exists x) (f(\Pi(1, m, a), \dots, \Pi(m, m, a), x) = g(\Pi(1, m, a), \dots, \Pi(m, m, a), x)) \}.$$

As a composition of (total) computable functions, \hat{f} and \hat{g} given by

$$\hat{f}(a,x) = f(\Pi(1,m,a),\dots,\Pi(m,m,a),x) \hat{g}(a,x) = g(\Pi(1,m,a),\dots,\Pi(m,m,a),x)$$

are total computable, so by Proposition 11.6 the set \hat{R} is listable.

Using Proposition 11.13 it is easy to generalize the DPRM to relations.

Theorem 11.14. (DPRM for Relations) A relation $R \subseteq \mathbb{N}^m$ ($m \ge 2$) is listable if and only if it is Diophantine.

Proof. Assume that R is Diophantine so that there is a polynomial $P(x_1, \ldots, x_m, y_1, \ldots, y_p)$ such that

 $(a_1, \dots, a_m) \in R$ iff $(\exists b_1, \dots, b_p)(P(a_1, \dots, a_m, b_1, \dots, b_p) = 0).$

By grouping monomials with the same sign together we can write

$$P(x_1, ..., x_m, y_1, ..., y_p) = Q(x_1, ..., x_m, y_1, ..., y_p) - R(x_1, ..., x_m, y_1, ..., y_p),$$

where $Q(x_1, \ldots, x_m, y_1, \ldots, y_p)$ and $R(x_1, \ldots, x_m, y_1, \ldots, y_p)$ have positive integer coefficients. Then we have

$$(a_1, \dots, a_m) \in R$$
 iff $(\exists b_1, \dots, b_p)(Q(a_1, \dots, a_m, b_1, \dots, b_p) = R(a_1, \dots, a_m, b_1, \dots, b_p)),$

and by the sequence number theorem we can find $u \in \mathbb{N}$ such that $b_1 = S(1, u), \ldots, b_p = S(p, u)$, so

$$(a_1, \dots, a_m) \in R$$
 iff $(\exists u)(Q(a_1, \dots, a_m, S(1, u), \dots, S(p, u)))$
= $R(a_1, \dots, a_m, S(1, u), \dots, S(p, u))).$

Since Q and R compute primitive recursive functions and S is primitive recursive, by Proposition 11.13, R is listable.

Conversely, assume that R is listable. By Proposition 11.13, a relation $R \subseteq \mathbb{N}^m$ is listable iff there are two (total) computable functions $f, g: \mathbb{N}^{m+1} \to \mathbb{N}$ such that

$$R = \{ (a_1, \dots, a_m) \in \mathbb{N}^m \mid (\exists x) (f(a_1, \dots, a_m, x) = g(a_1, \dots, a_m, x)) \}.$$

But then

$$(a_1,\ldots,a_m) \in R \quad \text{iff} \quad \exists x \exists z ((z = f(a_1,\ldots,a_m,x)) \land (z = g(a_1,\ldots,a_m,x))).$$

By Theorem 11.8, the computable functions f and g have Diophantine definitions and we finish the proof as in Step 5 of Theorem 11.8 to obtain a Diophantine definition of R.

11.7 Some Applications of the DPRM Theorem

The first application of the DRPM theorem is a particularly striking way of defining the listable subsets of \mathbb{N} as the nonnegative ranges of polynomials with integer coefficients. This result is due to Hilary Putnam.

Theorem 11.15. For every listable subset S of \mathbb{N} , there is some polynomial $Q(x, x_1, \ldots, x_n)$ with integer coefficients such that

$$S = \{Q(a, b_1, \dots, b_n) \mid Q(a, b_1, \dots, b_n) \in \mathbb{N}, a, b_1, \dots, b_n \in \mathbb{N}\}.$$

Proof. By the DPRM theorem (Theorem 11.8), there is some polynomial $P(x, x_1, \ldots, x_n)$ with integer coefficients such that

$$S = \{a \in \mathbb{N} \mid (\exists x_1, \dots, x_n) (P(a, x_1, \dots, x_n) = 0)\}.$$

Let $Q(x, x_1, \ldots, x_n)$ be given by

$$Q(x, x_1, \dots, x_n) = (x+1)(1 - P^2(x, x_1, \dots, x_n)) - 1.$$

We claim that Q satisfies the statement of the theorem. If $a \in S$, then $P(a, b_1, \ldots, b_n) = 0$ for some $b_1, \ldots, b_n \in \mathbb{N}$, so

$$Q(a, b_1, \dots, b_n) = (a+1)(1-0) - 1 = a.$$

This shows that all $a \in S$ show up the the nonnegative range of Q. Conversely, assume that $Q(a, b_1, \ldots, b_n) \ge 0$ for some $a, b_1, \ldots, b_n \in \mathbb{N}$. Then by definition of Q we must have

$$(a+1)(1-P^2(a,b_1,\ldots,b_n))-1 \ge 0,$$

that is,

$$(a+1)(1-P^2(a,b_1,\ldots,b_n)) \ge 1,$$

and since $a \in \mathbb{N}$, this implies that $P^2(a, b_1, \ldots, b_n) < 1$, but since P is a polynomial with integer coefficients and $a, b_1, \ldots, b_n \in \mathbb{N}$, the expression $P^2(a, b_1, \ldots, b_n)$ must be a nonnegative integer, so we must have

0,

$$P(a, b_1, \ldots, b_n) =$$

which shows that $a \in S$.

Remark: It should be noted that in general, the polynomials Q arising in Theorem 11.15 may take on negative integer values, and to obtain all listable sets, we must restrict ourself to their nonnegative range.

As an example, the set S_3 of natural numbers that are congruent to 1 or 2 modulo 3 is given by

$$S_3 = \{ a \in \mathbb{N} \mid (\exists y)(3y + 1 - a^2 = 0) \}.$$
so by Theorem 11.15, S_3 is the nonnegative range of the polynomial

$$Q(x,y) = (x+1)(1 - (3y+1-x^2)^2)) - 1$$

= -(x+1)((3y-x^2)^2 + 2(3y-x^2))) - 1
= (x+1)(x^2 - 3y)(2 - (x^2 - 3y)) - 1.

Observe that Q(x, y) takes on negative values. For example, Q(0, 0) = -1. Also, in order for Q(x, y) to be nonnegative, $(x^2 - 3y)(2 - (x^2 - 3y))$ must be positive, but this can only happen if $x^2 - 3y = 1$, that is, $x^2 = 3y + 1$, which is the original equation defining S_3 .

There is no miracle. The nonnegativity of $Q(x, x_1, \ldots, x_n)$ must subsume the solvability of the equation $P(x, x_1, \ldots, x_n) = 0$.

A particularly interesting listable set is the set of primes. By Theorem 11.15, in theory, the set of primes is the positive range of some polynomial with integer coefficients.

Remarkably, some explicit polynomials have been found. This is a nontrivial task. In particular, the process involves showing that the exponential function is definable, which was the stumbling block to the completion of the DPRM theorem for many years.

We now explain how to express primality in terms of equations, provided that we allow free uses of the exponential function. The key idea is to express primality using the Bezout identity (Proposition 11.2). We will obtain a set of equations involving the function factorial (s!). The factorial function can be equationally defined using the binomial coefficient $\binom{t}{s}$, which in turn can be defined equationally in terms of the exponential function. This is as far as we will go, since proving that the exponential function is Diophantine definable is a long and complicated process.

Recall that Proposition 11.2 (the Bezout identity) implies that for any two integers $m, n \in \mathbb{Z}$, if d = gcd(m, n), then there are some integers $a, b \in \mathbb{Z}$ such that

$$am + bn = d$$

If both m, n > 0, then d > 0, so if we write $m = q_1 d$ and $n = q_2 d$ (with $q_1, q_2 \in \mathbb{N}$), then for any $k \in \mathbb{Z}$ we also have

$$(a+kq_2)m + (b-kq_1)n = am + bn + kq_2m - kq_1n = am + bn + kq_2q_1d - kq_1q_2d = am + bn = d.$$

As a consequence, if a < 0, in which case we must have b > 0, we can pick $k \in \mathbb{Z}$ large enough so that $a + kq_2 \ge 0$ and $b - kq_1 \le 0$, that is $kq_2 \ge -a$ and $kq_1 \ge b$, so $k \ge \max(-a, b)$ will do. Therefore, if m > 0 and n > 0, we may assume that $a \ge 0$ and $b \le 0$, or equivalently that the equation

$$am - bn = d$$
 (*_B)

holds for some $a, b \in \mathbb{N}$.

Remark: By picking $k > \max(-a, b)$ we can ensure that a > 0 and b < 0 in am + bn = d, but we don't need this stronger condition. Also, if m = 0 and n > 0, or m > 0 and n = 0, the condition $(*_B)$ needs to be replaced by

$$am - bn = d$$
 or $bn - am = d$,

for some $m, n \in \mathbb{N}$.

Now m, n > 0 are relatively prime iff gcd(d) = 1, which by the Bezout identity and the above discussion is equivalent to the fact that the equation

$$am - bn = 1$$

has a solution for some $m, n \in \mathbb{N}$. We can now apply this fact to assert that a number p is prime.

Observe that by the Bezout identity, if p = s + 1 and q = s!, then we can assert that p and q are relatively prime (gcd(p,q) = 1) as the fact that the Diophantine equation

$$ap - bq = 1$$

is satisfied for some $a, b \in \mathbb{N}$. Then $p \in \mathbb{N}$ is prime iff $p \ge 2$ and p has no divisor h such that 1 < h < p iff $p \ge 2$ and gcd(p,q) = gcd(p,(p-1)!) = 1. We leave the details an an exercise.

Then it is not hard to see that $p \in \mathbb{N}$ is prime iff the following set (P) of equations has a solution for $a, b, s, r, q \in \mathbb{N}$:

$$p = s + 1$$

$$p = r + 2$$

$$q = s!$$

$$ap - bq = 1.$$
(P)

The problem with the above is that the equation q = s! is not Diophantine. The next step is to show that the factorial function is Diophantine, and this involves a lot of work. One way to proceed is to show that the above system is equivalent to a system allowing the use of the exponential function $exp(m, n) = m^n$.

The first trick is express the factorial function in terms of the exponential function and the binomial coefficient. Indeed, for $t \ge s \in \mathbb{N}$ (with $s \ge 1$ fixed), since

$$\binom{t}{s} = \frac{t!}{s!(t-s)!} = \frac{t(t-1)\cdots(t-s+1)}{s!},$$

we have

$$s! = \frac{t(t-1)\cdots(t-s+1)}{\binom{t}{s}}.$$

For s = 1 we have

$$s! = \frac{t^1}{\binom{t}{1}}$$

since 1! = 1 and

$$\frac{t^1}{\binom{t}{1}} = \frac{t}{t} = 1.$$

For $s \ge 2$, if we replace every term in the product in the numerator by t, we deduce that

$$s! \le \frac{t^s}{\binom{t}{s}} = \frac{s!t^s}{t(t-1)\cdots(t-s+1)} \\ = s! \left(1 + \frac{1}{t-1}\right)\cdots\left(1 + \frac{s-1}{t-s+1}\right).$$

Observe that if let t go to infinity, then for $k = 1, \ldots, s - 1$

$$\lim_{t \to \infty} \left(1 + \frac{k}{t-k} \right) = 1,$$

which implies that

$$\lim_{t \to \infty} \left(1 + \frac{1}{t-1} \right) \cdots \left(1 + \frac{s-1}{t-s+1} \right) = 1,$$

and so

$$\lim_{t \to \infty} \frac{t^s}{\binom{t}{s}} = s!.$$

More precisely, it is not hard to see that if $t \ge 2s^{s+2}$, then

$$\left(1+\frac{1}{t-1}\right)\cdots\left(1+\frac{s-1}{t-s+1}\right) \le 1+\frac{1}{s^{s-1}},$$

with $s^{s-1} > s!$ (since $s \ge 2$), and so

$$s! = \left\lfloor \frac{t^s}{\binom{t}{s}} \right\rfloor = q, \qquad (*!)$$

where q the largest natural number (the floor) such that

$$q \le \frac{t^s}{\binom{t}{s}} < q+1.$$

As we already know, the above formula also holds for s = 1. But then after some thinking we can show that q = s! is equivalent to the following equations (where all the variables range over \mathbb{N}):

$$t = 2s^{s+2} \tag{1}$$

$$t^s = qu + w \tag{2}$$

$$u = \begin{pmatrix} t \\ s \end{pmatrix} \tag{3}$$

$$u = w + x + 1. \tag{4}$$

For s = 0, since $0^2 = 0$, the first equation yields t = 0, and then by the third equation, $u = \begin{pmatrix} 0 \\ 0 \end{pmatrix} = 1$. The fourth equation forces w = x = 0. Since $0^0 = 1$, the second equation yields q = 1, which is indeed 0!.

Let us now assume that $s \ge 1$. From (2) and (3) we have

$$q = \frac{t^s}{\binom{t}{s}} - \frac{w}{\binom{t}{s}},$$

 \mathbf{SO}

$$q \le \frac{t^s}{\binom{t}{s}}.$$

By (2) and (4) we have

$$t^{s} = qu + w = qu + u - x - 1 = (q+1)u - x - 1,$$

so using (3) we get

$$q+1 = \frac{t^s}{\binom{t}{s}} + \frac{x+1}{\binom{t}{s}},$$

which implies that

$$\frac{t^s}{\binom{t}{s}} < q+1,$$

and since by (1), $t = 2s^{s+2}$, we get

$$q = \left\lfloor \frac{t^s}{\binom{t}{s}} \right\rfloor = s!$$

This astute maneuver shows that s! is equationally definable if we allow the exponential function $exp(m, n) = m^n$ and the binomial coefficient $\binom{t}{s}$.

Actually, another trick shows that the binomial coefficients are definable in terms of the exponential function too. Since

$$(y+1)^t = \sum_{i=0}^t \binom{t}{i} y^i,$$

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if y is large enough, in fact $y > 2^t$ will do, then it turns out that the binomial coefficients $\binom{t}{i}$ are the digits in the expansion of $(y+1)^t$ in base y.

We claim that $u = {t \choose s}$ is equivalent to the following system of equations (where all the variables range over \mathbb{N}):

$$y = 2^t + 1 \tag{5}$$

$$z = y + 1 \tag{6}$$

$$z^t = \ell y^{s+1} + u y^s + m \tag{7}$$

$$u + v = 2^t \tag{8}$$

$$m+n+1 = y^s. (9)$$

If t = 0, then Equations (5) and (6) yield y = 2, z = 3. Equation (7) yields

$$1 = \ell 2^{s+1} + u 2^s + m$$

Since $y^{s+1} = 2^{s+1} \ge 2$, we must have $\ell = 0$.

If s = 0, then $y^s = 2^0 = 1$ and Equation (9) yields m + n + 1 = 1, so m = n = 0. We have $2^t = 2^0 = 1$, so Equation (7) implies that u = 1, and then v = 0. We get $\binom{0}{0} = u = 1$, as desired.

If $s \ge 1$, then $y^s = 2^s \ge 2$, so we must have u = 0. Then Equation (9) implies that m = 1, and then $n = 2^s - 1$ and v = 1. We get $\binom{0}{s} = u = 0$, as desired.

If $t \ge 1$ and s > t, we claim that $y > 2^t$ implies that $(y+1)^t < y^s$. This is because

$$(y+1)^t < (y+y)^t = (2y)^t = 2^t y^t < y^{t+1}$$

Assume that $t \ge 1$ and s > t. Since z = y + 1 and the equation $y = 2^t + 1$ implies that $y > 2^t$, the equation

$$(y+1)^t = z^t = \ell y^{s+1} + uy^s + m$$

and the fact that $(y+1)^t < y^s$ implies that $\ell = u = 0$. Then $m = (y+1)^t$, $v = 2^t$, and $n = y^s - (y+1)^t - 1$, which is a natural number since $(y+1)^t < y^s$. Therefore $\binom{t}{s} = u = 0$ if $1 \le t < s$, as desired.

Finally, assume that $t \ge 1$ and $0 \le s \le t$. Using the binomial formula, we have

$$(y+1)^{t} = \sum_{k=0}^{t} {t \choose t-k} y^{t-k}$$

= $\sum_{k=0}^{t-s-1} {t \choose t-k} y^{t-k} + {t \choose s} y^{s} + \sum_{k=t-s+1}^{t} {t \choose t-k} y^{t-k}$
= $\left(\sum_{k=0}^{t-s-1} {t \choose t-k} y^{t-s-1-k}\right) y^{s+1} + {t \choose s} y^{s} + \sum_{k=t-s+1}^{t} {t \choose t-k} y^{t-k}.$

The equation $y = 2^t + 1$ implies that $y > 2^t$, and since $\binom{t}{k} \le 2^t < y$ (because of the well-known identity $\sum_{k=0}^t \binom{t}{k} = 2^t$), we deduce that $\binom{t}{s}$ is the coefficient of y^s in the representation of $(y+1)^t$ in base $y > 2^t$. Consequently, the unique solutions of the equation

$$(y+1)^t = z^t = \ell y^{s+1} + uy^s + m$$

are

$$m = \sum_{k=t-s+1}^{t} {t \choose t-k} y^{t-k}$$
$$u = {s \choose t}$$
$$\ell = \sum_{k=0}^{t-s-1} {t \choose t-k} y^{t-s-1-k}$$

Since they appear in the representation of $(y + 1)^t$ in base y, the numbers u and v satisfy the inequalities

$$m < y^s$$
$$u \le 2^t$$

so the equations

$$u + v = 2^t$$
$$m + n + 1 = y^s$$

are satisfied. Therefore, there is a unique solution $u = \binom{t}{s}$, as desired.

In summary, the binomial coefficients can be equationally defined by the Equations (5)–(9) (with $s, t \in \mathbb{N}$) and the factorial function can be equationally defined by the Equations (1)–(2) and (4)–(9). In both cases we allow the use of the exponential function. Since the equation q = s! in the set (P) of four equations stated earlier can be replaced by the equations (1)–(2) and (4)–(9) we deduce that any prime p is equationally defined, provided that we allow the use of the exponential function.

The final step is to show that the exponential function can be eliminated in favor of polynomial equations. This is the hardest step which was overcome by Matyasevich by building up on results of Robinson.

We refer the interested reader to the remarkable expository paper by Davis, Matiyasevich and Robinson [12] for details. Here is a polynomial of total degree 25 in 26 variables (due to J. Jones, D. Sato, H. Wada, D. Wiens) which produces the primes as its positive range:

$$\begin{split} &(k+2) \left[1 - ([wz+h+j-q]^2 + [(gk+2g+k+1)(h+j)+h-z]^2 \\ &+ [16(k+1)^3(k+2)(n+1)^2 + 1 - f^2]^2 \\ &+ [2n+p+q+z-e]^2 + [e^3(e+2)(a+1)^2 + 1 - o^2]^2 \\ &+ [(a^2-1)y^2 + 1 - x^2]^2 + [16r^2y^4(a^2-1) + 1 - u^2]^2 \\ &+ [((a+u^2(u^2-a))^2-1)(n+4dy)^2 + 1 - (x+cu)^2]^2 \\ &+ [(a^2-1)l^2 + 1 - m^2]^2 + [ai+k+1-l-i]^2 + [n+l+v-y]^2 \\ &+ [p+l(a-n-1) + b(2an+2a-n^2-2n-2) - m]^2 \\ &+ [q+y(a-p-1) + s(2ap+2a-p^2-2p-2) - x]^2 \\ &+ [z+pl(a-p) + t(2ap-p^2-1) - pm]^2) \Big]. \end{split}$$

Around 2004, Nachi Gupta, an undergraduate student at Penn, and I tried to produce the prime 2 as one of the values of the positive range of the above polynomial. It turns out that this leads to values of the variables that are so large that we never succeeded!

Other interesting applications of the DPRM theorem are the re-statements of famous open problems, such as the Riemann hypothesis, as the unsolvability of certain Diophantine equations. For all this, see Davis, Matiyasevich and Robinson [12]. One may also obtain a nice variant of Gödel's incompleteness theorem.

11.8 Gödel's Incompleteness Theorem

Gödel published his famous incompleteness theorem in 1931. At the time, his result rocked the mathematical world, and certainly the community of logicians.

In order to understand why his result had such impact one needs to step back in time. In the late 1800's, Hilbert had advanced the thesis that it should be possible to completely formalize mathematics in such a way that every true statement should be provable "mechanically." In modern terminology, Hilbert believed that one could design a theorem prover that should be complete. His quest is known as *Hilbert's program*. In order to achieve his goal, Hilbert was led to investigate the notion of proof, and with some collaborators including Ackerman, Hilbert developed a significant amount of what is known as *proof theory*. When the young Gödel announced his incompleteness theorem, Hilbert's program came to an abrupt halt. Even the quest for a complete proof system for arithmetic was impossible.

It should be noted that when Gödel proved his incompleteness theorem, computability theory basically did not exist, so Gödel had to start from scratch. His proof is really a tour de force. Gödel's theorem also triggered extensive research on the notion of computability and undecidability between 1931 and 1936, the major players being Church, Gödel himself, Herbrand, Kleene, Rosser, Turing, and Post. In this section we will give a (deceptively) short proof that relies on the DPRM and the existence of universal functions. The proof is short because the hard work lies in the proof of the DPRM!

The first step is to translate the fact that there is a universal partial computable function φ_{univ} (see Proposition 8.7), such that for all $x, y \in \mathbb{N}$, if φ_x is the *x*th partial computable function, then

$$\varphi_x(y) = \varphi_{univ}(x, y).$$

Also recall from Definition 9.7 that for any acceptable indexing of the partial computable functions, the listable (c.e. r.e.) sets W_x are given by

$$W_x = dom(\varphi_x), \quad x \in \mathbb{N}.$$

Since φ_{univ} is a partial computable function, it can be converted into a Diophantine equation so that we have the following result.

Theorem 11.16. (Universal Equation Theorem) There is a Diophantine equation $U(m, a, x_1, \ldots x_{\nu}) = 0$ such that for every listable (c.e., r.e.) set W_m ($m \in \mathbb{N}$) we have

 $a \in W_m$ iff $(\exists x_1, \dots, x_\nu)(U(m, a, x_1, \dots, x_\nu) = 0).$

Proof. We have

$$W_m = \{ a \in \mathbb{N} \mid (\exists x_1)(\varphi_{univ}(m, a) = x_1) \},\$$

and since φ_{univ} is partial computable, by the DPRM (Theorem 11.8), there is Diophantine polynomial $U(m, a, x_1, \ldots, x_{\nu})$ such that

 $x_1 = \varphi_{univ}(m, a)$ iff $(\exists x_2, \dots, x_{\nu})(U(m, a, x_1, \dots, x_{\nu}) = 0),$

and so

$$W_m = \{ a \in \mathbb{N} \mid (\exists x_1, \dots, x_{\nu}) (U(m, a, x_1, \dots, x_{\nu}) = 0) \},\$$

as claimed.

The Diophantine equation $U(m, a, x_1, \dots, x_{\nu}) = 0$ is called a *universal Diophantine equa*tion. It is customary to denote $U(m, a, x_1, \dots, x_{\nu})$ by $P_m(a, x_1, \dots, x_{\nu})$.

Gödel's incompleteness theorem applies to sets of logical (first-order) formulae of arithmetic built from the mathematical symbols $0, S, +, \cdot, <$ and the logical connectives $\land, \lor, \neg, \Rightarrow$, $=, \forall, \exists$. Recall that logical equivalence, \equiv , is defined by

$$P \equiv Q$$
 iff $(P \Rightarrow Q) \land (Q \Rightarrow P)$.

The term

$$\underbrace{S(S(\cdots(S(0))\cdots))}_{n}$$

is denoted by $S^{n}(0)$, and represents the natural number n.

For example,

$$\exists x (S(S(S(0))) < (S(S(0)) + x)),$$

$$\exists x \exists y \exists z ((0 < x) \land (0 < y) \land (0 < z) \land ((x \cdot x + y \cdot y) = z \cdot z)),$$

and

$$\forall x \forall y \forall z ((0 < x) \land (0 < y) \land (0 < z) \Rightarrow \neg ((x \cdot x \cdot x \cdot x + y \cdot y \cdot y \cdot y) = z \cdot z \cdot z \cdot z))$$

are formulae in the language of arithmetic. All three are true. The first formula is satisfied by x = S(S(0)), the second by $x = S^3(0)$, $y = S^4(0)$ and $z = S^5(0)$ (since $3^2 + 4^2 = 9 + 16 = 25 = 5^2$), and the third formula asserts a special case of Fermat's famous theorem: for every $n \ge 3$, the equation $x^n + y^n = z^n$ has no solution with $x, y, z \in \mathbb{N}$ and x > 0, y > 0, z > 0. The third formula corresponds to n = 4. Even for this case, the proof is hard.

To be completely rigorous we should explain precisely what is a formal proof. Roughly speaking, a proof system consists of axioms and inference rule. A proof is a certain kind of tree whose nodes are labeled with formulae, and this tree is constructed in such a way that for every node some inference rule is applied. Proof systems are discussed in Chapter 1 and in more detail in Chapter 2. The reader is invited to review this material. Such proof systems are also presented in Gallier [24, 23].

Given a polynomial $P(x_1, \ldots, x_m)$ in $\mathbb{Z}[x_1, \ldots, x_m]$, we need a way to "prove" that some natural numbers $n_1, \ldots, n_m \in \mathbb{N}$ are a solution of the Diophantine equation

$$P(x_1,\ldots,x_m)=0,$$

which means that we need to have enough formulae of arithmetric to allow us to simplify the expression $P(n_1, \ldots, n_m)$ and check whether or not it is equal to zero.

For example, if P(x, y) = 2x - 3y - 1, we have the solution x = 2 and y = 1. What we do is to group all monomials with positive signs, 2x, and all monomials with negative signs, 3y + 1, plug in the values for x and y, simplify using the arithmetic tables for + and \cdot , and then compare the results. If they are equal, then we proved that the equation has a solution.

In our language, $x = S^2(0)$, $2x = S^2(0) \cdot x$, and $y = S^1(0)$, $3y + 1 = S^3(0) \cdot y + S(0)$. We need to simplify the expressions

$$2x = S^2(0) \cdot S^2(0)$$
 and $3y + 1 = S^3(0) \cdot S(0) + S(0)$.

Using the formulae

$$S^{m}(0) + S^{n}(0) = S^{m+n}(0)$$

$$S^{m}(0) \cdot S^{n}(0) = S^{mn}(0)$$

$$S^{m}(0) < S^{n}(0) \text{ iff } m < n,$$

with $m, n \in \mathbb{N}$, we simplify $S^2(0) \cdot S^2(0)$ to $S^4(0), S^3(0) \cdot S(0) + S(0)$ to $S^4(0)$, and we see that the results are equal.

In general, given a polynomial $P(x_1, \ldots, x_m)$ in $\mathbb{Z}[x_1, \ldots, x_m]$, we write it as

$$P(x_1,\ldots,x_m) = P_{\text{pos}}(x_1,\ldots,x_m) - P_{\text{neg}}(x_1,\ldots,x_m),$$

where $P_{\text{pos}}(x_1, \ldots, x_m)$ consists of the monomials with positive coefficients, and $-P_{\text{neg}}(x_1, \ldots, x_m)$ consists of the monomials with negative coefficients. Next we plug in $S^{n_1}(0), \ldots, S^{n_m}(0)$ in $P_{\text{pos}}(x_1, \ldots, x_m)$, and evaluate using the formulae for the addition and multiplication tables obtaining a term of the form $S^p(0)$. Similarly, we plug in $S^{n_1}(0), \ldots, S^{n_m}(0)$ in $P_{\text{neg}}(x_1, \ldots, x_m)$, and evaluate using the formulae for the addition and multiplication tables obtaining a term of the form $S^p(0)$. Similarly, we plug in $S^{n_1}(0), \ldots, S^{n_m}(0)$ in $P_{\text{neg}}(x_1, \ldots, x_m)$, and evaluate using the formulae for the addition and multiplication tables obtaining a term of the form $S^q(0)$. Then, since exactly one of the formulae

$$S^{p}(0) = S^{q}(0), \text{ or } S^{p}(0) < S^{q}(0), \text{ or } S^{q}(0) < S^{p}(0)$$

is true, we obtain a proof that either $P(n_1, \ldots, n_m) = 0$ or $P(n_1, \ldots, n_m) \neq 0$.

A more economical way that does use not an infinite number of formulae expressing the addition and multiplication tables is to use various axiomatizations of arithmetic.

One axiomatization known as *Robinson arithmetic* (R. M. Robinson (1950)) consists of the following seven axioms:

$$\begin{aligned} \forall x \neg (S(x) = 0) \\ \forall x \forall y ((S(x) = S(y)) \Rightarrow (x = y)) \\ \forall y ((y = 0) \lor \exists x (S(x) = y)) \\ \forall x (x + 0 = x) \\ \forall x \forall y (x + S(y) = S(x + y)) \\ \forall x (x \cdot 0 = 0) \\ \forall x \forall y (x \cdot S(y) = x \cdot y + x). \end{aligned}$$

Peano arithmetic is obtained from Robinson arithmetic by adding a rule schema expressing induction:

$$[\varphi(0) \land \forall n(\varphi(n) \Rightarrow \varphi(n+1))] \Rightarrow \forall m\varphi(m),$$

where $\varphi(x)$ is any (first-order) formula of arithmetic. To deal with $\langle \rangle$, we also have the axiom

$$\forall x \forall y (x < y \equiv \exists z (S(z) + x = y)).$$

It is easy to prove that the formulae

$$S^{m}(0) + S^{n}(0) = S^{m+n}(0)$$

$$S^{m}(0) \cdot S^{n}(0) = S^{mn}(0)$$

$$S^{m}(0) < S^{n}(0) \quad \text{iff} \quad m < n,$$

are provable in Robinson arithmetic, and thus in Peano arithmetic (with $m, n \in \mathbb{N}$).

Gödel's incompleteness applies to sets \mathcal{A} of formulae of arithmetic that are "nice" and strong enough. A set \mathcal{A} of formulae is nice if it is listable and *consistent* (see Definition 10.3), which means that it is impossible to prove φ and $\neg \varphi$ from \mathcal{A} for some formula φ . In other words, \mathcal{A} is free of contradictions.

Since the axioms of Peano arithmetic are obviously true statements about \mathbb{N} and since the induction principle holds for \mathbb{N} , the set of all formulae provable in Robinson arithmetic and in Peano arithmetic is consistent.

As in Section 10.3, it is possible to assign a Gödel number #(A) to every first-order sentence A in the language of arithmetic; see Enderton [16] (Chapter III) or Kleene I.M. [42] (Chapter X). With a slight abuse of notation, we say that a set T is sentences of arithmetic is computable (*resp.* listable) iff the set of Gödel numbers #(A) of sentences A in T is computable (*resp.* listable). It can be shown that the set of all formulae provable in Robinson arithmetic and in Peano arithmetic are listable.

Here is a rather strong version of Gödel's incompleteness from Davis, Matiyasevich and Robinson [12].

Theorem 11.17. (Gödel's Incompleteness Theorem) Let \mathcal{A} be a set of formulae of arithmetic satisfying the following properties:

- (a) The set \mathcal{A} is consistent.
- (b) The set \mathcal{A} is listable (c.e., r.e.)
- (c) The set \mathcal{A} is strong enough to prove all formulae

$$S^{m}(0) + S^{n}(0) = S^{m+n}(0)$$

$$S^{m}(0) \cdot S^{n}(0) = S^{mn}(0)$$

$$S^{m}(0) < S^{n}(0) \quad iff \quad m < n,$$

for all $m, n \in \mathbb{N}$.

Then we can construct a Diophantine equation $F(x_1, \ldots, x_{\nu}) = 0$ corresponding to \mathcal{A} such that $F(x_1, \ldots, x_{\nu}) = 0$ has **no** solution with $x_1, \ldots, x_{\nu} \in \mathbb{N}$ but the formula

$$\neg(\exists x_1, \dots, x_{\nu})(F(x_1, \dots, x_{\nu}) = 0)$$
(*)

is **not** provable from A. In other words, there is a true statement of arithmetic not provable from A; that is, A is incomplete.

Proof. Define the subset $A \subseteq \mathbb{N}$ as follows:

$$A = \{a \in \mathbb{N} \mid \neg(\exists x_1, \dots, x_\nu) (P_a(a, x_1, \dots, x_\nu) = 0) \text{ is provable from } \mathcal{A}\}, \qquad (**)$$

where $P_m(a, x_1, \ldots, x_{\nu})$ is defined just after Theorem 11.16. Because by (b) \mathcal{A} is listable, it is easy to see (because the set of formulae provable from a listable set is listable) that \mathcal{A} is listable, so by the DPRM \mathcal{A} is Diophantine, and by Theorem 11.16, there is some $k \in \mathbb{N}$ such that

$$A = W_k = \{ a \in \mathbb{N} \mid (\exists x_1, \dots, x_{\nu}) (P_k(a, x_1, \dots, x_{\nu}) = 0) \}$$

The trick is now to see whether $k \in W_k$ or not. We claim that $k \notin W_k$.

We proceed by contradiction. Assume that $k \in W_k$. This means that

$$(\exists x_1, \dots, x_{\nu})(P_k(k, x_1, \dots, x_{\nu}) = 0), \qquad (\dagger_1)$$

and since $A = W_k$, by (**), that

$$\neg(\exists x_1, \dots, x_\nu)(P_k(k, x_1, \dots, x_\nu) = 0) \text{ is provable from } \mathcal{A}.$$
 (†2)

By (\dagger_1) and (c), since the equation $P_k(k, x_1, \ldots, x_{\nu}) = 0$ has a solution, we can prove the formula

$$(\exists x_1,\ldots,x_{\nu})(P_k(k,x_1,\ldots,x_{\nu})=0)$$

from \mathcal{A} . By (\dagger_2) , the formula $\neg(\exists x_1, \ldots, x_\nu)(P_k(k, x_1, \ldots, x_\nu) = 0)$ is provable from \mathcal{A} , but since $(\exists x_1, \ldots, x_\nu)(P_k(k, x_1, \ldots, x_\nu) = 0)$ is also provable from \mathcal{A} , this contradicts the fact that \mathcal{A} is consistent (which is hypothesis (a)).

Therefore we must have $k \notin W_k$. This means that $P_k(k, x_1, \ldots, x_\nu) = 0$ has **no** solution with $x_1, \ldots, x_\nu \in \mathbb{N}$, and since $A = W_k$, the formula

$$\neg(\exists x_1,\ldots,x_\nu)(P_k(k,x_1,\ldots,x_\nu)=0)$$

is **not** provable from \mathcal{A} , since otherwise, by definition of $A = W_k$, we would have $k \in W_k$, contradicting the fact that $k \notin W_k$.

Remark: Going back to the proof of Theorem 10.16, observe that A plays the role of $\{F_x \mid \neg F_x \text{ is provable}\}$, that k plays the role of x_0 , and that the fact that

$$\neg(\exists x_1,\ldots,x_\nu)(P_k(k,x_1,\ldots,x_\nu)=0)$$

is **not** provable from \mathcal{A} corresponds to $\neg F_{x_0}$ being true.

As a corollary of Theorem 11.17, since the theorems provable in Robinson arithmetic satisfy (a), (b), (c), we deduce that there are true theorems of arithmetic not provable in Robinson arithmetic; in short, Robinson arithmetic is incomplete. Since Robinson arithmetic does not have induction axioms, this shows that induction is not the culprit behind incompleteness. Since Peano arithmetic is an extension (consistent) of Robinson arithmetic, it is also incomplete. This is Gödel's original incompleteness theorem, but Gödel had to develop from scratch the tools needed to prove his result, so his proof is very different (and a tour de force).

But the situation is even more dramatic. Adding a true unprovable statement to a set \mathcal{A} satisfying (a), (b), (c) preserves properties (a), (b), (c), so there is no escape from incompleteness (unless perhaps we allow unreasonable sets of formulae violating (b)). The reader should compare this situation with the results given by Theorem 10.14 and Theorem 10.15.

Gödel's incomplenetess theorem is a negative result, in the sense that it shows that there is no hope of obtaining proof systems capable of proving all true statements for various mathematical theories such as arithmetic. We can also view Gödel's incomplenetess theorem positively as evidence that mathematicians will never be replaced by computers! There is always room for creativity.

The true but unprovable formulae arising in Gödel's incompleteness theorem are rather contrived and by no means "natural." For many years after Gödel's proof was published logicians looked for natural incompleteness phenomena. In the early 1980's such results were found, starting with a result of Kirby and Paris. Harvey Friedman then found more spectacular instances of natural incompleteness, one of which involves a finite miniaturization of Kruskal's tree theorem. The proof of such results uses some deep methods of proof theory involving a tool known as ordinal notations. In particular, two ordinals denoted ϵ_0 and Γ_0 play an important role in consistency proofs; see Takeuti [71] and Schütte [65]. A survey of such results can be found in Gallier [17] and an introduction to ordinals and cardinals is provided in Chapter A.

Chapter 12

The Post Correspondence Problem; Applications to Undecidability Results

12.1 The Post Correspondence Problem

The Post correspondence problem (due to Emil Post) is another undecidable problem that turns out to be a very helpful tool for proving problems in logic or in formal language theory to be undecidable.

Definition 12.1. Let Σ be an alphabet with at least two letters. An instance of the *Post Correspondence problem* (for short, PCP) is given by two nonempty sequences $U = (u_1, \ldots, u_m)$ and $V = (v_1, \ldots, v_m)$ of strings $u_i, v_i \in \Sigma^*$. Equivalently, an instance of the PCP is a sequence of pairs $(u_1, v_1), \ldots, (u_m, v_m)$.

The problem is to find whether there is a (finite) sequence (i_1, \ldots, i_p) , with $i_j \in \{1, \ldots, m\}$ for $j = 1, \ldots, p$, so that

$$u_{i_1}u_{i_2}\cdots u_{i_p}=v_{i_1}v_{i_2}\cdots v_{i_p}.$$

Example 12.1. Consider the following problem:

(abab, ababaaa), (aaabbb, bb), (aab, baab), (ba, baa), (ab, ba), (aa, a).

There is a solution for the string 1234556:

abab aaabbb aab ba ab ab aa = ababaaa bb baab baa ba ba a.

If you are not convinced that this is a hard problem, try solving the following instance of the PCP:

 $\{(aab, a), (ab, abb), (ab, bab), (ba, aab).\}$

The shortest solution is a sequence of length 66.

We are beginning to suspect that this is a hard problem. Indeed, it is undecidable!

Theorem 12.1. (Emil Post, 1946) The Post correspondence problem is undecidable, provided that the alphabet Σ has at least two symbols.

There are several ways of proving Theorem 12.1, but the strategy is more or less the same: reduce the halting problem to the PCP, by encoding sequences of ID's as partial solutions of the PCP. In Machtey and Young [51] (Section 2.6), the undecidability of the PCP is shown by demonstrating how to simulate the computation of a Turing machine as a sequence of ID's. We give a proof involving special kinds of RAM programs (called Post machines in Manna [52]), which is an adaptation of a proof due to Dana Scott presented in Manna [52] (Section 1.5.4, Theorem 1.8).

Proof. The first step of the proof is to show that a RAM program with $p \ge 2$ registers can be simulated by a RAM program using a single register. The main idea of the simulation is that by using the instructions add, tail, and jmp, it is possible to perform cyclic permutations on the string held by a register.

First we can also assume that RAM programs only uses instructions of the form

(1_{j})	N		add_j	X
(2)	N		tail	X
$(6_j a)$	N	X	jmp_i	N1a
$(6_j b)$	N	X	jmp_i	N1b
(7)	N		continue	

We can simulate $p \ge 2$ registers with a single register, by encoding the contents r_1, \ldots, r_p of the p registers as the string

 $r_1 \# r_2 \# \cdots \# r_p,$

using a single marker #. For instance, if p = 2, the effect of the instruction add_b on register R1 is achieved as follows: Assuming that the initial contents are

aab#baba

using cyclic permutations (also inserting or deleting # whenever necessary), we get

aab#babaab#baba#ab#baba#aababa#aabbaba#aabbaba#aabb#bba#aabb#baa#aabb#babaabb#baba Similarly, the effect of the instruction tail on register R2 is achieved as follows

aab#baba ab#baba#a b#baba#aa baba#aab aba#aab aba#aab#aa a#aab#abaab#aba

Since the halting problem for RAM programs is undecidable and since every RAM program can be simulated by another RAM with a single register, the halting problem for RAM programs with a single register is undecidable.

The second step of the proof is to reduce the halting problem for RAM programs with one register to the PCP (over an alphabet with at least two symbols).

Recall that $\Sigma = \{a_1, \ldots, a_k\}$. First, it is easily shown that every RAM program P (with a single register X) is equivalent to a RAM program P' such that all instructions are labeled with distinct line numbers, and such that there is only one occurrence of the instruction continue at the end of the program.

In order to obtain a reasonably simple reduction of the halting problem for RAM programs with a single register to the PCP, we modify the jump instructions as follows: the new instruction

$$\operatorname{Jmp} N_1, \ldots, N_k, N_{k+1}$$

tests whether $head(X) = a_j$, with $1 \leq j \leq k$. Since there is a single register X, it is omitted in the instruction Jmp. If $head(X) = a_j$, then jump to the instruction labeled N_j and perform the tail instruction so that X = tail(X), otherwise if $X = \epsilon$ (which implies that j = k + 1), jump to the instruction labeled N_{k+1} . The instruction tail is eliminated. We leave it as an exercise to show how to simulate the new instruction

Jmp
$$N_1, \ldots, N_k, N_{k+1}$$

using the instructions tail, $jmp_j Na$ and $jmp_j Nb$, and vice-versa. From now on we will use the second version using the instructions

$$\operatorname{Jmp} N_1, \ldots, N_k, N_{k+1}.$$

For the purpose of deciding whether a RAM program terminates, we may assume without loss of generality that we deal with programs that clear the register X when they halt. In

fact, by adding an extra symbol # to the alphabet (which now has k + 1 symbols), we may also assume that in every instruction

Jmp
$$N_1, \ldots, N_{k+1}, N_{k+2},$$

 N_{k+2} is the line number of the last instruction in the RAM program, which must be a **continue**. This implies that the program clears the register X before it halts. We can execute the instruction $\operatorname{add}_{k+1} X$ at the very beginning of the program and perform an $\operatorname{add}_{k+1} X$ after each tail instruction to make sure that in the new program the register X always has # as its rightmost symbol. When the original program performs an instruction

Jmp
$$N_1, \ldots, N_{k+1}, N_{k+2}$$

with $X = \epsilon$, the new program performs the instruction

Jmp
$$N_1, \ldots, N_{k+2}, N_1$$
.

Since X is never empty during execution of the new program, the line number N_1 is irrelevant. Finally, when the original program halts, the new program clears the register X and then jumps to the last continue. We leave the details as an exercise.

From now on, we assume that $\Sigma = \{a_1, \ldots, a_k, \#\}$. Given a RAM program P satisfying all the restrictions described above, we construct an instance of the PCP as follows. Assume that P has q lines numbered $N1, \ldots, Nq$. The alphabet Δ of the PCP is $\Delta = \Sigma \cup \{*, N_0, N_1, \ldots, N_q\}$. Indeed, the construction requires one more line number N_0 to force a solution of the PCP to start with some specified pair.

The lists U and V are constructed so that given any nonempty input $x = x_1 \cdots x_m$ (with $x_i \in \Sigma$), the only possible U-lists u and V-lists v that could lead to a solution are of the form

$$u = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n}$$

and

$$v = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n} w_n * N_{i_{n+1}} *,$$

where each w_i is of the form

$$w_i = w_{i,1} * \cdots * w_{i,n_i}$$
 or $w_i = \epsilon$,

with

$$w_0 = *x_1 * x_2 * \cdots * x_m,$$

where $w_{i,j} \in \Sigma$, $1 \leq j \leq n_i$, $1 \leq i \leq n$.

The sequence $N_1, \ldots, N_{i_{n+1}}$ is the sequence of line numbers of the instructions executed by the RAM program P after n steps, started on input x, and w_j is the value of the (single) register X just after executing the jth step, *i.e.*, the instruction at line number N_{i_j} . We make sure that the V-list is always ahead of the U-list by one instruction. The lists U and V are defined according to the following rules. Rather than defining U and V explicitly, we define the pairs (u_i, v_i) , where $u_i \in U$ and $v_i \in V$.

To get started: we have the initial pair

$$(N_0, N_0 * x_1 * x_2 * \dots * x_m * N_1 *).$$

To simulate an instruction

$$N_i$$
 add_j X ,

create the pair

$$(* N_i, a_j * N_{i+1} *), \text{ for all } a \in \Sigma.$$

To simulate an instruction of the form

$$N_i$$
 Jmp $N_1, \ldots, N_{k+1}, N_{k+2},$

create the pairs

$$(* N_i * a_j, N_j *), \quad 1 \le j \le k+1,$$

and

 $(* N_i * N_q, N_q).$

To build up the register contents, we need pairs

$$(*a, a*), \text{ for all } a \in \Sigma.$$

Note that we used the alphabet $\Delta = \Sigma \cup \{*, N_0, N_1, \ldots, N_q\}$, which uses more than 2 symbols in general. Let us finish our reduction for an instance of the PCP over the alphabet Δ . Then after this construction is finished we will explain how to convert the instance of the PCP that we obtained to an instance of the PCP over a two-symbol alphabet.

The pairs of the PCP are designed so that the only possible U-lists u and V-lists v that could lead to a solution are of the form

$$u = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n}$$

and

$$v = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n} w_n * N_{i_{n+1}} *,$$

where each w_i is of the form

$$w_i = w_{i,1} * \cdots * w_{i,n_i}$$
 or $w_i = \epsilon$,

with

$$w_0 = *x_1 * x_2 * \cdots * x_m$$

where $w_{i,j} \in \Sigma$, $1 \leq j \leq n_i$, $1 \leq i \leq n$, and where v is an encoding of n steps of the computation of the RAM program P on input $x = x_1 \cdots x_m$, and u lags behind v by one step.

For example, let us see how the U-list and the V-list are updated, assuming that N_{i_n} is the following instruction:

$$N_{i_n}$$
 add_b X

Just after execution of the instruction at line number N_{i_n} , we have

$$u = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}}$$

and

$$v = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n} *$$

Since $w_{n-1} = * w_{n-1,1} * \cdots * w_{n-1,n_{n-1}}$, using the pairs

$$(*w_{n-1,1}, w_{n-1,1}*), (*w_{n-1,2}, w_{n-1,2}*), \cdots, (*w_{n-1,n_{n-1}}, w_{n-1,n_{n-1}}*),$$

we get

$$u = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1}$$

and

$$v = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n} w_{n-1} *$$

Next we use the pair

$$(* N_{i_n}, b * N_{i_{n+1}} *)$$

simulating add_b , and we get

$$u = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n}$$

and

$$v = N_0 w_0 * N_1 w_1 * \dots * N_{i_{n-1}} w_{n-1} * N_{i_n} w_{n-1} * b * N_{i_{n+1}} * .$$

Observe that the only chance for getting a solution of the PCP is to start with the pairs involving N_0 . It is easy to see that the PCP constructed from P has a solution iff P halts on input x. However, the halting problem for RAM's with a single register is undecidable, and thus, the PCP over the alphabet Δ is also undecidable.

It remains to show that we can recode the instance of the PCP that we obtained over the alphabet $\Delta = \Sigma \cup \{*, N_0, N_1, \ldots, N_q\}$ as an instance of the PCP over the alphabet $\{a_1, *\}$. To achieve this, we recode each symbol a_i in Σ as $*a_1^i$ (with $a_{k+1} = \#$) and each N_j as $*a_1^{k+j+2}$. This way, we are only using the alphabet $\Delta = \{a_1, *\}$. We need the second character *, whose purpose is to avoid trivial solutions of the form

This could happen if we had used pairs (a, a) to build up the register. Then we substitute $*a_1^i$ for a_i and $*a_1^{k+j+2}$ for N_j in the pairs that we created. Observe that the pairs (*a, a*) become pairs involving longer strings. It is easy to see that the original PCP over Δ has a solution iff the new PCP over $\{a_1, *\}$ has a solution, so the PCP over two-letter alphabet is undecidable.

In the next two sections we present some undecidability results for context-free grammars and context-free languages.

12.2 Some Undecidability Results for CFG's

Theorem 12.2. It is undecidable whether a context-free grammar is ambiguous.

Proof. We reduce the PCP to the ambiguity problem for CFG's. Given any instance $U = (u_1, \ldots, u_m)$ and $V = (v_1, \ldots, v_m)$ of the PCP, let c_1, \ldots, c_m be *m* new symbols, and consider the following languages:

$$L_{U} = \{u_{i_{1}} \cdots u_{i_{p}} c_{i_{p}} \cdots c_{i_{1}} \mid 1 \leq i_{j} \leq m, \\ 1 \leq j \leq p, \ p \geq 1\}, \\ L_{V} = \{v_{i_{1}} \cdots v_{i_{p}} c_{i_{p}} \cdots c_{i_{1}} \mid 1 \leq i_{j} \leq m, \\ 1 \leq j \leq p, \ p \geq 1\},$$

and $L_{U,V} = L_U \cup L_V$.

We can easily construct a CFG, $G_{U,V}$, generating $L_{U,V}$. The productions are:

It is easily seen that the PCP for (U, V) has a solution iff $L_U \cap L_V \neq \emptyset$ iff G is ambiguous.

Remark: As a corollary, we also obtain the following result: it is undecidable for arbitrary context-free grammars G_1 and G_2 whether $L(G_1) \cap L(G_2) = \emptyset$ (see also Theorem 12.4).

Recall that the computations of a Turing Machine, M, can be described in terms of instantaneous descriptions, upav.

We can encode computations

$$ID_0 \vdash ID_1 \vdash \cdots \vdash ID_n$$

halting in a proper ID, as the language, L_M , consisting all of strings

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k} \# w_{2k+1}^R,$$

or

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k-2} \# w_{2k-1}^R \# w_{2k},$$

where $k \ge 0$, w_0 is a starting ID, $w_i \vdash w_{i+1}$ for all i with $0 \le i < 2k + 1$ and w_{2k+1} is proper halting ID in the first case, $0 \le i < 2k$ and w_{2k} is proper halting ID in the second case.

The language L_M turns out to be the intersection of two context-free languages L_M^0 and L_M^1 defined as follows:

(1) The strings in L_M^0 are of the form

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k} \# w_{2k+1}^R$$

or

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k-2} \# w_{2k-1}^R \# w_{2k},$$

where $w_{2i} \vdash w_{2i+1}$ for all $i \geq 0$, and w_{2k} is a proper halting ID in the second case.

(2) The strings in L_M^1 are of the form

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k} \# w_{2k+1}^R$$

or

$$w_0 \# w_1^R \# w_2 \# w_3^R \# \cdots \# w_{2k-2} \# w_{2k-1}^R \# w_{2k}$$

where $w_{2i+1} \vdash w_{2i+2}$ for all $i \ge 0$, w_0 is a starting ID, and w_{2k+1} is a proper halting ID in the first case.

Theorem 12.3. Given any Turing machine M, the languages L_M^0 and L_M^1 are context-free, and $L_M = L_M^0 \cap L_M^1$.

Proof. We can construct PDA's accepting L_M^0 and L_M^1 . It is easily checked that $L_M = L_M^0 \cap L_M^1$.

As a corollary, we obtain the following undecidability result:

Theorem 12.4. It is undecidable for arbitrary context-free grammars G_1 and G_2 whether $L(G_1) \cap L(G_2) = \emptyset$.

Proof. We can reduce the problem of deciding whether a partial recursive function is undefined everywhere to the above problem. By Rice's theorem, the first problem is undecidable.

However, this problem is equivalent to deciding whether a Turing machine never halts in a proper ID. By Theorem 12.3, the languages L_M^0 and L_M^1 are context-free. Thus, we can construct context-free grammars G_1 and G_2 so that $L_M^0 = L(G_1)$ and $L_M^1 = L(G_2)$. Then Mnever halts in a proper ID iff $L_M = \emptyset$ iff (by Theorem 12.3), $L_M = L(G_1) \cap L(G_2) = \emptyset$. \Box

Given a Turing machine M, the language L_M is defined over the alphabet $\Delta = \Gamma \cup Q \cup \{\#\}$. The following fact is also useful to prove undecidability:

Theorem 12.5. Given any Turing machine M, the language $\Delta^* - L_M$ is context-free.

Proof. One can easily check that the conditions for not belonging to L_M can be checked by a PDA.

As a corollary, we obtain:

Theorem 12.6. Given any context-free grammar, $G = (V, \Sigma, P, S)$, it is undecidable whether $L(G) = \Sigma^*$.

Proof. We can reduce the problem of deciding whether a Turing machine never halts in a proper ID to the above problem.

Indeed, given M, by Theorem 12.5, the language $\Delta^* - L_M$ is context-free. Thus, there is a CFG, G, so that $L(G) = \Delta^* - L_M$. However, M never halts in a proper ID iff $L_M = \emptyset$ iff $L(G) = \Delta^*$.

As a consequence, we also obtain the following:

Theorem 12.7. Given any two context-free grammar, G_1 and G_2 , and any regular language, R, the following facts hold:

(1) $L(G_1) = L(G_2)$ is undecidable.

(2) $L(G_1) \subseteq L(G_2)$ is undecidable.

(3) $L(G_1) = R$ is undecidable.

(4) $R \subseteq L(G_2)$ is undecidable.

In contrast to (4), the property $L(G_1) \subseteq R$ is decidable!

12.3 More Undecidable Properties of Languages; Greibach's Theorem

We discuss a nice theorem of S. Greibach, which is a sort of version of Rice's theorem for families of languages.

Let \mathcal{L} be a countable family of languages. We assume that there is a coding function $c: \mathcal{L} \to \mathbb{N}$ and that this function can be extended to code the regular languages (all alphabets are subsets of some given countably infinite set).

We also assume that \mathcal{L} is effectively closed under union, and concatenation with the regular languages.

This means that given any two languages L_1 and L_2 in \mathcal{L} , we have $L_1 \cup L_2 \in \mathcal{L}$, and $c(L_1 \cup L_2)$ is given by a recursive function of $c(L_1)$ and $c(L_2)$, and that for every regular language R, we have $L_1R \in \mathcal{L}$, $RL_1 \in \mathcal{L}$, and $c(RL_1)$ and $c(L_1R)$ are recursive functions of c(R) and $c(L_1)$.

Given any language, $L \subseteq \Sigma^*$, and any string, $w \in \Sigma^*$, we define L/w by

$$L/w = \{ u \in \Sigma^* \mid uw \in L \}.$$

Theorem 12.8. (Greibach) Let \mathcal{L} be a countable family of languages that is effectively closed under union and concatenation with the regular languages, and assume that the problem $L = \Sigma^*$ is undecidable for $L \in \mathcal{L}$ and any given sufficiently large alphabet Σ . Let P be any nontrivial property of languages that is true for the regular languages, so that if P(L) holds for any $L \in \mathcal{L}$, then P(L/a) also holds for any letter a. Then P is undecidable for \mathcal{L} .

Proof. Since P is nontrivial for \mathcal{L} , there is some $L_0 \in \mathcal{L}$ so that $P(L_0)$ is false.

Let Σ be large enough, so that $L_0 \subseteq \Sigma^*$, and the problem $L = \Sigma^*$ is undecidable for $L \in \mathcal{L}$.

We show that given any $L \in \mathcal{L}$, with $L \subseteq \Sigma^*$, we can construct a language $L_1 \in \mathcal{L}$, so that $L = \Sigma^*$ iff $P(L_1)$ holds. Thus, the problem $L = \Sigma^*$ for $L \in \mathcal{L}$ reduces to property P for \mathcal{L} , and since for Σ big enough, the first problem is undecidable, so is the second.

For any $L \in \mathcal{L}$, with $L \subseteq \Sigma^*$, let

$$L_1 = L_0 \# \Sigma^* \cup \Sigma^* \# L.$$

Since \mathcal{L} is effectively closed under union and concatenation with the regular languages, we have $L_1 \in \mathcal{L}$.

If $L = \Sigma^*$, then $L_1 = \Sigma^* \# \Sigma^*$, a regular language, and thus, $P(L_1)$ holds, since P holds for the regular languages.

Conversely, we would like to prove that if $L \neq \Sigma^*$, then $P(L_1)$ is false.

Since $L \neq \Sigma^*$, there is some $w \notin L$. But then,

$$L_1/\#w = L_0.$$

Since P is preserved under quotient by a single letter, by a trivial induction, if $P(L_1)$ holds, then $P(L_0)$ also holds. However, $P(L_0)$ is false, so $P(L_1)$ must be false.

Thus, we proved that $L = \Sigma^*$ iff $P(L_1)$ holds, as claimed.

Greibach's theorem can be used to show that it is undecidable whether a context-free grammar generates a regular language.

It can also be used to show that it is undecidable whether a context-free language is inherently ambiguous.

12.4 Undecidability of Validity in First-Order Logic

The PCP can also be used to give a quick proof of Church's famous result stating that validity in first-order logic is undecidable. Here we are considering first-order formulae as defined in Section 2.17. Given a first-order language **L** consisting of constant symbols c, function symbols f, and predicate symbols P, a first-order structure \mathcal{M} consists of a nonempty domain \mathcal{M} , of an assignment of some element of $c_{\mathcal{M}} \in \mathcal{M}$ to every constant symbol c, of a function $f_{\mathcal{M}} \colon \mathcal{M}^n \to \mathcal{M}$ to every n-ary function symbol f, and to a boolean-valued function $P_{\mathcal{M}} \colon \mathcal{M}^m \to \{\mathbf{T}, \mathbf{F}\}$ to any m-ary predicate symbol P.

Then given any assignment $\rho: X \to M$ to the first-order variables $x_i \in X$, we can define recursively the truth value $\varphi_{\mathcal{M}}[\rho]$ of every first-order formula φ . If φ is a sentence, which means that φ has no free variables, then the truth value $\varphi_{\mathcal{M}}[\rho]$ is independent of ρ , so we simply write $\varphi_{\mathcal{M}}$. Details can be found in Gallier [24], Enderton [16], or Shoenfield [67]. The formula φ is valid in \mathcal{M} if $\varphi_{\mathcal{M}}[\rho] = \mathbf{T}$ for all ρ . We also say that \mathcal{M} is a model of φ and we write

 $\mathcal{M}\models\varphi.$

The formula φ is *valid* (or *universally valid*) if it is valid in *every* first-order structure \mathcal{M} ; this denoted by

 $\models \varphi.$

The *validity problem* in first-order logic is to decide whether there is algorithm to decide whether any first-order formula is valid.

Theorem 12.9. (Church, 1936) The validity problem for first-order logic is undecidable.

Proof. The following proof due to R. Floyd is given in Manna [52] (Section 2.16). The proof consists in reducing the PCP over the alphabet $\{0,1\}$ to the validity problem. Given an instance S = (U, V) of the PCP, we construct a first-order sentence Φ_S (using a computable

function) such that S has a solution if and only if Φ_S is valid. Since the PCP is undecidable, so is the validity problem for first-order logic.

For this construction, we need a constant symbol a, two unary function symbols f_0 and f_1 , and a binary predicate symbol P. We denote the term

$$f_{s_p}(\cdots(f_{s_2}(f_{s_1}(x))\cdots)$$

as $f_{s_1s_2\cdots s_p}$, where $s_i \in \{0, 1\}$. Suppose S is the set of pairs

$$S = \{(u_1, v_1), \dots, (u_m, v_m)\}$$

The key ingredent is the sentence

$$\Phi_S \equiv \left(\bigwedge_{i=1}^m P(f_{u_i}(a), f_{v_i}(a)) \land \forall x \forall y \Big(P(x, y) \Rightarrow \bigwedge_{i=1}^m P(f_{u_i}(x), f_{v_i}(x)) \Big) \right)$$

$$\Rightarrow \exists z P(z, z).$$

We claim that the PCP S has a solution iff Φ_S is valid.

Step 1. We prove that if Φ_S is valid, then the PCP has a solution. Consider the first-order structure \mathcal{M} with domain $\{0,1\}^*$, with $a_{\mathcal{M}} = \epsilon$, $(f_0)_{\mathcal{M}}$ is concatenation on the right with 0 $((f_0)_{\mathcal{M}}(x) = x0)$, $(f_1)_{\mathcal{M}}$ is concatenation on the right with 1 $((f_1)_{\mathcal{M}}(x) = x1)$, and

$$P(x,y) = \mathbf{T}$$
 iff $x = u_{i_1}u_{i_2}\cdots u_{i_n}, \quad y = v_{i_1}v_{i_2}\cdots v_{i_n},$

for some nonempty sequence i_1, i_2, \ldots, i_n with $1 \le i_j \le m$.

Since Φ_S is valid, it must be valid in \mathcal{M} , but then we see immediately that both

$$\bigwedge_{i=1}^{m} P(f_{u_i}(a), f_{v_i}(a))$$

and

$$\forall x \forall y \Big(P(x, y) \Rightarrow \bigwedge_{i=1}^{m} P(f_{u_i}(x), f_{v_i}(x)) \Big)$$

are valid in \mathcal{M} , thus

 $\exists z P(z, z)$

is also valid in \mathcal{M} . This means that there is some nonempty sequence i_1, i_2, \ldots, i_n with $1 \leq i_j \leq m$ such that

$$z=u_{i_1}u_{i_2}\cdots u_{i_n}=v_{i_1}v_{i_2}\cdots v_{i_n},$$

and so we have a solution of the PCP.

Step 2. We prove that if the PCP has a solution, then Φ_S is valid. Let i_1, i_2, \ldots, i_n be a nonempty sequence with $1 \leq i_j \leq m$ such that

$$u_{i_1}u_{i_2}\cdots u_{i_n}=v_{i_1}v_{i_2}\cdots v_{i_n}$$

which means that i_1, i_2, \ldots, i_n is a solution of the PCP S. We prove that for every first-order structure \mathcal{M} , if

$$\bigwedge_{i=1}^{m} P(f_{u_i}(a), f_{v_i}(a))$$

and

$$\forall x \forall y \Big(P(x,y) \Rightarrow \bigwedge_{i=1}^{m} P(f_{u_i}(x), f_{v_i}(x)) \Big)$$

are valid in \mathcal{M} , then

 $\exists z P(z, z)$

is also valid in \mathcal{M} . But then Φ_S is valid in *every* first-order structure \mathcal{M} , and thus it is valid.

To finish the proof, assume that \mathcal{M} is any first-order structure such that

$$\bigwedge_{i=1}^{m} P(f_{u_i}(a), f_{v_i}(a))$$
 (*1)

and

$$\forall x \forall y \Big(P(x,y) \Rightarrow \bigwedge_{i=1}^{m} P(f_{u_i}(x), f_{v_i}(x)) \Big)$$
(*2)

are valid in \mathcal{M} . Using $(*_1)$, by repeated application on $(*_2)$, we deduce that

$$P(f_{u_{i_1}u_{i_2}\cdots u_{i_n}}(a), f_{v_{i_1}v_{i_2}\cdots v_{i_n}}(a)),$$

is valid in \mathcal{M} . For example, since (u_{i_1}, v_{i_1}) is a pair in the PCP instance, by $(*_1)$ the proposition $P(f_{u_{i_1}}(a), f_{v_{i_1}}(a))$ holds, so by $(*_2)$ with $x = f_{u_{i_1}}(a)$ and $v = f_{v_{i_1}}(a)$, we get the implication

$$P(f_{u_{i_1}}(a), f_{v_{i_1}}(a)) \Rightarrow \bigwedge_{i=1}^m P(f_{u_i}(f_{u_{i_1}}(a)), f_{v_i}(f_{v_{i_1}}(a)))$$

and since $P(f_{u_{i_1}}(a), f_{v_{i_1}}(a))$ holds, we deduce that $\bigwedge_{i=1}^m P(f_{u_i}(f_{u_{i_1}}(a)), f_{v_i}(f_{v_{i_1}}(a)))$ holds, and consequently $P(f_{u_{i_2}}(f_{u_{i_1}}(a)), f_{v_{i_2}}(f_{v_{i_1}}(a))) = P(f_{u_{i_1}u_{i_2}}(a), f_{v_{i_1}v_{i_2}}(a))$ holds.

Since by hypothesis

 $u_{i_1}u_{i_2}\cdots u_{i_n}=v_{i_1}v_{i_2}\cdots v_{i_n},$

we deduce that $\exists z P(z, z)$ is valid in \mathcal{M} , and so Φ_S is valid in \mathcal{M} , as claimed.

There are other ways of proving Church's theorem. Among other sources, see Shoenfield [67] (Section 6.8) and Machtey and Young [51] (Chapter 4, theorem 4.3.6). These proofs are rather long and involve complicated arguments. Floyd's proof has the virtue of being quite short and transparent, if we accept the undecidability of the PCP.

Lewis shows the stronger result than even with a *single* unary function symbol f, one constant a, and one binary predicate symbol P, the validity problem is undecidable; see

Lewis [49] (Chapter IIC). Lewis' proof is a very clever reduction of a tiling problem. Lewis' book also contains an extensive classification of undecidable classes of first-order sentences. On the positive side, Dreben and Goldfarb [14] contains a very complete study of classes of first-order sentences for which the validity problem *is* decidable.

Chapter 13

Computational Complexity; \mathcal{P} and \mathcal{NP}

13.1 The Class \mathcal{P}

In the previous two chapters, we clarified what it means for a problem to be decidable or undecidable. This chapter is heavily inspired by Lewis and Papadimitriou's excellent treatment [50].

In principle, if a problem is decidable, then there is an algorithm (i.e., a procedure that halts for every input) that decides every instance of the problem.

However, from a practical point of view, knowing that a problem is decidable may be useless, if the number of steps (*time complexity*) required by the algorithm is excessive, for example, exponential in the size of the input, or worse.

For instance, consider the *traveling salesman problem*, which can be formulated as follows:

We have a set $\{c_1, \ldots, c_n\}$ of cities, and an $n \times n$ matrix $D = (d_{ij})$ of nonnegative integers, the *distance matrix*, where d_{ij} denotes the distance between c_i and c_j , which means that $d_{ii} = 0$ and $d_{ij} = d_{ji}$ for all $i \neq j$.

The problem is to find a *shortest tour* of the cities, that is, a permutation π of $\{1, \ldots, n\}$ so that the *cost*

$$C(\pi) = d_{\pi(1)\pi(2)} + d_{\pi(2)\pi(3)} + \dots + d_{\pi(n-1)\pi(n)} + d_{\pi(n)\pi(1)}$$

is as small as possible (minimal).

One way to solve the problem is to consider all possible tours, i.e., n! permutations. Actually, since the starting point is irrelevant, we need only consider (n-1)! tours, but this still grows very fast. For example, when n = 40, it turns out that 39! exceeds 10^{45} , a huge number. Consider the 4×4 symmetric matrix given by

$$D = \begin{pmatrix} 0 & 2 & 1 & 1 \\ 2 & 0 & 1 & 1 \\ 1 & 1 & 0 & 3 \\ 1 & 1 & 3 & 0 \end{pmatrix},$$

and the budget B = 4. The tour specified by the permutation

$$\pi = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 4 & 2 & 3 \end{pmatrix}$$

has cost 4, since

$$c(\pi) = d_{\pi(1)\pi(2)} + d_{\pi(2)\pi(3)} + d_{\pi(3)\pi(4)} + d_{\pi(4)\pi(1)}$$

= $d_{14} + d_{42} + d_{23} + d_{31}$
= $1 + 1 + 1 + 1 = 4.$

The cities in this tour are traversed in the order

Remark: The permutation π shown above is described in Cauchy's two-line notation,

$$\pi = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 4 & 2 & 3 \end{pmatrix},$$

where every element in the second row is the image of the element immediately above it in the first row: thus

$$\pi(1) = 1, \ \pi(2) = 4, \ \pi(3) = 2, \ \pi(4) = 3.$$

Thus, to capture the essence of practically feasible algorithms, we must limit our computational devices to run only for a number of steps that is bounded by a *polynomial* in the length of the input.

We are led to the definition of polynomially bounded computational models.

We talked about problems being decidable in polynomial time. Obviously, this is equivalent to deciding some property of a certain class of objects, for example, finite graphs.

Our framework requires that we first encode these classes of objects as strings (or numbers), since \mathcal{P} consists of languages.

Thus, when we say that a property is decidable in polynomial time, we are really talking about the encoding of this property as a language. Thus, we have to be careful about these encodings, but it is rare that encodings cause problems. **Definition 13.1.** A deterministic Turing machine M is said to be *polynomially bounded* if there is a polynomial p(X) so that the following holds: for every input $x \in \Sigma^*$, there is no ID ID_n so that

 $ID_0 \vdash ID_1 \vdash^* ID_{n-1} \vdash ID_n$, with n > p(|x|),

where $ID_0 = q_0 x$ is the starting ID.

A language $L \subseteq \Sigma^*$ is *polynomially decidable* if there is a polynomially bounded Turing machine that accepts L. The family of all polynomially decidable languages is denoted by \mathcal{P} .

Remark: Even though Definition 13.1 is formulated for Turing machines, it can also be formulated for other models, such as RAM programs. The reason is that the conversion of a Turing machine into a RAM program (and vice versa) produces a program (or a machine) whose size is polynomial in the original device.

The following proposition, although trivial, is useful:

Proposition 13.1. The class \mathcal{P} is closed under complementation.

Of course, many languages do not belong to \mathcal{P} . One way to obtain such languages is to use a diagonal argument. But there are also many natural languages that are not in \mathcal{P} , although this may be very hard to prove for some of these languages.

Let us consider a few more problems in order to get a better feeling for the family \mathcal{P} .

13.2 Directed Graphs, Paths

Recall that a *directed graph*, G, is a pair G = (V, E), where $E \subseteq V \times V$. Every $u \in V$ is called a *node* (or *vertex*) and a pair $(u, v) \in E$ is called an *edge* of G.

We will restrict ourselves to *simple graphs*, that is, graphs without edges of the form (u, u); equivalently, G = (V, E) is a simple graph if whenever $(u, v) \in E$, then $u \neq v$.

Given any two nodes $u, v \in V$, a path from u to v is any sequence of n + 1 edges $(n \ge 0)$

$$(u, v_1), (v_1, v_2), \ldots, (v_n, v).$$

(If n = 0, a path from u to v is simply a single edge, (u, v).)

A graph G is *strongly connected* if for every pair $(u, v) \in V \times V$, there is a path from u to v. A *closed path*, or cycle, is a path from some node u to itself.

We will restrict out attention to finite graphs, i.e. graphs (V, E) where V is a finite set.

Definition 13.2. Given a graph G, an *Eulerian cycle* is a cycle in G that passes through all the nodes (possibly more than once) and every edge of G exactly once. A *Hamiltonian cycle* is a cycle that passes through all the nodes exactly once (note, some edges may not be traversed at all).

Eulerian Cycle Problem: Given a graph G, is there an Eulerian cycle in G? Hamiltonian Cycle Problem: Given a graph G, is there an Hamiltonian cycle in G?

13.3 Eulerian Cycles

The following graph is a directed graph version of the Königsberg bridge problem, solved by Euler in 1736.

The nodes A, B, C, D correspond to four areas of land in Königsberg and the edges to the seven bridges joining these areas of land.



Figure 13.1: A directed graph modeling the Königsberg bridge problem.

The problem is to find a closed path that crosses every bridge exactly once and returns to the starting point.

In fact, the problem is unsolvable, as shown by Euler, because some nodes do not have the same number of incoming and outgoing edges (in the undirected version of the problem, some nodes do not have an even degree.)

It may come as a surprise that the Eulerian Cycle Problem does have a polynomial time algorithm, but that so far, not such algorithm is known for the Hamiltonian Cycle Problem. The reason why the Eulerian Cycle Problem is decidable in polynomial time is the following theorem due to Euler:

Theorem 13.2. A graph G = (V, E) has an Eulerian cycle iff the following properties hold:

- (1) The graph G is strongly connected.
- (2) Every node has the same number of incoming and outgoing edges.

Proving that properties (1) and (2) hold if G has an Eulerian cycle is fairly easy. The converse is harder, but not that bad (try!).

Theorem 13.2 shows that it is necessary to check whether a graph is strongly connected. This can be done by computing the transitive closure of E, which can be done in polynomial time (in fact, $O(n^3)$).

Checking property (2) can clearly be done in polynomial time. Thus, the Eulerian cycle problem is in \mathcal{P} . Unfortunately, no theorem analogous to Theorem 13.2 is known for Hamiltonian cycles.

13.4 Hamiltonian Cycles

A game invented by Sir William Hamilton in 1859 uses a regular solid dodecahedron whose twenty vertices are labeled with the names of famous cities.

The player is challenged to "travel around the world" by finding a closed cycle along the edges of the dodecahedron which passes through every city exactly once (this is the undirected version of the Hamiltonian cycle problem). See Figure 13.2.



Figure 13.2: A tour "around the world."

In graphical terms, assuming an orientation of the edges between cities, the graph D shown in Figure 13.2 is a plane projection of a regular dodecahedron and we want to know if there is a Hamiltonian cycle in this directed graph. Finding a Hamiltonian cycle in this graph does not appear to be so easy!

A solution is shown in Figure 13.3 below.



Figure 13.3: A Hamiltonian cycle in D.

13.5 Propositional Logic and Satisfiability

We define the syntax and the semantics of propositions in conjunctive normal form (CNF).

The syntax has to do with the legal form of propositions in CNF. Such propositions are interpreted as truth functions, by assigning truth values to their variables.

We begin by defining propositions in CNF. Such propositions are constructed from a countable set, **PV**, of *propositional (or boolean) variables*, say

$$\mathbf{PV} = \{x_1, x_2, \dots, \},\$$

using the connectives \land (and), \lor (or) and \neg (negation).

Definition 13.3. We define a *literal (or atomic proposition)*, L, as L = x or $L = \neg x$, also denoted by \overline{x} , where $x \in \mathbf{PV}$.

A *clause*, C, is a disjunction of pairwise distinct literals,

$$C = (L_1 \lor L_2 \lor \cdots \lor L_m).$$

Thus, a clause may also be viewed as a nonempty set

$$C = \{L_1, L_2, \ldots, L_m\}.$$

We also have a special clause, the *empty clause*, denoted \perp or \square (or {}). It corresponds to the truth value false.

A proposition in CNF, or boolean formula, P, is a conjunction of pairwise distinct clauses

$$P = C_1 \wedge C_2 \wedge \dots \wedge C_n.$$

Thus, a boolean formula may also be viewed as a nonempty set

$$P = \{C_1, \ldots, C_n\},\$$

but this time, the comma is interpreted as conjunction. We also allow the proposition \perp , and sometimes the proposition \top (corresponding to the truth value true).

For example, here is a boolean formula:

$$P = \{ (x_1 \lor x_2 \lor x_3), (\overline{x_1} \lor x_2), (\overline{x_2} \lor x_3), (\overline{x_3} \lor x_1), (\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}) \}.$$

In order to interpret boolean formulae, we use truth assignments.

Definition 13.4. We let $BOOL = \{F, T\}$, the set of *truth values*, where F stands for false and T stands for true. A *truth assignment (or valuation)*, v, is any function $v: PV \to BOOL$.

Example 13.1. The function $v_F \colon \mathbf{PV} \to \text{BOOL}$ given by

$$v_F(x_i) = \mathbf{F}$$
 for all $i \ge 1$

is a truth assignment, and so is the function $v_T \colon \mathbf{PV} \to \text{BOOL}$ given by

$$v_T(x_i) = \mathbf{T}$$
 for all $i \ge 1$.

The function $v: \mathbf{PV} \to \text{BOOL}$ given by

$$v(x_1) = \mathbf{T}$$

$$v(x_2) = \mathbf{F}$$

$$v(x_3) = \mathbf{T}$$

$$v(x_i) = \mathbf{T} \text{ for all } i \ge 4$$

is also a truth assignment.

Definition 13.5. Given a truth assignment $v \colon \mathbf{PV} \to \text{BOOL}$, we define the *truth value* $\hat{v}(X)$ of a literal, clause, and boolean formula, X, using the following recursive definition:

- (1) $\widehat{v}(\perp) = \mathbf{F}, \ \widehat{v}(\top) = \mathbf{T}.$
- (2) $\widehat{v}(x) = v(x)$, if $x \in \mathbf{PV}$.

(3)
$$\widehat{v}(\overline{x}) = \overline{v(x)}$$
, if $x \in \mathbf{PV}$, where $\overline{v(x)} = \mathbf{F}$ if $v(x) = \mathbf{T}$ and $\overline{v(x)} = \mathbf{T}$ if $v(x) = \mathbf{F}$.

- (4) $\hat{v}(C) = \mathbf{F}$ if C is a clause and iff $\hat{v}(L_i) = \mathbf{F}$ for all literals L_i in C, otherwise **T**.
- (5) $\hat{v}(P) = \mathbf{T}$ if P is a boolean formula and iff $\hat{v}(C_j) = \mathbf{T}$ for all clauses C_j in P, otherwise **F**.

Since a boolean formula P only contains a finite number of variables, say $\{x_{i_1}, \ldots, x_{i_n}\}$, one should expect that its truth value $\hat{v}(P)$ depends only on the truth values assigned by the truth assignment v to the variables in the set $\{x_{i_1}, \ldots, x_{i_n}\}$, and this is indeed the case. The following proposition is easily shown by induction on the depth of P (viewed as a tree).

Proposition 13.3. Let P be a boolean formula containing the set of variables $\{x_{i_1}, \ldots, x_{i_n}\}$. If $v_1: \mathbf{PV} \to \text{BOOL}$ and $v_2: \mathbf{PV} \to \text{BOOL}$ are any truth assignments agreeing on the set of variables $\{x_{i_1}, \ldots, x_{i_n}\}$, which means that

$$v_1(x_{i_j}) = v_2(x_{i_j}) \text{ for } j = 1, \dots, n,$$

then $\widehat{v}_1(P) = \widehat{v}_2(P)$.

In view of Proposition 13.3, given any boolean formula P, we only need to specify the values of a truth assignment v for the variables occurring on P.

Example 13.2. Given the boolean formula

$$P = \{ (x_1 \lor x_2 \lor x_3), (\overline{x_1} \lor x_2), (\overline{x_2} \lor x_3), (\overline{x_3} \lor x_1), (\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}) \},$$

we only need to specify $v(x_1), v(x_2), v(x_3)$. Thus there are $2^3 = 8$ distinct truth assignments:

${f F},{f F},{f F}$	$\mathbf{T},\mathbf{F},\mathbf{F}$
$\mathbf{F}, \mathbf{F}, \mathbf{T}$	$\mathbf{T}, \mathbf{F}, \mathbf{T}$
$\mathbf{F},\mathbf{T},\mathbf{F}$	$\mathbf{T},\mathbf{T},\mathbf{F}$
$\mathbf{F},\mathbf{T},\mathbf{T}$	$\mathbf{T}, \mathbf{T}, \mathbf{T}.$

In general, there are 2^n distinct truth assignments to n distinct variables.

Example 13.3. Here is an example showing the evaluation of the truth value $\hat{v}(P)$ for the boolean formula

$$P = (x_1 \lor x_2 \lor x_3) \land (\overline{x_1} \lor x_2) \land (\overline{x_2} \lor x_3) \land (\overline{x_3} \lor x_1) \land (\overline{x_1} \lor \overline{x_2} \lor \overline{x_3})$$

= { (x₁ \lap x₂ \lap x₃), (\vec{x_1} \lap x_2), (\vec{x_2} \lap x_3), (\vec{x_3} \lap x_1), (\vec{x_1} \lor \vec{x_2} \lor \vec{x_3})},
and the truth assignment

$$v(x_1) = \mathbf{T}, \quad v(x_2) = \mathbf{F}, \quad v(x_3) = \mathbf{F}.$$

For the literals, we have

$$\widehat{v}(x_1) = \mathbf{T}, \quad \widehat{v}(x_2) = \mathbf{F}, \quad \widehat{v}(x_3) = \mathbf{F}, \quad \widehat{v}(\overline{x_1}) = \mathbf{F}, \quad \widehat{v}(\overline{x_2}) = \mathbf{T}, \quad \widehat{v}(\overline{x_3}) = \mathbf{T},$$

for the clauses

$$\widehat{v}(x_1 \lor x_2 \lor x_3) = \widehat{v}(x_1) \lor \widehat{v}(x_2) \lor \widehat{v}(x_3) = \mathbf{T} \lor \mathbf{F} \lor \mathbf{F} = \mathbf{T}, \widehat{v}(\overline{x_1} \lor x_2) = \widehat{v}(\overline{x_1}) \lor \widehat{v}(x_2) = \mathbf{F} \lor \mathbf{F} = \mathbf{F}, \widehat{v}(\overline{x_2} \lor x_3) = \widehat{v}(\overline{x_2}) \lor \widehat{v}(x_3) = \mathbf{T} \lor \mathbf{F} = \mathbf{T}, \widehat{v}(\overline{x_3} \lor x_1) = \widehat{v}(\overline{x_3}) \lor \widehat{v}(x_1) = \mathbf{T} \lor \mathbf{T} = \mathbf{T}, \widehat{v}(\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}) = \widehat{v}(\overline{x_1}) \lor \widehat{v}(\overline{x_2}) \lor \widehat{v}(\overline{x_3}) = \mathbf{F} \lor \mathbf{T} \lor \mathbf{T} = \mathbf{T},$$

and for the conjunction of the clauses,

$$\widehat{v}(P) = \widehat{v}(x_1 \lor x_2 \lor x_3) \land \widehat{v}(\overline{x_1} \lor x_2) \land \widehat{v}(\overline{x_2} \lor x_3) \land \widehat{v}(\overline{x_3} \lor x_1) \land \widehat{v}(\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}) \\ = \mathbf{T} \land \mathbf{F} \land \mathbf{T} \land \mathbf{T} \land \mathbf{T} = \mathbf{F}.$$

Therefore, $\hat{v}(P) = \mathbf{F}$.

Definition 13.6. We say that a truth assignment v satisfies a boolean formula P, if $\hat{v}(P) = \mathbf{T}$. In this case, we also write

$$v \models P$$

A boolean formula P is *satisfiable* if $v \models P$ for some truth assignment v, otherwise, it is *unsatisfiable*. A boolean formula P is *valid (or a tautology)* if $v \models P$ for all truth assignments v, in which case we write

 $\models P.$

One should check that the boolean formula

$$P = \{ (x_1 \lor x_2 \lor x_3), (\overline{x_1} \lor x_2), (\overline{x_2} \lor x_3), (\overline{x_3} \lor x_1), (\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}) \}$$

is **un**satisfiable.

One may think that it is easy to test whether a proposition is satisfiable or not. Try it, it is not that easy!

As a matter of fact, the *satisfiability problem*, testing whether a boolean formula is satisfiable, also denoted SAT, is not known to be in \mathcal{P} . Moreover, it is an \mathcal{NP} -complete problem (see Section 13.6). Most people believe that the satisfiability problem is **not** in \mathcal{P} , but a proof still eludes us!

Before we explain what is the class \mathcal{NP} , we state the following result.

Proposition 13.4. The satisfiability problem for clauses containing at most two literals (2-satisfiability, or 2-SAT) is solvable in polynomial time.

Proof sketch. The first step consists in observing that if every clause in P contains at most two literals, then we can reduce the problem to testing satisfiability when every clause has exactly two literals.

Indeed, if P contains some clause (x), then any valuation satisfying P must make x true. Then all clauses containing x will be true, and we can delete them, whereas we can delete \overline{x} from every clause containing it, since \overline{x} is false.

Similarly, if P contains some clause (\overline{x}) , then any valuation satisfying P must make x false. Then all clauses containing \overline{x} will be true, and we can delete them, whereas we can delete x from every clause containing it.

Thus in a finite number of steps, either all the clauses were satisfied and P is satisfiable, or we get the empty clause and P is unsatisfiable, or we get a set of clauses with exactly two literals. The number of steps is clearly linear in the number of literals in P. Here are some examples illustrating the three possible oucomes.

(1) Consider the conjunction of clauses

$$P_1 = (x_1 \lor \overline{x_2}) \land (x_2) \land (x_1 \lor x_3) \land (x_2 \lor \overline{x_3})$$

We must set x_2 to **T**, so $(x_1 \vee \overline{x_2})$ becomes (x_1) and $(x_2 \vee \overline{x_3})$ becomes **T** and can be deleted. We now have

$$P = (x_1) \land (x_1 \lor x_3).$$

We must set x_1 to **T**, so $(x_1 \vee x_3)$ becomes **T** and all the clauses are satisfied.

(2) Consider the conjunction of clauses

$$P_2 = (x_1) \land (x_3) \land (\overline{x_1} \lor x_2) \land (\overline{x_2} \lor \overline{x_3})$$

We must set x_1 to **T**, so $(\overline{x_1} \lor x_2)$ becomes (x_2) . We now have

$$(x_3) \wedge (x_2) \wedge (\overline{x_2} \vee \overline{x_3}).$$

We must set x_3 to **T**, so $(\overline{x_2} \lor \overline{x_3})$ becomes $(\neg x_2)$. We now have

 $(x_2) \wedge (\overline{x_2}).$

We must set x_2 to **T**, so $(\overline{x_2})$ becomes the empty clause, which means that P_2 is unsatisfiable.

For the second step, we construct a directed graph from P. The purpose of this graph is to propagate truth. The nodes of this graph are the literals in P, and edges are defined as follows:

- (1) For every clause $(\overline{x} \lor y)$, there is an edge from x to y and an edge from \overline{y} to \overline{x} .
- (2) For every clause $(x \lor y)$, there is an edge from \overline{x} to y and an edge from \overline{y} to x
- (3) For every clause $(\overline{x} \vee \overline{y})$, there is an edge from x to \overline{y} and an edge from y to \overline{x} .

Then it can be shown that P is unsatisfiable iff there is some x so that there is a cycle containing x and \overline{x} . As a consequence, 2-satisfiability is in \mathcal{P} .

Example 13.4. Consider the following conjunction of clauses:

 $P = (x_1 \lor \overline{x_2}) \land (x_1 \lor x_2) \land (x_2 \lor \overline{x_3}).$

It is satisfied by any valuation v such that $v(x_1) = \mathbf{T}$, and if $v(x_2) = \mathbf{F}$ then $v(x_3) = \mathbf{F}$. The construction of the graph associated with P is shown in Figure 13.4.



Figure 13.4: The graph corresponding to the clauses of Example 13.4.

13.6 The Class \mathcal{NP} , Polynomial Reducibility, \mathcal{NP} -Completeness

One will observe that the hard part in trying to solve either the Hamiltonian cycle problem or the satisfiability problem, SAT, is to *find* a solution, but that *checking* that a candidate solution is indeed a solution can be done easily in polynomial time.

This is the essence of problems that can be solved *nondetermistically* in polynomial time: a solution can be guessed and then checked in polynomial time.

Definition 13.7. A nondeterministic Turing machine M is said to be *polynomially bounded* if there is a polynomial p(X) so that the following holds: For every input $x \in \Sigma^*$, there is no ID ID_n so that

$$ID_0 \vdash ID_1 \vdash^* ID_{n-1} \vdash ID_n$$
, with $n > p(|x|)$,

where $ID_0 = q_0 x$ is the starting ID.

A language $L \subseteq \Sigma^*$ is *nondeterministic polynomially decidable* if there is a polynomially bounded nondeterministic Turing machine that accepts L. The family of all nondeterministic polynomially decidable languages is denoted by \mathcal{NP} .

Observe that Definition 13.7 has to do with testing *membership* of a string w in a language L. Here the language L consists of the strings encodings all objects satisfying a given property P. So in this sense, a reason (a certificate) why $w \in L$ is not actually produced by the machine. The machine just decides whether $w \in L$, that is, whether the object coded by w satisfies the property P.

For example, if the problem is the satisfiability of sets of clauses, then L is the set SAT of strings encoding all satisfiable propositions in CNF. Given any proposition P in CNF encoded as a string s(P), a Turing machine accepting SAT will nondeterminiscally guess a truth assignment, and check in polynomial time whether this truth assignment satisfies P.

In the case of clauses we can easily design such a language. The key point is that we can represent the propositional variable x_i as a string in binary, namely as the binary representation $bin(x_i)$ of the number *i*. Our language for encoding clauses uses the alphabet

$$\Delta = \{0, 1, \wedge, \lor, \neg, (,)\}.$$

The encoding s(P) (a string in Δ^*) of a proposition P in CNF is defined recursively as follows.

- (1) The variable x_i is represented the binary representation $s(x_i) = bin(i)$ of the number i.
- (2) The literal $\neg x_i$ is represented by the string $s(\neg x_i) = \neg s(x_i) = \neg bin(i)$.
- (3) The clause

$$C = (L_1 \lor \cdots \lor L_m)$$

is represented by the string

$$s(C) = (s(L_1) \lor \cdots \lor s(L_m)).$$

(3) The proposition P in CNF

$$P = C_1 \wedge \dots \wedge C_p$$

is represented by the string

$$s(P) = s(C_1) \wedge \dots \wedge s(C_p).$$

Example 13.5. The proposition

$$P = (x_1 \lor x_2 \lor x_3) \land (\neg x_1 \lor \neg x_2) \land (x_1 \lor \neg x_3) \land (x_2 \lor x_3)$$

is encoded by the string

$$s(P) = (1 \lor 10 \lor 11) \land (\neg 1 \lor \neg 10) \land (1 \lor \neg 11) \land (10 \lor 11).$$

If we assign the truth value **F** to x_1 , to satisfy the clause $(x_1 \vee \neg x_3)$ we must assign **F** to x_3 , and then to satisfy the clauses $(x_1 \vee x_2 \vee x_3)$ and $(x_2 \vee x_3)$, we must assign **T** to x_2 .

If we assign the truth value **T** to x_1 , to satisfy the clause $(\neg x_1 \lor \neg x_2)$ we must assign **F** to x_2 , and then to satisfy the clause $(x_2 \lor x_3)$, we must assign **T** to x_3 .

Therefore there are two truth assignments satisfying the proposition P,

$$x_1 := \mathbf{F}, \ x_2 := \mathbf{T}, \ x_3 := \mathbf{F}$$

 $x_1 := \mathbf{T}, \ x_2 := \mathbf{F}, \ x_3 := \mathbf{T}.$

The language SAT $\subseteq \Delta^*$ consists of all string encodings s(P) of propositions that are satisfiable. For example, the string

$$s(P) = (1 \lor 10 \lor 11) \land (\neg 1 \lor \neg 10) \land (1 \lor \neg 11) \land (10 \lor 11)$$

belongs to the language SAT. On the other hand, the proposition

$$(x_1 \lor x_2) \land (\neg x_1 \lor x_2) \land (\neg x_2 \lor x_1) \land (\neg x_1 \lor \neg x_2)$$

is not satisfiable, and thus its encoding

$$(1 \lor 10) \land (\neg 1 \lor 10) \land (\neg 10 \lor 1) \land (\neg 1 \lor \neg 10)$$

does *not* belong to SAT.

Remark: The language consisting of all string encodings of propositions in CNF, satisfiable or not, is a context-free language.

Note that a nondeterminitsic Turing machine operating in polynomial time accepting a string in SAT encoding a satisfiable clause does not actually produce a truth assignment, called a certificate, as output. The machine simply accepts or rejects s(P) depending on whether P is satisfiable or not.

Similarly, if the problem is the existence of a Hamiltonian cycle, then L is the set of strings encoding all directed graphs having a Hamiltonian cycle. Given any directed graph G encoded as a string s(G), a Turing machine accepting L will nondeterminiscally guess a cycle in G, and check in polynomial time whether this is a Hamiltonian cycle. But such a Hamiltonian cycle (if any), called a certificate, is not actually produced as output.

Here is a way to encode a simple directed graph G = (V, E). A slight complication arises with *isolated nodes*, which are the nodes $u \in V$ such that there is no edge $(u, v) \in E$ or $(v, u) \in E$ for some $v \in V$, in other words, the nodes that are not the endpoint of any edge.

If $V = \{v_1, \ldots, v_n\}$, as in the case of clauses, we encode the node v_i as the binary representation $s(v_i) = bin(i)$ of the number *i*. We use alphabet

$$\Delta = \{0, 1, \to, (,), \#\}$$

The string encoding s(G) of the graph G = (V, E) is obtained by concatenating the strings $(s(v_i) \to s(v_j))$ in the order where $(s(v_i) \to s(v_j))$ precedes $(s(v_k) \to s(v_l))$ if either i = k and j < l, or i < k, possibly followed by the string

$$\#s(v_{i_1})\#\cdots \#s(v_{i_k})$$

corresponding to the isolated vertices, if any, where v_{i_1}, \ldots, v_{i_k} are listed in increasing order of the indices.

Example 13.6. Consider the graph G = (V, E) shown in Figure 13.5 where $V = \{v_1, \ldots, v_5\}$ consists of five nodes and the set of edges is

$$E = \{ (v_1, v_2), (v_1, v_4), (v_1, v_5), (v_2, v_3), (v_2, v_4), (v_3, v_1), (v_3, v_4), (v_4, v_5), (v_5, v_3) \}.$$

The string encoding of this graph is

$$s(G) = (1 \to 10)(1 \to 100)(1 \to 101)(10 \to 11)(10 \to 100)(11 \to 1)(11 \to 100)$$
$$(100 \to 101)(101 \to 11).$$

Observe that the cycle $v_1 \rightarrow v_2 \rightarrow v_4 \rightarrow v_5 \rightarrow v_3 \rightarrow v_1$ is a Hamiltonian cycle.

The language HAM $\subseteq \Delta^*$ consists of all encodings s(G) of directed graphs G that have a Hamiltonian cycle. Thus for the graph above, $s(G) \in HAM$.

It is possible to give an alternate definition of \mathcal{NP} that explicitly involves certificates. This definition relies on the notion of a polynomially balanced language; see Section 14.3, Definition 14.3. The trick is to consider strings of form $x; y \in \Sigma^*$ (with $x, y \in \Sigma^*$, where ; is a special symbol not in Σ), such that for some given polynomial p(X), we have $|y| \leq p(|x|)$.



Figure 13.5: A pentagonal graph with a Hamiltonian cycle.

If a language L' consisting of strings of the form x; y with $|y| \leq p(|x|)$ (for some given p) is in \mathcal{P} , then the language

$$L = \{ x \in \Sigma^* \mid (\exists y \in \Sigma^*) (x; y \in L') \}$$

is in \mathcal{NP} , and every language in \mathcal{NP} arises in this fashion; see Theorem 14.1. The set of strings $\{y \in \Sigma^* \mid x; y \in L'\}$ can be regarded as the set of certificates for the fact that $x \in L$. The fact that $|y| \leq p(|x|)$ ensures that the certificate y is not too big, so that L' can be accepted *deterministically* in polynomial time. We will come back to this point of view in Section 14.3.

For example, going back to Example 13.5, examples of strings x; y are

$$(1 \lor 10 \lor 11) \land (\neg 1 \lor \neg 10) \land (1 \lor \neg 11) \land (10 \lor 11); \mathbf{FTF}$$

and

$$(1 \lor 10 \lor 11) \land (\neg 1 \lor \neg 10) \land (1 \lor \neg 11) \land (10 \lor 11); \mathbf{TFT}$$

This time, a *deterministic* Turing machine accepts such strings in polynomial time by checking that the certificates **FTF** or **TFT** satisfy the proposition.

For Example 13.6 dealing with Hamiltonian cycles, here is an example of a string x; y where the certificate y is an encoding of a Hamiltonian cycle:

$$(1 \to 10)(1 \to 100)(1 \to 101)(10 \to 11)(10 \to 100)(11 \to 1)(11 \to 100) (100 \to 101)(101 \to 11); 1 \to 10 \to 100 \to 101 \to 11 \to 1.$$

Returning to the definition of \mathcal{NP} given in Definition 13.7, of course, we have the inclusion

$$\mathcal{P} \subseteq \mathcal{NP}$$

but whether or not we have equality is one of the most famous open problems of theoretical computer science and mathematics.

In fact, the question $\mathcal{P} \neq \mathcal{NP}$ is one of the open problems listed by the CLAY Institute, together with the Poincaré conjecture and the Riemann hypothesis, among other problems, and for which one million dollar is offered as a reward! Actually the Poincaré conjecture was setlled by G. Perelman in 2006, but he rejected receiving the prize in 2010! He also declined the Fields Medal which was awarded to him in 2006.

It is easy to check that SAT is in \mathcal{NP} , and so is the Hamiltonian cycle problem.

As we saw in recursion theory, where we introduced the notion of many-one reducibility, in order to compare the "degree of difficulty" of problems, it is useful to introduce the notion of reducibility and the notion of a complete set.

Definition 13.8. A function $f: \Sigma^* \to \Sigma^*$ is *polynomial-time computable* if there is a polynomial p(X) so that the following holds: there is a deterministic Turing machine M computing it so that for every input $x \in \Sigma^*$, there is no ID ID_n so that

$$ID_0 \vdash ID_1 \vdash^* ID_{n-1} \vdash ID_n$$
, with $n > p(|x|)$,

where $ID_0 = q_0 x$ is the starting ID.

Given two languages $L_1, L_2 \subseteq \Sigma^*$, a polynomial-time reduction from L_1 to L_2 is a polynomial-time computable function $f: \Sigma^* \to \Sigma^*$ so that for all $u \in \Sigma^*$,

$$u \in L_1$$
 iff $f(u) \in L_2$

The notation $L_1 \leq_P L_2$ is often used to denote the fact that there is polynomial-time reduction from L_1 to L_2 . Sometimes, the notation $L_1 \leq_m^P L_2$ is used to stress that this is a many-to-one reduction (that is, f is not necessarily injective). This type of reduction is also known as a *Karp reduction*.

A polynomial reduction $f: \Sigma^* \to \Sigma^*$ from a language L_1 to a language L_2 is a method that converts in polynomial time every string $u \in \Sigma^*$ (viewed as an instance of a problem A encoded by language L_1) to a string $f(u) \in \Sigma^*$ (viewed as an instance of a problem Bencoded by language L_2) in such way that membership in L_1 , that is $u \in L_1$, is equivalent to membership in L_2 , that is $f(u) \in L_2$.

As a consequence, if we have a procedure to decide membership in L_2 (to solve every instance of problem B), then we have a procedure for solving membership in L_1 (to solve every instance of problem A), since given any $u \in L_1$, we can first apply f to u to produce f(u), and then apply our procedure to decide whether $f(u) \in L_2$; the defining property of f says that this is equivalent to deciding whether $u \in L_1$. Furthermore, if the procedure for deciding membership in L_2 runs deterministically in polynomial time, since f runs deterministically in polynomial time, so does the procedure for deciding membership in L_1 , and similarly if the procedure for deciding membership in L_2 runs non deterministically in polynomial time. For the above reason, we see that membership in L_2 can be considered at least as hard as membership in L_1 , since any method for deciding membership in L_2 yields a method for deciding membership in L_1 . Thus, if we view L_1 an encoding a problem A and L_2 as encoding a problem B, then B is at least as hard as A.

The following version of Proposition 9.16 for polynomial-time reducibility is easy to prove.

Proposition 13.5. Let A, B, C be subsets of \mathbb{N} (or Σ^*). The following properties hold:

- (1) If $A \leq_P B$ and $B \leq_P C$, then $A \leq_P C$.
- (2) If $A \leq_P B$ then $\overline{A} \leq_P \overline{B}$.
- (3) If $A \leq_P B$ and $B \in \mathcal{NP}$, then $A \in \mathcal{NP}$.
- (4) If $A \leq_P B$ and $A \notin \mathcal{NP}$, then $B \notin \mathcal{NP}$.
- (5) If $A \leq_P B$ and $B \in \mathcal{P}$, then $A \in \mathcal{P}$.
- (6) If $A \leq_P B$ and $A \notin \mathcal{P}$, then $B \notin \mathcal{P}$.

Intuitively, we see that if L_1 is a hard problem and L_1 can be reduced to L_2 in polynomial time, then L_2 is also a hard problem.

For example, one can construct a polynomial reduction from the Hamiltonian cycle problem to the satisfiability problem SAT. Given a directed graph G = (V, E) with n nodes, say $V = \{1, \ldots, n\}$, we need to construct in polynomial time a set $F = \tau(G)$ of clauses such that G has a Hamiltonian cycle iff $\tau(G)$ is satisfiable. We need to describe a permutation of the nodes that forms a Hamiltonian cycle. For this we introduce n^2 boolean variables x_{ij} , with the intended interpretation that x_{ij} is true iff node i is the jth node in a Hamiltonian cycle.

To express that at least one node must appear as the jth node in a Hamiltonian cycle, we have the n clauses

$$(x_{1j} \lor x_{2j} \lor \dots \lor x_{nj}), \quad 1 \le j \le n.$$

$$(1)$$

The conjunction of these clauses is satisfied iff for every j = 1, ..., n there is some node *i* which is the *j*th node in the cycle. These *n* clauses can be produced in time $O(n^2)$.

To express that only one node appears in the cycle, we have the clauses

$$(\overline{x_{ij}} \lor \overline{x_{kj}}), \quad 1 \le i, j, k \le n, \ i \ne k.$$
 (2)

Since $(\overline{x_{ij}} \vee \overline{x_{kj}})$ is equivalent to $(\overline{x_{ij} \wedge x_{kj}})$, each such clause asserts that no two distinct nodes may appear as the *j*th node in the cycle. Let S_1 be the set of all clauses of type (1) or (2). These n^3 clauses can be produced in time $O(n^3)$.

The conjunction of the clauses in S_1 assert that exactly one node appear at the *j*th node in the Hamiltonian cycle. We still need to assert that each node *i* appears exactly once in the cycle. For this, we have the clauses

$$(x_{i1} \lor x_{i2} \lor \dots \lor x_{in}), \quad 1 \le i \le n, \tag{3}$$

and

$$(\overline{x_{ij}} \lor \overline{x_{ik}}), \quad 1 \le i, j, k \le n, \ j \ne k.$$
 (4)

Let S_2 be the set of all clauses of type (3) or (4). These n^3 clauses can be produced in time $O(n^3)$.

The conjunction of the clauses in $S_1 \cup S_2$ asserts that the x_{ij} represents a bijection of $\{1, 2, \ldots, n\}$, in the sense that for any truth assignment v satisfying all these clauses, $i \mapsto j$ iff $v(x_{ij}) = \mathbf{T}$ defines a bijection of $\{1, 2, \ldots, n\}$.

It remains to assert that this permutation of the nodes is a Hamiltonian cycle, which means that if x_{ij} and x_{kj+1} are both true then there there must be an edge (i,k). By contrapositive, this equivalent to saying that if (i,k) is not an edge of G, then $(x_{ij} \wedge x_{kj+1})$ is true, which as a clause is equivalent to $(\overline{x_{ij}} \vee \overline{x_{kj+1}})$.

Therefore, for all (i, k) such that $(i, k) \notin E$ (with $i, k \in \{1, 2, ..., n\}$), we have the clauses

$$(\overline{x_{ij}} \lor \overline{x_{k\,j+1 \pmod{n}}}), \quad j = 1, \dots, n.$$
(5)

Let S_3 be the set of clauses of type (5). These n clauses can be produced in time $O(n^2)$.

The conjunction of all the clauses in $S_1 \cup S_2 \cup S_3$ is the boolean formula $F = \tau(G)$. It can be produced in time $O(n^3)$.

We leave it as an exercise to prove that G has a Hamiltonian cycle iff $F = \tau(G)$ is satisfiable.

Example 13.7. Here is an example of a graph with four nodes and four edges shown in Figure 13.6. The Hamiltonian circuit is (x_4, x_3, x_1, x_2) .

It is also possible to construct a reduction of the satisfiability problem to the Hamiltonian cycle problem but this is harder. It is easier to construct this reduction in two steps by introducing an intermediate problem, the exact cover problem, and to provide a polynomial reduction from the satisfiability problem to the exact cover problem, and a polynomial reduction from the exact cover problem to the Hamiltonian cycle problem. These reductions are carried out in Section 14.2.

The above construction of a set $F = \tau(G)$ of clauses from a graph G asserting that G has a Hamiltonian cycle iff F is satisfiable illustrates the expressive power of propositional logic.

Remarkably, *every* language in \mathcal{NP} can be reduced to SAT. Thus, SAT is a hardest language in \mathcal{NP} (since it is in \mathcal{NP}).

Definition 13.9. A language L is \mathcal{NP} -hard if there is a polynomial reduction from every language $L_1 \in \mathcal{NP}$ to L. A language L is \mathcal{NP} -complete if $L \in \mathcal{NP}$ and L is \mathcal{NP} -hard.



Figure 13.6: A directed graph with a Hamiltonian

Thus, an \mathcal{NP} -hard language is as hard to decide as any language in \mathcal{NP} .

Remark: There are \mathcal{NP} -hard languages that do not belong to \mathcal{NP} . Such languages are really difficult. A standard example is K_0 , which encodes the halting problem. Since K_0 is not computable, it can't be in \mathcal{NP} . Furthermore, since every language L in \mathcal{NP} is accepted nondeterministically in polynomial time p(X), for some polynomial p(X), for every input wwe can try all computations of length at most p(|w|) (there can be exponentially many, but only a finite number), so every language in \mathcal{NP} is computable. Finally, a Turing machine which takes a clause as input and tries all possible truth assignments and loops iff there is no satisfying assignment can be constructed. We can use this machine to show that 3-SAT can be reduced in polynomial time to K_0 , the details are left as an exercise. Since K_0 is defined in terms of natural numbers and not strings, we need to assume that boolean propositions are first encoded as natural numbers and that our Turing machine for testing satisfiability operates on such numbers. Such a machine may not run in polynomial time because of the steps needed for decoding but this does not matter. What is important is that the reduction works in polynomial time. An example of a computable \mathcal{NP} -hard language not in \mathcal{NP} will be described after Theorem 13.7.

The importance of \mathcal{NP} -complete languages stems from the following theorem which follows immediately from Proposition 13.5.

Theorem 13.6. Let L be an \mathcal{NP} -complete language. Then $\mathcal{P} = \mathcal{NP}$ iff $L \in \mathcal{P}$.

There are analogies between \mathcal{P} and the class of computable sets, and \mathcal{NP} and the class of listable sets, but there are also important differences. One major difference is that the

family of computable sets is properly contained in the family of listable sets, but it is an open problem whether \mathcal{P} is properly contained in \mathcal{NP} . We also know that a set L is computable iff both L and \overline{L} are listable, but it is also an open problem whether if both $L \in \mathcal{NP}$ and $\overline{L} \in \mathcal{NP}$, then $L \in \mathcal{P}$. This suggests defining

$$\mathrm{co}\mathcal{NP} = \{\overline{L} \mid L \in \mathcal{NP}\},\$$

that is, coNP consists of all complements of languages in NP. Since $P \subseteq NP$ and P is closed under complementation,

$$\mathcal{P} \subseteq \mathrm{co}\mathcal{N}\mathcal{P},$$

and thus

$$\mathcal{P} \subseteq \mathcal{NP} \cap \mathrm{co}\mathcal{NP},$$

but nobody knows whether the inclusion is proper. There are languages in $\mathcal{NP} \cap co\mathcal{NP}$ not known to be in \mathcal{P} ; see Section 14.3. It is unknown whether \mathcal{NP} is closed under complementation, that is, nobody knows whether $\mathcal{NP} = co\mathcal{NP}$. This is considered unlikely. We will come back to $co\mathcal{NP}$ in Section 14.3.

Next we prove a famous theorem of Steve Cook and Leonid Levin (proven independently): SAT is \mathcal{NP} -complete.

13.7 The Bounded Tiling Problem is \mathcal{NP} -Complete

Instead of showing directly that SAT is \mathcal{NP} -complete, which is rather complicated, we proceed in two steps, as suggested by Lewis and Papadimitriou.

- (1) First, we define a tiling problem adapted from H. Wang (1961) by Harry Lewis, and we prove that it is \mathcal{NP} -complete.
- (2) We show that the tiling problem can be reduced to SAT.

We are given a finite set $\mathcal{T} = \{t_1, \ldots, t_p\}$ of *tile patterns*, for short, *tiles*. We assume that these tiles are unit squares. Copies of these tile patterns may be used to tile a rectangle of predetermined size $2s \times s$ (s > 1). However, there are constraints on the way that these tiles may be adjacent horizontally and vertically.

The *horizontal constraints* are given by a relation $H \subseteq \mathcal{T} \times \mathcal{T}$, and the *vertical constraints* are given by a relation $V \subseteq \mathcal{T} \times \mathcal{T}$.

Thus, a *tiling system* is a triple $T = (\mathcal{T}, V, H)$ with V and H as above.

The bottom row of the rectangle of tiles is specified before the tiling process begins.

	a	с.		a	с.			c.	(d e	е		е	е
				a	,		a	,				,		
	b			b			с			0	ł]		е
с		d ,	c		d ,	d		е,	,	е	e	,	e	
				b			с			C	1			е
	с]		
d		е,	с		d ,	d		е,		е	е	,	e	
				b			с			Ċ	l			e

Example 13.8. For example, consider the following tile patterns:

The horizontal and the vertical constraints are that the letters on adjacent edges match (blank edges do not match).

For s = 3, given the bottom row

a	b		с		d		d			e		
С	с	d	d	е	е		е	е		е	е	

we have the tiling shown below:

		с	c	,	d	d		е	е	1	е	е	1	е	e	
a	J			b			с			d			d			е
a	,			b			с			d			d			е
		с	с		d	d		е	е		е	е		е	e	
a	,			b			с			d			d			e
a	J			b			с			d			d			e
		с	c		d	d		е	е		е	е		е	e	

Formally, the problem is then as follows:

The Bounded Tiling Problem

Given any tiling system (\mathcal{T}, V, H) , any integer s > 1, and any initial row of tiles σ_0 (of length 2s)

$$\sigma_0\colon \{1,2,\ldots,s,s+1,\ldots,2s\} \to \mathcal{T},$$

find a $2s \times s$ -tiling σ extending σ_0 , i.e., a function

$$\sigma \colon \{1, 2, \dots, s, s+1, \dots, 2s\} \times \{1, \dots, s\} \to \mathcal{T}$$

so that

- (1) $\sigma(m, 1) = \sigma_0(m)$, for all m with $1 \le m \le 2s$.
- (2) $(\sigma(m,n), \sigma(m+1,n)) \in H$, for all m with $1 \le m \le 2s 1$, and all n, with $1 \le n \le s$.
- (3) $(\sigma(m,n), \sigma(m,n+1)) \in V$, for all m with $1 \le m \le 2s$, and all n, with $1 \le n \le s-1$.

Example 13.9. In this example the set of tiles is shown in Figure 13.7. The horizontal



Figure 13.7: A set of tiles

constraints are schematically illustrated in Figure 13.8



Figure 13.8: Schematic illustration of the horizontal constraints.



Figure 13.9: Schematic illustration of the vertical constraints.

and the vertical constraints are are schematically illustrated in Figure 13.9. The set of horizontal constraints is shown in Figure 13.10



Figure 13.10: Horizontal constraints.

and the set of vertical constraints is shown in Figure. 13.11 A solution to the puzzle



Figure 13.11: Vertical constraints.

(tiling problem) is shown in Figure 13.12, assuming that the bottom row is given as part of the input.

Yes	Math	95	Fun	
15	Math	Fun	?	
Math	15	Fun	/	

Figure 13.12: A solution to the tiling problem.

Formally, an *instance of the tiling problem* is a triple $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$, where (\mathcal{T}, V, H) is a tiling system, \hat{s} is the string representation of the number $s \geq 2$, in binary and σ_0 is an initial row of tiles (the bottom row).

For example, if s = 1025 (as a decimal number), then its binary representation is $\hat{s} = 10000000001$. The length of \hat{s} is $\log_2 s + 1$.

Recall that the input must be a string. This is why the number s is represented by a string in binary. If we only included a *single* tile σ_0 in position (s + 1, 1), then the length of

the input $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$ would be $\log_2 s + 1 + C + 1 = \log_2 s + C + 2$ for some constant C corresponding to the length of the string encoding (\mathcal{T}, V, H) .

However, the rectangular grid has size $2s^2$, which is *exponential* in the length $\log_2 s + C + 2$ of the input $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$. Thus, it is impossible to check in polynomial time that a proposed solution is a tiling.

However, if we include in the input the bottom row σ_0 of length 2s, then the length of input is $\log_2 s + 1 + C + 2s = \log_2 s + C + 2s + 1$ and the size $2s^2$ or the grid is indeed polynomial in the size of the input.

Theorem 13.7. The tiling problem defined earlier is \mathcal{NP} -complete.

Proof. Let $L \subseteq \Sigma^*$ be any language in \mathcal{NP} and let u be any string in Σ^* . Assume that L is accepted in polynomial time bounded by p(|u|).

We show how to construct an instance of the tiling problem, $((\mathcal{T}, V, H)_L, \hat{s}, \sigma_0)$, where s = p(|u|) + 2, and where the bottom row encodes the starting ID, so that $u \in L$ iff the tiling problem $((\mathcal{T}, V, H)_L, \hat{s}, \sigma_0)$ has a solution.

First, note that the problem is indeed in \mathcal{NP} , since we have to guess a rectangle of size $2s^2$, and that checking that a tiling is legal can indeed be done in $O(s^2)$, where s is **bounded** by the the size of the input $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$, since the input contains the bottom row of 2s symbols (this is the reason for including the bottom row of 2s tiles in the input!).

The idea behind the definition of the tiles is that, in a solution of the tiling problem, the labels on the horizontal edges between two adjacent rows represent a legal ID, *xpay*. In a given row, the labels on vertical edges of adjacent tiles keep track of the change of state and direction.

Let Γ be the tape alphabet of the TM, M. As before, we assume that M signals that it accepts u by halting with the output 1 (true).

From M, we create the following tiles:

(1) For every $a \in \Gamma$, tiles



(2) For every $a \in \Gamma$, the bottom row uses tiles



where q_0 is the start state.

(3) For every instruction $(p, a, b, R, q) \in \delta$, for every $c \in \Gamma$, tiles

b	q, c
q, R,	q, R
p, a	c

(4) For every instruction $(p, a, b, L, q) \in \delta$, for every $c \in \Gamma$, tiles

q, c	b
q,L ,	q, L
С	p, a

(5) For every halting state, p, tiles

$$p, 1$$

 $p, 1$

The purpose of tiles of type (5) is to fill the $2s \times s$ rectangle iff M accepts u. Since s = p(|u|) + 2 and the machine runs for at most p(|u|) steps, the $2s \times s$ rectangle can be tiled iff $u \in L$.

The vertical and the horizontal constraints are that adjacent edges have the same label (or no label).

If $u = u_1 \cdots u_k$, the initial bottom row σ_0 , of length 2s, is



where the tile labeled q_0, u_1 is in position s + 1.

The example below illustrates the construction:

Example 13.10.

В	В	f, 1	В
	 f, R	f, R	
В	q,c	1	B
В	q, c	1	В
	 q, L	q, L	
В	c	p, a	B
В	С	p, a	В
	 p, R	p, R	
В	r, b		В

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We claim that $u = u_1 \cdots u_k$ is accepted by M iff the tiling problem just constructed has a solution.

The upper horizontal edge of the first (bottom) row of tiles represents the starting configuation $B^s q_0 u B^{s-|u|}$. By induction, we see that after i ($i \leq p(|u|) = s - 2$) steps the upper horizontal edge of the (i + 1)th row of tiles represents the current ID xpay reached by the Turing machine; see Example 13.10. Since the machine runs for at most p(|u|) steps and since s = p(|u|) + 2, when the computation stops, at most the lowest p(|u|) + 1 = s - 1 rows of the the $2s \times s$ rectangle have been tiled. Assume the machine M stops after $r \leq s - 2$ steps. Then the lowest r + 1 rows have been tiled, and since no further instruction can be executed (since the machine entered a halting state), the remaining s - r - 1 rows can be filled iff tiles of type (5) can be used iff the machine stopped in an ID containing a pair p 1where p is a halting state. Therefore, the machine M accepts u iff the $2s \times s$ rectangle can be tiled.

Remark:

- (1) The problem becomes harder if we only specify a *single* tile σ_0 as input, instead of a row of length 2s. If s is specified in binary (or any other base, but not in tally notation), then the $2s^2$ grid has size exponential in the length $\log_2 s + C + 2$ of the input $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$, and this tiling problem is actually \mathcal{NEXP} -complete! The class \mathcal{NEXP} is the family of languages that can be accepted by a nondeterministic Turing machine that runs in time bounded by $2^{p(|x|)}$, for every x, where p is a polynomial; see the remark after Definition 14.5. By the time hierarchy theorem (Cook, Seiferas, Fischer, Meyer, Zak), it is known that \mathcal{NP} is properly contained in \mathcal{NEXP} ; see Papadimitriou [56] (Chapters 7 and 20) and Arora and Barak [4] (Chapter 3, Section 3.2). Then the tiling problem with a single tile as input is a computable \mathcal{NP} -hard problem not in \mathcal{NP} .
- (2) If we relax the finiteness condition and require that the entire upper half-plane be tiled, i.e., for every s > 1, there is a solution to the $2s \times s$ -tiling problem, then the problem is undecidable.

In 1972, Richard Karp published a list of twenty one \mathcal{NP} -complete problems.

13.8 The Cook–Levin Theorem: SAT is \mathcal{NP} -Complete

We finally prove the Cook-Levin theorem.

Theorem 13.8. (Cook, 1971, Levin, 1973) The satisfiability problem SAT is \mathcal{NP} -complete.

Proof. We reduce the tiling problem to SAT. Given a tiling problem, $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$, we introduce boolean variables

 x_{mnt} ,

for all m with $1 \le m \le 2s$, all n with $1 \le n \le s$, and all tiles $t \in \mathcal{T}$.

The intuition is that $x_{mnt} = \mathbf{T}$ iff tile t occurs in some tiling σ so that $\sigma(m, n) = t$. We define the following clauses:

(1) For all m, n in the correct range, as above,

$$(x_{mnt_1} \lor x_{mnt_2} \lor \cdots \lor x_{mnt_p}),$$

for all p tiles in \mathcal{T} .

This clause states that every position in σ is tiled.

(2) For any two distinct tiles $t \neq t' \in \mathcal{T}$, for all m, n in the correct range, as above,

 $(\overline{x}_{mnt} \vee \overline{x}_{mnt'}).$

This clause states that a position may not be occupied by more than one tile.

(3) For every pair of tiles $(t, t') \in \mathcal{T} \times \mathcal{T} - H$, for all m with $1 \le m \le 2s - 1$, and all n, with $1 \le n \le s$,

 $(\overline{x}_{mnt} \lor \overline{x}_{m+1\,nt'}).$

This clause enforces the horizontal adjacency constraints.

(4) For every pair of tiles $(t, t') \in \mathcal{T} \times \mathcal{T} - V$, for all m with $1 \le m \le 2s$, and all n, with $1 \le n \le s - 1$,

$$(\overline{x}_{mnt} \lor \overline{x}_{m\,n+1\,t'}).$$

This clause enforces the vertical adjacency constraints.

(5) For all m with $1 \le m \le 2s$,

 $(x_{m1\sigma_0(m)}).$

This clause states that the bottom row is correctly tiled with σ_0 .

It is easily checked that the tiling problem has a solution iff the conjunction of the clauses just defined is satisfiable. Thus, SAT is \mathcal{NP} -complete.

We sharpen Theorem 13.8 to prove that 3-SAT is also \mathcal{NP} -complete. This is the satisfiability problem for clauses containing at most three literals.

We know that we can't go further and retain \mathcal{NP} -completeteness, since 2-SAT is in \mathcal{P} .

Theorem 13.9. (Cook, 1971) The satisfiability problem 3-SAT is \mathcal{NP} -complete.

Proof. We have to break "long clauses"

$$C = (L_1 \vee \cdots \vee L_k),$$

i.e., clauses containing $k \ge 4$ literals, into clauses with at most three literals, in such a way that satisfiability is preserved.

Example 13.11. For example, consider the following clause with k = 6 literals:

$$C = (L_1 \lor L_2 \lor L_3 \lor L_4 \lor L_5 \lor L_6).$$

We create 3 new boolean variables y_1, y_2, y_3 , and the 4 clauses

 $(L_1 \vee L_2 \vee y_1), (\overline{y_1} \vee L_3 \vee y_2), (\overline{y_2} \vee L_4 \vee y_3), (\overline{y_3} \vee L_5 \vee L_6).$

Let C' be the conjunction of these clauses. We claim that C is satisfiable iff C' is.

Assume that C' is satisfiable but C is not. If so, in any truth assignment v, $v(L_i) = \mathbf{F}$, for i = 1, 2, ..., 6. To satisfy the first clause, we must have $v(y_1) = \mathbf{T}$. Then to satisfy the second clause, we must have $v(y_2) = \mathbf{T}$, and similarly satisfy the third clause, we must have $v(y_3) = \mathbf{T}$. However, since $v(L_5) = \mathbf{F}$ and $v(L_6) = \mathbf{F}$, the only way to satisfy the fourth clause is to have $v(y_3) = \mathbf{F}$, contradicting that $v(y_3) = \mathbf{T}$. Thus, C is indeed satisfiable.

Let us now assume that C is satisfiable. This means that there is a smallest index i such that L_i is satisfied.

Say i = 1, so $v(L_1) = \mathbf{T}$. Then if we let $v(y_1) = v(y_2) = v(y_3) = \mathbf{F}$, we see that C' is satisfied.

Say i = 2, so $v(L_1) = \mathbf{F}$ and $v(L_2) = \mathbf{T}$. Again if we let $v(y_1) = v(y_2) = v(y_3) = \mathbf{F}$, we see that C' is satisfied.

Say i = 3, so $v(L_1) = \mathbf{F}$, $v(L_2) = \mathbf{F}$, and $v(L_3) = \mathbf{T}$. If we let $v(y_1) = \mathbf{T}$ and $v(y_2) = v(y_3) = \mathbf{F}$, we see that C' is satisfied.

Say i = 4, so $v(L_1) = \mathbf{F}$, $v(L_2) = \mathbf{F}$, $v(L_3) = \mathbf{F}$, and $v(L_4) = \mathbf{T}$. If we let $v(y_1) = \mathbf{T}$, $v(y_2) = \mathbf{T}$ and $v(y_3) = \mathbf{F}$, we see that C' is satisfied.

Say i = 5, so $v(L_1) = \mathbf{F}$, $v(L_2) = \mathbf{F}$, $v(L_3) = \mathbf{F}$, $v(L_4) = \mathbf{F}$, and $v(L_5) = \mathbf{T}$. If we let $v(y_1) = \mathbf{T}$, $v(y_2) = \mathbf{T}$ and $v(y_3) = \mathbf{T}$, we see that C' is satisfied.

Say i = 6, so $v(L_1) = \mathbf{F}$, $v(L_2) = \mathbf{F}$, $v(L_3) = \mathbf{F}$, $v(L_4) = \mathbf{F}$, $v(L_5) = \mathbf{F}$, and $v(L_6) = \mathbf{T}$. Again, if we let $v(y_1) = \mathbf{T}$, $v(y_2) = \mathbf{T}$ and $v(y_3) = \mathbf{T}$, we see that C' is satisfied.

Therefore if C is satisfied, then C' is satisfied in all cases.

In general, for every long clause, create k - 3 new boolean variables y_1, \ldots, y_{k-3} , and the k - 2 clauses

$$(L_1 \lor L_2 \lor y_1), (\overline{y_1} \lor L_3 \lor y_2), (\overline{y_2} \lor L_4 \lor y_3), \cdots, (\overline{y_{k-4}} \lor L_{k-2} \lor y_{k-3}), (\overline{y_{k-3}} \lor L_{k-1} \lor L_k).$$

Let C' be the conjunction of these clauses. We claim that C is satisfiable iff C' is.

Assume that C' is satisfiable, but that C is not. Then for every truth assignment v, we have $v(L_i) = \mathbf{F}$, for i = 1, ..., k.

However, C' is satisfied by some v, and the only way this can happen is that $v(y_1) = \mathbf{T}$, to satisfy the first clause. Then $v(\overline{y_1}) = \mathbf{F}$, and we must have $v(y_2) = \mathbf{T}$, to satisfy the second clause.

By induction, we must have $v(y_{k-3}) = \mathbf{T}$, to satisfy the next to the last clause. However, the last clause is now false, a contradiction.

Thus, if C' is satisfiable, then so is C.

Conversely, assume that C is satisfiable. If so, there is some truth assignment, v, so that $v(C) = \mathbf{T}$, and thus, there is a smallest index i, with $1 \le i \le k$, so that $v(L_i) = \mathbf{T}$ (and so, $v(L_j) = \mathbf{F}$ for all j < i).

Let v' be the assignment extending v defined so that

$$v'(y_j) = \mathbf{F} \quad \text{if} \quad \max\{1, i-1\} \le j \le k-3,$$

and $v'(y_j) = \mathbf{T}$, otherwise.

It is easily checked that $v'(C') = \mathbf{T}$.

Another version of 3-SAT can be considered, in which every clause has exactly three literals. We will call this the problem *exact* 3-SAT.

Theorem 13.10. (Cook, 1971) The satisfiability problem for exact 3-SAT is \mathcal{NP} -complete.

Proof. A clause of the form (L) is satisfiable iff the following four clauses are satisfiable:

 $(L \lor u \lor v), (L \lor \overline{u} \lor v), (L \lor u \lor \overline{v}), (L \lor \overline{u} \lor \overline{v})$

where u, v are new variables. A clause of the form $(L_1 \vee L_2)$ is satisfiable iff the following two clauses are satisfiable:

$$(L_1 \lor L_2 \lor u), (L_1 \lor L_2 \lor \overline{u}).$$

Thus, we have a reduction of 3-SAT to exact 3-SAT.

We now make some remarks about the conversion of propositions to CNF and about the satisfiability and validity of arbitrary propositions.

13.9 Satisfiability of Arbitrary Propositions and CNF

The satisfiability problem for arbitrary propositions belongs to \mathcal{NP} because if we can guess a truth assignment v satisfying a proposition A, then evaluating the truth value of A under v can certainly be done in polynomial time. Since a proposition in CNF is a special kind of proposition and since the satisfiability problem for propositions in CNF (SAT) is \mathcal{NP} complete, the satisfiability problem for arbitrary propositions is also \mathcal{NP} -complete.

Since the satisfiability problem for propositions in CNF is \mathcal{NP} -complete, there is a polynomial-time reduction that takes an arbitrary proposition A and produces a proposition A' in CNF such that A is satisfiable iff A' is satisfiable. In general, given a proposition A, a proposition A' in CNF equivalent to A may have an exponential length in the size of A. However, using new variables, there is an algorithm to convert a proposition A to another proposition A' (containing the new variables) whose length is polynomial in the length of Aand such that A is satisfiable iff A' is satisfiable.

We will explain how to convert an arbitrary proposition A to an equivalent proposition in CNF, and also how to construct in polynomial time a proposition A' such that A is satisfiable iff A' is satisfiable. We also briefly discuss the issue of uniqueness of the CNF. In short, it is not unique!

Recall the definition of arbitrary propositions.

Definition 13.10. The set of *propositions* (over the connectives \lor , \land , and \neg) is defined inductively as follows:

- (1) Every propositional letter, $x \in \mathbf{PV}$, is a proposition (an *atomic* proposition).
- (2) If A is a proposition, then $\neg A$ is a proposition.
- (3) If A and B are propositions, then $(A \lor B)$ is a proposition.
- (4) If A and B are propositions, then $(A \wedge B)$ is a proposition.

Two propositions A and B are equivalent, denoted $A \equiv B$, if

$$v \models A$$
 iff $v \models B$

for all truth assignments, v. It is easy to show that $A \equiv B$ iff the proposition

$$(\neg A \lor B) \land (\neg B \lor A)$$

is valid.

Definition 13.11. A proposition P is in *conjunctive normal form* (*CNF*) if it is a conjunction $P = C_1 \wedge \cdots \wedge C_n$ of propositions C_j which are disjunctions of literals (a literal is either a variable x or the negation $\neg x$ (also denoted \overline{x}) of a variable x).

A proposition P is in *disjunctive normal form* (DNF) if it is a disjunction $P = D_1 \vee \cdots \vee D_n$ of propositions D_j which are conjunctions of literals.

There are propositions such that any equivalent proposition in CNF has size exponential in terms of the original proposition.

Example 13.12. Here is such an example:

$$A = (x_1 \wedge x_2) \lor (x_3 \wedge x_4) \lor \cdots \lor (x_{2n-1} \wedge x_{2n}).$$

Observe that it is in DNF. We will prove a little later that any CNF for A contains 2^n occurrences of variables.

Proposition 13.11. Every proposition A is equivalent to a proposition A' in CNF.

There are several ways of proving Proposition 13.11. One method is algebraic, and consists in using the algebraic laws of boolean algebra. First one may convert a proposition to *negation normal form*, or nnf.

Definition 13.12. A proposition is in *negation normal form* or *nnf* if all occurrences of \neg only appear in front of propositional variables, but not in front of compound propositions.

Any proposition can be converted to an equivalent one in nnf by using the de Morgan laws:

$$\neg (A \lor B) \equiv (\neg A \land \neg B)$$
$$\neg (A \land B) \equiv (\neg A \lor \neg B)$$
$$\neg \neg A \equiv A.$$

Observe that if A has n connectives, then the equivalent formula A' in nnf has at most 2n-1 connectives. Then a proposition in nnf can be converted to CNF,

A nice method to convert a proposition in nnf to CNF is to construct a tree whose nodes are labeled with sets of propositions using the following (Gentzen-style) rules:

$$\frac{P, \Delta \qquad Q, \Delta}{(P \land Q), \Delta}$$
$$P, Q, \Delta$$

 $\overline{(P \lor Q), \Delta}$

and

where Δ stands for any set of propositions (even empty), and the comma stands for union. Thus, it is assumed that $(P \land Q) \notin \Delta$ in the first case, and that $(P \lor Q) \notin \Delta$ in the second case.

Since we interpret a set, Γ , of propositions as a disjunction, a valuation, v, satisfies Γ iff it satisfies *some* proposition in Γ .

Observe that a valuation v satisfies the conclusion of a rule iff it satisfies both premises in the first case, and the single premise in the second case. Using these rules, we can build a finite tree whose leaves are labeled with sets of literals. By the above observation, a valuation v satisfies the proposition labeling the root of the tree iff it satisfies all the propositions labeling the leaves of the tree.

But then, a CNF for the original proposition A (in nnf, at the root of the tree) is the conjunction of the clauses appearing as the leaves of the tree. We may exclude the clauses that are tautologies, and we may discover in the process that A is a tautology (when all leaves are tautologies).

Example 13.13. An illustration of the above method to convert the proposition

$$A = (x_1 \land y_1) \lor (x_2 \land y_2)$$

is shown below:

$$\frac{x_1, x_2 \quad x_1, y_2}{x_1, x_2 \land y_2} \quad \frac{y_1, x_2 \quad y_1, y_2}{y_1, x_2 \land y_2}$$
$$\frac{x_1 \land y_1, x_2 \land y_2}{(x_1 \land y_1) \lor (x_2 \land y_2)}$$

We obtain the CNF

$$B = (x_1 \lor x_2) \land (x_1 \lor y_2) \land (y_1 \lor x_2) \land (y_1 \lor y_2).$$

Remark: Rules for dealing for \neg can also be created. In this case, we work with pairs of sets of propositions,

 $\Gamma \to \Delta$,

where, the propositions in Γ are interpreted conjunctively, and the propositions in Δ are interpreted disjunctively. We obtain a sound and complete proof system for propositional logic (a "Gentzen-style" proof system, see *Logic for Computer Science*, Gallier [24]).

Going back to our "bad" proposition A from Example 13.12, by induction, we see that any tree for A has 2^n leaves.

However, the following result holds.

Proposition 13.12. For any proposition A, we can construct in polynomial time a formula A' in CNF, so that A is satisfiable iff A' is satisfiable, by creating new variables.

Sketch of proof. First we convert A to nnf, which yields a proposition at most twice as long. Then we proceed recursively. For a conjunction $C \wedge D$, we apply recursively the procedure to C and D. The trick is that for a disjunction $C \vee D$, first we apply recursively the procedure to C and D obtain

$$(C_1 \wedge \dots \wedge C_m) \vee (D_1 \wedge \dots \wedge D_n)$$

where the C_i 's and the D_j 's are clauses. Then we create

 $(C_1 \lor y) \land \dots \land (C_m \lor y) \land (D_1 \lor \overline{y}) \land \dots \land (D_n \lor \overline{y}),$

where y is a new variable.

It can be shown that the number of new variables required is at most quadratic in the size of A. For details on this construction see Hopcroft, Motwani and Ullman [37] (Section 10.3.3), but beware that the proof on page 455 contains a mistake. Repair the mistake. \Box

Example 13.14. Consider the proposition

$$A = (x_1 \land \neg x_2) \lor ((\neg x_1 \land x_2) \lor (x_2 \lor x_3)).$$

First, since x_1 and $\neg x_2$ are clauses, we get

$$A_1 = x_1 \land \neg x_2.$$

Since $\neg x_1$, x_2 and $x_2 \lor x_3$ are clauses, from $(\neg x_1 \land x_2) \lor (x_2 \lor x_3)$ we construct

$$A_2 = (\neg x_1 \lor y_1) \land (x_2 \lor y_1) \land (x_2 \lor x_3 \lor \neg y_1).$$

Next, since A_1 and A_2 are conjunctions of clauses, we construct

$$A' = (x_1 \lor y_2) \land (\neg x_2 \lor y_2) \land (\neg x_1 \lor y_1 \lor \neg y_2) \land (x_2 \lor y_1 \lor \neg y_2) \land (x_2 \lor x_3 \lor \neg y_1 \lor \neg y_2),$$

a conjunction of clauses which is satisfiable iff A is satisfiable.

Warning: In general, the proposition A' is not equivalent to the proposition A.

Remark: Other authors, including Hoprcoft, Motwani, and Ullman, prove that the satisfiability problem for *arbitrary* propositions is \mathcal{NP} -complete, by showing how the computation of a nondeterministic Turing machine (operating in polynomial time) can be simulated using propositions. For this simulation to work, it appears that propositions that are not in CNF are required. Then Proposition 13.12 is used to show that the satisfiability problem for propositions in CNF (SAT) is also \mathcal{NP} -complete.

In our approach, since we have already shown that the bounded tiling problem is \mathcal{NP} complete, in the second step to reduce the tiling problem to SAT we only need clauses to
perform the reduction. Thus we don't need Proposition 13.12 to prove that SAT is \mathcal{NP} complete.

We just observed that the satisfiability problems for propositions in CNF is as hard as the satisfiability problems for arbitrary propositions. However, the situation is completely different for the validity problem. Indeed, a proposition $P = C_1 \wedge \cdots \wedge C_m$ in CNF is valid iff every conjunct C_i is valid. But each C_i is clause, namely a disjunction of literals

$$C_i = L_{i1} \vee \cdots \vee L_{in_i},$$

where $L_{i,j}$ is either a variable x or the negation $\neg x$ of a variable. But such a disjunction is valid iff some variable and its negation both occur in C_i . This is because if all the L_{ij} were

variables, we could falsify C_i by assigning the truth value **F** to all of them, and if all the L_{ij} were negations of variables, we could falsify C_i by assigning the truth value **T** to all of them. Therefore, the validity problem for proposition in CNF is in \mathcal{P} .

This does not help to obtain a polynomial time algorithm to test the validity of arbitrary propositions because converting a proposition to a CNF may yield a proposition whose size is exponential in terms of the size of the original proposition. We can view the method using the Gentzen rules described earlier for building a tree from a proposition P in nnf as an attempt to demonstrate that the proposition P is valid. If this attempt fails, then we obtain a CNF for P, so our efforts are not wasted.

The question of uniqueness of the CNF is a bit tricky. For example, the proposition

$$A = (u \land (x \lor y)) \lor (\neg u \land (x \lor y))$$

has

$$A_1 = (u \lor x \lor y) \land (\neg u \lor x \lor y)$$

$$A_2 = (u \lor \neg u) \land (x \lor y)$$

$$A_3 = x \lor y,$$

as equivalent propositions in CNF!

We can get a *unique* CNF equivalent to a given proposition if we do the following:

- (1) Let $Var(A) = \{x_1, \ldots, x_m\}$ be the set of variables occurring in A.
- (2) Define a maxterm w.r.t. Var(A) as any disjunction of m pairwise distinct literals formed from Var(A), and not containing both some variable x_i and its negation $\neg x_i$.
- (3) Then it can be shown that for any proposition A that is not a tautology, there is a unique proposition in CNF equivalent to A, whose clauses consist of maxterms formed from Var(A).

The above definition can yield strange results. For instance, the CNF of any unsatisfiable proposition with m distinct variables is the conjunction of all of its 2^m maxterms! The above notion does not cope well with minimality.

For example, according to the above, the CNF of

$$A = (u \land (x \lor y)) \lor (\neg u \land (x \lor y))$$

should be

$$A_1 = (u \lor x \lor y) \land (\neg u \lor x \lor y).$$

Chapter 14

Some \mathcal{NP} -Complete Problems

14.1 Statements of the Problems

In this chapter we will show that certain classical algorithmic problems are \mathcal{NP} -complete. This chapter is heavily inspired by Lewis and Papadimitriou's excellent treatment [50]. In order to study the complexity of these problems in terms of resource (time or space) bounded Turing machines (or RAM programs), it is crucial to be able to encode instances of a problem P as strings in a language L_P . Then an instance of a problem P is solvable iff the corresponding string belongs to the language L_P . This implies that our problems must have a yes-no answer, which is not always the usual formulation of optimization problems where what is required is to find some *optimal* solution, that is, a solution minimizing or maximizing so objective (cost) function F. For example the standard formulation of the traveling salesman problem asks for a tour (of the cities) of minimal cost.

Fortunately, there is a trick to reformulate an optimization problem as a yes-no answer problem, which is to explicitly incorporate a *budget* (or *cost*) term *B* into the problem, and instead of asking whether some objective function *F* has a minimum or a maximum w, we ask whether there is a solution w such that $F(w) \leq B$ in the case of a minimum solution, or $F(w) \geq B$ in the case of a maximum solution.

If we are looking for a minimum of F, we try to guess the minimum value B of F and then we solve the problem of finding w such that $F(w) \leq B$. If our guess for B is too small, then we fail. In this case, we try again with a larger value of B. Otherwise, if B was not too small we find some w such that $F(w) \leq B$, but w may not correspond to a minimum of F, so we try again with a smaller value of B, and so on. This yields an approximation method to find a minimum of F.

Similarly, if we are looking for a maximum of F, we try to guess the maximum value B of F and then we solve the problem of finding w such that $F(w) \ge B$. If our guess for B is too large, then we fail. In this case, we try again with a smaller value of B. Otherwise, if B was not too large we find some w such that $F(w) \ge B$, but w may not correspond to a maximum of F, so we try again with a greater value of B, and so on. This yields an

approximation method to find a maximum of F.

We will see several examples of this technique in Problems 5–8 listed below.

The problems that will consider are

(1) Exact Cover

- (2) Hamiltonian Cycle for directed graphs
- (3) Hamiltonian Cycle for undirected graphs
- (4) The Traveling Salesman Problem

(5) Independent Set

- (6) Clique
- (7) Node Cover
- (8) Knapsack, also called subset sum
- (9) Inequivalence of *-free Regular Expressions
- (10) The 0-1-integer programming problem

We begin by describing each of these problems.

(1) Exact Cover

We are given a finite nonempty set $U = \{u_1, \ldots, u_n\}$ (the universe), and a family $\mathcal{F} = \{S_1, \ldots, S_m\}$ of $m \ge 1$ nonempty subsets of U. The question is whether there is an *exact cover*, that is, a subfamily $\mathcal{C} \subseteq \mathcal{F}$ of subsets in \mathcal{F} such that the sets in \mathcal{C} are disjoint and their union is equal to U.

For example, let $U = \{u_1, u_2, u_3, u_4, u_5, u_6\}$, and let \mathcal{F} be the family

$$\mathcal{F} = \{\{u_1, u_3\}, \{u_2, u_3, u_6\}, \{u_1, u_5\}, \{u_2, u_3, u_4\}, \{u_5, u_6\}, \{u_2, u_4\}\}.$$

The subfamily

$$\mathcal{C} = \{\{u_1, u_3\}, \{u_5, u_6\}, \{u_2, u_4\}\}$$

is an exact cover.

It is easy to see that **Exact Cover** is in \mathcal{NP} . To prove that it is \mathcal{NP} -complete, we will reduce the **Satisfiability Problem** to it. This means that we provide a method running in polynomial time that converts every instance of the **Satisfiability Problem** to an instance of **Exact Cover**, such that the first problem has a solution iff the converted problem has a solution.

(2) Hamiltonian Cycle (for Directed Graphs)

Recall that a directed graph G is a pair G = (V, E), where $E \subseteq V \times V$. Elements of V are called nodes (or vertices). A pair $(u, v) \in E$ is called an *edge* of G. We will restrict ourselves to simple graphs, that is, graphs without edges of the form (u, u); equivalently, G = (V, E) is a simple graph if whenever $(u, v) \in E$, then $u \neq v$.

Given any two nodes $u, v \in V$, a path from u to v is any sequence of n+1 edges $(n \ge 0)$

$$(u, v_1), (v_1, v_2), \dots, (v_n, v).$$

(If n = 0, a path from u to v is simply a single edge, (u, v).)

A directed graph G is strongly connected if for every pair $(u, v) \in V \times V$, there is a path from u to v. A closed path, or cycle, is a path from some node u to itself. We will restrict out attention to finite graphs, i.e. graphs (V, E) where V is a finite set.

Definition 14.1. Given a directed graph G, a *Hamiltonian cycle* is a cycle that passes through all the nodes exactly once (note, some edges may not be traversed at all).

Hamiltonian Cycle Problem (for Directed Graphs): Given a directed graph G, is there an Hamiltonian cycle in G?

Is there is a Hamiltonian cycle in the directed graph D shown in Figure 14.1?

Finding a Hamiltonian cycle in this graph does not appear to be so easy! A solution is shown in Figure 14.2 below.

It is easy to see that Hamiltonian Cycle (for Directed Graphs) is in \mathcal{NP} . To prove that it is \mathcal{NP} -complete, we will reduce Exact Cover to it. This means that we provide a method running in polynomial time that converts every instance of Exact Cover to an instance of Hamiltonian Cycle (for Directed Graphs) such that the first problem has a solution iff the converted problem has a solution. This is perphaps the hardest reduction.



Figure 14.1: A tour "around the world."



Figure 14.2: A Hamiltonian cycle in D.

(3) Hamiltonian Cycle (for Undirected Graphs)

Recall that an *undirected graph* G is a pair G = (V, E), where E is a set of subsets $\{u, v\}$ of V consisting of exactly two distinct elements. Elements of V are called *nodes* (or *vertices*). A pair $\{u, v\} \in E$ is called an *edge* of G.

Given any two nodes $u, v \in V$, a path from u to v is any sequence of n nodes $(n \ge 2)$

$$u = u_1, u_2, \ldots, u_n = v$$

such that $\{u_i, u_{i+1}\} \in E$ for i = 1, ..., n-1. (If n = 2, a path from u to v is simply a single edge, $\{u, v\}$.)

An undirected graph G is *connected* if for every pair $(u, v) \in V \times V$, there is a path from u to v. A *closed path*, or cycle, is a path from some node u to itself.

Definition 14.2. Given an undirected graph G, a Hamiltonian cycle is a cycle that passes through all the nodes exactly once (note, some edges may not be traversed at all).

Hamiltonian Cycle Problem (for Undirected Graphs): Given an undirected graph G, is there an Hamiltonian cycle in G?

An instance of this problem is obtained by changing every directed edge in the directed graph of Figure 14.1 to an undirected edge. The directed Hamiltonian cycle given in Figure 14.1 is also an undirected Hamiltonian cycle of the undirected graph of Figure 14.3.

We see immediately that Hamiltonian Cycle (for Undirected Graphs) is in \mathcal{NP} . To prove that it is \mathcal{NP} -complete, we will reduce Hamiltonian Cycle (for Directed Graphs) to it. This means that we provide a method running in polynomial time that converts every instance of Hamiltonian Cycle (for Directed Graphs) to an instance of Hamiltonian Cycle (for Undirected Graphs) such that the first problem has a solution iff the converted problem has a solution. This is an easy reduction.

(4) **Traveling Salesman Problem**

We are given a set $\{c_1, c_2, \ldots, c_n\}$ of $n \ge 2$ cities, and an $n \times n$ matrix $D = (d_{ij})$ of nonnegative integers, where d_{ij} is the *distance* (or *cost*) of traveling from city c_i to city c_j . We assume that $d_{ii} = 0$ and $d_{ij} = d_{ji}$ for all i, j, so that the matrix D is symmetric and has zero diagonal.

Traveling Salesman Problem: Given some $n \times n$ matrix $D = (d_{ij})$ as above and some integer $B \ge 0$ (the *budget* of the traveling salesman), find a permutation π of $\{1, 2, \ldots, n\}$ such that

$$c(\pi) = d_{\pi(1)\pi(2)} + d_{\pi(2)\pi(3)} + \dots + d_{\pi(n-1)\pi(n)} + d_{\pi(n)\pi(1)} \le B.$$



Figure 14.3: A tour "around the world," undirected version.

The quantity $c(\pi)$ is the *cost* of the trip specified by π . The Traveling Salesman Problem has been stated in terms of a budget so that it has a yes or no answer, which allows us to convert it into a language. A minimal solution corresponds to the smallest feasible value of B.

Example 14.1. Consider the 4×4 symmetric matrix given by

$$D = \begin{pmatrix} 0 & 2 & 1 & 1 \\ 2 & 0 & 1 & 1 \\ 1 & 1 & 0 & 3 \\ 1 & 1 & 3 & 0 \end{pmatrix},$$

and the budget B = 4. The tour specified by the permutation

$$\pi = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 4 & 2 & 3 \end{pmatrix}$$

has cost 4, since

$$c(\pi) = d_{\pi(1)\pi(2)} + d_{\pi(2)\pi(3)} + d_{\pi(3)\pi(4)} + d_{\pi(4)\pi(1)}$$

= $d_{14} + d_{42} + d_{23} + d_{31}$
= $1 + 1 + 1 + 1 = 4.$

The cities in this tour are traversed in the order

It is clear that the **Traveling Salesman Problem** is in \mathcal{NP} . To show that it is \mathcal{NP} complete, we reduce the **Hamiltonian Cycle Problem (Undirected Graphs)** to it.
This means that we provide a method running in polynomial time that converts every
instance of **Hamiltonian Cycle Problem (Undirected Graphs)** to an instance of
the **Traveling Salesman Problem** such that the first problem has a solution iff the
converted problem has a solution.

(5) Independent Set

The problem is this: Given an undirected graph G = (V, E) and an integer $K \ge 2$, is there a set C of nodes with $|C| \ge K$ such that for all $v_i, v_j \in C$, there is no edge $\{v_i, v_j\} \in E$?

A maximal independent set with 3 nodes is shown in Figure 14.4. A maximal solution



Figure 14.4: A maximal Independent Set in a graph.

corresponds to the largest feasible value of K. The problem **Independent Set** is obviously in \mathcal{NP} . To show that it is \mathcal{NP} -complete, we reduce **Exact 3-Satisfiability** to it. This means that we provide a method running in polynomial time that converts every instance of **Exact 3-Satisfiability** to an instance of **Independent Set** such that the first problem has a solution iff the converted problem has a solution.

(6) Clique

The problem is this: Given an undirected graph G = (V, E) and an integer $K \ge 2$, is there a set C of nodes with $|C| \ge K$ such that for all $v_i, v_j \in C$, there is some edge $\{v_i, v_j\} \in E$? Equivalently, does G contain a complete subgraph with at least Knodes?

A maximal clique with 4 nodes is shown in Figure 14.5. A maximal solution corresponds



Figure 14.5: A maximal Clique in a graph.

to the largest feasible value of K. The problem **Clique** is obviously in \mathcal{NP} . To show that it is \mathcal{NP} -complete, we reduce **Independent Set** to it. This means that we provide a method running in polynomial time that converts every instance of **Independent Set** to an instance of **Clique** such that the first problem has a solution iff the converted problem has a solution.

(7) Node Cover

The problem is this: Given an undirected graph G = (V, E) and an integer $B \ge 2$, is there a set C of nodes with $|C| \le B$ such that C covers all edges in G, which means that for every edge $\{v_i, v_j\} \in E$, either $v_i \in C$ or $v_j \in C$?

A minimal node cover with 6 nodes is shown in Figure 14.6. A minimal solution corresponds to the smallest feasible value of B. The problem **Node Cover** is obviously in \mathcal{NP} . To show that it is \mathcal{NP} -complete, we reduce **Independent Set** to it. This means that we provide a method running in polynomial time that converts every instance of


Figure 14.6: A minimal Node Cover in a graph.

Independent Set to an instance of **Node Cover** such that the first problem has a solution iff the converted problem has a solution.

The Node Cover problem has the following interesting interpretation: think of the nodes of the graph as rooms of a museum (or art gallery *etc.*), and each edge as a straight corridor that joins two rooms. Then Node Cover may be useful in assigning as few as possible guards to the rooms, so that all corridors can be seen by a guard.

(8) Knapsack (also called Subset sum)

The problem is this: Given a finite nonempty set $S = \{a_1, a_2, \ldots, a_n\}$ of nonnegative integers, and some integer $K \ge 0$, all represented in binary, is there a nonempty subset $I \subseteq \{1, 2, \ldots, n\}$ such that

$$\sum_{i \in I} a_i = K?$$

A "concrete" realization of this problem is that of a hiker who is trying to fill her/his backpack to its maximum capacity with items of varying weights or values.

It is easy to see that the **Knapsack** Problem is in \mathcal{NP} . To show that it is \mathcal{NP} complete, we reduce **Exact Cover** to it. This means that we provide a method running
in polynomial time that converts every instance of **Exact Cover** to an instance of **Knapsack** Problem such that the first problem has a solution iff the converted problem
has a solution.

Remark: The **0-1 Knapsack Problem** is defined as the following problem. Given a set of *n* items, numbered from 1 to *n*, each with a weight $w_i \in \mathbb{N}$ and a value $v_i \in \mathbb{N}$, given a maximum capacity $W \in \mathbb{N}$ and a budget $B \in \mathbb{N}$, is there a set of *n* variables x_1, \ldots, x_n with $x_i \in \{0, 1\}$ such that

$$\sum_{i=1}^{n} x_i v_i \ge B,$$
$$\sum_{i=1}^{n} x_i w_i \le W.$$

Informally, the problem is to pick items to include in the knapsack so that the sum of the values exceeds a given minimum B (the goal is to maximize this sum), and the sum of the weights is less than or equal to the capacity W of the knapsack. A maximal solution corresponds to the largest feasible value of B.

The **Knapsack** Problem as we defined it (which is how Lewis and Papadimitriou define it) is the special case where $v_i = w_i$ for i = 1, ..., n, the v_i are pairwise distinct (they form a set), and W = B. For this reason, it is also called the **Subset Sum** Problem. Clearly, the **Knapsack** (**Subset Sum**) Problem reduces to the **0-1 Knapsack** Problem, and thus the **0-1 Knapsack** Problem is also NP-complete.

(9) Inequivalence of *-free Regular Expressions

Recall that the problem of deciding the equivalence $R_1 \cong R_2$ of two regular expressions R_1 and R_2 is the problem of deciding whether R_1 and R_2 define the same language, that is, $\mathcal{L}[R_1] = \mathcal{L}[R_2]$. Is this problem in \mathcal{NP} ?

In order to show that the equivalence problem for regular expressions is in \mathcal{NP} we would have to be able to somehow check in polynomial time that two expressions define the same language, but this is still an open problem.

What might be easier is to decide whether two regular expressions R_1 and R_2 are *inequivalent*. For this, we just have to find a string w such that either $w \in \mathcal{L}[R_1] - \mathcal{L}[R_2]$ or $w \in \mathcal{L}[R_2] - \mathcal{L}[R_1]$. The problem is that if we can guess such a string w, we still have to check in polynomial time that $w \in (\mathcal{L}[R_1] - \mathcal{L}[R_2]) \cup (\mathcal{L}[R_2] - \mathcal{L}[R_1])$, and this implies that there is a bound on the length of w which is polynomial in the sizes of R_1 and R_2 . Again, this is an open problem.

To obtain a problem in \mathcal{NP} we have to consider a restricted type of regular expressions, and it turns out that *-free regular expressions are the right candidate. A *-free regular expression is a regular expression which is built up from the atomic expressions using only + and \cdot , but not *. For example,

$$R = ((a+b)aa(a+b) + aba(a+b)b)$$

is such an expression.

It is easy to see that if R is a *-free regular expression, then for every string $w \in \mathcal{L}[R]$ we have $|w| \leq |R|$. In particular, $\mathcal{L}[R]$ is finite. The above observation shows that if R_1 and R_2 are *-free and if there is a string $w \in (\mathcal{L}[R_1] - \mathcal{L}[R_2]) \cup (\mathcal{L}[R_2] - \mathcal{L}[R_1])$, then $|w| \leq |R_1| + |R_2|$, so we can indeed check this in polynomial time. It follows that the inequivalence problem for * -free regular expressions is in \mathcal{NP} . To show that it is \mathcal{NP} complete, we reduce the **Satisfiability Problem** to it. This means that we provide a method running in polynomial time that converts every instance of **Satisfiability Problem** to an instance of **Inequivalence of Regular Expressions** such that the first problem has a solution iff the converted problem has a solution.

Observe that both problems of Inequivalence of Regular Expressions and Equivalence of Regular Expressions are as hard as Inequivalence of *-free Regular Expressions, since if we could solve the first two problems in polynomial time, then we we could solve Inequivalence of *-free Regular Expressions in polynomial time, but since this problem is \mathcal{NP} -complete, we would have $\mathcal{P} = \mathcal{NP}$. This is very unlikely, so the complexity of Equivalence of Regular Expressions remains open.

(10) 0-1 integer programming problem

Let A be any $p \times q$ matrix with integer coefficients and let $b \in \mathbb{Z}^p$ be any vector with integer coefficients. The 0-1 integer programming problem is to find whether a system of p linear equations in q variables

$$a_{11}x_1 + \dots + a_{1q}x_q = b_1$$

$$\vdots$$

$$a_{i1}x_1 + \dots + a_{iq}x_q = b_i$$

$$\vdots$$

$$a_{p1}x_1 + \dots + a_{pq}x_q = b_p$$

with $a_{ij}, b_i \in \mathbb{Z}$ has any solution $x \in \{0, 1\}^q$, that is, with $x_i \in \{0, 1\}$. In matrix form, if we let

$$A = \begin{pmatrix} a_{11} & \cdots & a_{1q} \\ \vdots & \ddots & \vdots \\ a_{p1} & \cdots & a_{pq} \end{pmatrix}, \quad b = \begin{pmatrix} b_1 \\ \vdots \\ b_p \end{pmatrix}, \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_q \end{pmatrix},$$

then we write the above system as

Ax = b.

Example 14.2. Is there a solution $x = (x_1, x_2, x_3, x_4, x_5, x_6)$ of the linear system

$$\begin{pmatrix} 1 & -2 & 1 & 3 & -1 & 4 \\ 2 & 2 & -1 & 0 & 1 & -1 \\ -1 & 1 & 2 & 3 & -2 & 3 \\ 3 & 1 & -1 & 2 & -1 & 4 \\ 0 & 1 & -1 & 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} 9 \\ 0 \\ 7 \\ 8 \\ 2 \end{pmatrix}$$

with $x_i \in \{0, 1\}$?

Indeed, x = (1, 0, 1, 1, 0, 1) is a solution.

It is immediate that 0-1 integer programming problem is in \mathcal{NP} . To prove that it is \mathcal{NP} -complete we reduce the **bounded tiling** problem to it. This means that we provide a method running in polynomial time that converts every instance of the **bounded tiling** problem to an instance of the 0-1 integer programming problem such that the first problem has a solution iff the converted problem has a solution.

14.2 Proofs of \mathcal{NP} -Completeness

(1) Exact Cover

To prove that **Exact Cover** is \mathcal{NP} -complete, we reduce the **Satisfiability Problem** to it:

Satisfiability Problem \leq_P Exact Cover

Given a set $F = \{C_1, \ldots, C_\ell\}$ of ℓ clauses constructed from n propositional variables x_1, \ldots, x_n , we must construct in polynomial time (in the sum of the lengths of the clauses) an instance $\tau(F) = (U, \mathcal{F})$ of **Exact Cover** such that F is satisfiable iff $\tau(F)$ has a solution.

Example 14.3. If

$$F = \{C_1 = (x_1 \lor \overline{x_2}), \ C_2 = (\overline{x_1} \lor x_2 \lor x_3), \ C_3 = (x_2), \ C_4 = (\overline{x_2} \lor \overline{x_3})\}$$

then the universe U is given by

 $U = \{x_1, x_2, x_3, C_1, C_2, C_3, C_4, p_{11}, p_{12}, p_{21}, p_{22}, p_{23}, p_{31}, p_{41}, p_{42}\},\$

and the family \mathcal{F} consists of the subsets

$$\{p_{11}\}, \{p_{12}\}, \{p_{21}\}, \{p_{22}\}, \{p_{23}\}, \{p_{31}\}, \{p_{41}\}, \{p_{42}\}$$

$$T_{1,\mathbf{F}} = \{x_1, p_{11}\}$$

$$T_{1,\mathbf{T}} = \{x_1, p_{21}\}$$

$$T_{2,\mathbf{F}} = \{x_2, p_{22}, p_{31}\}$$

$$T_{2,\mathbf{F}} = \{x_2, p_{12}, p_{41}\}$$

$$T_{3,\mathbf{F}} = \{x_3, p_{23}\}$$

$$T_{3,\mathbf{T}} = \{x_3, p_{42}\}$$

$$\{C_1, p_{11}\}, \{C_1, p_{12}\}, \{C_2, p_{21}\}, \{C_2, p_{22}\}, \{C_2, p_{23}\},$$

$$\{C_3, p_{31}\}, \{C_4, p_{41}\}, \{C_4, p_{42}\}.$$

The above construction is illustrated in Figure 14.7.



Figure 14.7: Construction of an exact cover from the set of clauses in Example 14.3.

It is easy to check that the set \mathcal{C} consisting of the following subsets is an exact cover:

$$T_{1,\mathbf{T}} = \{x_1, p_{21}\}, T_{2,\mathbf{T}} = \{x_2, p_{12}, p_{41}\}, T_{3,\mathbf{F}} = \{x_3, p_{23}\}, \{C_1, p_{11}\}, \{C_2, p_{22}\}, \{C_3, p_{31}\}, \{C_4, p_{42}\}.$$

The general method to construct (U, \mathcal{F}) from $F = \{C_1, \ldots, C_\ell\}$ proceeds as follows. The size *n* of the input is the sum of the lengths of the clauses C_i as strings, Say

$$C_j = (L_{j1} \vee \cdots \vee L_{jm_j})$$

is the *j*th clause in F, where L_{jk} denotes the *k*th literal in C_j and $m_j \ge 1$. The universe of $\tau(F)$ is the set

$$U = \{x_i \mid 1 \le i \le n\} \cup \{C_j \mid 1 \le j \le \ell\} \cup \{p_{jk} \mid 1 \le j \le \ell, \ 1 \le k \le m_j\}$$

where in the third set p_{jk} corresponds to the kth literal in C_j . The universe U can be constructed in time $O(n^2)$.

The following subsets are included in \mathcal{F} :

- (a) There is a set $\{p_{jk}\}$ for every p_{jk} .
- (b) For every boolean variable x_i , the following two sets are in \mathcal{F} :

$$T_{i,\mathbf{T}} = \{x_i\} \cup \{p_{jk} \mid L_{jk} = \overline{x_i}\}$$

which contains x_i and all negative occurrences of x_i , and

$$T_{i,\mathbf{F}} = \{x_i\} \cup \{p_{jk} \mid L_{jk} = x_i\}$$

which contains x_i and all its positive occurrences. Note carefully that $T_{i,\mathbf{T}}$ involves negative occurrences of x_i whereas $T_{i,\mathbf{F}}$ involves positive occurrences of x_i .

(c) For every clause C_i , the m_i sets $\{C_i, p_{ik}\}$ are in \mathcal{F} .

The subsets in (a), (b), (c) can be constructed in time $O(n^3)$. It remains to prove that F is satisfiable iff $\tau(F)$ has a solution. We claim that if v is a truth assignment that satisfies F, then we can make an exact cover C as follows:

For each x_i , we put the subset $T_{i,\mathbf{T}}$ in \mathcal{C} iff $v(x_i) = \mathbf{T}$, else we we put the subset $T_{i,\mathbf{F}}$ in \mathcal{C} iff $v(x_i) = \mathbf{F}$. Also, for every clause C_j , we put some subset $\{C_j, p_{jk}\}$ in \mathcal{C} for a literal L_{jk} which is made true by v. By construction of $T_{i,\mathbf{T}}$ and $T_{i,\mathbf{F}}$, this p_{jk} is not in any set in \mathcal{C} selected so far. Since by hypothesis F is satisfiable, such a literal exists for every clause. Having covered all x_i and C_j , we put a set $\{p_{jk}\}$ in \mathcal{C} for every remaining p_{jk} which has not yet been covered by the sets already in \mathcal{C} .

Going back to Example 14.3, the truth assignment $v(x_1) = \mathbf{T}, v(x_2) = \mathbf{T}, v(x_3) = \mathbf{F}$ satisfies F, so we put

$$T_{1,\mathbf{T}} = \{x_1, p_{21}\}, T_{2,\mathbf{T}} = \{x_2, p_{12}, p_{41}\}, T_{3,\mathbf{F}} = \{x_3, p_{23}\}, \{C_1, p_{11}\}, \{C_2, p_{22}\}, \{C_3, p_{31}\}, \{C_4, p_{42}\}$$

in \mathcal{C} .

We leave as an exercise to check that the above procedure works.

Conversely, if \mathcal{C} is an exact cover of $\tau(F)$, we define a truth assignment as follows:

For every x_i , if $T_{i,\mathbf{T}}$ is in \mathcal{C} , then we set $v(x_i) = \mathbf{T}$, else if $T_{i,\mathbf{F}}$ is in \mathcal{C} , then we set $v(x_i) = \mathbf{F}$. We leave it as an exercise to check that this procedure works.

Example 14.4. Given the exact cover

$$T_{1,\mathbf{T}} = \{x_1, p_{21}\}, T_{2,\mathbf{T}} = \{x_2, p_{12}, p_{41}\}, T_{3,\mathbf{F}} = \{x_3, p_{23}\}, \{C_1, p_{11}\}, \{C_2, p_{22}\}, \{C_3, p_{31}\}, \{C_4, p_{42}\},$$

we get the satisfying assignment $v(x_1) = \mathbf{T}, v(x_2) = \mathbf{T}, v(x_3) = \mathbf{F}$.

If we now consider the proposition is CNF given by

$$F_2 = \{ C_1 = (x_1 \lor \overline{x_2}), \ C_2 = (\overline{x_1} \lor x_2 \lor x_3), \ C_3 = (x_2), \ C_4 = (\overline{x_2} \lor \overline{x_3} \lor x_4) \}$$

where we have added the boolean variable x_4 to clause C_4 , then U also contains x_4 and p_{43} so we need to add the following subsets to \mathcal{F} :

$$T_{4,\mathbf{F}} = \{x_4, p_{43}\}, \ T_{4,\mathbf{T}} = \{x_4\}, \ \{C_4, p_{43}\}, \ \{p_{43}\}$$

The truth assignment $v(x_1) = \mathbf{T}, v(x_2) = \mathbf{T}, v(x_3) = \mathbf{F}, v(x_4) = \mathbf{T}$ satisfies F_2 , so an exact cover \mathcal{C} is

$$T_{1,\mathbf{T}} = \{x_1, p_{21}\}, T_{2,\mathbf{T}} = \{x_2, p_{12}, p_{41}\}, T_{3,\mathbf{F}} = \{x_3, p_{23}\}, T_{4,\mathbf{T}} = \{x_4\}, \{C_1, p_{11}\}, \{C_2, p_{22}\}, \{C_3, p_{31}\}, \{C_4, p_{42}\}, \{p_{43}\}.$$

The above construction is illustrated in Figure 14.8.

Observe that this time, because the truth assignment v makes both literals corresponding to p_{42} and p_{43} true and since we picked p_{42} to form the subset $\{C_4, p_{42}\}$, we need to add the singleton $\{p_{43}\}$ to C to cover all elements of U.

(2) Hamiltonian Cycle (for Directed Graphs)

To prove that Hamiltonian Cycle (for Directed Graphs) is \mathcal{NP} -complete, we will reduce Exact Cover to it:

Exact Cover \leq_P Hamiltonian Cycle (for Directed Graphs)

We need to find an algorithm working in polynomial time that converts an instance (U, \mathcal{F}) of **Exact Cover** to a directed graph $G = \tau(U, \mathcal{F})$ such that G has a Hamiltonian cycle iff (U, \mathcal{F}) has an exact cover. The size n of the input (U, \mathcal{F}) is $|U| + |\mathcal{F}|$.



Figure 14.8: Construction of an exact cover from the set of clauses in Example 14.4.

The construction of the graph G uses a trick involving a small subgraph Gad with 7 (distinct) nodes known as a *gadget* shown in Figure 14.9.

The crucial property of the graph Gad is that if Gad is a subgraph of a bigger graph G in such a way that no edge of G is incident to any of the nodes u, v, w unless it is one of the eight edges of Gad incident to the nodes u, v, w, then for any Hamiltonian cycle in G, either the path (a, u), (u, v), (v, w), (w, b) is traversed or the path (c, w), (w, v), (v, u), (u, d) is traversed, but not both.

The reader should convince herself/himself that indeed, any Hamiltonian cycle that does not traverse either the subpath (a, u), (u, v), (v, w), (w, b) from a to b or the subpath (c, w), (w, v), (v, u), (u, d) from c to d will not traverse one of the nodes u, v, w. Also, the fact that node v is traversed exactly once forces only one of the two paths to be traversed but not both. The reader should also convince herself/himself that a smaller graph does not guarantee the desired property.

It is convenient to use the simplified notation with a special type of edge labeled with the exclusive or sign \oplus between the "edges" between a and b and between d and c, as shown in Figure 14.10.



Figure 14.9: A gadget Gad.



Figure 14.10: A shorthand notation for a gadget.

Whenever such a figure occurs, the actual graph is obtained by substituting a copy of the graph Gad (the four nodes a, b, c, d must be distinct). This abbreviating device can be extended to the situation where we build gadgets between a given pair (a, b) and several other pairs $(c_1, d_1), \ldots, (c_m, d_m)$, all nodes being distinct, as illustrated in Figure 14.11.

Either all three edges $(c_1, d_1), (c_2, d_2), (c_3, d_3)$ are traversed or the edge (a, b) is traversed, and these possibilities are mutually exclusive.

The graph $G = \tau(U, \mathcal{F})$ where $U = \{u_1, \ldots, u_n\}$ (with $n \ge 1$) and $\mathcal{F} = \{S_1, \ldots, S_m\}$ (with $m \ge 1$) is constructed as follows:

The graph G has m + n + 2 nodes $\{u_0, u_1, \ldots, u_n, S_0, S_1, \ldots, S_m\}$. Note that we have added two extra nodes u_0 and S_0 . For $i = 1, \ldots, m$, there are *two* edges $(S_{i-1}, S_i)_1$ and $(S_{i-1}, S_i)_2$ from S_{i-1} to S_i . For $j = 1, \ldots, n$, from u_{j-1} to u_j , there are as many edges as there are sets $S_i \in \mathcal{F}$ containing the element u_j . We can think of each edge between u_{j-1} and u_j as an occurrence of u_j in a uniquely determined set $S_i \in \mathcal{F}$; we denote this edge by $(u_{j-1}, u_j)_i$. We also have an edge from u_n to S_0 and an edge from S_m to u_0 , thus "closing the cycle."

What we have constructed so far is not a legal graph since it may have many parallel



Figure 14.11: A shorthand notation for several gadgets.

edges, but are going to turn it into a legal graph by pairing edges between the u_j 's and edges between the S_i 's. Indeed, since each edge $(u_{j-1}, u_j)_i$ between u_{j-1} and u_j corresponds to an occurrence of u_j in some uniquely determined set $S_i \in \mathcal{F}$ (that is, $u_j \in S_i$), we put an exclusive-or edge between the edge $(u_{j-1}, u_j)_i$ and the edge $(S_{i-1}, S_i)_2$ between S_{i-1} and S_i , which we call the *long edge*. The other edge $(S_{i-1}, S_i)_1$ between S_{i-1} and S_i (not paired with any other edge) is called the *short edge*. Effectively, we put a copy of the gadget graph Gad with $a = u_{j-1}, b = u_j, c = S_{i-1}, d = S_i$ for any pair (u_j, S_i) such that $u_j \in S_i$. The resulting object is indeed a directed graph with no parallel edges. The graph G can be constructed from (U, \mathcal{F}) in time $O(n^2)$.

Example 14.5. The above construction is illustrated in Figure 14.12 for the instance of the exact cover problem given by

$$U = \{u_1, u_2, u_3, u_4\}, \ \mathcal{F} = \{S_1 = \{u_3, u_4\}, \ S_2 = \{u_2, u_3, u_4\}, \ S_3 = \{u_1, u_2\}\}.$$

It remains to prove that (U, \mathcal{F}) has an exact cover iff the graph $G = \tau(U, \mathcal{F})$ has a Hamiltonian cycle. First, assume that G has a Hamiltonian cycle. If so, for every j some unique "edge" $(u_{j-1}, u_j)_i$ is traversed once (since every u_j is traversed once), and by the exclusive-or nature of the gadget graphs, the corresponding long edge $(S_{i-1}, S_i)_2$ can't be traversed, which means that the short edge $(S_{i-1}, S_i)_1$ is traversed. Consequently, if \mathcal{C} consists of those subsets S_i such that the short edge $(S_{i-1}, S_i)_1$ is traversed, then \mathcal{C} consists of pairwise disjoint subsets whose union is U, namely \mathcal{C} is an exact cover.

In our example, there is a Hamiltonian where the blue edges are traversed between the S_i nodes, and the red edges are traversed between the u_i nodes, namely

short
$$(S_0, S_1)$$
, long (S_1, S_2) , short (S_2, S_3) , (S_3, u_0) ,
 $(u_0, u_1)_3$, $(u_1, u_2)_3$, $(u_2, u_3)_1$, $(u_3, u_4)_1$, (u_4, S_0) .

The subsets corresponding to the short (S_{i-1}, S_i) edges are S_1 and S_3 , and indeed $\mathcal{C} = \{S_1, S_3\}$ is an exact cover.

Note that the exclusive-or property of the gadgets implies the following: since the edge $(u_0, u_1)_3$ must be chosen to obtain a Hamiltonian, the long edge (S_2, S_3) can't be chosen, so the edge $(u_1, u_2)_3$ must be chosen, but then the edge $(u_1, u_2)_2$ is not chosen so the long edge (S_1, S_2) must be chosen, so the edges $(u_2, u_3)_2$ and $(u_3, u_4)_2$ can't be chosen, and thus edges $(u_2, u_3)_1$ and $(u_3, u_4)_1$ must be chosen.

Conversely, if \mathcal{C} is an exact cover for (U, \mathcal{F}) , then consider the path in G obtained by traversing each short edge $(S_{i-1}, S_i)_1$ for which $S_i \in \mathcal{C}$, each edge $(u_{j-1}, u_j)_i$ such that $u_j \in S_i$, which means that this edge is connected by a \oplus -sign to the long edge $(S_{i-1}, S_i)_2$ (by construction, for each u_j there is a unique such S_i), and the edges (u_n, S_0) and (S_m, u_0) , then we obtain a Hamiltonian cycle. Observe that the long edges are the inside edges joining the S_i .



Figure 14.12: The directed graph constructed from the data (U, \mathcal{F}) of Example 14.5.

In our example, the exact cover $\mathcal{C} = \{S_1, S_3\}$ yields the Hamiltonian

short (S_0, S_1) , long (S_1, S_2) , short (S_2, S_3) , (S_3, u_0) , $(u_0, u_1)_3$, $(u_1, u_2)_3$, $(u_2, u_3)_1$, $(u_3, u_4)_1$, (u_4, S_0)

that we encountered earlier.

(3) Hamiltonian Cycle (for Undirected Graphs)

To show that Hamiltonian Cycle (for Undirected Graphs) is \mathcal{NP} -complete we reduce Hamiltonian Cycle (for Directed Graphs) to it:

Hamiltonian Cycle (for Directed Graphs) \leq_P Hamiltonian Cycle (for Undirected Graphs)

Given any directed graph G = (V, E) we need to construct in polynomial time an undirected graph $\tau(G) = G' = (V', E')$ such that G has a (directed) Hamiltonian cycle iff G' has a (undirected) Hamiltonian cycle. This is easy. We make three distinct copies v_0, v_1, v_2 of every node $v \in V$ which we put in V', and for every edge $(u, v) \in E$ we create five edges $\{u_0, u_1\}, \{u_1, u_2\}, \{u_2, v_0\}, \{v_0, v_1\}, \{v_1, v_2\}$ which we put in E', as illustrated in the diagram shown in Figure 14.13.



Figure 14.13: Conversion of a directed graph into an undirected graph.

If the size n of the input is |V| + |E|, then G' is constructed in time O(n). The crucial point about the graph G' is that although there may be several edges adjacent to a node u_0 or a node u_2 , the only way to reach u_1 from u_0 is through the edge $\{u_0, u_1\}$ and the only way to reach u_1 from u_2 is through the edge $\{u_1, u_2\}$.

Suppose there is a Hamiltonian cycle in G'. If this cycle arrives at a node u_0 from the node u_1 , then by the above remark, the previous node in the cycle must be u_2 . Then the predecessor of u_2 in the cycle must be a node v_0 such that there is an edge $\{u_2, v_0\}$ in G' arising from an edge (u, v) in G. The nodes in the cycle in G' are traversed in the order (v_0, u_2, u_1, u_0) where v_0 and u_2 are traversed in the opposite order in which they occur as the endpoints of the edge (u, v) in G. If so, consider the reverse of our Hamiltonian cycle in G', which is also a Hamiltonian cycle since G' is unoriented. In this cycle, we go from u_0 to u_1 , then to u_2 , and finally to v_0 . In G, we traverse the edge from u to v. In order for the cycle in G' to be Hamiltonian, we must continue by visiting v_1 and v_2 , since otherwise v_1 is never traversed. Now the next node w_0 in

the Hamiltonian cycle in G' corresponds to an edge (v, w) in G, and by repeating our reasoning we see that our Hamiltonian cycle in G' determines a Hamiltonian cycle in G. We leave it as an easy exercise to check that a Hamiltonian cycle in G yields a Hamiltonian cycle in G'. The process of expanding a directed graph into an undirected graph and the inverse process are illustrated in Figure 14.14 and Figure 14.15.



Figure 14.14: Expanding the directed graph into an undirected graph.

(4) **Traveling Salesman Problem**

To show that the **Traveling Salesman Problem** is \mathcal{NP} -complete, we reduce the **Hamiltonian Cycle Problem (Undirected Graphs)** to it:

Hamiltonian Cycle Problem (Undirected Graphs) \leq_P Traveling Salesman Problem

This is a fairly easy reduction.

Given an undirected graph G = (V, E), we construct an instance $\tau(G) = (D, B)$ of the Traveling Salesman Problem so that G has a Hamiltonian cycle iff the traveling salesman problem has a solution. If we let n = |V|, we have n cities and the matrix



Figure 14.15: Collapsing the undirected graph onto a directed graph.

 $D = (d_{ij})$ is defined as follows:

$$d_{ij} = \begin{cases} 0 & \text{if } i = j \\ 1 & \text{if } \{v_i, v_j\} \in E \\ 2 & \text{otherwise.} \end{cases}$$

We also set the budget B as B = n. The construction of (D, B) from G can be done in time $O(n^2)$.

Any tour of the cities has cost equal to n plus the number of pairs (v_i, v_j) such that $i \neq j$ and $\{v_i, v_j\}$ is *not* an edge of G. It follows that a tour of cost n exists iff there are no pairs (v_i, v_j) of the second kind iff the tour is a Hamiltonian cycle.

The reduction from Hamiltonian Cycle Problem (Undirected Graphs) to the Traveling Salesman Problem is quite simple, but a direct reduction of say Satisfiability to the Traveling Salesman Problem is hard. By breaking this reduction into several steps made it simpler to achieve.

(5) Independent Set

To show that **Independent Set** is \mathcal{NP} -complete, we reduce **Exact 3-Satisfiability** to it:

Exact 3-Satisfiability \leq_P Independent Set

Recall that in **Exact 3-Satisfiability** every clause C_i has exactly three literals L_{i1}, L_{i2}, L_{i3} .

Given a set $F = \{C_1, \ldots, C_m\}$ of $m \ge 2$ such clauses, we construct in polynomial time an undirected graph G = (V, E) such that F is satisfiable iff G has an independent set C with at least K = m nodes.

For every i $(1 \le i \le m)$, we have three nodes c_{i1}, c_{i2}, c_{i3} corresponding to the three literals L_{i1}, L_{i2}, L_{i3} in clause C_i , so there are 3m nodes in V. The "core" of G consists of m triangles, one for each set $\{c_{i1}, c_{i2}, c_{i3}\}$. We also have an edge $\{c_{ik}, c_{j\ell}\}$ iff L_{ik} and $L_{j\ell}$ are complementary literals. If the size n of the input is the sum of the lengths of the clauses, then the construction of G can be done in time $O(n^2)$.

Example 14.6. Let F be the set of clauses

 $F = \{C_1 = (x_1 \lor \overline{x_2} \lor x_3), C_2 = (\overline{x_1} \lor \overline{x_2} \lor x_3), C_3 = (\overline{x_1} \lor \overline{x_2} \lor \overline{x_3}), C_4 = (x_1 \lor x_2 \lor x_3)\}.$

The graph G associated with F is shown in Figure 14.16.



Figure 14.16: The graph constructed from the clauses of Example 14.6.

It remains to show that the construction works. Since any three nodes in a triangle are connected, an independent set C can have at most one node per triangle and thus has at most m nodes. Since the budget is K = m, we may assume that there is an independent set with m nodes. Define a (partial) truth assignment by

$$v(x_i) = \begin{cases} \mathbf{T} & \text{if } L_{jk} = x_i \text{ and } c_{jk} \in C \\ \mathbf{F} & \text{if } L_{jk} = \overline{x_i} \text{ and } c_{jk} \in C. \end{cases}$$

Since the non-triangle edges in G link nodes corresponding to complementary literals and nodes in C are not connected, our truth assignment does not assign clashing truth values to the variables x_i . Not all variables may receive a truth value, in which case we assign an arbitrary truth value to the unassigned variables. This yields a satisfying assignment for F.

In Example 14.6, the set $C = \{c_{11}, c_{22}, c_{32}, c_{41}\}$ corresponding to the nodes shown in red in Figure 14.16 form an independent set, and they induce the partial truth assignment $v(x_1) = \mathbf{T}, v(x_2) = \mathbf{F}$. The variable x_3 can be assigned an arbitrary value, say $v(x_3) = \mathbf{F}$, and v is indeed a satisfying truth assignment for F.

Conversely, if v is a truth assignment for F, then we obtain an independent set C of size m by picking for each clause C_i a node c_{ik} corresponding to a literal L_{ik} whose value under v is **T**.

(6) Clique

To show that Clique is \mathcal{NP} -complete, we reduce Independent Set to it:

Independent Set \leq_P Clique

The key to the reduction is the notion of the complement of an undirected graph G = (V, E). The complement $G^c = (V, E^c)$ of the graph G = (V, E) is the graph with the same set of nodes V as G but there is an edge $\{u, v\}$ (with $u \neq v$) in E^c iff $\{u, v\} \notin E$. Then it is not hard to check that there is a bijection between maximum independent sets in G and maximum cliques in G^c . The reduction consists in constructing from a graph G its complement G^c , and then G has an independent set iff G^c has a clique. Obviously, the reduction can be done in linear time.

This construction is illustrated in Figure 14.17, where a maximum independent set in the graph G is shown in blue and a maximum clique in the graph G^c is shown in red.



Figure 14.17: A graph (left) and its complement (right).

(7) Node Cover

To show that Node Cover is \mathcal{NP} -complete, we reduce Independent Set to it:

Independent Set \leq_P Node Cover

This time the crucial observation is that if N is an independent set in G, then the complement C = V - N of N in V is a node cover in G. Thus there is an independent set of size at least K iff there is a node cover of size at most n - K where n = |V| is the number of nodes in V. The reduction leaves the graph unchanged and replaces K by n - K. Obviously, the reduction can be done in linear time. An example is shown in Figure 14.18 where an independent set is shown in blue and a node cover is shown in red.



Figure 14.18: An inpendent set (left) and a node cover (right).

(8) Knapsack (also called Subset sum)

To show that **Knapsack** is \mathcal{NP} -complete, we reduce **Exact Cover** to it:

Exact Cover \leq_P Knapsack

Given an instance (U, \mathcal{F}) of set cover with $U = \{u_1, \ldots, u_n\}$ and $\mathcal{F} = \{S_1, \ldots, S_m\}$, a family of subsets of U, we need to produce in polynomial time an instance $\tau(U, \mathcal{F})$ of the Knapsack Problem consisting of k nonnegative integers a_1, \ldots, a_k and another integer K > 0 such that there is a subset $I \subseteq \{1, \ldots, k\}$ such that $\sum_{i \in I} a_i = K$ iff there is an exact cover of U using subsets in \mathcal{F} .

The trick here is the relationship between set union and integer addition.

Example 14.7. Consider the exact cover problem given by $U = \{u_1, u_2, u_3, u_4\}$ and

$$\mathcal{F} = \{S_1 = \{u_3, u_4\}, S_2 = \{u_2, u_3, u_4\}, S_3 = \{u_1, u_2\}\}$$

We can represent each subset S_j by a binary string a_j of length 4, where the *i*th bit from the left is 1 iff $u_i \in S_j$, and 0 otherwise. In our example

$$a_1 = 0011$$

 $a_2 = 0111$
 $a_3 = 1100.$

Then the trick is that some family C of subsets S_j is an exact cover if the sum of the corresponding numbers a_j adds up to $1111 = 2^4 - 1 = K$. For example,

$$\mathcal{C} = \{S_1 = \{u_3, u_4\}, S_3 = \{u_1, u_2\}\}$$

is an exact cover and

$$a_1 + a_3 = 0011 + 1100 = 1111.$$

Unfortunately, there is a problem with this encoding which has to do with the fact that addition may involve carry. For example, assuming four subsets and the universe $U = \{u_1, \ldots, u_6\},\$

$$11 + 13 + 15 + 24 = 63.$$

in binary

$$001011 + 001101 + 001111 + 011000 = 111111$$

but if we convert these binary strings to the corresponding subsets we get the subsets

$$S_{1} = \{u_{3}, u_{5}, u_{6}\}$$

$$S_{2} = \{u_{3}, u_{4}, u_{6}\}$$

$$S_{3} = \{u_{3}, u_{4}, u_{5}, u_{6}\}$$

$$S_{4} = \{u_{2}, u_{3}\},$$

which are not disjoint and do not cover U.

The fix is surprisingly simple: use base m (where m is the number of subsets in \mathcal{F}) instead of base 2.

Example 14.8. Consider the exact cover problem given by $U = \{u_1, u_2, u_3, u_4, u_5, u_6\}$ and \mathcal{F} given by

$$S_{1} = \{u_{3}, u_{5}, u_{6}\}$$

$$S_{2} = \{u_{3}, u_{4}, u_{6}\}$$

$$S_{3} = \{u_{3}, u_{4}, u_{5}, u_{6}\}$$

$$S_{4} = \{u_{2}, u_{3}\},$$

$$S_{5} = \{u_{1}, u_{2}, u_{4}\}.$$

In base m = 5, the numbers corresponding to S_1, \ldots, S_5 are

```
a_1 = 001011
a_2 = 001101
a_3 = 001111
a_4 = 011000
a_5 = 110100.
```

This time,

$$a_1 + a_2 + a_3 + a_4 = 001011 + 001101 + 001111 + 011000 = 014223 \neq 111111,$$

so $\{S_1, S_2, S_3, S_4\}$ is not a solution. However

 $a_1 + a_5 = 001011 + 110100 = 111111,$

and $\mathcal{C} = \{S_1, S_5\}$ is an exact cover.

Thus, given an instance (U, \mathcal{F}) of **Exact Cover** where $U = \{u_1, \ldots, u_n\}$ and $\mathcal{F} =$ $\{S_1, \ldots, S_m\}$ the reduction to **Knapsack** consists in forming the *m* numbers a_1, \ldots, a_m (each of n bits) encoding the subsets S_j , namely $a_{ji} = 1$ iff $u_i \in S_j$, else 0, and to let $K = 1 + m^2 + \dots + m^{n-1}$, which is represented in base m by the string <u>11...1</u>. In testing whether $\sum_{i \in I} a_i = K$ for some subset $I \subseteq \{1, \ldots, m\}$, we use arithmetic in

base m.

If a candidate solution \mathcal{C} involves at most m-1 subsets, then since the corresponding numbers are added in base m, a carry can never happen. If the candidate solution involves all m subsets, then $a_1 + \cdots + a_m = K$ iff \mathcal{F} is a partition of U, since otherwise some bit in the result of adding up these m numbers in base m is not equal to 1, even if a carry occurs. Since the number K is written in binary, it takes time O(mn) to produce $((a_1,\ldots,a_m),K)$ from (U,\mathcal{F}) .

(9) Inequivalence of *-free Regular Expressions

To show that **Inequivalence of *-free Regular Expressions** is \mathcal{NP} -complete, we reduce the **Satisfiability Problem** to it:

Satisfiability Problem \leq_P Inequivalence of *-free Regular Expressions

We already argued that **Inequivalence of *-free Regular Expressions** is in \mathcal{NP} because if R is a *-free regular expression, then for every string $w \in \mathcal{L}[R]$ we have $|w| \leq |R|$. The above observation shows that if R_1 and R_2 are *-free and if there is a string $w \in (\mathcal{L}[R_1] - \mathcal{L}[R_2]) \cup (\mathcal{L}[R_2] - \mathcal{L}[R_1])$, then $|w| \leq |R_1| + |R_2|$, so we can indeed check this in polynomial time. It follows that the inequivalence problem for * -free regular expressions is in \mathcal{NP} .

We reduce the **Satisfiability Problem** to the **Inequivalence of *-free Regular Expressions** as follows. For any set of clauses $P = C_1 \wedge \cdots \wedge C_p$, if the propositional variables occurring in P are x_1, \ldots, x_n , we produce two *-free regular expressions R, S over $\Sigma = \{0, 1\}$, such that P is satisfiable iff $L_R \neq L_S$. The expression S is actually

$$S = \underbrace{(0+1)(0+1)\cdots(0+1)}_{n}.$$

The expression R is of the form

$$R = R_1 + \dots + R_p,$$

where R_i is constructed from the clause C_i in such a way that L_{R_i} corresponds precisely to the set of truth assignments that falsify C_i ; see below.

Given any clause C_i , let R_i be the *-free regular expression defined such that, if x_j and \overline{x}_j both belong to C_i (for some j), then $R_i = \emptyset$, else

$$R_i = R_i^1 \cdot R_i^2 \cdots R_i^n$$

where R_i^j is defined by

$$R_i^j = \begin{cases} 0 & \text{if } x_j \text{ is a literal of } C_i \\ 1 & \text{if } \overline{x}_j \text{ is a literal of } C_i \\ (0+1) & \text{if } x_j \text{ does not occur in } C_i. \end{cases}$$

The construction of R from P takes linear time.

Example 14.9. If we apply the above conversion to the clauses of Example 14.3, namely

$$F = \{ C_1 = (x_1 \lor \overline{x_2}), \ C_2 = (\overline{x_1} \lor x_2 \lor x_3), \ C_3 = (x_2), \ C_4 = (\overline{x_2} \lor \overline{x_3}) \},$$

we get

$$R_1 = 0 \cdot 1 \cdot (0+1), \quad R_2 = 1 \cdot 0 \cdot 0, \quad R_3 = (0+1) \cdot 0 \cdot (0+1), \quad R_4 = (0+1) \cdot 1 \cdot 1.$$

Clearly, all truth assignments that falsify C_i must assign \mathbf{F} to x_j if $x_j \in C_i$ or assign \mathbf{T} to x_j if $\overline{x}_j \in C_i$. Therefore, L_{R_i} corresponds to the set of truth assignments that falsify C_i (where 1 stands for \mathbf{T} and 0 stands for \mathbf{F}) and thus, if we let

$$R = R_1 + \dots + R_p,$$

then L_R corresponds to the set of truth assignments that falsify $P = C_1 \wedge \cdots \wedge C_p$. Since $L_S = \{0, 1\}^n$ (all binary strings of length n), we conclude that $L_R \neq L_S$ iff P is satisfiable. Therefore, we have reduced the **Satisfiability Problem** to our problem and the reduction clearly runs in polynomial time. This proves that the problem of deciding whether $L_R \neq L_S$, for any two *-free regular expressions R and S is \mathcal{NP} complete.

(10) 0-1 integer programming problem

It is easy to check that the problem is in \mathcal{NP} .

To prove that the is \mathcal{NP} -complete we reduce the **bounded-tiling problem** to it:

bounded-tiling problem $\leq_P 0$ -1 integer programming problem

Given a tiling problem, $((\mathcal{T}, V, H), \hat{s}, \sigma_0)$, we create a 0-1-valued variable x_{mnt} , such that $x_{mnt} = 1$ iff tile t occurs in position (m, n) in some tiling. Write equations or inequalities expressing that a tiling exists and then use "slack variables" to convert inequalities to equations. For example, to express the fact that every position is tiled by a single tile, use the equation

$$\sum_{t \in \mathcal{T}} x_{mnt} = 1$$

for all m, n with $1 \le m \le 2s$ and $1 \le n \le s$. We leave the rest as as exercise.

14.3 Succinct Certificates, coNP, and EXP

All the problems considered in Section 14.1 share a common feature, which is that for each problem, a solution is produced nondeterministically (an exact cover, a directed Hamiltonian cycle, a tour of cities, an independent set, a node cover, a clique *etc.*), and then this candidate solution is checked deterministically and in polynomial time. The candidate solution is a string called a *certificate* (or *witness*).

It turns out that membership on \mathcal{NP} can be defined in terms of certificates. To be a certificate, a string must satisfy two conditions:

- 1. It must be *polynomially succinct*, which means that its length is at most a polynomial in the length of the input.
- 2. It must be *checkable* in polynomial time.

All "yes" inputs to a problem in \mathcal{NP} must have at least one certificate, while all "no" inputs must have none.

The notion of certificate can be formalized using the notion of a polynomially balanced language.

Definition 14.3. Let Σ be an alphabet, and let ";" be a symbol not in Σ . A language $L' \subseteq \Sigma^*; \Sigma^*$ is said to be *polynomially balanced* if there exists a polynomial p(X) such that for all $x, y \in \Sigma^*$, if $x; y \in L'$ then $|y| \leq p(|x|)$.

Suppose L' is a polynomially balanced language and that $L' \in \mathcal{P}$. Then we can consider the language

$$L = \{ x \in \Sigma^* \mid (\exists y \in \Sigma^*) (x; y \in L') \}.$$

The intuition is that for each $x \in L$, the set

$$\{y \in \Sigma^* \mid x; y \in L'\}$$

is the set of certificates of x. For every $x \in L$, a Turing machine can nondeterministically guess one of its certificates y, and then use the deterministic Turing machine for L' to check in polynomial time that $x; y \in L'$. Note that, by definition, strings not in L have no certificate. It follows that $L \in \mathcal{NP}$.

Conversely, if $L \in \mathcal{NP}$ and the alphabet Σ has at least two symbols, we can encode the paths in the computation tree for every input $x \in L$, and we obtain a polynomially balanced language $L' \subseteq \Sigma^*; \Sigma^*$ with L' in \mathcal{P} such that

$$L = \{ x \in \Sigma^* \mid (\exists y \in \Sigma^*) (x; y \in L') \}.$$

The details of this construction are left as an exercise. In summary, we obtain the following theorem.

Theorem 14.1. Let $L \subseteq \Sigma^*$ be a language over an alphabet Σ with at least two symbols, and let ";" be a symbol not in Σ . Then $L \in \mathcal{NP}$ iff there is a polynomially balanced language $L' \subseteq \Sigma^*; \Sigma^*$ such that $L' \in \mathcal{P}$ and

$$L = \{ x \in \Sigma^* \mid (\exists y \in \Sigma^*) (x; y \in L') \}.$$

Theorem 14.1 shows that the introduction of non-deterministic Turing machines is not really needed to define the class \mathcal{NP} , but this extreme point of view is not fruitful.

A striking illustration of the notion of succint certificate is illustrated by the set of *composite* integers, namely those natural numbers $n \in \mathbb{N}$ that can be written as the product pq of two numbers $p, q \geq 2$ with $p, q \in \mathbb{N}$. For example, the number

is a composite!

This is far from obvious, but if an oracle gives us the certificate {6,700,417, 641}, it is easy to carry out in polynomial time the multiplication of these two numbers and check that it is equal to 4,294,967,297. Finding a certificate is usually (very) hard, but checking that it works is easy. This is the point of certificates. We conclude this section with a brief discussion of the complexity classes coNP and \mathcal{EXP} .

By definition,

$$\mathrm{co}\mathcal{NP} = \{\overline{L} \mid L \in \mathcal{NP}\},\$$

that is, coNP consists of all complements of languages in NP. Since $P \subseteq NP$ and P is closed under complementation,

$$\mathcal{P} \subseteq \mathrm{co}\mathcal{N}\mathcal{P},$$

so $\mathcal{P} \subseteq \mathcal{NP} \cap \operatorname{co}\mathcal{NP}$, but nobody knows whether this inclusion is proper or whether \mathcal{NP} is closed under complementation, that is, nobody knows whether $\mathcal{NP} = \operatorname{co}\mathcal{NP}$.

A language L is coNP-hard if every language in coNP is polynomial-time reducible to L, and coNP-complete if $L \in coNP$ and L is coNP-hard.

What can be shown is that if $\mathcal{NP} \neq co\mathcal{NP}$, then $\mathcal{P} \neq \mathcal{NP}$. However it is possible that $\mathcal{P} \neq \mathcal{NP}$ and yet $\mathcal{NP} = co\mathcal{NP}$, although this is considered unlikely.

We have $\mathcal{P} \subseteq \mathcal{NP} \cap \mathrm{co}\mathcal{NP}$, but there are problems in $\mathcal{NP} \cap \mathrm{co}\mathcal{NP}$ not known to be in \mathcal{P} . One of the most famous in the following problem:

Integer factorization problem:

Given an integer $N \ge 3$, and another integer M (a budget) such that 1 < M < N, does N have a factor d with $1 < d \le M$?

Proposition 14.2. The problem Integer factorization is in $\mathcal{NP} \cap co\mathcal{NP}$.

Proof. That **Integer factorization** is in \mathcal{NP} is clear. To show that **Integer factorization** is in $\operatorname{co}\mathcal{NP}$, we can guess a factorization of N into distinct factors all greater than M, check that they are prime using the results of Chapter 15 showing that testing primality is in \mathcal{NP} (even in \mathcal{P} , but that's much harder to prove), and then check that the product of these factors is N.

It is widely believed that Integer factorization does not belong to \mathcal{P} , which is the technical justification for saying that this problem is hard. Most cryptographic algorithms rely on this unproven fact. If Integer factorization was either \mathcal{NP} -complete or co \mathcal{NP} -complete, then we would have $\mathcal{NP} = co\mathcal{NP}$, which is considered very unlikely.

Remark: If $\sqrt{N} \leq M < N$, the above problem is equivalent to asking whether N is prime.

A natural instance of a problem in coNP is the *unsatisfiability problem* for propositions UNSAT = \neg SAT, namely deciding that a proposition P has no satisfying assignment.

Definition 14.4. A proposition P (in CNF) is *falsifiable* if there is some truth assignment v such that $\hat{v}(P) = \mathbf{F}$.

It is obvious that the set of falsifiable propositions is in \mathcal{NP} . Since a proposition P is valid iff P is not falsifiable, the *validity (or tautology) problem* TAUT for propositions is in $co\mathcal{NP}$. In fact, the following result holds.

Proposition 14.3. The problem TAUT is coNP-complete.

Proof. See Papadimitriou [56]. Since SAT is \mathcal{NP} -complete, for every language $L \in \mathcal{NP}$, there is a polynomial-time computable function $f: \Sigma^* \to \Sigma^*$ such that $x \in L$ iff $f(x) \in SAT$. Then $x \notin L$ iff $f(x) \notin SAT$, that is, $x \in \overline{L}$ iff $f(x) \in \neg SAT$, which means that every language $\overline{L} \in \operatorname{co}\mathcal{NP}$ is polynomial-time reducible to $\neg SAT = \operatorname{UNSAT}$. But TAUT = $\{\neg P \mid P \in \operatorname{UNSAT}\}$, so we have the polynomial-time computable function g given by $g(x) = \neg f(x)$ which gives us the reduction $x \in \overline{L}$ iff $g(x) \in \operatorname{TAUT}$, which shows that TAUT is $\operatorname{co}\mathcal{NP}$ -complete.

Despite the fact that this problem has been extensively studied, not much is known about its exact complexity.

The reasoning used to show that TAUT is coNP-complete can also be used to show the following interesting result.

Proposition 14.4. If a language L is \mathcal{NP} -complete, then its complement \overline{L} is $co\mathcal{NP}$ -complete.

Proof. By definition, since $L \in \mathcal{NP}$, we have $\overline{L} \in co\mathcal{NP}$. Since L is \mathcal{NP} -complete, for every language $L_2 \in \mathcal{NP}$, there is a polynomial-time computable function $f: \Sigma^* \to \Sigma^*$ such that $x \in L_2$ iff $f(x) \in L$. Then $x \notin L_2$ iff $f(x) \notin L$, that is, $x \in \overline{L_2}$ iff $f(x) \in \overline{L}$, which means that \overline{L} is $co\mathcal{NP}$ -hard as well, thus $co\mathcal{NP}$ -complete. \Box

The class \mathcal{EXP} is defined as follows.

Definition 14.5. A deterministic Turing machine M is said to be *exponentially bounded* if there is a polynomial p(X) such that for every input $x \in \Sigma^*$, there is no ID ID_n such that

$$ID_0 \vdash ID_1 \vdash^* ID_{n-1} \vdash ID_n$$
, with $n > 2^{p(|x|)}$.

The class \mathcal{EXP} is the class of all languages that are accepted by some exponentially bounded deterministic Turing machine.

Remark: We can also define the class \mathcal{NEXP} as in Definition 14.5, except that we allow nondeterministic Turing machines.

One of the interesting features of \mathcal{EXP} is that it contains \mathcal{NP} .

Theorem 14.5. We have the inclusion $\mathcal{NP} \subseteq \mathcal{EXP}$.

Sketch of proof. Let M be some nondeterministic Turing machine accepting L in polynomial time bounded by p(X). We can construct a deterministic Turing machine M' that operates as follows: for every input x, M' simulates M on all computations of length 1, then on all possible computations of length 2, and so on, up to all possible computations of length p(|x|) + 1. At this point, either an accepting computation has been discovered or all computations have halted rejecting. We claim that M' operates in time bounded by $2^{q(|x|)}$ for some polynomial q(X). First, let r be the degree of nondeterminism of M, that is, the maximum number of triples (b, m, q) such that a quintuple (p, q, b, m, q) is an instructions of M. Then to simulate a computation of M of length ℓ , M' needs $O(\ell)$ steps—to copy the input, to produce a string c in $\{1, \ldots, r\}^{\ell}$, and so simulate M according to the choices specified by c. It follows that M' can carry out the simulation of M on an input x in

$$\sum_{\ell=1}^{p(|x|)+1} r^{\ell} \le (r+1)^{p(|x|)+1}$$

steps. Including the $O(\ell)$ extra steps for each ℓ , we obtain the bound $(r+2)^{p(|x|)+1}$. Then we can pick a constant k such that $2^k > r+2$, and with q(X) = k(p(X) + 1), we see that M' operates in time bounded by $2^{q(|x|)}$.

It is also immediate to see that \mathcal{EXP} is closed under complementation. Furthermore the strict inclusion $\mathcal{P} \subset \mathcal{EXP}$ holds.

Theorem 14.6. We have the strict inclusion $\mathcal{P} \subset \mathcal{EXP}$.

Sketch of proof. We use a diagonalization argument to produce a language E such that $E \notin \mathcal{P}$, yet $E \in \mathcal{EXP}$. We need to code a Turing machine as a string, but this can certainly be done using the techniques of Chapter 8. Let #(M) be the code of Turing machine M and let #(x) be the code of x. Define E as

 $E = \{ \#(M) \#(x) \mid M \text{ accepts input } x \text{ after at most } 2^{|x|} \text{ steps} \}.$

We claim that $E \notin \mathcal{P}$. We proceed by contradiction. If $E \in \mathcal{P}$, then so is the language E_1 given by

 $E_1 = \{ \#(M) \mid M \text{ accepts } \#(M) \text{ after at most } 2^{|\#(M)|} \text{ steps} \}.$

Since \mathcal{P} is closed under complementation, we also have $\overline{E_1} \in \mathcal{P}$. Let M^* be a deterministic Turing machine accepting $\overline{E_1}$ in time p(X), for some polynomial p(X). Since p(X) is a polynomial, there is some n_0 such that $p(n) \leq 2^n$ for all all $n \geq n_0$. We may also assume that $|\#(M^*)| \geq n_0$, since if not we can add n_0 "dead states" to M^* .

Now what happens if we run M^* on its own code $\#(M^*)$?

It is easy to see that we get a contradiction, namely M^* accepts $\#(M^*)$ iff M^* rejects $\#(M^*)$. We leave this verification as an exercise.

In conclusion, $\overline{E_1} \notin \mathcal{P}$, which in turn implies that $E \notin \mathcal{P}$.

It remains to prove that $E \in \mathcal{EXP}$. This is because we can construct a Turing machine that can in exponential time simulate any Turing machine M on input x for $2^{|x|}$ steps. \Box

In summary, we have the chain of inclusions

$$\mathcal{P}\subseteq\mathcal{NP}\subseteq\mathcal{EXP},$$

where the inclusions $\mathcal{P} \subset \mathcal{EXP}$ is strict (by Theorem 14.6), but the left inclusion and the right inclusion are both open problems, and we know that at least one of these two inclusions is strict.

We also have the inclusions

$$\mathcal{P} \subseteq \mathcal{NP} \subseteq \mathcal{EXP} \subseteq \mathcal{NEXP},$$

where the inclusions $\mathcal{P} \subset \mathcal{EXP}$ and $\mathcal{NP} \subset \mathcal{NEXP}$ are strict. The strict inclusion $\mathcal{NP} \subset \mathcal{NEXP}$ is a consequence of the time hierarchy theorem (Cook, Seiferas, Fischer, Meyer, Zak); see Papadimitriou [56] (Chapters 7 and 20) and Arora and Barak [4] (Chapter 3, Section 3.2). The left inclusion and the right inclusion in $\mathcal{NP} \subseteq \mathcal{EXP} \subseteq \mathcal{NEXP}$ are both open problems, but we know that at least one of these two inclusions is strict. It can be shown that if $\mathcal{EXP} \neq \mathcal{NEXP}$, then $\mathcal{P} \neq \mathcal{NP}$; see Papadimitriou [56].

Chapter 15 Primality Testing is in \mathcal{NP}

15.1 Prime Numbers and Composite Numbers

Prime numbers have fascinated mathematicians and more generally curious minds for thousands of years. What is a prime number? Well, $2, 3, 5, 7, 11, 13, \ldots, 9973$ are prime numbers.

Definition 15.1. A positive integer p is prime if $p \ge 2$ and if p is only divisible by 1 and p. Equivalently, p is prime if and only if p is a positive integer $p \ge 2$ that is not divisible by any integer m such that $2 \le m < p$. A positive integer $n \ge 2$ which is not prime is called *composite*.

Observe that the number 1 is considered neither a prime nor a composite. For example, $6 = 2 \cdot 3$ is composite. Is $3\,215\,031\,751$ composite? Yes, because

 $3\,215\,031\,751 = 151 \cdot 751 \cdot 28351.$

Even though the definition of primality is very simple, the structure of the set of prime numbers is highly nontrivial. The prime numbers are the basic building blocks of the natural numbers because of the following theorem bearing the impressive name of *fundamental* theorem of arithmetic.

Theorem 15.1. Every natural number $n \ge 2$ has a unique factorization

$$n = p_1^{i_1} p_2^{i_2} \cdots p_k^{i_k},$$

where the exponents i_1, \ldots, i_k are positive integers and $p_1 < p_2 < \cdots < p_k$ are primes.

Every book on number theory has a proof of Theorem 15.1. The proof is not difficult and uses induction. It has two parts. The first part shows the existence of a factorization. The second part shows its uniqueness. For example, see Apostol [3] (Chapter 1, Theorem 1.10).

How many prime numbers are there? Many! In fact, infinitely many.

Theorem 15.2. The set of prime numbers is infinite.

Proof. The following proof attributed to Hermite only use the fact that every integer greater than 1 has some prime divisor. We prove that for every natural number $n \ge 2$, there is some prime p > n. Consider N = n! + 1. The number N must be divisible by some prime p (p = N is possible). Any prime p dividing N is distinct from $2, 3, \ldots, n$, since otherwise p would divide N - n! = 1, a contradiction.

The problem of determining whether a given integer is prime is one of the better known and most easily understood problems of pure mathematics. This problem has caught the interest of mathematicians again and again for centuries. However, it was not until the 20th century that questions about primality testing and factoring were recognized as problems of practical importance and a central part of applied mathematics. The advent of cryptographic systems that use large primes, such as RSA, was the main driving force for the development of fast and reliable methods for primality testing. Indeed, in order to create RSA keys, one needs to produce large prime numbers.

15.2 Methods for Primality Testing

The general strategy to test whether an integer n > 2 is prime or composite is to choose some property, say A, implied by primality, and to search for a counterexample a to this property for the number n, namely some a for which property A fails. We look for properties for which checking that a candidate a is indeed a countexample can be done quickly.

A simple property that is the basis of several primality testing algorithms is the *Fermat* test, namely

$$a^{n-1} \equiv 1 \pmod{n},$$

which means that $a^{n-1} - 1$ is divisible by n (see Definition 15.2 for the meaning of the notation $a \equiv b \pmod{n}$). If n is prime, and if gcd(a, n) = 1, then the above test is indeed satisfied; this is Fermat's little theorem, Theorem 15.7.

Typically, together with the number n being tested for primality, some candidate counterexample a is supplied to an algorithm which runs a test to determine whether a is really a counterexample to property A for n. If the test says that a is a counterexample, also called a *witness*, then we know for sure that n is composite.

For example, using the Fermat test, if n = 10 and a = 3, we check that

$$3^9 = 19683 = 10 \cdot 1968 + 3.$$

so $3^9 - 1$ is not divisible by 10, which means that

$$a^{n-1} = 3^9 \not\equiv 1 \pmod{10},$$

and the Fermat test fails. This shows that 10 is not prime and that a = 3 is a witness of this fact.

If the algorithm reports that a is not a witness to the fact that n is composite, does this imply that n is prime? Unfortunately, no. This is because, there may be some composite number n and some candidate counterexample a for which the test says that a is not a countexample. Such a number a is called a *liar*.

For example, using the Fermat test for $n = 91 = 7 \cdot 13$ and a = 3, we can check that

$$a^{n-1} = 3^{90} \equiv 1 \pmod{91},$$

so the Fermat test succeeds even though 91 is not prime. The number a = 3 is a liar.

The other reason is that we haven't tested all the candidate counterexamples a for n. In the case where n = 91, it is shown in Section 15.5 that $2^{90} - 64$ is divisible by 91, so the Fermat test fails for a = 2, which confirms that 91 is not prime, and a = 2 is a witness of this fact.

Unfortunately, the Fermat test has the property that it may succeed for all candidate counterexamples, even though n is composite. The number $n = 561 = 3 \cdot 11 \cdot 17$ is such a devious number. It can be shown that for all $a \in \{2, \ldots, 560\}$ such that gcd(a, 561) = 1, we have

$$a^{560} \equiv 1 \pmod{561},$$

so *all* these a are liars.

Such composite numbers for which the Fermat test succeeds for all candidate counterexamples are called *Carmichael numbers*, and unfortunately there are infinitely many of them. Thus the Fermat test is doomed. There are various ways of strengthening the Fermat test, but we will not discuss this here. We refer the interested reader to Crandall and Pomerance [7] and Gallier and Quaintance [21].

The remedy is to make sure that we pick a property A such that if n is composite, then at least some candidate a is not a liar, and to test all potential countexamples a. The difficulty is that trying all candidate countexamples can be too expensive to be practical.

There are two classes of primality testing algorithms:

(1) Algorithms that try all possible countexamples and for which the test does not lie. These algorithms give a definite answer: n is prime or n is composite. Until 2002, no algorithms running in polynomial time were known. The situation changed in 2002 when a paper with the title "PRIMES is in **P**," by Agrawal, Kayal and Saxena, appeared on the website of the Indian Institute of Technology at Kanpur, India. In this paper, it was shown that testing for primality has a deterministic (nonrandomized) algorithm that runs in polynomial time.

We will not discuss algorithms of this type here, and instead refer the reader to Crandall and Pomerance [7] and Ribenboim [62].

- (2) Randomized algorithms. To avoid having problems with infinite events, we assume that we are testing numbers in some large finite interval \mathcal{I} . Given any positive integer $m \in \mathcal{I}$, some candidate witness a is chosen at random. We have a test which, given m and a potential witness a, determines whether or not a is indeed a witness to the fact that m is composite. Such an algorithm is a *Monte Carlo* algorithm, which means the following:
 - (1) If the test is positive, then $m \in \mathcal{I}$ is composite. In terms of probabilities, this is expressed by saying that the conditional probability that $m \in \mathcal{I}$ is composite given that the test is positive is equal to 1. If we denote the event that some positive integer $m \in \mathcal{I}$ is composite by C, then we can express the above as

 $\Pr(C \mid \text{test is positive}) = 1.$

(2) If $m \in \mathcal{I}$ is composite, then the test is positive for at least 50% of the choices for a. We can express the above as

$$\Pr(\text{test is positive} \mid C) \ge \frac{1}{2}.$$

This gives us a degree of confidence in the test.

The contrapositive of (1) says that if $m \in \mathcal{I}$ is prime, then the test is negative. If we denote by P the event that some positive integer $m \in \mathcal{I}$ is prime, then this is expressed as

Pr(test is negative | P) = 1.

If we repeat the test ℓ times by picking independent potential witnesses, then the conditional probability that the test is negative ℓ times given that n is composite, written $\Pr(\text{test is negative } \ell \text{ times } | C)$, is given by

Pr(test is negative
$$\ell$$
 times $|C) = Pr(test is negative $|C)^{\ell}$
= $(1 - Pr(test is positive |C))^{\ell}$
 $\leq \left(1 - \frac{1}{2}\right)^{\ell}$
= $\left(\frac{1}{2}\right)^{\ell}$,$

where we used Property (2) of a Monte Carlo algorithm that

$$\mathsf{Pr}(\text{test is positive} \mid C) \geq \frac{1}{2}$$

and the independence of the trials. This confirms that if we run the algorithm ℓ times, then $\Pr(\text{test is negative } \ell \text{ times } | C)$ is very small. In other words, it is very unlikely that the test will lie ℓ times (is negative) given that the number $m \in \mathcal{I}$ is composite.

If the probability $\Pr(P)$ of the event P is known, which requires knowledge of the distribution of the primes in the interval \mathcal{I} , then the conditional probability

 $\Pr(P \mid \text{test is negative } \ell \text{ times})$

can be determined using Bayes's rule.

A Monte Carlo algorithm does not give a definite answer. However, if ℓ is large enough (say $\ell = 100$), then the conditional probability that the number *n* being tested is prime given that the test is negative ℓ times, is very close to 1.

Two of the best known randomized algorithms for primality testing are the *Miller-Rabin* test and the *Solovay-Strassen* test. We will not discuss these methods here, and we refer the reader to Gallier and Quaintance [21].

However, what we will discuss is a nondeterministic algorithm that checks that a number n is prime by guessing a certain kind of tree that we call a Lucas tree (because this algorithm is based on a method due to E. Lucas), and then verifies in polynomial time (in the length $\log_2 n$ of the input given in binary) that this tree constitutes a "proof" that n is indeed prime. This shows that primality testing is in \mathcal{NP} , a fact that is not obvious at all. Of course, this is a much weaker result than the AKS algorithm, but the proof that the AKS works in polynomial time (in $\log_2 n$) is much harder.

The Lucas test, and basically all of the primality-testing algorithms, use modular arithmetic and some elementary facts of number theory such as the Euler-Fermat theorem, so we proceed with a review of these concepts.

15.3 Modular Arithmetic, the Groups $\mathbb{Z}/n\mathbb{Z}$, $(\mathbb{Z}/n\mathbb{Z})^*$

Recall the fundamental notion of congruence modulo n and its notation due to Gauss (circa 1802).

Definition 15.2. For any $a, b \in \mathbb{Z}$, we write $a \equiv b \pmod{m}$ iff a - b = km, for some $k \in \mathbb{Z}$ (in other words, a - b is divisible by m), and we say that a and b are congruent modulo m.

For example, $37 \equiv 1 \pmod{9}$, since $37 - 1 = 36 = 4 \cdot 9$. It can also be shown that $200^{250} \equiv 1 \pmod{251}$, but this is impossible to do by brute force, so we will develop some tools to either avoid such computations, or to make them tractable.

It is easy to check that congruence is an equivalence relation but it also satisfies the following properties.

Proposition 15.3. For any positive integer m, for all $a_1, a_2, b_1, b_2 \in \mathbb{Z}$, the following properties hold. If $a_1 \equiv b_1 \pmod{m}$ and $a_2 \equiv b_2 \pmod{m}$, then

(1) $a_1 + a_2 \equiv b_1 + b_2 \pmod{m}$.

- (2) $a_1 a_2 \equiv b_1 b_2 \pmod{m}$.
- (3) $a_1a_2 \equiv b_1b_2 \pmod{m}$.

Proof. We only check (3), leaving (1) and (2) as easy exercises. Because $a_1 \equiv b_1 \pmod{m}$ and $a_2 \equiv b_2 \pmod{m}$, we have $a_1 = b_1 + k_1 m$ and $a_2 = b_2 + k_2 m$, for some $k_1, k_2 \in \mathbb{Z}$, so we obtain

$$a_1a_2 - b_1b_2 = a_1(a_2 - b_2) + (a_1 - b_1)b_2$$

= $(a_1k_2 + k_1b_2)m.$

Proposition 15.3 allows us to define addition, subtraction, and multiplication on equivalence classes modulo m.

Definition 15.3. Given any positive integer m, we denote by $\mathbb{Z}/m\mathbb{Z}$ the set of equivalence classes modulo m. If we write \overline{a} for the equivalence class of $a \in \mathbb{Z}$, then we define addition, subtraction, and multiplication on residue classes as follows:

$$\overline{a} + \overline{b} = \overline{a + b}$$
$$\overline{a} - \overline{b} = \overline{a - b}$$
$$\overline{a} \cdot \overline{b} = \overline{ab}.$$

The above operations make sense because $\overline{a+b}$ does not depend on the representatives chosen in the equivalence classes \overline{a} and \overline{b} , and similarly for $\overline{a-b}$ and \overline{ab} . Each equivalence class \overline{a} contains a unique representative from the set of remainders $\{0, 1, \ldots, m-1\}$, modulo m, so the above operations are completely determined by $m \times m$ tables. Using the arithmetic operations of $\mathbb{Z}/m\mathbb{Z}$ is called *modular arithmetic*.

The addition tables of $\mathbb{Z}/n\mathbb{Z}$ for n = 2, 3, 4, 5, 6, 7 are shown below.

	m = 4	n = 5			
n-2 $n=3$	$\begin{array}{c c} n-4 \\ \hline + & 0 & 1 & 2 & 3 \end{array}$	+ 0 1 2 3 4			
$\begin{array}{c c} n-2 \\ + & 0 & 1 \\ \end{array}$	+ 0 1 2 3	0 0 1 2 3 4			
		1 1 2 3 4 0			
		$2 \ 2 \ 3 \ 4 \ 0 \ 1$			
		3 3 4 0 1 2			
	3 3 0 1 2	4 4 0 1 2 3			
	n -	7			
n = 6		$\frac{1}{2}$ 4 \mathbb{E} 6			
+ 0 1 2 3 4 5	+ 0 1 2	5 4 5 0			
	$0 \mid 0 \mid 1 \mid 2$	3 4 5 6			
		4 5 6 0			
	$2 \ 2 \ 3 \ 4$	$5 \ 6 \ 0 \ 1$			
		6 0 1 2			
		0 1 2 3			
		1 2 3 4			
5 5 0 1 2 3 4		2 3 4 2 3 4			
<u> </u>		2 3 4 3			

It is easy to check that the addition operation + is commutative (abelian), associative, that 0 is an identity element for +, and that every element a has -a as additive inverse, which means that

$$a + (-a) = (-a) + a = 0.$$

The set $\mathbb{Z}/n\mathbb{Z}$ of residue classes modulo n is a group under addition, a notion defined formally in Definition 15.4

It is easy to check that the multiplication operation \cdot is commutative (abelian), associative, that 1 is an identity element for \cdot , and that \cdot is distributive on the left and on the right with respect to addition. We usually suppress the dot and write $\overline{a} \overline{b}$ instead of $\overline{a} \cdot \overline{b}$. The multiplication tables of $\mathbb{Z}/n\mathbb{Z}$ for $n = 2, 3, \ldots, 9$ are shown below. Since $0 \cdot m = m \cdot 0 = 0$ for all m, these tables are only given for nonzero arguments.

<i>n</i> =	= 2	
•	1]
1	1	

1

1

 $\mathbf{2}$ 21

	<i>n</i> =	= 4	
•	1	2	3
1	1	2	3
2	2	0	2
3	3	2	1

n = 5								
•	1	2	3	4				
1	1	2	3	4				
2	2	4	1	3				
3	3	1	4	2				
4	4	3	2	1				

n = 6									
•	1	2	3	4	5				
1	1	2	3	4	5				
2	2	4	0	2	4				
3	3	0	3	0	3				
4	4	2	0	4	2				
5	5	4	3	2	1				

n = 7								
•	1	2	3	4	5	6		
1	1	2	3	4	5	6		
2	2	4	6	1	3	5		
3	3	6	2	5	1	4		
4	4	1	5	2	6	3		
5	5	3	1	6	4	2		
6	6	5	4	3	2	1		

n = 8									
•	1	2	3	4	5	6	7		
1	1	2	3	4	5	6	7		
2	2	4	6	0	2	4	6		
3	3	6	1	4	7	2	5		
4	4	0	4	0	4	0	4		
5	5	2	7	4	1	6	3		
6	6	4	2	0	6	4	2		
7	7	6	5	4	3	2	1		

n = 9

					-			
•	1	2	3	4	5	6	7	8
1	1	2	3	4	5	6	7	8
2	2	4	6	8	1	3	5	7
3	3	6	0	3	6	0	3	6
4	4	8	3	7	2	6	1	5
5	5	1	6	2	7	3	8	4
6	6	3	0	6	3	0	6	3
7	7	5	3	1	8	6	4	2
8	8	7	6	5	4	3	2	1

Examining the above tables, we observe that for n = 2, 3, 5, 7, which are primes, every element has an inverse, which means that for every nonzero element a, there is some (actually, unique) element b such that

$$a \cdot b = b \cdot a = 1.$$

For n = 2, 3, 5, 7, the set $\mathbb{Z}/n\mathbb{Z} - \{0\}$ is an abelian group under multiplication (see Definition 15.4). When n is composite, there exist nonzero elements whose product is zero. For example, when n = 6, we have $3 \cdot 2 = 0$, when n = 8, we have $4 \cdot 4 = 0$, when n = 9, we have $6 \cdot 6 = 0$.

For n = 4, 6, 8, 9, the elements a that have an inverse are precisely those that are relatively prime to the modulus n (that is, gcd(a, n) = 1).

These observations hold in general. Recall the Bezout criterion (Proposition 11.3): two nonzero integers $m, n \in \mathbb{Z}$ are relatively prime $(\gcd(m, n) = 1)$ iff there are integers $a, b \in \mathbb{Z}$ such that

$$am + bn = 1.$$

Proposition 15.4. Given any integer $n \ge 1$, for any $a \in \mathbb{Z}$, the residue class $\overline{a} \in \mathbb{Z}/n\mathbb{Z}$ is invertible with respect to multiplication iff gcd(a, n) = 1.

Proof. If \overline{a} has inverse \overline{b} in $\mathbb{Z}/n\mathbb{Z}$, then $\overline{a}\overline{b} = 1$, which means that

$$ab \equiv 1 \pmod{n},$$

that is ab = 1 + nk for some $k \in \mathbb{Z}$, which is the Bezout identity

$$ab - nk = 1$$

and implies that gcd(a, n) = 1. Conversely, if gcd(a, n) = 1, then by Bezout's identity there exist $u, v \in \mathbb{Z}$ such that

$$au + nv = 1,$$

so au = 1 - nv, that is,

 $au \equiv 1 \pmod{n}$,

which means that $\overline{a} \, \overline{u} = 1$, so \overline{a} is invertible in $\mathbb{Z}/n\mathbb{Z}$.

We have alluded to the notion of a group. Here is the formal definition.

Definition 15.4. A group is a set G equipped with a binary operation $:: G \times G \to G$ that associates an element $a \cdot b \in G$ to every pair of elements $a, b \in G$, and having the following properties: \cdot is associative, has an identity element $e \in G$, and every element in G is invertible (w.r.t. \cdot). More explicitly, this means that the following equations hold for all $a, b, c \in G$:

(G1)
$$a \cdot (b \cdot c) = (a \cdot b) \cdot c.$$
 (associativity);

(G2)
$$a \cdot e = e \cdot a = a.$$
 (identity);

 \square

(G3) For every $a \in G$, there is some $a^{-1} \in G$ such that $a \cdot a^{-1} = a^{-1} \cdot a = e$. (inverse).

A group G is abelian (or commutative) if

$$a \cdot b = b \cdot a$$
 for all $a, b \in G$.

It is easy to show that the element e satisfying property (G2) is unique, and for any $a \in G$, the element $a^{-1} \in G$ satisfying $a \cdot a^{-1} = a^{-1} \cdot a = e$ required to exist by (G3) is actually unique. This element is called *the* inverse of a.

The set of integers \mathbb{Z} with the addition operation is an abelian group with identity element 0. The set $\mathbb{Z}/n\mathbb{Z}$ of residues modulo m is an abelian group under addition with identity element 0. In general, $\mathbb{Z}/n\mathbb{Z} - \{0\}$ is *not* a group under multiplication, because some nonzero elements may not have an inverse. However, by Proposition 15.4, if p is prime, then $\mathbb{Z}/n\mathbb{Z} - \{0\}$ is an abelian group under multiplication.

When p is not prime, the subset of elements, shown in boldface in the multiplication tables, forms an abelian group under multiplication.

Definition 15.5. The group (under multiplication) of invertible elements of the ring $\mathbb{Z}/n\mathbb{Z}$ is denoted by $(\mathbb{Z}/n\mathbb{Z})^*$. Note that this group is abelian and only defined if $n \geq 2$.

Definition 15.6. If G is a finite group, the number of elements in G is called the *the order* of G.

Given a group G with identity element e, and any element $g \in G$, we often need to consider the powers of g defined as follows.

Definition 15.7. Given a group G with identity element e, for any nonnegative integer n, it is natural to define the power g^n of g as follows:

$$g^0 = e$$
$$g^{n+1} = g \cdot g^n$$

Using induction, it is easy to show that

$$g^m g^n = g^{n+m}$$

for all $m, n \in \mathbb{N}$.

Since g has an inverse g^{-1} , we can extend the definition of g^n to negative powers. For $n \in \mathbb{Z}$, with n < 0, let

$$g^n = (g^{-1})^{-n}.$$

Then it is easy to prove that

$$g^{i} \cdot g^{j} = g^{i+j}$$
$$(g^{i})^{-1} = g^{-i}$$
$$g^{i} \cdot g^{j} = g^{j} \cdot g^{i}$$

for all $i, j \in \mathbb{Z}$.

Given a finite group G of order n, for any element $a \in G$, it is natural to consider the set of powers $\{e, a^1, a^2, \ldots, a^k, \ldots\}$. A crucial fact is that there is a smallest positive $s \in \mathbb{N}$ such that $a^s = e$, and that s divides n.

Proposition 15.5. Let G be a finite group of order n. For every element $a \in G$, the following facts hold:

- (1) There is a smallest positive integer $s \leq n$ such that $a^s = e$.
- (2) The set $\{e, a, \dots, a^{s-1}\}$ is an abelian group denoted $\langle a \rangle$.
- (3) We have $a^n = e$, and the positive integer s divides n, More generally, for any positive integer m, if $a^m = e$, then s divides m.

Proof. (1) Consider the sequence of n + 1 elements

$$(e, a^1, a^2, \ldots, a^n).$$

Since G only has n distinct elements, by the pigeonhole principle, there exist i, j such that $0 \le i < j \le n$ such that

$$a^i = a^j$$

By multiplying both sides by $(a^i)^{-1} = a^{-i}$, we get

$$e = a^{i}(a^{i})^{-1} = a^{j}(a^{i})^{-1} = a^{j}a^{-i} = a^{j-i}.$$

Since $0 \le i < j \le n$, we have $0 \le j - i \le n$ with $a^{j-i} = e$. Thus there is some s with $0 < s \le n$ such that $a^s = e$, and thus a smallest such s.

(2) Since $a^s = e$, for any $i, j \in \{0, ..., s-1\}$ if we write i+j = sq+r with $0 \le r \le s-1$, we have

$$a^{i}a^{j} = a^{i+j} = a^{sq+r} = a^{sq}a^{r} = (a^{s})^{q}a^{r} = e^{q}a^{r} = a^{r},$$

so $\langle a \rangle$ is closed under multiplication. We have $e \in \langle a \rangle$ and the inverse of a^i is a^{s-i} , so $\langle a \rangle$ is a group. This group is obviously abelian.

(3) For any element $g \in G$, let $g\langle a \rangle = \{ga^k \mid 0 \le k \le s-1\}$. Observe that for any $i \in \mathbb{N}$, we have

$$a^i \langle a \rangle = \langle a \rangle$$

We claim that for any two elements $g_1, g_2 \in G$, if $g_1\langle a \rangle \cap g_2\langle a \rangle \neq \emptyset$, then $g_1\langle a \rangle = g_2\langle a \rangle$.
Proof of the claim. If $g \in g_1(a) \cap g_2(a)$, then there exist $i, j \in \{0, \ldots, s-1\}$ such that

 $g_1 a^i = g_2 a^j.$

Without loss of generality, we may assume that $i \ge j$. By multipliving both sides by $(a^j)^{-1}$, we get

 $q_2 = q_1 a^{i-j}.$

Consequently

$$g_2\langle a\rangle = g_1 a^{i-j} \langle a\rangle = g_1 \langle a\rangle,$$

as claimed.

It follows that the pairwise disjoint nonempty subsets of the form $g\langle a \rangle$, for $g \in G$, form a partition of G. However, the map φ_g from $\langle a \rangle$ to $g\langle a \rangle$ given by $\varphi_g(a^i) = ga^i$ has for inverse the map $\varphi_{g^{-1}}$, so φ_g is a bijection, and thus the subsets $g\langle a \rangle$ all have the same number of elements s. Since these subsets form a partition of G, we must have n = sq for some $q \in \mathbb{N}$, which implies that $a^n = e$.

If $g^m = 1$, then writing m = sq + r, with $0 \le r < s$, we get

$$1 = g^m = g^{sq+r} = (g^s)^q \cdot g^r = g^r,$$

so $g^r = 1$ with $0 \le r < s$, contradicting the minimality of s, so r = 0 and s divides m. \Box

Definition 15.8. Given a finite group G of order n, for any $a \in G$, the smallest positive integer $s \leq n$ such that $a^s = e$ in (1) of Proposition 15.5 is called the *order* of a.

The Euler φ -function plays an important role in the theory of the groups $(\mathbb{Z}/n\mathbb{Z})^*$.

Definition 15.9. Given any positive integer $n \ge 1$, the Euler φ -function (or Euler totient function) is defined such that $\varphi(n)$ is the number of integers a, with $1 \le a \le n$, which are relatively prime to n; that is, with gcd(a, n) = 1.¹

If p is prime, then by definition

$$\varphi(p) = p - 1.$$

We leave it as an exercise to show that if p is prime and if $k \ge 1$, then

$$\varphi(p^k) = p^{k-1}(p-1).$$

It can also be shown that if gcd(m, n) = 1, then

$$\varphi(mn) = \varphi(m)\varphi(n).$$

¹We allow a = n to accomodate the special case n = 1.

The above properties yield a method for computing $\varphi(n)$, based on its prime factorization. If $n = p_1^{i_1} \cdots p_k^{i_k}$, then

$$\varphi(n) = p_1^{i_1-1} \cdots p_k^{i_k-1} (p_1-1) \cdots (p_k-1).$$

For example, $\varphi(17) = 16$, $\varphi(49) = 7 \cdot 6 = 42$,

$$\varphi(900) = \varphi(2^2 \cdot 3^2 \cdot 5^2) = 2 \cdot 3 \cdot 5 \cdot 1 \cdot 2 \cdot 4 = 240.$$

Proposition 15.4 shows that $(\mathbb{Z}/n\mathbb{Z})^*$ has $\varphi(n)$ elements. It also shows that $\mathbb{Z}/n\mathbb{Z} - \{0\}$ is a group (under multiplication) iff n is prime.

For any integer $n \ge 2$, let $(\mathbb{Z}/n\mathbb{Z})^*$ be the group of invertible elements of the ring $\mathbb{Z}/n\mathbb{Z}$. This is a group of order $\varphi(n)$. Then Proposition 15.5 yields the following result.

Theorem 15.6. (Euler) For any integer $n \ge 2$ and any $a \in \{1, \ldots, n-1\}$ such that gcd(a, n) = 1, we have

$$a^{\varphi(n)} \equiv 1 \pmod{n}.$$

In particular, if n is a prime, then $\varphi(n) = n - 1$, and we get Fermat's little theorem.

Theorem 15.7. (Fermat's little theorem) For any prime p and any $a \in \{1, ..., p-1\}$, we have

$$a^{p-1} \equiv 1 \pmod{p}.$$

Since 251 is prime, and since gcd(200, 252) = 1, Fermat's little theorem implies our earlier claim that $200^{250} \equiv 1 \pmod{251}$, without making any computations.

Proposition 15.5 suggests considering groups of the form $\langle g \rangle$.

Definition 15.10. A finite group G is cyclic iff there is some element $g \in G$ such that $G = \langle g \rangle$. An element $g \in G$ with this property is called a generator of G.

Even though, in principle, a finite cyclic group has a very simple structure, finding a generator for a finite cyclic group is generally hard. For example, it turns out that the multiplicative group $(\mathbb{Z}/p\mathbb{Z})^*$ is a cyclic group when p is prime, but no efficient method for finding a generator for $(\mathbb{Z}/p\mathbb{Z})^*$ is known (besides a brute-force search).

Examining the multiplication tables for $(\mathbb{Z}/n\mathbb{Z})^*$ for $n = 3, 4, \ldots, 9$, we can check the following facts:

- 1. 2 is a generator for $(\mathbb{Z}/3\mathbb{Z})^*$.
- 2. 3 is a generator for $(\mathbb{Z}/4\mathbb{Z})^*$.
- 3. 2 is a generator for $(\mathbb{Z}/5\mathbb{Z})^*$.

- 4. 5 is a generator for $(\mathbb{Z}/6\mathbb{Z})^*$.
- 5. 3 is a generator for $(\mathbb{Z}/7\mathbb{Z})^*$.
- 6. Every element of $(\mathbb{Z}/8\mathbb{Z})^*$ satisfies the equation $a^2 = 1 \pmod{8}$, thus $(\mathbb{Z}/8\mathbb{Z})^*$ has no generators.
- 7. 2 is a generator for $(\mathbb{Z}/9\mathbb{Z})^*$.

More generally, it can be shown that the multiplicative groups $(\mathbb{Z}/p^k\mathbb{Z})^*$ and $(\mathbb{Z}/2p^k\mathbb{Z})^*$ are cyclic groups when p is an odd prime and $k \geq 1$.

Definition 15.11. A generator of the group $(\mathbb{Z}/n\mathbb{Z})^*$ (when there is one), is called a *primitive* root modulo n.

As an exercise, the reader should check that the next value of n for which $(\mathbb{Z}/n\mathbb{Z})^*$ has no generator is n = 12.

The following theorem due to Gauss can be shown. For a proof, see Apostol [3] or Gallier and Quaintance [21].

Theorem 15.8. (Gauss) For every odd prime p, the group $(\mathbb{Z}/p\mathbb{Z})^*$ is cyclic of order p-1. It has $\varphi(p-1)$ generators.

According to Definition 15.11, the generators of $(\mathbb{Z}/p\mathbb{Z})^*$ are the *primitive roots modulo* p.

15.4 The Lucas Theorem

In this section we discuss an application of the existence of primitive roots in $(\mathbb{Z}/p\mathbb{Z})^*$ where p is an odd prime, known an the n-1 test. This test due to E. Lucas determines whether a positive odd integer n is prime or not by examining the prime factors of n-1 and checking some congruences.

The n-1 test can be described as the construction of a certain kind of tree rooted with n, and it turns out that the number of nodes in this tree is bounded by $2\log_2 n$, and that the number of modular multiplications involved in checking the congruences is bounded by $2\log_2^2 n$.

When we talk about the complexity of algorithms dealing with numbers, we assume that all inputs (to a Turing machine) are strings representing these numbers, typically in base 2. Since the length of the binary representation of a natural number $n \ge 1$ is $\lfloor \log_2 n \rfloor + 1$ (or $\lceil \log_2(n+1) \rceil$, which allows n = 0), the complexity of algorithms dealing with (nonzero) numbers m, n, etc. is expressed in terms of $\log_2 m, \log_2 n, etc.$ Recall that for any real number $x \in \mathbb{R}$, the *floor of* x is the greatest integer $\lfloor x \rfloor$ that is less that or equal to x, and the *ceiling of* x is the least integer $\lceil x \rceil$ that is greater that or equal to x.

If we choose to represent numbers in base 10, since for any base b we have $\log_b x = \ln x / \ln b$, we have

$$\log_2 x = \frac{\ln 10}{\ln 2} \log_{10} x.$$

Since $(\ln 10)/(\ln 2) \approx 3.322 \approx 10/3$, we see that the number of decimal digits needed to represent the integer n in base 10 is approximately 30% of the number of bits needed to represent n in base 2.

Since the Lucas test yields a tree such that the number of modular multiplications involved in checking the congruences is bounded by $2 \log_2^2 n$, it is not hard to show that testing whether or not a positive integer n is prime, a problem denoted PRIMES, belongs to the complexity class \mathcal{NP} . This result was shown by V. Pratt [59] (1975), but Peter Freyd told me that it was "folklore." Since 2002, thanks to the AKS algorithm, we know that PRIMES actually belongs to the class \mathcal{P} , but this is a much harder result.

Here is Lehmer's version of the Lucas result, from 1876.

Theorem 15.9. (Lucas theorem) Let n be a positive integer with $n \ge 2$. Then n is prime iff there is some integer $a \in \{1, 2, ..., n-1\}$ such that the following two conditions hold:

- (1) $a^{n-1} \equiv 1 \pmod{n}$.
- (2) If n > 2, then $a^{(n-1)/q} \not\equiv 1 \pmod{n}$ for all prime divisors q of n-1.

Proof. First assume that Conditions (1) and (2) hold. If n = 2, since 2 is prime, we are done. Thus assume that $n \ge 3$, and let r be the order of a (we are working in the abelian group $(\mathbb{Z}/n\mathbb{Z})^*$). We claim that r = n - 1. The condition $a^{n-1} \equiv 1 \pmod{n}$ implies that r divides n - 1. Suppose that r < n - 1, and let q be a prime divisor of (n - 1)/r (so q divides n - 1). Since r is the order of a we have $a^r \equiv 1 \pmod{n}$, so we get

$$a^{(n-1)/q} \equiv a^{r(n-1)/(rq)} \equiv (a^r)^{(n-1)/(rq)} \equiv 1^{(n-1)/(rq)} \equiv 1 \pmod{n},$$

contradicting Condition (2). Therefore, r = n - 1, as claimed.

We now show that n must be prime. Now $a^{n-1} \equiv 1 \pmod{n}$ implies that a and n are relatively prime so by Euler's theorem (Theorem 15.6),

$$a^{\varphi(n)} \equiv 1 \pmod{n}$$

Since the order of a is n-1, we have $n-1 \leq \varphi(n)$. If $n \geq 3$ is not prime, then n has some prime divisor p, but n and p are integers in $\{1, 2, \ldots, n\}$ that are not relatively prime to n, so by definition of $\varphi(n)$, we have $\varphi(n) \leq n-2$, contradicting the fact that $n-1 \leq \varphi(n)$. Therefore, n must be prime.

Conversely, assume that n is prime. If n = 2, then we set a = 1. Otherwise, pick a to be any primitive root modulo p.

Clearly, if n > 2 then we may assume that $a \ge 2$. The main difficulty with the n-1 test is not so much guessing the primitive root a, but finding a *complete prime factorization* of n-1. However, as a nondeterministic algorithm, the n-1 test yields a "proof" that a number n is indeed prime which can be represented as a tree, and the number of operations needed to check the required conditions (the congruences) is bounded by $c \log_2^2 n$ for some positive constant c, and this implies that testing primality is in \mathcal{NP} .

Before explaining the details of this method, we sharpen slightly Lucas theorem to deal only with odd prime divisors.

Theorem 15.10. Let n be a positive odd integer with $n \ge 3$. Then n is prime iff there is some integer $a \in \{2, ..., n-1\}$ (a guess for a primitive root modulo n) such that the following two conditions hold:

- (1b) $a^{(n-1)/2} \equiv -1 \pmod{n}$.
- (2b) If n-1 is not a power of 2, then $a^{(n-1)/2q} \not\equiv -1 \pmod{n}$ for all odd prime divisors q of n-1.

Proof. Assume that Conditions (1b) and (2b) of Theorem 15.10 hold. Then we claim that Conditions (1) and (2) of Theorem 15.9 hold. By squaring the congruence $a^{(n-1)/2} \equiv -1 \pmod{n}$, we get $a^{n-1} \equiv 1 \pmod{n}$, which is Condition (1) of Theorem 15.9. Since $a^{(n-1)/2} \equiv -1 \pmod{n}$, Condition (2) of Theorem 15.9 holds for q = 2. Next, if q is an odd prime divisor of n-1, let $m = a^{(n-1)/2q}$. Condition (1b) means that

$$m^q \equiv a^{(n-1)/2} \equiv -1 \pmod{n}.$$

Now if $m^2 \equiv a^{(n-1)/q} \equiv 1 \pmod{n}$, since q is an odd prime, we can write q = 2k + 1 for some $k \geq 1$, and then

$$m^q \equiv m^{2k+1} \equiv (m^2)^k m \equiv 1^k m \equiv m \pmod{n}$$

and since $m^q \equiv -1 \pmod{n}$, we get

$$m \equiv -1 \pmod{n}$$

(regardless of whether n is prime or not). Thus we proved that if $m^q \equiv -1 \pmod{n}$ and $m^2 \equiv 1 \pmod{n}$, then $m \equiv -1 \pmod{n}$. By contrapositive, we see that if $m \not\equiv -1 \pmod{n}$, then $m^2 \not\equiv 1 \pmod{n}$ or $m^q \not\equiv -1 \pmod{n}$, but since $m^q \equiv a^{(n-1)/2} \equiv -1 \pmod{n}$ by Condition (1a), we conclude that $m^2 \equiv a^{(n-1)/q} \not\equiv 1 \pmod{n}$, which is Condition (2) of Theorem 15.9. But then Theorem 15.9 implies that n is prime.

Conversely, assume that n is an odd prime, and let a be any primitive root modulo n. Then by little Fermat we know that

$$a^{n-1} \equiv 1 \pmod{n},$$

 \mathbf{SO}

$$(a^{(n-1)/2} - 1)(a^{(n-1)/2} + 1) \equiv 0 \pmod{n}.$$

Since *n* is prime, either $a^{(n-1)/2} \equiv 1 \pmod{n}$ or $a^{(n-1)/2} \equiv -1 \pmod{n}$, but since *a* generates $(\mathbb{Z}/n\mathbb{Z})^*$, it has order n-1, so the congruence $a^{(n-1)/2} \equiv 1 \pmod{n}$ is impossible, and Condition (1b) must hold. Similarly, if we had $a^{(n-1)/2q} \equiv -1 \pmod{n}$ for some odd prime divisor *q* of n-1, then by squaring we would have

$$a^{(n-1)/q} \equiv 1 \pmod{n},$$

and a would have order at most (n-1)/q < n-1, which is absurd.

15.5 Lucas Trees

If n is an odd prime, we can use Theorem 15.10 to build recursively a tree which is a proof, or certificate, of the fact that n is indeed prime. We first illustrate this process with the prime n = 1279.

Example 15.1. If n = 1279, then we easily check that $n - 1 = 1278 = 2 \cdot 3^2 \cdot 71$. We build a tree whose root node contains the triple (1279, ((2, 1), (3, 2), (71, 1)), 3), where a = 3 is the guess for a primitive root modulo 1279. In this simple example, it is clear that 3 and 71 are prime, but we must supply proofs that these number are prime, so we recursively apply the process to the odd divisors 3 and 71.

Since $3 - 1 = 2^1$ is a power of 2, we create a one-node tree (3, ((2, 1)), 2), where a = 2 is a guess for a primitive root modulo 3. This is a leaf node.

Since $71-1 = 70 = 2 \cdot 5 \cdot 7$, we create a tree whose root node is (71, ((2, 1), (5, 1), (7, 1)), 7), where a = 7 is the guess for a primitive root modulo 71. Since $5 - 1 = 4 = 2^2$, and $7 - 1 = 6 = 2 \cdot 3$, this node has two successors (5, ((2, 2)), 2) and (7, ((2, 1), (3, 1)), 3), where 2 is the guess for a primitive root modulo 5, and 3 is the guess for a primitive root modulo 7.

Since $4 = 2^2$ is a power of 2, the node (5, ((2, 2)), 2) is a leaf node.

Since $3 - 1 = 2^1$, the node (7, ((2, 1), (3, 1)), 3) has a single successor, (3, ((2, 1)), 2), where a = 2 is a guess for a primitive root modulo 3. Since $2 = 2^1$ is a power of 2, the node (3, ((2, 1)), 2) is a leaf node.

To recap, we obtain the following tree:



We still have to check that the relevant congruences hold at every node. For the root node (1279, ((2, 1), (3, 2), (71, 1)), 3), we check that

$$3^{1278/2} \equiv 3^{864} \equiv -1 \pmod{1279}$$
 (1b)

$$3^{1278/(2\cdot3)} \equiv 3^{213} \equiv 775 \pmod{1279}$$
 (2b)

$$3^{1278/(2\cdot71)} \equiv 3^9 \equiv 498 \pmod{1279}.$$
 (2b)

Assuming that 3 and 71 are prime, the above congruences check that Conditions (1a) and (2b) are satisfied, and by Theorem 15.10 this proves that 1279 is prime. We still have to certify that 3 and 71 are prime, and we do this recursively.

For the leaf node (3, ((2, 1)), 2), we check that

$$2^{2/2} \equiv -1 \pmod{3}.$$
 (1b)

For the node (71, ((2, 1), (5, 1), (7, 1)), 7), we check that

$$7^{70/2} \equiv 7^{35} \equiv -1 \pmod{71}$$
 (1b)

$$7^{70/(2 \cdot 5)} \equiv 7^7 \equiv 14 \pmod{71}$$
 (2b)

$$7^{70/(2\cdot7)} \equiv 7^5 \equiv 51 \pmod{71}.$$
 (2b)

Now we certified that 3 and 71 are prime, assuming that 5 and 7 are prime, which we now establish.

For the leaf node (5, ((2, 2)), 2), we check that

$$2^{4/2} \equiv 2^2 \equiv -1 \pmod{5}.$$
 (1b)

For the node (7, ((2, 1), (3, 1)), 3), we check that

$$3^{6/2} \equiv 3^3 \equiv -1 \pmod{7}$$
 (1b)

$$3^{6/(2\cdot3)} \equiv 3^1 \equiv 3 \pmod{7}.$$
 (2b)

We have certified that 5 and 7 are prime, given that 3 is prime, which we finally verify.

At last, for the leaf node (3, ((2, 1)), 2), we check that

$$2^{2/2} \equiv -1 \pmod{3}.$$
 (1b)

The above example suggests the following definition.

Definition 15.12. Given any odd integer $n \ge 3$, a *pre-Lucas tree for* n is defined inductively as follows:

- (1) It is a one-node tree labeled with $(n, ((2, i_0)), a)$, such that $n 1 = 2^{i_0}$, for some $i_0 \ge 1$ and some $a \in \{2, \ldots, n-1\}$.
- (2) If L_1, \ldots, L_k are k pre-Lucas (with $k \ge 1$), where the tree L_j is a pre-Lucas tree for some odd integer $q_j \ge 3$, then the tree L whose root is labeled with $(n, ((2, i_0), ((q_1, i_1), \ldots, (q_k, i_k)), a))$ and whose jth subtree is L_j is a pre-Lucas tree for n if

$$n-1 = 2^{i_0} q_1^{i_1} \cdots q_k^{i_k},$$

for some $i_0, i_1, \dots, i_k \ge 1$, and some $a \in \{2, \dots, n-1\}$.

Both in (1) and (2), the number a is a guess for a primitive root modulo n.

A pre-Lucas tree for n is a *Lucas tree for* n if the following conditions are satisfied:

(3) If L is a one-node tree labeled with $(n, ((2, i_0)), a)$, then

$$a^{(n-1)/2} \equiv -1 \pmod{n}.$$

- (4) If L is a pre-Lucas tree whose root is labeled with $(n, ((2, i_0), ((q_1, i_1), \dots, (q_k, i_k)), a))$, and whose *j*th subtree L_j is a pre-Lucas tree for q_j , then L_j is a Lucas tree for q_j for $j = 1, \dots, k$, and
 - (a) $a^{(n-1)/2} \equiv -1 \pmod{n}$.
 - (b) $a^{(n-1)/2q_j} \not\equiv -1 \pmod{n}$ for $j = 1, \dots, k$.

Since Conditions (3) and (4) of Definition 15.12 are Conditions (1b) and (2b) of Theorem, 15.10, we see that Definition 15.12 has been designed in such a way that Theorem 15.10 yields the following result.

Theorem 15.11. An odd integer $n \ge 3$ is prime iff it has some Lucas tree.

The issue is now to see how long it takes to check that a pre-Lucas tree is a Lucas tree. For this, we need a method for computing $x^n \mod n$ in polynomial time in $\log_2 n$. This is the object of the next section.

Algorithms for Computing Powers Modulo m Let us first consider computing the nth power x^n of some positive integer. The idea is to look at the parity of n and to proceed recursively. If n is even, say n = 2k, then

$$x^n = x^{2k} = (x^k)^2,$$

so, compute x^k recursively and then square the result. If n is odd, say n = 2k + 1, then

$$x^{n} = x^{2k+1} = (x^{k})^{2} \cdot x,$$

so, compute x^k recursively, square it, and multiply the result by x.

What this suggests is to write $n \ge 1$ in binary, say

$$n = b_{\ell} \cdot 2^{\ell} + b_{\ell-1} \cdot 2^{\ell-1} + \dots + b_1 \cdot 2^1 + b_0,$$

where $b_i \in \{0, 1\}$ with $b_{\ell} = 1$ or, if we let $J = \{j \mid b_j = 1\}$, as

$$n = \sum_{j \in J} 2^j$$

Then we have

$$x^n \equiv x^{\sum_{j \in J} 2^j} = \prod_{j \in J} x^{2^j} \mod m$$

This suggests computing the residues r_j such that

$$x^{2^j} \equiv r_j \; (\text{mod } m),$$

because then,

$$x^n \equiv \prod_{j \in J} r_j \; (\text{mod } m),$$

where we can compute this latter product modulo m two terms at a time.

For example, let us compute $2^{90} \mod 91$ (recall that $91 = 7 \cdot 13$). We have

$$91 = 2^6 + 2^4 + 2^3 + 2^1,$$

and we compute the following powers modulo 91:

$$2^{2^{1}} \equiv 4 \pmod{91}$$

$$2^{2^{2}} \equiv 16 \pmod{91}$$

$$2^{2^{3}} \equiv 16^{2} \equiv 74 \pmod{91}$$

$$2^{2^{4}} \equiv 74^{2} \equiv 16 \pmod{91}$$

$$2^{2^{5}} \equiv 16^{2} \equiv 74 \pmod{91}$$

$$2^{2^{6}} \equiv 74^{2} \equiv 16 \pmod{91}.$$

Consequently,

$$2^{90} \equiv 4 \cdot 74 \cdot 16 \cdot 16 \pmod{91} \\ \equiv 23 \cdot 16 \cdot 16 \pmod{91} \\ \equiv 4 \cdot 16 = 64 \pmod{91},$$

 \mathbf{SO}

 $2^{90} \equiv 64 \pmod{91},$

confirming what we claimed in Section 15.2.

As a second example, let us compute $3^{90} \mod 91$. We have

 $91 = 2^6 + 2^4 + 2^3 + 2^1,$

and we compute the following powers modulo 91:

$$3^{2^{1}} \equiv 9 \pmod{91}$$

$$3^{2^{2}} \equiv 81 \pmod{91}$$

$$3^{2^{3}} \equiv 81^{2} \equiv 9 \pmod{91}$$

$$3^{2^{4}} \equiv 81 \pmod{91}$$

$$3^{2^{5}} \equiv 9 \pmod{91}$$

$$3^{2^{6}} \equiv 81 \pmod{91}.$$

Consequently,

$$3^{90} \equiv 9 \cdot 9 \cdot 81 \cdot 81 \pmod{91}$$
$$\equiv 81 \cdot 81 \cdot 81 \pmod{91}$$
$$\equiv 9 \cdot 81 \pmod{91}$$
$$\equiv 1 \pmod{91},$$

 \mathbf{SO}

 $3^{90} \equiv 1 \pmod{91},$

confirming what we claimed in Section 15.2.

As a third example, say we want to compute $999^{179} \mod 1763$. First, we observe that

$$179 = 2^7 + 2^5 + 2^4 + 2^1 + 1,$$

and we compute the following powers modulo 1763:

$$999^{2^{1}} \equiv 143 \pmod{1763}$$

$$999^{2^{2}} \equiv 143^{2} \equiv 1056 \pmod{1763}$$

$$999^{2^{3}} \equiv 1056^{2} \equiv 920 \pmod{1763}$$

$$999^{2^{4}} \equiv 920^{2} \equiv 160 \pmod{1763}$$

$$999^{2^{5}} \equiv 160^{2} \equiv 918 \pmod{1763}$$

$$999^{2^{6}} \equiv 918^{2} \equiv 10 \pmod{1763}$$

$$999^{2^{7}} \equiv 10^{2} \equiv 100 \pmod{1763}.$$

Consequently,

$$999^{179} \equiv 999 \cdot 143 \cdot 160 \cdot 918 \cdot 100 \pmod{1763}$$
$$\equiv 54 \cdot 160 \cdot 918 \cdot 100 \pmod{1763}$$
$$\equiv 1588 \cdot 918 \cdot 100 \pmod{1763}$$
$$\equiv 1546 \cdot 100 \pmod{1763}$$
$$\equiv 1219 \pmod{1763},$$

and we find that

$$999^{179} \equiv 1219 \pmod{1763}$$

Of course, it would be impossible to exponentiate 999^{179} first and then reduce modulo 1763. As we can see, the number of multiplications needed is bounded by $2\log_2 n$, which is quite good.

The above method can be implemented without actually converting n to base 2. If n is even, say n = 2k, then n/2 = k, and if n is odd, say n = 2k + 1, then (n - 1)/2 = k, so we have a way of dropping the unit digit in the binary expansion of n and shifting the remaining digits one place to the right without explicitly computing this binary expansion. Here is an algorithm for computing $x^n \mod m$, with $n \ge 1$, using the repeated squaring method.

An Algorithm to Compute $x^n \mod m$ Using Repeated Squaring

```
begin

u := 1; a := x;

while n > 1 do

if even(n) then e := 0 else e := 1;
```

 $\begin{array}{l} \mathbf{if} \ e=1 \ \mathbf{then} \ u:=a \cdot u \ \mathrm{mod} \ m; \\ a:=a^2 \ \mathrm{mod} \ m; \ n:=(n-e)/2 \\ \mathbf{endwhile}; \\ u:=a \cdot u \ \mathrm{mod} \ m \\ \mathbf{end} \end{array}$

The final value of u is the result. The reason why the algorithm is correct is that after j rounds through the while loop, $a = x^{2^j} \mod m$ and

$$u = \prod_{i \in J \mid i < j} x^{2^i} \mod m,$$

with this product interpreted as 1 when j = 0.

Observe that the while loop is only executed n-1 times to avoid squaring once more unnecessarily and the last multiplication $a \cdot u$ is performed outside of the while loop. Also, if we delete the reductions modulo m, the above algorithm is a fast method for computing the nth power of an integer x and the time speed-up of not performing the last squaring step is more significant. We leave the details of the proof that the above algorithm is correct as an exercise.

15.6 PRIMES is in \mathcal{NP}

Exponentiation modulo n can performed by repeated squaring, as explained in Section 15.5. In that section, we observed that computing $x^m \mod n$ requires at most $2\log_2 m$ modular multiplications. Using this fact, we obtain the following result adapted from Crandall and Pomerance [7].

Proposition 15.12. If p is any odd prime, then any pre-Lucas tree L for p has at most $\log_2 p$ nodes, and the number M(p) of modular multiplications required to check that the pre-Lucas tree L is a Lucas tree is less than $2\log_2^2 p$.

Proof. Let N(p) be the number of nodes in a pre-Lucas tree for p. We proceed by complete induction. If p = 3, then $p - 1 = 2^1$, any pre-Lucas tree has a single node, and $1 < \log_2 3$.

Suppose the results holds for any odd prime less than p. If $p - 1 = 2^{i_0}$, then any Lucas tree has a single node, and $1 < \log_2 3 < \log_2 p$. If p - 1 has the prime factorization

$$p - 1 = 2^{i_0} q_1^{i_1} \cdots q_k^{i_k},$$

then by the induction hypothesis, each pre-Lucas tree L_j for q_j has less than $\log_2 q_j$ nodes, so

$$N(p) = 1 + \sum_{j=1}^{k} N(q_j) < 1 + \sum_{j=1}^{k} \log_2 q_j = 1 + \log_2(q_1 \cdots q_k) \le 1 + \log_2\left(\frac{p-1}{2}\right) < \log_2 p,$$

15.6. PRIMES IS IN \mathcal{NP}

establishing the induction hypothesis.

If r is one of the odd primes in the pre-Lucas tree for p, and r < p, then there is some other odd prime q in this pre-Lucas tree such that r divides q-1 and $q \leq p$. We also have to show that at some point, $a^{(q-1)/2r} \not\equiv -1 \pmod{q}$ for some a, and at another point, that $b^{(r-1)/2} \equiv -1 \pmod{r}$ for some b. Using the fact that the number of modular multiplications required to exponentiate to the power m is at most $2\log_2 m$, we see that the number of multiplications required by the above two exponentiations does not exceed

$$2\log_2\left(\frac{q-1}{2r}\right) + 2\log_2\left(\frac{r-1}{2}\right) = 2\log_2\left(\frac{(q-1)(r-1)}{4r}\right) < 2\log_2 q - 4 < 2\log_2 p$$

As a consequence, we have

$$M(p) < 2\log_2\left(\frac{p-1}{2}\right) + (N(p)-1)2\log_2 p < 2\log_2 p + (\log_2 p - 1)2\log_2 p = 2\log_2^2 p,$$

claimed.

as claimed.

The following impressive example is from Pratt [59].

Example 15.2. Let n = 474397531. It is easy to check that n - 1 = 474397531 - 1 = $474\,397\,530 = 2 \cdot 3 \cdot 5 \cdot 251^3$. We claim that the following is a Lucas tree for $n = 474\,397\,531$:

$$(3, ((2,1)), 2) (5, ((2,2)), 2) (251, ((2,1), (5,3)), 6))$$

To verify that the above pre-Lucas tree is a Lucas tree, we check that 2 is indeed a primitive root modulo 474 397 531 by computing (using Mathematica) that

$$2^{474\,397\,530/2} \equiv 2^{237\,198\,765} \equiv -1 \pmod{474\,397\,531} \tag{1}$$

$$2^{474\,397\,530/(2\cdot3)} \equiv 2^{79\,066\,255} \equiv 9\,583\,569 \pmod{474\,397\,531} \tag{2}$$

$$2^{474\,397\,530/(2\cdot5)} \equiv 2^{47\,439\,753} \equiv 91\,151\,207 \pmod{474\,397\,531} \tag{3}$$

$$2^{474\,397\,530/(2\cdot251)} \equiv 2^{945\,015} \equiv 282\,211\,150 \pmod{474\,397\,531}.\tag{4}$$

The number of modular multiplications is: 27 in (1), 26 in (2), 25 in (3) and 19 in (4).

We have $251 - 1 = 250 = 2 \cdot 5^3$, and we verify that 6 is a primitive root modulo 251 by computing:

$$6^{250/2} \equiv 6^{125} \equiv -1 \pmod{251} \tag{5}$$

$$6^{250/(2\cdot5)} \equiv 6^{10} \equiv 175 \pmod{251}.$$
(6)

The number of modular multiplications is: 6 in (5), and 3 in (6).

We have $5 - 1 = 4 = 2^2$, and 2 is a primitive root modulo 5, since

$$2^{4/2} \equiv 2^2 \equiv -1 \pmod{5}.$$
 (7)

This takes one multiplication.

We have $3 - 1 = 2 = 2^1$, and 2 is a primitive root modulo 3, since

$$2^{2/2} \equiv 2^1 \equiv -1 \pmod{3}.$$
 (8)

This takes 0 multiplications.

Therefore, $474\,397\,531$ is prime.

As nice as it is, Proposition 15.12 is deceiving, because *finding* a Lucas tree is hard.

Remark: Pratt [59] presents his method for finding a certificate of primality in terms of a proof system. Although quite elegant, we feel that this method is not as transparent as the method using Lucas trees, which we adapted from Crandall and Pomerance [7]. Pratt's proofs can be represented as trees, as Pratt sketches in Section 3 of his paper. However, Pratt uses the basic version of Lucas' theorem, Theorem 15.9, instead of the improved version, Theorem 15.10, so his proof trees have at least twice as many nodes as ours.

As nice as it is, Proposition 15.12 is deceiving, because *finding* a Lucas tree is hard.

The following nice result was first shown by V. Pratt in 1975 [59].

Theorem 15.13. The problem PRIMES (testing whether an integer is prime) is in \mathcal{NP} .

Proof. Since all even integers besides 2 are composite, we can restrict out attention to odd integers $n \geq 3$. By Theorem 15.11, an odd integer $n \geq 3$ is prime iff it has a Lucas tree. Given any odd integer $n \geq 3$, since all the numbers involved in the definition of a pre-Lucas tree are less than n, there is a finite (very large) number of pre-Lucas trees for n. Given a guess of a Lucas tree for n, checking that this tree is a pre-Lucas tree can be performed in $O(\log_2 n)$, and by Proposition 15.12, checking that it is a Lucas tree can be done in $O(\log_2^2 n)$. Therefore PRIMES is in \mathcal{NP} .

Of course, checking whether a number n is composite is in \mathcal{NP} , since it suffices to guess to factors n_1, n_2 and to check that $n = n_1 n_2$, which can be done in polynomial time in $\log_2 n$. Therefore, PRIMES $\in \mathcal{NP} \cap \operatorname{co}\mathcal{NP}$. As we said earlier, this was the situation until the discovery of the AKS algorithm, which places PRIMES in \mathcal{P} .

Remark: Altough finding a primitive root modulo p is hard, we know that the number of primitive roots modulo p is $\varphi(\varphi(p))$. If p is large enough, this number is actually quite large. According to Crandal and Pomerance [7] (Chapter 4, Section 4.1.1), if p is a prime and if p > 200560490131, then p has more than $p/(2 \ln \ln p)$ primitive roots.

Chapter 16

Polynomial- Space Complexity; \mathcal{PS} and \mathcal{NPS}

16.1 The Classes \mathcal{PS} (or PSPACE) and \mathcal{NPS} (NPSPACE)

In this chapter we consider complexity classes based on restricting the amount of *space* used by the Turing machine rather than the amount of time.

Definition 16.1. A deterministic or nondeterminitic Turing machine M is polynomial-space bounded if there is a polynomial p(X) such that for every input $x \in \Sigma^*$, no matter how much time it uses, the machine M never visits more than p(|x|) tape cells (symbols). Equivalently, for every ID upav arising during the computation, we have $|uav| \leq p(|x|)$.

The class of languages $L \subseteq \Sigma^*$ accepted by some *deterministic* polynomial-space bounded Turing machine is denoted by \mathcal{PS} or PSPACE. Similarly, the class of languages $L \subseteq \Sigma^*$ accepted by some *nondeterministic* polynomial-space bounded Turing machine is denoted by \mathcal{NPS} or NPSPACE.

Obviously $\mathcal{PS} \subseteq \mathcal{NPS}$. Since a (time) polynomially bounded Turing machine can't visit more tape cells (symbols) than one plus the number of moves it makes, we have

$$\mathcal{P} \subseteq \mathcal{PS}$$
 and $\mathcal{NP} \subseteq \mathcal{NPS}$.

Nobody knows whether these inclusions are strict, but these are the most likely assumptions. Unlike the situation for time-bounded Turing machines where the big open problem is whether $\mathcal{P} \neq \mathcal{NP}$, for *time-bounded* Turing machines, we have

$$\mathcal{PS} = \mathcal{NPS}$$

Walter Savitch proved this result in 1970 (and it is known as *Savitch's theorem*).

Now Definition 16.1 does not say anything about the time-complexity of the Turing machine, so such a machine could even run forever. However, the number of ID's that a polynomial-space bounded Turing machine can visit started on input x is a function of |x| of the form $sp(|x|)t^{p(|x|)}$ for some constants s > 0 and t > 0, so by the pigeonhole principle, it the number of moves is larger than a certain constant $(c^{1+p(|x|)})$ with c = s+t, then some ID must repeat. This fact can be used to show that there is a shorter computation accepting x of length at most $c^{1+p(|x|)}$.

Proposition 16.1. For any deterministic or nondeterministic polynomial-space bound Turing machine M with polynomial space bound p(X), there is a constant c > 1 such that for every input $x \in \Sigma^*$, if M accepts x, then M accepts x in at most $c^{1+p(|x|)}$ steps.

Proof. Suppose there are t symbols in the tape alphabet and s states. Then the number of distinct ID's when only p(|x|) tape cells are used is at most $sp(|x|)t^{p(|x|)}$, because we can choose one of s states, place the reading head in any of p(|x|) distinct positions, and there are $t^{p(|x|)}$ strings of tape symbols of length p(|x|). If we let c = s + t, by the binomial formula we have

$$c^{1+p(|x|)} = (s+t)^{1+p(|x|)} = \sum_{k=0}^{1+p(|x|)} {\binom{1+p(|x|)}{k}} s^k t^{1+p(|x|)-k}$$
$$= t^{1+p(|x|)} + (1+p(|x|))st^{p(|x|)} + \cdots$$

Obviously $(1 + p(|x|))st^{p(|x|)} > sp(|x|)t^{p(|x|)}$, so if the number of ID's in the computation is greater than $c^{1+p(|x|)}$, by the pigeonhole principle, two ID's must be identical. By considering a shortest accepting sequence of ID's with n steps, we deduce that $n \leq c^{1+p(|x|)}$, since otherwise the preceding argument shows that the computation would be of the form

$$ID_0 \vdash^* \cdots \vdash^* ID_h \vdash^+ ID_k \vdash^* ID_n$$

with $ID_h = ID_k$, so we would have an even shorter computation

$$ID_0 \vdash^* \cdots \vdash^* ID_h \vdash^* ID_n,$$

contradicting the minimality of the original computation.

Proposition 16.1 implies that languages in \mathcal{NPS} are computable (in fact, primitive recursive, and even in \mathcal{EXP}). This still does not show that languages in \mathcal{NPS} are accepted by polynomial-space Turing machines that *always halt* within some time $c^{q(|x|)}$ for some polynomial q(X). Such a result can be shown using a simulation involving a Turing machine with two tapes.

Proposition 16.2. For any language $L \in \mathcal{PS}$ (resp. $L \in \mathcal{NPS}$), there is deterministic (resp. nondeterministic) polynomial-space bounded Turing machine M, a polynomial q(X) and a constant c > 1, such that for every input $x \in \Sigma^*$, M accepts x in at most $c^{q(|x|)}$ steps.

A proof of Proposition 16.2 can be found in Hopcroft, Motwani and Ullman [37] (Section 11.2.2, Theorem 11.4).

We now turn to Savitch's theorem.

 \square

16.2 Savitch's Theorem: $\mathcal{PS} = \mathcal{NPS}$

The key to the fact that $\mathcal{PS} = \mathcal{NPS}$ is that given a polynomial-space bounded nondeterministic Turing machine M, there is a recursive method to check whether $I \vdash^k J$ with $0 \leq k \leq m$ using at most $\log_2 m$ recursive calls, for any two ID's I and J and any natural number $m \geq 1$, (that is, whether there is some computation of $k \leq m$ steps from I to J).

The idea is reminiscent of binary search, namely, to recursively find some intermediate ID K such that $I \vdash^{m_1} K$ and $K \vdash^{m_2} J$ with $m_1 \leq m/2$ and $m_2 \leq m/2$ (here m/2 is the integer quotient obtained by dividing m by 2). Because the Turing machine M is polynomialspace bounded, for a given input x, we know from Proposition 16.1 that there are at most $c^{1+p(|x|)}$ distinct ID's, so the search is finite. We will initially set $m = c^{1+p(|x|)}$, so at most $\log_2 c^{1+p(|x|)} = O(p(|x|)$ recursive calls will be made. We will show that each stack frame takes O(p(|x|) space, so altogether the search uses $O(p(|x|)^2)$ amount of space. This is the crux of Savitch's argument.

The recursive procedure that deals with stack frames of the form [I, J, m] is shown below.

function reach(I, J, m): boolean

begin

```
if m = 1 then

if I = J = K or I \vdash^1 J then

reach = true

else

reach = false

endif

else

for each possible ID K do

if reach(I, K, m/2) and reach(K, J, m/2) then

reach = true

else

reach = false

endif

endif

endif
```

end

Even though the above procedure makes two recursive calls, they are performed sequentially, so the maximum number of stack frames that may arise corresponds to the sequence

 $[I_1, J_1, m], [I_2, J_2, m/2], [I_3, J_3, m/4], [I_4, J_4, m/8], \cdots, [I_k, J_k, m/2^{k-1}], \cdots$

which has length at most $\log_2 m$. Using the procedure *search*, we obtain Savitch's theorem.

Theorem 16.3. (Savitch, 1970) The complexity classes \mathcal{PS} and \mathcal{NPS} are identical. In fact, if L is accepted by the polynomial-space bounded nondeterministic Turing machine M with space bound p(X), then there is a polynomial-space bounded deterministic Turing machine D accepting L with space bound $O(p(X)^2)$.

Sketch of proof. Assume that L is accepted by the polynomial-space bounded nondeterministic Turing machine M with space bound p(X). By Proposition 16.1 we may assume that M accepts any input $x \in L$ in at most $c^{1+p(|x|)}$ steps (for some c > 1). Set $m = c^{1+p(|x|)}$.

We can design a deterministic Turing machine D which determines (using the function search) whether $I_0 \vdash^k J$ with $k \leq m$ where $I_0 = q_0 x$ is the starting ID, for all accepting ID's J, by enumerate all accepting ID's J using at most p(|x|) tape cells, using a scratch tape.

As we explained above, the function *search* makes no more than $\log_2 c^{1+p(|x|)} = O(p(|x|))$ recursive calls, Each stack frame takes O(p(|x|)) space. The reason is that every ID has at most 1 + p(|x|) tape cells and that if we write $m = c^{1+p(|x|)}$ in binary, this takes $\log_2 m = O(p(|x|))$ tape cells. Since at most O(p(|x|)) stack frames may arise and since each stack frame has size at most O(p(|x|)), the deterministic TM D uses at most $O(p(|x|)^2)$ space. For more details, see Hopcroft, Motwani and Ullman [37] (Section 11.2.3, Theorem 11.5).

Savitch's theorem and Proposition 16.1 show that $\mathcal{PS} = \mathcal{NPS} \subseteq \mathcal{EXP}$. Whether this inclusion is strict is an open problem. The present status of the relative containments of the complexity classes that we have discussed so far is illustrated in Figure 16.1

Savitch's theorem shows that nondeterminism does not help as far as polynomial *space* is concerned, but we still don't have a good example of a language in $\mathcal{PS} = \mathcal{NPS}$ which is not known to be in \mathcal{NP} . The next section is devoted to such a problem. This problem also turns out to be \mathcal{PS} -complete, so we discuss this notion as well.

16.3 A Complete Problem for \mathcal{PS} : QBF

Logic is a natural source of problems complete with respect to a number of complexity classes: SAT is \mathcal{NP} -complete (see Theorem 13.8), TAUT is $co\mathcal{NP}$ -complete (see Proposition 14.3). It turns out that the validity problem for quantified boolean formulae is \mathcal{PS} -complete. We will describe this problem shortly, but first we define \mathcal{PS} -completeness.

Definition 16.2. A language $L \subseteq \Sigma^*$ is \mathcal{PS} -complete if:

- (1) $L \in \mathcal{PS}$.
- (2) For every language $L_2 \in \mathcal{PS}$, there is a *polynomial-time computable* function $f: \Sigma^* \to \Sigma^*$ such that $x \in L_2$ iff $f(x) \in L$, for all $x \in \Sigma^*$.

Observe that we require the reduction function f to be *polynomial-time computable* rather than *polynomial-space computable*. The reason for this is that with this stronger form of reduction we can prove the following proposition whose simple proof is left as an exercise.



Figure 16.1: Relative containments of the complexity classes.

Proposition 16.4. Suppose L is a \mathcal{PS} -complete language. Then the following facts hold:

- (1) If $L \in \mathcal{P}$, then $\mathcal{P} = \mathcal{PS}$.
- (2) If $L \in \mathcal{NP}$, then $\mathcal{NP} = \mathcal{PS}$.

The premises in Proposition 16.4 are very unlikely, but we never know!

We now define the class of quantified boolean formulae. These are actually second-order formulae because we are allowed to quantify over propositional variables, which are 0-ary (constant) predicate symbols. As we will see, validity is still decidable, but the fact that we allow alternation of the quantifiers \forall and \exists makes the problem harder, in the sense that testing validity or nonvalidity no longer appears to be doable in \mathcal{NP} (so far, nobody knows how to do this!).

Recall from Section 13.5 that we have a countable set **PV** of *propositional (or boolean)*

variables,

$$\mathbf{PV} = \{x_1, x_2, \dots, \}.$$

Definition 16.3. A quantified boolean formula (for short QBF) is an expression A defined inductively as follows:

- (1) The constants \top and \perp and every propositional variable x_i are QBF's called *atomic* QBF's.
- (2) If B is a QBF, then $\neg B$ is a QBF.
- (3) If B and C are QBF's, then $(B \lor C)$ is a QBF.
- (4) If B and C are QBF's, then $(B \wedge C)$ is a QBF.
- (5) If B is a QBF and if x is a propositional variable, then $\forall xB$ is a QBF. The variable x is said to be *universally bound by* \forall .
- (6) If B is a QBF and if x is a propositional variable, then $\exists xB$ is a QBF. The variable x is said to be *existentially bound by* \exists .
- (7) If allow the connective \Rightarrow , and if B and C are QBF's, then $(B \Rightarrow C)$ is a QBF.

Example 16.1. The following formula is a QBF:

$$A = \forall x \big(\exists y (x \land y) \lor \forall z (\neg x \lor z) \big).$$

As usual, we can define inductively the notion of free and bound variable as follows.

Definition 16.4. Given any QBF A, we define the set FV(A) of variables free in A and the set BV(A) of variables bound in A as follows:

$$FV(\bot) = FV(\top) = \emptyset$$

$$FV(x_i) = \{x_i\}$$

$$FV(\neg B) = FV(B)$$

$$FV((B * C)) = FV(B) \cup FV(C), \quad * \in \{\lor, \land, \Rightarrow\}$$

$$FV(\forall xB) = FV(B) - \{x\}$$

$$FV(\exists xB) = FV(B) - \{x\},$$

and

$$BV(\bot) = BV(\top) = \emptyset$$

$$BV(x_i) = \emptyset$$

$$BV(\neg B) = BV(B)$$

$$BV((B * C)) = BV(B) \cup BV(C), \quad * \in \{\lor, \land, \Rightarrow\}$$

$$BV(\forall xB) = BV(B) \cup \{x\}$$

$$BV(\exists xB) = BV(B) \cup \{x\}.$$

A QBF A such that $FV(A) = \emptyset$ (A has no free variables) is said to be *closed* or a *sentence*.

It should be noted that FV(A) and BV(A) may not be disjoint! For example, if

$$A = x_1 \lor \forall x_1 (\neg x_1 \lor x_2),$$

then $FV(A) = \{x_1, x_2\}$ and $BV(A) = \{x_1\}$. This situation is somewhat undesirable. Intuitively, A is "equivalent" to the QBF

$$A' = x_1 \lor \forall x_3 (\neg x_3 \lor x_2),$$

with $FV(A') = \{x_1, x_2\}$ and $BV(A') = \{x_3\}$. Here equivalent means that A and A' have the same truth value for all truth assignments. To make all this precise we proceed as follows.

Definition 16.5. A substitution is a set of pairs $\varphi = \{(y_1, A_1), \dots, (y_m, A_m)\}$ where the variables y_1, \dots, y_m are distinct and A_1, \dots, A_m are arbitrary QBF's. We write $\varphi = [y_1 := A_1, \dots, y_m := A_m]$. For any QBF B, we also denote by $\varphi[y_i := B]$ the substitution such that $y_i := A_i$ is replaced by $y_i := B$. In particular, $\varphi[y_i := y_i]$ leaves y_i unchanged.

Given a QBF A, the result of applying the substitution $\varphi = [y_1 := A_1, \ldots, y_m := A_m]$ to A, denoted $A[\varphi]$, is defined inductively as follows:

$$\begin{split} \bot [\varphi] = \bot \\ \top [\varphi] = \top \\ x[\varphi] = A_i \quad \text{if } x = y_i, \ 1 \le i \le m \\ x[\varphi] = x \quad \text{if } x \notin \{y_1, \dots, y_m\} \\ (\neg B)[\varphi] = (\neg B)[\varphi] \\ (B * C)[\varphi] = (B[\varphi] * C[\varphi]), \qquad * \in \{\lor, \land, \Rightarrow\} \\ (\forall xB)[\varphi] = \forall xB[\varphi[y_i := y_i]] \quad \text{if } x = y_i, \ 1 \le i \le m \\ (\forall xB)[\varphi] = \forall xB[\varphi] \quad \text{if } x \notin \{y_1, \dots, y_m\} \\ (\exists xB)[\varphi] = \exists xB[\varphi[y_i := y_i]] \quad \text{if } x = y_i, \ 1 \le i \le m \\ (\exists xB)[\varphi] = \exists xB[\varphi] \quad \text{if } x \notin \{y_1, \dots, y_m\}. \end{split}$$

Definition 16.6. A QBF A is *rectified* if distinct quantifiers bind distinct variables and if $BV(A) \cap FV(A) = \emptyset$.

Given a QBF A and any finite set V of variables, we can define recursively a new rectified QBF A' such that $BV(A') \cap V = \emptyset$.

- (1) If $A = \top$, or $A = \bot$, or $A = x_i$, then A' = A.
- (2) If $A = \neg B$, then A' = A.
- (3) If $A = (B \lor C)$, then first we find recursively some rectified QBF B_1 such that $BV(B_1) \cap V = \emptyset$, then we find recursively some rectified QBF C_1 such that $BV(C_1) \cap (FV(B_1) \cup BV(B_1) \cup V) = \emptyset$, and we set $A' = (B_1 \lor C_1)$. We proceed similarly if $A = (B \land C)$ or $A = (B \Rightarrow C)$, with \lor replaced by \land or \Rightarrow .

- (4) If $A = \forall xB$, first we find recursively some rectified QBF B_1 such that $BV(B_1) \cap V = \emptyset$, and then we let $A' = \forall zB_1[x := z]$ for some new variable z such that $z \notin FV(B_1) \cup BV(B_1) \cup V$. Note that in this step it is possible that $x \notin FV(B)$.
- (5) If $A = \exists xB$, first we find recursively some rectified QBF B_1 such that $BV(B_1) \cap V = \emptyset$, and then we let $A' = \exists zB_1[x := z]$ for some new variable z such that $z \notin FV(B_1) \cup BV(B_1) \cup V$. Note that in this step it is possible that $x \notin FV(B)$.

Given any QBF A, we find a rectified QBF A' by applying the above procedure recursively starting with A and $V = \emptyset$.

Recall that a *truth assignment* or *valuation* is a function $v \colon \mathbf{PV} \to {\mathbf{T}, \mathbf{F}}$. We also let $\overline{\mathbf{T}} = \mathbf{F}$ and $\overline{\mathbf{T}} = \mathbf{T}$.

Definition 16.7. Given a valuation $v \colon \mathbf{PV} \to {\mathbf{T}, \mathbf{F}}$, we define *truth value* A[v] of a QBF A inductively as follows.

$$\perp [v] = \mathbf{F} \tag{1}$$

$$\top[v] = \mathbf{T} \tag{2}$$

$$x[v] = v(x) \tag{3}$$

$$(\neg B)[v] = B[v] = \mathbf{F} \text{ if } B[v] = \mathbf{T} \text{ else } \mathbf{T} \text{ if } B[v] = \mathbf{F}$$
(4)

$$(B \lor C)[v] = B[v] \text{ or } C[v]$$
(5)

$$(B \wedge C)[v] = B[v] \text{ and } C[v]$$
(6)

$$(B \Rightarrow C)[v] = \overline{B[v]} \text{ or } C[v]$$
(7)

$$(\forall x B)[v] = B[v[x := \mathbf{T}]] \text{ and } B[v[x := \mathbf{F}]]$$
(8)

$$(\exists x B)[v] = B[v[x := \mathbf{T}]] \text{ or } B[v[x := \mathbf{F}]].$$
(9)

If $A[v] = \mathbf{T}$, we write say that v satisfies A and we write $v \models A$. If $A[v] = \mathbf{T}$ for all valuations v, we say that A is valid and we write $\models A$.

As usual, we write $A \equiv B$ iff $(A \Rightarrow B) \land (B \Rightarrow A)$ is valid.

In Clause (5) when evaluating $(B \vee C)[v]$, if $B[v] = \mathbf{T}$, then we don't need to evaluate C[v], since $\mathbf{Tor} b = \mathbf{T}$ independently of $b \in {\mathbf{T}, \mathbf{F}}$, and so $(B \vee C)[v] = \mathbf{T}$. If $B[v] = \mathbf{F}$, then we need to evaluate C[v], and $(B \vee C)[v] = \mathbf{T}$ iff $C[v] = \mathbf{T}$. Even though the above method is more economical, we usually evaluate both B[v] and C[v] and then compute B[v] or C[v].

A similar discussion applies to evaluating $(\exists xB)[v]$ in Clause (9). If $B[v[x := \mathbf{T}]] = \mathbf{T}$, then we don't need to evaluate $B[v[x := \mathbf{F}]]$ and $(\exists xB)[v] = \mathbf{T}$. If $B[v[x := \mathbf{T}]] = \mathbf{F}$, then we need to evaluate $B[v[x := \mathbf{F}]]$, and $(\exists xB)[v] = \mathbf{T}$ iff $B[v[x := \mathbf{F}]] = \mathbf{T}$. Even though the above method is more economical, we usually evaluate both $B[v[x := \mathbf{T}]]$ and $B[v[x := \mathbf{F}]]$ and then compute $B[v[x := \mathbf{T}]]$ or $B[v[x := \mathbf{F}]]$. **Example 16.2.** Let us show that the QBF

$$A = \forall x \big(\exists y (x \land y) \lor \forall z (\neg x \lor z) \big)$$

from Example 16.1 is valid. This is a closed formula so v is irrelevant. By Clause (8) of Definition 16.7, we need to evaluate $A[x := \mathbf{T}]$ and $A[x := \mathbf{F}]$.

To evaluate $A[x := \mathbf{T}]$, by Clause (5) of Definition 16.7, we need to evaluate $(\exists y(x \land y))[x := \mathbf{T}]$ and $(\forall z(\neg x \lor z))[x := \mathbf{T}]$.

To evaluate $(\exists y(x \land y))[x := \mathbf{T}]$, by Clause (9) of Definition 16.7, we need to evaluate $(x \land y)[x := \mathbf{T}, y := \mathbf{T}]$ and $(x \land y)[x := \mathbf{T}, y := \mathbf{F}]$.

We have (by Clause (6)) $(x \wedge y)[x := \mathbf{T}, y := \mathbf{T}] = \mathbf{T}$ and $\mathbf{T} = \mathbf{T}$ and $(x \wedge y)[x := \mathbf{T}, y := \mathbf{F}] = \mathbf{T}$ and $\mathbf{F} = \mathbf{F}$, so

$$(\exists y(x \land y))[x := \mathbf{T}] = (x \land y)[x := \mathbf{T}, y := \mathbf{T}] \text{ or } (x \land y)[x := \mathbf{T}, y := \mathbf{F}] = \mathbf{T} \text{ or } \mathbf{F} = \mathbf{T}.$$
(1)

To evaluate $(\forall z(\neg x \lor z))[x := \mathbf{T}]$, by Clause (8) of Definition 16.7, we need to evaluate $(\neg x \lor z)[x := \mathbf{T}, z := \mathbf{T}]$ and $(\neg x \lor z)[x := \mathbf{T}, z := \mathbf{F}]$.

Using Clauses (4) and (5) of Definition 16.7, we have $(\neg x \lor z)[x := \mathbf{T}, z := \mathbf{T}] = \overline{\mathbf{T}}$ land $\mathbf{T} = \mathbf{T}$ and $(\neg x \lor z)[x := \mathbf{T}, z := \mathbf{F}] = \overline{\mathbf{T}}$ land $\mathbf{F} = \mathbf{F}$, so

$$(\forall z(\neg x \lor z))[x := \mathbf{T}] = (\neg x \lor z)[x := \mathbf{T}, z := \mathbf{T}] \text{ and } (\neg x \lor z)[x := \mathbf{T}, z := \mathbf{F}] = \mathbf{F}.$$
 (2)

By (1) and (2) we have

$$A[x := \mathbf{T}] = (\exists y(x \land y))[x := \mathbf{T}] \text{ or } (\forall z(\neg x \lor z))[x := \mathbf{T}] = \mathbf{T} \text{ or } \mathbf{F} = \mathbf{T}.$$
 (3)

Now we need to evaluate $A[x := \mathbf{F}]$. By Clause (5) of Definition 16.7, we need to evaluate $(\exists y(x \land y))[x := \mathbf{F}]$ and $(\forall z(\neg x \lor z))[x := \mathbf{F}]$.

To evaluate $(\exists y(x \land y))[x := \mathbf{F}]$, by Clause (9) of Definition 16.7, we need to evaluate $(x \land y)[x := \mathbf{F}, y := \mathbf{T}]$ and $(x \land y)[x := \mathbf{F}, y := \mathbf{F}]$.

We have (by Clause (6)) $(x \wedge y)[x := \mathbf{F}, y := \mathbf{T}] = \mathbf{F}$ and $\mathbf{T} = \mathbf{F}$ and $(x \wedge y)[x := \mathbf{F}, y := \mathbf{F}] = \mathbf{F}$ and $\mathbf{F} = \mathbf{F}$, so

$$(\exists y(x \land y))[x := \mathbf{F}] = (x \land y)[x := \mathbf{F}, y := \mathbf{T}] \text{ or } (x \land y)[x := \mathbf{F}, y := \mathbf{F}] = \mathbf{F} \text{ or } \mathbf{F} = \mathbf{F}.$$
(4)

To evaluate $(\forall z(\neg x \lor z))[x := \mathbf{F}]$, by Clause (8) of Definition 16.7, we need to evaluate $(\neg x \lor z)[x := \mathbf{F}, z := \mathbf{T}]$ and $(\neg x \lor z)[x := \mathbf{F}, z := \mathbf{F}]$.

Using Clauses (4) and (5) of Definition 16.7, we have $(\neg x \lor z)[x := \mathbf{F}, z := \mathbf{T}] = \overline{\mathbf{F}} \text{ or } \mathbf{T} = \mathbf{T}$ and $(\neg x \lor z)[x := \mathbf{F}, z := \mathbf{F}] = \overline{\mathbf{F}} \text{ or } \mathbf{F} = \mathbf{T}$, so

$$(\forall z(\neg x \lor z))[x := \mathbf{F}] = (\neg x \lor z)[x := \mathbf{F}, z := \mathbf{T}] \text{ and } (\neg x \lor z)[x := \mathbf{F}, z := \mathbf{F}] = \mathbf{T}$$
(5)

By (4) and (5) we have

$$A[x := \mathbf{F}] = (\exists y(x \land y))[x := \mathbf{F}] \text{ or } (\forall z(\neg x \lor z))[x := \mathbf{F}] = \mathbf{F} \text{ or } \mathbf{T} = \mathbf{T}.$$
 (6)

Finally, by (3) and (6) we get

$$A[x := \mathbf{T}] \text{ and } A[x := \mathbf{F}] = \mathbf{T} \text{ and } \mathbf{T} = \mathbf{T},$$
(7)

so A is valid.

The reader should observe that in evaluating

$$(\exists xB)[v] = B[v[x := \mathbf{T}]] \text{ or } B[v[x := \mathbf{F}]],$$

if $(\exists xB)[v] = \mathbf{T}$, it is only necessary to guess which of $B[v[x := \mathbf{T}]]$ or $B[v[x := \mathbf{F}]]$ evaluates to \mathbf{T} , so we can view the computation of A[v] as an AND/OR tree, where an AND node corresponds to the evaluation of a formula $(\forall xB)[v]$, and an OR node corresponds to the evaluation of a formula $(\exists xB)[v]$.

Evaluating the truth value A[v] of a QBF A can take exponential time in the size n of A, but we will see that it only requires $O(n^2)$ space. Also, the validity of QBF's of the form

$$\exists x_1 \exists x_2 \cdots \exists x_m B$$

where B is quantifier-free and $FV(B) = \{x_1, \ldots, x_m\}$ is equivalent to SAT (the satisfiability problem), and the validity of QBF's of the form

$$\forall x_1 \forall x_2 \cdots \forall x_m B$$

where B is quantifier-free and $FV(B) = \{x_1, \ldots, x_m\}$ is equivalent to TAUT (the validity problem). This is why the validity problem for QBF's is as hard as both SAT and TAUT.

We mention the following technical results. Part (1) and Part (2) are used all the time.

Proposition 16.5. Let A be any QBF.

- (1) For any two valuations v_1 and v_2 , if $v_1(x) = v_2(x)$ for all $x \in FV(A)$, then $A[v_1] = A[v_2]$. In particular, if A is a sentence, then A[v] is independent of v.
- (2) If A' is any rectified QBF obtained from A, then A[v] = A'[v] for all valuations v; that is, $A \equiv A'$.
- (3) For any QBF A of the form $A = \forall xB$ and any QBF C such that $BV(B) \cap FV(C) = \emptyset$, if A is valid, then B[x := C] is also valid.
- (4) For any QBF B and any QBF C such that $BV(B) \cap FV(C) = \emptyset$, if B[x := C] is valid, then $\exists xB$ is also valid.

We also repeat Proposition 7.2 which states that the connectives \land, \lor, \neg and \exists are definable in terms of \Rightarrow and \forall . This shows the power of the second-order quantifier \forall .

Proposition 16.6. The connectives \land, \lor, \neg, \bot and \exists are definable in terms of \Rightarrow and \forall , which means that the following equivalences are valid, where x is not free in B or C:

$$B \wedge C \equiv \forall x \big((B \Rightarrow (C \Rightarrow x)) \Rightarrow x \big)$$
$$B \vee C \equiv \forall x \big((B \Rightarrow x) \Rightarrow ((C \Rightarrow x) \Rightarrow x) \big)$$
$$\perp \equiv \forall xx$$
$$\neg B \equiv B \Rightarrow \forall xx$$
$$\exists y B \equiv \forall x \big((\forall y (B \Rightarrow x)) \Rightarrow x \big).$$

We now prove the first step in establishing that the validity problem for QBF's is \mathcal{PS} complete.

Proposition 16.7. Let A be any QBF of length n. Then for any valuation v, the truth value A[v] can be evaluated in $O(n^2)$ space. Thus the validity problem for closed QBF's is in \mathcal{PS} .

Proof. The clauses of Definition 16.7 show that A[v] is evaluated recursively. In clauses (5)-(9), even though two recursive calls are performed, it is only necessary to save one of the two stack frames at a time. It follows that the stack will never contain more than n stack frames, and each stack frame has size at most n. Thus only $O(n^2)$ space is needed. For more details, see Hopcroft, Motwani and Ullman [37] (Section 11.3.4, Theorem 11.10).

Finally we state the main theorem proven by Meyer and Stockmeyer (1973).

Theorem 16.8. The validity problem for closed QBF's is \mathcal{PS} -complete.

We will not prove Theorem 16.8, mostly because it requires simulating the computation of a polynomial-space bounded deterministic Turing machine, and this is very technical and tedious. Most details of such a proof can be found in Hopcroft, Motwani and Ullman [37] (Section 11.3.4, Theorem 11.11).

Let us simply make the following comment which gives a clue as to why QBF's are helpful in describing the simulation (for details, see Hopcroft, Motwani and Ullman [37] (Theorem 11.11)). It turns out that the idea behind the function *reach* presented in Section 16.2 plays a key role. It is necessary to express for any two ID's I and J and any $i \ge 1$, that $I \vdash^k J$ with $k \le i$. This is achieved by defining $N_{2i}(I, J)$ as the following QBF:

$$N_{2i}(I,J) = \exists K \forall R \forall S \Big(\big((R = I \land S = K) \lor (R = K \land S = J) \big) \Rightarrow N_i(R,S) \Big).$$

Another interesting \mathcal{PS} -complete problem due to Karp (1972) is the following. Given any alphabet Σ , decide whether a regular expression R denotes Σ^* ; that is, $\mathcal{L}[R] = \Sigma^*$.

We conclude with some comments regarding some remarkable results of Statman regarding the connection between validity of closed QBF's and provability in intuitionistic propositional logic.

16.4 Complexity of Provability in Intuitionistic Propositional Logic

Recall that intuitionistic logic is obtained from classical logic by taking away the proof-bycontradiction rule. The reader is strongly advised to review Chapter 2, especially Sections 2.2, 2.3, 2.4, 2.6 and 2.8, before proceeding.

Statman [68] shows how to reduce the validity problem for QBFs to provability in intuitionistic propositional logic. To simplify the construction we may assume that we consider QBF's in *prenex form*, which means that they are of the form

$$A = Q_n x_n Q_{n-1} x_{n-1} \cdots Q_1 x_1 B_0$$

where B_0 is quantifier-free and $Q_i \in \{\forall, \exists\}$ for i = 1, ..., n. We also assume that A is rectified. It is easy to show that any QBF A is equivalent to some QBF A' in prenex form by adapting the method for converting a first-order formula to prenex form; see Gallier [24] or Shoenfield [67].

Statman's clever trick is to exploit some properties of intuitionistic provability that do not hold for classical logic. One of these properties is that if a proposition $B \vee C$ is provable intuitionistically, we write $\vdash_I B \vee C$, then either $\vdash_I B$ or $\vdash_I C$, that is, either B is provable or C is provable (of course, intuitionistically). This fact is used in the "easy direction" of the proof of Theorem 16.9.

To illustrate the power of the above fact, in his construction, Statman associates the proposition

$$(x \Rightarrow B) \lor (\neg x \Rightarrow B) \tag{(*)}$$

to the QBF $\exists x B$. Classically this is useless, because (*) is classically valid, but if (*) is *intuitionistically provable*, then either $x \Rightarrow B$ is provable or $\neg x \Rightarrow B$ is intuitionistically provable, but this implies that either $x \Rightarrow B$ is classically provable or $\neg x \Rightarrow B$ is classically provable, and so either $B[x := \mathbf{T}]$ is valid or $B[x := \mathbf{F}]$ is valid, which means that $\exists x B$ is valid.

As a first step, Statman defines the proposition B_k^+ inductively as follows: for all k such that $0 \le k \le n-1$,

$$B_0^+ = \neg \neg B_0$$

$$B_{k+1}^+ = (x_{k+1} \lor \neg x_{k+1}) \Rightarrow B_k^+ \qquad \text{if } Q_{k+1} = \forall$$

$$B_{k+1}^+ = (x_{k+1} \Rightarrow B_k^+) \lor (\neg x_{k+1} \Rightarrow B_k^+), \qquad \text{if } Q_{k+1} = \exists$$

and set $A^+ = B_n^+$. Obviously A^+ is quantifier-free. We also let $B_{k+1} = Q_{k+1}x_{k+1}B_k$ for $k = 0, \ldots n - 1$, so that $A = B_n$.

The following example illustrates the above definition.

Example 16.3. Consider the QBF is prenex form

$$A = \exists x_3 \forall x_2 \exists x_1 ((x_1 \lor x_2) \land (\neg x_1 \lor \neg x_2) \land (\neg x_3 \lor x_1)).$$

It is indeed valid, as we see by setting $x_3 = \mathbf{F}$, and if $x_2 = \mathbf{T}$ then $x_1 = \mathbf{F}$, else if $x_2 = \mathbf{F}$ then $x_1 = \mathbf{T}$. We have

$$\begin{split} B_0^+ &= \neg \neg ((x_1 \lor x_2) \land (\neg x_1 \lor \neg x_2) \land (\neg x_3 \lor x_1)) \\ B_1^+ &= (x_1 \Rightarrow B_0^+) \lor (\neg x_1 \Rightarrow B_0^+) \\ B_2^+ &= (x_2 \lor \neg x_2) \Rightarrow B_1^+ \\ B_3^+ &= (x_3 \Rightarrow B_2^+) \lor (\neg x_3 \Rightarrow B_2^+), \end{split}$$

and $A^+ = B_3^+$.

Statman proves the following remarkable result (Statman [68], Proposition 1).

Theorem 16.9. For any closed QBF A in prenex form, A is valid iff $\vdash_I A^+$; that is, A^+ is intuitionistically provable.

Proof sketch. Here is a sketch of Statman's proof using the QBF of Example 16.3. First assume the QBF A is valid. The first step is to eliminate existential quantifiers using a variant of what is known as Skolem functions; see Gallier [24] or Shoenfield [67].

The process is to assign to the *j*th existential quantifier $\exists x_k$ from the left in the formula $Q_n x_n \cdots Q_1 x_1 B_0$ a boolean function C_j depending on the universal quantifiers $\forall x_{i_1}, \ldots, \forall x_{i_p}$ to the left of $\exists x_k$ and defined such that $Q_n x_n \cdots Q_{k+1} x_{k+1} \exists x_k B_{k-1}$ is valid iff $\forall x_{i_1} \cdots \forall x_{i_q} B_{k-1}^s$ is valid, where B_{k-1}^s is the result of substituting the functions C_1, \ldots, C_j associated with the *j* existential quantifiers from the left for these existentially quantified variables.

We associate with $\exists x_3$ the constant C_1 such that $C_1 = \mathbf{F}$, and with $\exists x_1$ the boolean function $C_2(x_2)$ given by

$$C_2(\mathbf{T}) = \mathbf{F}, \quad C_2(\mathbf{F}) = \mathbf{T}.$$

The constant C_1 and the function C_2 are chosen so that

$$A = \exists x_3 \forall x_2 \exists x_1 ((x_1 \lor x_2) \land (\neg x_1 \lor \neg x_2) \land (\neg x_3 \lor x_1))$$

is valid iff

$$A^{s} = \forall x_{2}((C_{2}(x_{2}) \lor x_{2}) \land (\neg C_{2}(x_{2}) \lor \neg x_{2}) \land (\neg C_{1} \lor C_{2}(x_{2})))$$
(S)

is valid. Indeed, since $C_1 = \mathbf{F}$, the clause $(\neg C_1 \lor C_2(x_2))$ evaluates to **T** regardless of the value of x_2 , and by definition of C_2 , the expression

$$\forall x_2(C_2(x_2) \lor x_2) \land (\neg C_2(x_2) \lor \neg x_2))$$

also evaluates to **T**. We now build a tree of Gentzen sequents (from the root up) from the expression in (S) which guides us in deciding which disjunct to pick when dealing with a proposition B_k^+ associated with an existential quantifier. Here is the tree.

We will see that by adding subtrees proving the sequents in the leaf nodes, this tree becomes an intuitionistic proof of A^+ . Note that this a proof in a Gentzen sequent style formulation of intuitionistic logic (see Kleene [42], Gallier [18], Takeuti [71]), not a proof in a natural deduction style proof system as in Section 2.6.

The tree is constructed from the bottom-up starting with $\rightarrow A^+$. For every leaf node in the tree where a sequent is of the form

$$\ell_n, \dots, \ell_{k+1} \to (x_k \Rightarrow B_{k-1}^+) \lor (\neg x_k \Rightarrow B_{k-1}^+)$$

where $\ell_n, \ldots, \ell_{k+1}$ are literals, we know that $Q_k = \exists$ is the *j*th existential quantifier from the left, so we use the boolean function C_j to determine which of the two disjuncts $x_k \Rightarrow B_{k-1}^+$ or $\neg x_k \Rightarrow B_{k-1}^+$ to keep. The function C_j depends on the value of the literals $\ell_n, \ldots, \ell_{k+1}$ associated with universal quantifiers (where ℓ_i has the value **T** if $\ell_i = x_i$ and ℓ_i has the value **F** if $\ell_i = \neg x_i$). Even though C_j is independent of the value of the literals ℓ_i associated with existential quantifiers, to simplify notation we write $C_j(\ell_n, \ldots, \ell_{k+1})$ for the value of the function C_j . If $C_j(\ell_n, \ldots, \ell_{k+1}) = \mathbf{T}$, then we pick the disjunct $x_k \Rightarrow B_{k-1}^+$, else if $C_j(\ell_n, \ldots, \ell_{k+1}) = \mathbf{F}$, then we pick the disjunct $\neg x_k \Rightarrow B_{k-1}^+$. Denote the literal corresponding to the chosen disjunct by ℓ_k ($\ell_k = x_k$ in the first case, $\ell_k = \neg x_k$ in the second case). Then we grow two new nodes

$$\ell_n, \ldots, \ell_{k+1} \to \ell_k \Rightarrow B_{k-1}^+$$

and

$$\ell_n, \ldots, \ell_{k+1}, \ell_k \to B_{k-1}^+$$

above the (leaf) node

$$\ell_n, \ldots, \ell_{k+1} \to (x_k \Rightarrow B_{k-1}^+) \lor (\neg x_k \Rightarrow B_{k-1}^+).$$

For every leaf node of the form

$$\ell_n, \ldots, \ell_{k+1} \to (x_k \lor \neg x_k) \Rightarrow B_{k-1}^+$$

we grow the new node

$$\ell_n, \ldots, \ell_{k+1}, x_k \lor \neg x_k \to B_{k-1}^+$$

$$\ell_n, \ldots, \ell_{k+1}, x_k \to B_{k-1}^+$$
 and $\ell_n, \ldots, \ell_{k+1}, \neg x_k \to B_{k-1}^+$.

By induction from the bottom-up, since A is valid and since the tree was constructed in terms of the constant C_1 and the function C_2 which ensure the validity of A, it is easy to see that for every node $\ell_n, \ldots, \ell_{k+1} \to B_k^+$, the sequent $\ell_n, \ldots, \ell_{k+1} \to B_k$ (note, the right-hand side is the original formula B_k) is classically valid, and thus classically provable (by the completeness theorem for propositional logic). Consequently every leaf $\ell_n, \ldots, \ell_1 \to B_0$ is classically provable, so by Glivenko's theorem (see Kleene [42] (Theorem 59), or Gallier [18] (Section 13)), the sequent $\ell_n, \ldots, \ell_1 \to \neg \neg B_0$ is intuitionistically provable. But this is the sequent $\ell_n, \ldots, \ell_1 \to B_0^+$ so all the leaves of the tree are intuitionistically provable, and since the tree is a deduction tree in a Gentzen sequent style formulation of intuitionistic logic (see Kleene [42], Gallier [18], Takeuti [71]), the root $A^+ = B_n^+$ is intuitionistically provable.

In the other direction, assume that A^+ is intuitionistically provable. We use the fact that if

$$\ell_n, \ldots, \ell_k \to A \lor B$$

is intuitionistically provable and the ℓ_i are literals, then either $\ell_n, \ldots, \ell_k \to A$ is intuitionistically provable or $\ell_n, \ldots, \ell_k \to B$ is intuitionistically provable, and other proof rules of intuitionistic logic (see Kleene [42], Gallier [18], Takeuti [71]), to build a proof tree just as we did before. Then every sequent $\ell_n, \ldots, \ell_{k+1} \to B_k^+$ is intuitionistically provable, thus classically provable, and consequently classically valid. But this immediately implies (by induction starting from the leaves) that $\ell_n, \ldots, \ell_{k+1} \to B_k$ is also classically valid for all k, and thus $A = B_n$ is valid. \Box

Statman does not specifically state which proof system of intuitionistic logic is used in Theorem 16.9. Careful inspection of the proof shows that we can construct proof trees in a Gentzen sequent calculus as described in Gallier [18] (system \mathcal{G}_i , Section 4) or Kleene [42] (system G3a, Section 80, pages 481-482). This brings up the following issue: could we use instead proofs in natural deduction style, as in Prawitz [60] or Gallier [18]? The answer is yes, because there is a polynomial-time translation of intuitionistic proofs in Gentzen sequent style to intuitionistic proofs in natural deduction style, as shown in Gallier [18], Section 5. So Theorem 16.9 applies to a Gentzen sequent style proof system or to a natural deduction style proof system.

The problem with the translation $A \mapsto A^+$ is that A^+ may not have size polynomial in the size (the length of A as a string) of A because in the case of an existential quantifier the length of the formula B_{k+1}^+ is more than twice the length of the formula B_k^+ , so Statman introduces a second translation.

The proposition B_k^{\dagger} is defined inductively as follows. Let y_0, y_1, \ldots, y_n be n+1 new

propositional variables. For all k such that $0 \le k \le n-1$,

$$B_0^{\dagger} = \neg \neg B_0 \equiv y_0$$

$$B_{k+1}^{\dagger} = ((x_{k+1} \lor \neg x_{k+1}) \Rightarrow y_k) \equiv y_{k+1} \qquad \text{if } Q_{k+1} = \forall Q_{k+1} =$$

and set

$$A^* = B_0^{\dagger} \Rightarrow (B_1^{\dagger} \Rightarrow (\cdots (B_n^{\dagger} \Rightarrow y_n) \cdots))$$

It is easy to see that the translation $A \mapsto A^*$ can be done in polynomial space. Statman proves the following result (Statman [68], Proposition 2).

Theorem 16.10. For any closed QBF A in prenex form, $\vdash_I A^+$ iff $\vdash_I A^*$; that is, A^+ is intuitionistically provable iff A^* is intuitionistically provable.

Proof. First suppose the sequent $\rightarrow A^+$ is provable (in Kleene G3a). We claim that the sequent

$$B_0^{\dagger}, \ldots, B_k^{\dagger} \to B_k^+ \equiv y_k$$

is provable for k = 0, ..., n. We proceed by induction on k. For the base case k = 0, we have $B_0^{\dagger} = (\neg \neg B_0 \equiv y_0)$ and $B_0^+ = \neg \neg B_0$, so $B_0^{\dagger} \to (B_0^+ \equiv y_0) = (B_0^+ \equiv y_0) \to (B_0^+ \equiv y_0)$, which is an axiom.

For the induction step, if $Q_{k+1} = \forall$, then

$$B_{k+1}^+ = (x_{k+1} \lor \neg x_{k+1}) \Rightarrow B_k^+, \qquad B_{k+1}^\dagger = ((x_{k+1} \lor \neg x_{k+1}) \Rightarrow y_k) \equiv y_{k+1},$$

by the induction hypothesis

$$B_0^{\dagger}, \dots, B_k^{\dagger} \to B_k^+ \equiv y_k$$

is provable, and since the sequent

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to B_{k+1}^{\dagger}$$

is an axiom, by substituting B_k^+ for y_k in $B_{k+1}^\dagger = ((x_{k+1} \vee \neg x_{k+1}) \Rightarrow y_k) \equiv y_{k+1}$ in the conclusion of the above sequent, we deduce that

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to ((x_{k+1} \lor \neg x_{k+1}) \Rightarrow B_k^{\dagger}) \equiv y_{k+1}$$

is provable. Since $B_{k+1}^+ = (x_{k+1} \vee \neg x_{k+1}) \Rightarrow B_k^+$, we conclude that

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to B_{k+1}^{+} \equiv y_{k+1}$$

is provable.

If
$$Q_{k+1} = \exists$$
, then
 $B_{k+1}^+ = (x_{k+1} \Rightarrow B_k^+) \lor (\neg x_{k+1} \Rightarrow B_k^+), \qquad B_{k+1}^\dagger = ((x_{k+1} \Rightarrow y_k) \lor (x_{k+1} \Rightarrow y_k)) \equiv y_{k+1},$

by the induction hypothesis

$$B_0^{\dagger}, \dots, B_k^{\dagger} \to B_k^+ \equiv y_k$$

is provable, and since the sequent

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to B_{k+1}^{\dagger}$$

is an axiom, by substituting B_k^+ for y_k in $B_{k+1}^\dagger = ((x_{k+1} \Rightarrow y_k) \lor (x_{k+1} \Rightarrow y_k)) \equiv y_{k+1}$ in the conclusion of the above sequent, we deduce that

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to ((x_{k+1} \Rightarrow B_k^+) \lor (\neg x_{k+1} \Rightarrow B_k^+)) \equiv y_{k+1}$$

is provable. Since $B_{k+1}^+ = (x_{k+1} \Rightarrow B_k^+) \lor (\neg x_{k+1} \Rightarrow B_k^+)$, we conclude that

$$B_0^{\dagger}, \dots, B_k^{\dagger}, B_{k+1}^{\dagger} \to B_{k+1}^+ \equiv y_{k+1}$$

is provable. Therefore the induction step holds. For k = n, we see that the sequent

$$B_0^{\dagger}, \dots, B_n^{\dagger} \to (B_n^+ \equiv y_n) = B_0^{\dagger}, \dots, B_n^{\dagger} \to (A^+ \equiv y_n)$$

is provable, and since by hypothesis $\rightarrow A^+$ is provable, we deduce that

 $B_0^{\dagger}, \ldots, B_n^{\dagger} \to y_n$

is provable. Finally we deduce that

$$A^* = B_0^{\dagger} \Rightarrow (B_1^{\dagger} \Rightarrow (\cdots (B_n^{\dagger} \Rightarrow y_n) \cdots))$$

is provable intuitionistically.

Conversely assume that $A^* = B_0^{\dagger} \Rightarrow (B_1^{\dagger} \Rightarrow (\cdots (B_n^{\dagger} \Rightarrow y_n) \cdots))$ is provable intuitionistically. Then using basic properties of intuitionistic provability, the sequent

$$B_0^{\dagger}, \ldots, B_n^{\dagger} \to y_n$$

is provable intuitionistically. Now if we substitute B_{k+1}^+ for y_{k+1} in B_{k+1}^\dagger for $k = 0, \ldots, n-1$, we see immediately that

$$B_{k+1}^{\dagger}[y_{k+1} := B_{k+1}^{+}] = B_{k+1}^{+} \equiv B_{k+1}^{+}$$

so the proof of

$$B_0^{\dagger}, \ldots, B_n^{\dagger} \to y_n$$

yields a proof of

$$B_0^+ \equiv B_0^+, \dots, B_n^+ \equiv B_n^+ \to B_n^+$$

that is, a proof (intuitionistic) of $B_n^+ = A^+$.

Remark: Note that we made implicit use of the cut rule several times, but by Gentzen's cut-elimination theorem this does not matter (see Gallier [18]). \Box

Using Theorems 16.9 and 16.10 we deduce from the fact that validity of QBF's is \mathcal{PS} complete that provability in propositional intuitionistic logic is \mathcal{PS} -hard (every problem in \mathcal{PS} reduces in polynomial time to provability in propositional intuitionistic logic). Using
results of Tarski and Ladner, it is can be shown that validity in Kripke models for propositional intuitionistic logic belongs to \mathcal{PS} , so Statman proves the following result (Statman
[68], Section 2, Theorem).

Theorem 16.11. The problem of deciding whether a proposition is valid in all Kripke models is \mathcal{PS} -complete.

Theorem 16.11 also applies to any proof system for intuitionisic logic which is sound and complete for Kripke semantics.

Theorem 16.12. The problem of deciding whether a proposition is intuitionistically provable in any sound and complete proof system (for Kripke semantics) is \mathcal{PS} -complete.

Theorem 16.12 applies to Gallier's system \mathcal{G}_i , to Kleene's system G3a, and to natural deduction systems. To prove that \mathcal{G}_i is complete for Kripke semantics it is better to convert proofs in \mathcal{G}_i to proofs in a system due to Takeuti, the system denoted \mathcal{GKT}_i in Gallier [18]; see Section 9, Definition 9.3. Since there is a polynomial-time translation of proofs in \mathcal{G}_i to proofs in natural deduction, the latter system is also complete. This is also proven in van Dalen [75].

Statman proves an even stronger remarkable result, namely that \mathcal{PS} -completeness holds even for propositions using only the connective \Rightarrow (Statman [68], Section 2, Proposition 3).

Theorem 16.13. There is an algorithm which given any proposition A constructs another proposition A^{\sharp} only involving \bot, \Rightarrow , such that $\det \Box_I A$ iff $\vdash_I A^{\sharp}$.

Theorem 16.13 is somewhat surprising in view of the fact that \lor, \land, \Rightarrow are independent connectives in propositional intuitionistic logic. Finally Statman obtains the following beautiful result (Statman [68], Section 2, Theorem).

Theorem 16.14. The problem of deciding whether a proposition only involving \bot , \Rightarrow is valid in all Kripke models, and intuitionistically provable in any sound and complete proof system, is \mathcal{PS} -complete.

We highly recommend reading Statman [68], but we warn the reader that this requires perseverance.

Appendix A

Well-Ordered Sets, Ordinals, Cardinals, Alephs

The purpose of this chapter is to define the notions of ordinal, cardinal and alephs, and to review some of their main properties. Intuitively the ordinals are the equivalence classes of well-ordered sets under the equivalence relation of order-isomorphism (the order-types). This idea goes back to Cantor; see Levy [48] for a thorough discussion of this approach. However, such a definition does not make sense because the collection of well-ordered sets is not a set. To circumvent this difficulty, following Von Neumann, we can define an ordinal as a certain special type of set.

We also define the operations of addition, multiplication, and exponentiation on infinite ordinals. Multisets, nested multisets and certain orderings on them turn out to be convenient tools to understand the orderings on ordinals which are powers of ω . We also introduce the Cantor normal form.

A.1 Well-Ordered Sets

We begin by reviewing the notions of partial orders, total orders, strict partial orders, and strict total orders. Given a set X and a binary relation $\preceq \subseteq X \times X$ on X, we write $x \preceq y$ for $(x, y) \in \preceq$ and $x \not\preceq y$ for $\neg(x \preceq y)$.

Definition A.1. Given a set X, a binary relation \leq on X is a *partial order* if it satisfies the following properties:

- (1) The relation \leq is *reflexive*, which means that for all x, if $x \in X$, then $x \leq x$.
- (2) The relation \leq is *transitive*, which means that for all x, y, z, if $x, y, z \in X$, $x \leq y$ and $y \leq z$, then $x \leq z$.
- (3) The relation \leq is *antisymmetric*, which means that for all x, y, if $x, y \in X$, $x \leq y$ and $y \leq x$, then x = y. The pair (X, \leq) is called a *partially ordered set*.

A binary relation \leq on X is a *total order (or simple order)* if it is a partial order and if it is *strongly connected*, which means that for all x, y, if $x, y \in X$, then either $x \leq y$ or $y \leq x$. The pair (X, \leq) is called a *totally ordered set*.

The empty set (with the empty relation) is trivially a partially and a totally ordered set.

Example A.1.

- (1) Given any nonempty set X, the inclusion relation $Y \subseteq Z$ on subsets Y and Z of X is a partial order which is not a total order if X has at least two elements.
- (2) The set \mathbb{N} of natural numbers with its usual ordering is a totally ordered set.
- (3) The set \mathbb{Z} of integers with its usual ordering is a totally ordered set.
- (4) The relation \ll on $\mathbb{N} \times \mathbb{N}$ defined such that for all $(m_1, n_1), (m_2, n_2) \in \mathbb{N} \times \mathbb{N}$,

$$(m_1, n_1) \ll (m_2, n_2)$$
 iff $\begin{cases} m_1 = m_2 \text{ and } n_1 = n_2, \text{ or} \\ m_1 < m_2, \text{ or} \\ m_1 = m_2 \text{ and } n_1 < n_2 \end{cases}$

is a total order.

Definition A.2. Given a set X, a binary relation \leq on X is a *strict partial order* if it satisfies the following properties:

- (1) The relation \leq is *asymmetric*, which means that for all x, y, if $x, y \in X$, then either $x \not\leq y$ or $y \not\leq x$, equivalently $\neg((x \leq y) \land (y \leq x))$.
- (2) The relation \leq is *transitive*, which means that for all x, y, z, if $x, y, z \in X$, $x \leq y$ and $y \leq z$, then $x \leq z$. The pair (X, \leq) is called a *strictly partially ordered set*.

A binary relation \leq on X is a strict total order (or strict simple order) if it is a strict partial order and if it is connected, which means that for all x, y, if $x, y \in X$ and $x \neq y$, then $x \leq y$ or $y \leq x$. The pair (X, \leq) is called a strictly totally ordered set.

The empty set (with the empty relation) is trivially a strictly partially and a strictly totally ordered set.

Example A.2.

- (1) Given any nonempty set X, the strict inclusion relation $Y \subseteq Z$ and $Y \neq Z$ on subsets Y and Z of X is a strict partial order which is not a strict total order if X has at least two elements.
- (2) The set \mathbb{N} of natural numbers with the strict ordering m < n (namely $m \leq n$ and $m \neq n$) is a strictly totally ordered set.

- (3) The set \mathbb{Z} of integers with its strict ordering m < n (namely $m \le n$ and $m \ne n$) is a strictly totally ordered set.
- (4) The relation \ll on $\mathbb{N} \times \mathbb{N}$ defined such that for all $(m_1, n_1), (m_2, n_2) \in \mathbb{N} \times \mathbb{N}$,

$$(m_1, n_1) \ll (m_2, n_2)$$
 iff $\begin{cases} m_1 < n_1, \text{ or} \\ m_1 = n_1 \text{ and } m_2 < n_2 \end{cases}$

is a strict total order.

Definition A.3. Given a set X, a partial order \leq on X is a *well-order* if every nonempty subset Y of X has a smallest element, which can be expressed as follows: for all Y, if $Y \neq \emptyset$ and $Y \subseteq X$, then there is some $x \in Y$ such that for y, if $y \in Y$, then $x \leq y$. The pair (X, \leq) is called a *well-ordered set*.

A strict partial order \leq on X is a *strictly well-order* if every nonempty subset Y of X has a smallest element. The pair (X, \leq) is called a *strictly well-ordered set*.

The empty set (with the empty relation) is trivially a well-ordered set and strictly wellordered set. If a well-ordered set is nonempty, then by picking $Y = \{x, y\}$ for any $x, y \in X$, since Y must have a smallest element, we see that either $x \leq y$ or $y \leq x$, that is, a wellordered set is totally ordered. The same reasoning shows that a strictly well-ordered set is strictly totally ordered.

Example A.3.

- (1) The partial order of Example A.1 is not a well-order (in fact, it is not a total order).
- (2) The set \mathbb{N} is well-ordered under its natural ordering.
- (3) The set \mathbb{Z} is not well-ordered under its natural ordering. For example, the subset $\{n \in \mathbb{Z} \mid n \leq 0\}$ does not have a smallest element.
- (4) The set $\mathbb{N} \times \mathbb{N}$ under the total order of Example A.1 is well-ordered.

Proposition A.1. Let (X, \leq) be a partially ordered set. The relation < on X given by

$$x < y$$
 iff $x \leq y$ and $x \neq y$

is a strict partial order on X. If (X, \leq) is a totally ordered set, then the relation < on X defined above is a strict total order. If (X, \leq) is a well-ordered set, then the relation < on X defined above is a strict well-order.

Proof. Assume that (X, \leq) is a partially ordered set. The relation < is transitive because if x < y and y < z, then $x \leq y$, $y \leq z$, $x \neq y$ and $y \neq z$, so by transitivity of \leq we have $x \leq z$. If x = z, then $y \leq z$ is equivalent to $y \leq x$, and since $x \leq y$, and \leq is antisymmetric, we get x = y, a contradiction. The relation < is asymmetric, because if x < y and y < x, then $x \leq y$, $y \leq x$ and $x \neq y$, but since \leq is antisymmetric, x = y, a contradiction.

The other statements are left as exercises to the reader.

We say that (X, <) is the strictly partially ordered set associated with the partially ordered set (X, \leq) , etc.

A detailed exposition of the above results and much more can be found in Suppes [70].

The importance of well-orders has to do with the fact that they support a powerful induction principle.

Definition A.4. For any partially ordered set (E, \leq) , for any $x \in E$, the subset $s(x) = \{y \in E \mid y < x\} = \{y \in E \mid y \leq x, y \neq x\}$ is called an *initial segment* of E.

Theorem A.2. Let (E, \leq) be a well-ordered set. For any subset A of E, if for every $a \in E$,

if $a \in A$ whenever $b \in A$ for all $b \in E$ such that b < a,

then A = E. Equivalently, for all $a \in E$, if $s(a) \subseteq A$ implies that $a \in A$, then A = E.

Proof. Suppose by contradiction that $A \neq E$. Then the subset E - A is nonempty, and since E is well-ordered, it has a least element $b \notin A$. We claim that $s(b) \subseteq A$. Indeed, $y \in s(b)$ iff y < b, but then we can't have $y \in E - A$, because this would contradict the fact that b is the smallest element of E - A, so $y \in A$. Since $s(b) \subseteq A$, by hypothesis $b \in A$, a contradiction.

Theorem A.2 immediately implies the following induction principle.

Theorem A.3. Let (E, \leq) be a well-ordered set and let P(x) be a first-order formula with free variable x. For every $a \in E$, if P(a) holds whenever P(b) holds for all $b \in E$ such that b < a, then P(x) holds for all $x \in E$.

Theorem A.3 follows immediately from Theorem A.2 by setting $A = \{a \in E \mid P(a) =$ **true** $\}$. The induction principle in Theorem A.3 is sometimes called *transfinite induction on* a well-ordered set. It is a generalization of complete induction on N.

Definition A.5. Let (X_1, \leq_1) and (X_2, \leq_2) be two partially ordered sets. A function $f: X_1 \to X_2$ is an *(order) isomorphism* if it is a bijection and if

 $x \leq_1 y$ iff $f(x) \leq_2 f(y)$, for all $x, y \in X_1$.

The same definition applies if (X_1, \leq_1) and (X_2, \leq_2) are two strictly partially ordered sets, and if the orderings are total or well-orders.

Note that a well-ordered set may be isomorphic to a proper subset of itself. For example, (\mathbb{N}, \leq) is isomorphic to $(2\mathbb{N}, \leq)$ (where $2\mathbb{N} = \{2n \mid n \in \mathbb{N}\}$). However, we have the following important results.

Proposition A.4. Let (E, \leq) be a well-ordered set. If $f: E \to E$ is a function such that for all $x, y \in E$, if $x \neq y$ and $x \leq y$ implies that $f(x) \neq f(y)$ and $f(x) \leq f(y)$, then

$$x \le f(x)$$
 for all $x \in E$.
Using Proposition A.4 we can prove the following result.

Proposition A.5. Let (E_1, \leq_1) and (E_2, \leq_2) be two well-ordered sets. If $f: E_1 \to E_2$ and $g: E_1 \to E_2$ are isomorphisms, then f = g.

As a corollary of Proposition A.5 it can be shown that if (E, \leq) is a well-ordered set, then there is no isomorphism between E and any initial segment $s(x) = \{y \in E \mid y < x\}$, for any $x \in E$.

A.2 Ordinals

Technically, the definition of an ordinal depends on the precise axiomatic definition chosen for set theory (in first-order logic), specifically whether individual constants other than the symbol \emptyset (the empty set) are allowed. Suppose [70] allows such individual symbols. For simplicity we follow Krivine [45] who does not allow such symbols. What this means is that the sets under consideration only have other sets as members, building up from the empty set.

Definition A.6. An *ordinal* is a set α such that

- (1) The membership relation $x \in y$ on α (with $x, y \in \alpha$) is a strict well-order.
- (2) For every x, if $x \in \alpha$, then $x \subseteq \alpha$. By definition of the inclusion relation, this means that for all x, y, if $y \in x$ and $x \in \alpha$, then $y \in \alpha$. Sometimes it is said that α is a *transitive set*.¹

Remark: One of the axioms of set theory, the sum axiom, also called the union axiom, states that for every set X, the collection of all y such that $y \in x$ for some $x \in X$ is a set, denoted $\bigcup X$ or $\bigcup_{x \in X} x$. Then Condition (2) of Definition A.6 is equivalent to the condition

$$\bigcup \alpha \subseteq \alpha.$$

This condition is used in Suppes [70] and Levy [48].

We see that Definition A.6 implies that an ordinal is a set of sets of sets, etc.

For example, \emptyset , $\{\emptyset\}$, $\{\emptyset, \{\emptyset\}\}$, $\{\emptyset, \{\emptyset\}\}$ are ordinals, and more generally, if α is an ordinal, then $\alpha \cup \{\alpha\}$ is also an ordinal denoted α^+ . The ordinal \emptyset is also denoted by 0.

This is the method used by Von Neumann to define the natural numbers. The number 0 is represented by the empty set, 1 is represented by $\{\emptyset\} = \{0\}, 2$ is represented by $\{\emptyset, \{\emptyset\}\} = \{0, 1\}, 3$ is represented by $\{\emptyset, \{\emptyset\}, \{\emptyset, \{\emptyset\}\}\} = \{0, 1, 2\}$, and if α represents a natural number, then $\alpha^+ = \alpha \cup \{\alpha\}$ represents the natural number $\alpha + 1$. For this reason, we also denote α^+ as $\alpha + 1$.

¹This use of the word transitive is unfortunate since it differs from its meaning in Definition A.1(2).

We now list (mostly) without proof the most important properties of ordinals. Proofs can be found in Suppes [70] and Krivine [45]. A more advanced, rigorous and very thorough presentation can be found in Levy [48].

Proposition A.6. Let α be an ordinal.

(1) For any $\xi \in \alpha$, we have $s(\xi) = \{\eta \in \alpha \mid \eta \in \xi\} = \xi$.

(2) If $\xi \in \alpha$, then ξ is an ordinal.

Proposition A.7. For every ordinal α , we have $\alpha \notin \alpha$.

Proof. For any $\xi \in \alpha$, since the membership relation \in on α is a strict order, we have $\xi \notin \xi$. Then if $\alpha \in \alpha$, we also have $\alpha \notin \alpha$, a contradiction.

Using Theorem A.3 the following result can be shown.

Proposition A.8. For any two ordinals α , β , if there is an isomorphism between α and β (each equipped with the strict order of membership), then $\alpha = \beta$.

Proposition A.9. For any two ordinals α, β , either $\alpha = \beta$, $\alpha \in \beta$, or $\beta \in \alpha$, and these three cases are mutually exclusive.

Proposition A.9 implies that for any two ordinals α, β , we have $\alpha \subseteq \beta$ iff $\alpha = \beta$ or $\alpha \in \beta$. It follows that the relation $\alpha \subseteq \beta$ is a total order on the ordinals, and we also write $\alpha \leq \beta$ instead of $\alpha \subseteq \beta$ and $\alpha < \beta$ for $\alpha \in \beta$. Observe that the relation $\alpha \in \beta$ is the strict total order associated with the total order \subseteq .

Proposition A.10. For any ordinal α , the ordinal $\alpha^+ = \alpha \cup \{\alpha\}$ is the smallest ordinal strictly greater than α .

Proposition A.11. For any set S of ordinals, the set $\beta = \bigcup_{\alpha \in S} \alpha = \bigcup S$ is an ordinal which is the least upper bound of the set S.

Proposition A.12. For any set S of ordinals, the membership relation on S is a strict wellorder. As a consequence, for any ordinal α , the ordinals $\beta < \alpha$ form a strictly well-ordered set (under inclusion).

Proposition A.13. (Burali–Forti paradox) The collection of all ordinals is not a set.

Proof. Assume that the collection of all ordinals is a set α . Then by Proposition A.12, the set α is strictly well-ordered. Also, by definition of the set α , if $\beta \in \alpha$, then β is an ordinal, and since by Proposition A.6(2), every $\xi \in \beta$ is an ordinal, we have $\xi \in \alpha$ (since α is the set of all ordinals), so $\beta \subseteq \alpha$. Then by definition of an ordinal, α is an ordinal, and since α is the set of all ordinals, $\alpha \in \alpha$, contradicting Proposition A.7.

Proposition A.14 confirms that the concept of ordinal captures the idea that the ordinals are the "order-types" of well-ordered sets.

A.2. ORDINALS

Proposition A.14. For every well-ordered set (S, \leq) , there is a unique ordinal α and a unique isomorphism between (S, <) and α (where (S, <) is the strictly well-ordered set associated with the well-ordered set (S, \leq) and α is strictly well-ordered by the membership relation).

Proposition A.14 is proven using Theorem A.3.

Finite and infinite ordinals are defined as follows.

Definition A.7. An ordinal α is *finite* if either $\alpha = \emptyset$ or for every $\beta \subseteq \alpha$ with $\beta \neq \emptyset$, there is some ordinal ξ such that $\beta = \xi + 1$. An *infinite ordinal* is an ordinal that is not finite.

Remark: Definition A.7 is the definition found in Levy [48] and Krivine [45]. A different definition is used in Suppos [70].

So far we don't know if infinite ordinals exist! The axiom of infinity asserts that infinite ordinals exist.

Axiom of Infinity. There exists an infinite ordinal.

It can be shown that the axiom of infinity is equivalent to the fact that the collection of finite ordinals is a set (which is an ordinal), denoted ω ; see Krivine [45].

Remark: In an axiomatic presentation of the axioms of Zermelo–Frankel set theory it is customary to state a version of the axiom of infinity which does not involve the notion of ordinal. It can be shown that this version of the axiom of infinity is equivalent to the above version about ordinals. For this classical approach, see Suppes [70] and Levy [48]. Since it is not our intention to give an axiomatic presentation of Zermelo–Frankel set theory, the above version of the axiom of infinity is preferable.

Definition A.8. Under the axiom of infinity, the set of all finite ordinals is an ordinal denoted ω .

In the Von Neumann approach, the natural numbers are identified with the finite ordinals. Thus ω is the set of natural numbers and it is also denoted \mathbb{N} by most mathematicians. The ordinal ω is not a finite ordinal. It is the smallest infinite ordinal because if ξ is an infinite ordinal such that $\xi \in \omega$, then ξ is a finite ordinal (ω is the set of all finite ordinals), a contradiction.

Definition A.9. An ordinal $\alpha \neq \emptyset$ is a *limit ordinal* if for all $\beta \in \alpha$, we also have $\beta + 1 \in \alpha$.

It is easy to see that an ordinal $\alpha \neq \emptyset$ is a limit ordinal iff there is no ordinal β such that $\alpha = \beta + 1$ iff

$$\alpha = \bigcup \alpha = \bigcup_{\beta \in \alpha} \beta$$

Furthermore, it can be shown that every limit ordinal is infinite and that the axiom of infinity is equivalent to the existence of a limit ordinal; see Krivine [45].

A.3 Cardinals, Alephs (\aleph_{α}) and Beths (\beth_{α})

Having defined the ordinals, we can define cardinals and the cardinality of a set. This is where the axiom of choice shows its nose.

Definition A.10. A *cardinal* is an ordinal \mathfrak{a} such that if β is any ordinal in bijection with \mathfrak{a} , then $\mathfrak{a} \subseteq \beta$.

A cardinal is often referred to as an *initial ordinal*. It appears that the universal notation adopted to denote cardinals is to use lower case German letters ("Fraktur" font), $\mathfrak{a}, \mathfrak{b}, etc$. This convention is convenient since if we denote ordinals by lower case Greek letters (as it is customary), then we have a visual mechanism to distinguish between ordinals and cardinals. As we will see shortly, cardinals are also denoted using the Hebrew letter aleph with an ordinal subscript (\aleph_{α}).

Proposition A.15. Every finite ordinal is a cardinal.

Definition A.11. The smallest infinite ordinal ω is a cardinal, which is also denoted \aleph_0 .

As we will see later, there is no largest cardinal, but this is not easy to prove; see Suppes [70] (Section 7.3, Theorem 60).

Assume that the **axiom of choice holds**. An easy-going version of the axiom of choice is that for any two nonempty sets X and Y, for any surjection $f: X \to Y$, there is some injection $g: Y \to X$ such that $f \circ g = id_Y$.

Theorem A.16. (Zermelo) Every set has some well-ordering.

A proof of Theorem A.16 can be found in all set theory texts, in particular Suppes [70] Krivine [45]. Theorem A.16 is one of many results equivalent to the famous axiom of choice. If you think Theorem A.16 is obvious, try finding a well-ordering on the power set $\mathcal{P}(\mathbb{N})$ of the set \mathbb{N} of natural numbers.

Now, if we accept the axiom of choice, since by Theorem A.16 every set X has some wellorder (not unique if X has at least two elements), by Proposition A.14, there is a bijection between X and some ordinal α . Then it is not hard to show that the ordinals β that are in bijection with X form a set (because if γ is an ordinal in bijection with the power set $\mathcal{P}(X)$, then $\beta \in \gamma$), so by Proposition A.12, there is a smallest ordinal, denoted |X|, among the ordinals in bijection with X.

Definition A.12. Given any set X, the smallest ordinal |X| (also denoted card(X)) in bijection with X is a cardinal called the *cardinal number (or cardinality)* of X.

It can be shown that the collection of cardinals numbers is *not* a set.

Remark: It is possible to define the notion of cardinality of a set even if we do not assume the axiom of choice. But then the cardinal |X| of set X is a certain kind of set that may not be an ordinal. In fact, the cardinal |X| is an ordinal iff the set |X| is well-orderable. See Levy [48] (Chapter III, Section 2).

Definition A.13. The cardinality of the set \mathbb{R} of real numbers is denoted by \mathfrak{c} and is called the *cardinality of the continuum* (or *power of the continuum*).

It is a standard theorem of set theory that there is a bijection between $\mathcal{P}(\mathbb{N})$, the power set of the set \mathbb{N} of natural numbers, and the set \mathbb{R} of real numbers; see Section 6.7 of Suppes [70].

Definition A.14. For any cardinal \mathfrak{a} , the cardinality of the power set $\mathcal{P}(\mathfrak{a})$ of \mathfrak{a} is denoted $2^{\mathfrak{a}}$.

Using the above definition, the fact that there is a bijection between $\mathcal{P}(N)$ and \mathbb{R} is restated as $\mathfrak{c} = 2^{\aleph_0}$. Cantor's theorem (which says that there is no surjection of a set X onto its power set $\mathcal{P}(X)$) stated in terms of cardinals says that for any cardinal \mathfrak{a} , we have

$$\mathfrak{a} < 2^{\mathfrak{a}}.$$

Our next goal is to show that it is possible to provide an enumeration of the infinite cardinals indexed by the ordinals. We first proceed informally. The idea is to define the infinite cardinal \aleph_{α}

for every ordinal α as follows: the cardinal \aleph_{α} is the infinite cardinal β such that the set $\{\xi \mid \xi \in \beta, \xi \text{ is an infinite cardinal}\}$ is isomorphic (as a strictly well-ordered set under the membership relation) to α (also with the strict order of membership). Intuitively, \aleph_{α} is the α 's infinite cardinal. So \aleph_1 is the smallest cardinal of cardinality strictly greater than \aleph_0 , then \aleph_2 is the smallest cardinal of cardinality strictly greater than \aleph_1 , and more generally $\aleph_{\alpha+1}$ is the smallest cardinal of cardinality strictly greater than \aleph_{α} . See Definition A.17 for a rigorous approach (which needs to deal with the case where α is a limit ordinal).

Then Cantor's theorem implies that

$$\aleph_{\alpha+1} \subseteq 2^{\aleph_{\alpha}}$$

Whether or not the above inequality is actually an equality is a famous problem called the *generalized continuum hypothesis*. For $\alpha = 0$, famous results of Gödel and Cohen show that the statement $\aleph_1 = \mathfrak{c} = 2^{\aleph_0}$ is independent of Zermelo–Frankel set theory (with the axiom of choice).

Our definition of the *alephs* (denoted \aleph_{α}) is not rigorous. It is actually possible to define rigorously the alephs without assuming the axiom of choice, as explained in Suppes [70].

We need to recall the following notation.

Definition A.15. Let *A* and *B* be any two sets.

- (1) We write $A \approx B$ if there is a bijection from A to B. In this case we say that A and B are *equipollent*.
- (2) We write $A \preceq B$ if there is a subset C of B such that $A \approx C$.

(3) We write $A \prec B$ if $A \preceq B$ and $\neg(B \preceq A)$, and we write $A \succ B$ if $B \preceq A$ and $\neg(A \preceq B)$.

Two ordinals may be equipollent and yet be very different in terms of they order structure. A simple example consists of the two ordinals ω and $\omega + 1 = \omega \cup \{\omega\}$. We can define the bijection f from $\omega + 1$ to ω given by $f(\{\omega\}) = 0$ and f(n) = n + 1, for any $n \in \omega$.

If $\varphi(\alpha)$ is a first-order formula in which α ranges over the ordinals, it can be shown that if there is some ordinal α such that $\varphi(\alpha)$ holds, then there is a smallest ordinal β such that $\varphi(\beta)$ holds; see Suppes [70] (Section 7.1, Theorem 5). The above fact suggests the definition of the smallest ordinal $\mu_{\alpha}(\varphi(\alpha))$ satisfying a first-order formula $\varphi(\alpha)$ (where α denotes an ordinal). If $\forall \alpha \neg \varphi(\alpha)$, that is, $\varphi(\alpha)$ is not satisfied by any ordinal, then we set $\mu_{\alpha}(\varphi(\alpha)) = 0$.

Definition A.16. Given a first-order formula $\varphi(\alpha)$ where α denotes an ordinal, the ordinal $\mu_{\alpha}(\varphi(\alpha))$ is defined such that for every ordinal β , we have the equivalence

$$\mu_{\alpha}(\varphi(\alpha)) = \beta \quad \text{iff} \quad [\varphi(\beta) \land \forall \gamma(\varphi(\gamma) \Longrightarrow (\beta \subseteq \gamma))] \lor [\forall \alpha \neg \varphi(\alpha) \land (\beta = 0)].$$

Then it can be shown that

- (1) If $\varphi(\beta)$ holds for some ordinal β , then $\mu_{\alpha}(\varphi(\alpha)) \subseteq \beta$.
- (2) If $\exists \alpha \varphi(\alpha)$ holds, then $\varphi(\mu_{\alpha}(\varphi(\alpha)))$ holds.

The alephs are then defined by transfinite recursion as follows.

Definition A.17. The ordinals \aleph_{α} (the *alephs*) are defined as follows:

- (1) $\aleph_0 = \omega$.
- (2) For any successor ordinal $\alpha + 1$,

$$\aleph_{\alpha+1} = \mu_{\beta}(\beta \succ \aleph_{\alpha}).$$

(3) For any limit ordinal α ,

$$\aleph_{\alpha} = \bigcup_{\beta \in \alpha} \aleph_{\beta}$$

Actually, we really have to justify why a recursive definition as in Definition A.17 is legitimate. To do so requires delving into axiomatic set theory more than we want to for the purpose of this appendix. Let us just say that the *axiom schema of replacement* (due to Zermelo) is required. Intuitively, this axiom says that if $\varphi(x, y)$ is a functional relation, which means that for all $x, y_1, y_2, \varphi(x, y_1)$ and $\varphi(x, y_2)$ implies that $y_1 = y_2$, then for any set A, the image of A by φ , that is, the collection of y such that $\varphi(x, y)$ for some $x \in A$, is also a set. Then a powerful version of definition by *transfinite recursion* can be established. For details, see Suppes [70] (Chapter 7). Incidentally, this version of transfinite recursion is also used to define addition, multiplication, and exponentiation of ordinals. Returning to the alephs, the following properties can be shown; see Suppes [70] (Chapter 7).

Actually, it is not obvious at all that for every \aleph_{α} , there is some ordinal β such that $\beta \succ \aleph_{\alpha}$, so that in Clause (2) of Definition A.17, some nonzero ordinal is returned. The next proposition shows that this is indeed the case; see Suppes [70] (Section 7.3, Theorem 63).

Proposition A.17. For any ordinal α , there is some ordinal β such that for every ordinal $\gamma \in \alpha$ we have $\beta \succ \aleph_{\gamma}$.

Proposition A.17 implies the following result which, together with the equation $\aleph_0 = \omega$, can be used as a definition of \aleph_{α} .

Proposition A.18. If α is a nonzero ordinal, then

 $\aleph_{\alpha} = \mu_{\beta}(\forall \gamma((\gamma \in \alpha) \Longrightarrow (\beta \succ \aleph_{\gamma}))).$

Proposition A.19. For every ordinal α , the ordinal \aleph_{α} is an infinite cardinal.

Proposition A.20. For any two ordinals α, β , if $\alpha \in \beta$, then $\aleph_{\alpha} \in \aleph_{\beta}$.

Proposition A.20 implies that there is no largest aleph.

Proposition A.21. For any ordinal α , there is no infinite cardinal β such that $\aleph_{\alpha} \in \beta \in \aleph_{\alpha+1}$.

It can also be shown that every cardinal \aleph_{α} is a limit ordinal; see Levy [48]. Finally, every infinite cardinal arises as some aleph, which means that there is an "enumeration" of the infinite cardinals by the ordinals.

Theorem A.22. For every infinite cardinal \mathfrak{a} , there is an ordinal α (necessarily unique by Proposition A.20) such that $\mathfrak{a} = \aleph_{\alpha}$.

All the above results do *not* rely on the axiom of choice. However, the axiom of choice is needed to show that every set has a cardinal (is in bijection with a cardinal).

Remark: Let us again assume that the axiom of choice holds. Then we can restate the generalized continuum hypothesis by introducing cardinals known as the *beth's*.

Definition A.18. We define by transfinite recursion the cardinals *beth* α , denoted \beth_{α} , as follows: for every ordinal α ,

$$\exists_0 = \aleph_0 \exists_{\alpha+1} = \operatorname{card}(\mathcal{P}(\exists_\alpha)) \exists_\alpha = \bigcup_{\beta < \alpha} \exists_\beta \quad \text{if } \alpha \text{ is a limit ordinal}$$

Observe that

 $\beth_1 = \mathfrak{c},$

the cardinality of the continuum. We can show by transfinite induction that

 $\aleph_{\alpha} \leq \beth_{\alpha}$

for every ordinal α , and the generalized continuum hypothesis is restated as

$$\aleph_{\alpha} = \beth_{\alpha}$$

for every ordinal α . The continuum hypothesis is restated as

$$\aleph_1 = \beth_1$$

Infinite ordinals beyond ω are very hard to understand. A way to get a better grasp of the infinite ordinals is to generalize the operations of addition, multiplication, and exponentiation defined on the natural numbers (the finite ordinals) to infinite ordinals. This is done by generalizing the familiar recursive definitions to infinite ordinals, and the trick for doing so is to extends these recursive definitions to limit ordinals. To do this rigorously requires a form of transfinite recursion. To prove properties of these operations requires transfinite induction. The operations of addition, multiplication and exponentiation on infinite ordinals exhibit somewhat unexpected behaviors. For example, addition and multiplication are no longer commutative. However we now have a tool for describing ordinals beyond ω , for example, $\omega^{\omega} + \omega^3 \cdot 3 + 1$.

A.4 Ordinal Arithmetic

First we need to present two versions of transfinite induction. Let $\varphi(\alpha)$ be a first-order formula, where the variable α ranges over the ordinals.

Theorem A.23. (Transfinite Induction: First Formulation) If for every ordinal α we have the implication,

$$\forall \beta((\beta \in \alpha) \Longrightarrow \varphi(\beta)) \Longrightarrow \varphi(\alpha), \tag{\dagger}$$

then $\varphi(\alpha)$ holds for all ordinals α .

Theorem A.23 is actually quite easy to prove. The proof relies on the fact that every nonempty set of ordinals is well-ordered; see Suppes [70] (Section 7.1, Theorem 1). Theorem A.23 can be viewed as a generalization of transfinite induction on a well-ordered set. In practice a more convenient of transfinite induction breaks the induction step (\dagger) into two cases depending whether or not α is a limit ordinal.

Theorem A.24. (Transfinite Induction: Second Formulation) If for every ordinal α ,

- (1) $\varphi(0)$ holds.
- (2) For every ordinal α , if $\varphi(\alpha)$ holds, then $\varphi(\alpha + 1)$ holds.
- (3) For every limit ordinal γ , if

$$\forall \beta ((\beta \in \gamma) \Longrightarrow \varphi(\beta)) \tag{\phi_2}$$

implies $\varphi(\gamma)$,

then $\varphi(\alpha)$ holds for all ordinals α .

See Suppes [70] (Section 7.1, Theorem 2). In addition to the usual induction step in (2), we need a "complete induction step" (Step 3) to deal with limit ordinals.

Next we need a method to define "functions" on the ordinals by transfinite recursion. Here we have to be a bit careful because the ordinals do not form a set. Still this can be done but a rigorous justification requires the axiom of replacement. All this is carefully explained in Suppes [70] (Section 7.1) but this is beyond the scope of our exposition. There are several versions of transfinite recursion, but the only version we need is the following.

Theorem A.25. (Transfinite Recursion) Let $\sigma(\alpha_1, \ldots, \alpha_{n-1})$ $(n \ge 1)$ be a term with at most the free variables $\alpha_1, \ldots, \alpha_{n-1}$ defining a function on the ordinals and let $\mu(\alpha_1, \ldots, \alpha_n)$ be a term with at most the free variables $\alpha_1, \ldots, \alpha_n$ defining a function on the ordinals. Then for any ordinals $\alpha_1, \ldots, \alpha_{n-1}$ and any ordinal $\alpha \ne 0$, there is a unique term $\tau(\alpha_1, \ldots, \alpha_{n-1}, \alpha)$ such that the following properties hold:

- (1) $\tau(\alpha_1, \ldots, \alpha_{n-1}, \alpha)$ is a function $\beta \mapsto \tau(\alpha_1, \ldots, \alpha_{n-1}, \alpha)(\beta)$ defined for all $\beta \in \alpha$.
- (2) $\tau(\alpha_1,\ldots,\alpha_{n-1},\alpha)(0) = \sigma(\alpha_1,\ldots,\alpha_{n-1}).$
- (3) For every ordinal β with $\beta + 1 \in \alpha$,

$$\tau(\alpha_1,\ldots,\alpha_{n-1},\alpha)(\beta+1)=\mu(\alpha_1,\ldots,\alpha_{n-1},\tau(\alpha_1,\ldots,\alpha_{n-1},\alpha)(\beta)).$$

(4) For every limit ordinal $\beta \in \alpha$,

$$\tau(\alpha_1,\ldots,\alpha_{n-1},\alpha)(\beta) = \bigcup_{\gamma\in\beta}\tau(\alpha_1,\ldots,\alpha_{n-1},\alpha)(\gamma).$$

Observe that $\tau(\alpha_1, \ldots, \alpha_{n-1}, \alpha)$ is defined for *fixed* ordinals $\alpha_1, \ldots, \alpha_{n-1}$ and $\alpha \neq 0$, but is only a function of one argument $\beta \in \alpha$. This fact is crucial for allowing the use of the axiom of replacement and in proving that the set whose existence is guaranteed by this axiom is actually a function. It can also be shown that for any two ordinals η_1 and η_2 , if $\eta_1 \neq 0$ and $\eta_1 \in \eta_2$, then

$$\tau(\alpha_1, \ldots, \alpha_{n-1}, \eta_1)(\beta) = \tau(\alpha_1, \ldots, \alpha_{n-1}, \eta_2)(\beta)$$
 for all $\beta \in \eta_1$.

So intuitively $\tau(\alpha_1, \ldots, \alpha_{n-1}, \alpha)$ is the "same function" for all $\alpha \neq 0$. But the collection of all ordinals is not a set so we can't refer to it as a function on all ordinals. For a detailed exposition with proofs, see Suppes [70] (Section 7.1, Theorems 8-12). We now show how to use Theorem A.25 to define addition, multiplication, and exponentiation of ordinals. After each definition, transfinite induction (Second Formulation) is needed to prove various properties of these operations. Although not very difficult, some of these proofs are quite involved and we refer the reader to Suppes [70] for details.

We begin with the definition of addition.

Definition A.19. The operation of *addition* on the ordinals, denoted +, is defined by transfinite recursion as follows: for any two ordinals α, β we have

(1) $\alpha + 0 = \alpha$.

(2)
$$\alpha + (\beta + 1) = (\alpha + \beta) + 1.$$

(3) If β is a limit ordinal, then

$$\alpha + \beta = \bigcup_{\gamma \in \beta} \alpha + \gamma.$$

In Clause (2), there is a slight ambiguity since the symbol + is used with two different meanings. The occurrence of + between α and $(\beta + 1)$ is the addition of ordinals, but the ordinal $\beta + 1$ denotes the successor $\beta^+ = \beta \cup \{\beta\}$ of the ordinal β . To be perfectly clear, (2) should be written as

$$\alpha + \beta^+ = (\alpha + \beta)^+.$$

We will often use the notation $\beta + 1$ instead of β^+ , adding parentheses if necessary for clarity.

Here is how Theorem A.25 is used to justify Definition A.19. We let

$$\sigma(\alpha_1) = \alpha_1$$
$$\mu(\alpha_1, \alpha_2) = \alpha_2^+,$$

and the function $\tau(\alpha, \beta^+)$, where in $\tau(\alpha_1, \alpha)$ we substitute α for α_1 and β^+ for α , is defined as a function on β^+ by the clauses

- (1) $\tau(\alpha, \beta^+)(0) = \sigma(\alpha) = \alpha$.
- (2) For η such that $\eta^+ \in \beta^+$, namely $\eta \in \beta$,

$$\tau(\alpha,\beta^+)(\eta^+) = \mu(\alpha,\tau(\alpha,\beta^+)(\eta)) = (\tau(\alpha,\beta^+)(\eta))^+.$$

(3) If $\eta \in \beta^+$ is a limit ordinal, then

$$\tau(\alpha, \beta^+)(\eta) = \bigcup_{\gamma \in \eta} \tau(\alpha, \beta^+)(\gamma).$$

Then by definition

$$\alpha + \beta = \tau(\alpha, \beta^+)(\beta).$$

Observe that Definition A.19 is just the familiar recursive definition of addition on the natural numbers, except that a new clause is added to deal with limit ordinals. As we will see, this new clause makes a big difference in the behavior of addition on infinite ordinals.

Actually it is not obvious that Definition A.19 yields an ordinal. Fortunately this is the case.

Proposition A.26. For any two ordinals α, β , the term $\alpha + \beta$ is an ordinal.

We will shortly list a number of properties of ordinal addition. As we will see, there are a few surprises. But first let us figure out a few additions.

Example A.4. Since ω is the set of natural numbers, we can write

$$\omega = \{0, 1, 2, \dots, n, \dots\},\$$

with $1 = \{0\}, 2 = \{0, 1\}, \dots, n + 1 = \{0, 1, \dots, n\}$, so

$$\omega + 1 = \omega^+ = \omega \cup \{\omega\} = \{0, 1, 2, \dots, n, \dots, \omega\}.$$

Then

$$\omega + 2 = (\omega + 1)^{+} = \omega + 1 \cup \{\omega + 1\} = \{0, 1, 2, \dots, n, \dots, \omega, \omega + 1\}.$$

More generally, for any natural number n,

$$\omega + (n+1) = (\omega + n)^{+} = \omega + n \cup \{\omega + n\} = \{0, 1, 2, \dots, n, \dots, \omega, \omega + 1, \dots, \omega + n\}.$$

So $\omega + (n + 1)$ is a "longer" ordinal than ω . Intuitively, after running through a first track consisting of a copy of ω , we switch to a second track consisting of copies of $0, 1, \ldots, n$. So we can figure out what $\omega + \omega$ is, since

$$\omega + \omega = \bigcup_{n \in \omega} \omega + n = \{0, 1, 2, 3, \dots, \omega, \omega + 1, \omega + 2, \omega + 3, \dots\}.$$

We can think of $\omega + \omega$ as consisting of two parallel tracks, each consisting of a copy of ω . After running through the first track, we switch to the second track.

We can now figure out what is $(\omega + \omega) + n$, which is left an exercise to the reader. Then we obtain $(\omega + \omega) + \omega$, which is

$$(\omega + \omega) + \omega = \bigcup_{n \in \omega} (\omega + \omega) + n$$

= {0, 1, 2, 3, ..., ω , $\omega + 1$, $\omega + 2$, $\omega + 3$, ...,
 $\omega + \omega$, $(\omega + \omega) + 1$, $(\omega + \omega) + 2$, $(\omega + \omega) + 3$, ...}.

This time we have three parallel tracks of ω 's. As we will see later, we can even have ω tracks of ω 's; this is $\omega \cdot \omega$, the product of ω by ω . We can also have much wilder ordinals.

Let us now figure out what $n + \omega$ is, where n is a natural number. We are in for a surprise.

Example A.5. First, we easily check that for any two natural numbers (finite ordinals) m and n, m + n as given by Definition A.19 is just the usual sum of m and n. Then

$$0 + \omega = \bigcup_{n \in \omega} 0 + n = \bigcup_{n \in \omega} n = \omega.$$

So far, no surprise. Now

$$1 + \omega = \bigcup_{n \in \omega} 1 + n = \bigcup_{n \in \omega} n + 1.$$

But $n + 1 = \{0, \dots, n\}$, so

$$\bigcup_{n\in\omega}n+1=\omega$$

Thus we proved that

$$1 + \omega = \omega,$$

which shows that addition of ordinals is not commutative, since

$$1 + \omega = \omega \neq \omega + 1.$$

Similarly we easily show that

$$n + \omega = \omega$$

for all natural number n.

Since

$$1 + \omega = 2 + \omega,$$

we see that contrary to the natural numbers $\alpha + \gamma = \beta + \gamma$ does not imply that $\alpha = \beta$.

Now some desirable properties. All proofs are by transfinite induction.

Proposition A.27. For all ordinals α , we have

$$\alpha + 0 = 0 + \alpha = \alpha.$$

Although Proposition A.27 is intuitively obvious, a proof by transfinite induction, although simple, takes about half a page since it is necessary to treat separately the three cases of the induction, and the corresponding three cases of the recursive definition.

Proposition A.28. For all ordinals α, β , we have

$$\alpha + (\beta + 1) = (\alpha + \beta) + 1,$$

or equivalently

 $\alpha + \beta^+ = (\alpha + \beta)^+,$

As a corollary,

$$\alpha + 1 = \alpha^+$$

Proposition A.29. For all ordinals α, β, γ , if $\beta \in \gamma$, then $\alpha + \beta \in \alpha + \gamma$.

It should be noted that the implication, if $\beta \in \gamma$, then $\beta + \alpha \in \gamma + \alpha$, is *false*. For example, $1 \in 2$, but

$$1 + \omega = 2 + \omega = \omega.$$

Proposition A.30. For all ordinals α, β , if $\beta \neq 0$, then $\alpha \in \alpha + \beta$.

Proposition A.31. For all ordinals α, β, γ , if $\alpha + \beta = \alpha + \gamma$, then $\beta = \gamma$.

Cancellation from the right is *false*. For example, $1 + \omega = 2 + \omega = \omega$ does *not* imply that 1 = 2.

Proposition A.32. For all ordinals α, β, γ , if $\alpha \subseteq \beta$, then $\alpha + \gamma \subseteq \beta + \gamma$. As a corollary,

$$\beta \in \alpha + \beta$$
.

Proposition A.33. For all ordinals α , β , if β is a limit ordinal, then $\alpha + \beta$ is a limit ordinal.

Proposition A.34. For all ordinals α, β , if $\alpha \subseteq \beta$, then there is a unique γ that $\alpha + \gamma = \beta$.

Proposition A.35. For all ordinals α, β, γ , if $\beta \neq 0$, then there is no ordinal γ such that for all $\delta < \beta$,

 $\alpha + \delta < \gamma < \alpha + \beta.$

Proposition A.36. (Associativity of addition) For all ordinals α, β, γ ,

$$\alpha + (\beta + \gamma) = (\alpha + \beta) + \gamma.$$

As we already showed, addition is *not* commutative. For example,

$$\omega = 1 + \omega \neq \omega + 1.$$

Next we define multiplication.

Definition A.20. The operation of *multiplication* on the ordinals, denoted \cdot , is defined by transfinite recursion as follows: for any two ordinals α, β we have

- (1) $\alpha \cdot 0 = 0.$
- (2) $\alpha \cdot (\beta + 1) = (\alpha \cdot \beta) + \alpha$.
- (3) If β is a limit ordinal, then

$$\alpha \cdot \beta = \bigcup_{\gamma \in \beta} \alpha \cdot \gamma.$$

We leave it as an exercise to justify Definition A.20 using Theorem A.25.

Clause (2) may be written perhaps more clearly as

$$\alpha \cdot \beta^+ = (\alpha \cdot \beta) + \alpha.$$

Observe that Definition A.20 is just the familiar recursive definition of multiplication on the natural numbers, except that a new clause is added to deal with limit ordinals. As in the case of addition, this new clause makes a big difference in the behavior of multiplication on infinite ordinals.

Proposition A.37. For any two ordinals α, β , the term $\alpha \cdot \beta$ is an ordinal.

Proposition A.38. For all ordinals α , we have

$$0 \cdot \alpha = \alpha \cdot 0 = 0.$$

Proposition A.39. For all ordinals α , we have

$$1 \cdot \alpha = \alpha \cdot 1 = \alpha.$$

As in the case of addition let us figure out a few multiplications.

Example A.6. We begin by computing $\omega \cdot 2$. Since $2 = 1^+ = 1 + 1$, according to Clause (2) of Definition A.20, we have

$$\omega \cdot 2 = \omega \cdot 1^+ = \omega \cdot 1 + \omega$$

Since by Proposition A.38, $\omega \cdot 1 = \omega$, we get

$$\omega \cdot 2 = \omega + \omega.$$

Similarly, for every natural number n,

$$\omega \cdot (n+1) = \omega \cdot n^+ = \omega \cdot n + \omega.$$

So by induction (and using associativity of addition), for any natural number $n \ge 1$, we get

$$\omega \cdot n = \underbrace{\omega + \dots + \omega}_{n}$$

We can view $\omega \cdot n$ as n infinite parallel tracks each in bijection with ω , namely for all $n \geq 1$,

$$\begin{split} \omega \cdot n &= \{ 0, 1, 2, 3, \dots, \\ \omega, \omega + 1, \omega + 2, \omega + 3, \dots, \\ \omega \cdot 2, \omega \cdot 2 + 1, \omega \cdot 2 + 2, \omega \cdot 2 + 3, \dots, \\ \vdots \\ \omega \cdot (n-1), \omega \cdot (n-1) + 1, \omega \cdot (n-1) + 2, \omega \cdot (n-1) + 3, \dots, \}. \end{split}$$

If we define the set $[n-1] \times \omega$ for $n \ge 1$ as

$$[n-1] \times \omega = \{(i,p) \mid 0 \le i \le n-1, \ p \in \omega\},\$$

then we have a bijection from $[n-1] \times \omega$ to $\omega \cdot n$, obtained by mapping (i, p) to $\omega \cdot i + p$. This is an order isomorphism if we define the ordering on $[n-1] \times \omega$ as

$$(i,p) \le (j,q)$$
 iff $\begin{cases} i = j \text{ and } p = q, \text{ or } \\ i < j, \text{ or } \\ i = j \text{ and } p < q . \end{cases}$

Example A.7. Let us now compute $\omega \cdot \omega$. According to Clause (3) of Definition A.20, we have

$$\omega \cdot \omega = \bigcup_{m \in \omega} \omega \cdot m$$

If we define the usual cartesian product $\omega \times \omega$ as

$$\omega \times \omega = \{ (m, n) \mid m \in \omega, n \in \omega \}$$

then we have a bijection from $\omega \times \omega$ to $\omega \cdot \omega$, where (m, n) goes to $\omega \cdot m + n$. This is an order isomorphism if we define the ordering on $\omega \times \omega$ as

$$(m_1, n_1) \le (m_2, n_2)$$
 iff $\begin{cases} m_1 = m_2 \text{ and } n_1 = n_2, \text{ or} \\ m_1 < m_2, \text{ or} \\ m_1 = m_2 \text{ and } n_1 < n_2 . \end{cases}$

This is precisely the total order of Example A.1(4). This ordering is called the *left lexicographic ordering*, usually abbreviated as *lexicographic ordering*. Observe that we can visualize $\omega \cdot \omega$ as an infinite 2-dimensional lattice of integral points (m, n) consisting of parallel track, where the (m + 1)th track consists of the points $\omega \cdot m + n$.

We will see later that it may be more convenient to consider the bijection $(m, n) \mapsto \omega \cdot n + m$. This time we need to use the *right lexicographic ordering* given by

$$(m_1, n_1) \le (m_2, n_2)$$
 iff $\begin{cases} m_1 = m_2 \text{ and } n_1 = n_2, \text{ or} \\ n_1 < n_2, \text{ or} \\ n_1 = n_2 \text{ and } m_1 < m_2 \end{cases}$.

In a similar way, we can show that $(\omega \cdot \omega) \cdot \omega$ is a 3D grid with integral points (m_1, m_2, m_3) , where we use the bijection between $\omega \times \omega \times \omega$ and $(\omega \cdot \omega) \cdot \omega$ given by $(m_1, m_2, m_3) \mapsto \omega^2 \cdot m_3 + \omega \cdot m_2 + m_1$, with the right lexicographic ordering on triples of natural numbers given by

$$(p_1, p_2, p_3) \le (q_1, q_2, q_3) \quad \text{iff} \quad \left\{ \begin{array}{l} p_1 = q_1, \ p_2 = q_2, \ p_3 = q_3 \text{ or} \\ \exists k, \ 1 \le k \le 3, \ p_i = q_i, \ k+1 \le i \le 3, \text{ and } p_k < q_k. \end{array} \right.$$

The advantage of the right lexicographic ordering is the following. We have the natural inclusion of $\omega \times \omega$ into $\omega \times \omega \times \omega$ given by $(m_1, m_2) \mapsto (m_1, m_2, 0)$, and since

$$\omega^2 \cdot 0 + \omega \cdot m_2 + m_1 = \omega \cdot m_2 + m_1,$$

we see that the restriction of the right lexicographic ordering on $\omega \times \omega \times \omega$ agrees with the right lexicographic ordering on $\omega \times \omega$, and we also have $(m_1, m_2, 0) < (n_1, n_2, n_3)$ for any $n_3 > 0$. This time the points (m_1, m_2, m_3) belong to a 3D grid consisting of parallel horizontal layers which are lattices. So the points $(m_1, m_2, 0)$ are in the first layer, and the points (m_1, m_2, m_3) with $m_3 \neq 0$ belong to the $(m_3 + 1)$ th horizontal layer with corner point $\omega^2 \cdot m_3$, which is a copy of the bottom layer, except that $\omega^2 \cdot m_3 + \omega \cdot m_2 + m_1$ belongs to the $(m_2 + 1)$ th track of the m_3 th horizontal layer.

More generally, we can figure out that the *n*-fold product $(\cdots (\omega \cdot \omega) \cdot \cdots \cdot \omega)$ is an *n*dimensional grid with integral points (m_1, \ldots, m_n) , with the right lexicographic ordering on *n*-tuples of natural numbers. See Example A.10 for details. This is harder to visualize for n > 3. This product is also denoted as ω^n ; it is indeed the result of exponentiating ω , as we will see later. It is also easy to see that $\omega^n \in \omega^{n+1}$. Thus an unhealthy curiosity leads us to ask what is

$$\bigcup_{n\in\omega}\omega^n.$$

Naturally this is the ordinal ω^{ω} , as we will see when we introduce ordinal exponentiation. This ordinal is even harder to visualize, since it is an infinite dimensional grid!

Example A.8. Let us now compute $2 \cdot \omega$, Since ω is a limit ordinal we have

$$2 \cdot \omega = \bigcup_{n \in \omega} 2 \cdot n = \bigcup_{n \in \omega} 2n.$$

But

$$2n = \{0, 1, 2 \dots, 2n - 1\}$$

for $n \ge 1$, and so

$$2 \cdot \omega = \bigcup_{n \in \omega} 2n = \omega.$$

In a similar way, for any natural number $n \ge 1$, we have

$$n \cdot \omega = \omega.$$

The previous example shows that ordinal multiplication is *not commutative*, since

$$\omega = 2 \cdot \omega \neq \omega \cdot 2 = \omega + \omega.$$

Here are more properties of ordinal multiplication.

Proposition A.40. For all ordinals α, β, γ , if $\alpha \neq 0$ and $\beta \in \gamma$, then $\alpha \cdot \beta \in \alpha \cdot \gamma$. As a corollary, if $\alpha \neq 0$ and $\beta \neq 0$, then $\alpha \cdot \beta \neq 0$.

Proposition A.41. (Left cancellation) For all ordinals α, β, γ , if $\alpha \neq 0$ and $\alpha \cdot \beta = \alpha \cdot \gamma$, then $\beta = \gamma$.

However, right cancellation fails. For example,

$$\omega = 2 \cdot \omega = 3 \cdot \omega,$$

yet $2 \neq 3$.

Proposition A.42. For all ordinals α, β , if $\alpha \neq 0$ and β is a limit ordinal, then $\alpha \cdot \beta$ is a limit ordinal.

Proposition A.43. For all ordinals α, β , if α is a limit ordinal and $\beta \neq 0$, then $\alpha \cdot \beta$ is a limit ordinal.

Proposition A.44. (Distributivity of multiplication from the left) For all ordinals α, β, γ ,

$$\alpha \cdot (\beta + \gamma) = \alpha \cdot \beta + \alpha \cdot \gamma.$$

On the other hand distributivity of multiplication from the right fails. For example,

$$(1+1) \cdot \omega = 2 \cdot \omega = \omega \neq \omega + \omega = 1 \cdot \omega + 1 \cdot \omega$$

We finish with a nice positive fact.

Proposition A.45. (Associativity of multiplication) For all ordinals α, β, γ ,

$$(\alpha \cdot \beta) \cdot \gamma = \alpha \cdot (\beta \cdot \gamma).$$

Finally we define exponentiation.

Definition A.21. The operation of *exponentiation* on the ordinals, denoted α^{β} , is defined by transfinite recursion as follows: for any two ordinals α, β we have

(1) $\alpha^0 = 1.$

(2)
$$\alpha^{\beta+1} = \alpha^{\beta} \cdot \alpha$$
.

(3) If β is a limit ordinal and $\alpha \neq 0$, then

$$\alpha^{\beta} = \bigcup_{\gamma \in \beta} \alpha^{\gamma}.$$

(4) If β is a limit ordinal and $\alpha = 0$, then

$$\alpha^{\beta} = 0.$$

We leave it as an exercise to justify Definition A.21 using Theorem A.25.

Clause (2) may be written perhaps more clearly as

$$\alpha^{(\beta^+)} = \alpha^\beta \cdot \alpha.$$

Observe that Definition A.21 is just the familiar recursive definition of exponentiation on the natural numbers, except that new clauses are added to deal with limit ordinals. As in the case of multiplication, these new clauses make a big difference in the behavior of exponentiation on infinite ordinals.

Proposition A.46. For any two ordinals α, β , the term α^{β} is an ordinal.

Proposition A.47. For any ordinal α , we have $\alpha^1 = \alpha$.

Proposition A.48. For any ordinal β , if $\beta \neq 0$, then $0^{\beta} = 0$.

Proposition A.49. For any ordinal α , we have $1^{\alpha} = 1$.

Proposition A.50. For any ordinals α, β, γ , we have

$$\alpha^{\beta+\gamma} = \alpha^{\beta} \cdot \alpha^{\gamma}$$

Proposition A.51. For any ordinals α, β, γ , we have

$$(\alpha^{\beta})^{\gamma} = \alpha^{\beta \cdot \gamma}.$$

On the other hand, the identity

$$(\alpha \cdot \beta)^{\gamma} = \alpha^{\gamma} \cdot \beta^{\gamma}$$

is false in general. We leave it as an exercise to show that

$$(\omega \cdot 2)^2 \neq \omega^2 \cdot 2^2.$$

To get started, note that

$$(\omega \cdot 2)^2 = (\omega \cdot 2) \cdot (\omega \cdot 2) = (\omega \cdot 2) \cdot (\omega + \omega)$$

= $(\omega \cdot 2) \cdot \omega + (\omega \cdot 2) \cdot \omega = \omega \cdot (2 \cdot \omega) + \omega \cdot (2 \cdot \omega)$
= $\omega \cdot \omega + \omega \cdot \omega = \omega^2 \cdot 2.$

Proposition A.52. For any ordinals α, β , if $1 \in \alpha$ and $\beta \in \gamma$, then $\alpha^{\beta} \in \alpha^{\gamma}$.

Proposition A.53. For any ordinals α, β , if $1 \in \alpha$ and $1 \in \beta$, then

$$\alpha + \beta \subseteq \alpha \cdot \beta \subseteq \alpha^{\beta}.$$

Example A.9. For any ordinal α , let us compute α^2 . By Clause (2) of Definition A.21 and Proposition A.47, we have

$$\alpha^2 = \alpha^{(1^+)} = \alpha^1 \cdot \alpha = \alpha \cdot \alpha.$$

In general, for any natural number n, we have

$$\alpha^{n+1} = \alpha^{(n^+)} = \alpha^n \cdot \alpha.$$

By induction and associativity of multiplication, this yields

$$\alpha^n = \underbrace{\alpha \cdots \alpha}_n,$$

for any natural number $n \ge 1$. In particular, if $\alpha = \omega$, we have

$$\omega^{n+1} = \omega^n \cdot \omega = \bigcup_{n \in \omega} \omega^n \cdot n$$

This shows that $\omega^n \in \omega^{n+1}$.

Example A.10. By Clause (3) of Definition A.21, we have

$$\omega^{\omega} = \bigcup_{n \in \omega} \omega^n.$$

As we mentioned in Example A.7, we can view ω^n $(n \ge 1)$ as the set of *n*-tuples of natural numbers (m_1, \ldots, m_n) , under the bijection

$$(m_1,\ldots,m_n)\mapsto\omega^{n-1}\cdot m_n+\omega^{n-2}\cdot m_{n-1}+\cdots+\omega^1\cdot m_2+m_1,$$

with the right lexicographic ordering given by

$$(p_1, \dots, p_n) \le (q_1, \dots, q_n)$$
 iff $\begin{cases} p_i = q_i, \ 1 \le i \le n, \ \text{or} \\ \exists k, 1 \le k \le n, \ p_i = q_i, \ k+1 \le i \le n, \ \text{and} \ p_k < q_k. \end{cases}$

Thus we can view ω^{ω} as the set of countably infinite sequences of natural numbers $(p_i)_{i\in\omega}$ (with $p_i \in \omega$) such that there is some $n \ge 0$ and $p_i = 0$ for all $i \ge n$. Given any two such sequences $(p_i)_{i\in\omega}$ and $(q_i)_{i\in\omega}$, there is some smallest $N \ge 1$ such that $p_i = 0$ and $q_i = 0$ for all $i \ge N$, so we compare $(p_i)_{i\in\omega}$ and $(q_i)_{i\in\omega}$ with the right lexicographic ordering on ω^N .

There is a better way to describe this ordering due to Dershowitz and Manna, which is to view the elements of ω^{ω} as finite multisets of elements in ω . Indeed, we can view a countably infinite sequence $(p_i)_{i\in\omega}$ as above as the *finite multiset* M of elements of ω consisting of the $i \in \omega$ that occur $p_i > 0$ times. If $p_i = 0$, then i is not an element of M.

A.5 Multisets, Nested Multisets and the Ordinal ϵ_0

Actually, in order to generalize multisets to nested multisets it is more convenient to define finite multisets as partial functions of finite domain with range $\mathbb{N}_+ = \mathbb{N} - \{0\}$,

Definition A.22. Given a nonempty set S, a finite multiset M on S is either the empty set of a finite nonempty set $M = \{(s_1, m_1), \ldots, (s_n, m_n)\}$ of pairs (s_i, m_i) , with $m_i > 0$ for $i = 1, \ldots, n$, and where $\{s_1, \ldots, s_n\}$ is a finite nonempty subset of S called the *domain of* M and denoted dom(M). We say that $s_i \in S$ occurs m_i times in M. The set of all finite multisets on S is denoted by $\mathcal{M}(S)$.

We usually denote a multiset $M = \{(s_1, m_1), \ldots, (s_n, m_n)\}$ as a "set with repetitions," that is, as any expression

$$\{s_1,\ldots,s_1,s_2,\ldots,s_2,\ldots,s_n,\ldots,s_n\}$$

with $m_1 + \cdots + m_n$ occurences of elements of S, where s_i occurs m_i times for $i = 1, \ldots, n$. The order of the elements is irrelevant.

Example A.11. Let $S = \omega$. The multiset $\{3, 3, 4, 0\}$ is one way of representing the official multiset $\{(0, 1), (3, 2), (4, 1)\}$, so 4 occurs once, 3 occurs twice, and 0 occurs once. The multiset $\{(0, 1), (3, 2), (4, 1)\}$ corresponds to the ordinal

$$\omega^4 \cdot 1 + \omega^3 \cdot 2 + 1.$$

As a function from ω to \mathbb{N} , the multiset $\{3, 3, 4, 0\}$ is also represented by the sequence $(1, 0, 0, 2, 1, 0, \dots, 0, \dots)$. The multiset $\{2, 2, 3, 4, 0, 0, 1\}$ is one way of representing the official multiset $\{(0, 2), (1, 1), (2, 2), (3, 1), (4, 1)\}$, so 4 occurs once, 3 occurs once, 2 occurs twice, 1 occurs once, and 0 occurs twice. The multiset $\{(0, 2), (1, 1), (2, 2), (3, 1), (4, 1)\}$, corresponds to the ordinal

$$\omega^4 \cdot 1 + \omega^3 \cdot 1 + \omega^2 \cdot 2 + \omega^1 \cdot 1 + 2.$$

As a function from ω to \mathbb{N} , the multiset $\{(0,2), (1,1), (2,2), (3,1), (4,1)\}$ is also represented by the sequence $(2, 1, 2, 1, 1, 0, \dots, 0, \dots)$.

Some operations on multisets are defined below.

Definition A.23. Given any nonempty set S, for any two finite multisets $M_1, M_2 \in \mathcal{M}(S)$, we say that M_1 is a submultiset of M_2 , written $M_1 \subseteq M_2$, if $M_1 = \emptyset$, or dom $(M_1) \subseteq \text{dom}(M_2)$ and for any $(s, m) \in M_1$, we have $(s, m') \in M_2$ with $m \leq m'$. The union $M_1 \cup M_2$ of the multisets M_1 and M_2 is the multiset defined by

$$(M_1 \cup M_2) = \{(s,m) \mid s \in \operatorname{dom}(M_1) - \operatorname{dom}(M_2), (s,m) \in M_1\} \\ \cup \{(s,m) \mid s \in \operatorname{dom}(M_2) - \operatorname{dom}(M_1), (s,m) \in M_2\} \\ \cup \{(s,m+m') \mid s \in \operatorname{dom}(M_1) \cap \operatorname{dom}(M_2), (s,m) \in M_1, (s,m') \in M_2\}.$$

The difference $M_1 - M_2$ of the multisets M_1 and M_2 is the multiset defined by

$$M_1 - M_2 = \{(s,m) \mid s \in \operatorname{dom}(M_1) - \operatorname{dom}(M_2), (s,m) \in M_1\} \\ \cup \{(s,m-m') \mid s \in \operatorname{dom}(M_1) \cap \operatorname{dom}(M_2), (s,m) \in M_1, (s,m') \in M_2, m > m'\}.$$

Then the multiset ordering on finite multisets of elements of a partially ordered set (S, \leq) is defined as follows.

Definition A.24. Let (S, \leq) be any partially ordered set. For any two finite multisets M_1 and $M_2 \in \mathcal{M}(S)$, we have $M_1 \leq M_2$ iff either $M_1 = M_2$, or there exist two finite multisets $X, Y \in \mathcal{M}(S)$, with $X \neq \emptyset$ and $X \subseteq M_2$, such that

- (1) $M_1 = (M_2 X) \cup Y.$
- (2) For every $y \in \text{dom}(Y)$, there is some $x \in \text{dom}(X)$ such that y < x.

Example A.12. Since

(2, 1, 2, 1, 1) < (1, 0, 0, 2, 1)

in the right lexicographic ordering, we have

$$\{2, 2, 3, 4, 0, 0, 1\} \prec \{3, 3, 4, 0\}$$

Indeed, one occurrence of 3 is deleted from the greater multiset, so $X = \{3\}$, the elements in $Y = \{0, 1, 2, 2\}$ are added to the smaller multiset, and 0, 1, 2 < 3.

The mapping

$$\{(s_1, m_1), \dots, (s_n, m_n)\} \mapsto \omega^{s_n} \cdot m_n + \omega^{s_{n-1}} \cdot m_{n-1} + \dots + \omega^{s_1} \cdot m_1$$

with $s_1 < s_2 < \cdots < s_n$ and $m_i > 0$ is a bijection from $\mathcal{M}(\omega)$ to ω^{ω} (with $\emptyset \mapsto 0$), and we leave it as an exercise to check that the multiset ordering on $\mathcal{M}(\omega)$ corresponds to the well-ordering on ω^{ω} defined in terms of the right lexicographic ordering.

More generally, if α is an infinite ordinal, every finite multiset M on α is given by a set of pairs $\{(\gamma_1, m_1), \ldots, (\gamma_n, m_n)\}$, with $\gamma_i \in \alpha$, $m_i > 0$, and $\gamma_1 \in \gamma_2 \in \cdots \in \gamma_n$ (with $\emptyset \mapsto 0$), so the map

$$\{(\gamma_1, m_1), \dots, (\gamma_n, m_n)\} \mapsto \omega^{\gamma_n} \cdot m_n + \omega^{\gamma_{n-1}} \cdot m_{n-1} + \dots + \omega^{\gamma_1} \cdot m_n$$

is a bijection from $\mathcal{M}(\alpha)$ to ω^{α} , and the multiset ordering on $\mathcal{M}(\alpha)$ corresponds to the ordering on ω^{α} .

It should be noted that if $S = \alpha$, since α is totally ordered, Clause (2) of Definition A.24 is equivalent to:

There is some $x \in \text{dom}(X)$ such that y < x for every $y \in \text{dom}(Y)$.

The advantage of Definition A.24 is that it also applies to multisets of elements from some *partially ordered* set (S, \leq) . In this case we do not require S to be totally ordered. However, we require S to be *well-founded*.

Definition A.25. A partially ordered set (S, \leq) is *well-founded* if every nonempty subset Y of S has a minimal element, which means that there is some $z \in Y$ such that for all $y \in Y$, if $y \leq z$, then y = z.

It is easy to see that if a partially ordered set (S, \leq) is well-founded, then there are no strictly infinite decreasing sequences

$$\cdots < s_{n+1} < s_n < \cdots < s_2 < s_1$$

of elements $s_i \in S$. Under the axiom of choice, since every set can be well-ordered (by Zermelo's theorem A.16), the above condition is equivalent to the condition of Definition A.25; see Levy [48] (Proposition 5.3). The analog of transfinite induction (Theorem A.3) also holds for well-founded sets. The proof is a simple modification of the proof of Theorem A.2. Dershowitz and Manna proved that if (S, \leq) is a well-founded partially ordered set, then so is the set $\mathcal{M}(S)$ of finite multisets under the multiset ordering.

Multisets and multiset orderings play an important role in proving the termination of programs and sets of rewrite rules used in automated theorem-proving.

Exponentiation can be used to define a very interesting ordinal denoted ϵ_0 , which plays an important role in consistency proofs of the axiomatization of arithmetic on the natural numbers known as *Peano arithmetic*; see Takeuti [71]. For any natural number m, define the ordinals ω_n as follows:

$$\omega_0 = 1$$
$$\omega_{n+1} = \omega^{\omega_n}.$$

So ω_n $(n \ge 1)$ is a stack of exponentials of height n. The ordinals ω_n are all limit ordinals and $\omega_n \in \omega^{\omega_n}$, since

$$\omega_{n+1} = \bigcup_{\beta \in \omega_n} \omega^{\beta}.$$

For example,

$$\omega_1 = \omega, \ \omega_2 = \omega^{\omega}, \ \omega_3 = \omega^{\omega^{\omega}}.$$

The ordering on ω_n can be understood in terms of *nested multisets*, as shown by Dershowitz and Manna. Roughly speaking, a nested multiset is either a multiset or a multiset whose elements are nested multisets.

Definition A.26. Technically, given a nonempty set S, we define $\mathcal{M}^{(i)}(S)$ by induction as follows:

$$\mathcal{M}^{(0)}(S) = S$$
$$\mathcal{M}^{(i+1)}(S) = S \cup \mathcal{M}(\mathcal{M}^{(i)}(S))$$

It is easily shown by induction that

$$\mathcal{M}^{(i)}(S) \subseteq \mathcal{M}^{(i+1)}(S) \quad \text{for all } i \ge 0.$$

The set of nested multisets on S is

$$\mathcal{M}^*(S) = \bigcup_{i \ge 0} \mathcal{M}^{(i)}(S).$$

For example, $3, \{1, 1, 2\} \in \mathcal{M}^{(1)}(\omega), \{5, 5, \{1, 2, 2\}\} \in \mathcal{M}^{(2)}(\omega)$, and $\{5, 5, \{1, 2, 2\}, \{2, 2, \{3, 3, 5\}, \{3, 3, 5\}\} \in \mathcal{M}^{(3)}(\omega)$.

The multiset ordering can be extended to an ordering on nested multisets.

Definition A.27. Let (S, \leq) be a nonempty partially ordered set. The relations \leq_i (and \prec_i , the strict order associated with \leq_i) on $\mathcal{M}^{(i)}(S)$ are defined inductively as follows:

- (a) $\preceq_0 = \leq$.
- (b) For any $i \ge 0$, if $M_1 \in \mathcal{M}^{(0)}(S) = S$ and $M_2 \in \mathcal{M}^{(i+1)}(S) S$, then

$$M_1 \prec_{i+1} M_2.$$

- (c) If $M_1, M_2 \in \mathcal{M}^{(i+1)}(S) S$, then $M_1 \leq_{i+1} M_2$ iff either $M_1 = M_2$, or there exist two finite nested multisets $X, Y \in \mathcal{M}^{(i+1)}(S)$, with $X \neq \emptyset$ and $X \subseteq M_2$, such that
 - (1) $M_1 = (M_2 X) \cup Y$.
 - (2) For every $y \in \text{dom}(Y)$, there is some $x \in \text{dom}(X)$ such that $y \prec_i x$.

The relation \leq_* on $\mathcal{M}^*(S)$ is defined by

$$\preceq_* = \bigcup_{i \ge 0} \preceq_i .$$

Then it can be shown that if (S, \leq) is a well-founded partially ordered set, then so is $\mathcal{M}^*(S)$ under the ordering \leq_* of nested multisets.

Example A.13. The reader should check that

$$\{\{1,0,0\},5,\{\{0\},1,2\},0\}\prec_*\{\{1,1\},\{\{0\},1,2\},0\}$$

with $X = \{1, 1\}, Y = \{\{1, 0, 0\}, 5\}$, and

$$\{\{\emptyset, 1, 2\}, \{5, 5, 2\}, 5\} \prec_* \{\{1, 1\}, \{\{0\}, 1, 2\}, 0\}$$

with $X = \{\{1, 1\}, \{\{0\}, 1, 2\}, 0\}, Y = \{\{\emptyset, 1, 2\}, \{5, 5, 2\}, 5\}.$

We define the ordinal ϵ_0 as

$$\epsilon_0 = \bigcup_{n \in \omega} \omega_n.$$

For $S = \omega$, let $\nu_0: \omega \to \omega$ be the identity function, and for $i \ge 0$, define inductively the maps $\nu_{i+1}: \mathcal{M}^{(i+1)}(\omega) \to \omega_{i+1}$ such that $\nu_{i+1}(\emptyset) = 0$, for any nested multiset $M \in \mathcal{M}^{(i)}(\omega)$ we have

$$\nu_{i+1}(M) = \nu_i(M),$$

and for any nested multiset $M = \{(s_1, m_1), \ldots, (s_n, m_n)\} \in \mathcal{M}^{(i+1)}(\omega) - \mathcal{M}^{(i)}(\omega)$, where $m_j > 0, s_j \in \mathcal{M}^{(i)}(\omega)$, and $s_1 \prec_i s_2 \prec_i \cdots \prec_i s_n$, we set

$$\nu_{i+1}(M) = \omega^{\nu_i(s_n)} \cdot m_n + \omega^{\nu_i(s_{n-1})} \cdot m_{n-1} + \dots + \omega^{\nu_i(s_1)} \cdot m_1$$

Also define $\nu \colon \mathcal{M}^*(\omega) \to \epsilon_0$ by

$$\nu = \bigcup_{i \ge 0} \nu_i.$$

Example A.14. If $M = \{\{5,1\}, \{1,2,3\}, \{1,2,3\}, 2\} \in \mathcal{M}^{(2)}(\omega)$, we have $\nu_2(M) = \omega^{\nu_1(\{5,1\})} + \omega^{\nu_1(\{1,2,3\})} \cdot 2 + \omega^{\nu_1(2)}$.

We also have

$$\nu_1(\{5,1\}) = \omega^5 + \omega \nu_1(\{1,2,3\}) = \omega^3 + \omega^2 + \omega \nu_1(2) = 2,$$

so we get

$$\nu_2(M) = \omega^{\omega^5 + \omega} + \omega^{\omega^3 + \omega^2 + \omega} \cdot 2 + \omega^2.$$

The maps ν_i are not quite what we want because they are not injective. The problem is that the multiset consisting of m copies of 0 and the integer m both map to m. For example,

$$\nu_1(\{0,0,0\}) = \omega^0 \cdot 3 = 3 = \nu_1(3).$$

This minor problem is easily overcome. Define $\mathcal{M}^{+(i)}(S)$ by

$$\mathcal{M}^{+(i)}(S) = \mathcal{M}^{(i)}(S) - S_{i}$$

and $\mathcal{M}^+(S)$ by

$$\mathcal{M}^+(S) = \bigcup_{i \ge 1} \mathcal{M}^{+(i)}(S) = \mathcal{M}^*(S) - S.$$

Then it can be shown that ν_i is an order-isomorphism between $\mathcal{M}^{+(i)}(\omega)$ and ω_i $(i \geq 1)$ and that ν is an order-isomorphism between $\mathcal{M}^+(\omega)$ and ϵ_0 . The ordering on ϵ_0 is hard to understand, but it can be understood in terms of nested multisets. There are other notation systems for the ordinals less than ϵ_0 ; see Takeuti [71]. Amazingly, we also have the equation

$$\epsilon_0 = \omega^{\epsilon_0}$$

We conclude with a result of Cantor which generalizes the representation of the natural numbers in base b > 1. The proof is by transfinite induction.

A.6 Cantor Normal Form

Theorem A.54. (Cantor Normal Form) Let α be any ordinal such that $\alpha > 1$, which means that $1 \in \alpha$. Then for any ordinal $\beta \neq 0$, there is some natural number $k \geq 1$ and some unique sequences of ordinals $(\beta_1, \ldots, \beta_k)$ with $\beta_1 \in \beta_2 \in \cdots \in \beta_k$, and (μ_1, \ldots, μ_k) with $1 \leq \mu_i \in \alpha$ for $i = 1, \ldots, k$, such that

$$\beta = \alpha^{\beta_k} \cdot \mu_k + \alpha^{\beta_{k-1}} \cdot \mu_{k-1} + \dots + \alpha^{\beta_1} \cdot \mu_1.$$

Furthermore, for any η such that $\beta_k \in \eta$, we have $\beta \in \alpha^{\eta}$.

In most applications we pick $\alpha = \omega$. In this case the μ_i are natural numbers.

Recall that for $\beta = \epsilon_0$, we have

$$\epsilon_0 = \omega^{\epsilon_0}.$$

Suppose that $\beta_k \in \epsilon_0$ in the Cantor normal form of ϵ_0 . But then the second property of Theorem A.54 with $\eta = \epsilon_0$ would imply that $\epsilon_0 \in \omega^{\epsilon_0} = \epsilon_0$, a contradiction. Therefore the Cantor normal form of ϵ_0 is given by k = 1, $\beta_1 = \epsilon_0$, and $\mu_1 = 1$. Thus, unfortunately we can't ensure that $\beta_k \in \beta$ in the Cantor normal form for β . However, for every ordinal $\beta \in \epsilon_0$, it is true that the exponent β_k in the Cantor normal form for β has the property that $\beta_k \in \beta$, so this fact can be used to develop a notation system for all ordinals $\beta \in \epsilon_0$; see Takeuti [71]. One can go way beyond ϵ_0 , namely an ordinal denoted Γ_0 ; see Schütte [65] and Gallier [17].

The Cantor normal form can also be used to compare two ordinals β and γ . The idea is that the Cantor normal form

$$\beta = \alpha^{\beta_k} \cdot \mu_k + \alpha^{\beta_{k-1}} \cdot \mu_{k-1} + \dots + \alpha^{\beta_1} \cdot \mu_1$$

can be viewed as defining a finite sequence (μ_1, \ldots, μ_k) indexed by the increasing powers $\alpha^{\beta_1}, \ldots, \alpha^{\beta_k}$ (since $\beta_1 \in \beta_2 \in \cdots \in \beta_k$). If γ is another ordinal given by its normal form

$$\gamma = \alpha^{\gamma_{\ell}} \cdot \delta_{\ell} + \alpha^{\gamma_{\ell-1}} \cdot \delta_{\ell-1} + \dots + \alpha^{\gamma_1} \cdot \delta_1,$$

then it corresponds to the sequence $(\delta_1, \ldots, \delta_\ell)$ indexed by the increasing powers $\alpha^{\gamma_1}, \ldots, \alpha^{\gamma_\ell}$, with $\gamma_1 \in \gamma_2 \in \cdots \in \gamma_\ell$. If θ is the smallest of β_1 and γ_1 and σ is the largest of β_k and γ_ℓ , we can construct a finite increasing sequence of length L of powers of α ,

$$\alpha^{\theta_1}, \cdots, \alpha^{\theta_L}, \quad \theta_1 \in \theta_2 \in \cdots \in \theta_L,$$

starting with $\theta_1 = \theta$ and ending with $\theta_L = \sigma$, including all the α^{β_i} and α^{γ_j} (a single occurrence of α^{β_i} occurs if $\beta_i = \gamma_j$). Then we can form two sequences of length L, s_β and s_γ , where for $j = 1, \ldots, L$, we have

$$s_{\beta}(j) = \begin{cases} \beta_i & \text{if } \theta_j = \beta_i, \\ 0 & \text{otherwise,} \end{cases}$$

and

$$s_{\gamma}(j) = \begin{cases} \gamma_i & \text{if } \theta_j = \gamma_i, \\ 0 & \text{otherwise.} \end{cases}$$

Then we compare s_{β} and s_{γ} using the right lexicographic ordering. It is also possible to compare β and γ by scanning simultaneously their normal forms from left to right until the first "discrepancy" is found; see Levy [48] (Chapter 2, Theorem 2.14).

It is possible to define a notion of ordinal sum which is commutative. This notion known as *natural sum* due to Hessenberg (1906) is useful to define systems of ordinal notation; see Schütte [65] (Chapter VI, Section $\S16$).

Definition A.28. For any two nonzero ordinal α and β , if we write

$$\alpha = \omega^{\gamma_k} \cdot m_k + \omega^{\gamma_{k-1}} \cdot m_{k-1} + \dots + \omega^{\gamma_1} \cdot m_1$$

$$\beta = \omega^{\gamma_k} \cdot n_k + \omega^{\gamma_{k-1}} \cdot n_{k-1} + \dots + \omega^{\gamma_1} \cdot n_1,$$

with $\gamma_1 \in \gamma_2 \in \cdots \in \gamma_k$, $m_i, n_i \in \mathbb{N}$, and $m_i + n_i > 0$, for $i = 1, \ldots, k$, then we define the *natural sum* $\alpha \# \beta$ of α and β as

$$\alpha \# \beta = \omega^{\gamma_k} \cdot (m_k + n_k) + \omega^{\gamma_{k-1}} \cdot (m_{k-1} + n_{k-1}) + \dots + \omega^{\gamma_1} \cdot (m_1 + n_1).$$

Since we allow either $m_i = 0$ or $n_i = 0$ (but not both), we can use the same exponents $\gamma_1, \ldots, \gamma_k$ in both expansions. We also let

$$\alpha \# 0 = 0 \# \alpha = \alpha.$$

It can be shown that the natural sum is commutative and associative; see Levy [48] (Exercise 2.22).

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|X|, 616(MN), 114, 269 $(W, \varphi), 107$ (X, <), 612 $(X, \leq), 609-611$ $(\lambda x: \sigma. M), 114$ +, 6220, 130 $2^A, 61, 151$ $2^{a}, 617$ <, 611 =, 130A - B, 56, 152 $A \approx B, \, 617$ $A \cap B$, 56 $A \cup B, 56, 150$ $A \prec B, 618$ $A \preceq B, 617$ $A \succ B$, 618 $A \cap B$, 152 $A \subset B, 55, 151$ $A \subseteq B, 55, 151$ $A^+, 60, 150, 156$ $M = \{(s_1, m_1), \dots, (s_n, m_n)\}, 632$ $M[\varphi], 118, 273$ M[x := N], 119 $P(\tau_1, \ldots, \tau_n), 130$ $P[\tau/t], 132$ $P[\tau_1/t_1,\ldots,\tau_n/t_n], 49, 131$ P[u/t], 132, 133 $P \equiv Q, 130$ $P \Rightarrow Q, 17, 71, 130$

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