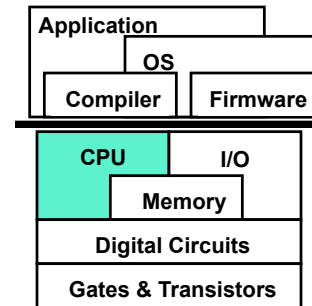


CIS 501 Computer Architecture

Unit 10: Hardware Multithreading

This Unit: Multithreading (MT)



- Why multithreading (MT)?
 - Utilization vs. performance
- Three implementations
 - Coarse-grained MT
 - Fine-grained MT
 - Simultaneous MT (SMT)

Readings

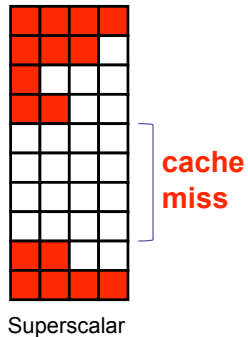
- H+P
 - Chapter 3.5-3.6
- Paper
 - Tullsen et al., "Exploiting Choice..."

Performance And Utilization

- Performance (IPC) important
- Utilization (actual IPC / peak IPC) important too
- Even moderate superscalars (e.g., 4-way) not fully utilized
 - Average sustained IPC: 1.5–2 → < 50% utilization
 - Mis-predicted branches
 - Cache misses, especially L2
 - Data dependences
- **Multi-threading (MT)**
 - Improve utilization by multi-plexing multiple threads on single CPU
 - One thread cannot fully utilize CPU? Maybe 2, 4 (or 100) can

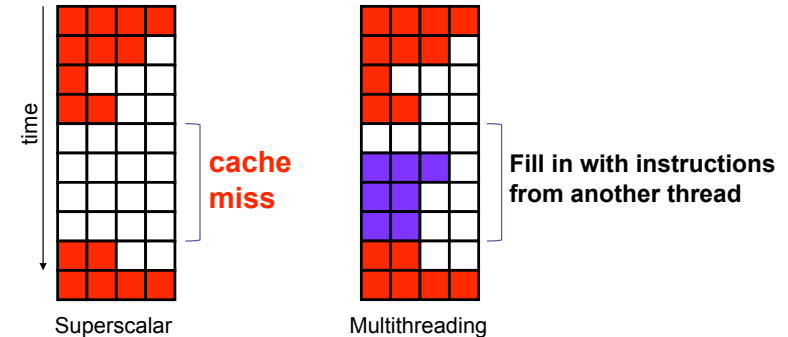
Superscalar Under-utilization

- Time evolution of issue slot
 - 4-issue processor



Simple Multithreading

- Time evolution of issue slot
 - 4-issue processor



- Where does it find a thread? Same problem as multi-core
 - Same shared-memory abstraction

Latency vs Throughput

- MT trades (single-thread) latency for throughput**
 - Sharing processor degrades latency of individual threads
 - + But improves aggregate latency of both threads
 - + Improves utilization
- Example
 - Thread A: individual latency=10s, latency with thread B=15s
 - Thread B: individual latency=20s, latency with thread A=25s
 - Sequential latency (first A then B or vice versa): 30s
 - Parallel latency (A and B simultaneously): 25s
 - MT slows each thread by 5s
 - + But improves total latency by 5s
- Different workloads have different parallelism**
 - SpecFP has lots of ILP (can use an 8-wide machine)
 - Server workloads have TLP (can use multiple threads)

MT Implementations: Similarities

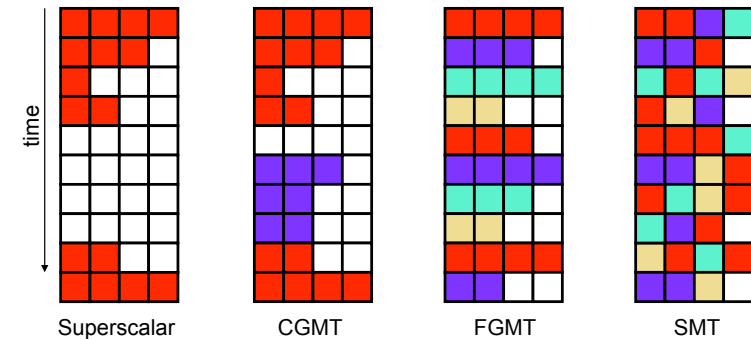
- How do multiple threads share a single processor?
 - Different sharing mechanisms for different kinds of structures
 - Depend on what kind of state structure stores
- No state:** ALUs
 - Dynamically shared
- Persistent hard state (aka "context"):** PC, registers
 - Replicated
- Persistent soft state:** caches, bpred
 - Dynamically partitioned (like on a multi-programmed uni-processor)
 - TLBs need thread ids, caches/bpred tables don't
 - Exception: **ordered "soft" state** (BHR, RAS) is replicated
- Transient state:** pipeline latches, ROB, RS
 - Partitioned ... somehow

MT Implementations: Differences

- Main question: **thread scheduling policy**
 - When to switch from one thread to another?
- Related question: **pipeline partitioning**
 - How exactly do threads share the pipeline itself?
- Choice depends on
 - What kind of latencies (specifically, length) you want to tolerate
 - How much single thread performance you are willing to sacrifice
- Three designs
 - Coarse-grain multithreading (CGMT)
 - Fine-grain multithreading (FGMT)
 - Simultaneous multithreading (SMT)

The Standard Multithreading Picture

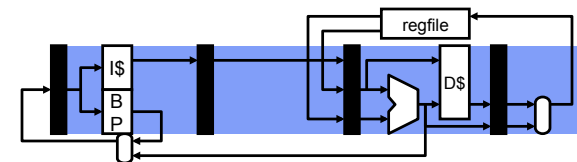
- Time evolution of issue slots
 - Color = thread



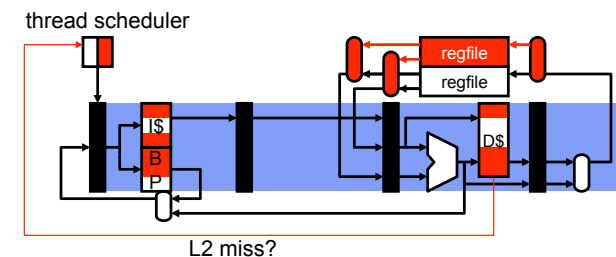
Coarse-Grain Multithreading (CGMT)

- **Coarse-Grain Multi-Threading (CGMT)**
 - + Sacrifices very little single thread performance (of one thread)
 - Tolerates only long latencies (e.g., L2 misses)
- Thread scheduling policy
 - Designate a "preferred" thread (e.g., thread A)
 - Switch to thread B on thread A L2 miss
 - Switch back to A when A L2 miss returns
- Pipeline partitioning
 - None, flush on switch
 - Can't tolerate latencies shorter than twice pipeline depth
 - Need short in-order pipeline for good performance
- Example: IBM Northstar/Pulsar

CGMT



- CGMT

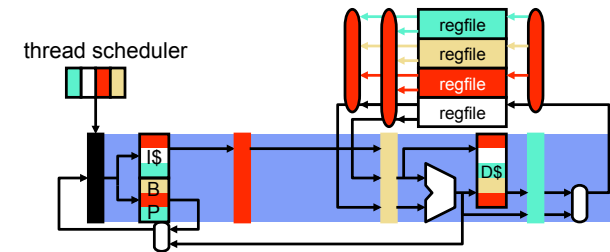


Fine-Grain Multithreading (FGMT)

- **Fine-Grain Multithreading (FGMT)**
 - Sacrifices significant single thread performance
 - + Tolerates latencies (e.g., L2 misses, mispredicted branches, etc.)
 - Thread scheduling policy
 - Switch threads every cycle (round-robin), L2 miss or no
 - Pipeline partitioning
 - Dynamic, no flushing
 - Length of pipeline doesn't matter so much
 - Need a lot of threads
 - Extreme example: Denelcor HEP
 - So many threads (100+), it didn't even need caches
 - Failed commercially
 - Not popular today
 - Many threads → many register files

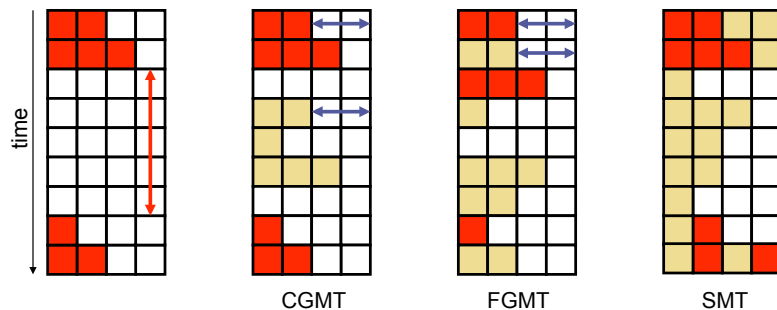
Fine-Grain Multithreading

- FGM
 - **Multiple threads in pipeline at once**
 - (Many) more threads



Vertical and Horizontal Under-Utilization

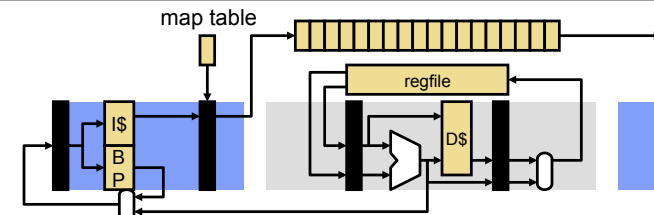
- FGM and CGMT reduce **vertical under-utilization**
 - Loss of all slots in an issue cycle
- Do not help with **horizontal under-utilization**
 - Loss of some slots in an issue cycle (in a superscalar processor)



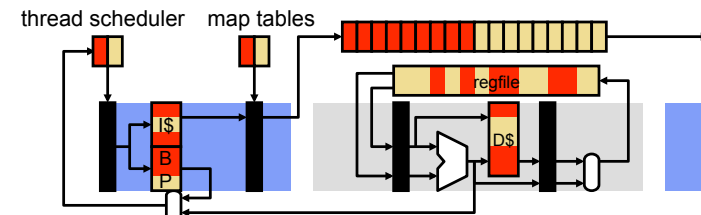
Simultaneous Multithreading (SMT)

- What can issue insns from multiple threads in one cycle?
 - Same thing that issues insns from multiple parts of same program...
 - ...out-of-order execution
- **Simultaneous multithreading (SMT):** OOO + FGMT
 - Aka **"hyper-threading"**
 - Observation: once insns are renamed, scheduler doesn't care which thread they come from (well, for non-loads at least)
 - Some examples
 - IBM Power5: 4-way issue, 2 threads
 - Intel Pentium4: 3-way issue, 2 threads
 - Intel "Nehalem": 4-way issue, 2 threads
 - Alpha 21464: 8-way issue, 4 threads (canceled)
 - Notice a pattern? #threads (T) * 2 = #issue width (N)

Simultaneous Multithreading (SMT)

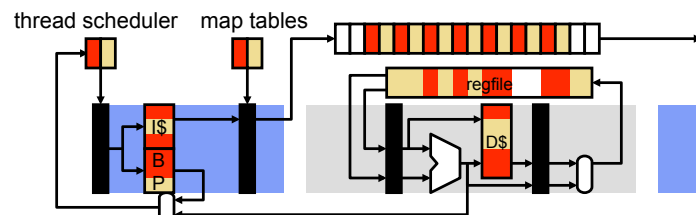


- SMT
 - Replicate map table, share (larger) physical register file



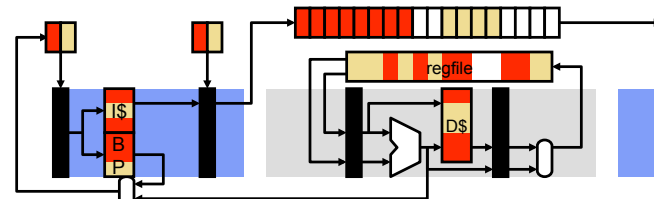
SMT Resource Partitioning

- Physical regfile and insn buffer entries shared at fine-grain
 - Physically unordered and so fine-grain sharing is possible
- How are physically ordered structures (ROB/LSQ) shared?
 - Fine-grain sharing (below) would entangle commit (and squash)
 - Allowing threads to commit independently is important



Static & Dynamic Resource Partitioning

- **Static partitioning** (below)
 - T equal-sized contiguous partitions
 - ± No starvation, sub-optimal utilization (fragmentation)
- **Dynamic partitioning**
 - P > T partitions, available partitions assigned on need basis
 - ± Better utilization, possible starvation
 - ICOUNT: fetch policy prefers thread with fewest in-flight insns
- Couple both with larger ROB/LSQs



Multithreading Issues

- Shared soft state (caches, branch predictors, TLBs, etc.)
- Key example: **cache interference**
 - General concern for all MT variants
 - Can the working sets of multiple threads fit in the caches?
 - Shared memory SPMD threads help here
 - + Same insns → share I\$
 - + Shared data → less D\$ contention
 - MT is good for workloads with shared insn/data
 - To keep miss rates low, SMT might need a larger L2 (which is OK)
 - Out-of-order tolerates L1 misses
- Large physical register file (and map table)
 - physical registers = (**#threads** * #arch-regs) + #in-flight insns
 - map table entries = (**#threads** * #arch-regs)

Notes About Sharing Soft State

- Caches are shared naturally...
 - Physically-tagged: address translation distinguishes different threads
- ... but TLBs need explicit thread IDs to be shared
 - Virtually-tagged: entries of different threads indistinguishable
 - Thread IDs are only a few bits: enough to identify on-chip contexts
- Thread IDs make sense on BTB (branch target buffer)
 - BTB entries are already large, a few extra bits / entry won't matter
 - Different thread's target prediction → automatic mis-prediction
- ... but not on a BHT (branch history table)
 - BHT entries are small, a few extra bits / entry is huge overhead
 - Different thread's direction prediction → mis-prediction not automatic
- Ordered soft-state should be replicated
 - Examples: Branch History Register (BHR), Return Address Stack (RAS)
 - Otherwise it becomes meaningless... Fortunately, it is typically small

Multithreading vs. Multicore

- If you wanted to run multiple threads would you build a...
 - A multicore: multiple separate pipelines?
 - A multithreaded processor: a single larger pipeline?
- **Both will get you throughput on multiple threads**
 - Multicore core will be simpler, possibly faster clock
 - SMT will get you better performance (IPC) on a single thread
 - SMT is basically an ILP engine that converts TLP to ILP
 - Multicore is mainly a TLP (thread-level parallelism) engine
- **Do both**
 - Sun's Niagara (UltraSPARC T1)
 - 8 processors, each with 4-threads (non-SMT threading)
 - 1Ghz clock, in-order, short pipeline (6 stages or so)
 - Designed for power-efficient "throughput computing"

Research: Speculative Multithreading

- **Speculative multithreading**
 - Use multiple threads/processors for **single-thread performance**
 - Speculatively parallelize sequential loops, that might not be parallel
 - Processing elements (called PE) arranged in logical ring
 - Compiler or hardware assigns iterations to consecutive PEs
 - Hardware tracks logical order to detect mis-parallelization
 - Techniques for doing this on non-loop code too
 - Detect reconvergence points (function calls, conditional code)
 - Effectively chains ROBs of different processors into one big ROB
 - Global commit "head" travels from one PE to the next
 - Mis-parallelization flushes one PEs, but **not all** PEs
 - Also known as split-window or "Multiscalar"
 - Not commercially available yet...
 - But it is the "biggest idea" from academia not yet adopted

Research: Multithreading for Reliability

- Can multithreading help with reliability?
 - Design bugs/manufacturing defects? No
 - Gradual defects, e.g., thermal wear? No
 - Transient errors? Yes
- **Staggered redundant multithreading (SRT)**
 - Run two copies of program at a slight stagger
 - Compare results, difference? Flush both copies and restart
 - Significant performance overhead

Multithreading Summary

- Latency vs. throughput
- Partitioning different processor resources
- Three multithreading variants
 - Coarse-grain: no single-thread degradation, but long latencies only
 - Fine-grain: other end of the trade-off
 - Simultaneous: fine-grain with out-of-order
- Multithreading vs. chip multiprocessing